Before using this information and the product it supports, read the information in “Notices” on page 1169.

This edition applies to Version 2 Release 2 of z/OS (5650-ZOS) and to all subsequent releases and modifications until otherwise indicated in new editions.

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About this document

This document provides information about implementing programs that are written in C and C++. It contains advanced guidelines and information for developing C and C++ programs to run under z/OS®.

This document contains terminology, maintenance, and editorial changes. Technical changes or additions to the text and illustrations are indicated by a vertical line (|) to the left of the change.

You may notice changes in the style and structure of some of the contents in this document; for example, headings that use uppercase for the first letter of initial words only, and procedures that have a different look and format. The changes are ongoing improvements to the consistency and retrievability of information in our documents.

How to read syntax diagrams

This section describes how to read syntax diagrams. It defines syntax diagram symbols, items that may be contained within the diagrams (keywords, variables, delimiters, operators, fragment references, operands) and provides syntax examples that contain these items.

Syntax diagrams pictorially display the order and parts (options and arguments) that comprise a command statement. They are read from left to right and from top to bottom, following the main path of the horizontal line.

For users accessing the Information Center using a screen reader, syntax diagrams are provided in dotted decimal format.

The following symbols may be displayed in syntax diagrams:

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>➡➡➡➡</td>
<td>Indicates the beginning of the syntax diagram.</td>
</tr>
<tr>
<td>➡➡</td>
<td>Indicates that the syntax diagram is continued to the next line.</td>
</tr>
<tr>
<td>➡➡➡</td>
<td>Indicates that the syntax is continued from the previous line.</td>
</tr>
<tr>
<td>➡➡➡➡</td>
<td>Indicates the end of the syntax diagram.</td>
</tr>
</tbody>
</table>

Syntax diagrams contain many different items. Syntax items include:

- **Keywords** - a command name or any other literal information.
- **Variables** - variables are italicized, appear in lowercase, and represent the name of values you can supply.
- **Delimiters** - delimiters indicate the start or end of keywords, variables, or operators. For example, a left parenthesis is a delimiter.
- **Operators** - operators include add (+), subtract (-), multiply (*), divide (/), equal (=), and other mathematical operations that may need to be performed.
- **Fragment references** - a part of a syntax diagram, separated from the diagram to show greater detail.
Separators - a separator separates keywords, variables or operators. For example, a comma (,) is a separator.

Note: If a syntax diagram shows a character that is not alphanumeric (for example, parentheses, periods, commas, equal signs, a blank space), enter the character as part of the syntax.

Keywords, variables, and operators may be displayed as required, optional, or default. Fragments, separators, and delimiters may be displayed as required or optional.

**Item type**

**Definition**

**Required**

Required items are displayed on the main path of the horizontal line.

**Optional**

Optional items are displayed below the main path of the horizontal line.

**Default**

Default items are displayed above the main path of the horizontal line.

The following table provides syntax examples.

**Table 1. Syntax examples**

<table>
<thead>
<tr>
<th>Item</th>
<th>Syntax example</th>
</tr>
</thead>
<tbody>
<tr>
<td>Required item</td>
<td></td>
</tr>
<tr>
<td>Required items appear on the main path of the horizontal line. You must specify these items.</td>
<td></td>
</tr>
<tr>
<td>Required choice.</td>
<td></td>
</tr>
<tr>
<td>A required choice (two or more items) appears in a vertical stack on the main path of the horizontal line. You must choose one of the items in the stack.</td>
<td></td>
</tr>
<tr>
<td>Optional item</td>
<td></td>
</tr>
<tr>
<td>Optional items appear below the main path of the horizontal line.</td>
<td></td>
</tr>
<tr>
<td>Optional choice.</td>
<td></td>
</tr>
<tr>
<td>An optional choice (two or more items) appears in a vertical stack below the main path of the horizontal line. You may choose one of the items in the stack.</td>
<td></td>
</tr>
<tr>
<td>Default</td>
<td></td>
</tr>
<tr>
<td>Default items appear above the main path of the horizontal line. The remaining items (required or optional) appear on (required) or below (optional) the main path of the horizontal line. The following example displays a default with optional items.</td>
<td></td>
</tr>
</tbody>
</table>
Table 1. Syntax examples (continued)

<table>
<thead>
<tr>
<th>Item</th>
<th>Syntax example</th>
</tr>
</thead>
<tbody>
<tr>
<td>Variable.</td>
<td></td>
</tr>
<tr>
<td>Variables appear in lowercase italics. They represent names or values.</td>
<td>![diagram]</td>
</tr>
<tr>
<td>Repeatable item.</td>
<td></td>
</tr>
<tr>
<td>An arrow returning to the left above the main path of the horizontal line indicates an item that can be repeated.</td>
<td>![diagram]</td>
</tr>
<tr>
<td>A character within the arrow means you must separate repeated items with that character.</td>
<td>![diagram]</td>
</tr>
<tr>
<td>An arrow returning to the left above a group of repeatable items indicates that one of the items can be selected, or a single item can be repeated.</td>
<td>![diagram]</td>
</tr>
<tr>
<td>Fragment.</td>
<td></td>
</tr>
<tr>
<td>The fragment symbol indicates that a labelled group is described below the main syntax diagram. Syntax is occasionally broken into fragments if the inclusion of the fragment would overly complicate the main syntax diagram.</td>
<td>![diagram]</td>
</tr>
</tbody>
</table>

z/OS XL C/C++ and related documents

This topic summarizes the content of the z/OS XL C/C++ documents and shows where to find related information in other documents.
<table>
<thead>
<tr>
<th>Document Title and Number</th>
<th>Key Sections/Chapters in the Document</th>
</tr>
</thead>
</table>
| **z/OS XL C/C++ Programming Guide, SC14-7315** | Guidance information for:  
  - XL C/C++ input and output  
  - Debugging z/OS XL C programs that use input/output  
  - Using linkage specifications in C++  
  - Combining C and assembler  
  - Creating and using DLLs  
  - Using threads in z/OS UNIX System Services applications  
  - Reentrancy  
  - Handling exceptions, error conditions, and signals  
  - Performance optimization  
  - Network communications under z/OS UNIX  
  - Interprocess communications using z/OS UNIX  
  - Structuring a program that uses C++ templates  
  - Using environment variables  
  - Using System Programming C facilities  
  - Library functions for the System Programming C facilities  
  - Using runtime user exits  
  - Using the z/OS XL C multitasking facility  
  - Using other IBM® products with z/OS XL C/C++ (IBM CICS® Transaction Server for z/OS, CSP, DWS, IBM DB2®, IBM GDDM, IBM IMS®, ISPF, IBM QMF®)  
  - Globalization: locales and character sets, code set conversion utilities, mapping variant characters  
  - POSIX character set  
  - Code point mappings  
  - Locales supplied with z/OS XL C/C++  
  - Charmap files supplied with z/OS XL C/C++  
  - Examples of charmap and locale definition source files  
  - Converting code from coded character set IBM-1047  
  - Using built-in functions  
  - Using vector programming support  
  - Using runtime check library  
  - Using high performance libraries  
  - Programming considerations for z/OS UNIX C/C++ |
| **z/OS XL C/C++ User’s Guide, SC14-7307** | Guidance information for:  
  - z/OS XL C/C++ examples  
  - Compiler options  
  - Binder options and control statements  
  - Specifying Language Environment® runtime options  
  - Compiling, IPA Linking, binding, and running z/OS XL C/C++ programs  
  - Utilities (Object Library, CXXFILT, DSECT Conversion, Code Set and Locale, ar and make, BXPBATCH, c89, xlc)  
  - Diagnosing problems  
  - Cataloged procedures and IBM REXX EXECs  
  - Customizing default options for the z/OS XL C/C++ compiler |
Table 2. z/OS XL C/C++ and related documents (continued)

<table>
<thead>
<tr>
<th>Document Title and Number</th>
<th>Key Sections/Chapters in the Document</th>
</tr>
</thead>
</table>
| z/OS XL C/C++ Language Reference, SC14-7308 | Reference information for:  
- The C and C++ languages  
- Lexical elements of z/OS XL C and C++  
- Declarations, expressions, and operators  
- Implicit type conversions  
- Functions and statements  
- Preprocessor directives  
- C++ classes, class members, and friends  
- C++ overloading, special member functions, and inheritance  
- C++ templates and exception handling  
- z/OS XL C and C++ compatibility |
| z/OS XL C/C++ Messages, GC14-7305 | Provides error messages and return codes for the compiler, and its related application interface libraries and utilities. For the XL C/C++ runtime library messages, refer to z/OS Language Environment Runtime Messages, SA38-0686. For the c89 and xlc utility messages, refer to z/OS UNIX System Services Messages and Codes, SA23-2284. |
| z/OS XL C/C++ Runtime Library Reference, SC14-7314 | Reference information for:  
- header files  
- library functions |
| z/OS C Curses, SA38-0690 | Reference information for:  
- Curses concepts  
- Key data types  
- General rules for characters, renditions, and window properties  
- General rules of operations and operating modes  
- Use of macros  
- Restrictions on block-mode terminals  
- Curses functional interface  
- Contents of headers  
- The terminfo database |
| z/OS XL C/C++ Compiler and Runtime Migration Guide for the Application Programmer, GC14-7306 | Guidance and reference information for:  
- Common migration questions  
- Application executable program compatibility  
- Source program compatibility  
- Input and output operations compatibility  
- Class library migration considerations  
- Changes between releases of z/OS  
- Pre-z/OS C and C++ compilers to current compiler migration  
- Other migration considerations |
| z/OS Metal C Programming Guide and Reference, SC14-7313 | Guidance and reference information for:  
- Metal C run time  
- Metal C programming  
- AR mode |
Table 2. z/OS XL C/C++ and related documents (continued)

<table>
<thead>
<tr>
<th>Document Title and Number</th>
<th>Key Sections/Chapters in the Document</th>
</tr>
</thead>
</table>
| Standard C++ Library Reference, SC14-7309 | The documentation describes how to use the following three main components of the Standard C++ Library to write portable C/C++ code that complies with the ISO standards:  
  - ISO Standard C Library  
  - ISO Standard C++ Library  
  - Standard Template Library (C++)  
  The ISO Standard C++ library consists of 51 required headers. These 51 C++ library headers (along with the additional 18 Standard C headers) constitute a hosted implementation of the C++ library. Of these 51 headers, 13 constitute the Standard Template Library, or STL. |
| z/OS Common Debug Architecture User’s Guide, SC14-7310 | This documentation is the user’s guide for IBM’s libddpi library. It includes:  
  - Overview of the architecture  
  - Information on the order and purpose of API calls for model user applications and for accessing DWARF information  
  - Information on using the Common Debug Architecture with C/C++ source  
  This user’s guide is part of the Runtime Library Extensions documentation. |
| z/OS Common Debug Architecture Library Reference, SC14-7311 | This documentation is the reference for IBM’s libddpi library. It includes:  
  - General discussion of Common Debug Architecture  
  - Description of APIs and data types related to stacks, processes, operating systems, machine state, storage, and formatting  
  This reference is part of the Runtime Library Extensions documentation. |
| DWARF/ELF Extensions Library Reference, SC14-7312 | This documentation is the reference for IBM’s extensions to the libdwarf and libelf libraries. It includes information on:  
  - Consumer APIs  
  - Producer APIs  
  This reference is part of the Runtime Library Extensions documentation. |
| README file | The README file provides additional information for using the z/OS XL C/C++ licensed program, including late changes to z/OS XL C/C++ publications. To access any README files that were published after the ship date, go to [http://www.ibm.com/support/docview.wss?uid=swg27007531](http://www.ibm.com/support/docview.wss?uid=swg27007531). |

Note: For complete and detailed information on linking and running with Language Environment services and using the Language Environment runtime options, refer to z/OS Language Environment Programming Guide, SA38-0682. For complete and detailed information on using interlanguage calls, refer to z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications, SA38-0684.

The following table lists the z/OS XL C/C++ and related documents. The table groups the documents according to the tasks they describe.
### Table 3. Documents by task

<table>
<thead>
<tr>
<th>Tasks</th>
<th>Documents</th>
</tr>
</thead>
</table>
| Planning, preparing, and migrating to z/OS XL C/C++ | • z/OS XL C/C++ Compiler and Runtime Migration Guide for the Application Programmer, GC14-7306  
• z/OS Language Environment Customization, SA38-0685  
• z/OS V2R1.0 Language Environment Runtime Application Migration Guide, GA32-0912  
• z/OS UNIX System Services Planning, GA32-0884  
• z/OS Planning for Installation, GA32-0890 |
| Installing                                  | • z/OS Program Directory  
• z/OS Planning for Installation, GA32-0890  
• z/OS Language Environment Customization, SA38-0685 |
| Option customization                        | • z/OS XL C/C++ User’s Guide, SC14-7307                                    |
| Coding programs                             | • z/OS XL C/C++ Runtime Library Reference, SC14-7314  
• z/OS XL C/C++ Language Reference, SC14-7308  
• z/OS XL C/C++ Programming Guide, SC14-7315  
• z/OS Metal C Programming Guide and Reference, SC14-7313  
• z/OS V2R1.0 Language Environment Concepts Guide, SA38-0687  
• z/OS Language Environment Programming Guide, SA38-0682  
• z/OS Language Environment Programming Reference, SA38-0683 |
| Coding and binding programs with interlanguage calls | • z/OS XL C/C++ Programming Guide, SC14-7315  
• z/OS XL C/C++ Language Reference, SC14-7308  
• z/OS Language Environment Programming Guide, SA38-0682  
• z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications, SA38-0684  
• z/OS MVS Program Management: User’s Guide and Reference, SA23-1393  
• z/OS MVS Program Management: Advanced Facilities, SA23-1392 |
| Compiling, binding, and running programs    | • z/OS XL C/C++ User’s Guide, SC14-7307  
• z/OS Language Environment Programming Guide, SA38-0682  
• z/OS Language Environment Debugging Guide, GA32-0908  
• z/OS MVS Program Management: User’s Guide and Reference, SA23-1393  
• z/OS MVS Program Management: Advanced Facilities, SA23-1392 |
| Compiling and binding applications in the z/OS UNIX (z/OS UNIX) environment | • z/OS XL C/C++ User’s Guide, SC14-7307  
• z/OS V2R2.0 UNIX System Services User’s Guide, SA23-2279  
• z/OS UNIX System Services Command Reference, SA23-2280  
• z/OS MVS Program Management: User’s Guide and Reference, SA23-1393  
• z/OS MVS Program Management: Advanced Facilities, SA23-1392 |
## Table 3. Documents by task (continued)

<table>
<thead>
<tr>
<th>Tasks</th>
<th>Documents</th>
</tr>
</thead>
<tbody>
<tr>
<td>Debugging programs</td>
<td>• README file</td>
</tr>
<tr>
<td></td>
<td>• z/OS XL C/C++ User’s Guide, SC14-7307</td>
</tr>
<tr>
<td></td>
<td>• z/OS XL C/C++ Messages, GC14-7305</td>
</tr>
<tr>
<td></td>
<td>• z/OS XL C/C++ Programming Guide, SC14-7315</td>
</tr>
<tr>
<td></td>
<td>• z/OS Language Environment Programming Guide, SA38-0682</td>
</tr>
<tr>
<td></td>
<td>• z/OS Language Environment Debugging Guide, GA32-0908</td>
</tr>
<tr>
<td></td>
<td>• z/OS Language Environment Runtime Messages, SA38-0686</td>
</tr>
<tr>
<td></td>
<td>• z/OS UNIX System Services Messages and Codes, SA23-2284</td>
</tr>
<tr>
<td></td>
<td>• z/OS V2R2.0 UNIX System Services User’s Guide, SA23-2279</td>
</tr>
<tr>
<td></td>
<td>• z/OS UNIX System Services Command Reference, SA23-2280</td>
</tr>
<tr>
<td></td>
<td>• z/OS UNIX System Services Programming Tools, SA23-2282</td>
</tr>
<tr>
<td>Developing debuggers and profilers</td>
<td>• z/OS Common Debug Architecture User’s Guide, SC14-7310</td>
</tr>
<tr>
<td></td>
<td>• z/OS Common Debug Architecture Library Reference, SC14-7311</td>
</tr>
<tr>
<td></td>
<td>• DWARF/ELF Extensions Library Reference, SC14-7312</td>
</tr>
<tr>
<td>Packaging XL C/C++ applications</td>
<td>• z/OS XL C/C++ Programming Guide, SC14-7315</td>
</tr>
<tr>
<td></td>
<td>• z/OS XL C/C++ User’s Guide, SC14-7307</td>
</tr>
<tr>
<td>Using shells and utilities in the z/OS UNIX environment</td>
<td>• z/OS XL C/C++ User’s Guide, SC14-7307</td>
</tr>
<tr>
<td></td>
<td>• z/OS UNIX System Services Command Reference, SA23-2280</td>
</tr>
<tr>
<td></td>
<td>• z/OS UNIX System Services Messages and Codes, SA23-2284</td>
</tr>
<tr>
<td>Using sockets library functions in the z/OS UNIX environment</td>
<td>• z/OS XL C/C++ Runtime Library Reference, SC14-7314</td>
</tr>
<tr>
<td>Using the ISO Standard C++ Library to write portable C/C++ code that complies with ISO standards</td>
<td>• Standard C++ Library Reference, SC14-7309</td>
</tr>
<tr>
<td>Performing diagnosis and submitting an Authorized Program Analysis Report (APAR)</td>
<td>• z/OS XL C/C++ User’s Guide, SC14-7307</td>
</tr>
</tbody>
</table>

**Note:** For information on using the prelinker, see the appendix on prelinking and linking z/OS XL C/C++ programs in z/OS XL C/C++ User’s Guide.

## Softcopy documents


To read a PDF file, use the Adobe Reader. If you do not have the Adobe Reader, you can download it (subject to Adobe license terms) from the Adobe website at [http://www.adobe.com](http://www.adobe.com).


**Note:** For further information on viewing and printing softcopy documents and using IBM BookManager®, see z/OS V2R2 Information Roadmap.
Softcopy examples

Most of the larger examples in the following documents are available in machine-readable form:

- z/OS XL C/C++ Language Reference, SC14-7308
- z/OS XL C/C++ User's Guide, SC14-7307
- z/OS XL C/C++ Programming Guide, SC14-7315

In the following documents, a label on an example indicates that the example is distributed as a softcopy file:

- z/OS XL C/C++ Language Reference, SC14-7308
- z/OS XL C/C++ Programming Guide, SC14-7315
- z/OS XL C/C++ User's Guide, SC14-7307

The label is the name of a member in the CBC.SCCNSAM data set. The labels begin with the form CCN or CLB. Examples labelled as CLB appear only in the z/OS XL C/C++ User’s Guide, while examples labelled as CCN appear in all three documents, and are further distinguished by x following CCN, where x represents one of the following:

- R and X refer to z/OS XL C/C++ Language Reference, SC14-7308
- G refers to z/OS XL C/C++ Programming Guide, SC14-7315
- U refers to z/OS XL C/C++ User’s Guide, SC14-7307

Related z/OS XL C/C++ information

The following list shows where to find related z/OS XL C/C++ information:

- Softcopy examples and related documents information in z/OS XL C/C++ User’s Guide

Where to find more information

For an overview of the information associated with z/OS, see z/OS V2R2 Information Roadmap.

Information updates on the web

For the latest information updates that have been provided in PTF cover letters and documentation APARs for z/OS, see the online document z/OS APAR book ([http://publibz.boulder.ibm.com/cgi-bin/bookmgr_OS390/Shelves/ZDOCAPAR](http://publibz.boulder.ibm.com/cgi-bin/bookmgr_OS390/Shelves/ZDOCAPAR)).

This document is updated weekly and lists documentation changes before they are incorporated into z/OS publications.

The z/OS Basic Skills Information Center

The z/OS Basic Skills Information Center is a Web-based information resource intended to help users learn the basic concepts of z/OS, the operating system that runs most of the IBM mainframe computers in use today. The Information Center is designed to introduce a new generation of Information Technology professionals to basic concepts and help them prepare for a career as a z/OS professional, such as a z/OS system programmer.
Specifically, the z/OS Basic Skills Information Center is intended to achieve the following objectives:

- Provide basic education and information about z/OS without charge
- Shorten the time it takes for people to become productive on the mainframe
- Make it easier for new people to learn z/OS.

To access the z/OS Basic Skills Information Center, open your Web browser to the following Web site, which is available to all users (no login required): z/OS Basic Skills in IBM Knowledge Center (http://www.ibm.com/support/knowledgecenter/zosbasics/com.ibm.zos.zbasics/homepage.html)

How to send your comments to IBM

We appreciate your input on this publication. Feel free to comment on the clarity, accuracy, and completeness of the information or provide any other feedback that you have.

Use one of the following methods to send your comments:

1. Send an email to mhvrcfs@us.ibm.com.
2. Send an email from the "Contact us" web page for z/OS (http://www.ibm.com/systems/z/os/zos/webqs.html).

Include the following information:

- Your name and address.
- Your email address.
- Your telephone or fax number.
- The publication title and order number:
  
z/OS V2R2 XL C/C++ Programming Guide
  SC14-7315-02
- The topic and page number that is related to your comment.
- The text of your comment.

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IBM or any other organizations use the personal information that you supply to contact you only about the issues that you submit.

If you have a technical problem

Do not use the feedback methods that are listed for sending comments. Instead, take one of the following actions:

- Contact your IBM service representative.
- Call IBM technical support.
Summary of changes for z/OS Version 2 Release 1

See the following publications for all enhancements to z/OS Version 2 Release 1 (V2R1):

- z/OS V2R2 Migration, GA32-0889
- z/OS Planning for Installation, GA32-0890
- z/OS Summary of Message and Interface Changes, SA23-2300
- z/OS V2R2 Introduction and Release Guide, GA32-0887
Part 1. Introduction

This part discusses introductory concepts on the z/OS XL C/C++ feature. Specifically, it discusses the following:

- Chapter 1, “About IBM z/OS XL C/C++,” on page 3
Chapter 1. About IBM z/OS XL C/C++

For an introduction to z/OS XL C/C++ and for information about changes to z/OS XL C/C++ for the current release, see About IBM z/OS XL C/C++ in z/OS XL C/C++ User's Guide.
Part 2. Input and Output

This part describes the models of input and output available with IBM z/OS XL C/C++.

The C runtime functions are available if the corresponding C header files are used. C I/O can be used by C++ when the C runtime library functions are used.

The following references provide a description and examples of I/O streams:

- Chapter 2, “Introduction to C and C++ input and output,” on page 7
- Chapter 3, “Understanding models of C I/O,” on page 11
- Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23
- Chapter 5, “Opening files,” on page 27
- Chapter 6, “Buffering of C streams,” on page 45
- Chapter 7, “Using ASA text files,” on page 47
- Chapter 8, “z/OS XL C Support for the double-byte character set,” on page 53
- Chapter 9, “Using C and C++ standard streams and redirection,” on page 63
- Chapter 10, “Performing OS I/O operations,” on page 83
- Chapter 11, “Performing z/OS UNIX file system I/O operations,” on page 127
- Chapter 12, “Performing VSAM I/O operations,” on page 151
- Chapter 13, “Performing terminal I/O operations,” on page 191
- Chapter 14, “Performing memory file and hiperspace I/O operations,” on page 201
- Chapter 15, “Performing CICS Transaction Server I/O operations,” on page 215
- Chapter 16, “Language Environment Message file operations,” on page 217
- Chapter 17, “CELQPIPI MSGRTN file operations,” on page 219
- Chapter 18, “Debugging I/O programs,” on page 223
Chapter 2. Introduction to C and C++ input and output

This chapter provides you with a general introduction to C and C++ input and output (I/O). Four types of C and C++ input and output are discussed in this chapter:

- **text streams**
- **binary streams**
- **record I/O**
- **blocked I/O**

Types of C and C++ input and output

A stream is a flow of data elements that are transmitted or intended for transmission in a defined format. A record is a set of data elements treated as a unit, and a file (or data set) is a named set of records that is stored or processed as a unit.

The z/OS XL C/C++ compiler supports four types of input and output: text streams, binary streams, record I/O, and blocked I/O. Text and binary streams are both ANSI standards; record I/O and blocked I/O are extensions for z/OS XL C. Record I/O and blocked I/O are not supported by either the USL I/O Stream Class Library or the Standard C++ I/O stream classes.

**Note:** If you have written data in one of these four types and try to read it as another type (for example, reading a binary file in text mode), you may not get the behavior that you expect.

**Text streams**

Text streams contain printable characters and, depending on the type of file, control characters. Text streams are organized into lines. Each line ends with a control character, usually a new-line. The last record in a text file may or may not end with a control character, depending on what kind of file you are using. Text files recognize the following control characters:

- `\a` Alarm.
- `\b` Backspace.
- `\f` Form feed.
- `\n` New-line.
- `\r` Carriage return.
- `\t` Horizontal tab character.
- `\v` Vertical tab character.
- `\x0E` DBCS shift-out character. Indicates the beginning of a DBCS string, if `MB_CUR_MAX>1` in the definition of the locale that is in effect. For more information about `__MBCURMAX`, see Chapter 8, “z/OS XL C Support for the double-byte character set,” on page 53.
- `\x0F` DBCS shift-in character. Indicates the end of a DBCS string, if `MB_CUR_MAX>1`
in the definition of the locale that is in effect. For more information about
MBCURMAX, see Chapter 8, "z/OS XL C Support for the double-byte
caracter set," on page 53.

Control characters behave differently in terminal files (see Chapter 13, "Performing
terminal I/O operations," on page 191) and ASA files (see Chapter 7, "Using ASA
text files," on page 47).

Binary streams

Binary streams contain a sequence of bytes. For binary streams, the library does not translate any characters on input or output. It treats them as a continuous stream of bytes, and ignores any record boundaries. When data is written out to a record-oriented file, it fills one record before it starts filling the next. Streams in the z/OS UNIX file system follow the binary model, regardless of whether they are opened for text, binary, record I/O, or blocked I/O. You can simulate record I/O by using new-line characters as record boundaries.

Record I/O

Record I/O is an extension to the ISO standard. For files opened in record format, 
z/OS XL C/C++ reads and writes one record at a time. If you try to write more data to a record than the record can hold, the data is truncated. For record I/O, 
z/OS XL C/C++ allows only the use of fread() and fwrite() to read and write to files. Any other functions (such as fprintf(), fscanf(), getc(), and putc()) will fail. For record-oriented files, records do not change size when you update them. If the new record has fewer bytes than the original record, the new data fills the first \( n \) bytes, where \( n \) is the number of bytes of the new data. The record will remain the same size, and the old bytes (those after \( n \)) are left unchanged. A subsequent update begins at the next boundary. For example, if you have the string "abcdefgh":

```
 a b c d e f g h
```

and you overwrite it with the string "1234", the record will look like this:

```
 1 2 3 4 e f g h
```

z/OS XL C/C++ record I/O is binary. That is, it does not interpret any of the data in a record file and therefore does not recognize control characters. The only exception is for file categories that do not support records, such as the UNIX file system (also known as POSIX I/O). For these files, z/OS XL C/C++ uses new-line characters as record boundaries.

Blocked I/O

Blocked I/O is an extension to the ISO standard. For files opened in block format, 
z/OS XL C/C++ reads and writes one block at a time. If you try to write more data to a block than the block can hold, the data is truncated. For blocked I/O, 
z/OS XL C/C++ allows only the use of fread() and fwrite() to read and write to files. Any other functions (such as fprintf(), fscanf(), getc(), and putc()) will
Blocks do not change size when you update them. If the new block has fewer bytes than the original block, the new data fills the first $n$ bytes, where $n$ is the number of bytes of the new data. The block will remain the same size, and the old bytes (those after $n$) are left unchanged. A subsequent update begins at the next boundary. For example, if you have the string "abcdefg":

```
  a b c d e f g h
```

and you overwrite it with the string "1234", the block will look like this:

```
  1 2 3 4 e f g h
```

*z/OS XL C/C++* blocked I/O is binary. That is, it does not interpret any of the data in a block file and therefore does not recognize control characters.

The fflush() function has no effect for blocked I/O files.
Chapter 3. Understanding models of C I/O

This chapter describes z/OS XL C/C++ support for the major models of C I/O:

• The record model
• The byte stream model

The next chapter, Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23, describes a third major model, the object-oriented model.

The record model for C I/O

Almost all kinds of I/O that z/OS XL C/C++ supports use this model. The only ones that do not are z/OS UNIX file system, memory file, and Hiperspace™ I/O.

The record model consists of the following:

• A record, which is the unit of data transmitted to and from a program.
• A block, which is the unit of data transmitted to and from a device. Each block may contain one or more records.

In the record model of I/O, records and blocks have the following attributes:

RECFM
    Specifies the format of the data or how the data is organized on the physical device.

LRECL
    Specifies the length of logical records (as opposed to physical ones). Variable length records include a count field that is normally not available to the programmer.

BLKSIZE
    Specifies the length of physical records (blocks on the physical device).

Record formats

Use the RECFM attribute to specify the record format. The records in a file using the record model have one of the following formats:

• Fixed-length (F)
• Variable-length (V)
• Undefined-length (U)

Note: z/OS XL C/C++ does not support Format-0 files.

These formats support the following additional options for RECFM. The record formats and the options associated with them are discussed in the following sections.

A    Specifies that the file contains ASA control characters.
B    Specifies that a file is blocked. A blocked file can have more than one record in each block.
M    Specifies that the file contains machine control characters.
S specifies that a file is either in standard format (if it is fixed) or spanned (if it is variable). In a standard file, every block must be full before another one starts. In a spanned file, a record can be longer than a block. If it is, the record is divided into segments and stored in consecutive blocks.

Not all the I/O categories (listed in Table 6 on page 29) support all of these attributes. Depending on what category you are using, z/OS XL C/C++ ignores or simulates attributes that do not apply. For more information on the record formats and the options supported for each I/O category, see Chapter 5, “Opening files,” on page 27.

Fixed-format records
These are the formats you can specify for RECFM if you want to use a fixed-format file:

F Fixed-length, unblocked
FA Fixed-length, ASA print-control characters
FB Fixed-length, blocked
FM Fixed-length, machine print-control codes
FS Fixed-length, unblocked, standard
FBA Fixed-length, blocked, ASA print-control characters
FBM Fixed-length, blocked, machine print-control codes
FBS Fixed-length, blocked, standard
FSA Fixed-length, unblocked, standard, ASA print-control characters
FSM Fixed-length, unblocked, standard, machine print-control codes
FBSM Fixed-length, blocked, standard, machine print-control codes
FBSA Fixed-length, blocked, standard, ASA print-control characters.

In general, all references to files with record format FB also refer to FBM and FBA. The specific behavior of ASA files (such as FBA) is explained in Chapter 7, “Using ASA text files,” on page 47.

Attention: z/OS XL C/C++ distinguishes between FB and FBS formats, because an FBS file contains no embedded short blocks (the last block may be short). FBS files give you much better performance. The use of standard (S) blocks optimizes the sequential processing of a file on a direct-access device. With a standard format file, the file pointer can be directly repositioned by calculating the exact position in that file of a given record rather than reading through the entire file.

If the records are FB, some blocks may contain fewer records than others, as shown in Figure 1 on page 13.
The section describes the following formats:

- **Binary**
- **Text (non-ASA)**
- **Text (ASA)**
- **Record**
- **Blocked**

**Binary**

On binary input and output, data flows over record boundaries. Because all fixed-format records must be full, z/OS XL C/C++ completes any incomplete output record by padding it with nulls ("\0") when you close the file. Incomplete blocks are not padded. On input, nulls are visible and are treated as data.

For example, if record length is set to 10 and you are writing 25 characters of data, z/OS XL C/C++ will write two full records, each containing 10 characters, and then an incomplete record containing 5 characters. If you then close the file, z/OS XL C/C++ will complete the last record with 5 nulls. If you open the file for reading, z/OS XL C/C++ will read the records in order. z/OS XL C/C++ will not strip off the nulls at the end of the last record.

**Text (non-ASA)**

When writing in a text stream, you indicate the end of the data for a record by writing a new-line ("\n") or carriage return ("\r") to the stream. In a fixed-format file, the new-line or carriage return will not appear in the external file, and the record will be padded with blanks from the position of the new-line or carriage return to LRECL. (A carriage return is considered the same as a new-line because the "\r" is not written to the file.)

For example, if you have set LRECL to 10, and you write the string "ABC\n" to a fixed-format text file, z/OS XL C/C++ will write this to the physical
A record containing only a new-line is written to the file as LRECL blanks.

When reading in a text stream, the I/O functions place a new-line character ('\n') in the buffer to indicate the end of data for the record. In a fixed-format file, the new-line character is placed at the start of the blank padding at the end of the data.

For example, if your file position points to the start of the following record in a fixed-format file opened as a text stream:

```
A B C
```

and you call `fgets()` to read the line of text, `fgets()` places the string "ABC\n" in your input buffer.

**Attention:** Any blanks written immediately before a new-line or carriage return will be considered blank padding when the record is read back from the file. You cannot change the padding character.

When you are updating a fixed-format file opened as a text stream, you can update the amount of data in a record. The maximum length of the updated data is LRECL bytes plus the new-line character; the minimum length is zero data bytes plus the new-line character. Writing new data into an existing record replaces the old data. If the new data is longer or shorter than the old data, the number of blank padding characters in the record in the external file is changed. When you extend a record, thereby writing over the old new-line, there will be a new-line character implied after the new characters. For instance, if you were to overwrite the record mentioned in the previous example with the string "123456", the records in the physical file would then look like this:

```
1 2 3 4 5 6
```

The blanks at the end of the record imply a new-line at position 7. You can see this new-line by calling `fflush()` and then performing a read. The implied new-line is the first character returned from this read.

A fixed record can hold only LRECL characters. If you try to write more than that, z/OS XL C/C++ truncates the data unless you are using a standard stream or a terminal file. In this case, the output is split across multiple records. If truncation occurs, z/OS XL C/C++ raises SIGIOERR and sets both errno and the error flag.
**Text (ASA)**

For ASA files, the first character of each record is reserved for the ASA control character that represents a new-line, a carriage return, or a form feed. This control character represents what should happen before the record is written.

### Table 4. C control to ASA characters

<table>
<thead>
<tr>
<th>C Control Character</th>
<th>ASA Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\n</td>
<td>' '</td>
<td>skip one line</td>
</tr>
<tr>
<td>\n\n</td>
<td>'0'</td>
<td>skip two lines</td>
</tr>
<tr>
<td>\n\n\n</td>
<td>'1'</td>
<td>new page</td>
</tr>
<tr>
<td>\f</td>
<td>'r'</td>
<td>overstrike</td>
</tr>
</tbody>
</table>

A control character that ends a logical record is represented at the beginning of the following record in the external file. Since the ASA control character is in the first byte of each record, a record can hold only LRECL - 1 bytes of data. As with non-ASA text files described above, z/OS XL C/C++ adds blank padding to complete any record shorter than LRECL - 1 when it writes the record to the file. On input, z/OS XL C/C++ removes all trailing blanks. For example, if LRECL is 10, and you enter the string:

\nABC\nDEF

the record in the physical file will look like this:

```
A B C
```

On input, this string is read as follows:

\nABC\nDEF

You can lengthen and shorten records the same way as you can for non-ASA files. For more information about ASA, refer to Chapter 7, “Using ASA text files,” on page 47.

---

**Record**

As with fixed-format text files, a record can hold LRECL bytes. Every call to `fwrite()` is considered to be writing a full record. If you write fewer than LRECL bytes, z/OS XL C/C++ completes the record with enough nulls to make it LRECL bytes long. If you try to write more than that, z/OS XL C/C++ truncates the data.

**Blocked**

Each call to `fwrite()` creates a block that must be shorter than or equal to the size established by `BLKSIZE`. When you write less than `BLKSIZE` bytes, if the request is to create a new block, a short block will be created; if it is to update an existing block, only requested part of the block will be updated. If you try to write more than `BLKSIZE` at one time, z/OS XL C/C++ truncates the data. z/OS XL C/C++ will not check the provided data. You might need to take the following cases into consideration:
Because all fixed-format records must be full, any block you write must be multiple of a record. Otherwise, z/OS XL C/C++ will fail the write request.

- When updating an FBS short block at the end of a file, it could be updated to a full block or a longer short block.
- When writing or appending to an FBS short block, z/OS XL C/C++ will use the request buffer to replace the previous block, which might extend or shrink the short block.
- You must make sure that there is no short block in the middle of the FBS data set.

**Variable-format records**

In a file with variable-length records, each record may be a different length. The variable length formats permit both variable-length records and variable-length blocks. The first 4 bytes of each block are reserved for the Block Descriptor Word (BDW); the first 4 bytes of each record are reserved for the Record Descriptor Word (RDW), or, if you are using spanned files, the Segment Descriptor Word (SDW). Illustrations of variable-length records are shown in Figure 2 on page 17.

Once you have set the LRECL for a variable-format file, you can write up to LRECL minus 4 characters in each record. z/OS XL C/C++ does not let you see RDWs, BDWs, or SDWs when you open a file as variable-format. To see the RDWs or SDWs and BDWs, open the variable file as undefined-format, as described in “Undefined-format records” on page 19.

The value of LRECL must be greater than 4 to accommodate the RDW or SDW. The value of BLKSIZE must be greater than or equal to the value of LRECL plus 4. You should not use a BLKSIZE greater than LRECL plus 4 for an unblocked data set. Doing so results in buffers that are larger than they need to be. The largest amount of data that any one record can hold is LRECL bytes minus 4.

For striped data sets, a block is padded out to its full BLKSIZE. This makes specifying an unnecessarily large BLKSIZE very inefficient.

**Record format (RECFM):** You can specify the following formats for variable-length records:

- **V** Variable-length, unblocked
- **VA** Variable-length, ASA print control characters, unblocked
- **VB** Variable-length, blocked
- **VM** Variable-length, machine print-control codes, unblocked
- **VS** Variable-length, unblocked, spanned
- **VBA** Variable-length, blocked, ASA print control characters
- **VBM** Variable-length, blocked, machine print-control codes
- **VBS** Variable-length, blocked, spanned
- **VSA** Variable-length, spanned, ASA print control characters
- **VSM** Variable-length, spanned, machine print-control codes
- **VBSA** Variable-length, blocked, spanned, ASA print control characters
- **VBSM** Variable-length, blocked, spanned, machine print-control codes
**Note:** In general, all references in this guide to files with record format VB also refer to VBM and VBA. The specific behavior of ASA files (such as VBA) is explained in Chapter 7, “Using ASA text files,” on page 47.

V-format signifies unblocked variable-length records. Each record is treated as a block containing only one record.

VB-format signifies blocked variable-length records. Each block contains as many complete records as it can accommodate.

**Spanned records:** A spanned record is opened using both V and S in the format specifier. A spanned record is a variable-length record in which the length of the record can exceed the size of a block. If it does, the record is divided into segments and accommodated in two or more consecutive blocks. The use of spanned records allows you to select a block size, independent of record length, that will combine optimum use of auxiliary storage with the maximum efficiency of transmission.

VS-format specifies that each block contains only one record or segment of a record. The first 4 bytes of a block describe the block control information. The second 4 bytes contain record or segment control information, including an indication of whether the record is complete or is a first, intermediate, or last segment.

VBS-format differs from VS-format in that each block in VBS-format contains as many complete records or segments as it can accommodate, while each block in VS-format contains at most one record per block.

**V-format:**

```
C1 C2 Record 1  C1 C2 Record 2  C1 C2
```

**VB-format:**

```
Block
C1 C2 Record 1  C2 Record 2  C1 C2 Record 3
```

**VS-format:**

```
Spanned Record
C1 C2 Record 1 (entire)  C1 C2 (first segment)  C1 C2 (next segment)
```

**VBS-format:**

```
Spanned Record
C1 C2 Record 1 (entire)  C2 Record 2 (first segment)  C1 C2 Record 3
```

C1: Block control information  
C2: Record or segment control information

*Figure 2. Variable-length records on z/OS*
Mapping C types to variable format:

Binary
On input and output, data flows over record boundaries. Any record will hold up to LRECL minus 4 characters of data. If you try to write more than that, your data will go to the next record, after the RDW or SDW. You will not be able to see the descriptor words when you read the file.

Note: If you need to see the BDWs, RDWs, or SDWs, you can open and read a V-format file as a U-format file. See "Undefined-format records" on page 19 for more information.

z/OS XL C/C++ never creates empty binary records for files opened in V-format. See "Writing to binary files" on page 108 for more information. An empty binary record is one that contains only an RDW, which is 4 bytes long. On input, empty records are ignored.

Text (non-ASA)
Record boundaries are used in the physical file to represent the position of the new-line character. You can indicate the end of a record by including a new-line or carriage return character in your data. In variable-format files, z/OS XL C/C++ treats the carriage return character as if it were a new-line. z/OS XL C/C++ does not write either of these characters to the physical file; instead, it creates a record boundary. When you read the file back, boundaries are read as new-lines.

If a record only contains a new-line character, the default behavior of z/OS XL C/C++ is to write a record containing a single blank to the file. Therefore, the string " \n" is treated the same way as the string "\n"; both are read back as "\n". All other blanks in your output are read back as is. Any empty (zero-length) record is ignored on input. However, if the environment variable _EDC_ZERO_RECLEN was set to Y at the time the file was opened, a single new-line is written to the file as an empty record, and a single blank represents " \n". On input, an empty record is treated as a single new-line and is not ignored.

After a record has been written to a file, you cannot change its length. If you try to shorten a logical record by writing a new, smaller amount of data into it, the C I/O library will add blank characters until the record is full. Writing more data to a record than it can hold causes your data to be truncated unless you are writing to a standard stream or a terminal file. In this case, your output is split across multiple records. If truncation occurs, z/OS XL C/C++ raises SIGIOERR and sets both errno and the error flag.

Note: If you did not explicitly set the _EDC_ZERO_RECLEN environment variable when you opened the file, you can update a record that contains a single blank to contain a non-blank character, thereby lengthening the logical record from ' \n' to 'x\n'), where x is the non-blank character.

Text (ASA)
z/OS XL C/C++ treats variable-format ASA text files similarly to the way it treats fixed-format ones. Empty records are always ignored in ASA variable-format files; for a record to be recognized, it must contain at least one character as the ASA control character. For more information about ASA, refer to Chapter 7, "Using ASA text files," on page 47.

Record
Each call to fwrite() creates a record that must be shorter than or equal to the size established by LRECL. If you try to write more than LRECL bytes
on one call to fwrite(), z/OS XL C/C++ will truncate your data. z/OS XL C/C++ never creates empty records using record I/O. On input, empty records are ignored unless you have set the _EDC_ZERO_RECLEN environment variable to Y. In this case, empty records are treated as records with length 0.

If your application sets _EDC_ZERO_RECLEN to Y, bear in mind that fread() returns back 0 bytes read, but does not set errno, and that both feof() and ferror() return 0 as well.

Blocked

Each call to fwrite() creates a block that must be shorter than or equal to the size established by BLKSIZE. When you write less than BLKSIZE bytes, if the request is to create a new block, a short block will be created; if it is to update an existing block, only requested part of the block will be updated. If you try to write more than BLKSIZE at one time, z/OS XL C/C++ truncates the data. z/OS XL C/C++ will not check the provided data. You must make sure that BDWs, RDWs, and SDWs in a block are correct.

Undefined-format records

Everything in an undefined-format file is treated as data, including control characters and record boundaries. Blocks in undefined-format records are variable-length; each block is considered a record.

It is impossible to have an empty record. Whatever you specify for LRECL has no effect on your data, but the value of LRECL must be less than or equal to the value you specify for BLKSIZE. Regardless of what you specify, z/OS XL C/C++ sets LRECL to zero when it creates an undefined-format file.

Reading a file in U-format enables you to read an entire block at once.

Record format (RECFM): You can specify the following formats for undefined-length records:

U Undefined-length
UA Undefined-length, ASA print control characters
UM Undefined-length, machine print-control codes

U, UA, and UM formats permit the processing of records that do not conform to F- and V-formats. The operating system treats each block as a record; your program must perform any additional blocking or deblocking.

You can read any file in U-format. This is useful if, for example, you want to see the BDWs and RDWs of a file that you have written in V-format.

Mapping C types to undefined format:

Binary

When you are writing to an undefined-format file, binary data fills a block and then begins a new block.

Text (non-ASA)

Record boundaries (that is, block boundaries) are used in the physical file to represent the position of the new-line character. You can indicate the end of a record by including a new-line or carriage return character in your data. In undefined-format files, z/OS XL C/C++ treats the carriage return character as if it were a new-line. z/OS XL C/C++ does not write either of
these characters to the physical file; instead, it creates a record boundary. When you read the file back, these boundaries are read as new-lines.

If a record contains only a new-line character, z/OS XL C/C++ writes a record containing a single blank to the file regardless of the setting of the _EDC_ZERO_RECLEN environment variable. Therefore, the string '\n' (a single blank followed by a new-line character) is treated the same way as ' \n'; both are written out as a single blank. On input, both are read as ' \n'. All other blank characters are written and read as you intended.

After a record has been written to a file, you cannot change its length. If you try to shorten a logical record by writing a new, smaller amount of data into it, the C I/O library adds blank characters until the record is full. Writing more data to a record than it can hold will cause your data to be truncated unless you are writing to a standard stream or a terminal file. In these cases, your output is split across multiple records. If truncation occurs, z/OS XL C/C++ raises SIGIOERR and sets both errno and the error flag.

**Note:** You can update a record that contains a single blank to contain a non-blank character, thereby lengthening the logical record from ' \n' to ' \n x', where x is the non-blank character.

### Text (ASA)

For a record to be recognized, it must contain at least one character as the ASA control character. For more information about ASA, refer to Chapter 7, "Using ASA text files," on page 47.

### Record

Each call to fwrite() creates a record that must be shorter than or equal to the size established by BLKSIZE. If you try to write more than BLKSIZE bytes on one call to fwrite(), z/OS XL C/C++ truncates your data.

### Blocked

Each call to fwrite() creates a block that must be shorter than or equal to the size established by BLKSIZE. When you write less than BLKSIZE bytes, if the request is to create a new block, a short block will be created; if it is to update an existing block, only requested part of the block will be updated. If you try to write more than BLKSIZE at one time, z/OS XL C/C++ truncates the data. z/OS XL C/C++ will not check the provided data.

---

**The byte stream model for C I/O**

The byte stream model differs from the record I/O model. In the byte stream model, a file is just a stream of bytes, with no record boundaries. New-line characters written to the stream appear in the external file.

If the file is opened in binary mode, any new-line characters previously written to the file are visible on input. z/OS XL C/C++ memory file I/O and Hiperspace memory file I/O are based on the byte stream model (see Chapter 14, "Performing memory file and hiperspace I/O operations," on page 201 for more information).

UNIX file system I/O, defined by POSIX, is also based on the byte stream model. See Chapter 11, "Performing z/OS UNIX file system I/O operations," on page 127 for information about I/O with UNIX file system.
Mapping the C types of I/O to the byte stream model

**Binary**

In the byte stream model, files opened in binary mode do not contain any record boundaries. Data is written as is to the file.

**Text**

The byte stream model does not support ASA. New-lines, carriage returns, and other control characters are written as-is to the file.

**Record**

If record I/O is supported by the kind of file you are using, z/OS XL C/C++ simulates it by treating new-line characters as record boundaries. New-lines are not treated as part of the record. A record written out with a new-line inside it is not read back as it was written, because z/OS XL C/C++ treats the new-line as a record boundary instead of data.

Files in z/OS UNIX file system support record I/O, but memory files do not.

As with all other record I/O, you can use only `fread()` and `fwrite()` to read from and write to files. Each call to `fwrite()` inserts a new-line in the byte stream; each call to `fread()` strips it off. For example, if you use one `fwrite()` statement to write the string `ABC` and the next to write `DEF`, the byte stream will look like this:

```
A  B  C  \n  D  E  F  \n  ...
```

There are no limitations on lengthening and shortening records. If you then rewind the file and write new data into it, z/OS XL C/C++ will replace the old data. For example, if you used the `rewind()` function on the stream in the previous example and then called `fwrite()` to place the string `12345` into it, the stream would look like this:

```
1  2  3  4  5  \n  F  \n  ...
```

If you are using files with this model, do not use new-line characters in your output. If you do, they will create extra record boundaries. If you are unsure about the data being written or are writing numeric data, use binary instead of text to avoid writing a byte that has the hex value of a new-line.
Chapter 4. Using the Standard C++ Library I/O Stream Classes

The object-oriented model for input and output (I/O) is a set of classes and header files that are provided by the Standard C++ Library. These classes implement and manage the stream buffers and the data held in the buffers. Stream buffers hold data sent to the program (input) and from the program (output), enabling the program to manipulate and format the data.

There are two base classes, `ios` and `streambuf`, from which all other I/O stream classes are derived. The `ios` class and its derivative classes are used to implement formatting of I/O and maintain error state information of stream buffers implemented with the `streambuf` class.

There are two shipped versions of the I/O stream classes:
- The UNIX Systems Laboratories C++ Language System Release (USL) I/O Stream Class Library
  - The UNIX Systems Laboratories C++ Language System Release (USL) I/O Stream Class Library is declared in the `iostream.h` header file. This version does not support ASCII and large files.
- The Standard C++ I/O stream classes
  - The Standard C++ I/O stream classes are declared in the `iostream` header file. This version supports ASCII and large files. For more detailed information on the I/O stream classes provided by the Standard C++ Library, see [LARGE_FILES] in z/OS XL C/C++ Language Reference.

The I/O stream classes use OBJECTMODEL(CLASSIC). They cannot be used with other classes that use OBJECTMODEL(IBM), within the same inheritance hierarchy. For more information, see [OBJECTMODEL] in z/OS XL C/C++ User’s Guide.

Advantages to using the C++ I/O stream classes

Although input and output are implemented with streams for both C and C++, the C++ I/O stream classes provide the same facilities for input and output as C `stdio.h`. The I/O stream classes in the Standard C++ Library have the following advantages:
- The input (`>>`) operator and output (`<<`) operator are typesafe. These operators are easier to use than `scanf()` and `printf()`.
- You can overload the input and output operators to define input and output for your own types and classes. This makes input and output across types, including your own, uniform.

Predefined streams for C++

z/OS XL C++ provides the following predefined streams:
- `cin` The standard input stream
- `cout` The standard output stream
- `cerr` The standard error stream, unit-buffered such that characters sent to this stream are flushed on each output operation
- `clog` The buffered error stream
All predefined streams are tied to cout. When you use cin, cerr, or clog, cout gets flushed sending the contents of cout to the ultimate consumer.

z/OS C standard streams create all I/O to I/O streams:

- Input to cin comes from stdin (unless cin is redirected)
- cout output goes to stdout (unless cout is redirected)
- cerr output goes to stderr (unit-buffered) (unless cerr is redirected)
- clog output goes to stderr (unless clog is redirected)

When redirecting or intercepting a C standard stream, the corresponding C++ standard stream becomes redirected. This applies unless you redirect an I/O stream. See Chapter 9, “Using C and C++ standard streams and redirection,” on page 63 for more information.

### How C++ I/O streams relate to C I/O streams

Typically, USL I/O Stream Class Library file I/O is implemented in terms of z/OS XL C file I/O, and is buffered from it.

**Note:** The only exception is that cerr is unit-buffered (that is, ios::unitbuf is set).

A filebuf object is associated with each ifstream, ofstream, and fstream object. When the filebuf is flushed, it writes to the underlying C stream, which has its own buffer. The filebuf object follows every fwrite() to the underlying C stream with an fflush().

### Mixing the Standard C++ I/O stream classes, USL I/O stream class library, and C I/O library functions

It is not recommended to mix the usage of the Standard C++ I/O stream classes, USL I/O Stream Class Library, and C I/O library functions.

The USL I/O stream class library uses a separate buffer, which means that you would need to flush the buffer after each call to cout either by setting ios::unitbuf or by calling sync_with_stdio().

You should avoid switching between the formatted extraction functions of the C++ I/O stream classes and C stdio library functions whenever possible. You should also avoid switching between versions of these classes.

For more information on mixing the I/O stream classes refer to “Interleaving the standard streams with sync_with_stdio()” on page 65 and “Interleaving the standard streams without sync_with_stdio()” on page 66.

### Specifying file attributes

The fstream, ifstream, and ofstream classes specialize stream input and output for files.

For z/OS XL C++, overloaded fstream, ifstream, and ofstream constructors, and open() member functions, with an additional parameter, are provided so you can specify z/OS XL C fopen() mode values. You can use this additional parameter to specify any z/OS XL C fopen() mode value except type=record or type=blocked. If
you choose to use a constructor without this additional parameter, you will get the default z/OS XL C fopen() file characteristics. Table 8 on page 35 describes the default fopen() characteristics.
Chapter 5. Opening files

This chapter describes how to open I/O files. You can open files using the Standard C fopen() and freopen() library functions. Alternatively, if you want to use the C++ I/O stream classes, you can use the constructors for the ifstream, ofstream or fstream classes, or the open() member functions of the filebuf, ifstream, ofstream or fstream classes.

To open a file stream with a previously opened z/OS UNIX file descriptor, use the fdopen() function.

To open files with UNIX file system low-level I/O, use the open() function. For more information about opening files in UNIX file system, see Chapter 11, "Performing z/OS UNIX file system I/O operations," on page 127.

Table 5 summarizes the prototypes of various functions. For more detailed information about the C I/O stream functions, see z/OS XL C/C++ Runtime Library Reference. For more detailed information about the C++ I/O stream classes, see Standard C++ Library Reference, which discusses the Standard C++ I/O stream classes.

Table 5. Summary of prototype functions

<table>
<thead>
<tr>
<th>Type of function</th>
<th>Prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>C Library Functions</td>
<td><code>FILE *fopen(const char *filename, const char *mode);</code></td>
</tr>
<tr>
<td></td>
<td><code>FILE *freopen(const char *filename, const char *mode, FILE *stream);</code></td>
</tr>
<tr>
<td></td>
<td><code>FILE *fdopen(int filedes, char *mode);</code></td>
</tr>
</tbody>
</table>
| USL I/O stream library functions | // ifstream constructor
<p>|                                  | ifstream(const char* fname, int mode=ios::in,                            |
|                                  |     int prot=filebuf::openprot);                                        |
|                                  | // ifstream constructor; z/OS C++ extension                              |
|                                  | ifstream(const char* fname, const char* fattr,                           |
|                                  |     int mode=ios::in, int prot=filebuf::openprot);                      |
|                                  | // ifstream::open()                                                      |
|                                  | void open(const char* fname, int mode=ios::in,                           |
|                                  |     int prot=filebuf::openprot);                                        |
|                                  | // z/OS C++ extension                                                    |
|                                  | void open(const char* fname, const char* fattr,                          |
|                                  |     int mode=ios::in, int prot=filebuf::openprot);                      |
|                                  | // ofstream constructor                                                  |
|                                  | ofstream(const char* fname, int mode=ios::out,                           |
|                                  |     int prot=filebuf::openprot);                                        |</p>
<table>
<thead>
<tr>
<th>Type of function</th>
<th>Prototype</th>
</tr>
</thead>
</table>
| USL I/O stream library functions (continued) | // ofstream constructor; z/OS C++ extension  
    ofstream(const char* fname, const char* fattr,  
    int mode=ios::out, int prot=filebuf::openprot);  
    // ofstream::open()  
    void open(const char* fname, int mode=ios::out,  
    int prot=filebuf::openprot);  
    // z/OS C++ extension  
    void open(const char* fname, const char* fattr,  
    int mode=ios::out, int prot=filebuf::openprot);  
    // fstream constructor  
    fstream(const char* fname, int mode,  
    int prot=filebuf::openprot);  
    // fstream constructor; z/OS C++ extension  
    fstream(const char* fname, const char* fattr,  
    int mode, int prot=filebuf::openprot);  
    // fstream::open()  
    void open(const char* fname, int mode,  
    int prot=filebuf::openprot);  
    // z/OS C++ extension  
    void open(const char* fname, const char* fattr,  
    int mode, int prot=filebuf::openprot);  
    // filebuf::open()  
    filebuf* open(const char* fname, int mode,  
    int prot=filebuf::openprot);  
    // z/OS C++ extension  
    filebuf* open(const char* fname, const char* fattr,  
    int mode, int prot=filebuf::openprot); |
| Standard C++ I/O stream functions      | // z/OS C++ Standard Library ifstream constructor  
    ifstream(const char *, ios_base::openmode, const char * _A)  
    // z/OS C++ Standard Library ifstream::open  
    void ifstream::open(const char *, ios_base::openmode, const char * _A)  
    void ifstream::open(const char *, ios_base::open_mode, const char * _A)  
    // z/OS C++ Standard Library ofstream constructor  
    ofstream(const char *, ios_base::openmode, const char * _A)  
    // z/OS C++ Standard Library ofstream::open  
    void ofstream::open(const char *, ios_base::openmode, const char * _A)  
    void ofstream::open(const char *, ios_base::open_mode, const char * _A)  
    // z/OS C++ Standard Library fstream constructor  
    fstream(const char *, ios_base::openmode, const char * _A)  
    // z/OS C++ Standard Library fstream::open  
    void fstream::open(const char *, ios_base::openmode, const char * _A)  
    void fstream::open(const char *, ios_base::open_mode, const char * _A)  
    // C++ Standard Library filebuf::open  
    filebuf::open(const char *, ios_base::openmode, const char * _A)  
    filebuf::open(const char *, ios_base::open_mode, const char * _A) |
Categories of I/O

Table 6 lists the categories of I/O that z/OS XL C/C++ supports and points to the section where each category is described.

**Note:** CICS Data Queues and z/OS Language Environment Message File do not apply in AMODE 64 applications. Hiperspace Memory Files are opened as (regular) Memory Files since the size of a (regular) Memory File can exceed 2GB in AMODE 64 applications.

Table 6. Kinds of I/O supported by z/OS XL C/C++

<table>
<thead>
<tr>
<th>Type of I/O</th>
<th>Suggested Uses and Supported Devices</th>
<th>Model</th>
<th>Detail</th>
</tr>
</thead>
<tbody>
<tr>
<td>OS I/O</td>
<td>Used for dealing with the following kinds of files: * Generation data group * MVS™ sequential DASD files * Regular and extended partitioned data sets * Tapes * Printers * Punch data sets * Card reader data sets * MVS inline JCL data sets * MVS spool data sets * Striped data sets * Optical readers</td>
<td>Record</td>
<td>Link</td>
</tr>
<tr>
<td>UNIX file system I/O</td>
<td>Used under z/OS UNIX System Services (z/OS UNIX) to support data sets in the UNIX file system, and access the byte-oriented UNIX file system files according to POSIX .1 and XPG 4.2 interfaces. This increases the portability of applications written on UNIX-based systems to z/OS XL C/C++ systems.</td>
<td>Byte stream</td>
<td>Link</td>
</tr>
<tr>
<td>VSAM I/O</td>
<td>Used for working with VSAM data sets. Supports direct access to records by key, relative record number, or relative byte address. Supports entry-sequenced, relative record, and key-sequenced data sets.</td>
<td>Record</td>
<td>Link</td>
</tr>
<tr>
<td>Terminal I/O</td>
<td>Used to perform interactive input and output operations with a terminal.</td>
<td>Record</td>
<td>Link</td>
</tr>
<tr>
<td>Memory Files</td>
<td>Used for applications requiring temporary I/O files without the overhead of system data sets. Fast and efficient.</td>
<td>Byte stream</td>
<td>Link</td>
</tr>
<tr>
<td>Hiperspace Memory Files</td>
<td>Used to deal with memory files as large as 2 gigabytes.</td>
<td>Byte stream</td>
<td>Link</td>
</tr>
<tr>
<td>CICS Data Queues</td>
<td>Used under the Customer Information Control System (CICS). CICS data queues are automatically selected under CICS for the standard streams std*out and std*err for C, or cout and cerr for C++. The CICS I/O commands are supported through the Command Level interface. The standard stream stdin under C (or cin under C++) is treated as an empty file under CICS.</td>
<td>Record</td>
<td>Link</td>
</tr>
<tr>
<td>z/OS Language Environment Message File</td>
<td>Used when you are running with z/OS Language Environment. The message file is automatically selected for std*err under z/OS Language Environment. For C++, automatic selection is of cerr.</td>
<td>Record</td>
<td>Link</td>
</tr>
</tbody>
</table>

Table 7 on page 30 lists the environments that z/OS XL C/C++ supports, and which categories of I/O work in which environment.
Table 7. I/O categories and environments that support them

<table>
<thead>
<tr>
<th>Type of I/O</th>
<th>MVS batch</th>
<th>IMS online</th>
<th>TSO</th>
<th>TSO batch</th>
<th>CICS</th>
</tr>
</thead>
<tbody>
<tr>
<td>OS I/O</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>UNIX file system I/O</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>VSAM I/O</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Terminal I/O</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Memory Files</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Hiperspace Memory Files</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>CICS Data Queues</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>z/OS Language Environment</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
</tbody>
</table>

Note: MVS batch includes IMS batch. TSO is interactive. TSO batch indicates an environment set up by a batch call to IKJEFT01. Programs run in such an environment behave more like a TSO interactive program than an MVS batch program.

Specifying what kind of file to use

This section discusses:
- the kinds of files you can use
- how to specify RECFM, LRECL, and BLKSIZE
- how to specify DDnames

OS files

*z/OS XL C/C++* treats a file as an OS file, provided that it is not a CICS data queue, or a UNIX file system, VSAM, memory, terminal, or Hiperspace file.

UNIX file system files

When you are running under MVS, TSO (batch and interactive), or IMS, *z/OS XL C/C++* recognizes a UNIX file system I/O file as such if the name specified on the `fopen()` or `freopen()` call conforms to certain rules. These rules are described in “How *z/OS XL C/C++* determines what kind of file to open” on page 37.

VSAM data sets

*z/OS XL C/C++* recognizes a VSAM data set if the file exists and has been defined as a VSAM cluster before the call to `fopen()`.

Terminal files

When you are running with the runtime option `POSIX(0FF)` under interactive TSO, *z/OS XL C/C++* associates streams to the terminal. You can also call `fopen()` to open the terminal directly if you are running under TSO (interactive or batch), and either the file name you specify begins with an asterisk (*), or the ddname has been allocated with a DSN of *.

When running with `POSIX(ON)`, *z/OS XL C/C++* associates streams to the terminal under TSO and a shell if the file name you have specified fits one of the following criteria:
- **Under TSO (interactive and batch)**, the name must begin with the sequence `//*`, or the ddname must have been allocated with a DSN of *.
• **Under a shell**, the name specified on `fopen()` or `freopen()` must be the character string returned by `ttyname()`.

Interactive IMS and CICS behave differently from what is described here. For more information about terminal files with interactive IMS and CICS see Chapter 9, “Using C and C++ standard streams and redirection,” on page 63.

If you are running with `POSIX(ON)` outside a shell, you must use the regular z/OS XL C/C++ I/O functions for terminal I/O. If you are running with `POSIX(ON)` from a shell, you can use the regular z/OS XL C/C++ I/O functions or the POSIX low-level functions (such as `read()`) for terminal I/O.

**Memory files and hiperspace memory files**

You can use regular memory files on all the systems that z/OS XL C/C++ supports. To create one, specify `type=memory` on the `fopen()` or `freopen()` call that creates the file. A memory file, once created, exists until either of the following happens:

- You explicitly remove it with `remove()` or `clrmemf()`
- The root program is terminated

While a memory file exists, you can just use another `fopen()` or `freopen()` that specifies the memory file's name. As sample program CCNGOF1 shows in Figure 3, you do not have to specify `type=memory`.

```c
/* this example shows how fopen() may be used with memory files */
#include <stdio.h>
char text[3], *result;
FILE * fp;
int main(void)
{
  fp = fopen("a.b", "w, type=memory"); /* Opens a memory file */
  fprintf(fp, "%d\n", 10); /* Writes to the file */
  fclose(fp); /* Closes the file */
  fp = fopen("a.b", "r"); /* Reopens the same */
  /* file (already */
  /* a memory file) */
  if ((result=fgets(text,3,fp)) !=NULL) /* Retrieves results */
    printf("value retrieved is %s\n",result);
  fclose(fp); /* Closes the file */
  return(0);
}
```

*Figure 3. Memory file example*

A valid memory file name will match current file restrictions on a real file. Thus, a memory file name that is classified as UNIX file system can have more characters than can one classified as an MVS file name.

If you are not running under CICS, you can open a Hiperspace memory file as follows:

```c
fp = fopen("a.b", "w, type=memory(hiperspace)");
```

If you specify `hiperspace` and you are running in a CICS environment, z/OS XL C/C++ opens a regular memory file. If you are running with the runtime options
POSIX(ON) and TRAP(OFF), specifying hiperspace has no effect; z/OS XL C/C++ will open a regular memory file. You must specify TRAP(ON) to be able to create Hiperspace files.

**Restriction:** Hiperspace is not supported in AMODE 64 applications. If you specify hiperspace in AMODE 64 applications, z/OS XL C/C++ opens a regular memory file.

### CICS data queues

A CICS transient data queue is a pathway to a single predefined destination. The destination can be a ddname, another transient data queue, a VSAM file, a terminal, or another CICS environment. The CICS system administrator defines the queues that are active during execution of CICS. All users who direct data to a given queue will be placing data in the same location, in order of occurrence.

You cannot use `fopen()` or `freopen()` to specify this kind of I/O. It is the category selected automatically when you call any ANSI functions that reference `stdout` and `stderr` under CICS. If you reference either of these in a C or C++ program under CICS, z/OS XL C/C++ attempts to open the CESO (stdout) or CESE (stderr) queue. If you want to write to any other queue, you should use the CICS-provided interface.

### z/OS Language Environment Message file

The z/OS Language Environment message file is managed by z/OS Language Environment and may not be directly opened or closed with `fopen()`, `freopen()` or `fclose()` within a C or C++ application. In z/OS Language Environment, output from `stderr` is directed to the z/OS Language Environment message file by default. You can use `freopen()` and `fclose()` to manage `stderr`, or you can redirect it to another destination. There are application writer interfaces (AWIs) that enable you to access the z/OS Language Environment message file directly. These are documented in z/OS Language Environment Programming Guide.


### How to specify RECFM, LRECL, and BLKSIZE

For OS files and terminal files, the values of RECFM, LRECL, and BLKSIZE are significant. When you open a file, z/OS XL C/C++ searches for the RECFM, LRECL, and BLKSIZE values in the following places:

1. The `fopen()` or `freopen()` statement that opens the file
2. The DD statement (described in “DDnames” on page 36)
3. The values set in the existing file
4. The default values for `fopen()` or `freopen()`.

When you call `fopen()` and specify a write mode (w, wb, w+, wb+, w+b) for an existing file, z/OS XL C/C++ uses the default values for `fopen()` if:

- the data set is opened by the data set name or
- the data set is opened by ddname and the DD statement does not have any attributes filled in.

These defaults are listed in Table 8 on page 35. To force z/OS XL C/C++ to use existing attributes when you are opening a file, specify `recfm=*` (or `recfm=+`) on the `fopen()` or `freopen()` call.
RECFM=* or RECFM=+ is valid only for existing DASD data sets. It is ignored in all other cases.

RECFM=+ is identical to RECFM=* with the following exceptions:

- If there is no record format for the existing DASD data set, the defaults are assigned as if the data set did not exist.
- When append mode is used, the fopen() fails.

Notes:
1. When specifying a ddname on fopen() or freopen() you should be aware of the following when opening the ddname using one of the write modes:
2. If the ddname is allocated to an already existing file and that ddname has not yet been opened, then the DD statement will not contain the recfm, lrecl, or blksize. That information is not filled in until the ddname is opened for the first time. If the first open uses one of the write modes (w, wb, w+, wb+, w+b) and recfm=* (or recfm=+) is not specified, then the existing file attributes are not considered. Therefore, since the DD statement has not yet been filled in, the fopen() defaults are used.
3. If the ddname is allocated at the same time the file is created, then the DD statement will contain the same recfm, lrecl, and blksize specified for the file. If the first open uses one of the write modes (w, wb, w+, wb+, w+b) and recfm=* (or recfm=+) is not specified, then z/OS XL C/C++ picks up the existing file attributes from the DD statement since they were placed there at the time of allocation.

You can specify the record format in
- The RECFM parameter of the JCL DD statement under MVS
- The RECFM parameter of the ALLOCATE statement under TSO
- The __recfm field of the __dyn_t structure passed to the dynalloc() library function under MVS
- The RECFM parameter on the call to the fopen() or freopen() library function
- The __S99TXTPP text unit field on an SVC99 parameter list passed to the svc99() library function under MVS
- The ISPF data set utility under MVS

Certain categories of I/O may ignore or simulate some attributes such as BLKSIZE or RECFM that are not physically supported on the device. Table 6 on page 29 lists all the categories of I/O that z/OS XL C/C++ supports and directs you to where you can find more information about them.

You can specify the logical record length in
- The LRECL parameter of the JCL DD statement under MVS
- The LRECL parameter of the ALLOCATE statement under TSO
- The __lrecl field of the __dyn_t structure passed to the dynalloc() library function under MVS
- The LRECL parameter on the call to the fopen() or freopen() library function
- The __S99TXTPP text unit field on an SVC99 parameter list passed to the svc99() library function under MVS
- The ISPF data set utility
If you are creating a file and do not select a record size, z/OS XL C/C++ uses a default. See "fopen() defaults" for details on how defaults are calculated.

You can specify the block size in:

- The BLKSIZE parameter of the JCL DD statement
- The BLKSIZE parameter of the ALLOCATE statement under TSO
- The __blksize field of the __dyn_t structure passed to the dynalloc() library function under MVS
- The BLKSIZE parameter on a call to the fopen() or freopen() library function
- The _S99TXTPP text unit field on an SVC99 parameter list passed to the svc99() library function under MVS
- The ISPF data set utility

If you are creating a file and do not select a block size, z/OS XL C/C++ uses a default. The defaults are listed in Table 8 on page 35.

**fopen() defaults**

You cannot specify a file attribute more than once on a call to fopen() or freopen(). If you do, the function call fails. If the file attributes specified on the call to fopen() differ from the actual file attributes, fopen() usually fails. However, fopen() does not fail if:

- The file is opened for w, w+, wb, or wb+, and the file is neither an existing PDS or PDSE nor an existing file opened by a ddname that specifies DISP=MOD. In such instances, fopen() attributes override the actual file attributes. However, if recfm=* (or recfm=*) is specified on the fopen(), any attributes that are not specified either on the fopen() or for the ddname will be retrieved from the existing file. If the final combination of attributes is invalid, the fopen() will fail.
- The file is opened for reading (r or rb) with recfm=U. Any other specified attributes should be compatible with those of the existing data set.

In calls to fopen(), the LRECL, BLKSIZE, and RECFM parameters are optional. (If you are opening a file for read or append, any attributes that you specify must match the existing attributes.)

If you do not specify file attributes for fopen() (or for an I/O stream object), you get the following defaults.

**RECFM defaults**

If recfm is not specified in a fopen() call for an output binary file, recfm defaults to:

- recfm=VB for spool (printer) files
- recfm=FB otherwise

If recfm is not specified in a fopen() call for an output text file, recfm defaults to:

- recfm=F if _EDC_ANSI_OPEN_DEFAULT is set to Y and no LRECL or BLKSIZE specified. In this case, LRECL and BLKSIZE are both defaulted to 254.
- recfm=VBA for spool (printer) files.
- recfm=U for terminal files.
- recfm=V for MVS files.
- recfm=V for all other OS files.
If recfm is not specified for a record I/O file, you will get the default of recfm=VB.

**LRECL and BLKSIZE defaults**

Table 8 shows the defaults for LRECL and BLKSIZE when z/OS XL C/C++ is creating a file, not appending or updating it. The table assumes that z/OS XL C/C++ has already processed any information from the fopen() statement or ddname. The defaults provide a basis for fopen() to select values for unspecified attributes when you create a file.

<table>
<thead>
<tr>
<th>lrecl specified?</th>
<th>blksize specified?</th>
<th>RECFM</th>
<th>LRECL</th>
<th>BLKSIZE</th>
</tr>
</thead>
<tbody>
<tr>
<td>no</td>
<td>no</td>
<td>All F</td>
<td>80</td>
<td>80</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All FB</td>
<td>80</td>
<td>maximum integral multiple of 80 less than or equal to max</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All V, VB, VS, or VBS</td>
<td>minimum of 1028 or max–4</td>
<td>max</td>
</tr>
<tr>
<td></td>
<td>yes</td>
<td>All U</td>
<td>0</td>
<td>max</td>
</tr>
<tr>
<td>yes</td>
<td>no</td>
<td>All F</td>
<td>lrecl</td>
<td>lrecl</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All FB</td>
<td>lrecl</td>
<td>maximum integral multiple of lrecl less than or equal to max</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All V</td>
<td>lrecl</td>
<td>lrecl+4</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All U</td>
<td>0</td>
<td>lrecl</td>
</tr>
<tr>
<td>no</td>
<td>yes</td>
<td>All F or FB</td>
<td>blksize</td>
<td>blksize</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All V, VB, VS, or VBS</td>
<td>minimum of 1028 or blksize–4</td>
<td>blksize</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All U</td>
<td>0</td>
<td>blksize</td>
</tr>
</tbody>
</table>

**Note:** “All” includes the standard (S) specifier for fixed formats, the ASA (A) specifier, and the machine control character (M) specifier.

In Table 8, the value max represents the maximum block size for the device. These are the current default maximum block sizes for several devices that z/OS XL C/C++ supports:

<table>
<thead>
<tr>
<th>Device</th>
<th>Block Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>DASD</td>
<td>6144</td>
</tr>
<tr>
<td>3203 Printer</td>
<td>132</td>
</tr>
<tr>
<td>3211 Printer</td>
<td>132</td>
</tr>
<tr>
<td>4245 Printer</td>
<td>132</td>
</tr>
<tr>
<td>2540 Reader</td>
<td>80</td>
</tr>
<tr>
<td>2540 Punch</td>
<td>80</td>
</tr>
<tr>
<td>2501 Reader</td>
<td>80</td>
</tr>
<tr>
<td>3890 Document Processor</td>
<td>80</td>
</tr>
<tr>
<td>TAPE</td>
<td>32760</td>
</tr>
</tbody>
</table>
For more information about specific default block sizes, refer to z/OS DFSMS Using Data Sets.

For DASD files that do not have recfm=U, if you specify blksize=0 on the call to fopen() or freopen(), the system determines the optimal block size for your file. If you do not have the correct level of DFP or you specify blksize=0 for a ddname instead of specifying it on the fopen() or freopen() call, z/OS XL C/C++ behaves as if you had not specified the blksize parameter at all.

For information about block sizes for different categories of I/O, see the chapters listed in Table 6 on page 29.

You do not have to specify the LRECL and BLKSIZE attributes; however, it is possible to have conflicting attributes when you do specify them. The restrictions are:

- For a V file, the LRECL must be greater than 4 bytes and must be at least 4 bytes smaller than the BLKSIZE.
- For an F file, the LRECL must be equal to the BLKSIZE, and must be at least 1.
- For an FB file, the BLKSIZE must be an integer multiple of the LRECL.
- For a U file, the LRECL must be less than or equal to the BLKSIZE and must be greater than or equal to 0. The BLKSIZE must be at least 1.
- In spanned files, the LRECL and the BLKSIZE attributes must be greater than 4.
- If you specify LRECL=X, the BLKSIZE attribute must be less than or equal to the maximum block size allowed on the device.

To determine the maximum LRECL and BLKSIZE values for the various file types and devices available on your operating system, refer to the chapters listed in Table 6 on page 29.

**DDnames**

DD names are specified by prefixing the DD name with “DD:”. All the following forms of the prefix are supported:

- DD:
- dd:
- dD:
- Dd:

The DD statement enables you to write C source programs that are independent of the files and input/output devices they will use. You can modify the parameters of a file (such as LRECL, BLKSIZE, and RECFM) or process different files without recompiling your program.

- How to create a DDname under MVS batch

To create a ddname under MVS batch, you must write a JCL DD statement. For the C file PARTS.INSTOCK, you would write a JCL DD statement similar to the following:

```c
//STOCK DD DSN=PARTS.INSTOCK, ...
```

UNIX file system files can be allocated with a DD card, as shown in the following example:

```c
//STOCK DD PATH="/u/parts.instock",
// PATHOPTS=(OWRONLY, OCREAT, OTRUNC),
// PATHMODE=(SIRWXU, SIRWXO, SIRWXG)
```
When defining DD, do not use \texttt{DD ... FREE=CLOSE} for unallocating DD statements. The C library may close files to perform some file operations such as \texttt{freopen()}, and the DD statement will be unallocated.

For more information on writing DD statements, refer to the JCL manuals listed in \textit{z/OS V2R2 Information Roadmap}.

- **How to create a Ddbname under TSO**
  
  To create a ddname under TSO, you must write an \texttt{ALLOCATE} command. For the declaration shown above for the C file \texttt{STOCK}, you should write a TSO \texttt{ALLOCATE} statement similar to the following:

  \begin{verbatim}
  ALLOCATE FILE(STOCK) DATASET('PARTS.INSTOCK')
  \end{verbatim}

  You can also allocate UNIX file system files with TSO \texttt{ALLOCATE} commands. For example:

  \begin{verbatim}
  ALLOC FILE(stock) PATH('/used/parts.stock') PATHOPTS(OWRONLY,OCREAT)
  PATHMODE(sirwxu,sirwxo,sirwxg)
  \end{verbatim}

  See \textit{z/OS V2R2 Information Roadmap} for more information on TSO \texttt{ALLOCATE}.

- **How to create a Ddbname in source code**
  
  You can also use the \texttt{z/OS XL C/C++} library functions \texttt{svc99()} and \texttt{dynalloc()} to allocate ddbnames. See \textit{z/OS XL C/C++ Runtime Library Reference} for more information about these functions.

You do not always need to describe the characteristics of the data in files both within the program and outside it. There are, in fact, advantages to describing the characteristics of your data in only one place.

Opening a file by ddname may require the merging of information internal and external to the program. If any conflict is detected that will prevent the opening of a file, \texttt{fopen()} returns a NULL pointer to indicate that the file cannot be opened. See \textit{z/OS XL C/C++ Runtime Library Reference} for more information on \texttt{fopen()}.

If \texttt{DISP=MOD} is specified on a DD statement and if the file is opened in \texttt{w} or \texttt{wb} mode, the \texttt{DISP=MOD} causes the file to be opened in append mode rather than in write mode.

\textbf{Note}: You can open a ddname only with \texttt{fopen()} or \texttt{freopen()}. \texttt{open()} does not interpret ddbnames as such.

---

**Avoiding Undesirable Results when Using I/O**

File serialization is not provided for different tasks attempting to access the same file. When a C/C++ application is run on one task, and the same application or another C/C++ application is run on a different task, any attempts for both applications to access the same file is the responsibility of the application.

---

**How z/OS XL C/C++ determines what kind of file to open**

This section describes the criteria that \texttt{z/OS XL C/C++} uses to determine what kind of file it is opening. \texttt{z/OS XL C/C++} goes through the categories listed in \textit{Table 6 on page 29} in the order that follows. If a category applies to a file, \texttt{z/OS XL C/C++} stops searching.

\textbf{Note}: Files cannot be opened under CICS when you have specified the \texttt{POSIX(ON)} runtime option.
"Under TSO, MVS batch, IMS — POSIX(ON)" shows how z/OS XL C/C++ determines what type of file to open under TSO, MVS batch, and interactive IMS with POSIX(ON). For information on the types of files shown in the chart, see the appropriate chapter in the I/O section.

"Under TSO, MVS batch, IMS — POSIX(OFF)" on page 41 shows how z/OS XL C/C++ determines what type of file to open under TSO, MVS batch, and interactive IMS with POSIX(OFF). For information on the types of files shown in the chart, see the appropriate chapter in the I/O section.

"Under CICS" on page 43 shows how z/OS XL C/C++ determines what type of file to open under CICS. For information on the types of files shown in the chart, see the appropriate chapter in the I/O section.

### Under TSO, MVS batch, IMS — POSIX(ON)

#### Procedure

1. Is type=memory specified?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 2</td>
</tr>
<tr>
<td>No</td>
<td>See 5</td>
</tr>
</tbody>
</table>

2. Is hiperspace specified?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 3</td>
</tr>
<tr>
<td>No</td>
<td>See 4</td>
</tr>
</tbody>
</table>

3. a. z/OS XL C/C++ opens a memory file in Hiperspace.

4. a. z/OS XL C/C++ opens a regular memory file.

5. Does the name begin with // but NOT ///?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 6</td>
</tr>
<tr>
<td>No</td>
<td>See 7</td>
</tr>
</tbody>
</table>

6. a. Continue at 8

7. a. Continue at 17 on page 39

8. Is the next character an asterisk?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 9</td>
</tr>
<tr>
<td>No</td>
<td>See 12 on page 39</td>
</tr>
</tbody>
</table>

9. Are you running under TSO interactive?
10.  
   a.  z/OS XL C/C++ opens a terminal file.

11.  
   a.  z/OS XL C/C++ removes the asterisk from the name unless the asterisk is the only character, and proceeds to \[28 \text{ on page 40}\]

12.  Is name of form DDname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 13</td>
</tr>
<tr>
<td>No</td>
<td>See 14</td>
</tr>
</tbody>
</table>

13.  
   a.  Continue to \[29 \text{ on page 40}\]

14.  Does the name specified match that of an existing memory file?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 15</td>
</tr>
<tr>
<td>No</td>
<td>See 16</td>
</tr>
</tbody>
</table>

15.  
   a.  z/OS XL C/C++ opens the existing memory file.

16.  
   a.  z/OS XL C/C++ opens an OS file.

17.  Is the name of the form +DD:ddname or DD:ddname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 18</td>
</tr>
<tr>
<td>No</td>
<td>See 25 \text{ on page 40}</td>
</tr>
</tbody>
</table>

18.  Does ddname exist?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 19</td>
</tr>
<tr>
<td>No</td>
<td>See 22 \text{ on page 40}</td>
</tr>
</tbody>
</table>

19.  Is a path specified in ddname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 20</td>
</tr>
<tr>
<td>No</td>
<td>See 21</td>
</tr>
</tbody>
</table>

20.  
   a.  z/OS XL C/C++ opens a UNIX file system file.

21.  
   a.  z/OS XL C/C++ opens an OS file.
22. Does a memory file exist?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 23</td>
</tr>
<tr>
<td>No</td>
<td>See 24</td>
</tr>
</tbody>
</table>

23. 

a. z/OS XL C/C++ opens the existing memory file.

24. 

a. z/OS XL C/C++ opens a UNIX file system file called either *DD:ddname or DD:ddname.

25. Does the name specified match that of an existing memory file?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 26</td>
</tr>
<tr>
<td>No</td>
<td>See 27</td>
</tr>
</tbody>
</table>

26. 

a. z/OS XL C/C++ opens the existing memory file.

27. 

a. z/OS XL C/C++ opens a UNIX file system file.

28. Is the name of the form *DD:ddname or DD:ddname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 29</td>
</tr>
<tr>
<td>No</td>
<td>See 36 on page 41</td>
</tr>
</tbody>
</table>

29. Does ddname exist?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 30</td>
</tr>
<tr>
<td>No</td>
<td>See 33</td>
</tr>
</tbody>
</table>

30. Is a path specified in ddname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 31</td>
</tr>
<tr>
<td>No</td>
<td>See 32</td>
</tr>
</tbody>
</table>

31. 

a. z/OS XL C/C++ opens a UNIX file system file.

32. 

a. z/OS XL C/C++ opens an OS file.

33. Does a memory file exist?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 34 on page 41</td>
</tr>
<tr>
<td>No</td>
<td>See 35 on page 41</td>
</tr>
</tbody>
</table>
34.  
   a. z/OS XL C/C++ opens the existing memory file.

35.  
   a. ***ERROR***

36. Does the name specified match that of an existing memory file?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 37</td>
</tr>
<tr>
<td>No</td>
<td>See 38</td>
</tr>
</tbody>
</table>

37.  
   a. z/OS XL C/C++ opens the existing memory file.

38.  
   a. z/OS XL C/C++ opens an OS file.

**Under TSO, MVS batch, IMS — POSIX(OFF)**

**Procedure**

1. Is type=memory specified?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 2</td>
</tr>
<tr>
<td>No</td>
<td>See 5</td>
</tr>
</tbody>
</table>

2. Is h1perspace specified?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 3</td>
</tr>
<tr>
<td>No</td>
<td>See 4</td>
</tr>
</tbody>
</table>

3.  
   a. z/OS XL C/C++ opens a memory file in Hiperspace.

4.  
   a. z/OS XL C/C++ opens a regular memory file.

5. Does the name begin with // but NOT ///?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 6</td>
</tr>
<tr>
<td>No</td>
<td>See 7</td>
</tr>
</tbody>
</table>

6.  
   a. Continue at 8

7.  
   a. Continue at 17 on page 42

8. Is the next character an asterisk?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 9 on page 42</td>
</tr>
<tr>
<td>No</td>
<td>See 12 on page 42</td>
</tr>
</tbody>
</table>
9. Are you running under TSO interactive?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 10</td>
</tr>
<tr>
<td>No</td>
<td>See 11</td>
</tr>
</tbody>
</table>

10. a. z/OS XL C/C++ opens a terminal file.

11. a. z/OS XL C/C++ removes the asterisk from the name unless the asterisk is the only character, and proceeds to 17.

12. Is name of form DDname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 13</td>
</tr>
<tr>
<td>No</td>
<td>See 14</td>
</tr>
</tbody>
</table>


14. Does the name specified match that of an existing memory file?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 15</td>
</tr>
<tr>
<td>No</td>
<td>See 16</td>
</tr>
</tbody>
</table>

15. a. z/OS XL C/C++ opens the existing memory file.

16. a. z/OS XL C/C++ opens an OS file.

17. Is the name of the form *DD:ddname or DD:ddname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 18</td>
</tr>
<tr>
<td>No</td>
<td>See 25 on page 43</td>
</tr>
</tbody>
</table>

18. Does ddname exist?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 19</td>
</tr>
<tr>
<td>No</td>
<td>See 22 on page 43</td>
</tr>
</tbody>
</table>

19. Is a path specified in ddname?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 20</td>
</tr>
<tr>
<td>No</td>
<td>See 21 on page 43</td>
</tr>
</tbody>
</table>

20. a. z/OS XL C/C++ opens a UNIX file system file.
21.  
   a.  z/OS XL C/C++ opens an OS file.

22.  Does a memory file exist?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 23</td>
</tr>
<tr>
<td>No</td>
<td>See 24</td>
</tr>
</tbody>
</table>

23.  
   a.  z/OS XL C/C++ opens the existing memory file.

24.  
   a.  ***ERROR***

25.  Does the name specified match that of an existing memory file?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 26</td>
</tr>
<tr>
<td>No</td>
<td>See 27</td>
</tr>
</tbody>
</table>

26.  
   a.  z/OS XL C/C++ opens the existing memory file.

27.  
   a.  z/OS XL C/C++ opens an OS file.

**Under CICS**

**Procedure**

1.  Is `type=memory` specified?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 2</td>
</tr>
<tr>
<td>No</td>
<td>See 5</td>
</tr>
</tbody>
</table>

2.  Is `hiperspace` specified?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 3</td>
</tr>
<tr>
<td>No</td>
<td>See 4</td>
</tr>
</tbody>
</table>

3.  The `fopen()` call ignores the `hiperspace` specification and opens the memory file. See 8 on page 44

4.  
   a.  z/OS XL C/C++ opens the specified memory file.

5.  Does the name specified match that of an existing memory file?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 6</td>
</tr>
<tr>
<td>No</td>
<td>See 7 on page 44</td>
</tr>
</tbody>
</table>

6.  
   a.  z/OS XL C/C++ opens that memory file.
7. The fopen() call fails. See 8
8. End
Chapter 6. Buffering of C streams

This chapter describes buffering modes used by z/OS XL C/C++ library functions available to control buffering and methods of flushing buffers.

z/OS XL C/C++ uses buffers to map C I/O to system-level I/O. When z/OS XL C/C++ performs I/O operations, it uses one of the following buffering modes:

- **Line buffering** - characters are transmitted to the system as a block when a new-line character is encountered. Line buffering is meaningful only for text streams and UNIX file system files.
- **Full buffering** - characters are transmitted to the system as a block when a buffer is filled.
- **No buffering** - characters are transmitted to the system as they are written. Only regular memory files and UNIX file system files support the no buffering mode.

The buffer mode affects the way the buffer is flushed. You can use the `setvbuf()` and `setbuf()` library functions to control buffering, but you cannot change the buffering mode after an I/O operation has used the buffer, as all read, write, and reposition operations do. In some circumstances, repositioning alters the contents of the buffer. It is strongly recommended that you only use `setbuf()` and `setvbuf()` before any I/O, to conform with ANSI, and to avoid any dependency on the current implementation. If you use `setvbuf()`, z/OS XL C/C++ may or may not accept your buffer for its internal use. For a hiperspace memory file, if the size of the buffer specified to `setvbuf()` is 8K or more, it will affect the number of hiperspace blocks read or written on each call to the operating system; the size is rounded down to the nearest multiple of 4K.

Full buffering is the default except in the following cases:

- If you are using an interactive terminal, z/OS XL C/C++ uses line buffering.
- If you are using a memory file, z/OS XL C/C++ does not use any buffering.
- **stderr** is line-buffered by default.

For terminals, because I/O is always unblocked, line buffering is equivalent to full buffering.

For record I/O files, buffering is meaningful only for blocked files or for record I/O files in z/OS UNIX file system using full buffering. For unblocked files, the buffer is full after every write and is therefore written immediately, leaving nothing to flush. For blocked files or fully-buffered UNIX file system files, however, the buffer can contain one or more records that have not been flushed and that require a flush operation for them to go to the system.

For blocked I/O files, buffering is always meaningless.

You can flush buffers to the system in several different ways:

- If you are using full buffering, z/OS XL C/C++ automatically flushes a buffer when it is filled.
- If you are using line buffering for a text file or a UNIX file system file, z/OS XL C/C++ flushes a buffer when you complete it with a control character. Except
for UNIX file system files, specifying line buffering for a record I/O, blocked
I/O, or binary file has no effect; z/OS XL C/C++ treats the file as if you had
specified full buffering.

- z/OS XL C/C++ flushes buffers to the system when you close a file or end a
  program.
- z/OS XL C/C++ flushes buffers to the system when you call the fflush()
  library function, with the following restrictions:
  - A file opened in text mode does not flush data if a record has not been
    completed with a new-line.
  - A file opened in fixed format does not flush incomplete records to the file.
  - An FBS file does not flush out a short block unless it is a DISK file opened
    without the NOSEEK parameter.
- All streams are flushed across non-POSIX system() calls. Streams are not
  flushed across POSIX system() calls. For a POSIX system call, we recommend that you
do a fflush() before the system() call.

If you are reading a record that another user is writing to at the same time, you
can see the new data if you call fflush() to refresh the contents of the input
buffer.

Note: This is not supported for VSAM files.

You may not see output if a program that is using input and output fails, and the
error handling routines cannot close all the open files.
Chapter 7. Using ASA text files

This chapter describes the American Standards Association (ASA) text files, the control characters used in ASA files, how z/OS XL C/C++ translates the control characters, and how z/OS XL C/C++ treats ASA files during input and output.

The first column of each record in an ASA file contains a control character (‘ ’, ‘0’, ‘-’, ‘1’, or ‘+’) when it appears in the external medium.

z/OS XL C/C++ translates control characters in ASA files opened for text processing (r, w, a, r+, w+, a+ functions). On input, z/OS XL C/C++ translates ASA characters to sequences of control characters, as shown in Table 9. On output, z/OS XL C/C++ performs the reverse translation. The following sequences of control characters are translated, and the resultant ASA character becomes the first character of the following record.

Table 9. C control to ASA characters translation table

<table>
<thead>
<tr>
<th>C Control Character Sequence</th>
<th>ASA Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\n</td>
<td>‘ ’</td>
<td>skip one line</td>
</tr>
<tr>
<td>\n\n</td>
<td>‘0’</td>
<td>skip two lines</td>
</tr>
<tr>
<td>\n\n\n</td>
<td>‘-’</td>
<td>skip three lines</td>
</tr>
<tr>
<td>\f</td>
<td>‘1’</td>
<td>new page</td>
</tr>
<tr>
<td>\r</td>
<td>‘+’</td>
<td>overstrike</td>
</tr>
</tbody>
</table>

If you are writing to the first record or byte of the file and the output data does not start with a translatable sequence of C control characters, the ‘ ’ ASA control character is written to the file before the specified data.

z/OS XL C/C++ does not translate or verify control characters when you open an ASA file for binary, record I/O, or blocked I/O.

Example of writing to an ASA file

Sample program CCNGAS1, shown in Figure 4 on page 48 demonstrates how a program can write to an ASA file.
The program writes five records to the file `asa.file`, as follows. Note that the last record is 9034. The last single '
' does not create a record with a single control character (' '). If this same file is opened for read, and the `getc()` function is called to read the file 1 byte at a time, the same characters as those that were written out by `fputs()` in the first program are read.

```
0abcdef
+345

9034
```

ASA file control

ASA files are treated as follows:

- If the first record written does not begin with a control character, then a single new-line is written and then followed by data; that is, the ASA character defaults to a space when none is specified.
- In ASA files, control characters are treated the same way that they are treated in other text files, with the following exceptions (see Table 9 on page 47 for more information):

  - `` — **form feed**
    
    Defines a record boundary and determines the ASA character of the following record.

  - `
` — **new-line**
    
    Does either of these:
    
    - Define a record boundary and determines the ASA character of the following record.
    - Modify the preceding ASA character if the current position is directly after an ASA character of `' ' or `0'.

Figure 4. ASA Example

The program writes five records to the file `asa.file`, as follows. Note that the last record is 9034. The last single '
' does not create a record with a single control character (' '). If this same file is opened for read, and the `getc()` function is called to read the file 1 byte at a time, the same characters as those that were written out by `fputs()` in the first program are read.

```
0abcdef
+345

9034
```
'\r' — carriage return

Defines a record boundary and determines the ASA character of the
following record.

- Records are terminated by writing a new-line ('\n'), carriage return ('\r'), or
form feed ('\f') character.
- An ASA character can be updated to any other ASA character.

Updates made to any of the C control characters that make up an ASA character
cause the ASA character to change.

If the file is positioned directly after a ' ' or '0' ASA character, writing a '\n'
character changes the ASA character to a '0' or '-' respectively. However, if the
ASA character is a '-', '1' or '+', the '\n' truncates the record (that is, it adds blank
padding to the end of the record), and causes the following record's ASA
character to be written as a '. Writing a '\f' or '\r' terminates the record and
start a new one, but writing a normal data character simply overwrites the first
data character of the record.

- You cannot overwrite the ASA character with a normal data character. The
position at the start of a record (at the ASA character) is the logical end of the
previous record. If you write normal data there, you are writing to the end of
the previous record. z/OS XL C/C++ truncates data for the following files,
except when they are standard streams:
  - Variable-format files
  - Undefined-format files
  - Fixed-format files in which the previous record is full of data

When truncation occurs, z/OS XL C/C++ raises SIGIOERR and sets both errno
and the error flag.

- Even when you update an ASA control character, seeking to a previously
recorded position still succeeds. If the recorded position was at a control
character that no longer exists (because of an update), the reposition is to the
next character. Often, this is the first data character of the record.

For example, if you have the following string, you have saved the position of
the third new-line:

```
\n\n\nHELLO WORLD
```

```c
x = ftell()
```

If you then update the ASA character to a form feed ('\f'), the logical ASA
position x no longer exists:

```
\fHELLO WORLD
```

If you call fseek() with the logical position x, it repositions to the next valid
character, which is the letter 'H':

```
\fHELLO WORLD
```

```c
ftell() to pos x
```
If you try to shorten a record when you are updating it, z/OS XL C/C++ adds enough blank padding to fill the record.

- The ASA character can represent up to three new-lines, which can increase the logical record length by 1 or 2 bytes.
- Extending a fixed logical record on update implies that the logical end of the line follows the last written non-blank character.
- If an undefined text record is updated, the length of the physical records does not change. If the replacement record is:
  - Longer - data characters beyond the record boundary are truncated. At the point of truncation, the User error flag is set and SIGIOERR is raised (if the signal is not set up to be ignored). Truncation continues until you do one of these:
    1. Write a new-line character, carriage return, or form feed to complete the current record
    2. Close the file explicitly or implicitly at termination
    3. Reposition to another position in the file.
  - Shorter - the blank character is used to overwrite the rest of the record.
- If you close an ASA file that has a new-line as its last character, z/OS XL C/C++ does not write the new-line to the physical file. The next time you read from the file or update it, z/OS XL C/C++ returns the new-line to the end of the file. An exception to this rule happens when you write only a new-line to a new file. In this case, z/OS XL C/C++ does not truncate the new-line; it writes a single blank to the file. On input, however, you will read two new-lines.
- Using ASA format to read a file that contains zero-length records results in undefined behavior.
- You may have trouble updating a file if two ASA characters are next to each other in the file. For example, if there is a single-byte record (containing only an ASA character) immediately followed by the ASA character of the next record, you are positioned at or within the first ASA character. If you then write a sequence of '\n' characters intended to update both ASA characters, the '\n's will be absorbed by the first ASA character before overflowing to the next record. This absorption may affect the crossing of record boundaries and cause truncation or corruption of data.

At least one normal intervening data character (for example, a space) is required between '\n' and '\n' to differentiate record boundaries.

**Note:** Be careful when you update an ASA file with data containing more than one consecutive new-line: the result of the update depends on how the original ASA records were structured.

- If you are writing data to a non-blocked file without intervening flush or reposition requests, each record is written to the system on completion (that is, when a '\n', '\r' or '\f' character is written or when the file is closed).
  - If you are writing data to a blocked file without intervening flush or reposition requests, and the file is opened in full buffering mode, the block is written to the system on completion of the record that fills the block. If the blocked file is line buffered, each record is written to the system on completion.
  - If you are writing data to a spanned file without intervening flush or reposition requests, and the record spans multiple blocks, each block is written to the system once it is full and the user writes an additional byte of data.
- If a flush occurs while an ASA character indicating more than one new-line is being updated, the remaining new-lines will be discarded and a read will
continue at the first data character. For example, if '\n\n\n' is updated to be '\n\n' and a flush occurs, then a '0' will be written out in the ASA character position.
Chapter 8. z/OS XL C Support for the double-byte character set

The number of characters in some languages such as Japanese or Korean is larger than 256, the number of distinct values that can be encoded in a single byte. The characters in such languages are represented in computers by a sequence of bytes, and are called multibyte characters. This chapter explains how the z/OS XL C compiler supports multibyte characters.

Note: The z/OS XL C++ compiler does not have native support for multibyte characters. The support described here is what z/OS XL C provides; for C++, you can take advantage of this support by using interlanguage calls to C code. Please refer to Chapter 19, “Using Linkage Specifications in C or C++,” on page 239 for more information.

The z/OS XL C compiler supports the IBM EBCDIC encoding of multibyte characters, in which each natural language character is uniquely represented by one to four bytes. The number of bytes that encode a single character depends on the global shift state information. If a stream is in initial shift state, one multibyte character is represented by a byte or sequence of bytes that has the following characteristics:

- It starts with the byte containing the shift-out (0x0e) character.
- The shift-out character is followed by 2 bytes that encode the value of the character.
- These bytes may be followed by a byte containing the shift-in (0x0f) character.

If the sequence of bytes ends with the shift-in character, the state remains initial, making this sequence represent a 4-byte multibyte character. Multibyte characters of various lengths can be normalized by the set of z/OS XL C library functions and encoded in units of one length. Such normalized characters are called wide characters; in z/OS XL C they are represented by two bytes. Conversions between multibyte format and wide character format can be performed by string conversion functions such as wcsrtombs(), mbstowcs(), wcrtombs(), and mbrtowcs(), as well by the family of the wide character I/O functions. MB_CUR_MAX is defined in the stdlib.h header file. Depending on its value, either of the following happens:

- When MB_CUR_MAX is 1, all bytes are considered single-byte characters; shift-out and shift-in characters are treated as data as well.
- When MB_CUR_MAX is 4:
  - On input, the wide character I/O functions read the multibyte character from the streams, and convert them to the wide characters.
  - On output, they convert wide characters to multibyte characters and write them to the output streams.

Both binary and text streams have orientation. Streams opened with type=record or type=blocked do not. There are three possible orientations of a stream:

Non-oriented
A stream that has been associated with an open file before any I/O operation is performed. The first I/O operation on a non-oriented stream will set the orientation of the stream. The fwide() function may be used to set the orientation of a stream before any I/O operation is performed. You
can use the setbuf() and setvbuf() functions only when I/O has not yet been performed on a stream. When you use these functions, the orientation of the stream is not affected. When you perform one of the wide character input/output operations on a non-oriented stream, the stream becomes wide-oriented. When you perform one of the byte input/output operations on a non-oriented stream, the stream becomes byte-oriented.

Wide-oriented
A stream on which any wide character input/output functions are guaranteed to operate correctly. Conceptually, wide-oriented streams are sequences of wide characters. The external file associated with a wide-oriented stream is a sequence of multibyte characters. Using byte I/O functions on a wide-oriented stream results in undefined behavior. A stream opened for record I/O or blocked I/O cannot be wide-oriented.

Byte-oriented
A stream on which any byte input/output functions are guaranteed to operate properly. Using wide character I/O functions on a byte input/output stream results in undefined behavior. Byte-oriented streams have minimal support for multibyte characters.

Calls to the clearerr(), feof(), ferror(), fflush(), fgetpos(), or ftell() functions do not change the orientation. Other functions that do not change the orientation are ftello(), fsetpos(), fseek(), fseeko(), rewind(), fldata(), and fileno(). Also, the perror() function does not affect the orientation of the stderr stream.

Once you have established a stream's orientation, the only way to change it is to make a successful call to the freopen() function, which removes a stream's orientation.

The wchar.h header file declares the WEOF macro and the functions that support wide character input and output. The macro expands to a constant expression of type wint_t. Certain functions return WEOF type when the end-of-file is reached on the stream.

Note: The behavior of the wide character I/O functions is affected by the LC_CTYPE category of the current locale, and the setting of MB_CUR_MAX. Wide-character input and output should be performed under the same LC_CTYPE setting. If you change the setting between when you read from a file and when you write to it, or vice versa, you may get undefined behavior. If you change it back to the original setting, however, you will get the behavior that is documented. See the introduction of this chapter for a discussion of the effects of MB_CUR_MAX.

Opening files
You can use the fopen() or freopen() library functions to open I/O files that contain multibyte characters. You do not need to specify any special parameters on these functions for wide character I/O.

Reading streams and files
Wide character input functions read multibyte characters from the stream and convert them to wide characters. The conversion process is performed in the same way that the mbtowc() function performs conversions. The following z/OS XL C library functions support wide character input:

- fgetwc()
In addition, the following byte-oriented functions support handling multibyte characters by providing conversion specifiers to handle the wchar_t data type:

- fscanf()
- scanf()
- vfscanf()
- vscanf()

All other byte-oriented input functions treat input as single-byte.

For a detailed description of unformatted and formatted I/O functions, see z/OS XL C/C++ Runtime Library Reference.

The wide-character input/output functions maintain global shift state for multibyte character streams they read or write. For each multibyte character they read, wide-character input functions change global shift state as the mbtowc() function would do. Similarly, for each multibyte character they write, wide-character output functions change global shift state as the wcrtomb() function would do.

When you are using wide-oriented input functions, multibyte characters are converted to wide characters according to the current shift state. Invalid double-byte character sequences cause conversion errors on input. As z/OS XL C uses wide-oriented functions to read a stream, it updates the shift state when it encounters shift-out and shift-in characters. Wide-oriented functions always read complete multibyte characters. Byte-oriented functions do not check for complete multibyte characters, nor do they maintain information about the shift state. Therefore, they should not be used to read multibyte streams.

For binary streams, no validation is performed to ensure that records start or end in initial shift state. For text streams, however, all records must start and end in initial shift state.
Writing streams and files

Wide character output functions convert wide characters to multibyte characters and write the result to the stream. The conversion process is performed in the same way that the `wcrtomb()` function performs conversions.

The following z/OS XL C functions support wide character output:
- `fputwc()`
- `fputwc_unlocked()`
- `fputws()`
- `fputws_unlocked()`
- `fwprintf()`
- `fwprintf_unlocked()`
- `putwc()`
- `putwc_unlocked()`
- `putwchar()`
- `putwchar_unlocked()`
- `vfwprintf()`
- `vfwprintf_unlocked()`
- `vwprintf()`
- `vwprintf_unlocked()`
- `wprintf()`
- `wprintf_unlocked()`

In addition, the following byte-oriented functions support handling multibyte characters by providing conversion specifiers to handle the `wchar_t` data type:
- `fprintf()`
- `fprintf_unlocked()`
- `printf()`
- `printf_unlocked()`
- `vfprintf()`
- `vfprintf_unlocked()`
- `vprintf()`
- `vprintf_unlocked()`

All other output functions do not support the `wchar_t` data type. However, all of the output functions support multibyte character output for text streams if `MB_CUR_MAX` is 4.

For a detailed description of unformatted and formatted I/O functions, see z/OS XL C/C++ Runtime Library Reference.

Writing text streams

When you are using wide-oriented output functions, wide characters are converted to multibyte characters. For text streams, all records must start and end in initial shift state. The wide-character functions add shift-out and shift-in characters as they are needed. When the file is closed, a shift-out character may be added to complete the file in initial shift state.
When you are using byte-oriented functions to write out multibyte data, z/OS XL C starts each record in initial shift state and makes sure you complete each record in initial shift state before moving to the next record. When a string starts with a shift-out, all data written is treated as multibyte, not single-byte. This means that you cannot write a single-byte control character (such as a new-line) until you complete the multibyte string with a shift-in character.

Attempting to write a second shift-out character before a shift-in is not allowed. z/OS XL C truncates the second shift-out and raises SIGIOERR if SIGIOERR is not set to SIG_IGN.

When you write a shift-in character to an incomplete multibyte character, z/OS XL C completes the multibyte character with a padding character (0xfe) before it writes the shift-in. The padding character is not counted as an output character in the total returned by the output function; you will never get a return code indicating that you wrote more characters than you provided. If z/OS XL C adds a padding character, however, it does raise SIGIOERR, if SIGIOERR is not set to SIG_IGN.

Control characters written before the shift-in are treated as multibyte data and are not interpreted or validated.

When you close the file, z/OS XL C ensures that the file ends in initial shift state. This may require adding a shift-in and possibly a padding character to complete the last multibyte character, if it is not already complete. If padding is needed in this case, z/OS XL C does not raise SIGIOERR.

Multibyte characters are never split across record boundaries. In addition, all records end and start in initial shift state. When a shift-out is written to the file, either directly or indirectly by wide-oriented functions, z/OS XL C calculates the maximum number of complete multibyte characters that can be contained in the record with the accompanying shift-in. If multibyte output (including any required shift-out and shift-in characters) does not fit within the current record, the behavior depends on what type of file it is (a memory file has no record boundaries and so never has this particular problem). For a standard stream or terminal file, data is wrapped from one record to the next. Shift characters may be added to ensure that the first record ends in initial shift state and that the second record starts in the required shift state.

For files that are not standard streams, terminal files, or memory files, any attempt to write data that does not fit into the current record results in data truncation. In such a case, the output function returns an error code, raises SIGIOERR, and sets errno and the error flag. Truncation continues until initial state is reached and a new-line is written to the file. An entire multibyte stream may be truncated, including the shift-out and shift-in, if there are not at least two bytes in the record. For a wide-oriented stream, truncation stops when a wchar_t new-line character is written out.

Updating a wide-oriented file or a file containing multibyte characters is strongly discouraged, because your update may overwrite part of a multibyte string or character, thereby invalidating subsequent data. For example, you could inadvertently add data that overwrites a shift-out. The data after the shift-out is meaningless when it is treated in initial shift state. Appending new data to the end of the file is safe.
Writing binary streams

When you are using wide-oriented output functions, wide characters are converted
to multibyte characters. No validation is performed to ensure that records start or
end in initial shift state. When the file is closed, any appends are completed with a
shift-in character, if it is needed to end the stream in initial shift state. If you are
updating a record when the stream is closed, the stream is flushed. See "Flushing
buffers" for more information.

Byte-oriented output functions do not interpret binary data. If you use them for
writing multibyte data, ensure that your data is correct and ends in initial shift
state.

Updating a wide-oriented file or a file containing multibyte characters is strongly
discouraged, because your update may overwrite part of a multibyte string or
character, thereby invalidating subsequent data. For example, you could
inadvertently add data that overwrites a shift-out. The data after the shift-out is
meaningless when it is treated in initial shift state. Appending new data to the end
of the file is safe for a wide-oriented file.

If you update a record after you call fgetpos(), the shift state may change. Using
the fpos_t value with the fsetpos() function may cause the shift state to be set
incorrectly.

Flushing buffers

You can use the library function fflush() to flush streams to the system. For more
information about fflush(), see the z/OS XL C/C++ Runtime Library Reference.

The action taken by the fflush() library function depends on the buffering mode
associated with the stream and the type of stream. If you call one z/OS XL C
program from another z/OS XL C program by using the ANSI system() function,
all open streams are flushed before control is passed to the callee. A call to the
POSIX system() function does not flush any streams to the system. For a POSIX
system call, we recommend that you do a fflush() before the system call.

Flushing text streams

When you call fflush() after updating a text stream, fflush() calculates your
current shift state. If you are not in initial shift state, z/OS XL C looks forward in
the record to see whether a shift-in character occurs before the end of the record or
any shift-out. If not, z/OS XL C adds a shift-in to the data if it will not overwrite a
shift-out character. The shift-in is placed such that there are complete multibyte
characters between it and the shift-out that took the data out of initial state. z/OS
XL C may accomplish this by skipping over the next byte in order to leave an even
number of bytes between the shift-out and the added shift-in.

Updating a wide-oriented or byte-oriented multibyte stream is strongly
discouraged. In a byte-oriented stream, you may have written only half of a
multibyte character when you call fflush(). In such a case, z/OS XL C adds a
padding byte before the shift-out. For both wide-oriented and byte-oriented
streams, the addition of any shift or padding character does not move the current
file position.

Calling fflush() has no effect on the current record when you are writing new
data to a wide-oriented or byte-oriented multibyte stream, because the record is
incomplete.
Flushing binary streams

In a wide-oriented stream, calling fflush() causes z/OS XL C to add a shift-in character if the stream does not already end in initial shift state. In a byte-oriented stream, calling fflush() causes no special behavior beyond what a call to fflush() usually does.

ungetwc() considerations

ungetwc() pushes wide characters back onto the input stream for binary and text files. You can use it to push one wide character onto the ungetwc() buffer. Never use ungetc() on a wide-oriented file. After you call ungetwc(), calling fflush() backs up the file position by one wide character and clears the pushed-back wide character from the stream. Backing up by one wide character skips over shift characters and backs up to the start of the previous character (whether single-byte or double-byte). For text files, z/OS XL C counts the new-lines added to the records as single-byte characters when it calculates the file position. For example, if you have the following stream,

<table>
<thead>
<tr>
<th>A</th>
<th>B</th>
<th>SO</th>
<th>X'FE'</th>
<th>X'7F'</th>
<th>SI</th>
<th>C</th>
</tr>
</thead>
</table>

you can run the code fragment shown in Figure 5.

```c
fgetwc(fp); /* Returns X'00C1' (the hexadecimal wchar representation of A) */
fgetwc(fp); /* Returns X'00C2' (the hexadecimal wchar representation of B) */
fgetwc(fp); /* Returns X'7FFE' (the hexadecimal wchar representation of the DBCS character) between the SO and SI characters; leaves file position at C */
ungetwc('Z', fp); /* Logically inserts Z before SI character */
fflush(fp); /* Backs up one wchar, leaving position at */
             /* beginning of X'7FFE' DBCS char */
             /* and DBCS state in double-byte mode; */
             /* clears Z from the logical stream */
```

Figure 5. ungetwc() Example

You can set the_EDC_COMPAT environment variable before you open the file, so that fflush() ignores any character pushed back with ungetwc() or ungetc(), and leaves the file position where it was when ungetwc() or ungetc() was first issued. Any characters pushed back are still cleared. For more information about_EDC_COMPAT, see Chapter 32, “Using environment variables,” on page 467.

Setting positions within files

The following conditions apply to text streams and binary streams.

Repositioning within text streams

When you use the fseek() or fsetpos() function to reposition within files, z/OS XL C recalculates the shift state.
If you update a record after a successful call to the `fseek()` function or the `fsetpos()` function, a partial multibyte character can be overwritten. Calling a wide character function for data after the written character can result in undefined behavior.

Use the `fseek()` or `fsetpos()` functions to reposition only to the start of a multibyte character. If you reposition to the middle of a multibyte character, undefined behavior can occur.

**Repositioning within binary streams**

When you are working with a wide-oriented file, keep in mind the state of the file position that you are repositioning to. If you call `ftell()`, you can seek with SEEK_SET and the state will be reset correctly. You cannot use such an `ftell()` value across a program boundary unless the stream has been marked wide-oriented. A seek specifying a relative offset (SEEK_CUR or SEEK_END) will change the state to initial state. Using relative offsets is strongly discouraged, because you may be seeking to a point that is not in initial state, or you may end up in the middle of a multibyte character, causing wide-oriented functions to give you undefined behavior. These functions expect you to be at the beginning or end of a multibyte character in the correct state. Using your own offset with SEEK_SET also does the same. For a wide-oriented file, the number of valid bytes or records that `ftell()` supports is cut in half.

When you use the `fsetpos()` function to reposition within a file, the shift state is set to the state saved by the function. Use this function to reposition to a wide character that is not in the initial state.

**ungetwc() considerations**

For text files, the library functions `fgetpos()` and `ftell()` take into account the character you have pushed back onto the input stream with `ungetwc()`, and move the file position back by one wide character. The starting position for an `fseek()` call with a whence value of SEEK_CUR also takes into account this pushed-back wide character. Backing up one wide character means backing up either a single-byte character or a multibyte character, depending on the type of the preceding character. The implicit new-lines at the end of each record are counted as wide characters.

For binary files, the library functions `fgetpos()` and `ftell()` also take into account the character you have pushed back onto the input stream with `ungetwc()`, and adjust the file position accordingly. However, the `ungetwc()` must push back the same type of character just read by `fgetwc()`, so that `ftell()` and `fgetpos()` can save the state correctly. An `fseek()` with an offset of SEEK_CUR also accounts for the pushed-back character. Again, the `ungetwc()` must unget the same type of character for this to work properly. If the `ungetwc()` pushes back a character in the opposite state, you will get undefined behavior.

You can make only one call to `ungetwc()`. If the current logical file position is already at or before the first wchar in the file, a call to `ftell()` or `fgetpos()` after `ungetwc()` fails.

When you are using `fseek()` with a whence value of SEEK_CUR, the starting point for the reposition also accounts for the presence of `ungetwc()` characters and compensates as `ftell()` and `fgetpos()` do. Specifying a relative offset other than 0 is not supported and results in undefined behavior.
You can set the _EDC_COMPAT environment variable to specify that ungetwc() should not affect fgetpos() or fseek(). (It will still affect ftell().) If the environment variable is set, fgetpos() and fseek() ignore any pushed-back wide character. See Chapter 32, “Using environment variables,” on page 467 for more information about _EDC_COMPAT.

If a repositioning operation fails, z/OS XL C attempts to restore the original file position by treating the operation as a call to fflush(). It does not account for the presence of ungetwc() characters, which are lost.

Closing files

z/OS XL C expects files to end in initial shift state. For binary byte-oriented files, you must ensure that the ending state of the file is initial state. Failure to do so results in undefined behavior if you reaccess the file again. For wide-oriented streams and byte-oriented text streams, z/OS XL C tracks new data that you add. If necessary, z/OS XL C adds a padding byte to complete any incomplete multibyte character and a shift-in to end the file in initial state.

Manipulating wide character array functions

To manipulate wide character arrays in your program, you can use the functions shown in Table 10. For more information about these functions, refer to z/OS XL C/C++ Runtime Library Reference.

Table 10. Manipulating wide character arrays

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>wmemcmp()</td>
<td>Compare wide character</td>
</tr>
<tr>
<td>wmemchr()</td>
<td>Locate wide character</td>
</tr>
<tr>
<td>wmemcpy()</td>
<td>Copy wide character</td>
</tr>
<tr>
<td>wmemmove()</td>
<td>Move wide character</td>
</tr>
<tr>
<td>wmemset()</td>
<td>Set wide character</td>
</tr>
<tr>
<td>wcrtomb()</td>
<td>Convert a wide character to a multibyte character</td>
</tr>
<tr>
<td>wcsset()</td>
<td>Append to wide-character string</td>
</tr>
<tr>
<td>wcschr()</td>
<td>Search for wide-character substring</td>
</tr>
<tr>
<td>wcscmp()</td>
<td>Compare wide-character strings</td>
</tr>
</tbody>
</table>
Chapter 9. Using C and C++ standard streams and redirection

The standard streams are declared in the C header file stdio.h or in the C++
header files iostream.h or iostream. Table 11 shows the C standard streams and
the functions that use them. Table 12 on page 64 shows the C++ standard streams
and the operators typically used to perform I/O with them.

By default, the standard streams are opened implicitly the first time they are
referenced. You do not have to declare them or call their open() member functions
to open them. For example, with no preceding declaration or open() call, the
following statement writes the decimal number n to the cout stream.

```
cout << n << endl;
```

For more detailed information about C++ I/O streaming, see the following:
- z/OS XL C/C++ Runtime Library Reference discusses the C I/O stream functions.
- Standard C++ Library Reference discusses the Standard C++ I/O stream classes.

### Table 11. C standard streams

<table>
<thead>
<tr>
<th>Stream name</th>
<th>Purpose</th>
<th>Functions that use it</th>
</tr>
</thead>
</table>
| stdin       | The input device from which your C program usually retrieves its data. | getchar() 
gets() 
gets_unlocked() 
scanf() 
scanf_unlocked() 
vscanf() 
vscanf_unlocked() 
wscanf() 
wscanf_unlocked() 
vwscanf() 
vwscanf_unlocked() |
| stdout      | The output device to which your C program normally directs its output. | printf() 
printf_unlocked() 
puts() 
puts_unlocked() 
putchar() 
putchar_unlocked() 
vprintf() 
vprintf_unlocked() 
wprintf() 
wprintf_unlocked() 
vwprintf() 
vwprintf_unlocked() |
| stderr      | The output device to which your C program directs its diagnostic messages. z/OS XL C/C++ uses stderr to collect error messages about exceptions that occur. | perror() 
perror_unlocked() |
Table 12. C++ standard streams

<table>
<thead>
<tr>
<th>Stream name</th>
<th>Purpose</th>
<th>Common usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>cin</td>
<td>The object from which your C++ program usually retrieves its data. In z/OS XL C++, input from cin comes from stdin by default.</td>
<td>&gt;&gt;, the input (extraction) operator</td>
</tr>
<tr>
<td>cout</td>
<td>The object to which your C++ program normally directs its output. In z/OS XL C++, output to cout goes to stdout by default.</td>
<td>&lt;&lt;, the output (insertion) operator</td>
</tr>
<tr>
<td>cerr</td>
<td>The object to which your C++ program normally directs its diagnostic messages. In z/OS XL C++, output to cerr goes to stderr by default. cerr is unbuffered, so each character is flushed as you write it.</td>
<td>&lt;&lt;, the output (insertion) operator</td>
</tr>
<tr>
<td>clog</td>
<td>Another object intended for error messages. In z/OS XL C++, output to clog goes to stderr by default. Unlike cerr, clog is buffered.</td>
<td>&lt;&lt;, the output (insertion) operator</td>
</tr>
</tbody>
</table>

On I/O operations requiring a file pointer, you can use stdin, stdout, or stderr in the same manner as you would any other file pointer.

If you are running with POSIX(ON), standard streams are opened during initialization of the process, before the application receives control. With POSIX(OFF), the default behavior is for the C standard streams to open automatically on first reference. You do not have to call fopen() to open them. For example, if the following statement is specified without a preceding fopen() statement, it writes the decimal number n to the stdout stream.

```c
printf("%d\n",n);
```

By default, stdin interprets the character sequence /* as indicating that the end of the file has been reached. See Chapter 13, "Performing terminal I/O operations," on page 191 for more information.

Default open modes

The default open modes for the C standard streams are:
- stdin  r
- stdout  w
- stderr  w

Where the streams go depends on what kind of environment you are running under. These are the defaults:

- **Under interactive TSO**, all three standard streams go to the terminal.
- **Under MVS batch, TSO batch, and IMS (batch and interactive):**
  - stdin goes to dd:sysin. If dd:sysin does not exist, all read operations from stdin will fail.
  - stdout goes first to dd:sysprint. If dd:sysprint does not exist, stdout looks for dd:system and then dd:syserr. If neither of these files exists, z/OS XL C/C++ opens a sysout=* data set and sends the stdout stream to it.
  - stderr will go to the z/OS Language Environment message file. In AMODE 64 applications, stderr goes to dd:sysout.
Note: When a standard stream is allocated to a large format sequential data set, the stream will be opened without repositioning (noseek). In this situation, the open is initially attempted with repositioning (seek), fails with an ABEND 213-14 or 213-16, and the stream is then opened without repositioning. For more information on large format sequential data sets, see "Large format sequential data sets" on page 96.

- Under CICS, stdout and stderr are assigned to transient data queues, allocated during CICS initialization. The CICS standard streams can be redirected only to or from memory files. You can do this by using freopen().
- Under z/OS UNIX, if you are running in one of the z/OS UNIX shells, the shell controls redirection. See z/OS V2R2.0 UNIX System Services User’s Guide and z/OS UNIX System Services Command Reference for information.

You can also redirect the standard streams to other files. See Redirecting standard streams and sections following.

**Interleaving the standard streams with sync_with_stdio()**

The sync_with_stdio() function allows you to interleave C standard streams with standard streams from either the Standard C++ Library or the USL I/O Stream Class Library. A call to sync_with_stdio() does the following:

- cin, cout, cerr, and clog are initialized with stdiobuf objects associated with stdin, stdout, and stderr.
- The flags unitbuf and stdio are set for cout, cerr, and clog.

This ensures that subsequent standard streams may be mixed on a per-character basis. **However, a runtime performance penalty is incurred to ensure this synchronization.** Figure 6 shows an example program and the output that it produces.

```c
// Example of interleaving USL I/O with sync_with_stdio()

#include <stdio.h>
#include <fstream.h>

int main() {
    ios::sync_with_stdio();
    cout << "object: to show that sync_with_stdio() allows interleaving\n" << endl;
    printf( "line 1 \n" );
    cout << "rest of line 1\n";
    cout << "line 2 ";
    printf( "rest of line 2\n\n" );
    char string1[80] = "";
    char string2[80] = "";
    char string3[80] = "";
    char* rc = NULL;
    cout << "type the following 2 lines:\n";
    "hello world, here I am\n"
    "again\n" << endl;
}
```

**Interleaving I/O with sync_with_stdio() (Part 1 of 2)**

*Figure 6. Interleaving I/O with sync_with_stdio()*
Interleaving the standard streams without `sync_with_stdio()`

Output can be interleaved without `sync_with_stdio()`, since the C++ standard streams are based on z/OS XL C I/O. That is, `cout` can be interleaved with `stdout`, and `clog` can be interleaved with `stderr`. This is done by explicitly flushing `cout` or `clog` before calling the z/OS XL C output function. Results of attempting to interleave these streams without explicitly flushing, are undefined. Output to `cerr` doesn’t have to be explicitly flushed, since `cerr` is unit-buffered.

Input to `cin` may be interleaved with input to `stdin`, without `sync_with_stdio()`, on a line-by-line basis. Results of attempting to interleave on a per-character basis are undefined. Figure 7 on page 67 shows an example program and the output it produces.
// Example of interleaving I/O without sync_with_stdio()

#include <stdio.h>
#include <fstream.h>

int main() {
    //object: to illustrate interleaving input and output
    cout << "without sync_with_stdio()" << endl;
    printf( "interleaving output ");
    cout << "works with an (end of line 1) \n" << flush;
    cout << "explicit flush of cout " << flush;
    printf( "(end of line 2)\n\n" );

    char string1[80] = "";
    char string2[80] = "";
    char string3[80] = "";
    char* rc = NULL;
    cout << "type the following 3 lines:\n";
    cout << "interleaving input\n";
    cout << "on a per-line basis\n";
    cout << "is supported\n" << endl;

    cin.getline(string1, 80);
    rc = gets(string2);
    cin.getline(string3, 80);

    cout << "\nstring1 is " << string1 << "\n";
    cout << "string2 is " << string2 << "\n";
    cout << "string3 is " << string3 << "\n" << endl;

    char char1 = '\0';
    char char2 = '\0';
    char char3 = '\0';

    cout << "type the following 2 lines:\n";
    cout << "results of interleaving input on a per-\n";
    cout << "character basis are not defined\n" << endl;

    cin >> char1;
    cin >> char2;
    cin >> char3;

    cout << \nchar1 is " << char1 << "\nchar2 is " << char2 << "\nchar3 is " << char3 << " flush; }

Interleaving I/O without sync_with_stdio() (Part 1 of 2)

Figure 7. Interleaving I/O without sync_with_stdio()
Interleaving I/O without sync_with_stdio() (Part 2 of 2)

Redirecting standard streams

This section describes redirection of standard streams:

- From the command line
- By assignment
- With freopen()
- With the MSGFILE runtime option

Note that, C++ standard streams are implemented in terms of C standard streams. Therefore, cin, cout, cerr, and clog are implicitly redirected when the corresponding C standard streams are redirected. These streams can be redirected by assignment, as described in “Assigning the standard streams” on page 70. If freopen() is applied to a C standard stream, creating a binary stream or one with type=record or type=blocked, then behavior of the related stream is undefined.

Redirecting streams from the command line

To redirect a standard stream to a file from the command line, invoke your program by entering the following:

1. Program name
2. Any parameters your program requires (these may be specified before and after the redirection)
3. A redirection symbol followed by the name of the file that is to be used in place of the standard stream
Note: If you specify a redirection in a `system()` call, after `system()` returns, the streams are redirected back to those at the time of the `system()` call.

**Using the redirection symbols**

The following table lists the redirection symbols supported by z/OS XL C/C++ (when not running under one of the z/OS UNIX shells) for redirection of C standard streams from the command line or from a `system()` call. 0, 1, and 2 represent stdin, stdout, and stderr, respectively.

Table 13. z/OS XL C/C++ Redirection symbols

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;fn</code></td>
<td>associates the file specified as <code>fn</code> with stdin; reopens <code>fn</code> in mode r.</td>
</tr>
<tr>
<td><code>0&lt;fn</code></td>
<td>associates the file specified as <code>fn</code> with stdin; reopens <code>fn</code> in mode r.</td>
</tr>
<tr>
<td><code>&gt;fn</code></td>
<td>associates the file specified as <code>fn</code> with stdout; reopens <code>fn</code> in mode w.</td>
</tr>
<tr>
<td><code>1&gt;fn</code></td>
<td>associates the file specified as <code>fn</code> with stdout; reopens <code>fn</code> in mode w.</td>
</tr>
<tr>
<td><code>&gt;&gt;fn</code></td>
<td>associates the file specified as <code>fn</code> with stdout; reopens <code>fn</code> in mode a.</td>
</tr>
<tr>
<td><code>2&gt;&gt;fn</code></td>
<td>associates the file specified as <code>fn</code> with stderr; reopens <code>fn</code> in mode w.</td>
</tr>
<tr>
<td><code>2&gt;&amp;1</code></td>
<td>associate stderr with stdout; same file and mode.</td>
</tr>
<tr>
<td><code>1&gt;&amp;2</code></td>
<td>associate stdout with stderr; same file and mode.</td>
</tr>
</tbody>
</table>

Notes:

1. If you use the NOREDIR option on a `#pragma runopts` directive, or the NOREDIR compile-time option, you cannot redirect standard streams on the command line using the preceding list of symbols.

2. If you want to pass one of the redirection symbols as an argument, you can enclose it in double quotation marks. For example, the following passes the string "here are the args including a <" to prog and redirects stdout to redir1 output a.

   ```
   prog "here are args including a <" >"redir1 output a"
   ```

3. TSO (batch and online) and MVS batch support command line arguments. CICS and IMS do not.

4. When two options specifying redirection conflict with each other, or when you redirect a standard stream more than once, the redirection fails. If you do the latter, you will get an abend. For example, if you specify

   ```
   2>&1
   ```

and then

```
1>&2
```

z/OS XL C/C++ uses the first redirection and ignores any subsequent ones. If you specify

```
> a.out
```

and then

```
1>&2
```

the redirection fails and the program abends.

5. A failed attempt to redirect a standard stream causes your program to fail in initialization.

6. The C standard streams can be redirected to large format sequential data sets. If this occurs, the stream will be reopened without repositioning (noseek). In this
situation, the reopen is initially attempted with repositioning (seek), fails with an ABEND 213-14 or 213-16, and the stream is then reopened without repositioning.

Assigning the standard streams

This method of redirecting streams is known as direct assignment. You can redirect a C standard stream by assigning a valid file pointer to it, as follows:

```c
FILE *stream;
stream = fopen("new.file", "w");
stdout = stream;
```

You must ensure that the streams are appropriate; for example, do not assign a stream opened for `w` to `stdin`. Doing so would cause a function such as `getchar()` called for the stream to fail, because `getchar()` expects a stream to be opened for read access.

Similarly, you can redirect a standard stream under C++ by assignment:

```cpp
ofstream myfile("myfile.data");
cout = myfile;
```

Again, you must ensure that the assigned stream is appropriate; for example, do not assign an `fstream` opened for `ios::out` only to `cin`. This will cause a subsequent read operation to fail.

Using the freopen() library function

You can use the `freopen()` C library function to redirect C standard streams in all environments.

Redirecting streams with the MSGFILE option

**Restriction:** This section does not apply to AMODE 64.

You can redirect `stderr` by specifying a ddname on the MSGFILE runtime option and not redirecting `stderr` elsewhere (such as on the command line). The default ddname for the z/OS Language Environment MSGFILE is SYSOUT. See z/OS Language Environment Programming Guide for more information on MSGFILE.

MSGFILE considerations

z/OS XL C/C++ makes a distinction between types of error output according to whether the output is directed to the MSGFILE, to stderr, or to stdout:

Table 14. Output destinations under z/OS XL C/C++

<table>
<thead>
<tr>
<th>Destination of Output</th>
<th>Type of Message</th>
<th>Produced by</th>
<th>Default Destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>MSGFILE output</td>
<td>z/OS Language Environment messages (CEExxxx)</td>
<td>z/OS Language Environment conditions</td>
<td>MSGFILE ddname</td>
</tr>
<tr>
<td></td>
<td>z/OS XL C/C++ language messages (EDCxxxx)</td>
<td>z/OS XL C/C++ unhandled conditions</td>
<td>MSGFILE ddname</td>
</tr>
</tbody>
</table>
Table 14. Output destinations under z/OS XL C/C++ (continued)

<table>
<thead>
<tr>
<th>Destination of Output</th>
<th>Type of Message</th>
<th>Produced by</th>
<th>Default Destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>stderr messages</td>
<td>perror() messages (EDCxxxx)</td>
<td>Issued by a call, for example, to: perror()</td>
<td>MSGFILE ddname (see note 1)</td>
</tr>
<tr>
<td></td>
<td>User output sent explicitly to stderr</td>
<td>Issued by a call to fprintf()</td>
<td>MSGFILE ddname</td>
</tr>
<tr>
<td>stdout messages</td>
<td>User output sent explicitly to stdout</td>
<td>Issued by a call, for example, to: printf()</td>
<td>stdout (see note 2)</td>
</tr>
</tbody>
</table>

Notes:
1. When you are using one of the z/OS UNIX shells, stderr will go to file descriptor 2, which is typically the terminal. See Chapter 16, “Language Environment Message file operations,” on page 217 for more information about z/OS Language Environment message files.
2. When you are using one of the z/OS UNIX shells, stdout will go to file descriptor 1, which is typically the terminal.

All stderr output is by default sent to the MSGFILE destination, while stdout output is sent to its own destination. When stderr is redirected to stdout, both share the stdout destination. When stdout is redirected to stderr, both share the stderr destination.

If you specified one of the DDs used in the stdout open search order as the DD for the MSGFILE option, then that DD will be ignored in the stdout open search.

Table 15 describes the destination of output to stderr and stdout after redirection has occurred. Whenever stdout and stderr share a common destination, the output is interleaved. The default case is the one where stdout and stderr have not been redirected.

Table 15. z/OS XL C/C++ Interleaved output

<table>
<thead>
<tr>
<th>stderr not redirected</th>
<th>stderr redirected to destination other than stdout</th>
<th>stderr redirected to stdout</th>
</tr>
</thead>
<tbody>
<tr>
<td>stdout not redirected</td>
<td>stdout to itself sterr to MSGFILE</td>
<td>stderr to itself sterr to its other destination</td>
</tr>
<tr>
<td>stdout redirected to destination other than stderr</td>
<td>stdout to its other destination sterr to MSGFILE</td>
<td>stdout to its other destination sterr to its other destination</td>
</tr>
<tr>
<td>stdout redirected to stderr</td>
<td>Both to MSGFILE</td>
<td>Both to the new stderr destination</td>
</tr>
</tbody>
</table>

z/OS XL C/C++ routes error output as follows:
- MSGFILE output
  - z/OS Language Environment messages (messages prefixed with CEE)
  - Language messages (messages prefixed with EDC)
- stderr output
  - perror messages (messages prefixed with EDC and issued by a call to perror())
  - Output explicitly sent to stderr (for example, by a call to fprintf())
By default, z/OS XL C/C++ sends all stderr output to the MSGFILE destination and stdout output to its own destination. You can change this by using z/OS XL C/C++ redirection, which enables you to redirect stdout and stderr to a ddname, file name, or each other. Unless you have redirected stderr, it always uses the MSGFILE destination. When you redirect stderr to stdout, stderr and stdout share the stdout destination. When you redirect stdout to stderr, they share the stderr destination.

Redirecting streams under z/OS

This section describes how to redirect C standard streams under MVS batch and under TSO.

Restrictions: The following restrictions apply to AMODE 64 applications:
- IMS and CICS environments are not supported in AMODE 64 applications
- The Language Environment Message File (MSGFILE) is not supported in AMODE 64 applications
- The stderr stream goes to the ddname SYSOUT in AMODE 64 applications

Under MVS batch

You can redirect standard streams in the following ways:
- From the freopen() library function call
- On the PARM parameter of the EXEC used to invoke your C or C++ program
- Using DD statements

Because the topic of JCL statements goes beyond the scope of this book, only simple examples will be shown here.

Using the PARM parameter of the EXEC statement

The following example shows an excerpt taken from a job stream. It demonstrates both the redirection of stdout using the PARM parameter of the EXEC statement, and the way to redirect to a fully qualified data set. You can use the redirection symbols described in Table 13 on page 69.

Suppose you have a program called BATCHPGM, with 1 required parameter 'DEBUG'. The output from BATCHPGM is to be directed to a sequential data set called 'MAINT.LOG.LISTING'. You can use the following JCL statements:

```
//JOBname JOB...
  //STEP01 EXEC PGM=BATCHPGM,PARM='DEBUG >''MAINT.LOG.LISTING''
```

The following JCL redirects output to an unqualified data set using the same program name, parameter and output data set as the example above:

```
//STEP01 EXEC PGM=BATCHPGM,PARM='DEBUG >LOG.LISTING'
```

If your user ID was TSOU812, stdout would be sent to TSOU812.LOG.LISTING.

Using DD statements

When you use DD statements to redirect standard streams, the standard streams will be associated with ddnames as follows:
• **stdin** will be associated with the **SYSIN** ddname. If **SYSIN** is not defined, no characters can be read in from **stdin**.

• **stdout** will be associated with the **SYSPRINT** ddname. If **SYSPRINT** is not defined, the C library will try to associate **stdout** with **SYSTERM**, and if **SYSTERM** is also not defined, the C library will try to associate **stdout** with **SYSERR**. If any of the above DD statements are used as the MSGFILE DD, then that DD statement will not be considered for use as the **stdout** DD.

**Restriction:** The reference to the MSGFILE does not apply to AMODE 64 applications.

• **stderr** will be associated with the **MSGFILE**, which defaults to **SYSOUT**. See z/OS Language Environment Programming Guide for more information on **MSGFILE**.

**Restriction:** The reference to the MSGFILE does not apply to AMODE 64 applications.

• If you are running with the runtime option **POSIX(ON)**, you can redirect standard streams with ddnames only for MVS data sets, not for UNIX file system files.

• If the ddname for **stdout** is not allocated to a device or data set, it is dynamically allocated to the terminal in an interactive environment or to **SYSOUT** in an MVS batch environment.

**Table 16** summarizes the association of streams with ddnames:

<table>
<thead>
<tr>
<th>Standard stream</th>
<th>ddname</th>
<th>Alternate ddname</th>
</tr>
</thead>
<tbody>
<tr>
<td>stdin</td>
<td>SYSIN</td>
<td>none</td>
</tr>
<tr>
<td>stdout</td>
<td>SYSPRINT</td>
<td>SYSTERM, SYSERR</td>
</tr>
<tr>
<td>stderr</td>
<td>DD associated with MSGFILE. For AMODE 64 applications stderr is SYSOUT, and there is no alternate ddname.</td>
<td>None</td>
</tr>
</tbody>
</table>

**Figure 8** shows excerpt from an MVS example job stream that demonstrates the redirection of the three standard streams by using ddnames. In the example, your program name is MONITOR and the input to MONITOR is to be retrieved from a sequential data set called 'SAFETY.CHEM.LIST'. The output of MONITOR is to be directed to a partitioned data set member called 'YEAREND.ACTION(CHEM)', and any errors generated by MONITOR are to be written to a sequential data set called 'YEAREND.MONITOR.ERRLIST'. To redirect the standard streams using DD statements, you could use the JCL statements shown in **Figure 8**.

```
//JOBname JOB...
//STEPS
  EXEC PGM=MONITOR,PARM='MSGFILE(SYSERR)/'
  ...

//SYSIN DD DSN=SAFETY.CHEM.LIST,DISP=OLD
//SYSERR DD DSN=YEAREND.MONITOR.ERRLIST,DISP=MOD
//SYSPRINT DD DSN=YEAREND.ACTION(CHEM),DISP=OLD
```

**Figure 8. MVS example of redirecting three standard streams by ddnames**

**Figure 9 on page 74** shows how to get **stdout** and **stderr** to share the same file where: the program name is HOCKEY and the input to HOCKEY is to be retrieved from a sequential data set called 'HOCKEY.PLAYER.LIST'. The output of HOCKEY is to be directed to a sequential data set called 'HOCKEY.OUTPUT' and any errors generated by HOCKEY are also to be written to the sequential data set 'HOCKEY.OUTPUT'. You
could use the JCL statements shown in Figure 9.

```
//JOBname JOB...
//STEP01 EXEC PGM=HOCKEY,PARM=' / 2>&1'
//SYSIN DD DSN=HOCKEY.PLAYER.LIST,DISP=SHR
//SYSPRINT DD DSN=HOCKEY.OUTPUT,DISP=(OLD),DDB=...
```

Figure 9. Example of using stdout and stderr to share the same file

stderr shares stdout because of the 2>&1 redirection statement.

If you want to redirect to a UNIX file system file, you can modify the above examples to use the PATH and PATHOPT options described in "DDnames" on page 36.

**Under TSO**

You can redirect standard streams in the following ways:

- From the freopen() library function call
- From the command line
- Using the parameter list in a CALL command

**From the command line**

The following example illustrates the redirection of stdin under TSO. The program in this example is called BUILD and it has 2 required parameters, 'PLAN' and 'JOHNSTON'. The input to BUILD is to be retrieved from a partitioned data set member called 'CONDO(SPRING)'. To redirect stdin in this example under TSO you can use the following command:

```
BUILD PLAN JOHNSTON <'CONDO(SPRING)'
```

**Notes:**

1. If the data set name is not enclosed in quotation marks, your user prefix will be appended to the data set name specified.
2. If you specify a redirection in a system() call, after system() returns, the streams are redirected back to those at the time of the system() call.

**Using the parameter list in a CALL command**

You can also redirect the output to a file with a ddname in TSO by specifying the output file in the parameter list like the following:

```
CALL 'PREFIX.PROGRAM' '>&DD:OUTFILE'
```

The ddname can be created by an ALLOCATE command.

**Under IMS**

Under IMS online and batch, you can redirect the C standard streams in any of the following ways:

- with direct assignment
- with the freopen() function
- with ddnames

For details on ddnames, see "Using DD statements" on page 72.
Under CICS

There are several ways to redirect C standard streams under CICS:

- You can assign a memory file to the stream (for example, `stdout=myfile`).
- You can use `freopen()` to open a standard stream as a memory file.
- You can use CICS facilities to direct where the stream output goes.

If you assign a file pointer to a stream or use `freopen()` on it, you will not be able to use C functions to direct the information outside or elsewhere in the CICS environment. Once access to a CICS transient data queue has been removed, either by a call to `freopen()` or `fclose()`, or by the assignment of another file pointer to the stream, z/OS XL C/C++ does not provide a way to regain access. Once C functions have lost access to the transient data queues, you must use the CICS-provided facilities to regain it.

CICS provides a facility that enables you to direct where a given transient data queue, the default standard stream implementation, will go, but you must configure this facility before a CICS cold start.

Passing C and C++ standard streams across a system() call

A `system()` call occurs when one z/OS XL C/C++ program calls another z/OS XL C/C++ program by using the ANSI `system()` function, which z/OS XL C/C++ uses if you are not running with POSIX(ON). Standard streams are inherited across calls to the ANSI `system()` function. With a POSIX `system()` function, file descriptors 0, 1, and 2 will be mapped to standard streams stdin, stdout and stderr in the child process. The behavior of these streams is similar to binary streams called with the ANSI `system()` function.

Inheritance includes any redirection of the stream as well as the open mode of the stream. For example, if program A reopens stdout as "A.B" for "wb" and then calls program B, program B inherits the definition of stdout. If program B reopens stdout as "C.D" for "ab" and then uses `system()` to call program C, program C inherits stdout opened to "C.D" for append. Once control returns to the calling program, the definitions of the standard streams from the time of the `system()` call are restored. For example, when program B finally returns control to program A, stdout is restored to "A.B" opened for "wb".

The file position and the amount of data that is visible in the called and calling programs depend on whether the standard streams are opened for binary, text, record I/O, or blocked I/O.

The behavior of the C standard streams across a `system()` call indicates the behavior of all standard streams since they are implemented in terms of the C standard streams.

Passing binary streams

If the standard stream being passed across a `system()` call is opened in binary mode, any reads or writes issued in the called program occur at the next byte in the file. On return, the position of the file is wherever the called program is positioned. This includes any possible repositions made by the called program if the file is enabled for positioning. Because output to binary files is done byte by byte, all bytes are written to stdout and stderr in the order they are written. This is shown in the following example:
printf("123");
printf("456");
system("CHILD");        int main(void) { putc('7',stdout);}  
printf("89");

The output from this example is: 123456789

Memory files are always opened in binary mode, even if you specify text. Any standard streams redirected to memory files and passed across system() calls will be treated as binary files. UNIX file system files are also treated as binary files, because they do not contain any real record boundaries. Memory files are not passed across calls to the POSIX system() function.

If freopen() is applied to a C standard stream, thereby creating a binary stream, then the results of I/O to the associated standard stream across a system() call are undefined.

**Passing text streams**

If the C standard stream being passed across a system() call is opened in text mode (the default), the file position in the called program is placed at the next record boundary, if it is not already at the start of a record. Any data in the current record that is unread is skipped. [Figure 10] show an example.

<table>
<thead>
<tr>
<th>INPUT FILE</th>
<th>ROOT C PROGRAM</th>
<th>CHILD PROGRAM</th>
</tr>
</thead>
<tbody>
<tr>
<td>abcdefghijkl</td>
<td>int main() {</td>
<td>int main() {</td>
</tr>
<tr>
<td>mmnopqrstuvwxyz</td>
<td>char c[4];</td>
<td>char d[2];</td>
</tr>
<tr>
<td>0123456789ABC</td>
<td>c[0] = getchar();</td>
<td>d[0] = getchar();</td>
</tr>
<tr>
<td>DEFGHIJKLMNOP</td>
<td>system(&quot;CHILD&quot;);</td>
<td>printf(&quot;%.2s\n&quot;,</td>
</tr>
<tr>
<td></td>
<td>c[2] = getchar();</td>
<td></td>
</tr>
</tbody>
</table>
| | c[3] = getchar(); | }
| | printf("%.4s\n",c); | |

<table>
<thead>
<tr>
<th>OUTPUT</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>no</td>
<td>---&gt; from the child</td>
</tr>
<tr>
<td>ab01</td>
<td>---&gt; from root</td>
</tr>
</tbody>
</table>

*Figure 10. Example of passing text streams*

When you write to a spanned file, the file position moves to the beginning of the next record, if that record exists. If not, the position moves to the end of the incomplete record.

For non-spanned standard streams opened for output, if the caller has created a text record missing an ending control character, the last record is hidden from the called program. The called program can append new data if the stream is open in append mode. Any appends made by the called program will be after the last record that was complete at the time of the system() call.

When the called program terminates, it completes any new unfinished text record with a new-line; the addition of the new-line does not move the file position. Once any incomplete record is completed, the file position moves to the next record boundary, if it is not already on a record boundary or at EOF.

When control returns to the original caller, any incomplete record hidden at the time of the system() call is restored to the end of the file. If the called program is
at EOF when it is terminated and the caller was within an incomplete record at the
time of the system() call, the position upon return is restored to the original record
offset at the time of the system() call. This position is usually the end of the
incomplete record. Generally, if the caller is writing to a standard stream and does
not complete the last record before it calls system(), writes continue to add to the
last record when control returns to the caller. For example:

```c
printf("test");
printf("abc");
system("hello");    ------> int main(void) { printf("hello world\n");}
printf("def\n");
```

The output from this example is as follows:

```
test
  hello world
  abcdef
```

If stdout had been opened for "w+" in this example, and a reposition had been
made to the character 'b' before the system() call, upon return, the incomplete
record "abc" would have been restored and the position would have been at the
'b'. The subsequent write of def would have performed an update to give test
hello world adef.

**C++ standard streams considerations**

The following sections are considerations for C++ standard streams.

**Output with sync_with_stdio():** When a standard output stream is open in text
mode (the default), and sync_with_stdio() has been called, the output across a
system() call behaves the same as a C standard stream:

- If the parent program writes a newline character, the line will be flushed before
  the child program is invoked;
- Otherwise, the output from the parent will be held in a buffer until the child
  returns.

**Output without sync_with_stdio():** When a standard output stream is open in
text mode, and sync_with_stdio() has not been called, the behavior is as follows:

- If the parent program writes a newline character, and explicitly flushes it, the
  line will be written out before the child program is invoked;
- Otherwise, the behavior is undefined.

**Input with sync_with_stdio():** When cin is open in text mode (the default), and
sync_with_stdio() has been called, the input across a system() call behaves the
same as stdin:

- The child program begins reading at the next record boundary, that is, unread
data in the current record in the parent is hidden.
- When the child program returns, the parent program begins reading at the next
  record boundary, that is, unread data in the current record in the child is lost.

**Input without sync_with_stdio():** When cin is open in text mode, and
sync_with_stdio() has not been called, the behavior is as follows:

- The parent program must either not read from cin before calling the child, or
  must read to the end of a complete record.
- The child program begins reading at the next record boundary, that is, unread
data in the current record in the parent is hidden.
• When the child program returns, the parent program begins reading at the next record boundary, that is, unread data in the current record in the child is lost.
• If the parent program read only part of a record before calling the child, the behavior upon returning from the child is undefined.

Passing record I/O streams
For record I/O, all reads and writes made by the called program occur at the next record boundary. Because complete records are always read and written, there is no change in the file position across a system() call boundary.

In the example shown in Figure 11 stdout is a variable-length record I/O file.

```c
fwrite("test",1,4,stdout); 
fwrite("abc",1,3,stdout); 
system("hello"); ------> int main(void) {
  fwrite("def",1,3,stdout);
  fwrite("hello world",1,11,stdout) 
}
```

Figure 11. Example of passing record I/O streams
The output from this code fragment is as follows:

```
  test
  abc
  hello world
  def
```

If freopen() is applied to a C standard stream, creating a stream with type=record, then behavior of the associated I/O stream is undefined across a system() call.

Passing blocked I/O streams
For blocked I/O, all reads and writes made by the called program occur at the next block boundary. Because complete blocks are always read and written, there is no change in the file position across a system() call boundary.

If freopen() is applied to a C standard stream, creating a stream with type=blocked, then behavior of the associated I/O stream is undefined across a system() call.

Using global standard streams

Restriction: This section does not apply to AMODE 64.

In the default inheritance model, the behavior of C standard streams is such that a child main() function cannot affect the standard streams of the parent. The child can use the parent's definition or redirect a standard stream to a new location, but when control returns to the parent, the standard stream reverts back to the definition of the parent. In the global model, the C standard streams, stdin, stdout, and stderr, can be redirected to a different location while running in a child main() function and have that redirection stay in effect when control returns to the parent. You can use the _EDC_GLOBAL_STREAMS environment variable to set standard stream behavior to the global model. For more information, see "_EDC_GLOBAL_STREAMS" on page 493.
Table 17 highlights the standard stream behavior differences between the default inheritance model and the global model.

<table>
<thead>
<tr>
<th>Behavior</th>
<th>Default Inheritance Model</th>
<th>Global Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>POSIX(OFF)</td>
<td>Standard streams are opened automatically on first reference.</td>
<td>(Same)</td>
</tr>
<tr>
<td>POSIX(ON)</td>
<td>Standard streams are opened during initialization of the process, before the application receives control.</td>
<td>Not supported.</td>
</tr>
<tr>
<td>default open modes</td>
<td>As described in &quot;Default open modes&quot; on page 64.</td>
<td>(Same)</td>
</tr>
<tr>
<td>default locations</td>
<td>As described in this chapter.</td>
<td>(Same)</td>
</tr>
<tr>
<td>command line redirection</td>
<td>Changes the location for the main being called and subsequent child programs.</td>
<td>Changes the location for the entire C environment.</td>
</tr>
<tr>
<td>direct assignment</td>
<td>Affects the current main and subsequent child programs.</td>
<td>Affects the current main only. This definition is not passed on to a subsequent child program. The child gets the current global definition, if there is one defined.</td>
</tr>
<tr>
<td>freopen()</td>
<td>Changes location for the main from which it is called and affects any subsequent child programs.</td>
<td>Changes location for the entire C environment.</td>
</tr>
<tr>
<td>MSGFILE() runtime option</td>
<td>Redirects stderr for the main being invoked and affects any subsequent child programs. When control returns to a parent program, stderr reverts back to the definition of the parent. If stderr is also redirected on the command line, that redirection takes precedence.</td>
<td>(Same)</td>
</tr>
<tr>
<td>fclose()</td>
<td>Closes the standard stream in current main only.</td>
<td>Closes the standard stream for the entire C environment. The standard stream cannot be global anymore. Only direct assignment can be used to use the standard stream, and that would only be for the main in which it is assigned.</td>
</tr>
<tr>
<td>file position and visible data</td>
<td>As currently described in this chapter.</td>
<td>File position and visible data across mains are as if there were only one main. No special processing occurs during the ANSI system() call. The standard streams are left untouched. When either entering or returning from a child program, reading or writing to the standard streams begin where previously left off,</td>
</tr>
</tbody>
</table>

C++ I/O Stream

- cin defaults to stdin
- cout defaults to stdout
- cerr defaults to stderr (unbuffered)
- clog defaults to stderr (buffered) (Same)

Notes:

1. The following environments do not allow global standard stream behavior as an option:
   - POSIX(ON)
2. You must identify the behavior of the standard streams to the C runtime library before initialization of the first C main in the environment. The default behavior uses the inheritance model. Once you set the standard stream behavior, it cannot be changed. Attempts to change the behavior after the first C main has been initialized are ignored.

3. The value of the environment variable, when queried, does not necessarily reflect the standard stream behavior being used. This is because the value of the environment variable can be changed after the standard stream behavior has been set.

4. The behaviors described in Table 17 on page 79 only apply to the standard streams that use the global behavior.

**Command line redirection**

In the C standard stream global model, command line redirection of the standard streams is supported, but has much different behavior than the C standard stream inheritance model.

The most important difference is that when redirection is done at `system()` call time, the redirection takes effect for the entire C environment. When the child program terminates, the standard stream definitions do not revert back to what they were before the `system()` call.

Redirection of any of the standard streams, except when `stderr` is redirected to `stdout` or vice versa, causes the standard stream to be flushed. This is because an `freopen()` is done under the covers, which first closes the stream before reopening it. Since the standard stream is global, the close causes the flush.

Redirecting `stderr` to `stdout`, or `stdout` to `stderr`, does not flush the redirected stream. Any data in the buffer remains there until the stream is redirected again, to something other than `stdout` or `stderr`. Only then is the buffer flushed.

Consider the following example programs, `PARENT.C` and `CHILD.C`, shown in Figure 12 on page 81.
When run from TSO terminal using the command `parent ENVAR(_EDC_GLOBAL_STREAMS=7)/`, the output will be as follows:

```
(line 1
line 2
line 3
line 4
line 5
line 6
line 7
line 8
line 9
line 10
```

**Attention:** If the `stdout` or `stderr` stream has data in its buffer and it is redirected to `stderr` or `stdout`, then the data is lost if `stdout` or `stderr` is not redirected again.

**Note:** If either `stdout` or `stderr` is using global behavior, but not both, then any redirection of `stdout` or `stderr` to `stderr` or `stdout` is ignored.

### Direct assignment

You can directly assign the C standard streams in any main program. This assignment does not have any effect on the global standard stream. No flush is done and the new definition is not passed on to a child program nor back to a parent program. Once you directly assign a standard stream, there is no way to re-associate it with the global standard stream.

### freopen()

When you use `freopen()` to redirect a standard stream, the stream is closed, causing a flush, and then redirected. The new definition affects all C mains currently using the global stream.

### MSGFILE() runtime option

The MSGFILE() runtime option redirects the `stderr` stream similar to command line redirection. However, this redirection is controlled by the Common Execution Library and does not apply to all C mains in the environment. When control returns to a parent program, `stderr` reverts back to the definition of the parent.
fclose()

When a global standard stream is closed, only direct assignment can be used to begin using the standard stream again. That use would only be for the main performing the direct assignment. There is no way to get back global behavior for the standard stream that was closed.

File position and visible data

The file position and amount of visible data in the called and calling program is as if there is only one program. There is no data hidden from a called program. A child program continues where the parent program left off. This is true for all types of I/O: binary, text, and record.

C++ I/O stream library

Since cin, cout, cerr and clog are initially based on stdin, stdout and stderr, they continue to be in the global model. For example, if stdout is redirected using freopen() in a child program, then both stdout and cout retain that redirection when control returns to the parent.
Chapter 10. Performing OS I/O operations

This topic describes using OS I/O, which includes support for the following:

- Regular sequential DASD (including striped data sets)
- Partitioned DASD (PDS and PDSE)
- Tapes
- SYSOUT
- Printers
- In-stream JCL

Notes:
1. z/OS XL C/C++ does not support BDAM, ISAM, or non-VSAM keyed data sets. Attempting to open a non-VSAM keyed data set for read or append fails; attempting to open an existing non-VSAM keyed data set for write results in unpredictable results.
2. z/OS XL C/C++ provides complete read and write support for large format sequential data sets when seek is requested (not specifying the noseek keyword) and when noseek is requested and honored.
3. z/OS XL C/C++ provides support for extended format sequential data sets in the extended addressing space on extended address volumes (EAVs).
4. z/OS XL C/C++ supports opening DDNAMEs that have been dynamically allocated with the XTIOT, UCB nocapture, and DSAB-above-the-line options specified in the SVC99 parameters (S99TIOEX, S99ACUCB, S99DSABA flags).

OS I/O supports text, binary, record I/O, and blocked I/O, in record formats: fixed (F), variable (V), and undefined (U). For information about using wide-character I/O with z/OS XL C/C++, see Chapter 8, “z/OS XL C Support for the double-byte character set,” on page 53.

This topic describes C I/O stream functions as they can be used within C++ programs. If you want to use the C++ I/O stream classes instead, see Standard C++ Library Reference, which discusses the Standard C++ I/O stream classes

Opening files

To open an OS file, you can use the Standard C functions fopen() or freopen(). These are described in general terms in z/OS XL C/C++ Runtime Library Reference. Details about them specific to all z/OS XL C/C++ I/O are discussed in the “Opening Files” section. This section describes considerations for using fopen() and freopen() with OS files.

Using fopen() or freopen()

When you open a file using fopen() or freopen(), you must specify the filename (a data set name) or a ddname. Restriction: It is not possible to open a file for writing if there is already an open file with the same data set name on a different volume.
Using a data set name

Files are opened with a call to fopen() or freopen() in the format fopen("filename", "mode"). The following diagram shows the syntax for the filename argument on your fopen() or freopen() call:

```
//
//
//
//
```

Note: The single quotation marks in the filename syntax diagram must be matched; if you use one, you must use the other.

A sample construct is shown below:

```
'qualifier1.qualifier2(member)'
```

// Specifying these slashes indicates that the filename refers to a non-POSIX file or data set.

Qualifier

Each qualifier is a 1- to 8-character name. These characters may be alphanumeric, national ($, #, @), or the hyphen. The first character should be either alphabetic or national. Do not use hyphens in names for RACF-protected data sets.

You can join qualifiers with periods. The maximum length of a data set name is as follows:

- Generally, 44 characters, including periods.
- For a generation data group, 35 characters, including periods.

These numbers do not include a member name or GDG number and accompanying parentheses.

Specifying one or two ampersands before a single qualifier opens a temporary data set. Multiple qualifiers are not valid after ampersands, because the system generates additional qualifiers. Opening two temporary data sets with the same name creates two distinct files. If you open a second temporary data set using the same name as the first, you get a distinct data set. For example, the following statements open two temporary data sets:

```
fp = fopen("//&myfile" "wb+");
fp2 = fopen("//&myfile","wb+");
```

You cannot fully qualify a temporary data set name. The file is created at open time and is empty. When you close a temporary data set, the system removes it.
If you specify a *member*, the data set you are opening must be a PDS or a PDSE. For more information about PDSs and PDSEs, see “Regular and extended partitioned data sets” on page 89. For members, the member name (including trailing blanks) can be up to 8 characters long. A member name cannot begin with leading blanks. The characters in a member name may be alphanumeric, national ($, #, @), the hyphen, or the character X’C0’. The first character should be either alphabetic or national.

**+number**

**-number**

You specify a Generation Data Group (GDG) by using a plus (+) or minus (-) to precede the version number, or by using a 0. For more information about GDGs, see “Generation data group I/O” on page 87.

The Resource Access Control Facility (RACF®) expects the data set name to have a high-level qualifier that is defined to RACF. RACF uses the entire data set name when it protects a tape data set.

When you enclose a name in single quotation marks, the name is *fully qualified*. The file opened is the one specified by the name inside the quotation marks. If the name is not fully qualified, z/OS XL C/C++ does one of the following:

- If your system does not use RACF, z/OS XL C/C++ does not add a high-level qualifier to the name you specified.
- If you are running under TSO (batch or interactive), z/OS XL C/C++ appends the TSO user prefix to the front of the name. For example, the statement `fopen("a.b", "w");` opens a data set `tsoid.A.B`, where `tsoid` is the user prefix. If the name is fully qualified, z/OS XL C/C++ does not append a user prefix. You can set the user prefix by using the TSO PROFILE command with the PREFIX parameter.
- If you are running under z/OS batch or IMS (batch or online), z/OS XL C/C++ appends the RACF user ID to the front of the name.

If you want your code to be portable between the VM/CMS and z/OS systems and between memory files and disk files, use a name of the format `name1.name2`, where `name1` and `name2` are up to 8 characters and are delimited by a period, or use a ddname. You can also add a member name.

For example, the following piece of code can run under Language Environment for VM and z/OS Language Environment:

```c
FILE *stream;
stream = fopen("parts.instock", "r");
```

### Using a DDname

The DD statement enables you to write C or C++ source programs that are independent of the files and input/output devices they use. You can modify the parameters of a file or process different files without recompiling your program.

Use ddnames if you want to use non-DASD devices.

If you specify DISP=MOD on a DD statement and w or wb mode on the `fopen()` call, z/OS XL C/C++ treats the file as if you had opened it in append mode instead of write mode.

To open a file by ddname under z/OS batch, you must define the ddname first. You can do this in any of the following ways:
In batch (z/OS, TSO, or IMS), you can write a JCL DD statement. For the declaration shown above for the C or C++ file PARTS.INSTOCK, you write a JCL DD statement similar to the following:

```
//STOCK DD DSN=USERID.PARTS.INSTOCK,DISP=SHR
```

When defining DD, do not use `DD ... FREE=CLOSE` for unallocating DD statements. The C library may close files to perform some file operations such as `freopen()`, and the DD statement will be unallocated.

If you use `SPACE=RLSE` on a DD statement, z/OS XL C/C++ releases space only if all of the following are true:
- The file is open in w, wb, a, or ab mode
- It is not simultaneously open for read
- No positioning functions (`fseek()`, `ftell()`, `rewind()`, `fgetpos()`, `fsetpos()`)

have been performed.

For more information on writing DD statements, refer to the job control language (JCL) manuals listed in z/OS V2R2 Information Roadmap.

Under TSO (interactive and batch), you can issue an `ALLOCATE` command. The DD definition shown above for the C file `STOCK` has an equivalent TSO `ALLOCATE` command, as follows:

```
ALLOCATE FILE(STOCK) DATASET(PARTS.INSTOCK) SHR
```

See z/OS V2R2 Information Roadmap for manuals containing information on TSO `ALLOCATE`.

In the z/OS environment, you can use the `svc99()` or `dynalloc()` library functions to define ddnames. For information about these functions, refer to z/OS XL C/C++ Runtime Library Reference.

**DCB parameter:** The DCB (data control block) parameter of the DD statement allows you to describe the characteristics of the data in a file and the way it will be processed at run time. The other parameters of the DD statement deal chiefly with the identity, location, and disposition of the file. The DCB parameter specifies information required for the processing of the records themselves. The subparameters of the DCB parameter are described in z/OS MVS JCL User’s Guide.

The DCB parameter contains subparameters that describe:
- The organization of the file and how it will be accessed. Parameters supplied on `fopen()` override those specified in DCB.
- Device-dependent information such as the recording technique for magnetic tape or the line spacing for a printer (for example: `CODE`, `DEN`, `FUNC`, `MODE`, `OPTCD=J`, `PRTSP`, `STACK`, `SPACE`, `UNIT` and `TRTCH` subparameters).
- The data set format (for example: `BLKSIZE`, `LRECL`, and `RECFM` subparameters).

You cannot use the DCB parameter to override information already established for the file in your C or C++ program (by the file attributes declared and the other attributes that are implied by them). DCB subparameters that attempt to change information already supplied by `fopen()` or `freopen()` are ignored. An example of the DCB parameter is:

```
DCB=(RECFM=FB,BLKSIZE=400,LRECL=40)
```

It specifies that fixed-length records, 40 bytes in length, are to be grouped in a block 400 bytes long. You can copy attributes from another data set by either setting the DCB parameter to DCB=`(dsname)` or using the SVC 99 services provided by the `svc99()` and `dynalloc()` library functions.
**Generation data group I/O**

A Generation Data Group (GDG) is a group of related cataloged data sets. Each data set within a generation data group is called a generation data set. Generation data sets have sequentially ordered absolute and relative names that represent their age. The absolute generation name is the representation used by the catalog management routines in the catalog. The relative name is a signed integer used to refer to the latest (0), the next to the latest (-1), and so forth, generation. The relative number can also be used to catalog a new generation (+1). For more information on GDGs, see *z/OS DFSMS Using Data Sets*.

If you want to open a generation data set by data set name with `fopen()` or `freopen()`, you will require a model. This model specifies parameters for the group, including the maximum number of generations (the generation index). You can define such a model by using the Access Method Services `DEFINE` command. For more information on the `DEFINE` command, see *z/OS DFSMS Access Method Services Commands*. Note also that `fopen()` does not support a `DCB=` parameter. If you want to change the parameters, alter the JCL that describes the model and open it in `w` mode.

*z/OS* uses an absolute generation and version number to catalog each generation. The generation and version numbers are in the form `GxxxxVyy`, where `xxxx` is an unsigned 4-digit decimal generation number (0001 through 9999) and `yy` is an unsigned 2-digit decimal version number (00 through 99). For example:

- `A.B.C.G0001V00` is generation data set 1, version 0, in generation data group `A.B.C`.
- `A.B.C.G0009V01` is generation data set 9, version 1, in generation data group `A.B.C`.

The number of generations kept depends on the size of the generation index.

When you open a GDG by relative number, *z/OS XL C/C++* returns the relative generation in the `_dsn` field of the structure returned by the `fldata()` function. You cannot use the `rename()` library function to rename GDGs by relative generation number; rename GDG data sets by using their absolute names.

The example shown in Figure 13 on page 88 is valid only for C. The sample program (CCNGOS1) defines a GDG. The `fopen()` fails because it tries to change the RECFM of the data set.
The example shown in Figure 14 on page 89 (CCNGOS2) is valid only C++.
A relative number used in the JCL refers to the same generation throughout a job. The (+1) used in the example above exists for the life of the entire job and not just the step, so that fopen()’s reference to (+1) did not create another new data set but accessed the same data set as in previous steps.

**Note:** You cannot use fopen() to create another generation data set because fopen() does not fully support the DCB parameter.

### Regular and extended partitioned data sets

Partitioned data sets (PDS) and partitioned data sets extended (PDSE) are DASD data sets divided into sections known as members. Each member can be accessed...
individually by its unique 1- to 8-character name. As Table 18 shows, PDSEs are similar to PDSs, but contain a number of enhancements.

Table 18. PDSE and PDS differences

<table>
<thead>
<tr>
<th>PDSE Characteristics</th>
<th>PDS Characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data set has a 123-extent limit</td>
<td>Data set has a 16-extent limit</td>
</tr>
<tr>
<td>Directory is open-ended and indexed by member name; faster to search directory</td>
<td>Fixed-size directory is searched sequentially</td>
</tr>
<tr>
<td>PDSEs are device-independent: records are reblockable</td>
<td>Block sizes are device-dependent</td>
</tr>
<tr>
<td>Uses dynamic space allocation and reclamation</td>
<td>Must use IEBCOPY COMPRESS to reclaim space</td>
</tr>
<tr>
<td>Supports creation of more than one member at a time*</td>
<td>Supports creation of only one member at a time</td>
</tr>
</tbody>
</table>

Note: *z/OS XL C/C++ allows you to open two separate members of a PDSE for writing at the same time. However, you cannot open a single member for writing more than once.

You specify a member by enclosing its name in parentheses and placing it after the data set name. For example, the following JCL refers to member A of the data set MY.DATA:

```
//MYDD DD DSN=userid.MY.DATA(A),DISP=SHR
```

You can specify members on calls to fopen() and freopen(). You can specify members when you are opening a data set by its data set name or by a ddname. When you use a ddname and a member name, the definition of the ddname must not also specify a member. For example, using the DD statement above, the following will fail:

```
fp = fopen("dd:MYDD(B)", "r");
```

You cannot open a PDS or PDSE member using the modes a, ab, a+, a+b, w+, w+b, or wb+. If you want to perform the equivalent of the w+ or wb+ mode, you must first open the file as w or wb, write to it, and then close it. Then you can perform updates by reopening the file in r+ or rb+ mode. You can use the C library functions ftell() or fgetpos() to obtain file positions for later updates to the member. Normally, opening a file in r+ or rb+ mode enables you to extend a file by writing to the end; however, with these modes you cannot extend a member. To do so, you must copy the contents of the old member plus any extensions to a new member. You can remove the old member by using the remove() function and then rename the new member to the old name by using rename().

All members have identical attributes for RECFM, LRECL, and BLKSIZE. For PDSs, you cannot add a member with different attributes or specify a RECFM of FBS, FBSA, or FBSM. z/OS XL C/C++ verifies any attributes you specify.

For PDSEs, z/OS XL C/C++ checks to make sure that any attributes you specify are compatible with those of the existing data set. Compatible attributes are those that specify the same record format (F, V, or U) and the same LRECL. Compatibility of attributes enables you to choose whether to specify blocked or unblocked format, because PDSEs reblock all the records. For example, you can create a PDSE as FB LRECL=40 BLKSIZE=80, and later open it for read as FB LRECL=40 BLKSIZE=1600 or F LRECL=40 BLKSIZE=40. The LRECL cannot change, and the BLKSIZE must be compatible with the RECFM and LRECL. Also, you cannot change the basic format of the PDSE from F to V or vice versa. If the PDS or PDSE
already exists, you do not need to specify any attributes, because z/OS XL C/C++ uses the previously existing ones as its defaults.

At the start of each partitioned data set is its directory, a series of records that contain the member names and starting locations for each member within the data set. You can access the directory by specifying the PDS or PDSE name without specifying a member. You can open the directory only for read; update and write modes are not allowed. The only RECFM that you can specify for reading the directory is RECFM=U. However, you do not need to specify the RECFM, because z/OS XL C/C++ uses U as the default.

z/OS DFSMS Using Data Sets contains more detailed explanations about how to use PDSs and PDSEs.

### Partitioned and sequential concatenated data sets

There are two forms of concatenated data sets: partitioned and sequential. You can open concatenated data sets only by ddname, and only for read or update. Specifying any of the write, or append modes fails. As with PDS members, you cannot extend a concatenated data set.

**Partitioned concatenation** consists of specifying multiple PDSs or PDSEs under one ddname. When you access the concatenation, it acts as one large PDS or PDSE, from which you can access any member. If two or more partitioned data sets in the concatenation contain a member with the same name, using the concatenation ddname to specify that member refers to the first member with that name found in the entire concatenation. You cannot use the ddname to access subsequent members. For example, if you have a PDS named PDS1, with members A, B, and C, and a second PDS named PDS2, with members C, D, and E, and you concatenate the two data sets as follows:

```plaintext
//MYDD DD userid.PDS1,DISP=SHR
// DD userid.PDS2,DISP=SHR
```

and perform the following:

```c
fp = fopen("DD:MYDD(C)","r");
fp2 = fopen("DD:MYDD(D)","r");
```

the first call to fopen() finds member C from PDS1, even though there is also a member C in PDS2. The second call finds member D from PDS2, because PDS2 is the first PDS in the concatenation that contains this member. The member C in PDS2 is inaccessible.

When you are concatenating partitioned data sets, be aware of the DCB attributes for them. The concatenation is treated as a single data set with the following attributes:

- RECFM= the RECFM of the first data set in the concatenation
- LRECL= the LRECL of the first data set in the concatenation
- BLKSIZE= the largest BLKSIZE of any data set in the concatenation

Table 19 describes the rules for compatible concatenations.

<table>
<thead>
<tr>
<th>RECFM of first data set</th>
<th>RECFM of subsequent data sets</th>
<th>LRECL of subsequent data sets</th>
</tr>
</thead>
<tbody>
<tr>
<td>RECFM=F</td>
<td>RECFM=F</td>
<td>Same as that of first one</td>
</tr>
</tbody>
</table>

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Table 19. Rules for possible concatenations (continued)

<table>
<thead>
<tr>
<th>RECFM of first data set</th>
<th>RECFM of subsequent data sets</th>
<th>LRECL of subsequent data sets</th>
</tr>
</thead>
<tbody>
<tr>
<td>RECFM=FB</td>
<td>RECFM=F or RECFM=FB</td>
<td>Same as that of first one</td>
</tr>
<tr>
<td>RECFM=V</td>
<td>RECFM=V</td>
<td>Less than or equal to that of first one</td>
</tr>
<tr>
<td>RECFM=VS</td>
<td>RECFM=V or RECFM=VS</td>
<td>Less than or equal to that of first one</td>
</tr>
<tr>
<td>RECFM=VB</td>
<td>RECFM=V or RECFM=VB</td>
<td>Less than or equal to that of first one</td>
</tr>
<tr>
<td>RECFM=VBS</td>
<td>RECFM=V, RECFM=VB, RECFM=VS, or RECFM=VBS</td>
<td>Less than or equal to that of first one</td>
</tr>
<tr>
<td>RECFM=U</td>
<td>RECFM=U or RECFM=F (see note)</td>
<td></td>
</tr>
</tbody>
</table>

Note: You can use a data set in V-format, but when you read it, you will see all of the BDWs and RDWs or SDWs with the data.

If the first data set is in ASA format, all subsequent data sets must be ASA as well. The preceding rules apply to ASA files if you add an A to the RECFMs specified.

If you do not follow these rules, undefined behavior occurs. For example, trying to read a fixed-format member as RECFM=V could cause an exception or abend.

Repositioning is supported as it is for regular PDSs and PDSEs. If you try to read the directory, you will be able to read only the first one.

**Sequential concatenation** consists of treating multiple sequential data sets or partitioned data set members as one long sequential data set.

```c
//MYDD DD userid.PDS1(A),DISP=SHR
// DD userid.PDS2(E),DISP=SHR
// DD userid.DATA,DISP=SHR
```

creates a concatenation that contains two members and a regular sequential data set. You can read or update all of these in order. In partitioned concatenations, you can read only one member at a time.

z/OS XL C/C++ does not support concatenating data sets that do not have compatible DCB attributes. The rules for compatibility are the same as those for partitioned concatenations.

If all the data sets in the concatenation support repositioning, you can reposition within a concatenation by using the functions fseek(), ftell(), fgetpos(), fsetpos(), and rewind(). If the first one does not, all of the repositioning functions except rewind() fail for the entire concatenation. If the first data set supports repositioning but a subsequent one does not, you must specify the noseek() parameter on the fopen() or freopen() call. If you do not, fopen() or freopen() opens the file successfully; however, an error occurs when the read position gets to the data set that does not support repositioning.

Note: Concatenated and multivolume data sets only tolerate single buffering mode.
In-stream data sets

An in-stream data set is a data set contained within a set of JCL statements. In-stream data sets (also called inline data sets) begin with a DD * or DD DATA statement. These DD statements can have any valid ddname, including SYSIN. If you omit a DD statement before the input data, the system provides a DD * statement with the ddname of SYSIN. This example shows you how to indicate an in-stream data set:

```c
//MYDD DD *
record 1
record 2
record 3
/*
```

The // at the beginning of the data set starts in column 1. The statement `fopen("DD:MYDD","rb");` opens a data set with lrecl=80, blksize=80, and recfm=FB. In this example, the delimiter indicating the end of the data set is /*. In some cases, your data may contain this string. For example, if you are using C source code that contains comments, z/OS XL C/C++ treats the beginning of the first comment as the end of the in-stream data set. To avoid this occurrence, you can change the delimiter by specifying DLM=nn, where nn is a two-character delimiter, on the DD statement that identifies the file. For example:

```c
//MYDD DD *,DLM="¢¢"
#include <stdio.h>
/* Hello, world program */
int main() {printf("Hello, world\n"); }
00
```

For more information about in-stream data sets, see z/OS MVS JCL User’s Guide.

To open an in-stream data set, call the fopen() or freopen() library function and specify the ddname of the data set. You can open an in-stream data set only for reading. Specifying any of the update, write, or append modes fails. Once you have opened an in-stream data set, you cannot acquire or change the file position except by rewinding. This means that calls to the fseek(), ftell(), fgetpos(), and fsetpos() for in-stream data sets fail. Calling rewind() causes z/OS XL C/C++ to reopen the file, leaving the file position at the beginning.

You can concatenate regular sequential data sets and in-stream data sets. If you do so, note the following:
- If the first data set is in-stream, you cannot acquire or change the file position for the entire concatenation.
- If the first data set is not in-stream and supports repositioning, you must specify the noseek parameter on the fopen() or freopen() call that opens the concatenation. If you do not, fopen() or freopen() opens the file successfully; however, an error occurs when the read position gets to the in-stream.
- The in-stream data set is treated as FB 80 and the concatenation rules for sequential concatenation apply.

SYSOUT data sets

You can specify a SYSOUT data set by using the SYSOUT parameter on a DD statement. z/OS XL C/C++ supports opening SYSOUT data sets in two ways:
1. Specifying a ddname that has the SYSOUT parameter. For information about defining ddnames, see "Using a DDname" on page 85.

2. Specifying a data set name of * on a call to fopen() or freopen() while you are running under z/OS batch or IMS online or batch.

On a DD statement, you specify SYSOUT=*, where x is the output class. If the class matches the JOB statement MSGCLASS, the output appears with the job log. You can specify a SYSOUT data set and get the job MSGCLASS by specifying SYSOUT=*.

For more details about the SYSOUT parameter, refer to z/OS MVS JCL User’s Guide.

You can specify DCB attributes for a SYSOUT data set on a DD statement or a call to fopen() or freopen(). If you do not, z/OS XL C/C++ uses the following defaults:

**Binary, Record I/O, or Blocked I/O**

RECFM=VB LRECL=137 BLKSIZE=882

**Text I/O**

RECFM=VBA LRECL=137 BLKSIZE=882

### Tapes

z/OS XL C/C++ supports standard label (SL) tapes. If you are creating tape files, you can only open them by ddname. z/OS XL C/C++ provides support for opening tapes in read, write, or append mode, but not update. When you open a tape for read or append, any data set control block (DCB) characteristics you specify must match those of the existing data set exactly. The repositioning functions are available only when you have opened a tape for read. For tapes opened for write or append, calling rewind() has no effect; calls to any of the other repositioning functions fail. To open a tape file for write, you must open it by ddname.

Opening FBS-format tape files with append-only mode is not supported.

When you open a tape file for output, the data set name you specify in the JCL must match the data set name specified in the tape label, even if the existing tape file is empty. If this is not the case, you must either change the JCL to specify the correct data set name or write to another tape file, or reinitialize the tape to remove the tape label and the data. You can use IEBGENER with the following JCL to create an empty tape file before passing it to the subsequent steps:

```c
//ALLOC EXEC PGM=IEBGENER
//SYSUT1 DD *aison-of-OUTPUT-tape-file,UNIT=xxxx,LABEL=(x,SL),
// DISP=(NEW,PASS),(DCB=LRECL=xx,BLKSIZE=xx,RECFM=xx)
// VOL=SER=xxx
//SYSIN DD DUMMY
//SYSPRINT DD SYSOUT=*asion
```

**Note:** For tapes, the value for UNIT= can be TAPE or CART.
Because the C library does not create tape files, you can append only to a tape file that already exists. Attempting to append to a file that does not already exist on a tape will cause an error. You can create an empty data set on a tape by using the utility IEBGENER.

**Multivolume data sets**

z/OS XL C/C++ supports data sets that span more than one volume of DASD or tape. You can open multivolume DASD data sets for read (r, rb), write (w, wb), update (r+, rb+, w+, wb+), or append (a, a+, ab, ab+) by dsname and ddname. Multivolume data sets can be extended only in read/update mode (r+, rb+).

The repositioning functions are available when you have opened a multivolume data set for r, r+, rb, rb+, w+, wb+, a+, ab+. Repositioning multivolume data sets opened for w, wb, a, ab is not allowed because it would be meaningless. For multivolume data sets opened for write, calling rewind() has no effect; calls to any of the other repositioning functions fail.

Here is an example of a multivolume data set declaration:

```plaintext
//MYDD DD DSNAME=TEST.TWO,DISP=(NEW,CATLG),
//   VOLUME=(,,3,SER=(333001,333002,333003)),
//   SPACE=(TRK,(9,10)),UNIT=(3390,P)
```

This creates a data set that may span up to three volumes. For more information about the VOLUME parameter on DD statements, refer to z/OS MVS JCL User's Guide.

**Notes:**

1. Simultaneous readers (files that can support sharing by a writer and one or more readers) are not supported for multivolume data sets.
2. Concatenated and multivolume data sets only tolerate single buffering mode.

**Striped data sets**

z/OS XL C/C++ supports extended format sequential data sets. Extended format data sets must be SMS-managed. Optionally, extended format data sets can be striped. Stripping spreads a data set over a specified number of volumes such that I/O parallelism can be exploited. Unlike a multivolume data set in which physical record $n$ follows record $n-1$, a striped data set has physical records $n$ and $n-1$ on separate volumes. This enables asynchronous I/O to perform parallel operations, making requests for multiple reads and writes faster.

Striped data sets also facilitate repositioning once the relative block number is known. z/OS XL C/C++ exploits this capability when it uses fseek() to reposition. This can result in substantial savings for applications that use ftell() and fseek() with data sets that have RECFMs of V, U, and FB (not FBS). data sets. When a data set is striped, an fseek() can seek directly to the specified block just as an fsetpos() or rewind() can. For a normal data set with the aforementioned RECFMs, z/OS XL C/C++ has to read forward or rewind the data set to get to the desired position. Depending on how large the data set is, this can be quite inefficient compared to a direct reposition. Note that for such data sets, striping pads blocks to their maximum size. Therefore, you may be wasting space if you have short records.
Large format sequential data sets

A large format sequential data set is a modification to traditional sequential data sets that allows for more than 65535 tracks of data per volume. Large format sequential data sets can be single or multivolume, and can reside on SMS managed or non-SMS managed direct access storage devices.

A large format sequential data set is specified using the DSNTYPE=LARGE keyword on a JCL DD statement or using the dynamic allocation equivalent. z/OS XL C/C++ does not support the allocation of a large format sequential data set using fopen() or freopen().

z/OS XL C/C++ provides complete read and write support for:

- Large format sequential data sets when seek is requested (not specifying the noseek keyword).
- Large format sequential data sets when noseek is requested and honored. See "Access method selection" on page 97 for more information on when noseek is requested but not honored.

Note: Restrictions associated with traditional sequential single and multivolume data sets, or concatenations of such data sets, continue to apply when the data set is large format.

Other devices

z/OS XL C/C++ supports several other devices for input and output. You can open these devices only by ddname. Table 20 lists a number of these devices and describes which record formats are valid for them. None of the devices listed can be opened for update except the DUMMY data set.

<table>
<thead>
<tr>
<th>Device</th>
<th>Valid open modes</th>
<th>Repositioning?</th>
<th>fldata()__device</th>
</tr>
</thead>
<tbody>
<tr>
<td>Printer</td>
<td>w, wb, a, ab</td>
<td>No</td>
<td>__PRINTER</td>
</tr>
<tr>
<td>Card reader</td>
<td>r, rb</td>
<td>rewind() only</td>
<td>__OTHER</td>
</tr>
<tr>
<td>Card punch</td>
<td>w, wb, a, ab</td>
<td>No</td>
<td>__OTHER</td>
</tr>
<tr>
<td>Optical reader</td>
<td>r, rb</td>
<td>rewind() only</td>
<td>__OTHER</td>
</tr>
<tr>
<td>DUMMY data set</td>
<td>r, rb, r+, rb+, r+b, w, wb, w+, wb+ w+b, a, ab, a+, ab+, a+b</td>
<td>rewind() only</td>
<td>__DUMMY</td>
</tr>
<tr>
<td>SUBSYS=</td>
<td>r, rb</td>
<td>No</td>
<td>__OTHER</td>
</tr>
</tbody>
</table>

Note: For all devices above that support open modes a or ab, the modes are treated as if you had specified w or wb.

z/OS XL C/C++ queries each device to find out its maximum BLKSIZE.

The DUMMY data set is not truly a device, although z/OS XL C/C++ treats it as one. To use the DUMMY data set, specify DD DUMMY in your JCL. On input, the DUMMY data set always returns EOF; on output, it is always successful. This is the way to specify a DUMMY data set:

    //MYDD DD DUMMY

For more information on DUMMY data sets, see z/OS MVS JCL User’s Guide.
z/OS XL C/C++ provides minimal support for subsystem (SUBSYS=) managed data sets. Support is limited to opening for read using the dd:ddname(member) syntax with the fopen() filename. The ddname in the JCL stream must specify the SUBSYS= parameter. In this case, fopen() will open the DCB as DSORG=PS, required for subsystem managed data sets, but will perform the BLDL/FIND sequence to allow the subsystem to manage processing of the desired member.

**Access method selection**

The fopen() and freopen() keyword noseek requests QSAM (queued sequential access method) be used to process the data set. This request also indicates that the repositioning functions will not be used by the application. This access method generally provides the best performance. Omitting the keyword noseek selects BSAM (basic sequential access method) with NOTE and POINT macros requested, allowing repositioning functions to be used (where applicable) on the stream.

The following scenarios exist where QSAM (noseek) is requested, but the z/OS XL C/C++ runtime Library switches to BSAM with NOTE and POINT macros requested (seek):

- The data set is opened for update (r+, rb+, w+, wb+, a+, ab+)
- The data set is already opened for write (or update) in the same C process
- The data set is RECFM=FBS opened for append (a, ab, a+, ab+)
- The data set is LRECL=X
- The data set is the directory of a partitioned data set (PDS or PDSE)
- The data set is a member of a partitioned data set where the member was not specified at allocation, but rather specified at fopen() or freopen()

**Note:** Repositioning is not allowed when noseek is requested, even if there was a switch to seek.

**fopen() and freopen() parameters**

Table 21 lists the parameters that are available on the fopen() and freopen() functions, tells you which ones are allowed and applicable for OS I/O, and lists the option values that are valid for the applicable ones. Detailed descriptions of these options follow the table.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>recfm=</td>
<td>Yes</td>
<td>Yes</td>
<td>Any of the 27 record formats available under z/OS XL C/C++, plus * and A are valid.</td>
</tr>
<tr>
<td>lrecl=</td>
<td>Yes</td>
<td>Yes</td>
<td>0, any positive integer up to 32760, or X is valid. See the parameter list below.</td>
</tr>
<tr>
<td>blksize=</td>
<td>Yes</td>
<td>Yes</td>
<td>0 or any positive integer up to 32760 is valid.</td>
</tr>
<tr>
<td>space=</td>
<td>Yes</td>
<td>Yes</td>
<td>Valid only if you are opening a new data set by its data set name. See the parameter list below.</td>
</tr>
<tr>
<td>type=</td>
<td>Yes</td>
<td>Yes</td>
<td>May be omitted. If you do specify it, type=record or type=blocked can be the valid values.</td>
</tr>
<tr>
<td>acc=</td>
<td>Yes</td>
<td>No</td>
<td>Not used for OS I/O.</td>
</tr>
<tr>
<td>password=</td>
<td>Yes</td>
<td>No</td>
<td>Not used for OS I/O.</td>
</tr>
<tr>
<td>asis</td>
<td>Yes</td>
<td>No</td>
<td>Used to specify mixed-case filenames. Not recommended.</td>
</tr>
</tbody>
</table>
Table 21. Parameters for the fopen() and freopen() functions for z/OS OS I/O (continued)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>byteseek</td>
<td>Yes</td>
<td>Yes</td>
<td>Used for binary files to specify that the seeking functions should use relative byte offsets instead of encoded offsets.</td>
</tr>
<tr>
<td>noseek</td>
<td>Yes</td>
<td>Yes</td>
<td>Used to disable seeking functions for improved performance.</td>
</tr>
<tr>
<td>OS</td>
<td>Yes</td>
<td>No</td>
<td>Ignored.</td>
</tr>
<tr>
<td>abend=</td>
<td>Yes</td>
<td>Yes</td>
<td>See note below.</td>
</tr>
</tbody>
</table>

**recfm=**

z/OS XL C/C++ allows you to specify any of the 27 possible RECFM types (listed in “Fixed-format records” on page 12, “Variable-format records” on page 16, and “Undefined-format records” on page 19), as well as the z/OS XL C/C++ RECFMs * and A.

When you are opening an existing file for read or append (or for write, if you have specified DISP=MOD), any RECFM that you specify must match that of the existing file, except that you may specify recfm=U to open any file for read, and you may specify recfm=FBS for a file created as recfm=FB. Specifying recfm=FBS indicates to z/OS XL C/C++ that there are no short blocks within the file. If there are, undefined behavior results.

For variable-format OS files, the RDW, SDW, and BDW contain the length of the record, segment, and block as well as their own lengths. If you open a file for read with recfm=U, z/OS XL C/C++ treats each physical block as an undefined-format record. For files created with recfm=V, z/OS XL C/C++ does not strip off block descriptor words (BDWs) or record descriptor words (RDWs), and for blocked files, it does not deblock records. Using recfm=U is helpful for viewing variable-format files or seeing how records are blocked in the file.

When you are opening an existing PDS or PDSE for write and you specify a RECFM, it must be compatible with the RECFM of the existing data set. FS and FBS formats are invalid for PDS members. For PDSs, you must use exactly the same RECFM. For PDSEs, you may choose to change the blocked attribute (B), because PDSEs perform their own blocking. If you want to read a PDS or PDSE directory and you specify a RECFM, it must be recfm=U.

Specifying recfm=A indicates that the file contains ASA control characters. If you are opening an existing file and you specify that ASA characters exist (>recfm=A) when they do not, the call to fopen() or freopen() fails. If you create a file by opening it for write or append, the A attribute is added to the default RECFM. For more information about ASA, see Chapter 7, “Using ASA text files,” on page 47.

Specifying recfm=* causes z/OS XL C/C++ to fill in any attributes that you do not specify, taking the attributes from the existing data set. This is useful if you want to create a new version of a data set with the same attributes as the previous version. If you open a data set for write and the data set does not exist, z/OS XL C/C++ uses the default attributes specified in “fopen() defaults” on page 34. This parameter has no effect when you are opening for read or append, and when you use it for non-DASD files.

recfm+= is identical to recfm=* with the following exceptions:

- If there is no record format for the existing DASD data set, the defaults are assigned as if the data set did not exist.
When append mode is used, the fopen() fails.

lrecl= and blksize=

The LRECL that you specify on the fopen() call defines the maximum record length that the C library allows. Records longer than the maximum record length are not written to the file. The first 4 bytes of each block and the first 4 bytes of each record of variable-format files are used for control information. For more information, see "Variable-format records" on page 16.

The maximum LRECL supported for fixed, undefined, or variable-blocked-spanned format sequential disk files is 32760. For other variable-length format disk files the maximum LRECL is 32756. Sequential disk files for any format have a maximum BLKSIZE of 32760. The record length can be any size when opening a spanned file and specifying lrecl=X. You can now specify lrecl=X on the fopen() or freopen() call for spanned files. If you are updating an existing file, the file must have been originally opened with lrecl=X for the open to succeed. lrecl=X is useful only for text, record I/O, and blocked I/O.

When you are opening an existing file for read or append (or for write, if you have specified DISP=MOD), any LRECL or BLKSIZE that you specify must match that of the existing file, except when you open an F or FB format file on a disk device without specifying the noseek parameter. In this case, you can specify the $ attribute to indicate to z/OS XL C/C++ that the file has no imbedded short blocks. Files without short blocks improve the performance of z/OS XL C/C++.

BLKSIZE=0 will be ignored for an existing data set opened for read or append.

When you are opening an existing PDS or PDSE for write and you specify an LRECL or BLKSIZE, it must be compatible with the LRECL or BLKSIZE of the existing data set. For PDSs, you must use exactly the same values. For PDSEs, the LRECL must be the same, but the BLKSIZE may be different if you have changed the blocking attribute as described under the RECFM parameter above. You can change the blocking attribute, because PDSEs perform their own blocking. The BLKSIZE you choose should be compatible with the RECFM and LRECL. When you open the directory of a PDS or PDSE, do not specify LRECL or BLKSIZE; z/OS XL C/C++ uses the defaults. See Table 22 on page 104 for more information.

space=(units, (primary, secondary, directory) [rlse | norlse])

This keyword enables you to specify the space parameters for the allocation of a z/OS data set. It applies only to z/OS data sets that you open by filename and do not already exist. If you open a data set by ddname, this parameter has no effect. You cannot specify any whitespace inside the value for the space keyword. You must specify at least one value with this parameter. Any parameter that you specify will be validated for syntax. If that validation fails, then the fopen() or freopen() will fail even if the parameter would have been ignored.

The supported values for units are as follows:
- Any positive integer indicating BLKSIZE
- CYL (mixed case)
- TRK (mixed case)

The primary quantity, the secondary quantity, and the directory quantity all must be positive integers. The primary quantity is always required.

If you specify values only for units and primary, you do not have to specify the inside set of parentheses. You can use a comma to indicate a quantity is to take
the default value. For example:

```
space=(cyl,(100,,10)) - default secondary value
space=(trk,(100,,)) - default secondary and directory value
space=(500,(100,)) - default secondary, no directory
```

The last parameter, rlse or norlse, controls the disposition of the unused space. If you open a new file for write and specify the space keyword, by default, any unused space will be released when the file is closed. You can preserve the allocated space by specifying norlse. For example:

```
space=(cyl,(100,,10),norlse) - does not release unused space
space=(trk,(100,,),rlse) - releases unused space
pace=(500,(100,)) - releases unused space
```

You can specify only the values indicated on this parameter. If you specify any other values, fopen() or freopen() fails. Any values not specified are omitted on the allocation. These values are filled by the system during SVC 99 processing.

type=
You can omit this parameter. If you specify it, the valid values for OS I/O are type=record which opens a file for record I/O, and type=blocked which opens a file for blocked I/O.

acc=
This parameter is not valid for OS I/O. If you specify it, z/OS XL C/C++ ignores it.

password=
This parameter is not valid for OS I/O. If you specify it, z/OS XL C/C++ ignores it.

asis
If you use this parameter, z/OS XL C/C++ does not convert your filenames to upper case. The use of the asis parameter is strongly discouraged, because most of the I/O services used by z/OS XL C/C++ require uppercase filenames.

bytesseek
When you specify this parameter and open a file in binary mode, all repositioning functions (such as fseek() and ftell()) use relative byte offsets from the beginning of the file instead of encoded offsets. In previous releases of z/OS XL C/C++, byteseeking was performed only for fixed format binary files. To have the byteseek parameter set as the default for all your calls to fopen() or freopen(), you can set the environment variable _EDC_BYTESEEK to Y. See Chapter 32, “Using environment variables,” on page 467 for more information.

noseek
Specifying this parameter on the fopen() call disables the repositioning functions ftell(), fseek(), fgetpos(), and fsetpos() for as long as the file is open. When you have specified NOSEEK and have opened a disk file for read only, the only repositioning function allowed on the file is rewind(), if the device supports rewinding. Otherwise, a call to rewind() sets errno and raises SIGIOERR, if SIGIOERR is not set to SIG_IGN. Calls to ftell(), fseek(), fgetpos(), or fsetpos() return EOF, set errno, and set the stream error flag on.
The use of the noseek parameter may improve performance when you are reading and writing data sets.

**Note:** If you specify the NOSEEK parameter when you open a file for writing, you must specify NOSEEK on any subsequent fopen() call that simultaneously opens the file for reading; otherwise, you will get undefined behavior.

**OS**

If you specify this parameter, z/OS XL C/C++ ignores it.

**abend= abend | recover**

This parameter is ignored for SPC applications. The z/OS XL C/C++ runtime library uses the DCB ABEND exit to intercept abend conditions that occur during OS I/O operations. When an abend condition occurs, DFSMS issues a write-to-programmer message and gives control to the DCB ABEND exit. Within the information provided to the exit, a flag indicates if the abend condition can be ignored. It is not predictable when an abend condition can be ignored, and sometimes the same abend condition (completion code and reason code) can be ignored while at other times it cannot.

When the abend condition can be ignored, the runtime library instructs DFSMS to do so. This allows the runtime library to return gracefully back to the user code with a failing return value, errno set to 92 (meaning an I/O abend was trapped), and diagnostic information in the __amrc structure. DFSMS will have stopped processing the DCB. Only the fldata(), fclose(), and freopen() functions are permitted on the stream after an abend condition is trapped.

When the abend condition cannot be ignored, DFSMS issues the abend and Language Environment condition handling semantics take effect. If condition handling is active, the abend is converted to a Language Environment condition or SIGABND signal. In the absence of a condition handler or signal handler, the default behavior is to terminate the enclave. An application can write its own condition handler or SIGABND handler and try to recover from the error. As is the case when an abend condition can be ignored, DFSMS will have stopped processing the DCB and only the fldata(), fclose(), and freopen() functions are permitted on the stream.

**abend** instructs the runtime library to ignore abend conditions that can be ignored. No attempt is made to recover from abend conditions that cannot be ignored.

**recover**

instructs the runtime library to attempt to recover from an abend issued during certain low-level I/O operations (WRITE / CHECK sequence, CLOSE, GET, and PUT). If recovery is possible, control will be returned to the user code with a failing return value, errno set to 92, and diagnostic information in the __amrc structure.

The abend keyword specifies the behavior only for the stream being opened. It overrides the setting of the _EDC_IO_ABEND environment variable. See Chapter 32, “Using environment variables,” on page 467 for more information. Also, see Chapter 18, “Debugging I/O programs,” on page 223 for more information on the __amrc structure and handling errors during I/O operations.

### Buffering

z/OS XL C/C++ uses buffers to map C I/O to system-level I/O. When z/OS XL C/C++ performs I/O operations, it uses one of the following buffering modes:
• **Line buffering** — characters are transmitted to the system when a new-line character is encountered. Line buffering is meaningless for binary, record I/O, and blocked I/O files.

• **Full buffering** — characters are transmitted to the system when a buffer is filled.

C/C++ provides a third buffering mode, unbuffered I/O, which is not supported for OS files.

You can use the `setvbuf()` and `setbuf()` library functions to set the buffering mode before you perform any I/O operation to the file. `setvbuf()` fails if you specify unbuffered I/O. It also fails if you try to specify line buffering for an FBS data set opened in text mode, where the device does not support repositioning. This failure happens because z/OS XL C/C++ cannot deliver records at line boundaries without violating FBS format. Do not try to change the buffering mode after you have performed any I/O operation to the file.

For all files except `stderr`, full buffering is the default, but you can use `setvbuf()` to specify line buffering. For binary files, record I/O files, and unblocked text files, a block is written out as soon as it is full, regardless of whether you have specified line buffering or full buffering. For blocked I/O files, a block is written out as soon as `fwrite()` completes. Line buffering is different from full buffering only for blocked text files.

**Multiple buffering**

Multiple buffering (or asynchronous I/O) is supported for z/OS data sets. Multiple buffering is not supported for a data set opened for read at the same time that another file pointer has it opened for write or append. When you open files for multiple buffering, blocks are read into buffers before they are needed, eliminating the delay caused by waiting for I/O to complete. Multiple buffering may make I/O less efficient if you are seeking within or writing to a file, because seeking or writing may discard blocks that were read into buffers but never used.

To specify multiple buffering, code either the `NCP=xx` or `BUFNO=yy` subparameter of the DCB parameter on the JCL DD statement (or allocation), where `xx` is an integer number between 02 and 99, and `yy` is an integer number normally between 02 and 255. Whether z/OS XL C/C++ uses `NCP` or `BUFNO` depends on whether you are using BSAM or QSAM, respectively. `NCP` is supported under BSAM; `BUFNO` is supported under QSAM. BSAM and QSAM are documented in z/OS DFSMS Using Data Sets. If you specify `noseek`, z/OS XL C/C++ uses QSAM if possible. If z/OS XL C/C++ is using BSAM and you specify a value for `BUFNO`, z/OS XL C/C++ maps this value to `NCP`. If z/OS XL C/C++ is using QSAM and you specify a value for `NCP`, z/OS XL C/C++ maps this value to `BUFNO`.

If you specify both `NCP` and `BUFNO`, z/OS XL C/C++ takes the greater of the two values, up to the maximum for the applicable value. For example, if you specify a `BUFNO` of 120 and you are using BSAM, which uses `NCP` instead, z/OS XL C/C++ will use `NCP=99`.

If you do not specify either, z/OS XL C/C++ defaults to single buffering, except in the following cases, where z/OS XL C/C++ uses the system’s default `BUFNO` and performs multiple buffering for both reading and writing:

- If you open a device that does not support repositioning, and specify read-only or write-only mode (`r`, `rb`, `w`, `wb`, `a`, `ab`).

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If you specify the NOSEEK parameter on the call to fopen() or freopen(), and specify read-only or write-only mode. When you specify NOSEEK, you get multiple buffering for both reads and writes.

Here is an example of how to specify BUFNO:

```c
//DD5 DD DSNAME=TORONTO.BLUEJAYS,DISP=SHR,DCB=(BUFNO=5)
```

You may need to update code from previous releases that relies on z/OS XL C/C++ ignoring NCP or BUFNO parameters.

**Note:** Multiple buffering is ignored for concatenated and multivolume data sets.

### DCB (Data Control Block) attributes

For OS files, the C runtime library creates a skeleton data control block (DCB) for the file when you open it. File attributes are determined from the following sources in this order:

1. The fopen() or freopen() function call
2. Attributes for a ddname specified previously (if you are opening by ddname)
3. Existing file attributes (if you specify recfm= or you are opening an existing file for read or append)
4. Defaults from fopen() or freopen() for creating a new file.

If you do not specify RECFM when you are creating a new file, z/OS XL C/C++ uses the following defaults:

- If recfm is not specified in a fopen() call for an output binary file, recfm defaults to:
  - recfm=VB for spool (printer) files,
  - recfm=FB otherwise.

- If recfm is not specified in a fopen() call for an output text file, recfm defaults to:
  - recfm=F if \_EDC\_ANSI\_OPEN\_DEFAULT is set to Y and no LRECL or BLKSIZE specified. In this case, LRECL and BLKSIZE are both defaulted to 254.
  - recfm=VBA for spool (printer) files.
  - recfm=U for terminal files
  - recfm=Y if the LRECL or BLKSIZE is specified
  - recfm=VB for all other OS files.

If recfm is not specified for a record I/O or blocked I/O file, you will get the default of recfm=VB. [Table 22 on page 104](#) shows the defaults for LRECL and BLKSIZE when the z/OS XL C/C++ compiler creates an OS file. Information from the C or C++ program overrides that from the DD statement and the tape label. Information from the DD statement overrides that from the data set label.
## Table 22. fopen() defaults for LRECL and BLKSIZE when creating OS files

<table>
<thead>
<tr>
<th>lrecl specified?</th>
<th>blksize specified?</th>
<th>RECFM</th>
<th>LRECL</th>
<th>BLKSIZE</th>
</tr>
</thead>
<tbody>
<tr>
<td>no</td>
<td>no</td>
<td>All F</td>
<td>80</td>
<td>80</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All FB</td>
<td>80</td>
<td>maximum integral multiple of 80 less than or equal to max</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All V, VB, VS, or VBS</td>
<td>minimum of 1028 or max–4</td>
<td></td>
</tr>
<tr>
<td>yes</td>
<td>no</td>
<td>All U</td>
<td>0</td>
<td>max</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All F</td>
<td>lrecl</td>
<td>lrecl</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All FB</td>
<td>lrecl</td>
<td>maximum integral multiple of lrecl less than or equal to max</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All V</td>
<td>lrecl</td>
<td>lrecl+4</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All U</td>
<td>0</td>
<td>lrecl</td>
</tr>
<tr>
<td>no</td>
<td>yes</td>
<td>All F or FB</td>
<td>blksize</td>
<td>blksize</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All V, VB, VS, or VBS</td>
<td>minimum of 1028 or blksize–4</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>All U</td>
<td>0</td>
<td>blksize</td>
</tr>
</tbody>
</table>

**Note:** All includes the standard (S) specifier for fixed formats, the ASA (A) specifier, and the machine control character (M) specifier.

In Table 22, the value max represents the maximum reasonable block size for the device. These are the current default maximum block sizes for several devices that z/OS XL C/C++ supports:

**Device Default maximum block size**
For more information about specific default block sizes as returned by the \texttt{DEVTYPE} macro, refer to \textit{z/OS DFSMS Using Data Sets}.

You can perform multiple buffering under z/OS. See \textit{“Multiple buffering” on page 102} for details.

## Reading from files

You can use the following library functions to read from a file:

- \texttt{fread()}
- \texttt{fread_unlocked()}
- \texttt{fgetc()}
- \texttt{fgetc_unlocked()}
- \texttt{fgets()}
- \texttt{fgets_unlocked()}
- \texttt{fscanf()}
- \texttt{fscanf_unlocked()}
- \texttt{getc()}
- \texttt{getc_unlocked()}
- \texttt{gets()}
- \texttt{gets_unlocked()}
- \texttt{getchar()}
- \texttt{getchar_unlocked()}
- \texttt{scanf()}
- \texttt{scanf_unlocked()}
- \texttt{vfscanf()}
- \texttt{vfscanf_unlocked()}
- \texttt{vscanf()}
- \texttt{vscanf_unlocked()}

\texttt{fread()} is the only interface allowed for reading record I/O or blocked I/O files. Except for blocked I/O files, a read operation directly after a write operation
without an intervening call to fflush(), fsetpos(), fseek(), or rewind() fails.

z/OS XL C/C++ treats the following as read operations:

- Calls to read functions that request 0 bytes
- Read requests that fail because of a system error
- Calls to the ungetc() function

z/OS XL C/C++ does not consider a read to be at EOF until you try to read past the last byte visible in the file. For example, in a file containing three bytes, the feof() function returns FALSE after three calls to fgetc(). Calling fgetc() one more time causes feof() to return TRUE.

You can set up a SIGIOERR handler to catch read or write system errors. See the debugging section in this book for more details.

Reading from binary files

z/OS XL C/C++ reads binary records in the order that they were written to the file. Any null padding is visible and treated as data. Record boundaries are meaningless.

Reading from text files

For non-ASA variable text files, the default for z/OS XL C/C++ is to ignore any empty physical records in the file. If a physical record contains a single blank, z/OS XL C/C++ reads in a logical record containing only a new-line. However, if the environment variable _EDC_ZERO_RECLEN was set to Y, z/OS XL C/C++ reads an empty physical record as a logical record containing a new-line, and a physical record containing a single blank as a logical record containing a blank and a new-line. z/OS XL C/C++ differentiates between empty records and records containing single blanks, and does not ignore either of them. For more information about how z/OS XL C/C++ treats empty records in variable format, see “Mapping C types to variable format” on page 18.

For ASA variable text files, if a file was created without a control character as its first byte, the first byte defaults to the ‘ ’ character. When the file is read back, the first character is read as a new-line.

On input, ASA characters are translated to the corresponding sequence of control characters. For more information about using ASA files, refer to Chapter 7, “Using ASA text files,” on page 47.

For undefined format text files, reading a file causes a new-line character to be inserted at the end of each record. On input, a record containing a single blank character is considered an empty record and is translated to a new-line character. Trailing blanks are preserved for each record.

For files opened in fixed text format, rightmost blanks are stripped off a record at input, and a new-line character is placed in the logical record. This means that a record consisting of a single new-line character is represented by a fixed-length record made entirely of blanks.

Reading from record I/O files

For files opened in record format, fread() is the only interface that supports reading. Each time you call fread() for a record I/O file, fread() reads one record. If you call fread() with a request for less than a complete record, the requested bytes are copied to your buffer, and the file position is set to the start of the next
record. If the request is for more bytes than are in the record, one record is read and the position is set to the start of the next record. z/OS XL C/C++ does not strip any blank characters or interpret any data.

`fread()` returns the number of items read successfully, so if you pass a `size` argument equal to 1 and a `count` argument equal to the maximum expected length of the record, `fread()` returns the length, in bytes, of the record read. If you pass a `size` argument equal to the maximum expected length of the record, and a `count` argument equal to 1, `fread()` returns either 0 or 1, indicating whether a record of length `size` read. If a record is read successfully but is less than `size` bytes long, `fread()` returns 0.

A failed read operation may lead to undefined behavior until you reposition successfully.

**Reading from blocked I/O files**

For files opened in blocked format, `fread()` is the only interface that supports reading. Each time you call `fread()` for a blocked I/O file, `fread()` reads one block. If you call `fread()` with a request for less than a complete block, the requested bytes are copied to your buffer, and the file position is set to the start of the next block. If the request is for more bytes than are in the block, one block is read and the position is set to the start of the next block. z/OS XL C/C++ does not strip any blank characters or interpret any data.

`fread()` returns the number of items read successfully, so if you pass a `size` argument equal to 1 and a `count` argument equal to the maximum expected length of the block, `fread()` returns the length, in bytes, of the block read. If you pass a `size` argument equal to the maximum expected length of the block, and a `count` argument equal to 1, `fread()` returns either 0 or 1, indicating whether a block of length `size` read. If a block is read successfully but is less than `size` bytes long, `fread()` returns 0.

A failed read operation may lead to undefined behavior until you reposition successfully.

**Writing to files**

You can use the following library functions to write to a file:

- `fwrite()`
- `fwrite_unlocked()`
- `printf()`
- `printf_unlocked()`
- `fprintf()`
- `fprintf_unlocked()`
- `vprintf()`
- `vprintf_unlocked()`
- `vfprintf()`
- `vfprintf_unlocked()`
- `puts()`
- `puts_unlocked()`
- `fputc()`
- `fputc_unlocked()`
- fputs()
- fputs_unlocked()
- putc()
- putc_unlocked()
- putchar()
- putchar_unlocked()

`fwrite()` is the only interface allowed for writing to record I/O or blocked I/O files. See z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

A write operation directly after a read operation without an intervening call to `fflush()`, `fsetpos()`, `fseek()`, or `rewind()` fails unless the read operation has reached EOF. The file pointer does not reach EOF until after you have tried to read past the last byte of the file.

z/OS XL C/C++ counts a call to a write function writing 0 bytes or a write request that fails because of a system error as a write operation.

If you are updating a file and a system failure occurs, z/OS XL C/C++ tries to set the file position to the end of the last record updated successfully. For a fully-buffered file, this is at the end of the last record in a block. For a line-buffered file, this may be any record in the current block. If you are writing new data at the time of a system failure, z/OS XL C/C++ puts the file position at the end of the last block of the file. In files opened for blocked output, you may lose data written by other writes to that block before the system failure. The contents of a file after a system write failure are indeterminate.

If one user opens a file for writing, and another later opens the same file for reading, the user who is reading the file can check for records that may have been written past the end of the file by the other user. If the file is a spanned variable text file, the reader can read part of a spanned record and reach the end of the file before reading in the last segment of the spanned record.

**Writing to binary files**

Data flows over record boundaries in binary files. Writes or updates past the end of a record go to the next record. When you are writing to files and not making any intervening calls to `fflush()`, blocks are written to the system as they are filled. If a fixed record is incomplete when you close the file, z/OS XL C/C++ completes it with nulls. You cannot change the length of existing records in a file by updating them.

If you are using variable binary files, note the following:

- On input and on update, records that have no length are ignored; you will not be notified. On output, zero-length records are not written. However, in spanned files, if the first segment of a record has been written to the system, and the user flushes or closes the file, a zero-length last segment may be written to the file.
- If you are writing new data in a data set that has variable-length records (RECFM=V, VB, VBM, etc.), z/OS XL C/C++ may split a record between two blocks to fill the first block out to the maximum block size. This means that when you read them, the record boundaries will not necessarily be the same.
• If your file is spanned, records are written up to length LRECL, spanning multiple blocks if necessary. You can create a spanned file by specifying a RECFM containing V and S on the fopen() call.

Writing to text files

z/OS XL C/C++ treats the control characters as follows when you are writing to a non-ASA text file:

\a Alarm. Placed directly into the file; z/OS XL C/C++ does not interpret it.
\b Backspace. Placed directly into the file; z/OS XL C/C++ does not interpret it.
\f Form feed. Placed directly into the file; z/OS XL C/C++ does not interpret it.
\n New-line. Defines a record boundary; z/OS XL C/C++ does not place it in the file.
\r Carriage return. Defines a record boundary; z/OS XL C/C++ does not place it in the file. Treated like a new-line character.
\t Horizontal tab character. Placed directly into the file; z/OS XL C/C++ does not interpret it.
\v Vertical tab character. Placed directly into the file; z/OS XL C/C++ does not interpret it.
\x0E DBCS shift-out character. Indicates the beginning of a DBCS string, if MB_CUR_MAX > 1. Placed into the file.
\x0F DBCS shift-in character. Indicates the end of a DBCS string, if MB_CUR_MAX > 1. Placed into the file. See Chapter 8, “z/OS XL C Support for the double-byte character set,” on page 53 for more information about MB_CUR_MAX.

The way z/OS XL C/C++ treats text files depends on whether they are in fixed, variable, or undefined format, and whether they use ASA.

As with ASA files in other environments, the first character of each record is reserved for the ASA control character that represents a new-line, a carriage return, or a form feed. See Chapter 7, “Using ASA text files,” on page 47 for more information.

Table 23. C control to ASA characters

<table>
<thead>
<tr>
<th>C Control Character Sequence</th>
<th>ASA Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\n</td>
<td>' '</td>
<td>skip one line</td>
</tr>
<tr>
<td>\n\n\n</td>
<td>'0'</td>
<td>skip two lines</td>
</tr>
<tr>
<td>\n\n\n\n</td>
<td>'1'</td>
<td>skip three lines</td>
</tr>
<tr>
<td>\f</td>
<td>'1'</td>
<td>new page</td>
</tr>
<tr>
<td>\r</td>
<td>'+'</td>
<td>overstrike</td>
</tr>
</tbody>
</table>

Writing to fixed-format text files

Records in fixed-format files are all the same length. You complete each record with a new-line or carriage return character. For fixed text files, the new-line character is not written to the file. Blank padding is inserted to the LRECL of each
A logical record can be shortened to be an empty record (containing just a new-line) or extended to a record containing LRECL bytes of data plus a new-line. Because the physical record represents the new-line position by using padding blanks, the new-line position can be changed on an update as long as it is within the physical record.

**Note:** Using *ftell()* or *fgetpos()* values for positions that do not exist after you have shortened records results in undefined behavior.

When you are updating a file, writing new data into an existing record replaces the old data and, if the new data is longer or shorter than the old data, changes the size of the logical record by changing the number of blank characters in the physical record. When you extend a record, thereby writing over the old new-line, a new-line character is implied after the last character of the update. Calling *fflush()* flushes the data out to the file and inserts blank padding between the last data character and the end of the record. Once you have called *fflush()* , you can call any of the read functions, which begin reading at the new-line. Once the new-line is read, reading continues at the beginning of the next record.

### Writing to variable-format text files

In a file with variable-length records, each record may be a different length. The variable length formats permit both variable-length records and variable-length blocks. The first 4 bytes of each block are reserved for the Block Descriptor Word (BDW); the first 4 bytes of each record are reserved for the Record Descriptor Word (RDW).

For ASA and non-ASA, the ' \n ' (new-line) character implies a record boundary. On output, the new-line is not written to the physical file; instead, it is assumed to follow the data of the record.

If you have not set _EDC_ZERO_RECLEN, z/OS XL C/C++ writes out a record containing a single blank character to represent a single new-line. On input, a record containing a single blank character is considered an empty record and is translated to a new-line character. Note that a single blank followed by a new-line is written out as a single blank, and is treated as just a new-line on input. When _EDC_ZERO_RECLEN is set, writing a record containing only a new-line results in a zero-length variable record.

For more information about environment variables, refer to Chapter 32, “Using environment variables,” on page 467. For more information about how z/OS XL C/C++ treats empty records in variable format, see “Mapping C types to variable format” on page 18.

Attempting to shorten a record on update by specifying less data before the new-line causes the record to be padded with blanks to the original record size. For spanned records, updating a record to a shorter length results in the same blank padding to the original record length, over multiple blocks, if applicable.

Attempts to lengthen a record on update generally result in truncation. The exception to this rule is extending an empty record to a 1-byte record when the environment variable _EDC_ZERO_RECLEN is not set. Because the physical representation for an empty record is a record containing one blank character, it is...
possible to extend the logical record to a single non-blank character followed by a
new-line character. For standard streams, truncation in text files does not occur;
data is wrapped automatically to the next record as if you had added a new-line.

When you are writing data to a non-blocked file without intervening flush or
reposition requests, each record is written to the system when a new-line or
carriage return character is written or when the file is closed.

When you are writing data to a blocked file without intervening flush or reposition
requests, if the file is opened in full buffering mode, the block is written to the
system on completion of the record that fills the block. If the blocked file is line
buffered, each record is written to the system when it is completed. If you are
using full buffering for a VB format file, a write may not fill a block completely.
The data does not go to the system unless a block is full; you can complete the
block with another write. If the subsequent write contains more data than is
needed to fill the block, it flushes the current block to the system and starts writing
your data to a new block.

When you are writing data to a spanned file without intervening flush or
reposition requests, if the record spans multiple blocks, each block is written to the
system once it is full and the user writes an additional byte of data.

For ASA variable text files, if a file was created without a control character as its
first byte or record (after the RDW and BDW), the first byte defaults to the ' ' character. When the file is read back, the first character is read as a new-line.

**Writing to undefined-format text files**

In an undefined-format file, there is only one record per block. Each record may be
a different length, up to a maximum length of BLKSIZE. Each record is completed
with a new-line or carriage return character. The new-line character is not written
to the physical file; it is assumed to follow the data of the record. However, if a
record contains only a new-line character, z/OS XL C/C++ writes a record
containing a single blank to the file to represent an empty record. On input, the
blank is read in as a new-line.

Once a record has been written, you cannot change its length. If you try to shorten
a logical record by updating it with a shorter record, z/OS XL C/C++ completes
the record with blank padding. If you try to lengthen a record by updating it with
more data than it can hold, z/OS XL C/C++ truncates the new data. The only
instance in which this does not happen is when you extend an empty record so
that it contains a single byte. Any data beyond the single byte is truncated.

**Truncation versus splitting**

If you try to write more data to a record than z/OS XL C/C++ allows, and the file
you are writing to is not one of the standard streams (the defaults, or those
redirected by freopen() or command-level redirection), output is cut off at the
record boundary and the remaining bytes are discarded. z/OS XL C/C++ does not
count the discarded characters as characters that have been written out
successfully.

In all truncation cases, the SIGIOERR signal is raised if the action for SIGIOERR is not
SIG_IGN. The user error flag is set so that ferror() will return TRUE. For more
information about SIGIOERR, ferror(), and other I/O-related debugging tools, see
Chapter 18, “Debugging I/O programs,” on page 223. z/OS XL C/C++ continues
to discard new output until you complete the current record by writing a new-line
or carriage return character, close the file, or change the file position.
If you are writing to one of the standard streams, attempting to write more data than a record can hold results in the data being split across multiple records.

**Writing to record I/O files**

fwrite() is the only interface allowed for writing to a file opened for record I/O. Only one record is written at a time. If you attempt to write more new data than a full record can hold or you try to update a record with more data than it currently has, z/OS XL C/C++ truncates your output at the record boundary. When z/OS XL C/C++ performs a truncation, it sets errno and raises SIGIOERR, if SIGIOERR is not set to SIG_IGN.

When you update a record, you can update less than the full record. The remaining data that you do not update is left untouched in the file.

When you are writing new records to a fixed-record I/O file, if you try to write a short record, z/OS XL C/C++ pads the record with nulls out to LRECL.

At the completion of an fwrite(), the file position is at the start of the next record. For new data, the block is flushed out to the system as soon as it is full.

**Writing to blocked I/O files**

fwrite() is the only interface allowed for writing to a file opened for blocked I/O. Only one block is written at a time. If you attempt to write more new data than a full block can hold or you try to update a block with more data than it currently has, z/OS XL C/C++ truncates your output at the block boundary. When z/OS XL C/C++ performs a truncation, it sets errno and raises SIGIOERR, if SIGIOERR is not set to SIG_IGN.

When you write less than BLKSIZE bytes, if the request is to create a new block, a short block will be created; if it is to update an existing block, only requested part of the block will be updated. z/OS XL C/C++ will not check the provided data. At the completion of an fwrite(), the file position is at the start of the next block, and the block is flushed out to the system. You might need to consider the following cases:

- Because all fixed-format records must be full, any block you write must be multiple of a record. Otherwise, z/OS XL C/C++ will fail the write request.
- When updating an FBS short block at the end of file, it could be updated to a full block or a longer short block from start of the short block.
- When writing or appending to an FBS short block at the end of file, z/OS XL C/C++ will use the request buffer to replace the previous block, which might extend or shrink the short block.
- You must make sure that there is no short block in the middle of an FBS data set.
- You must make sure that BDWs, RDWs, and SDWs in a block of variable record file are correct.

**Flushing buffers**

You can use the library function fflush() to flush streams to the system. For more information about fflush(), see z/OS XL C/C++ Runtime Library Reference.

The action taken by the fflush() library function depends on the buffering mode associated with the stream and the type of streams. If you call one z/OS XL C/C++ program from another z/OS XL C/C++ program by using the ANSI
system() function, all open streams are flushed before control is passed to the callee, and again before control is returned to the caller. If you are running with POSIX(ON), a call to the POSIX system() function does not flush any streams to the system.

**Updating existing records**
Calling fflush() while you are updating flushes the updates out to the system. If you call fflush() when you are in the middle of updating a record, z/OS XL C/C++ writes the partially updated record out to the system. A subsequent write continues to update the current record.

**Reading updated records**
If you have a file open for read at the same time that the file is open for write in the same application, you will be able to see the new data if you call fflush() to refresh the contents of the input buffer, as shown in **Figure 16**.

```c
/* this example demonstrates how updated records are read */
#include <stdio.h>
int main(void)
{
    FILE * fp, * fp2;
    int rc, rc2, rc3, rc4;
    fp = fopen("a.b","w+");
    fprintf(fp,"first record");
    fp2 = fopen("a.b","r"); /* Simultaneous Reader */
    /* following gets EOF since fp has not completed first line */
    /* of output so nothing will be flushed to file yet          */
    rc = fgetc(fp2);
    printf("return code is %i\n", rc);
    fputc('\n', fp); /* this will complete first line */
    fflush(fp); /* ensures data is flushed to file */
    rc2 = fgetc(fp2); /* this gets 'f' from first record */
    printf("value is now %c\n", rc2);
    rewind(fp);
    fprintf(fp, "some updates\n");
    rc3 = fgetc(fp2); /* gets 'i' ..doesn't know about update */
    printf("value is now %c\n", rc3);
    fflush(fp); /* ensure update makes it to file */
    fflush(fp2); /* this updates reader's buffer */
    rc4 = fgetc(fp2); /* gets 'm', 3rd char of updated record */
    printf("value is now %c\n", rc4);
    return(0);
}
```

**Figure 16. Example of reading updated records**

**Writing new records**
Writing new records is handled differently for:
- Binary streams
- Text streams
• Record I/O
• Blocked I/O

Binary streams
z/OS XL C/C++ treats line buffering and full buffering the same way for binary files.

If the file has a variable length or undefined record format, fflush() writes the current record out. This may result in short records. In blocked files, this means that the block is written to disk, and subsequent writes are to a new block. For fixed files, no incomplete records are flushed.

For single-volume disk files in FBS format, fflush() flushes complete records in an incomplete block out to the file. For all other types of FBS files, fflush() does not flush an incomplete block out to the file.

For files in FB format, fflush() always flushes out all complete records in the current block. For sequential DASD files, new completed records are added to the end of the flushed block if it is short. For non-DASD or non-sequential files, any new record will start a new block.

Text streams
• Line-Buffered Streams
  fflush() has no effect on line-buffered text files, because z/OS XL C/C++ writes all records to the system as they are completed. All incomplete new records remain in the buffer.
• Fully Buffered Streams
  Calling fflush() flushes all completed records in the buffer, that is, all records ending with a new-line or carriage return (or form feed character, if you are using ASA), to the system. z/OS XL C/C++ holds any incomplete record in the buffer until you complete the record or close the file.

For ASA text files, if a flush occurs while an ASA character that indicates more than one new-line is being updated, the remaining new-lines will be discarded and a read will continue at the first data character. For example, if ‘\n\n\n’ is updated to be ‘\n\n’ and a flush occurs, then a ‘0’ will be written out in the ASA character position.

Record I/O
z/OS XL C/C++ treats line buffering and full buffering the same way for record I/O. For files in FB format, calling fflush() writes all records in the buffer to the system. For single-volume disk files in FBS format, fflush() will flush complete records in an incomplete block out to the file. For all other types of FBS files, fflush() will not flush an incomplete block out to the file. For all other formats, calling fflush() has no effect, because fwrite() has already written the records to disk.

Blocked I/O
For all record formats and all buffering mode, calling fflush() has no effect, because fwrite() has already written the block to disk.

ungetc() considerations
ungetc() pushes characters back onto the input stream for binary and text files. ungetc() handles only single-byte characters. You can use it to push back as many as four characters onto the ungetc() buffer. For every character pushed back with
ungetc(), fflush() backs up the file position by one character and clears all the
pushed-back characters from the stream. Backing up the file position may end up
going across a record boundary. Remember that for text files, z/OS XL C/C++
counts the new-lines added to the records as single-byte characters when it
calculates the file position.

For example, given the stream you can run the following code fragment:

```c
fgetc(fp); /* Returns A and puts the file position at */
/* the beginning of the character B */
ungetc('Z',fp); /* Logically inserts Z ahead of B */
fflush(fp); /* Moves the file position back by one to A, */
/* removes Z from the logical stream */
```

If you want fflush() to ignore ungetc() characters, you can set the _EDC_COMPAT
environment variable. See Chapter 32, “Using environment variables,” on page 467
for more information.

---

**Repositioning within files**

You can use the following library functions to help you position within a file:

- `fseek()`
- `fseek_unlocked()`
- `fseeko()`
- `fseeko_unlocked()`
- `ftell()`
- `ftell_unlocked()`
- `ftello()`
- `ftello_unlocked()`
- `fgetpos()`
- `fgetpos_unlocked()`
- `fsetpos()`
- `fsetpos_unlocked()`
- `rewind()`
- `rewind_unlocked()`

With large file support enabled for AMODE 31 C/C++ applications, you can use
the following library functions for 64-bit offsets:

- `fseeko()`
- `fseeko_unlocked()`
- `ftello()`
- `ftello_unlocked()`

For AMODE 64 C/C++ applications, large files are automatically supported in the
LP64 programming model. All of the above functions (both lists) can be used with
64-bit offsets.
See *z/OS XL C/C++ Runtime Library Reference* for more information on these library functions.

Opening a file with `fopen()` and specifying the `NOSEEK` parameter disables all of these library functions except `rewind()`. A call to `rewind()` causes the file to be reopened, unless the file is a non-disk file opened for write-only. In this case, `rewind()` sets `errno` and raises `SIGIOERR` (if `SIGIOERR` is not set to `SIG_IGN`, which is its default).

Calling any of these functions flushes all complete and updated records out to the system. If a repositioning operation fails, *z/OS XL C/C++* attempts to restore the original file position and treats the operation as a call to `fflush()`, except that it does not account for the presence of `ungetc()` or `ungetwc()` characters, which are lost. After a successful repositioning operation, `feof()` always returns 0, even if the position is just after the last byte of data in the file.

The `fsetpos()` and `fgetpos()` library functions are generally more efficient than `ftell()` and `fseek()`. The `fgetpos()` function can encode the current position into a structure that provides enough room to hold the system position as well as position data specific to C or C++. The `ftell()` function must encode the position into a single word of storage, which it returns. This compaction forces `fseek()` to calculate certain position information specific to C or C++ at the time of repositioning. For variable-format binary files, you can choose to have `ftell()` return relative byte offsets. In previous releases, `ftell()` returned only encoded offsets, which contained the relative block number. Since you cannot calculate the block number from a relative byte offset in a variable-format file, `fseek()` may have to read through the file to get to the new position. `fsetpos()` has system position information available within the `fpos_t` structure and can generally reposition directly to the desired location.

You can use the `ftell()` and `fseek()` functions to set the current position within all types of files except for the following:

- Files on nonseekable devices (for example, printers)
- Partitioned data sets opened in `w` or `wb` mode.

Although repositioning within files opened for write mode is not available, you can use `fgetpos()` and `ftell()` to save the current position, and this position can later be used to reposition within the same file if opened in one of the modes where reposition is allowed.

For AMODE 31 C/C++ applications, the repositioning functions can be used with large format sequential data sets under the following conditions:

- The data set contains 256 TB - 256 bytes or less.
- The data set uses 2 GB blocks or less.

**ungetc() considerations**

For binary and text files, the library functions `fgetpos()` and `ftell()` take into account the number of characters you have pushed back onto the input stream with `ungetc()`, and adjust the file position accordingly. `ungetc()` backs up the file position by a single byte each time you call it. For text files, *z/OS XL C/C++* counts the new-lines added to the records as single-byte characters when it calculates the file position.

If you make so many calls to `ungetc()` that the logical file position is before the beginning of the file, the next call to `ftell()` or `fgetpos()` fails.
When you are using `fseek()` with a whence value of SEEK_CUR, the starting point for the reposition also accounts for the presence of ungetc() characters and compensates as `ftell()` and `fgetpos()` do.

If you want `fgetpos()` and `fseek()` to ignore ungetc() characters, you can set the _EDC_COMPAT environment variable. See Chapter 32, “Using environment variables,” on page 467 for details. `ftell()` is not affected by the setting of _EDC_COMPAT.

**How long fgetpos() and ftell() values last**

As long as you do not re-create a file or shorten logical records, you can rely on the values returned by `ftell()` and `fgetpos()`, even across program boundaries and calls to `fclose()`. (Calling `fopen()` or `freopen()` with any of the w modes re-creates a file.) Using `ftell()` and `fgetpos()` values that point to information deleted or re-created results in undefined behavior. For more information about shortening records, see “Writing to variable-format text files” on page 110.

**Using fseek() and ftell() in binary files**

With binary files, `ftell()` returns two types of positions:

- Relative byte offsets
- Encoded offsets

**Relative byte offsets**

You get byte offsets by default when you are seeking or positioning in fixed-format binary files. You can also use byte offsets on a variable or undefined format file opened in binary mode with the BYTESEEK parameter specified on the `fopen()` or `freopen()` function call. You can specify BYTESEEK to be the default for `fopen()` calls by setting the environment variable _EDC_BYTESEEK to Y. See Chapter 32, “Using environment variables,” on page 467 for information on how to set environment variables.

You do not need to acquire an offset from `ftell()` to seek to a relative position; you may specify a relative offset to `fseek()` with a whence value of SEEK_SET. However, you cannot specify a negative offset to `fseek()` when you have specified SEEK_SET, because a negative offset would indicate a position before the beginning of the file. Also, you cannot specify a negative offset with whence values of SEEK_CUR or SEEK_END such that the resulting file position would be before the beginning of the file. If you specify such an offset, `fseek()` fails.

If your file is not opened read-only, you can specify a position that is beyond the current EOF. In such cases, a new end-of-file position is created; null characters are automatically added between the old EOF and the new EOF.

`fseek()` support of byte offsets in variable-format files generally requires reading all records from the whence value to the new position. The impact on performance is greatest if you open an existing file for append in BYTESEEK mode and then call `ftell()`. In this case, `ftell()` has to read from the beginning of the file to the current position to calculate the required byte offset. Support for byteseeking is intended to ease portability from other platforms. If you need better performance, consider using `ftell()`-encoded offsets, see “Encoded offsets” on page 118.

For AMODE 31 C/C++ applications repositioning within a large format sequential data set that need `fseek()` and `ftell()` to access positions beyond 2 GB - 1 byte must use the large file version of `fseeko()` and `ftello()`.
Encoded offsets

If you do not specify the BYTESEEK parameter and you set the_EDC_BYTESEEK variable to N, any variable- or undefined-format binary file gets encoded offsets from ftell(). This keeps this release of z/OS XL C/C++ compatible with code generated by old releases of C/370™.

Encoded offsets are values representing the block number and the relative byte within that block, all within one long int. Because z/OS XL C/C++ does not document its encoding scheme, you cannot rely on any encoded offset not returned by ftell(), except 0, which is the beginning of the file. This includes encoded offsets that you adjust yourself (for example, with addition or subtraction). When you call fseek() with the whence value SEEK_SET, you must use either 0 or an encoded offset returned from ftell(). For whence values of SEEK_CUR and SEEK_END, however, you specify relative byte offsets. If you want to seek to a certain relative byte offset, you can use SEEK_SET with an offset of 0 to rewind the file to the beginning, and then you can use SEEK_CUR to specify the desired relative byte offset.

In earlier releases, ftell() could determine position only for files with no more than 131,071 blocks. In the new design, this number increases depending on the block size. From a maximum block size of 32,760, every time this number decreases by half, the number of blocks that can be represented doubles. Using the large file version of ftello() for a large format sequential data set increases the maximum number of blocks that can be represented to 2 GB in AMODE 31 C/C++ applications.

If your file is not opened read-only, you can use SEEK_CUR or SEEK_END to specify a position that is beyond the current EOF. In such cases, a new end-of-file position is created; null characters are automatically added between the old EOF and the new EOF. This does not apply to PDS members, as they cannot be extended. For SEEK_SET, because you are restricted to using offsets returned by ftell(), any offset that indicates a position outside the current file is invalid and causes fseek() to fail.

Using fseek() and ftell() in text files (ASA and Non-ASA)

In text files, ftell() produces only encoded offsets. It returns a long int, in which the block number and the byte offset within the block are encoded. You cannot rely on any encoded offset not returned by ftell() except 0. This includes encoded offsets that you adjust yourself (for example, with addition or subtraction).

When you call fseek() with the whence value SEEK_SET, you must use an encoded offset returned from ftell(). For whence values of SEEK_CUR and SEEK_END, however, you specify relative byte offsets. If you want to seek to a certain relative byte offset, you can use SEEK_SET with an offset of 0 to rewind the file to the beginning, and then you can use SEEK_CUR to specify the desired relative byte offset. z/OS XL C/C++ counts new-line characters and skips to the next record each time it reads one.

Unlike binary files you cannot specify offsets for SEEK_CUR and SEEK_END that set the file position past the end of the file. Any offset that indicates a position outside the current file is invalid and causes fseek() to fail.

In earlier releases, ftell() could determine position only for files with no more than 131071 blocks. In the new design, this number increases depending on the block size. From a maximum block size of 32760, every time this number decreases
by half, the number of blocks that can be represented doubles. Using the large file
version of ftello() for a large format sequential data set increases the maximum
number of blocks that can be represented to 2 GB in AMODE 31 C/C++
applications.

Repositioning flushes all updates before changing position. An invalid call to
fseek() is now always treated as a flush. It flushes all updated records or all
complete new records in the block, and leaves the file position unchanged. If the
flush fails, any characters in the ungetc() buffer are lost. If a block contains an
incomplete new record, the block is saved and will be completed by another write
or by closing the file.

Using fseek() and ftell() in record files

For files opened with type=record, ftell() returns relative record numbers. The
behavior of fseek() and ftell() is similar to that when you use relative byte
offsets for binary files, except that the unit is a record rather than a byte. For
example,

\[
\text{fseek(dp, -2, SEEK_CUR);} \\
\text{fseek(dp, 6, SEEK_SET);}
\]

seeks backward two records from the current position.

You cannot seek past the end or before the beginning of a file.

The first record of a file is relative record 0.

For AMODE 31 C/C++ applications repositioning within a large format sequential
data set that need fseek() and ftell() to access positions beyond 2 GB - 1 record
must use the large file version of fseeko() and ftello().

Using fseek() and ftell() in blocked files

For files opened with type=blocked, ftell() returns relative block numbers. The
behavior of fseek() and ftell() is similar to that when you use relative byte
offsets for binary files, except that the unit is a block rather than a byte. For
example,

\[
\text{fseek(dp, -2, SEEK_CUR);} \\
\text{fseek(dp, 6, SEEK_SET);}
\]

seeks backward two blocks from the current position.

You cannot seek past the end or before the beginning of a file.

The first block of a file is relative block 0.

For AMODE 31 C/C++ applications repositioning within a large format sequential
data set that need fseek() and ftell() to access positions beyond 2 GB - 1 block
must use the large file version of fseeko() and ftello().

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Porting old C code that uses fseek() or ftell()

The encoding scheme used by ftell() in non-BYTESEEK mode in the z/OS XL C/C++ RTL is different from that used in the XL C/C++ runtime library prior to C/370 Release 2.2 and Language Environment prior to release 1.3.

- If your code obtains ftell() values and passes them to fseek(), the change to the encoding scheme should not affect your application. On the other hand, your application may not work if you have saved encoded ftell() values in a file and your application reads in these encoded values to pass to fseek(). For non-record I/O and non-blocked I/O files, you can set the environment variable _EDC_COMPAT with the ftell() encoding set to tell z/OS XL C/C++ that you have old ftell() values. Files opened for record I/O or blocked I/O do not support old ftell() values saved across the program boundary.

- In previous versions, the fseek() support for the ftell() encoding scheme inadvertently supported seeking from SEEK_SET with a byte offset up to 32K. This is no longer be supported. Users of this support must change to BYTESEEK mode. You can do this without changing your source code; just use the _EDC_BYTESEEK environment variable.

Closing files

Use the fclose() library function to close a file. z/OS XL C/C++ automatically closes files on normal program termination and attempts to do so under abnormal program termination or abend. See z/OS XL C/C++ Runtime Library Reference for more information on this library function.

For files opened in fixed binary mode, incomplete records will be padded with null characters when you close the file.

For files opened in variable binary mode, incomplete records are flushed to the system. In a spanned file, closing a file can cause a zero-length segment to be written. This segment will still be part of the non-zero-length record. For files opened in undefined binary mode, any incomplete output is flushed on close.

Closing files opened in text mode causes any incomplete new record to be completed with a new-line character. All records not yet flushed to the file are written out when the file is closed.

For files opened for record I/O, closing causes all records not yet flushed to the file to be written out.

Note: If an application has locked a (FILE *) object (with flockfile() or ftrylockfile()), it is responsible for relinquishing the locked (FILE *) object (with funlockfile()) before calling fclose(). Failure to relinquish a locked (FILE *) object may cause deadlock or looping.

When fclose() is used to close a stream associated with a z/OS data set, some failures may be unrecoverable, and will result in an ABEND. These ABENDs may include I/O ABENDs of the form x14 and x37. Control will not be returned to the caller of fclose() to report the error. To process these types of errors, applications need to use z/OS Language Environment condition handling to receive control (see z/OS Language Environment Programming Guide), or register a signal handler for SIGABND (see Chapter 28, “Handling error conditions, exceptions, and signals,” on page 403).
If an application fails during fclose() with a x37 abend, and the application would like to recover and perform any **functions not related** to file I/O, the following technique can be used. Refer to [Figure 17 on page 122](#) for an example.

1. Register a signal handler for SIGABND and SIGIOERR.
2. fopen() the file. The NOSEEK option cannot be specified.
3. Manipulate the file as needed by the application.
4. When the application is done with the file, fflush() the file, before any fclose() is issued. This will ensure, if an x37 is going to occur during fflush() or fclose() processing, that the x37 occurs in the fflush(), before the fclose() occurs.
5. An x37 abend occurs during fflush().
6. The signal handler will receive control.
7. Once inside the signal handler, any functions not related to file I/O may be performed.
Note: When an abend condition occurs, a write-to-programmer message about the abend is issued and your DCB abend exit is given control, provided there is an active DCB abend exit routine address in the exit list contained in the DCB being processed. If STOW called the end-of-volume routines to get secondary space to write an end-of-file mark for a PDS, or if the DCB being processed is for an indexed sequential data set, the DCB abend exit routine is not given control if an

```c
/* example of signal handler */

#include <stdio.h>
#include <stdlib.h>
#include <dynit.h>
#include <signal.h>
#include <setjmp.h>

void sighandler();
jmp_buf env;
FILE *f;

int main()
{
    int rc;
    int s=80;
    int w;
    char buff 80 ="data";
    _dyn_t ip;

    redo:
    dyninit(&ip);
    ip.__dsname="MY.DATASET";
    ip.__status=__DISP_OLD;
    ip.__ddname="NAMEDD";
    ip.__conddisp=__DISP_CATLG;
    rc= dynalloc(&ip);

    f=fopen("DD:NAMEDD","wb");
    if (f==0)
    {
        perror("open error");
        return 12;
    }

    signal(SIGABND,sighandler);
    signal(SIGIOERR,sighandler);

    while (1)
    {
        if (setjmp(env))
        {
            dyninit(&ip);
            ip.__dsname="NAMEDD";
            ip.__conddisp=__DISP_CATLG;
            rc= dynfree(&ip);
            goto redo;
        }
        w=fwrite(buff,1,s,f);
    }

    fflush(f);
    fclose(f);

    goto redo;
}

void sighandler()
{
    fclose(f);
    longjmp(env,1);
}
```

Figure 17. Example of signal handler
abend condition occurs. If the situation described above is encountered, the Language Environment DCB abend exit will not receive control, and therefore the signal handler routine in an application will not receive control for the x37 abend.

### Renaming and removing files

You can remove or rename a z/OS data set that has an uppercase filename by using the `remove()` or `rename()` library functions, respectively. `rename()` and `remove()` both accept data set names. `rename()` does not accept ddnames, but `remove()` does. You can use `remove()` or `rename()` on individual members or entire PDSs or PDSEs. If you use `rename()` for a member, you can change only the name of the member, not the name of the entire data set. To rename both the member and the data set, make two calls to `rename()`, one for the member and one for the whole PDS or PDSE.

### fldata() behavior

The format of the fldata() function is as follows:

```c
int fldata(FILE *file, char *filename, fldata_t *info);
```

The fldata() function is used to retrieve information about an open stream. The name of the file is returned in `filename` and other information is returned in the `fldata_t` structure, shown in Figure 18 on page 124. Values specific to this category of I/O are shown in the comment beside the structure element. Additional notes follow the figure. For more information on the fldata() function, refer to z/OS XL C/C++ Runtime Library Reference.
struct __fileData {
  unsigned int __recfmF : 1, /* */
  __recfmN : 1, /* UPDATE */
  __recfmU : 1, /* */
  __recfmS : 1, /* */
  __recfmBlk : 1, /* */
  __recfmASA : 1, /* */
  __recfmM : 1, /* */
  __dsorgPO : 1, /* */
  __dsorgPOSmem : 1, /* */
  __dsorgPOdir : 1, /* */
  __dsorgPS : 1, /* */
  __dsorgConcat : 1, /* */
  __dsorgMem : 1, /* N/A -- always off */
  __dsorgHiper : 1, /* N/A -- always off */
  __dsorgTemp : 1, /* */
  __dsorgVSAM : 1, /* N/A -- always off */
  __dsorgHFS : 1, /* N/A -- always off */
  __openmode : 2, /* one of: */
    /* __TEXT */
    /* __BINARY */
    /* __RECORD */
  __modeflag : 4, /* combination of: */
    /* __READ */
    /* __WRITE */
    /* __APPEND */
    /* __UPDATE */
  __dsorgPDSE : 1, /* N/A -- always off */
  __vsamRLS : 3, /* N/A */
  #if __EDC_TARGET >= 0x41080000
    __vsamEA : 1, */
    __recfmB : 1, */
    __reserve2: 3; */
  #else
    __reserve3: 5; */
  #endif
  __device_t __device; /* one of: */
    /* __DISK */
    /* __TAPE */
    /* __PRINTER */
    /* __DUMMY */
    /* __OTHER */
  unsigned long __blksize, /* */
  __maxreclen; /* */
union {
  struct {
    unsigned short __vsam_type; /* N/A */
    unsigned long __vsam_keylen; /* N/A */
    unsigned long __vsam_RKP; /* N/A */
  } __vsam; /* */
  struct {
    unsigned short __disk_vsam_type; /* */
    unsigned char __disk_access_method; /* */
    unsigned char __disk_noseek_to_seek; /* */
    long __disk_reserve[2]; /* */
  } __disk; /* */
} __device_specific; /* */
  char * __dsname; /* */
  unsigned int __reserve4; /* */
};
typedef struct __fileData fldata_t;

Figure 18. fldata() Structure

Notes:
1. If you have opened the file by its data set name, filename is fully qualified,
   including quotation marks. If you have opened the file by ddname, filename is
dd:ddname, without any quotation marks. The ddname is uppercase. If you specified a member on the fopen() or freopen() function call, the member is returned as part of filename.

2. Any of the _recfm bits may be set on for OS files.

3. The _dsorgP0 bit will be set on only if you are reading a directory or member of a partitioned data set, either regular or extended, regardless of whether the member is specified on a DD statement or on the fopen() or freopen() function call. The _dsorgPS bit will be set on for all other OS files.

4. The _dsorgP0SE bit will be set when processing an extended partitioned data set (PDSE).

5. The _dsorgconcat bit will be set on for a concatenation of sequential data sets, but not for a concatenation of partitioned data sets.

6. The _dsorgTemp bit will be set on only if the file was created using the tempfile() function.

7. The _blksize value may include BDW and RDWs.

8. The _maxreclen value may include the ASA character.

9. The _recfm bits and the _blksize and _maxreclen values correspond to the attributes of the open stream. They do not necessarily reflect the attributes of the existing data set.

10. The _dsname field is filled in for _DISK files with the data set name. The member name is added if the file is a member of a partitioned data set, either regular or extended. The _dsname value is uppercase unless the asis option was specified on the fopen() or freopen() function call. The _dsname field is set to NULL for all other OS files.
Chapter 11. Performing z/OS UNIX file system I/O operations

You can create the following file types in the z/OS UNIX file system:
- Regular
- Link
- Directory
- Character special
- FIFO

The Single UNIX Specification defines another type of file called STREAMS. Even though the system interfaces are provided, it is impossible to have a valid STREAMS file descriptor. These interfaces will always return a return code of -1 with errno set to indicate an error such as, EBADF, EINVAL, or ENOTTY.

z/OS UNIX file system streams follow the binary model, regardless of whether they are opened for text, binary, or record I/O. You can simulate record I/O by using new-line characters as record boundaries.

For information on the z/OS UNIX file system and access to files within it from other than the C or C++ language, see z/OS V2R2.0 UNIX System Services User’s Guide. For an introduction to and description of the behavior of a POSIX-defined file system, see Zlotnick, Fred, The POSIX.1 Standard: A Programmer’s Guide, Redwood City, CA: The Benjamin/Cummings Publishing Company, Inc., 1991.

This topic describes C I/O stream functions as they can be used within C++ programs. If you want to use the C++ I/O stream classes instead, see Chapter 4, "Using the Standard C++ Library I/O Stream Classes," on page 23. For more detailed information, see Standard C++ Library Reference. For information about using wide-character I/O with z/OS XL C/C++, see Chapter 8, "z/OS XL C Support for the double-byte character set," on page 53.

Creating files

You can use library functions to create the following types of z/OS UNIX file system files.
- Regular Files
- Link and Symbolic Link Files
- Directory Files
- Character Special Files
- FIFO Files

Regular files

Use any of the following C functions to create regular files in the z/OS UNIX file system:
- creat()
- fopen()
- freopen()
- open()
For a description of these and other I/O functions, see z/OS XL C/C++ Runtime Library Reference.

**Link and symbolic link files**

Use either of the following C functions to create z/OS UNIX file system link or symbolic link files:
- `link()`
- `symlink()`

**Directory files**

Use the `mkdir()` C function to create a z/OS UNIX file system directory file.

**Character special files**

Use the `mknod()` C function to create a character special file in the z/OS UNIX file system; you must have superuser authority to create a character special file.

Other functions used for character special files are:
- `ptsname()`
- `grantpt()`
- `unlockpt()`
- `tcgetsid()`
- `ttname()`
- `isatty()`

**FIFO files**

Use the `mkfifo()` C function to create a FIFO file (named pipe) in the z/OS UNIX file system.

To create an unnamed pipe, use the `pipe()` C function.

**Opening files**

This section discusses the use of the `fopen()` or `freopen()` library functions to open z/OS UNIX file system I/O files. You can also access z/OS UNIX file system files using low-level I/O `open()` function. See "Low-level z/OS UNIX I/O" on page 141 for information about low-level I/O, and z/OS XL C/C++ Runtime Library Reference for information about any of the functions listed above.

The name of a z/OS UNIX file system file can include characters chosen from the complete set of character values, except for null characters. If you want a portable filename, then choose characters from the POSIX .1 portable filename character set.

The complete `pathname` can begin with a slash and be followed by zero, one, or more filenames, each separated by a slash. If a directory is included within the pathname, it may have one or more trailing slashes. Multiple slashes following one another are interpreted as one slash.

If your program is running under POSIX(ON), all valid POSIX names are passed with the `asis fopen()` parameter to the POSIX `open()` function.

You can access either z/OS UNIX file system files or MVS data sets from programs. Programs accessing files or data sets can be executed with either the
POSIX(0FF) or POSIX(ON) runtime options. There are basic file naming rules that apply for z/OS UNIX file system files and MVS data sets. However, there are also special z/OS XL C/C++ naming considerations that depend on how you execute your program.

The POSIX runtime option determines the type of z/OS XL C/C++ services and I/O available to your program. (See z/OS XL C/C++ User's Guide for a discussion of the z/OS UNIX programming environment and overview of binding z/OS UNIX XL C/C++ applications.)

Both the basic and special z/OS XL C/C++ file naming rules for z/OS UNIX file system files are described in the sections that follow. Examples are provided. All examples must be run with the POSIX(ON) option. For information about MVS data sets, see Chapter 10, “Performing OS I/O operations,” on page 83.

Using fopen() or freopen()
When you open a file with fopen() or freopen(), you must specify the data set name, file name, or ddname.

File naming considerations
Files are opened with a call to fopen() or freopen() in the format fopen("filename", "mode").

z/OS UNIX file system files: The following is the format for the pathname argument on the fopen() or freopen() function:

```
"pathname"
```

The POSIX.1 standard defines pathname as the information that identifies a file. For the z/OS UNIX implementation of the POSIX.1 standard, a pathname can be up to 1024 characters—including the null-terminating character. Optionally, it can begin with a slash character (/) followed by directory names separated by slash characters and a filename. For the pathname, each directory name or the filename can be up to 255 characters long.

Note: Regardless of whether your program is run under z/OS UNIX or as a traditional MVS application, if the pathname that you attempt to open using fopen() or freopen() contains a slash character but does not begin with exactly two slashes, a z/OS UNIX file system file is opened. For example, if you code:
```
fopen("tradsell/parts.order", "w+")
```

the file tradsell/parts.order from the working directory is opened.

If you begin the pathname value with ./, the specified file in the working directory is opened:
```
fopen("./parts.order", "w+")
```
Likewise, if you begin the *pathname* value with /, the specified file in the root
directory is opened:

```c
fopen("/parts.order", "w+")
```

If you specify more than two consecutive slash characters anywhere in a
pathname, all but the first slash character is ignored, as in the following examples:

```
"//a.b"
  MVS data set prefix.a.b

"///a.b"
  z/OS UNIX file system file /a.b

"/////a.b"
  z/OS UNIX file system file /a.b

"a/////b.c"
  z/OS UNIX file system file a/b.c

"/a.b"  z/OS UNIX file system file /a.b

"/a///b.c"
  z/OS UNIX file system file /a/b.c
```

If you specify /dd:pathname or ./dd:pathname, a file named dd:pathname is opened
in the file system root directory or your working directory, respectively. For
example, if you code the following statement, the file dd:parder is opened in the
root directory.

```c
fopen("/dd:parder", "w+")
```

For z/OS UNIX file system files, leading and trailing white spaces are *significant*.

**Opening a file by name**
Which type of file (z/OS UNIX file system or MVS data set) you open may
depend on whether the z/OS XL C/C++ application program is running under
POSIX(ON).

For an application program that is to be run under POSIX(ON), you can include in
your program statements similar to the following to open the file parts.instock
for reading in the working directory:

```c
FILE *stream;
stream = fopen("parts.instock", "r");
```

To open the MVS data set `user-prefix.PARTS.INSTOCK` for reading, include statements
similar to the following in your program:

```c
FILE *stream;
stream = fopen("//parts.instock", "r");
```

For an application program that is to be run as a traditional z/OS XL C/C++
application program, with POSIX(OFF), to open the MVS data set
`user-prefix.PARTS.INSTOCK` for reading, include statements similar to the following in
your program:

```c
FILE *stream;
stream = fopen("parts.instock", "r");
```
To open the file parts.instock in the working directory for reading, include statements similar to the following in your program:

```c
FILE *stream;

stream = fopen("./parts.instock", "r");
```

### Opening a file by DDname

The DD statement enables you to write z/OS XL C/C++ source programs that are independent of the files and I/O devices they will use. You can modify the parameters of a file or process different files without recompiling your program.

When `//dd:ddname` is specified to `fopen()` or `freopen()`, the z/OS XL C/C++ library looks to find and resolve the data definition information for the filename to open. If the data definition information points to an MVS data set, MVS data set naming rules are followed. If a z/OS UNIX file system file is indicated using the PATH parameter on the data definition statement, a `ddname` is resolved to the associated pathname.

**Note:** Use of the z/OS XL C/C++ `fork()` library function from an application program under z/OS UNIX does not replicate the data definition information of the parent process in the child process. Use of any of the `exec()` library functions deallocates the data definition information for the application process.

For the declaration just shown for the file parts.instock, you should write a JCL DD statement similar to the following:

```plaintext
//PSTOCK DD PATH='/u/parts.instock',...
```

For more information on writing DD statements, you should refer to the job control language (JCL) manual z/OS MVS JCL Reference.

To open the file by DD name under TSO/E, you must write an `ALLOCATE` command. For the declaration of a file parts.instock, you should write a TSO/E `ALLOCATE` command similar to the following:

```plaintext
ALLOCATE DDNAME(PSTOCK) PATH('/u/parts.instock')...
```

See z/OS TSO/E Command Reference for more information on TSO `ALLOCATE`.

### `fopen()` and `freopen()` parameters

The following table lists the parameters that are available on the `fopen()` and `freopen()` functions, tells you which ones are useful for z/OS UNIX file system I/O, and lists the values that are valid for the applicable ones.

**Table 24. Parameters for the fopen() and freopen() functions for z/OS UNIX file system I/O**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>recfm=</td>
<td>Yes</td>
<td>No</td>
<td>z/OS UNIX file system I/O uses a continuous stream of data as its file format.</td>
</tr>
<tr>
<td>lrec=</td>
<td>Yes</td>
<td>No</td>
<td>z/OS UNIX file system I/O uses a continuous stream of data as its file format.</td>
</tr>
<tr>
<td>blksize=</td>
<td>Yes</td>
<td>No</td>
<td>z/OS UNIX file system I/O uses a continuous stream of data as its file format.</td>
</tr>
<tr>
<td>space=</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
<tr>
<td>type=</td>
<td>Yes</td>
<td>Yes</td>
<td>May be omitted. If you do specify it, type=record is the only valid value.</td>
</tr>
<tr>
<td>acc=</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
</tbody>
</table>
Table 24. Parameters for the fopen() and freopen() functions for z/OS UNIX file system I/O (continued)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>password=</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
<tr>
<td>asis</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
<tr>
<td>byteseek</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
<tr>
<td>noseek</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
<tr>
<td>OS</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
<tr>
<td>abend=</td>
<td>Yes</td>
<td>No</td>
<td>Not used for z/OS UNIX file system I/O.</td>
</tr>
<tr>
<td>recfm=</td>
<td>Ignored for z/OS UNIX file system I/O.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>lrecl= and blksize=</td>
<td>Ignored for z/OS UNIX file system I/O, except that lrecl affects the value returned in the __maxreclen field of fldata() as described below.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>acc=</td>
<td>Ignored for z/OS UNIX file system I/O.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>password</td>
<td>Ignored for z/OS UNIX file system I/O.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>space=</td>
<td>Ignored for z/OS UNIX file system I/O.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
| type=     | The only valid value for this parameter under the z/OS UNIX file system is type=record. If you specify this, your file follows the z/OS UNIX file system record I/O rules:
  1. One record is defined to be the data up to the next new-line character.
  2. When an fread() is done the data will be copied into the user buffer as if an fgets(buf, size_item*num_items, stream) were issued. Data is read into the user buffer up to the number of bytes specified on the fread(), or until a new-line character or EOF is found. The new-line character is not included.
  3. When an fwrite() is done the data will be written from the user buffer with a new-line character added by the RTL code. Data is written up to the number of bytes specified on the fwrite(); the new-line is added by the RTL and is not included in the return value from fwrite().
  4. If you have specified an lrecl and type=record, fldata() of this stream will return the lrecl you specified, in the __maxreclen field of the __fileData return structure of stdio.h. If you specified type=record but no lrecl, the __maxreclen field will contain 1024.
    If type=record is not in effect, a call to fldata() of this stream will return 0 in the __maxreclen field of the __fileData return structure of stdio.h. |
| asis      | Ignored for z/OS UNIX file system I/O. |
| byteseek  | Ignored for z/OS UNIX file system I/O. |
| noseek    | Ignored for z/OS UNIX file system I/O. |
Reading from z/OS UNIX file system files

You can use the following library functions to read in information from z/OS UNIX file system files:

- `fread()`
- `fread_unlocked()`
- `fgets()`
- `fgets_unlocked()`
- `gets()`
- `gets_unlocked()`
- `fgetc()`
- `fgetc_unlocked()`
- `getc()`
- `getc_unlocked()`
- ` getchar()`
- `getchar_unlocked()`
- `scanf()`
- `scanf_unlocked()`
- `fscanf()`
- `fscanf_unlocked()`
- `read()`
- `pread()`
- `vscanf()`
- `vscanf_unlocked()`
- `vfscanf()`
- `vfscanf_unlocked()`

`fread()` is the only interface allowed for reading record I/O files. See z/OS XL C/C++ Runtime Library Reference for more information on all of the above library functions.

For z/OS UNIX low-level I/O, you can use the `read()` and `readv()` function. See “Low-level z/OS UNIX I/O” on page 141.

Opening and reading from z/OS UNIX file system directory files

To open a z/OS UNIX file system directory, you can use the `opendir()` function.

You can use the following library functions to read from, and position within, z/OS UNIX file system directories:

- `readdir()`
- `seekdir()`
- `telldir()`

To close a directory, use the `closedir()` function.
Writing to z/OS UNIX file system files

You can use the following library functions to write to z/OS UNIX file system files:

- fwrite()
- fwrite_unlocked()
- printf()
- printf_unlocked()
- fprintf()
- fprintf_unlocked()
- printf_unlocked()
- fprintf_unlocked()
- vsprintf()
- vsprintf_unlocked()
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- vsprintf_unlocked()
- vsprintf_unlocked()
- vsprintf_unlocked()
• ftell()
• ftell_unlocked()
• ftello()
• ftello_unlocked()
• fgetpos()
• fgetpos_unlocked()
• fsetpos()
• fsetpos_unlocked()
• lseek()
• rewind()
• rewind_unlocked()

With large file support enabled for AMODE 31 C/C++ applications, you can use the following library functions for 64-bit offsets:
• fseeko()
• fseeko_unlocked()
• ftello()
• ftello_unlocked()
• lseek()

For AMODE 64 C/C++ applications, large files are automatically supported in the LP64 programming model. All of the above functions (both lists) can be used with 64-bit offsets.

See z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

Closing files

You can use fclose(), freopen(), or close() to close a file. z/OS XL C/C++ automatically closes files on normal program termination, and attempts to do so under abnormal program termination or abend. See z/OS XL C/C++ Runtime Library Reference for more information on these library functions. For z/OS UNIX low-level I/O, you can use the close() function. When you use any exec() or fork() function, files defined as “marked to be closed” are closed before control is returned.

Deleting files

Use the unlink() or remove() z/OS XL C/C++ function to delete the following types of z/OS UNIX file system files:
• Regular
• Character special
• FIFO
• Link files

Use the rmdir() z/OS XL C/C++ function to delete a z/OS UNIX file system directory file. See z/OS XL C/C++ Runtime Library Reference for more information about these functions.
Pipe I/O

POSIX.1 pipes represent an I/O channel that processes can use to communicate with other processes. Pipes are conceptually like z/OS UNIX file system files. One process can write data into a pipe, and another process can read data from the pipe.

z/OS UNIX XL C/C++ supports two types of POSIX.1-defined pipes: unnamed pipes and named pipes (FIFO files).

An **unnamed pipe** is accessible only by the process that created the pipe and its child processes. An unnamed pipe does not have to be opened before it can be used. It is a temporary file that lasts only until the last file descriptor that references it is closed. You can create an unnamed pipe by calling the **pipe()** function.

A **named pipe** can be used by independent processes and must be explicitly opened and closed. Named pipes are also referred to as first-in, first-out (FIFO) files, or FIFOs. You can create a named pipe by calling the **mkfifo()** function. If you want to stream I/O after a **pipe()** function, call the **fdopen()** function to build a stream on one of the file descriptors returned by **pipe()**. If you want to stream I/O on a FIFO file, open the file with **fdopen()** together with one of **fopen()**, **freopen()**, or **open()**. When the stream is built, you can then use Standard C I/O functions, such as **fgets()** or **printf()**, to carry out input and output.

### Using unnamed pipes

If your z/OS UNIX XL C/C++ application program forks processes that need to communicate among themselves for work to be done, you can take advantage of POSIX.1-defined unnamed pipes. If your application program’s processes need to communicate with other processes that it did not fork, you should use the POSIX.1-defined named pipe (FIFO special file) support. See “Using named pipes” on page 137 for more information.

When you code the **pipe()** function to create a pipe, you pass a pointer to a two-element integer array where **pipe()** puts the file descriptors it creates. One descriptor is for the input end of the pipe, and the other is for the output end of the pipe. You can code your application so that one process writes data to the input end of the pipe and another process reads from the output end on a first-in-first-out basis. You can also build a stream on the pipe by using **fdopen()**, and use buffered I/O functions. The result is that you can communicate data between a parent process and any of its child processes.

The opened pipe is assigned the two lowest-numbered file descriptors available.

z/OS UNIX provides no security checks for unnamed pipes, because such a pipe is accessible only by the parent process that creates the pipe and any of the parent process’s descendent processes. When the parent process ends, an unnamed pipe created by the process can still be used, if needed, by any existing descendant process that has an open file descriptor for the pipe.

Consider the sample program (CCNGHF1) in Figure 19 on page 137. In this example, where you open a pipe, do a write operation, and later do a read operation from the pipe. For more information on the **pipe()** function and the file I/O functions, see z/OS XL C/C++ Runtime Library Reference.
Using named pipes

If the z/OS UNIX XL C/C++ application program you are developing requires its active processes to communicate with other processes that are active but may not be from the same program, code your application program to create a named pipe (FIFO file). Named pipes allow transfer of data between processes in a FIFO manner and synchronization of process execution. Use of a named pipe allows processes to communicate even though they do not know what processes are on the other end of the pipe. Named pipes differ from standard unnamed pipes, created using the pipe() function, in that they involve the creation of a real file that is available for I/O operations to properly authorized processes.

Within the application program, you create a named pipe by coding a mkfifo() or mknod() function. You give the FIFO a name and an access mode when you create it. If the access mode allows all users read and write access to the named pipe, any process that knows its name can use it to send or receive data.

Processes can use the open() function to access named pipes and then use the regular I/O functions for files, such as read(), write(), and close(), when manipulating named pipes. Buffered I/O functions can also be used to access and
manipulate named pipes. For more information on the `mkfifo()` and `mknod()` functions and the file I/O functions, see z/OS XL C/C++ Runtime Library Reference.

**Restriction:** If `fopen()` is used to open named pipes in a multi-threaded environment, a deadlock will occur. This deadlock is caused by a named pipe waiting for the other end of the pipe to be opened, while still holding the `fopen()` multi-thread mutex. To prevent this deadlock, use `open()` to open the named pipe, instead of `fopen()`.

z/OS UNIX does security checks on named pipes.

The following steps outline how to use a named pipe from z/OS UNIX XL C/C++ application programs:

1. Create a named pipe using the `mkfifo()` function. Only one of the processes that use the named pipe needs to do this.
2. Access the named pipe using the appropriate I/O method.
3. Communicate through the pipe with another process using file I/O functions:
   a. Write data to the named pipe.
   b. Read data from the named pipe.
4. Close the named pipe.
5. If the process created the named pipe and the named pipe is no longer needed, remove that named pipe using the `unlink()` function.

A process running the following simple example program creates a new named pipe with the file pathname pointed to by the `path` value coded in the `mkfifo()` function. The access mode of the new named pipe is initialized from the `mode` value coded in the `mkfifo()` function. The file permission bits of the `mode` argument are modified by the process file creation mask.

As an example, a process running the program code (CCNGHF2) in Figure 20 on page 139 creates a child process and then creates a named pipe called `fifo.test`. The child process then writes a data string to the pipe file. The parent process reads from the pipe file and verifies that the data string it reads is the expected one.

**Note:** The two processes are related and have agreed to communicate through the named pipe. They need not be related, however. Other authorized users can run the same program and participate in (or interfere with) the process communication.
/* this example shows how named pipes may be used */
#define _OPEN_SYS
#include <stdio.h>
#include <unistd.h>
#include <errno.h>
#include <fcntl.h>
#include <sys/wait.h>

/* *
* Sample use of mkfifo()
*/

main()
{
   /* start of program */

   int flags, ret_value, c_status;
   pid_t pid;
   size_t n_elements;
   char char_ptr[32];
   char str[] = "string for fifo ";
   char fifoname[] = "temp.fifo";
   FILE *rd_stream,*wr_stream;

   if ((mkfifo(fifoname,S_IRWXU)) != 0) {
      printf("Unable to create a fifo; errno=%d\n",errno);
      exit(1); /* Print error message and return */
   }

   if ((pid = fork()) < 0) {
      perror("fork failed");
      exit(2);
   }

   if (pid == (pid_t)0) { /* CHILD process */
      /* issue fopen for write end of the fifo */
      wr_stream = fopen(fifoname,"w");
      if (wr_stream == (FILE *) NULL) {
         printf("In child process\n");
         printf("fopen returned a NULL, expected valid stream\n");
         exit(100);
      }

      /* perform a write */
      n_elements = fwrite(str,strlen(str),wr_stream);
      if (n_elements != (size_t) strlen(str)) {
         printf("Fwrite returned %d, expected %d\n",
               (int)n_elements,strlen(str));
         exit(101);
      }
      exit(0); /* return success to parent */
   }

   else { /* PARENT process */

      /* issue fopen for read */
      rd_stream = fopen(fifoname,"r");
      if (rd_stream == (FILE *) NULL) {
         printf("In parent process\n");
         printf("fopen returned a NULL, expected valid pointer\n");
         exit(2);
      }

      exit(0); /* start of program */
   }
}

Named pipes example (Part 1 of 2)

Figure 20. Named pipes example
/* get current flag settings of file */
if ((flags = fcntl(fileno(rd_stream),F_GETFL)) == -1) {
    printf("fcntl returned -1 for %s\n",fifoname);
    exit(3);
}

/* clear O_NONBLOCK and reset file flags */
flags &= (O_NONBLOCK);
if ((fcntl(fileno(rd_stream),F_SETFL,flags)) == -1) {
    printf("fcntl returned -1 for %s",fifoname);
    exit(4);
}

/* try to read the string */
ret_value = fread(char_ptr,sizeof(char),strlen(str),rd_stream);
if (ret_value != strlen(str)) {
    printf("Fread did not read %d elements as expected ",
            strlen(str));
    printf("ret_value is %d ",ret_value);
    exit(6);
}

if (strncmp(char_ptr,str,strlen(str))) {
    printf("contents of char_ptr are %s ",
            char_ptr);
    printf("contents of str are %s ",
            str);
    printf("These should be equal");
    exit(7);
}

ret_value = fclose(rd_stream);
if (ret_value != 0) {
    printf("fclose failed for %s",fifoname);
    printf("errno is %d",errno);
    exit(8);
}
ret_value = remove(fifoname);
if (ret_value != 0) {
    printf("nremove failed for %s",fifoname);
    printf("errno is %d",errno);
    exit(9);
}

pid = wait(c_status);
if ((WIFEXITED(c_status) !=0) &&; (WEXITSTATUS(c_status) !=0)) {
    printf("nchild exited with code %d",WEXITSTATUS(c_status));
    exit(10);
}

} /* end of else clause */
printf("About to issue exit(0), \
    processing completed successfully\n");
exit(0);

Named pipes example (Part 2 of 2)

Character special file I/O

A named pipe (FIFO file) is a type of character special file. Therefore, it obeys the
I/O rules for character special files rather than the rules for regular files:
• It cannot be opened in read/write mode. A process must open a named pipe in
either write-only or read-only mode.
• It must be opened in read mode by a process before it can be opened in write mode by another process. Otherwise, the file is blocked from use for I/O by processes. Blocked processes can cause an application program to hang. A single process intending to access a named pipe can use an open() function with O_NONBLOCK to open the read end of the named pipe. It can then open the named pipe in write mode.

Note: The fopen() function cannot be used to accomplish this.

Low-level z/OS UNIX I/O

Low-level z/OS UNIX I/O is the POSIX.1-defined I/O method. All input and output is processed using the defined read(), readv(), write(), and writev() functions.

For application programmers used to a UNIX environment, z/OS UNIX behaves in familiar and predictable ways. Standard UNIX programming practices for shared resources, along with designing applications to respect locks put on files by multiple threads running in a process, will ensure that data is handled predictably.


Example of z/OS UNIX file system I/O functions

This section contains examples that demonstrate different uses of z/OS UNIX I/O file system functions.

Figure 21 on page 142 is example code (CCNGHF3) that demonstrates the use of z/OS UNIX stream input/output by writing streams to a file, reading the input lines, and replacing a line.
/* this example uses HFS stream I/O */

#define _OPEN_SYS
#include <stdlib.h>
#include <string.h>
#include <stdio.h>
#include <unistd.h>
#include <fcntl.h>
#include <sys/types.h>
define _OPEN_SYS
FILE *stream;

char string1[] = "A line of text.";  /* NOTE: There are actually 16 */
char string2[] = "Find this line.";  /* characters in each line of */
char string3[] = "Another stream.";  /* text. The 16th is a null */
char string4[16];  /* terminator on each string. */
long position, strpos;  /* Since the null character */
int i, result, fd;  /* is not being written to */
int rc;  /* the file, 15 is used as */
ssize_t x;  /* the data stream length. */
char buffer[16];

Example of z/OS UNIX stream input and output functions (Part 1 of 3)

Figure 21. Example of z/OS UNIX stream input and output functions
int main(void)
{
  /* Write continuous streams to file */
  if (!((stream = fopen("./myfile.data","wb")))==NULL) {
    perror("Error opening file");
    exit(0);
  }

  for(i=0; i<12;i++) {
    int len1 = strlen(string1);
    rc = fwrite(string1, 1, len1, stream);
    if (rc != len1) {
      perror("fwrite failed");
      printf("i = %d\n", i);
      exit(99);
    }
  }
  rc = fwrite(string2,1,sizeof(string2)-1,stream);
  if (rc != sizeof(string2)-1) {
    perror("fwrite failed");
    exit(99);
  }

  for(i=0;i<12;i++) {
    rc = fwrite(string1,1,sizeof(string1)-1,stream);
    if (rc != sizeof(string1)-1) {
      perror("fwrite failed");
      printf("i = %d\n", i);
      exit(99);
    }
  }
  fclose(stream);
  /* Read data stream and search for location of string2.   */
  /* EOF is not set until an attempt is made to read past the */
  /* end-of-file, thus the fread is at the end of the while loop */
  stream = fopen("./myfile.data", "rb");
  if ((position = ftell(stream)) == -1L)
    perror("ftell stream failed");
  rc = fread(string4, 1, sizeof(string2)-1, stream);

Example of z/OS UNIX stream input and output functions (Part 2 of 3)
while(!feof(stream)) {
    if (rc != sizeof(string2)-1) {
        perror("fread failed");
        exit(99);
    }

    if (strstr(string4,string2) != NULL) /* If string2 is found */
        strpos = position ; /* then save position. */
    if ((position=ftell(stream)) == -1L)
        perror("Error saving file position.");
    rc = fread(string4, 1, sizeof(string2)-1, stream);
}

fclose(stream);
/* Replace line containing string2 with string3 */

fd = open("test.data",O_RDWR);
if (fd < 0){
    perror("open failed
");
}

x = write(fd,"a record",8);
if (x < 8){
    perror("write failed
");
}

rc = lseek(fd,0,SEEK_SET);
x = read(fd,buffer,8);
if (x < 8){
    perror("read failed
");
}
printf("data read is %.8s
",buffer);

close(fd);

Example of z/OS UNIX stream input and output functions (Part 3 of 3)

To use 64-bit offset and file sizes, you must make the following changes in your code:
1. Change any variables used for offsets in fseek() or ftell() that are int
   or long to the off_t data type.
2. Define the _LARGE_FILES 1 feature test macro.
3. Replace fseek() / ftell() with fseeko() / ftello(). See z/OS XL C/C++ Runtime
   Library Reference for descriptions of these functions.
4. Compile with the LANGLVL(LONGLONG) compiler option.

Notes:
1. These changes are compatible with your older files.
2. Large Files support (64-bit offset and file sizes) is automatic in the LP64
   programming model that is used in 64-bit. The long data type is widened to
   64-bits. This enables fseek() and ftell() to work with the larger offsets with
   no code change. The fseeko() and ftello() functions also work with 64-bit
   offsets since off_t is typedef’d as a long int.
The example program (CCNGHF4) in Figure 22 on page 146 provides the same function as CCNGHF3, but it uses 64-bit offsets. The changed lines are marked in a bold font.
/* this example uses HFS stream I/O and 64-bit offsets*/
#define _OPEN_SYS
#define _LARGE_FILES 1
#include <stdlib.h>
#include <string.h>
#include <stdio.h>
#include <unistd.h>
#include <fcntl.h>
#include <sys/types.h>
#undef _OPEN_SYS
FILE *stream;

char string1[] = "A line of text."; /* NOTE: There are actually 16 */
char string2[] = "Find this line."; /* characters in each line of */
char string3[] = "Another stream."; /* text. The 16th is a null */
char string4[16]; /* terminator on each string. */

off_t position, strpos;
/* Since the null character */
int i, result, fd; /* is not being written to */
int rc; /* the file, 15 is used as */
/* the data stream length. */

ssize_t x;
char buffer[16];

int main(void)
{
    /* Write continuous streams to file */
    
    if ((stream = fopen("./myfile.data","wb")) == NULL) {
      perror("Error opening file");
      exit(0);
    }

    for(i=0; i<12; i++) {
      int len1 = strlen(string1);
      rc = fwrite(string1, 1, len1, stream);
      if (rc != len1) {
        perror("fwrite failed");
        printf("i = %d\n", i);
        exit(99);
      }
    }

    rc = fwrite(string2, 1, sizeof(string2)-1, stream);
    if (rc != sizeof(string2)-1) {
      perror("fwrite failed");
      exit(99);
    }

    for(i=0; i<12; i++) {
      rc = fwrite(string1, 1, sizeof(string1)-1, stream);
      if (rc != sizeof(string1)-1) {
        perror("fwrite failed");
        printf("i = %d\n", i);
        exit(99);
      }
    }

    Example of HFS stream input and output functions (Part 1 of 2)

    Figure 22. Example of HFS stream input and output functions

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fclose(stream);
/* Read data stream and search for location of string2. */
/* EOF is not set until an attempt is made to read past the */
/* end-of-file, thus the fread is at the end of the while loop */
stream = fopen("./myfile.data", "rb");

if ((position=ftello(stream)) == -1LL)
  perror("Error saving file position.");

rc = fread(string4, 1, sizeof(string2)-1, stream);

while(!feof(stream)) {
  if (rc != sizeof(string2)-1) {
    perror("fread failed");
    exit(99);
  }
  if (strstr(string4,string2) != NULL) /* If string2 is found */
    strpos = position ; /* then save position. */
  if ((position=ftello(stream)) == -1LL)
    perror("Error saving file position.");
  rc = fread(string4, 1, sizeof(string2)-1, stream);
}
fclose(stream);
/* Replace line containing string2 with string3 */

fd = open("test.data",O_RDWR);
if (fd < 0)
  perror("open failed\n");
x = write(fd,"a record",8);
if (x < 8)
  perror("write failed\n");
strpos = lseek(fd,0LL,SEEK_SET);  /* Note off_t is 64bits with _LARGE_FILES */
  /* set and the off_t variable */
  /* needs a 64bit constant of 0LL */
x = read(fd,buffer,8);
if (x < 8)
  perror("read failed\n");
printf("data read is %.8s\n",buffer);
close(fd);
}

Example of HFS stream input and output functions (Part 2 of 2)

fldata() behavior

The format of the fldata() function is as follows:
The fldata() function is used to retrieve information about an open stream. The name of the file is returned in filename and other information is returned in the fldata_t structure, shown in Figure 23. Values specific to this category of I/O are shown in the comment beside the structure element. Additional notes pertaining to this category of I/O follow the figure. For more information on the fldata() function, refer to z/OS XL C/C++ Runtime Library Reference.

```c
int fldata(FILE *file, char *filename, fldata_t *info);
```

The fldata() function is used to retrieve information about an open stream. The name of the file is returned in filename and other information is returned in the fldata_t structure, shown in Figure 23. Values specific to this category of I/O are shown in the comment beside the structure element. Additional notes pertaining to this category of I/O follow the figure. For more information on the fldata() function, refer to z/OS XL C/C++ Runtime Library Reference.

**Figure 23. fldata() structure**

**Notes:**
1. The filename is the same as specified on the fopen() or freopen() function call.
2. The __maxreclen value is 0 for regular I/O (binary). For record I/O the value is 1rec1 or the default of 1024 when 1rec1 is not specified.
3. The __dsname value is the real POSIX pathname.
File tagging and conversion

In general, the file system knows the contents of a file only as a set of bytes. Applications which create and process bytes in a file know whether these bytes represent binary data, text (character) data, or a mixture of both. File tags are file metadata fields which describe the contents of a file. Enhanced ASCII includes the following file tag fields:

**txtflag** A flag indicating if a file consists solely of character data encoded by a single coded character set ID (CCSID).

**file ccsid**

A 16 bit field specifying the CCSID of characters in the file.

Applications can explicitly tag files using new `open()` or `fcntl()` options, or applications can allow the logical file system (LFS) to tag new files on first write, `fopen()`. A new environment variable, `_BPXK_CCSID`, is used to assign a program CCSID to an application, which LFS will use to tag new files on first write. LFS also uses the program CCSID derived from `_BPXK_CCSID` to set up auto-conversion of pure text data streams. LFS attempts to set up auto-conversion when:

- Auto-conversion is enabled for an application by the `_BPXK_AUTOCVT` environment variable
- The file txtflag flag is set indicating a pure text file
- The file and program CCSIDs do not match.

Automatic file conversion and file tagging include the following facilities:

- `_OPEN_SYS_FILE_EXT` feature test macro. For more information, see z/OS XL C/C++ Runtime Library Reference.
- `_BPXK_AUTOCVT` and `_BPXK_CCSIDS` environment variables. For more information, see Chapter 32, “Using environment variables,” on page 467.
- z/OS Language Environment FILETAG runtime option. For more information, see z/OS Language Environment Programming Reference.
- `__chattr()` and `__fchattr()` functions; `F_SETTAG` and `F_CONTROL_CVT` arguments for the `fcntl()` function; options for the `fopen()`, `popen()`, `stat()`, `fstat()`, and `lstat()` functions. For more information, see z/OS XL C/C++ Runtime Library Reference.

Access control lists (ACLs)

Access control lists (ACLs) enable you to control access to files and directories by individual user (UID) and group (GID). ACLs are used in conjunction with permission bits. You can create, modify, and delete ACLs using the following functions:

- `acl_create_entry()`
- `acl_delete_entry()`
- `acl_delete_fd()`
- `acl_delete_file()`
- `acl_first_entry()`
- `acl_free()`
- `acl_from_text()`
- `acl_get_entry()`
- `acl_get_fd()`
- `acl_get_file()`
- acl_init()
- acl_set_fd()
- acl_set_file()
- acl_sort()
- acl_to_text()
- acl_update_entry()
- acl_valid()

For descriptions of these functions see z/OS XL C/C++ Runtime Library Reference. For more information on using ACLs to protect file system resources see z/OS UNIX System Services Planning and z/OS Security Server RACF Security Administrator’s Guide.
Chapter 12. Performing VSAM I/O operations

This chapter outlines the use of Virtual Storage Access Method (VSAM) data sets in z/OS XL C/C++. Three I/O processing modes for VSAM data sets are available in z/OS XL C/C++:

- Record
- Text Stream
- Binary Stream

Because VSAM is a record-based access method, record mode is the logical processing mode and is specified by coding the type=record keyword parameter on the fopen() function call. z/OS XL C/C++ also provides limited support for VSAM text streams and binary streams. Because of the record-based nature of VSAM, this chapter is organized differently from the other chapters in this section. The focus of this chapter is on record I/O, and only those aspects of text and binary I/O that are specific to VSAM are also discussed.

For more information about the facilities of VSAM, see the list of "DFSMS" on page 1176 publications.

See Chapter 8, “z/OS XL C Support for the double-byte character set,” on page 53 for information about using wide-character I/O with z/OS XL C/C++.

Notes:
1. This chapter describes C I/O as it can be used within C++ programs.
2. The C++ I/O stream libraries cannot be used for VSAM I/O because these do not support the record processing mode (where type=record is specified).
3. Starting in z/OS V1R10, the C/C++ runtime library provides support for VSAM data sets in the extended addressing space on extended address volumes (EAVs).

VSAM types (data set organization)

There are three types of VSAM data sets supported by z/OS XL C/C++, all of which are held on direct-access storage devices.

- Key-Sequenced Data Set (KSDS) is used when a record is accessed through a key field within the record (for example, an employee directory file where the employee number can be used to access the record). KSDS also supports sequential access. Each record in a KSDS must have a unique key value.
- Entry-Sequenced Data Set (ESDS) is used for data that is primarily accessed in the order it was created (or the reverse order). It supports direct access by Relative Byte Address (RBA), and sequential access.
- Relative Record Data Set (RRDS) is used for data in which each item has a particular number, and the relevant record is accessed by that number (for example, a telephone system with a record associated with each number). It supports direct access by Relative Record Number (RRN), and sequential access.
In addition to the primary VSAM access described above, for KSDS and ESDS, there is also direct access by one or more additional key fields within each record. These additional keys can be unique or non-unique; they are called an alternate index (AIX).

**Notes:**
1. VSAM Linear Data Sets are not supported in z/OS XL C/C++ I/O.
2. z/OS XL C/C++ supports extended addressable KSDS, ESDS, and RRDS data sets. Extended addressable KSDS data sets can be accessed through an alternate index, but extended addressable ESDS data sets cannot.

**Access method services**
Access Method Services are generally known by the name IDCAMS on MVS. For more information, see z/OS DFSMS Access Method Services Commands.

Before a VSAM data set is used for the first time, its structure is defined to the system by the Access Method Services DEFINE CLUSTER command. This command defines the type of VSAM data set, its structure, and the space it requires.

Before a VSAM alternate index is used for the first time, its structure is defined to the system by the Access Method Services DEFINE ALTERNATEINDEX command. To enable access to the base cluster records through the alternate index, use the DEFINE PATH command. Finally, to build the alternate index, use the BLDINDEX command.

When you have built the alternate index, you call fopen() and specify the PATH in order to access the base cluster through the alternate index. Do not use fopen() to access the alternate index itself.

**Note:** You cannot use the BLDINDEX command on an empty base cluster.

**Choosing VSAM data set types**

When you plan your program, you must first decide the type of data set to use. Figure 24 on page 153 shows you the possibilities available with the types of VSAM data sets.
The diagrams show how the information contained in the family tree below could be held in VSAM data sets of different types.

Andrew M. Smith & Valerie Suzie Ann Morgan (1967)

**Key-Sequenced Data Set**

**Entry-Sequenced Data Set**

**Relative Record Data Set**

*Figure 24. Types and advantages of VSAM data sets*

When choosing the VSAM data set type, you should base your choice on the most common sequence in which you require data. You should follow a procedure similar to the one suggested below to help ensure a combination of data sets and indexes that provide the function you require.
1. Determine the type of data and its primary access.
   - sequentially — favors ESDS
   - by key — favors KSDS
   - by number — favors RRDS

2. Determine whether you require access through an alternate index path. These are only supported on KSDS and ESDS. If you do, determine whether the alternate index is to have unique or nonunique keys. You should keep in mind that making an assumption that all future records will have unique keys may not be practical, and an attempt to insert a record with a nonunique key in an index that has been created for unique keys causes an error.

3. When you have determined the data sets and paths that you require, ensure that the operations you have in mind are supported.

**Keys, RBAs and RRNs**

All VSAM data sets have keys associated with their records. For KSDS, KSDS AIX, and ESDS AIX, the key is a defined field within the logical record. For ESDS, the key is the *relative byte address* (RBA) of the record. For RRDS, the key is a *relative record number* (RRN).

**Keys for indexed VSAM data sets**

For KSDS, KSDS AIX, and ESDS AIX, keys are part of the logical records recorded on the data set. For KSDS, the length and location of the keys are defined by the DEFINE CLUSTER command of Access Method Services. For KSDS AIX and ESDS AIX, the keys are defined by the DEFINE ALTERNATEINDEX command.

**Relative byte addresses**

Relative byte addresses (RBAs) enable you to access ESDS files directly. The RBAs are either 4 or 8 byte fields, depending on the usage, and their values are computed by VSAM. The 4 byte RBA can only be used when accessing within the first 4GB of a VSAM data set. The 8 byte RBA can be used to access beyond 4GB in an extended addressable VSAM data set.

**Notes:**

1. KSDS can also use RBAs. However, because the RBA of a KSDS record can change if an insert, delete or update operation is performed elsewhere in the file, it is not recommended.

2. You can call flocate() with RBA values in an RRDS cluster, but flocate() with RBA values does not work across control intervals. Therefore, using RBAs with RRDS clusters is not recommended. The RRDS access method does not support RBAs. z/OS XL C/C++ supports the use of RBAs in an RRDS cluster by translating the RBA value to an RRN. It does this by dividing the RBA value by the LRECL.

3. Alternate indexes do not allow positioning by RBA.

The RBA value is stored in the C structure __amrc, which is defined in the C <stdio.h> header file. The __amrc->__RBA field is defined as an unsigned int, and therefore will contain only a 4-byte RBA value. The __amrc->__XRBA field is 8 bytes (unsigned long long in AMODE 31 applications, and unsigned long in AMODE 64 applications), and therefore can hold the RBA for all locations within an extended addressable VSAM data set.

You can access the field __amrc->__RBA, as shown in< xref refid="gvs1">. This example code (CCNGVSI1) can be converted to use __amrc->__XRBA with just a few modifications. For more information about the __amrc structure, refer to
Relative record numbers
Records in an RRDS are identified by a relative record number that starts at 1 and is incremented by 1 for each succeeding record position. Only RRDS files support accessing a record by its relative record number.

Summary of VSAM I/O operations
Table 25 summarizes VSAM data set characteristics and the allowable I/O operations on them.

<table>
<thead>
<tr>
<th>Characteristic or I/O Operation</th>
<th>KSDS</th>
<th>ESDS</th>
<th>RRDS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Record Length</td>
<td>Variable. Length can be changed by update.</td>
<td>Variable. Length cannot be changed by update.</td>
<td>Fixed.</td>
</tr>
<tr>
<td>Alternate index</td>
<td>Allows access using unique or non-unique keys.</td>
<td>Allows access using unique or non-unique keys.</td>
<td>Not supported by VSAM.</td>
</tr>
<tr>
<td>Note: z/OS XL C/C++ does not support extended addressable ESDS alternate indexes.</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Record Read (Sequential)</td>
<td>The order is determined by the VSAM key</td>
<td>By entry sequence. Reads proceed in key sequence for the key of reference.</td>
<td>By relative record number.</td>
</tr>
</tbody>
</table>
### Table 25. Summary of VSAM data set characteristics and allowable I/O operations (continued)

<table>
<thead>
<tr>
<th>Characteristic or I/O Operation</th>
<th>KSDS</th>
<th>ESDS</th>
<th>RRDS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Record Write (Direct)</td>
<td>Position determined by the value in the field designated as the key.</td>
<td>Record written at the end of the file.</td>
<td>By relative record number.</td>
</tr>
<tr>
<td>Positioning for Record Read</td>
<td>By key or by RBA value. Positioning by RBA value is not recommended because changes to the file change the RBA.</td>
<td>By RBA value. Alternate index allows use by key.</td>
<td>By relative record number.</td>
</tr>
<tr>
<td>Delete (Record)</td>
<td>If not already in correct position, reposition the file pointer; read the record using fwrite(); delete the record using fwrite(). fwrite() must immediately precede fwrite().</td>
<td>Not supported by VSAM.</td>
<td>If not already in correct position, position the file pointer; read the record using fwrite(); delete the record using fwrite(). fwrite() must immediately precede fwrite().</td>
</tr>
<tr>
<td>Update (Record)</td>
<td>If not already in correct position, reposition the file pointer; read the record using fwrite(); update the record using fwrite(). fwrite() must immediately precede fwrite().</td>
<td>If not already in correct position, reposition the file pointer; read the record using fwrite(); update the record using fwrite(). fwrite() must immediately precede fwrite().</td>
<td>If not already in correct position, reposition the file pointer; read the record using fwrite(); update the record using fwrite(). fwrite() must immediately precede fwrite().</td>
</tr>
<tr>
<td>Empty the file</td>
<td>Define the file as reusable using the DEFINE CLUSTER command, and then open the data set in write (&quot;wb, type=record&quot; or &quot;wb+, type=record&quot;) mode. Not supported for alternate indexes.</td>
<td>Define the file as reusable using the DEFINE CLUSTER command, and then open the data set in write (&quot;wb, type=record&quot; or &quot;wb+, type=record&quot;) mode. Not supported for alternate indexes.</td>
<td>Define the file as reusable using the DEFINE CLUSTER command, and then open the data set in write (&quot;wb, type=record&quot; or &quot;wb+, type=record&quot;) mode.</td>
</tr>
<tr>
<td>Stream Read</td>
<td>Supported by z/OS XL C/C++.</td>
<td>Supported by z/OS XL C/C++.</td>
<td>Supported by z/OS XL C/C++.</td>
</tr>
<tr>
<td>Stream Write/Update</td>
<td>Not supported by z/OS XL C/C++.</td>
<td>Supported by z/OS XL C/C++.</td>
<td>Supported by z/OS XL C/C++.</td>
</tr>
<tr>
<td>Stream Repositioning</td>
<td>Supported by z/OS XL C/C++.</td>
<td>Supported by z/OS XL C/C++.</td>
<td>Supported by z/OS XL C/C++.</td>
</tr>
</tbody>
</table>

### Opening VSAM data sets

To open a VSAM data set, use the Standard C library functions fopen() and freopen() just as you would for opening non-VSAM data sets. The fopen() and freopen() functions are described in z/OS XL C/C++ Runtime Library Reference.

This section describes considerations for using fopen() and freopen() with VSAM files. Remember that a VSAM file must exist and be defined as a VSAM cluster before you call fopen().

#### Using fopen() or freopen()

This section covers using file names for MVS data sets, specifying fopen() and freopen() keywords, and buffering.
File names for MVS data sets: Using a data set name

The following diagram shows the syntax for the `filename` argument on your `fopen()` or `freopen()` call:

![Diagram showing syntax for filename argument on fopen() or freopen() call]

The following is a sample construct:

```
'qualifier1.qualifier2'
```

Single quotation marks indicate that you are passing a **fully-qualified** data set name, that is, one which includes the high-level qualifier. If you pass a data set name without single quotation marks, the z/OS XL C/C++ compiler prefixes the high-level qualifier (usually the user ID) to the name. See Chapter 10, "Performing OS I/O operations," on page 83 for information on fully qualified data set names.

// Specifying these slashes indicates that the file names refer to MVS data sets.

**qualifier**

Each qualifier is a 1- to 8-character name. These characters may be alphanumeric, national ($, #, @), the hyphen, or the character \xC0. The first character should be either alphabetic or national. Do not use hyphens in names for RACF-protected data sets.

You can join qualifiers with periods. The maximum length of a data set name is generally 44 characters, including periods.

To open a data set by its name, you can code something like the following in your C or C++ program:

```c
infile=fopen("VSAM.CLUSTER1", "ab+, type=record");
```

File names for MVS data sets: Using a DDname

To access a cluster or path by ddname, you can write the required DD statement and call `fopen()` as shown in the following example.

If your data set is `VSAM.CLUSTER1`, your C or C++ program refers to this data set by the ddname `CFILE`, and you want exclusive control of the data set for update, you can write the DD statement:

```
//CFILE DD DSNAME=VSAM.CLUSTER1,DISP=OLD
```

and code the following in your C or C++ source program:

```c
#include <stdio.h>

FILE *infile;
main()
{
  infile=fopen("DD:CFILE", "ab+, type=record");
};
```
To share your data set, use `DISP=SHR` on the DD statement. `DISP=SHR` is the default for `fopen()` calls that use a data set name and specify any of the `r`, `rb`, `rb+`, and `r+b` open modes.

**Note:** z/OS XL C/C++ does not check the value of `shareoptions` at `fopen()` time, and does not provide support for read-integrity and write-integrity, as required to share files under `shareoptions` 3 and 4.

For more information on `shareoptions`, see the information on `DEFINE CLUSTER` in the books listed in "DFSMS" on page 1176.

### Specifying `fopen()` and `freopen()` keywords

The `mode` argument is a character string specifying the type of access requested for the file. The `mode` argument contains one positional parameter (access mode) followed by keyword parameters. A description of these parameters, along with an explanation of how they apply to VSAM data sets is given in the following sections.

#### Specifying access mode:

The access mode is specified by the positional parameter of the `fopen()` function call. The possible record I/O and binary modes you can specify are:

- **rb** Open for reading. If the file is empty, `fopen()` fails.
- **wb** Open for writing. If the cluster is defined as reusable, the existing contents of the cluster are destroyed. If the cluster is defined as not reusable (clusters with paths are, by definition, not reusable), `fopen()` fails. However, if the cluster has been defined but not loaded, this mode can be used to do the initial load of both reusable and non reusable clusters.

  **Note:** If a "key out of sequence" condition is encountered, the data set will automatically be reopened with a mode string "ab:" and will no longer be in create mode.

- **ab** Open for writing.
- **rb+ or r+b**
  - Open for reading, writing, and/or updating.
- **wb+ or w+b**
  - Open for reading, writing, and/or updating. If the cluster is defined as reusable, the existing contents of the cluster are destroyed. If the cluster is defined as not reusable (clusters with paths are, by definition, not reusable), `fopen()` fails. However, if the cluster has been defined but not loaded, this mode can be used to do the initial load of both reusable and non reusable clusters.
- **ab+ or a+b**
  - Open for reading, writing, and/or updating.

For text files, you can specify the following modes: `r`, `w`, `a`, `r+`, `w+`, and `a+`.

**Note:** For KSDS, KSDS AIX and ESDS AIX in text and binary I/O, the only valid modes are `r` and `rb`, respectively.

### `fopen()` and `freopen()` keywords

The following table lists the keywords that are available on the `fopen()` and `freopen()` functions, tells you which ones are useful for VSAM I/O, and lists the values that are valid for the applicable ones.
### Table 26. Keywords for the fopen() and freopen() functions for VSAM data sets

<table>
<thead>
<tr>
<th>Keyword</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>recfm=</td>
<td>Yes</td>
<td>No</td>
<td>Ignored.</td>
</tr>
<tr>
<td>lrecl=</td>
<td>Yes</td>
<td>No</td>
<td>Ignored.</td>
</tr>
<tr>
<td>blksize=</td>
<td>Yes</td>
<td>No</td>
<td>Ignored.</td>
</tr>
<tr>
<td>space=</td>
<td>Yes</td>
<td>No</td>
<td>Ignored.</td>
</tr>
<tr>
<td>type=</td>
<td>Yes</td>
<td>Yes</td>
<td>May be omitted. If you do specify it, type=record is the only valid value.</td>
</tr>
<tr>
<td>acc=</td>
<td>Yes</td>
<td>Yes</td>
<td>Specifies the access direction for VSAM data sets. Valid values are BWD and FWD.</td>
</tr>
<tr>
<td>password=</td>
<td>Yes</td>
<td>Yes</td>
<td>Specifies the password for a VSAM data set.</td>
</tr>
<tr>
<td>asis</td>
<td>Yes</td>
<td>No</td>
<td>Enables the use of mixed-case file names. Not supported for VSAM.</td>
</tr>
<tr>
<td>bytesseek</td>
<td>Yes</td>
<td>Yes</td>
<td>Used for binary stream files to specify that the seeking functions should use relative byte offsets instead of encoded offsets. This is the default setting.</td>
</tr>
<tr>
<td>noseek</td>
<td>Yes</td>
<td>No</td>
<td>Ignored.</td>
</tr>
<tr>
<td>05</td>
<td>Yes</td>
<td>No</td>
<td>Ignored.</td>
</tr>
<tr>
<td>rls=</td>
<td>Yes</td>
<td>Yes</td>
<td>Indicates the VSAM RLS/TVS access mode in which a VSAM file is to be opened.</td>
</tr>
</tbody>
</table>

### Keyword descriptions

**recfm=**

Any values passed into fopen() are ignored.

**lrecl=** and **blksize=**

These keywords are set to the maximum record size of the cluster as initialized in the cluster definition. Any values passed into fopen() are ignored.

**space=**

This keyword is not supported under VSAM.

**type=**

If you use the type= keyword, the only valid value for VSAM data sets is type=record. This opens a file for record I/O.

**acc=**

For VSAM files opened with the keyword type=record, you can specify the direction by using the acc=access_type keyword on the fopen() function call. For text and binary files, the access direction is always forward. Attempts to open a VSAM data set with acc=BWD for either binary or text stream I/O will fail. The access_type can be one of the following:

- **FWD** The acc=FWD keyword specifies that the file be processed in a forward direction. When the file is opened, it will be positioned at the beginning of the first physical record, and any subsequent read operations sets the file position indicator to the beginning of the next record. The default value for the access keyword is acc=FWD.

- **BWD** The acc=BWD keyword specifies that the file be processed in a backward direction. When the file is opened, it is positioned at the beginning of the last physical record and any subsequent read operation sets the file position indicator to the beginning of the preceding record.
You can change the direction of sequential processing (from forward to backward or from backward to forward) by using the `flocate()` function. For more information about `flocate()`, see “Repositioning within record I/O files” on page 165.

**Note:** When opening paths, records with duplicate alternate index keys are processed in order of arrival time (oldest to newest) regardless of the current processing direction.

**password**

VSAM facilities provide password protection for your data sets. You access a data set that has password protection by specifying the password on the `password` keyword parameter of the `fopen()` function call; the password resides in the VSAM catalog entry for the named file. There can be more than one password in the VSAM catalog entry; data sets can have different passwords for different levels of authorization such as reading, writing, updating, inserting, or deleting. For a complete description of password protection on VSAM files, see the list of publications on “DFSMS” on page 1176.

The `password` keyword has the following form, where `x` is a 1- to 8-character password, and `n` is the exact number of characters in the password. The password can contain special characters such as blanks and commas.

```plaintext
password=mx
```

If a required password is not supplied, or if an incorrect password is given, `fopen()` fails.

**asis**

This keyword is not supported for VSAM.

**bytesseek**

When you specify this keyword and open a file in binary stream mode, `fseek()` and `ftell()` use relative byte offsets from the beginning of the file. This is the default setting.

**noseek**

This keyword is ignored for VSAM data sets.

**0S**

This keyword is ignored for VSAM data sets.

**rls=**

Indicates the VSAM RLS/TVS access mode in which a VSAM file is to be opened. This keyword is ignored for non-VSAM files. The following values are valid:

- `nri` — No Read Integrity
- `cr` — Consistent Read
- `cre` — Consistent Read Explicit

**Note:** When the RLS keyword is specified, DISP is changed to default to SHR when dynamic allocation of the data set is performed. In the rare case when a batch job must use RLS without sharing the data set with other tasks, DISP should be OLD. To set DISP to OLD, the application must specify DISP=OLD in the DD statement and start the application using JCL. You cannot specify DISP in the `fopen()` mode argument.
Buffering
Full buffering is the default. You can specify line buffering, but z/OS XL C/C++ treats line buffering as full buffering for VSAM data sets. Unbuffered I/O is not supported under VSAM; if you specify it, your setvbuf() call fails.

To find out how to optimize VSAM performance by controlling the number of VSAM buffers used for your data set, refer to z/OS DFSMS Access Method Services Commands.

Record I/O in VSAM
This section describes how to use record I/O in VSAM. The following topics are covered:
- RRDS Record Structure
- RRDS Record Structure
- Reading Record I/O Files
- Writing to Record I/O Files
- Updating Record I/O Files
- Deleting Records
- Repositioning within Record I/O Files
- Flushing Buffers
- Summary of VSAM Record I/O Operations
- Reading from Text and Binary I/O Files
- Writing to and Updating Text and Binary I/O Files
- Deleting Records in Text and Binary I/O Files
- Repositioning within Text and Binary I/O Files
- Flushing Buffers
- Summary of VSAM Text I/O Operations
- Summary of VSAM Binary I/O Operations

RRDS record structure
For RRDS files opened in record mode, z/OS XL C/C++ defines the following key structure in the C header file <stdio.h>:

```c
typedef struct {
    #ifndef _LP64
    unsigned int __fill, /* version: either 0 or 1 */
    __recnum; /* the key, starting at 1 */
    #else
    unsigned long __fill, /* version: either 0 or 1 */
    __recnum; /* the key, starting at 1 */
    #endif /* not _LP64 */
} __rrds_key_type;

struct {
    __rrds_key_type rrds_key; /* __fill value always 0 */
    char data[MY_REC_SIZE];
} rrds_rec_0;
```

In your source program, you can define an RRDS record structure as either:

```c
struct {
    rrds_key_type rrds_key; /* __fill value always 0 */
    char data[MY_REC_SIZE];
} rrds_rec_0;
```
or:

```c
struct {
   __rrds_key_type rrds_key; /* __fill value always 1 */
   char *data; /* fill value always 1 */
} rrds_rec_1;
```

The z/OS XL C/C++ library recognizes which type of record structures you have used by the value of `rrds_key.__fill`. Zero indicates that the data is contiguous with `rrds_key` and 1 indicates that a pointer to the data follows `rrds_key`.

### Reading record I/O files

To read from a VSAM data set opened with `type=record`, use the Standard C `fread()` library function. If you set the `size` argument to 1 and the `count` argument to the maximum record size, `fread()` returns the number of bytes read successfully.

For more information on `fread()`, see z/OS XL C/C++ Runtime Library Reference.

`fread()` reads one record from the system from the current file position. Thus, if you want to read a certain record, you can call `flocate()` to position the file pointer to point to it; the subsequent call to `fread()` reads in that record.

If you use an `fread()` call to request more bytes than the record about to be read contains, `fread()` reads the entire record and returns the number of bytes read. If you use `fread()` to request fewer bytes than the record about to read contains, `fread()` reads the number of bytes that you specified and returns your request.

`z/OS XL C/C++` VSAM Record I/O does not allow a read operation to immediately follow a write operation without an intervening reposition. `z/OS XL C/C++` treats the following as read operations:

- Calls to read functions that request 0 bytes
- Read requests that fail because of a system error
- Calls to the `ungetc()` function

Calling `fread()` several times in succession, with no other operations on this file in between, reads several records in sequence (sequential processing), which can be forward or backward, depending on the access direction, as described in the following.

- **KSDS, KSDS AIX and ESDS AIX**
  The records are retrieved according to the sequence of the key of reference, or in reverse key sequence.

  **Note:** Records with duplicate alternate index keys are processed in order of arrival time (oldest to newest) regardless of the current processing direction

- **ESDS**
  The records are retrieved according to the sequence they were written to the file (entry sequence), or in reverse entry sequence.

- **RRDS**
  The records are retrieved according to relative record number sequence or reverse relative record number sequence.

  When records are being read, RRNs without an associated record are ignored. For example, if a file has relative records of 1, 2, and 5, the nonexistent records 3 and 4 are ignored.
By default, in record mode, fread() must be called with a pointer to an RRDS record structure. The field __rrds_key_type.__fill must be set to either 0 or 1 indicating the type of the structure, and the count argument must include the length of the __rrds_key_type. fread() returns the RRN number in the __recnum field, and includes the length of the __rrds_key_type in the return value. You can override these operations by setting the _EDC_RRDS_HIDE_KEY environment variable to Y. Once this variable is set, fread() is called with a data buffer and not an RRDS data structure. The return value of fread() is now only the length of the data read. In this case, fread() cannot return the RRN. For information on setting environment variables, see Chapter 32, “Using environment variables,” on page 467.

Writing to record I/O files

To write new records to a VSAM data set opened with type=record, use the Standard C fwrite() library function. If you set size to 1 and count to the desired record size, fwrite() returns the number of bytes written successfully. For more information on fwrite() and the type=record parameter, see z/OS XL C/C++ Runtime Library Reference.

In general, C I/O does not allow a write operation to follow a read operation without an intervening reposition or fflush(). z/OS XL C/C++ counts a call to a write function writing 0 bytes or a write request that fails because of a system error as a write operation. However, z/OS XL C/C++ VSAM record I/O allows a write to directly follow a read. This feature has been provided for compatibility with earlier releases.

The process of writing to a data set for the first time is known as initial loading. Using the fwrite() function, you can write to a new VSAM file in initial load mode just as you would to a file not in initial load mode. Writing to a KSDS PATH or an ESDS PATH in initial load mode is not supported.

If your fwrite() call does not try to write more bytes than the maximum record size, fwrite() writes a record of the length you asked for and returns your request. If your fwrite() call asks for more than the maximum record size, fwrite() writes the maximum record size, sets errno, and returns the maximum record size. In either case, the next call to fwrite() writes to the following record.

Note: If an fwrite() fails, you must reposition the file before you try to read or write again.

- **KSDS, KSDS AIX**
  Records are written to the cluster according to the value stored in the field designated as the prime key.
  You can load a KSDS in any key order but it is most efficient to perform the fwrite() operations in key sequence.

- **ESDS, ESDS AIX**
  Records are written to the end of the file.

- **RRDS**
  Records are written according to the value stored in the relative record number field.
  fwrite() is called with the RRDS record structure.

By default, in record mode, fwrite() and fupdate() must be called with a pointer to an RRDS record structure. The __rrds_key_type fields __fill and __recnum must be set. __fill is set to 0 or 1 to indicate the type of the structure.
The __recnum field specifies the RRN to write, and is required for fwrite() but not fupdate(). The count argument must include the length of the __rrds_key_type. fwrite() and fupdate() include the length of the __rrds_key_type in the return value.

**Updating record I/O files**

The fupdate() function, a z/OS XL C/C++ extension to the SAA C library, is used to update records in a VSAM file. For more information on this function, see z/OS XL C/C++ Runtime Library Reference.

- **KSDS, ESDS, and RRDS**
  To update a record in a VSAM file, you must perform the following operations:
  1. Open the VSAM file in update mode (rb+/r+b, wb+/w+b, or ab+/a+b specified as the required positional parameter of the fopen() function call and type=record).
  2. If the file is not already positioned at the record you want to update, reposition to that record.
  3. Read in the record using fread().
     Once the record you want to update has been read in, you must ensure that no reading, writing, or repositioning operations are performed before fupdate().
  4. Make the necessary changes to the copy of the record in your buffer area.
  5. Update the record from your local buffer area using the fupdate() function. If an fupdate() fails, you must reposition using flocate() before trying to read or write.

**Notes:**

1. If a file is opened in update mode, a read operation can result in the locking of control intervals, depending on shareoptions specification of the VSAM file. If after reading a record, you decide not to update it, you may need to unlock a control interval by performing a file positioning operation to the same record, such as an flocate() using the same key.
2. If fupdate() wrote out a record the file position is the start of the next record. If the fupdate() call did not write out a record, the file position remains the same.

- **KSDS and KSDS PATH**
  You can change the length of the record being updated. If your request does not exceed the maximum record size of the file, fupdate() writes a record of the length requested and returns the request. If your request exceeds the maximum record size of the file, fupdate() writes a record that is the maximum record size, sets errno, and returns the maximum record size.
  You cannot change the prime key field of the record, and in KSDS AIX, you cannot change the key of reference of the record.

- **ESDS**
  You cannot change the length of the record being updated. If the size of the record being updated is less than the current record size, fupdate() updates the amount you specify and does not alter the data remaining in the record. If your request exceeds the length of the record that was read, fupdate() writes a record that is the length of the record that was read, sets errno, and returns the length of the record that was read.

- **ESDS PATH**
You cannot change the length of the record being updated or the key of reference of the record. If the size of the record being updated is less than the current record size, fupdate() updates the amount you specify and does not alter the data remaining in the record. If your request exceeds the length of the record that was read, fupdate() writes a record that is the length of the record that was read, sets errno, and returns the length of the record that was read.

- RRDS
  RRDS files have fixed record length. If you update the record with less than the record size, only those characters specified are updated, and the remaining data is not altered. If your request exceeds the record size of the file, fupdate() writes a record that is the record size, sets errno, and returns the length of the record that was read.

Deleting records
To delete records, use the library function fdel1rec(), a z/OS XL C/C++ extension to the SAA C library. For more information on this function, see z/OS XL C/C++ Runtime Library Reference.

- KSDS, KSDS PATH, and RRDS
  To delete records, you must perform the following operations:
  1. Open the VSAM file in update mode (rb+/r+b, ab+/a+b, or wb+/w+b specified as the required positional parameter of the fopen() function call and type=record).
  2. If the file is not already positioned at the record you want to delete, reposition to that record.
  3. Read the record using the fread() function.
     Once the record you want to delete has been read in, you must ensure that no reading, writing, or repositioning operations are performed before fdel1rec().
  4. Delete the record using the fdel1rec() function.

Note: If the data set was opened with an access mode of rb+ or r+b, a read operation can result in the locking of control intervals, depending on shareoptions specification of the VSAM file. If after reading a record, you decide not to delete it, you may need to unlock a control interval by performing a file-positioning operation to the same record, such as an flocate() using the same key.

- ESDS and ESDS PATH
  VSAM does not support deletion of records in ESDS files.

Repositioning within record I/O files
You can use the following functions to locate a record within a VSAM data set:
  - flocate()
  - ftell(), ftello() and fseek(), fseeko()
  - fgetpos() and fsetpos()
  - rewind()

For complete details on these library functions, see z/OS XL C/C++ Runtime Library Reference.
The `flocate()` C library function can be used to locate a specific record within a VSAM data set given the key, relative byte address, or the relative record number. The `flocate()` function also sets the access direction.

VSAM extended addressability support includes an 8 byte RBA for use with positioning functions such as `flocate()`. `flocate()` supports RBA lengths of 4 and 8 bytes. Existing applications that use `flocate()` with a 4 byte RBA will continue unaffected, but must use a key length of 8 to locate an RBA beyond 4GB.

The following `flocate()` parameters set the access direction to forward:
- `__KEY_FIRST` (the key and `key_len` parameters are ignored)
- `__KEY_EQ`
- `__KEY_GE`
- `__RBA_EQ`

The following `flocate()` parameters all set the access direction to backward and are only valid for record I/O:
- `__KEY_LAST` (the key and `key_len` parameters are ignored)
- `__KEY_EQ_BWD`
- `__RBA_EQ_BWD`

**Note:** The `__RBA_EQ` and `__RBA_EQ_BWD` parameters are not valid for paths and are not recommended for KSDS and RRDS data sets.

You can use the `rewind()` library function instead of calling `flocate()` with `__KEY_FIRST`.

**KSDS, KSDS AIX, and ESDS AIX**
The key parameter of `flocate()` for the options `__KEY_EQ`, `__KEY_GE`, and `__KEY_EQ_BWD` is a pointer to the key of reference of the data set. The `key_len` parameter is the key length as defined for the data set for a full key search, or less than the defined key length for a generic key search (a partial key match).

For KSDSs, `__RBA_EQ` and `__RBA_EQ_BWD` are supported, but are not recommended.

For `__KEY_EQ_BWD` the `key_len` parameter must be equal to the key length as defined for the data set for a full key search.

Alternate indexes do not allow positioning by RBA.

**ESDS**
The key parameter of `flocate()` is a pointer to the specified RBA value. The `key_len` parameter is either 4 or 8 depending on the size of the RBA.

**RRDS**
For `__KEY_EQ`, `__KEY_GE`, and `__KEY_EQ_BWD`, the key parameter of `flocate()` is a pointer to an unsigned long integer containing the specified relative record number. The `key_len` parameter is size of unsigned long. For `__RBA_EQ` and `__RBA_EQ_BWD`, the key parameter of `flocate()` is a pointer to the specified RBA. However, seeking to RBA values is not recommended, because it is not supported across control intervals. The `key_len` parameter is either 4 or 8 depending on the size of the RBA.
**fgetpos() and fsetpos()**

`fgetpos()` is used to store the current file position and access direction. `fsetpos()` is used to relocate to a file position stored by `fgetpos()` and restore the saved access direction.

- **KSDS**
  - `fgetpos()` stores the RBA value. This RBA value may be invalidated by subsequent insertions, deletions, or updates.

- **KSDS AIX and ESDS AIX**
  - `fgetpos()` and `fsetpos()` are not supported for PATHs.

- **ESDS and RRDS**
  - There are no special considerations.

**ftell() and fseek()**

`ftell()` is used to store the current file position. `fseek()` is used to relocate to one of the following:

- A file position stored by `ftell()`
- A calculated record number (SEEK_SET)
- A position relative to the current position (SEEK_CUR)
- A position relative to the end of the file (SEEK_END).

`ftell()` and `fseek()` offsets in record mode I/O are relative record offsets. For example, the following call moves the file position to the start of the previous record:

```c
fseek(fp, -1L, SEEK_CUR);
```

You cannot use `fseek()` to reposition to a file position before the beginning of the file or to a position beyond the end of the file.

**Note:** In general, the performance of this method is inferior to `flocate()`.

The access direction is unchanged by the repositioning.

- **KSDS and RRDS**
  - There are no special considerations.

- **KSDS AIX and ESDS AIX**
  - `ftell()` and `fseek()` are not supported.

- **ESDS**
  - `ftell()` is not supported.

- **RRDS**
  - `fseek()` seeks to a relative position in the file, and not to an RRN value. For example, in a file consisting of RRNs 1, 3, 5 and 7, `fseek(fp, 3L, SEEK_SET)`; followed by an `fread()` would read in RRN 7, which is at offset 3 in the file.

**rewind()**

The `rewind()` function repositions the file position to the beginning of the file, and clears the error setting for the file. `rewind()` does not reset the file access direction. For example, a call to `flocate()` with `__KEY_LAST` sets the file pointer to the end of the file and sets the access direction to backwards. A subsequent call to `rewind()` sets the file pointer to the beginning of the file, but the access direction remains backwards.
Flushing buffers

You can use the C library function `fflush()` to flush buffers. However, `fflush()` writes nothing to the system, because all records have already been written there by `fwrite()`. `fflush()` after a read operation does not refresh the contents of the buffer. For more information on `fflush()`, see z/OS XL C/C++ Runtime Library Reference.

Summary of VSAM record I/O operations

Table 27. Summary of VSAM record I/O operations

<table>
<thead>
<tr>
<th>Function</th>
<th>KSDS</th>
<th>ESDS</th>
<th>RRDS</th>
<th>PATH</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>fopen()</code>, <code>freopen()</code></td>
<td>rb, rb+, ab+, wb+, wb+ (empty cluster or reuse specified for wb &amp; wb+)</td>
<td>rb, rb+, ab+, wb+, wb+ (empty cluster or reuse specified for wb &amp; wb+)</td>
<td>rb, rb+, ab+, wb+, wb+ (empty cluster or reuse specified for wb &amp; wb+)</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>fwrite()</code>, <code>fwrite_unlocked()</code></td>
<td>rb+, ab+, wb+, wb+</td>
<td>rb+, ab+, wb+, wb+</td>
<td>rb+, ab+, wb+, wb+</td>
<td>rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>fread()</code>, <code>fread_unlocked()</code></td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>ftell()</code>, <code>ftell_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+ (see note 1)</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>ftello()</code>, <code>ftello_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+ (see note 1)</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>fseek()</code>, <code>fseek_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+ (see note 1)</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>fseeko()</code>, <code>fseeko_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+ (see note 1)</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>fgetpos()</code>, <code>fgetpos_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+ (see note 2)</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>fsetpos()</code>, <code>fsetpos_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+ (see note 2)</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>flocate()</code> <code>flocate_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
<td>rb, rb+, ab+</td>
</tr>
<tr>
<td><code>rewind()</code>, <code>rewind_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>fflush()</code>, <code>fflush_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>fdelrec()</code>, <code>fdelrec_unlocked()</code></td>
<td>rb+, ab+, wb+</td>
<td>rb+, ab+, wb+</td>
<td>rb+, ab+, wb+</td>
<td>rb+, ab+ (not ESDS)</td>
</tr>
<tr>
<td><code>fupdate()</code>, <code>fupdate_unlocked()</code></td>
<td>rb+, ab+, wb+</td>
<td>rb+, ab+, wb+</td>
<td>rb+, ab+, wb+</td>
<td>rb+, ab+</td>
</tr>
<tr>
<td><code>ferror()</code>, <code>ferror_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>feof()</code>, <code>feof_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>clearerr()</code>, <code>clearerr_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>fclose()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
<tr>
<td><code>fldata()</code>, <code>fldata_unlocked()</code></td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+, wb+</td>
<td>rb, rb+, ab+, wb+</td>
</tr>
</tbody>
</table>
Table 27. Summary of VSAM record I/O operations (continued)

<table>
<thead>
<tr>
<th>KSIDS</th>
<th>ESDS</th>
<th>RRDS</th>
<th>PATH</th>
</tr>
</thead>
</table>

**Notes:**
1. The saved position is based on the relative position of the record within the data set. Subsequent insertions or deletions may invalidate the saved position.
2. The saved position is based on the RBA of the record. Subsequent insertions, deletions or updates may invalidate the saved position.

---

**VSAM record level sharing and transactional VSAM**

VSAM Record Level Sharing (RLS) and Transactional VSAM (VSAM RLS/TVS) provide for the sharing of VSAM data at the record level, using the locking and caching functions of the coupling facility hardware. For more information on Record Level Sharing, see z/OS DFSMS Introduction.

The C/C++ runtime library provides the following support for VSAM RLS/TVS:
- Specification of RLS/TVS-related keywords in the mode string of `fopen()` and `freopen()`.
- Specification of RLS/TVS-related text unit key values in the `__dyn_t` structure, which is used as input to the `dynalloc()` function.
- Provides the application with VSAM return and reason codes for VSAM I/O errors.
- Performs implicit positioning for files opened for RLS/TVS access.

VSAM RLS/TVS has three read integrity file access modes. These modes tell VSAM the level of locking to perform when records are accessed within a file that has not been opened in update mode. The access modes are:

- **nri** No Read Integrity indicates that requests performed by the application are not to be serialized with updates or erases of the records by other calling programs. VSAM accesses the records without obtaining a lock on the record.

- **cr** Consistent Read indicates that requests performed by the application are to be serialized with updates or erases of the records by other calling programs. VSAM obtains a share lock when accessing the record. This lock is released once the record has been returned to the caller.

- **cre** Consistent Read Explicit indicates that requests performed by the application are to be serialized with updates or erases of the records by other requestors. VSAM obtains a share lock when accessing the record. This lock is held until the application commits its changes. This ensures that records read by the application are not changed by other requestors until the application commits or aborts its changes. Consistent Read Explicit is for use only by commit protocol applications.

VSAM RLS locks records to support record integrity. An application may wait for an exclusive record lock if another user has the record locked. The application is also subject to new locking errors such as deadlock or timeout errors.

If the file has been opened in update mode, and `RLS=CR` or `RLS=CRE` is specified, VSAM also serializes access to the records within the file. However, the type of serialization differs from non-update mode in the following ways:
- A reposition within the file causes VSAM to obtain a share lock for the record.
A read of a record causes VSAM to obtain an exclusive lock for the record. The lock is held until the record is updated in the file, or another record is read. If RLS=CRE is specified (for commit protocol applications), the lock is held until the application commits or aborts its changes.

Notes:
1. When a file is opened, it is implicitly positioned to the first record to be accessed.
2. You can also specify the RLS/TVS keyword on the JCL DD statement. When specified on both the JCL DD statement and in the mode string on fopen() or freopen(), the read integrity options specified in the mode string override those specified on the JCL DD statement.
3. VSAM RLS/TVS access is supported for the 3 types of VSAM files that the C/C++ runtime library supports: Key-Sequenced (KSDS), Entry-Sequenced (ESDS), and Relative Record (RRDS) data sets.
4. VSAM RLS/TVS functions require the use of a Coupling Facility. For more information on using the Coupling Facility, see z/OS DFSMS Introduction, and z/OS Parallel Sysplex Overview.
5. In an environment where one thread opens and another thread issues record management requests, VSAM RLS/TVS requires that record management requests be issued from a thread whose Task Control Block (TCB) is subordinate to the TCB of the thread which opened the file.
6. VSAM RLS/TVS does not support the following:
   - Key range data sets
   - Direct open of an AIX cluster as a KSDS
   - Access to individual components of a cluster
   - OS Checkpoint and Restart

Error reporting
Errors are reported through the __amrc structure and the SIGIOERR signal. The following are additional considerations for error reporting in a VSAM RLS application:
   - VSAM RLS/TVS uses the SMSVSAM server address space. When a file open fails because the server is not available, the C runtime library places the error return code and error value in the __amrc structure, and returns a null file descriptor. Record management requests return specific error return/reason codes, if the SMSVSAM server is not available. The server address space is automatically restarted. To recover from this type of error, an application should first close the file to clean up the file status, and then open the file prior to attempting record management requests. The close for the file returns a return code of 4, and an error code of 170(X'AA'). This is the expected result. It is not an error.
   - Opening a recoverable file for output is not supported. If you attempt to do so, the open will fail with error return code 255 in the __amrc structure.
   - Some of the VSAM errors, that are reported in the __amrc structure, are situations from which an application can recover. These are problems that can occur unpredictably in a sharing environment. Usually, the application can recover by simply accessing another record. Examples of such errors are the following:
     - RC 8, 21(X'15'): Request cancelled as part of deadlock resolution.
     - RC 8, 22(X'16'): Request cancelled as part of timeout resolution.
- RC 8, 24(X'18'): Request cancelled because transaction backout is pending on the requested record.
- RC 8, 29(X'14'): Intra-luwid contention between threads under a given TCB.

The application can intercept errors by registering a condition handler for the SIGIOERR condition. Within the condition handler, the application can examine the information in the __amrc structure and determine how to recover from each specific situation.

Refer to z/OS DFSMS Macro Instructions for Data Sets for a complete list of return and reason codes.

---

**VSAM extended addressability**

DFSMS supports VSAM data sets greater than 4GB in size through extended addressability (XADDR) support. XADDR support is an extension to DFSMS extended-format data set support. VSAM XADDR supports key sequenced data sets (KSDS), entry sequenced data sets (ESDS), and relative-record data set (RRDS).

**Restriction:** z/OS XL C/C++ does not support XADDR for ESDS alternate indexes.

VSAM XADDR support includes an 8 byte relative byte address for use with positioning functions such as flocate(). flocate() supports key lengths of 4 and 8 bytes. Existing applications that use flocate() to locate with a 4 byte relative byte address will continue unaffected, but must use a key length of 8 to locate a record within XADDR addresses.

The RBA field in the __amrc structure is set to -1 when applications access beyond the addresses that can be represented by the 4 byte value, effectively appearing to be EOF to any 4 byte RBA positioning (flocate()) calls. The __XRBA field will always be updated with the address, and must be used in these cases.

For AMODE 31 applications repositioning within a VSAM data set, users of ftell() and fseek() that need to access XADDR addresses, must use the large file version of ftello() and fseeko().

XADDR support for AMODE 31 applications is listed in the following table:

<table>
<thead>
<tr>
<th>Function</th>
<th>XADDR support</th>
</tr>
</thead>
<tbody>
<tr>
<td>fgetpos(), fgetpos_unlocked()</td>
<td>Yes</td>
</tr>
<tr>
<td>fsetpos(), fsetpos_unlocked()</td>
<td>Yes</td>
</tr>
<tr>
<td>ftell(), ftell_unlocked()</td>
<td>No</td>
</tr>
<tr>
<td>fseek(), fseek_unlocked()</td>
<td>No</td>
</tr>
<tr>
<td>ftello() or ftello_unlocked()</td>
<td>No</td>
</tr>
<tr>
<td>fseeko() or fseeko_unlocked()</td>
<td>No</td>
</tr>
<tr>
<td>ftello() or ftello_unlocked() non-large files version</td>
<td>No</td>
</tr>
<tr>
<td>fseeko() or fseeko_unlocked() non-large files version</td>
<td>No</td>
</tr>
<tr>
<td>flocate() or flocate_unlocked()</td>
<td>Yes</td>
</tr>
<tr>
<td>fseeko() or fseeko_unlocked() large files version</td>
<td>Yes</td>
</tr>
<tr>
<td>flocate() or flocate_unlocked() large files version</td>
<td>Yes</td>
</tr>
</tbody>
</table>

---

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Note: AMODE 64 applications also have the above restrictions on XADDR support.

Text and binary I/O in VSAM

Because VSAM is primarily record-based, this section only discusses those aspects of text and binary I/O that are specific to VSAM. For general information on text and binary I/O, refer to the respective sections in Chapter 10, “Performing OS I/O operations,” on page 83.

Reading from text and binary I/O files

- RRDS
  All the read functions support reading from text and binary RRDS files. fread() is called with a character buffer instead of an RRDS record structure.

Writing to and updating text and binary I/O files

- KSDS, KSDS AIX, and ESDS AIX
  z/OS XL C/C++ VSAM support for streams does not provide for writing and updating these types of data sets opened for text or binary stream I/O.

- ESDS
  Writes are supported for ESDSs opened as binary or text streams. Updating data in an ESDS stream cannot change the length of the record in the external file. Therefore, in a binary stream:
  - updates for less than the existing record length leave existing data beyond the updated length unchanged;
  - updates for longer than the existing record length flow over the record boundary and update the start of the next record.

  In text streams:
  - updates that specify records shorter than the original record pad the updated record to the existing record length with blanks;
  - updates for longer than the existing record length result in truncation, unless the original record contained only a new-line character, in which case it may be updated to contain one byte of data plus a new-line character.

- RRDS
  fwrite() is called with a character buffer instead of an RRDS record structure. Records are treated as contiguous. Once the current record is filled, the next record in the file is written to. For example, if the file consisted of only record 1, record 5, and record 28, a write would complete record 1 and then go directly to record 5.

  Writing past the last record in the file is allowed, up to the maximum size of the RRDS data set. For example, if the last record in the file is record 28, the next record to be written is record 29.

  Insertion of records is not supported. For example, in a file of records 1, 5, and 28, you cannot insert record 3 into the file.

Deleting records in text and binary I/O files

fdelrec() is not supported for text and binary I/O in VSAM.
Repositioning within text and binary I/O files

You can use the following functions to locate a record within a VSAM data set:
- `flocate()`
- `ftell()`, `ftello()`, `fseek()`, and `fseeko()`
- `fgetpos()` and `fsetpos()`
- `rewind()`

For complete details on these library functions, see z/OS XL C/C++ Runtime Library Reference.

`flocate()`
The `flocate()` C library function can be used to reposition to the beginning of a specific record within a VSAM data set given the key, relative byte address, or the relative record number. For more information on this function, see z/OS XL C/C++ Runtime Library Reference.

VSAM extended addressability support includes an 8 byte RBA for use with positioning functions such as `flocate()`. `flocate()` supports RBA lengths of 4 and 8 bytes. Existing applications that use `flocate()` with a 4 byte RBA will continue unaffected, but must use a key length of 8 to locate an RBA beyond 4GB.

The following `flocate()` parameters set the direction access to forward:
- `__KEY_FIRST` (the key and key_len parameters are ignored)
- `__KEY_EQ`
- `__KEY_GE`
- `__RBA_EQ`

The following `flocate()` parameters all set the access direction to backward and are not valid for text and binary I/O, because backwards access is not supported:
- `__KEY_LAST` (the key and key_len parameters are ignored)
- `__KEY_EQ_BWD`
- `__RBA_EQ_BWD`

You can use the `rewind()` library function instead of calling `flocate()` with `__KEY_FIRST`.

- **KSDS, KSDS AIX, and ESDS AIX**
The key parameter of `flocate()` for the options `__KEY_EQ` and `__KEY_GE` is a pointer to the key of reference of the data set. The key_len parameter is the key length as defined for the data set for a full key search, or less than the defined key length for a generic key search (a partial key match).

Alternate indexes do not allow positioning by RBA.

**Note:** The `__RBA_EQ` parameter is not valid for paths and is not recommended.

- **ESDS**
The key parameter of `flocate()` is a pointer to the specified RBA value. The key_len parameter is either 4 or 8 depending on the size of the RBA.

- **RRDS**
For `__KEY_EQ` and `__KEY_GE`, the key parameter of `flocate()` is a pointer to an unsigned long integer containing the specified relative record number. The key_len parameter is `sizeof(unsigned long)`. For `__RBA_EQ`, the key parameter of `flocate()` is a pointer to the specified RBA. However, seeking to RBA values is
not recommended, because it is not supported across control intervals. The key_len parameter is either 4 or 8 depending on the size of the RBA.

**fgetpos() and fsetpos()**

fgetpos() saves the access direction, an RBA value, and the file position, and fsetpos() restores the saved access direction. fgetpos() accounts for the presence of characters in the ungetc() buffer unless you have set the _EDC_COMPAT variable. See [Chapter 32, “Using environment variables,” on page 467](#) for information about _EDC_COMPAT. If ungetc() characters back the file position up to before the start of the file, calls to fgetpos() fail.

- **KSDS**
  fgetpos() stores the RBA value. This RBA value may be invalidated by subsequent insertions, deletions or updates.

- **KSDS PATH and ESDS PATH**
  fgetpos() and fsetpos() are not supported for PATHs.

- **ESDS and RRDS**
  There are no special considerations.

**ftell() and fseek()**

Using fseek() to seek beyond the current end of file in a writable ESDS or RRDS binary file results in the file being extended with nulls to the new position. An incomplete last record is completed with nulls, records of length lrecl are added as required, and the current record is filled with the remaining number of nulls and left in the current buffer. This is supported for relative byte offset from SEEK_SET, SEEK_CUR and SEEK_END.

For AMODE 31 applications repositioning within a VSAM data set, users of ftell() and fseek() that need to access positions beyond 4GB, must use the large file version of ftello() and fseeko() .

Table 29 provides a summary of the fseek() and ftell() parameters in binary and text.

<table>
<thead>
<tr>
<th>Type</th>
<th>Mode</th>
<th>ftell() return values</th>
<th>fseek() MODE</th>
<th>SEEK_SET</th>
<th>SEEK_CUR</th>
<th>SEEK_END</th>
</tr>
</thead>
<tbody>
<tr>
<td>KSDS</td>
<td>Binary</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Text</td>
<td>not supported</td>
<td>zero only</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td></td>
</tr>
<tr>
<td>ESDS</td>
<td>Binary</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Text</td>
<td>not supported</td>
<td>zero only</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td></td>
</tr>
<tr>
<td>RRDS</td>
<td>Binary</td>
<td>encoded byte offset</td>
<td>encoded byte offset</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Text</td>
<td>encoded byte offset</td>
<td>encoded byte offset</td>
<td>relative byte offset</td>
<td>relative byte offset</td>
<td></td>
</tr>
<tr>
<td>PATH</td>
<td>Binary</td>
<td>not supported</td>
<td>not supported</td>
<td>not supported</td>
<td>not supported</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Text</td>
<td>not supported</td>
<td>not supported</td>
<td>not supported</td>
<td>not supported</td>
<td></td>
</tr>
</tbody>
</table>

**flushing buffers**

You can use the C library function fflush() to flush data.
For text files, calling `fflush()` to flush an update to a record causes the new data to be written to the file.

If you call `fflush()` while you are updating, the updates are flushed out to VSAM.

For more information on `fflush()`, see z/OS XL C/C++ Runtime Library Reference.

### Summary of VSAM text I/O operations

Table 30 summarizes the VSAM text I/O operations.

<table>
<thead>
<tr>
<th>Function</th>
<th>KSDS</th>
<th>ESDS</th>
<th>RRDS</th>
<th>PATH</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>fopen()</code>, <code>freopen()</code></td>
<td>r</td>
<td>r, r, a, a+, w, w+ (empty cluster or reuse specified for w &amp; w+)</td>
<td>r, r, a, a+, w, w+</td>
<td></td>
</tr>
<tr>
<td><code>fwrite()</code>, <code>fwrite_unlocked()</code></td>
<td>r+, a, a+, w, w+</td>
<td>r+, a, a+, w, w+</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>fprintf()</code>, <code>fprintf_unlocked()</code></td>
<td>r+, a, a+, w, w+</td>
<td>r+, a, a+, w, w+</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>fputs()</code>, <code>fputs_unlocked()</code></td>
<td>r+, a, a+, w, w+</td>
<td>r+, a, a+, w, w+</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>fputc()</code>, <code>fputc_unlocked()</code></td>
<td>r+, a, a+, w, w+</td>
<td>r+, a, a+, w, w+</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>putc()</code>, <code>putc_unlocked()</code></td>
<td>r+, a, a+, w, w+</td>
<td>r+, a, a+, w, w+</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>vfprintf()</code>, <code>vfprintf_unlocked()</code></td>
<td>r+, a, a+, w, w+</td>
<td>r+, a, a+, w, w+</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>vfprintf()</code>, <code>vfprintf_unlocked()</code></td>
<td>r+, a, a+, w, w+</td>
<td>r+, a, a+, w, w+</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>fread()</code>, <code>fread_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, w+</td>
<td>r, r+, a+, w+</td>
<td></td>
</tr>
<tr>
<td><code>fscanf()</code>, <code>fscanf_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, w+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>vfprintf()</code>, <code>vfprintf_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, w+</td>
<td>r, r+, a+, w+</td>
<td></td>
</tr>
<tr>
<td><code>fgets()</code>, <code>fgets_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fgetc()</code>, <code>fgetc_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>ungetc()</code>, <code>ungetc_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>ftell()</code>, <code>ftell_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fseek()</code>, <code>fseek_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fseeko()</code>, <code>fseeko_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fsetpos()</code>, <code>fsetpos_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>flocate()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>rewind()</code>, <code>rewind_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fflush()</code>, <code>fflush_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>ferror()</code>, <code>ferror_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fdelrec()</code>, <code>fdelrec_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fupdate()</code>, <code>fupdate_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>feof()</code>, <code>feof_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>clearerr()</code>, <code>clearerr_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fclose()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
<tr>
<td><code>fldata()</code>, <code>fldata_unlocked()</code></td>
<td>r</td>
<td>r, r+, a+, W+</td>
<td>r, r+, a+, W+</td>
<td></td>
</tr>
</tbody>
</table>

---

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### Summary of VSAM binary I/O operations

Table 31 summarizes the VSAM binary I/O operations.

<table>
<thead>
<tr>
<th>Function</th>
<th>KDS</th>
<th>EDS</th>
<th>RRDS</th>
<th>PATH</th>
</tr>
</thead>
<tbody>
<tr>
<td>fopen(), freopen()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>...</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>fwrite(), fwrite_unlocked()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>fprintf(), fprintf_unlocked()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>fputc(), fputc_unlocked()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>...</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>ftell(), ftell_unlocked()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>ftello(), ftello_unlocked()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>fgetpos(), fgetpos_unlocked()</td>
<td>rb</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>...</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>fclose()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
</tbody>
</table>

#### Closing VSAM data sets

To close a VSAM data set, use the Standard C fclose() library function as you would for closing non-VSAM files. See z/OS XL C/C++ Runtime Library Reference for more details on the fclose() library function.

For ESDS binary files, if fclose() is called and there is a new record in the buffer that is less than the maximum record size, this record is written to the file at its

---

**Table 31. Summary of VSAM binary I/O operations**

<table>
<thead>
<tr>
<th>Function</th>
<th>KDS</th>
<th>EDS</th>
<th>RRDS</th>
<th>PATH</th>
</tr>
</thead>
<tbody>
<tr>
<td>fopen()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>freopen()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>fwrite()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>fprintf()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>fputs()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>fputc()</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
<td></td>
</tr>
<tr>
<td>getc()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>ungetc()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>ftell()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>ftello()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>fgetpos()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
<tr>
<td>...</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>fclose()</td>
<td>rb</td>
<td>rb+</td>
<td>ab+</td>
<td>wb+</td>
</tr>
</tbody>
</table>

---

**Closing VSAM data sets**

To close a VSAM data set, use the Standard C fclose() library function as you would for closing non-VSAM files. See z/OS XL C/C++ Runtime Library Reference for more details on the fclose() library function.

For ESDS binary files, if fclose() is called and there is a new record in the buffer that is less than the maximum record size, this record is written to the file at its
current size. A new RRDS binary record that is incomplete when the file is closed is filled with null characters to the record size.

A new ESDS or RRDS text record that is incomplete when the file is closed is completed with a new-line.

---

**VSAM return codes**

When failing return codes are received from z/OS XL C/C++ VSAM I/O functions, you can access the `__amrc` structure to help you diagnose errors. The `__amrc_type` structure is defined in the header file `stdio.h` (when the compiler option `LANGLVL(LIBEXT)` is used).

**Note:** The `__amrc` struct is global and can be reset by another I/O operation (such as `printf()`).

The following fields of the structure are important to VSAM users:

- `__amrc.__code.__feedback.__rc`  
  Stores the VSAM R15.

- `__amrc.__code.__feedback.__fdbk`  
  Stores the VSAM error code or reason code.

- `__amrc.__RBA`  
  Stores the RBA after some operations. The `__amrc.__RBA` field is defined as an unsigned int, and therefore will only contain a 4-byte RBA value. This field will be set to -1 when the RBA is beyond 4GB in an extended addressable VSAM data set. In this case, the `__XRBA` field should be used.

- `__amrc.__XRBA`  
  The 8 byte relative byte address returned by VSAM after an ESDS or KSDS record is written out. For an RRDS, it is the calculated value from the record number. It may be used in subsequent calls to `flocate()`.

- `__amrc.__last_op`  
  Stores a code for the last operation. The codes are defined in the header file `stdio.h`.

- `__amrc.__rplfdbwd`  
  Stores the feedback code from the IFGRPL control block.

For definitions of these return codes and feedback codes, refer to the publications listed in "DFSMS" on page 1176.

You can set up a `SIGIOERR` handler to catch read or write system errors. See Chapter 18, “Debugging I/O programs,” on page 223 for more information.

---

**VSAM examples**

This section provides several examples of using I/O under VSAM.

**KSDS example**

The example in Figure 26 shows a sample program (CCNGVS2) with two functions from an employee record entry system with a mainline driver to process selected options (display, display next, update, delete, create). The update routine is an example of KSDS clusters, and the display routine is an example of both KSDS clusters and alternate indexes.
For these examples, the clusters and alternate indexes should be defined as follows:

- The KSDS cluster has a record size of 150 with a key length of 4 with offset 0.
- The unique KSDS AIX has a key length of 20 with an offset of 10.
- The non-unique KSDS AIX has a key length of 40 with an offset of 30.

The update routine is passed the following:

- `data_ptr`, which points to the information that is to be updated
- `orig_data_ptr`, which points to the information that was originally displayed using the display option
- A file pointer to the KSDS cluster

The display routine is passed the following:

- `data_ptr`, which points to the information that was entered on the screen for the search query
- `orig_data_ptr`, which is returned with the information for the record to be displayed if it exists
- File pointers for the primary cluster, unique alternate index and non-unique alternate index

By definition, the primary key is unique and therefore the employee number was chosen for this key. The `user_id` is also a unique key; therefore, it was chosen as the unique alternate index key. The name field may not be unique; therefore, it was chosen as the non-unique alternate index key.
/* this example demonstrates the use of a KSDS file */
/* part 1 of 2-other file is CCNGVS3 */

#include <stdio.h>
#include <string.h>

/* global definitions */

struct data_struct {
    char emp_number[4];
    char user_id[8];
    char name[20];
    char pers_info[37];
};

#define REC_SIZE 69
#define CLUS_KEY_SIZE 4
#define AIX_UNIQUE_KEY_SIZE 8
#define AIX_NONUNIQUE_KEY_SIZE 20

static void print_amrc() {
    __amrc_type currErr = *__amrc; /* copy contents of __amrc */
    /* structure so that values */
    /* don't get jumbled by printf */
    printf("R15 value = %d\n", currErr.__code.__feedback.__rc);
    printf("Reason code = %d\n", currErr.__code.__feedback.__fdbk);
    printf("RBA = %d\n", currErr.__RBA);
    printf("Last op = %d\n", currErr.__last_op);
    return;
}

/* update_emp_rec() function definition */

int update_emp_rec (struct data_struct *data_ptr,
                struct data_struct *orig_data_ptr,
                FILE *fp)
{
    int rc;
    char buffer[REC_SIZE+1];

KSDS example (Part 1 of 5)

Figure 26. KSDS example
/* Check to see if update will change primary key (emp_number) */

if (memcmp(data_ptr->emp_number,orig_data_ptr->emp_number,4) != 0) {
    /* Check to see if changed primary key exists */
    rc = flocate(fp,&(data_ptr->emp_number),CLUS_KEY_SIZE,__KEY_EQ);
    if (rc == 0) {
        print_amrc();
        printf("Error: new employee number already exists\n");
        return 10;
    }

    clearerr(fp);

    /* Write out new record */
    rc = fwrite(data_ptr,1,REC_SIZE,fp);
    if (rc != REC_SIZE || ferror(fp)) {
        print_amrc();
        printf("Error: write with new employee number failed\n");
        return 20;
    }

    /* Locate to old employee record so it can be deleted */
    rc = flocate(fp,&(orig_data_ptr->emp_number),CLUS_KEY_SIZE,__KEY_EQ);
    if (rc != 0) {
        print_amrc();
        printf("Error: flocate to original employee number failed\n");
        return 30;
    }

    rc = fread(buffer,1,REC_SIZE,fp);
    if (rc != REC_SIZE || ferror(fp)) {
        print_amrc();
        printf("Error: reading old employee record failed\n");
        return 40;
    }

    rc = fdelrec(fp);
    if (rc != 0) {
        print_amrc();
        printf("Error: deleting old employee record failed\n");
        return 50;
    }
} /* end of checking for change in primary key */
else { /* Locate to current employee record */
    rc = flocate(fp,&(data_ptr->emp_number),CLUS_KEY_SIZE,__KEY_EQ);
    if (rc == 0) {
        /* record exists, so update it */
        rc = fread(buffer,1,REC_SIZE,fp);
        if (rc != REC_SIZE || ferror(fp)) {
            print_amrc();
            printf("Error: reading old employee record failed\n");
            return 60;
        }

        rc = fupdate(data_ptr,REC_SIZE,fp);
        if (rc == 0) {
            print_amrc();
            printf("Error: updating new employee record failed\n");
            return 70;
        }
    }
}

KSDS example (Part 2 of 5)
else { /* record doesn't exist so write out new record */
    clearerr(fp);
    printf("Warning: record previously displayed no longer\n");
    printf(" : exists, new record being created\n");
    rc = fwrite(data_ptr,1,REC_SIZE,fp);
    if (rc != REC_SIZE || ferror(fp)) {
        print_amrc();
        printf("Error: write with new employee number failed\n");
        return 80;
    }
}
}
return 0;

/* display_emp_rec() function definition */
int display_emp_rec (struct data_struct *data_ptr,
        struct data_struct *orig_data_ptr,
        FILE *clus_fp, FILE *aix_unique_fp,
        FILE *aix_non_unique_fp)
{
    int rc = 0;
    char buffer[REC_SIZE+1];

    /* Primary Key Search */
    if (memcmp(data_ptr->emp_number, "\0\0\0\0", 4) != 0) {
        rc = flocate(clus_fp,&(data_ptr->emp_number),CLUS_KEY_SIZE,  
                __KEY_EQ);
        if (rc != 0) {
            printf("Error: flocate with primary key failed\n");
            return 10;
        }
        /* Read record for display */
        rc = fread(orig_data_ptr,1,REC_SIZE,clus_fp);
        if (rc != REC_SIZE || ferror(clus_fp)) {
            printf("Error: reading employee record failed\n");
            return 15;
        }
    }

    /* Unique Alternate Index Search */
    else if (data_ptr->user_id[0] != '\0') {
        rc = flocate(aix_unique_fp,data_ptr->user_id,AIX_UNIQUE_KEY_SIZE,  
                __KEY_EQ);
        if (rc != 0) {
            printf("Error: flocate with user id failed\n");
            return 20;
        }
        /* Read record for display */
        rc = fread(orig_data_ptr,1,REC_SIZE,aix_unique_fp);
        if (rc != REC_SIZE || ferror(aix_unique_fp)) {
            printf("Error: reading employee record failed\n");
            return 25;
        }
    }
}

KSDS example (Part 3 of 5)
/* Non-unique Alternate Index Search */

else if (data_ptr->name[0] != '\'0') {
    rc = flocate(aix_non_unique_fp, data_ptr->name,
                 AIX_NONUNIQUE_KEY_SIZE, _KEY_GE);
    if (rc != 0) {
        printf("Error: flocate with name failed\n");
        return 30;
    }

    /* Read record for display */
    rc = fread(orig_data_ptr, 1, REC_SIZE, aix_non_unique_fp);
    if (rc != REC_SIZE || ferror(aix_non_unique_fp)) {  
        printf("Error: reading employee record failed\n");
        return 35;
    }
}
else {
    printf("Error: invalid search argument; valid search arguments\n"
           " : are either employee number, user id, or name\n");
    return 40;
}

/* display record data */

printf("Employee Number: %.4s\n", orig_data_ptr->emp_number);
printf("Employee Userid: %.8s\n", orig_data_ptr->user_id);
printf("Employee Name: %.20s\n", orig_data_ptr->name);
printf("Employee Info: %.37s\n", orig_data_ptr->pers_info);
return 0;
}

/* main() function definition */

int main() {
    FILE* clus_fp;
    FILE* aix_ufp;
    FILE* aix_nufp;
    int i;
    struct data_struct buf1, buf2;

    char data[3][REC_SIZE+1] = {
        "1LARRY  LARRY HI, I'M LARRY, ",
        "2DARRYL1 DARRYL AND THIS IS MY BROTHER DARRYL, ",
        "3DARRYL2 DARRYL ",
    };

    /* open file three ways */
    clus_fp = fopen("dd:cluster", "rb+,type=record");
    if (clus_fp == NULL) {
        print_amrc();
        printf("Error: fopen("dd:cluster"...) failed\n");
        return 5;
    }

    /* assume base cluster was loaded with at least one dummy record 
   */
    /* so aix could be defined */
    aix_ufp = fopen("dd:aixuniq", "rb,type=record");
    if (aix_ufp == NULL) {
        print_amrc();
        printf("Error: fopen("dd:aixuniq"...) failed\n");
        return 10;
    }

    /* assume base cluster was loaded with at least one dummy record */
    /* so aix could be defined */
    aix_nufp = fopen("dd:aixnuniq", "rb,type=record");
if (aix_nufp == NULL) {
    print_amrc();
    printf("Error: fopen("dd:aixnuniq"...) failed\n");
    return 15;
}

/* load sample records */
for (i=0; i<3; ++i) {
    if (fwrite(data[i],1,REC_SIZE,clus_fp) != REC_SIZE) {
        print_amrc();
        printf("Error: fwrite(data[%d]...) failed\n", i);
        return 66+i;
    }
}

/* display sample record by primary key */
memcpy(buf1.emp_number, " 1", 4);
if (display_emp_rec(&buf1, &buf2, clus_fp, aix_ufp, aix_nufp) != 0)
    return 69;

/* display sample record by nonunique aix key */
memset(buf1.emp_number, '\0', 4);
buf1.user_id[0] = '\0';
memcpy(buf1.name, "DARRYL ", 20);
if (display_emp_rec(&buf1, &buf2, clus_fp, aix_ufp, aix_nufp) != 0)
    return 70;

/* display sample record by unique aix key */
memcpy(buf1.user_id, "DARRYL2 ", 8);
if (display_emp_rec(&buf1, &buf2, clus_fp, aix_ufp, aix_nufp) != 0)
    return 71;

/* update record just read with new personal info */
memcpy(buf1, &buf2, REC_SIZE);
memcpy(buf1.pers_info, "AND THIS IS MY OTHER BROTHER DARRYL. ", 37);
if (update_emp_rec(&buf1, &buf2, clus_fp) != 0) return 72;

/* display sample record by unique aix key */
if (display_emp_rec(&buf1, &buf2, clus_fp, aix_ufp, aix_nufp) != 0)
    return 73;

return 0;
}

KSDS example (Part 5 of 5)

The JCL in the sample code (CCNGVS3) in Figure 27 on page 184 can be used to test the example code in Figure 26 on page 179.
/* this example illustrates the use of a KSDS file
/* part 2 of 2-other file is CCNGVS2
/*--------------------------------------------------------
/* Delete cluster, and AIX and PATH
/*--------------------------------------------------------
//DELETEC EXEC PGM=IDCAMS
//SYSPRINT DD SYSOUT=* 
//SYSIN DD *
DELETE -
  userid.KSDS.CLUSTER -
  CLUSTER -
  PURGE -
  ERASE

/*--------------------------------------------------------
/* Define KSDS
/*--------------------------------------------------------
//DEFINE EXEC PGM=IDCAMS
//VOLUME DD UNIT=SYSDA,DISP=SHR,VOL=SER=(XXXXXX)
//SYSPRINT DD SYSOUT=* 
//SYSIN DD *
DEFINE CLUSTER -
  (NAME(userid.KSDS.CLUSTER) -
   FILE(VOLUME) -
   VOL(XXXXXX) -
   TRK(4 4) -
   RECSZ(69 100) -
   INDEXED -
   NOREUSE -
   KEYS(4 0) -
   OWNER(userid) ) -
  DATA -
   (NAME(userid.KSDS.DA)) -
  INDEX -
   (NAME(userid.KSDS.IX))
/

KSDS example (Part 1 of 3)

Figure 27. KSDS example
// Repro data into KSDS
// REPRO EXEC PGM=IDCAMS
// SYSPRINT DD SYSOUT=* 
// SYsin DD *
// REPRO INDATASET(userid.DUMMY.DATA) -
// OUTDATASET(userid.KSDS.CLUSTER)
/*

// Define unique AIX, define and build PATH
// DEFINE AIX -
// (NAME(userid.KSDS.UAIX) -
// RECORDS(25) -
// KEYS(8,4) -
// VOL(XXXXXX) -
// UNIQUEKEY -
// RELATE(userid.KSDS.CLUSTER) -
// DATA -
// (NAME(userid.KSDS.UAIXDA)) -
// INDEX -
// (NAME(userid.KSDS.UAIXIX))
DEFINE PATH -
(NAME(userid.KSDS.UPATH) -
PATHENTRY(userid.KSDS.UAIX))
BLDINDEX -
(INDATASET(userid.KSDS.CLUSTER) -
OUTDATASET(userid.KSDS.UAIX)
/*

KSDS example (Part 2 of 3)
KSDS example (Part 3 of 3)

RRDS example

The sample program (CCNGVS4) in Figure 28 on page 187 illustrates the use of an RRDS file. It performs the following operations:

1. Opens an RRDS file in record mode (the cluster must be defined)
2. Writes three records (RRN 2, RRN 10, and RRN 32)
3. Sets the file position to the first record
4. Reads the first record in the file
5. Deletes it
6. Locates the last record in the file and sets the access direction to backwards
7. Reads the record
8. Updates the record
9. Sets the_EDC_RRDS_HIDE_KEY environment variable
10. Reads the next record in sequence (RRN 10) into a character string

```c
/* this example illustrates the use
of an RRDS file */
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <env.h>

struct rrds_struct {
  __rrds_key_type rrds_key;
  char *rrds_buf;
};

typedef struct rrds_struct RRDS_STRUCT;

main() {
  FILE *fileptr;
  RRDS_STRUCT RRDSstruct;
  RRDS_STRUCT *rrds_rec = &RRDSstruct;
  char buffer1[80] =
    "THIS IS THE FIRST RECORD IN THE FILE. I" 
    "T WILL BE WRITTEN AT RRN POSITION 2. ";
  char buffer2[80] =
    "THIS IS THE SECOND RECORD IN THE FILE. I" 
    "T WILL BE WRITTEN AT RRN POSITION 10. ";
  char buffer3[80] =
    "THIS IS THE THIRD RECORD IN THE FILE. I" 
    "T WILL BE WRITTEN AT RRN POSITION 32. ";
  char outputbuf[80];
  unsigned long flocate_key = 0;

  /*------------------------------------------------------------------*/
  /*
  | select RRDS record structure 2 by setting __fill to 1
  |*/
  /*------------------------------------------------------------------*/

  rrds_rec->rrds_key.__fill = 1;

  fileptr = fopen("DD:RRDSFILE", "wb+,type=record");
  if (fileptr == NULL) {
    perror("fopen");
    exit(99);
  }
  rrds_rec->rrds_key.__recnum = 2;
  rrds_rec->rrds_buf = buffer1;
  fwrite(rrds_rec,1,88, fileptr);

  rrds_rec->rrds_key.__recnum = 10;
  rrds_rec->rrds_buf = buffer2;
  fwrite(rrds_rec,1,88, fileptr);

  rrds_rec->rrds_key.__recnum = 32;
  rrds_rec->rrds_buf = buffer3;
  fwrite(rrds_rec,1,88, fileptr);

  /*-----------------------------*/
  /*| select RRDS record structure 2 by setting __fill to 1 */
  /*|*/
  /*------------------------------------------------------------------*/

  RRDS example (Part 1 of 2)

  Figure 28. RRDS example
```

Chapter 12. Performing VSAM I/O operations  187
/*-----------------------------*/
/*| 3. set file position to the first record */
/*| 4. read the first record in the file */
/*| 5. delete it */
/*-----------------------------*/

flocate(fileptr, &flocate_key; sizeof(unsigned long), __KEY_FIRST);
memset(outputbuf,0x00,80);
rrds_rec->rrds_buf = outputbuf;

fread(rrds_rec,1, 88, fileptr);
printf("The first record in the file (this will be deleted):
");
printf("RRN %d: %s

",rrds_rec->rrds_key.__recnum,outputbuf);
fdelrec(fileptr);

/*------------------------------*/
/*| 6. locate last record in file and set access direction backwards*/
/*| 7. read the record */
/*| 8. update the record */
/*------------------------------*/

flocate(fileptr, &flocate_key; sizeof(unsigned long), __KEY_LAST);
memset(outputbuf,0x00,80);
rrds_rec->rrds_buf = outputbuf;

fread(rrds_rec,1, 88, fileptr);
printf("The last record in the file (this one will be updated):
");
printf("RRN %d: %s

",rrds_rec->rrds_key.__recnum,outputbuf);

memset(outputbuf,0x00,80);
memcpy(outputbuf,"THIS IS THE UPDATED STRING... ",30);
fupdate(rrds_rec,88,fileptr);

/*-----------------------------*/
/*| 9. set \_EDC\_RRDS\_HIDE\_KEY environment variable */
/*|10. read the next record in sequence (ie. RRN 10) into a */
/*| + character string */
/*-----------------------------*/

setenv("\_EDC\_RRDS\_HIDE\_KEY","\"",1);
memset(outputbuf,0x00,80);
fclose(fileptr);
}

fclose(fileptr);

RRDS example (Part 2 of 2)

**fldata() behavior**

The format of the fldata() function is as follows:

```c
int fldata(FILE *file, char *filename, fldata_t *info);
```

The fldata() function is used to retrieve information about an open stream. The
name of the file is returned in *filename* and other information is returned in the
fldata_t structure, shown in Figure 29 on page 189. Values specific to this category
of I/O are shown in the comment beside the structure element. Other notes about
this category of I/O follow the figure. For more information on the fldata()
function, see z/OS XL C/C++ Runtime Library Reference.

Notes:

1. If you have opened the file by its data set name, the filename is fully qualified, including quotation marks. If you have opened the file by ddname, filename is dd:ddname, without any quotation marks. The ddname is uppercase.
2. The _dsname field is filled in with the data set name. The _dsname value is uppercase unless the asis option was specified on the fopen() or freopen() function call.
Chapter 13. Performing terminal I/O operations

This chapter describes how to use input and output interactively with a terminal (using TSO or z/OS UNIX). Terminal I/O supports text, binary, and record I/O, in undefined, variable and fixed-length formats, except that ASA format is not valid for any text terminal files.

Note: You cannot use the z/OS XL C/C++ I/O functions for terminal I/O under either IMS or CICS. Terminal I/O under CICS is supported through the CICS command level interface.

This chapter describes C I/O stream functions as they can be used within C++ programs. If you want to use the C++ I/O stream classes instead, see Chapter 4, "Using the Standard C++ Library I/O Stream Classes," on page 23 for general information. For more detailed information, see Standard C++ Library Reference, which discusses the Standard C++ I/O stream classes.

Opening files

You can use the library functions fopen() or freopen() to open a file.

Using fopen() and freopen()

This section covers:
- Opening a file by data set name
- Opening a file by DD name
- fopen() and freopen() keywords
- Opening a terminal file under a shell

Opening a file by data set name

Files are opened with a call to fopen() or freopen() in the format
fopen("filename", "mode"). The first character of the filename must be an asterisk (*).

z/OS UNIX Considerations: If you have specified POSIX(ON),
fopen("*file.data","r"); does not open a terminal file. Instead, it opens a file called *file.data in the UNIX file system. To open a terminal file under POSIX, you must specify two slashes before the asterisk, as follows:
fopen("//*file.data","r"): Terminal files cannot be opened in update mode.

Terminal files opened in append mode are treated as if they were opened in write mode.

Opening a file by DD name

The data set name that is associated with the DD statement must be an asterisk(*).
For example:
TSO ALLOC f(ddname) DA(*)
fopen("dd:ddname", "mode");
fopen() and freopen() keywords

The following table lists the keywords that are available on the fopen() and freopen() functions, tells you which ones are useful for terminal I/O, and lists the values that are valid for the applicable ones.

Table 32. Keywords for the fopen() and freopen() functions for terminal I/O

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>recfm=</td>
<td>Yes</td>
<td>Yes</td>
<td>F, V, U and additional keywords A, B, S, M are the valid values. A, B, S, and M are ignored.</td>
</tr>
<tr>
<td>lrecl=</td>
<td>Yes</td>
<td>Yes</td>
<td>See below.</td>
</tr>
<tr>
<td>blksize=</td>
<td>Yes</td>
<td>Yes</td>
<td>See below.</td>
</tr>
<tr>
<td>space=</td>
<td>Yes</td>
<td>No</td>
<td>Has no effect for terminal I/O.</td>
</tr>
<tr>
<td>type=</td>
<td>Yes</td>
<td>Yes</td>
<td>May be omitted. If you do specify it, type=record is the only valid value.</td>
</tr>
<tr>
<td>acc=</td>
<td>No</td>
<td>No</td>
<td>Not used for terminal I/O.</td>
</tr>
<tr>
<td>password=</td>
<td>No</td>
<td>No</td>
<td>Not used for terminal I/O.</td>
</tr>
<tr>
<td>asis</td>
<td>Yes</td>
<td>No</td>
<td>Has no effect for terminal I/O.</td>
</tr>
<tr>
<td>byteseek</td>
<td>Yes</td>
<td>No</td>
<td>Has no effect for terminal I/O.</td>
</tr>
<tr>
<td>noseek</td>
<td>Yes</td>
<td>No</td>
<td>Has no effect for terminal I/O.</td>
</tr>
<tr>
<td>OS</td>
<td>Yes</td>
<td>No</td>
<td>Not used for terminal I/O.</td>
</tr>
</tbody>
</table>

recfm=

z/OS XL C/C++ allows you to specify any of the 27 possible RECFM types (listed in “Fixed-format records” on page 12, “Variable-format records” on page 16, and “Undefined-format records” on page 19). The default is recfm=U. Any specification of ASA for the record format is ignored.

lrecl= and blksize=

The lrecl and blksize parameters allow you to set the record size and block size, respectively. The maximum limits on lrecl values are as follows:

- 32771 For input z/OS variable terminals (data length of 32767)
- 32767 For input z/OS fixed and undefined terminals
- 32770 For output z/OS variable terminals (data length of 32766)
- 32766 For output z/OS fixed and undefined terminals

In fixed and undefined terminal files, blksize is always the size of lrecl. In variable terminal files, blksize is always the size of lrecl plus 4 bytes. It is not necessary to specify values for lrecl and blksize. If neither is specified, the default values are used. The default lrecl sizes (not including the extra 4 bytes in the lrecl of variable length types) are as follows:

- Screen width for output terminals
- 1000 for input z/OS text terminals
- 254 for all other input terminals

space=

This parameter is accepted as an option for terminal I/O, but it is ignored. It does not generate an error.

type=

type=record specifies that the file is to be opened for sequential record I/O. The file must be opened as a binary file.
acc
This parameter is not valid for terminal I/O. If you specify it, your fopen() call fails.

password
This parameter is not valid for terminal I/O. If you specify it, your fopen() call fails.

asis
This parameter is accepted as an option for terminal I/O, but it is ignored. It does not generate an error.

byte.seek
This parameter is accepted as an option for terminal I/O, but it is ignored. It does not generate an error.

noseek
This parameter is accepted as an option for terminal I/O, but it is ignored. It does not generate an error.

OS
This parameter is not valid for terminal I/O. If you specify it, your fopen() call fails.

When you perform input and output in an interactive mode with the terminal, all standard streams and all files with * as the first character of their names are associated with the terminal. Output goes to the screen; input comes from the keyboard.

An input E0F can be generated by a /* if you open a stream in text mode. If you open the stream in binary or record mode, you can generate an E0F by entering a null string.

ASA characters are not interpreted in terminal I/O.

Opening a terminal file under a shell
Files are opened with a call to fopen() in the format fopen("/dev/tty", "mode").

Buffering
z/OS XL C/C++ uses buffers to map byte-level I/O (data stored in records and blocks) to system-level C I/O.

In terminal I/O, line buffering is always in effect.

The setvbuf() and setbuf() functions can be used to control buffering before any read or write operation to the file. If you want to reset the buffering mode, you must call setvbuf() or setbuf() before any other operation occurs on a file, because you cannot change the buffering mode after an I/O operation to the file.

Reading from files
You can use the following library functions to read in information from terminal files; see z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

• fread()
• fread_unlocked()
• fgets()
You can set up a 
SIGIOERR
handler to catch read or write system errors. See 
Chapter 18, “Debugging I/O programs,” on page 223
for more information.

A call to the 
rewind()
function clears unread input data in the terminal buffer so that on the next read request, the system waits for more user input.

With z/OS Language Environment, an empty record is considered EOF in binary mode or record mode. This remains in effect until a rewind() or clearerr() is issued. When the rewind() is issued, the buffer is cleared and reading can continue.

Under TSO, the virtual line size of the terminal is used to determine the line length.

When reading from the terminal and the RECFM has been set to be F (for example, by an ALLOCATE under TSO) in binary or record mode, the input is padded with blanks to the record length.

On input, all terminal files opened for output flush their output, no matter what type of file they are and whether a record is complete or not. This includes fixed terminal files that would normally withhold output until a record is completed, as well as text records that normally wait until a new-line or carriage return. In all cases, the data is placed into one line with a blank added to separate output from different terminal files. Fixed terminal files do not pad the output with blanks when flushing this way.

Note: This flush is not the same as a call to fflush(), because fixed terminal files do not have incomplete records and text terminal files do not output until the new-line or carriage return. This flush occurs only when actual input is required from the terminal. When data is still in the buffer, that data is read without flushing output terminal files.
Reading from binary files
This discussion includes reading from fixed binary files and from variable or undefined binary files.

Reading from fixed binary files
- Any input that is smaller than the record length is padded with blanks to the record length. The default record length is 254 bytes.
- The carriage return or new-line is not included as part of the data.
- An input line longer than the record length is returned to the calling program on subsequent system reads.
  For example, suppose a program requests 30 bytes of user input from an input fixed binary terminal with record length 25. The full 30 bytes of user input returns to satisfy the request, so that you do not need to enter a second line of input.
- An empty input line indicates EOF.

Reading from variable or undefined binary files
These files behave like fixed-length binary files, except that no padding is performed if the input is smaller than the record length.

Reading from text files
This discussion includes reading from fixed text files and from variable or undefined text files.

Reading from fixed text files
- The carriage return indicates the end of the record.
- A new-line character is added as part of the data to indicate the end of an input line.
- If the input is larger than the record length, it is truncated to the record length. The truncation causes SIGIOERR to be raised, if the default action for SIGIOERR is not SIG_IGN.
- When an input line is smaller than the record length, it is not padded with blanks.
- The character sequence /* indicates that the end of the file has been reached.

Reading from variable or undefined text files
These files behave like fixed-length text files.

Reading from record I/O files
This discussion includes reading from fixed record I/O files and from variable or undefined record I/O files.

Reading from fixed record I/O files
- Records smaller than the record length are padded with blanks up to the record length. The default record length is 254 bytes.
- Input record terminal records have an implicit logical record boundary at the record length if the input size exceeds the record length.
  If you enter input data larger than the record length, each subsequent block of record-length bytes from the user input satisfies successive read requests.
- The carriage return or new-line is not included as part of the data.
- An empty line indicates an EOF.
Reading from variable or undefined record I/O files

These files behave like fixed-length record files, except that no padding is performed.

Writing to files

You can use the following library functions to write to a terminal file; see z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

- fwrite()
- fwrite_unlocked()
- printf()
- printf_unlocked()
- fprintf()
- fprintf_unlocked()
- vprintf()
- vprintf_unlocked()
- vfprintf()
- vfprintf_unlocked()
- puts()
- puts_unlocked()
- fputs()
- fputs_unlocked()
- fputc()
- fputc_unlocked()
- putchar()
- putchar_unlocked()

If no record length is specified for the output terminal file, it defaults to the virtual line size of the terminal.

On output, records are written one line at a time up to the record length. For all output terminal files, records are not truncated. If you are printing a long string, it wraps around to another line.

Writing to binary files

This discussion includes writing to fixed binary files and to variable or undefined binary files.

Writing to fixed binary files

- Output data is sent to the terminal when the last character of a record is written.
- When closing an output terminal, any unwritten data is padded to the record length with blanks before it is flushed.

Writing to variable or undefined binary files

These files behave the same as fixed-length binary files, except that no padding occurs for output that is smaller than the record length.
Writing to text files

The following control characters are supported:

\a  Alarm. Causes the terminal to generate an audible beep.
\b  Backspace. Backs up the output position by one byte. If you are at the start of the record, you cannot back up to previous record, and backspace is ignored.
\f  Form feed. Sends any unwritten data to the terminal and clears the screen if the environment variable _EDC_CLEAR_SCREEN is set. If the variable is not set, the \f character is written to the screen.
\n  New-line. Sends the preceding unwritten character to the terminal. If no preceding data exists, it sends a single blank character.
\t  Horizontal tab. Pads the output record with blanks up to the next tab stop (set at eight characters).
\v  Vertical tab. Placed in the output as is.
\r  Carriage return. Treated as a new-line, sends preceding unwritten data to the terminal.

Writing to fixed text files

- Lines that are longer than the record length are not truncated. They are split across multiple lines, each LRECL bytes long. Subsequent writes begin on a new line.
- Output data is sent to the terminal when one character more than the record length is written, or when a \r, \n, or \f character is written. In the case of \f, output is displayed only if the _EDC_CLEAR_SCREEN environment variable is set.
- No padding occurs on output when a record is smaller than the record length.

Writing to variable or undefined text files

These terminal files behave like fixed-length terminal files.

Writing to record I/O files

This discussion includes writing to fixed record I/O files and to variable or undefined record I/O files.

Writing to fixed record I/O files

- Any output record that is smaller than the record length is padded to the record length with blanks, and trailing blanks are displayed.
- If a record is longer than the record length, all data is written to the terminal, wrapping at the record length.
- Output data is sent to the terminal with every record write.

Writing to variable or undefined record I/O files

These files behave like fixed-length record files except that no padding occurs when the output record is smaller than the record length.

Flushing records

The action taken by the fflush() library function depends on the file mode. The fflush() function only flushes buffers in binary files with Variable or Undefined record format.
If you call one z/OS XL C/C++ program from another z/OS XL C/C++ program by using the ANSI system() function, all open streams are flushed before control is passed to the callee, and again before control is returned to the caller. If you are running with POSIX(ON), a call to the POSIX system() function does not flush any streams to the system.

**Text streams**

- Writing a new record:
  Because a new-line character has not been encountered to indicate the end-of-line, fflush() takes no action. The record is written as a new record when one of the following takes place:
  - A new-line character is written.
  - The file is closed.
- Reading a record:
  fflush() clears a previous ungetc() character.

**Binary streams**

- Writing a new record:
  If the file is variable or undefined length in record format, fflush() causes the current record to be written out, which in turn causes a new record to be created for subsequent writes. If the file is of fixed record length, no action is taken.
- Reading a record:
  fflush() clears a previous ungetc() character.

**Record I/O**

- Writing a new record: fflush() takes no action.
- Reading a record: fflush() takes no action.

---

**Repositioning within files**

In terminal I/O, rewind() is the only positioning library function available. Using the library functions fseek(), fgetpos(), fsetpos(), and ftell() generates an error. See z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

When an input terminal reaches an EOF, the rewind() function:
1. Clears the EOF condition.
2. Enables the terminal to read again.

You can also use rewind() when reading from the terminal to flush out your record buffer for that stream.

**Closing files**

Use the fclose() library function to close a file. z/OS XL C/C++ automatically closes files on normal program termination and attempts to do so under abnormal program termination or abend. When closing a fixed binary terminal, z/OS XL C/C++ pads the last record with blanks if it is incomplete.

See z/OS XL C/C++ Runtime Library Reference for more information on this library function.
fldata() behavior

The format of the fldata() function is as follows:
The fldata() function is used to retrieve information about an open stream. The
name of the file is returned in filename and other information is returned in the
fldata_t structure, shown in Figure 30. Values specific to this category of I/O are
shown in the comment beside the structure element. Additional notes pertaining to
this category of I/O follow the figure.

For more information on the fldata() function, refer to z/OS XL C/C++ Runtime
Library Reference.

```
int fldata(FILE *file, char *filename, fldata_t *info);
```

Notes:
1. The filename value is dd:ddname if the file is opened by ddname; otherwise, the
   value is *. The ddname is uppercase.
2. Either __recfmF, __recfmV, or __recfmU will be set according to the recfm
   parameter specified on the fopen() or freopen() function call.

```c
struct __fileData {
    unsigned int __recfmF : 1, /* */
    __recfmV : 1, /* */
    __recfmM : 1, /* */
    __recfmS : 1, /* always off */
    __recfmBlk : 1, /* always off */
    __recfM : 1, /* always off */
    __dsorgPD : 1, /* N/A -- always off */
    __dsorgPDsm : 1, /* N/A -- always off */
    __dsorgPDdir : 1, /* N/A -- always off */
    __dsorgPS : 1, /* N/A -- always off */
    __dsorgConca : 1, /* N/A -- always off */
    __dsorgMem : 1, /* N/A -- always off */
    __dsorgHiper : 1, /* N/A -- always off */
    __dsorgTemp : 1, /* N/A -- always off */
    __dsorgVSSM : 1, /* N/A -- always off */
    __dsorgVSAM : 1, /* N/A -- always off */
    __openmode : 2, /* one of: */
    /* __TEXT */
    /* __BINARY */
    /* __RECORD */
    __modeflag : 4, /* combination of: */
    /* __READ */
    /* __WRITE */
    /* __APPEND */
    __dsorgPSE : 1, /* N/A -- always off */
    __reserve2 : 8; /* */
    __device_t __device; /* __TERMINAL */
    unsigned long __blksize, /* */
    __maxreclen; /* */
    unsigned short __vsamtype; /* N/A */
    __vsamkeylen; /* */
    unsigned long __vsamRKP; /* N/A */
    char * __dsname; /* N/A -- always NULL */
    unsigned int __reserve4; /* */
};
typedef struct __fileData fldata_t;
```

Figure 30. fldata() structure
Chapter 14. Performing memory file and hiperspace I/O operations

This chapter describes how to perform memory file and hiperspace I/O operations. z/OS XL C/C++ supports files known as memory files. Memory files are temporary work files that are stored in main memory rather than in external storage. There are two types of memory files:

- Regular memory files, which exist in your virtual storage
- Hiperspace memory files, which use special storage areas called hiperspaces.

Memory files can be written to, read from, and repositioned within like any other type of file. Memory files exist for the life of your root program, unless you explicitly delete them by using the remove() or clrmemf() functions. The root program is the first main() to be invoked. Any main() program called by a system() call is known as a child program. When the root program terminates, z/OS XL C/C++ removes memory files automatically. Memory files may give you better performance than other types of files.

Note: There may not be a one-to-one correspondence between the bytes in a memory file and the bytes in some other external representation of the file, such as a disk file. Applications that mix open modes on a file (for example, writing a file as text file and reading it back as binary) may not port readily from external I/O to memory file I/O.

This chapter describes C I/O streams as they can be used within C++ programs. If you want to use the C++ I/O stream classes instead, see Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23 for general information. For more detailed information, see Standard C++ Library Reference, which discusses the Standard C++ I/O stream classes.

Using hiperspace operations

Restriction: Hiperspace memory files are not supported in AMODE 64 applications. Attempts to open a memory file with type=memory(hiperspace) will be converted to a regular memory file.

On z/OS systems, large memory files can be placed in hiperspaces to reduce memory requirements within your address space.

If your installation supports hiperspaces, and you are not using CICS, you can use hiperspace memory files (see the appropriate book as listed in z/OS V2R2 Information Roadmap for more information on hiperspaces). Whereas a regular memory file stores all the file data in your address space, a hiperspace memory file uses one buffer in your address space, and keeps the rest of the data in the hiperspace. Therefore, a hiperspace memory file requires only a certain amount of storage in your address space, regardless of how large the file is. If you use setvbuf(), z/OS XL C/C++ may or may not accept your buffer for its internal use. For a hiperspace memory file, if the size of the buffer specified to setvbuf() is greater than 4K, then only the first 4K of the user buffer will be used.
Hiperspace memory files may not be shared by multiple threads. A hiperspace memory file that is created on one thread can only be read/written/closed by the same thread.

## Opening files

Use the Standard C `fopen()` or `freopen()` library functions to open a memory file. Details about these functions that apply to all z/OS XL C/C++ I/O operations are discussed in Chapter 5, “Opening files,” on page 27.

### Using fopen() or freopen()

This section describes considerations for using `fopen()` and `freopen()` with memory files. Memory files are always treated as binary streams of bytes, regardless of the parameters you specify on the function call that opens them.

### File-naming considerations

When you open a file using `fopen()` or `freopen()`, you must specify the filename (a data set name) or the ddname.

**Using a data set name:** Files are opened with a call to `fopen()` or `freopen()` in the format `fopen("filename", "mode")`. The following diagram shows the syntax for the `filename` argument on your `fopen()` or `freopen()` call:

![Diagram showing syntax for `filename` argument]

The following is a sample construct:

```
'qualifier1.qualifier2(member)'
```

// Ignored for memory files.

**qualifier**

There is no restriction on the length of each qualifier. All characters are considered valid. The total number of characters for all of the qualifiers, including periods and a TSO prefix, cannot exceed 44 characters when running POSIX(OFF). Under POSIX(ON), the TSO prefix is not added, and the total number of characters is not limited, except that the full file name, including the member, cannot exceed the limit for a POSIX pathname, currently 1024 characters.

**(member)**

If you specify a `member`, the data set you are opening is considered to be a simulated PDS or a PDSE. For more information about PDSs and PDSEs, see “Simulating partitioned data sets” on page 206. For members, the member name (including trailing blanks) can be up to 8 characters long. A member name cannot begin with leading blanks.

When you enclose a name in single quotation marks, the name is **fully qualified**. The file opened is the one specified by the name inside the quotation marks. If the name is not fully qualified, z/OS XL C/C++ does one of the following:
• If your system does not use RACF, z/OS XL C/C++ does not add a high-level qualifier to the name you specified.

• If you are running under TSO (batch or interactive), z/OS XL C/C++ appends the TSO user prefix to the front of the name. For example, the statement `fopen("a.b", "w")` opens a data set `tsopref.A.B`, where `tsopref` is the user prefix. You can set the user prefix by using the TSO PROFILE command with the PREFIX parameter.

Note: The TSO prefix is not added when running POSIX(ON).

• If you are running under MVS batch or IMS (batch or online), z/OS XL C/C++ appends the RACF user ID to the front of the name.

Using a DDname: You can specify names that begin with `dd:`, but z/OS XL C/C++ treats the `dd:` as part of the file name.

z/OS UNIX Considerations: Using the `fork()` library function from z/OS UNIX application programs causes the memory file to be copied into the child process. The memory file data in the child is identical to that of the parent at the time of the `fork()`. The memory file can be used in either the child or the parent, but the data is not visible in the other process.

**fopen() and freopen() keywords**

Table 33 lists the keywords that are available on the `fopen()` and `freopen()` functions, tells you which ones are useful for memory file I/O, and lists the values that are valid for the applicable ones.

**Table 33. Keywords for the fopen() and freopen() functions for memory file I/O**

<table>
<thead>
<tr>
<th>Keyword</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>recfm=</td>
<td>Yes</td>
<td>No</td>
<td>This parameter is ignored for memory file and hiperspace I/O. If you specify a RECFM, it must have correct syntax. Otherwise the <code>fopen()</code> call fails.</td>
</tr>
<tr>
<td>lrecl=</td>
<td>Yes</td>
<td>No</td>
<td>This parameter is ignored for memory file and hiperspace I/O. If you specify an LRECL, it must have correct syntax. Otherwise <code>fopen()</code> call fails.</td>
</tr>
<tr>
<td>blksize=</td>
<td>Yes</td>
<td>No</td>
<td>This parameter is ignored for memory file and hiperspace I/O. If you specify a BLKSIZE, it must have correct syntax. Otherwise <code>fopen()</code> call fails.</td>
</tr>
<tr>
<td>acc=</td>
<td>Yes</td>
<td>No</td>
<td>This parameter is ignored for memory file and hiperspace I/O. If you specify an ACC, it must have correct syntax. Otherwise <code>fopen()</code> call fails.</td>
</tr>
<tr>
<td>password=</td>
<td>No</td>
<td>No</td>
<td>Ignored for memory files.</td>
</tr>
<tr>
<td>space=</td>
<td>Yes</td>
<td>No</td>
<td>This parameter is ignored for memory file and hiperspace I/O. If you specify a SPACE, it must have correct syntax. Otherwise, <code>fopen()</code> call fails.</td>
</tr>
<tr>
<td>type=</td>
<td>Yes</td>
<td>Yes</td>
<td>Valid values are memory and memory(hiperspace). See the parameter list below.</td>
</tr>
<tr>
<td>asis</td>
<td>Yes</td>
<td>Yes</td>
<td>Enables the use of mixed-case file names.</td>
</tr>
</tbody>
</table>
Table 33. Keywords for the fopen() and freopen() functions for memory file I/O (continued)

<table>
<thead>
<tr>
<th>Keyword</th>
<th>Allowed?</th>
<th>Applicable?</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>byteseek</td>
<td>Yes</td>
<td>No</td>
<td>Ignored for memory files, as they use byteseeking by default.</td>
</tr>
<tr>
<td>noseek</td>
<td>Yes</td>
<td>No</td>
<td>This parameter is ignored for memory file and hiperspace I/O.</td>
</tr>
<tr>
<td>OS</td>
<td>No</td>
<td>No</td>
<td>This parameter is not valid for memory file and hiperspace I/O. If you specify OS, your fopen() call fails.</td>
</tr>
</tbody>
</table>

`recfm=`

z/OS XL C/C++ parses your specification for these values. If they do not have the correct syntax, your function call fails. If they do, z/OS XL C/C++ ignores their values and continues.

`lrecl=` and `blksize=`

z/OS XL C/C++ parses your specification for these values. If they do not have the correct syntax, your function call fails. If they do, z/OS XL C/C++ ignores their values and continues.

`acc=`

z/OS XL C/C++ parses your specification for these values. If they do not have the correct syntax, your function call fails. If they do, z/OS XL C/C++ ignores their values and continues.

`password=`

This parameter is not valid for memory file and hiperspace I/O. If you specify PASSWORD, your fopen() call fails.

`space=`

z/OS XL C/C++ parses your specification for these values. If they do not have the correct syntax, your function call fails. If they do, z/OS XL C/C++ ignores their values and continues.

`type=`

To create a memory file, you must specify type=memory. You cannot specify type=record or type=blocked; if you do, fopen() or freopen() fails. To create a hiperspace memory file, you must specify type=memory(hiperspace).

`asis`

If you use this parameter, you can specify mixed-case filenames, such as JaMeS dAtA or pErCy.FILE. If you are running with POSIX(0N), asis is the default.

`byteseek`

This parameter is ignored for memory file and hiperspace I/O.

`noseek`

This parameter is ignored for memory file and hiperspace I/O.

`OS`

This parameter is not allowed for memory file and hiperspace I/O. If you specify OS, your fopen() call fails.

Once a memory file has been created, it can be accessed by the module that created it as well as by any function or module that is subsequently invoked (including modules that are called using the system() library function), and by any modules in the current chain of system() calls, if you are running with POSIX(0FF). If you are running with POSIX(0N), the system() function is the POSIX one, not the ANSI one, and it does not propagate memory files to a child program. Once the
file has been created, you can open it with the same name, without specifying the type=memory parameter. You cannot specify type=record or type=blocked for a memory file.

This is how z/OS XL C/C++ searches for memory files:
1. `fopen("my.file","w.....,type=memory");` z/OS XL C/C++ checks the open files to see if a file with that name is already open. If not, it creates a memory file.
2. `fopen("my.file","w.......");` z/OS XL C/C++ checks the open files to see if a file with that name is already open. If not, it then checks to see whether a memory file exists with that name. If so, it opens the memory file; if not, it creates a disk file.
3. `fopen("my.file","a......,type=memory");` z/OS XL C/C++ checks the open files to see if a file with that name is already open. If not, it searches the existing memory files to see whether a memory file exists with that name. If so, z/OS XL C/C++ opens it; if not, it creates a new memory file.
4. `fopen("my.file","a....");` z/OS XL C/C++ checks the open files to see if a file with that name is already open. If not, z/OS XL C/C++ searches existing files (both disk and memory) according to file mode, and opens the first file that has that name. If there is no such file, z/OS XL C/C++ creates a disk file.
5. `fopen("my.file","r.....,type=memory");` z/OS XL C/C++ searches the memory files to see if a file with that name exists. If one does, z/OS XL C/C++ opens it. Otherwise, the fopen() call fails.
6. `fopen("my.file","r....");` z/OS XL C/C++ searches first through memory files. If it does not find the specified one, it then tries to open a disk file.

If you specify a memory file name that has an asterisk (*) as the first character, a name is created for that file. (You can acquire this name by using fldata().) For example, you can specify `fopen("*","type=memory");`. Opening a memory file this way is faster than using the tmpnam() function.

z/OS UNIX System Services Considerations: If you have specified POSIX(ON), `fopen("*file.data","w,type=memory")` does not generate a name for the memory file. Instead, it opens a memory file called *file.data. To generate a memory file name when POSIX(ON) has been specified, you must use two slashes before the asterisk, shown as follows:

`fopen("//*file.data","w,type=memory")`

You cannot have any blanks or periods in the member name of a memory file. Otherwise, all valid data set names are accepted for memory files. Note that if invalid disk file names are used for memory files, difficulties could occur when you try to port memory file applications to disk-file applications.

Memory files are always opened in fixed binary mode regardless of the open mode. There is no blank padding, and control characters such as the new line are written directly into the file (even if the fopen() specifies text mode).

Opening hiperspace files
To create a memory file in hiperspace, specify type=memory(hiperspace) on the fopen() call that creates the file. If hiperspace is not available, you get a regular memory file. Under systems that do not support hiperspaces, as well as when you are running with POSIX(ON) and TRAP(0FF), a specification of type=memory(hiperspace) is treated as type=memory. Use of TRAP(0FF) is not recommended.
You must decide whether a file is to be a hiperspace memory file before you create it. You cannot change a memory file to a hiperspace memory file by specifying type=memory(hiperspace) on a subsequent call to fopen() or freopen(). If the hiperspace to store the file cannot be created, the fopen() or freopen() call fails.

Once you have created a hiperspace memory file, you do not have to specify type=memory(hiperspace) on subsequent function calls that open the file.

If you open a hiperspace memory file for read at the same time that it is opened for write, you can attempt to read extensions made by the writer, even after the EOF flag has been set on by a previous read. If such a read succeeds, the EOF flag is set off until the new EOF is reached. If you have opened a file once for write and one or more times for read, a reader can now read past the original EOF.

Simulating partitioned data sets

You can create memory files that are conceptually grouped as a partitioned data set (PDS). Grouping the files in this way offers the following advantages:

- You can remove all the members of a PDS by stating the data set name.
- You can rename the qualifiers of a PDS without renaming each member individually.

When you establish that a memory file has members, you can rename and remove all the members by specifying the file name and no members, just as with a PDS or PDSE. None of the members can be open for you to perform this action. Once a memory file is created with or without a member, another memory file with the same name (with or without a member) cannot be created as well. For example, if you open memory file a.b and write to it, z/OS XL C/C++ does not allow a memory file named a.b(c) until you close and remove a.b. Also, if you create a memory file named a.b(mbr1), you cannot open a file named a.b until you close and remove a.b(mbr1).

Sample program CCNGMF1 [Figure 31 on page 207] demonstrates the removal of all the members of the data set a.b. After the call to remove(), neither a.b(mbr1) nor a.b(mbr2) exists.
Sample program CCNGMF2 (Figure 32 on page 208) demonstrates the renaming of a PDS from a.b to c.d.

```c
/* this example shows how to remove members of a PDS */
#include <stdio.h>

int main(void)
{
    FILE * fp1, * fp2;
    fp1=fopen("a.b(mbr1)","w,type=memory");
    fp2=fopen("a.b(mbr2)","w,type=memory");
    fwrite("hello, world\n", 1, 13, fp1);
    fwrite("hello, world\n", 1, 13, fp2);
    fclose(fp1);
    fclose(fp2);
    remove("a.b");
    fp1=fopen("a.b(mbr1)","r,type=memory");
    if (fp1 == NULL) {
        perror("fopen()");
        printf("fopen("a.b(mbr1)"...) failed as expected: "
               "the file has been removed\n");
    } else {
        printf("fopen() should have failed\n");
    }

    return(0);
}
```

**Figure 31. Removing members of a PDS**

Sample program CCNGMF2 (Figure 32 on page 208) demonstrates the renaming of a PDS from a.b to c.d.
Note: If you are using simulated PDSs, you can change either the name of the
PDS, or the member name. You cannot rename a.b(mbr1) to either c.d(mbr2) or
c.d, but you can rename a.b(mbr1) to a.b(mbr2), and a.b to c.d.

Memory files that are open as a sequential data set cannot be opened again with a
member name specified. Also, if a data set is already open with a member name,
the sequential data set version with only the data set name cannot be opened.
These operations result in fopen() returning NULL. For example, fopen() returns
NULL in the second line of the following:

```c
fp = fopen("a.b","w,type=memory");
fp1 = fopen("a.b(m1)","w,type=memory");
```

You cannot use the rename() or remove() functions on open files.

### Buffering

Regular memory files are not buffered. Any parameters passed to setvbuf() are
ignored. Each character that you write is written directly to the memory file.

Hiperspace memory files are fully buffered. The size of the I/O buffer in your own
address space is 4KB.

If you call setvbuf() for a hiperspace memory file:
If the size value is greater than or equal to 4K, it will be set to 4K, and this buffer size will be used. Otherwise, the size value is ignored, and z/OS XL C/C++ will allocate a buffer.

If a pointer to a buffer is passed, the buffer must be aligned on a 4K boundary. Otherwise, z/OS XL C/C++ will allocate a buffer.

### Reading from files

You can use the following library functions to read information from memory files; see z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

- `fread()`
- `fread_unlocked()`
- `fgets()`
- `fgets_unlocked()`
- `gets()`
- `gets_unlocked()`
- `fgetc()`
- `fgetc_unlocked()`
- `fgetc_unlocked()`
- `getc()`
- `getc_unlocked()`
- `getchar()`
- `getchar_unlocked()`
- `scanf()`
- `scanf_unlocked()`
- `fscanf()`
- `fscanf_unlocked()`
- `vscanf()`
- `vscanf_unlocked()`
- `vfscanf()`
- `vfscanf_unlocked()`

The `gets()`, `getchar()`, `scanf()`, and `vscanf()` functions read from `stdin`, which can be redirected to a memory or hiperspace memory file.

You can open an existing file for read one or more times, even if it is already open for write. You cannot open a file for write if it is already open (for either read or write). If you want to update or truncate a file or append to a file that is already open for reading, you must first close all the other streams that refer to that file.

For memory files, a read operation directly after a write operation without an intervening call to `fflush()`, `fsetpos()`, `fseek()`, or `rewind()` fails. z/OS XL C/C++ treats the following as read operations:

- Calls to read functions that request 0 bytes
- Read requests that fail because of a system error
- Calls to the `ungetc()` function

You can set up a `SIGIOERR` handler to catch read or write system errors that happen when you are using hiperspace memory files. See Chapter 18, “Debugging I/O programs,” on page 223 for more information.
Writing to files

You can use the following library functions to write to a file. See z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

- fwrite()
- fwrite_unlocked()
- printf()
- printf_unlocked()
- fprintf()
- fprintf_unlocked()
- vprintf()
- vprintf_unlocked()
- vfprintf()
- vfprintf_unlocked()
- puts()
- puts_unlocked()
- fputs()
- fputs_unlocked()
- fputc()
- fputc_unlocked()
- putchar()
- putchar_unlocked()

The printf(), puts(), putchar(), and vprintf() functions write to stdout, which can be redirected to a memory or hiperspace memory file.

In hiperspace memory files, each library function causes your data to be moved into the buffer in your address space. The buffer is written to hiperspace each time it is filled, or each time you call the fflush() library function.

z/OS XL C/C++ counts a call to a write function writing 0 bytes or a write request that fails because of a system error as a write operation. For regular memory files, the only possible system error that can occur is an error in acquiring storage.

Flush records

fflush() does not move data from an internal buffer to a memory file, because the data is written to the memory file as it is generated. However, fflush() does make the data visible to readers who have a regular or hiperspace memory file open for reading while a user has it open for writing.

Hiperspace memory files are fully buffered. The fflush() function writes data from the internal buffer to the hiperspace.

Any repositioning operation writes data to the hiperspace.

The fclose() function also invokes fflush() when it detects an incomplete buffer for a file that is open for writing or appending.
ungetc() considerations

ungetc() pushes characters back onto the input stream for memory files. ungetc() handles only single-byte characters. You can use it to push back as many as four characters onto the ungetc() buffer. For every character pushed back with ungetc(), fflush() backs up the file position by one character and clears all the pushed-back characters from the stream. Backing up the file position may end up going across a record boundary.

If you want fflush() to ignore ungetc() characters, you can set the _EDC_COMPAT environment variable. See Chapter 32, “Using environment variables,” on page 467 for more information.

Repositioning within files

You can use the following library functions to help you position within a memory or hiperspace memory file. See z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

- fgetpos()
- fgetpos_unlocked()
- fsetpos()
- fsetpos_unlocked()
- fseek()
- fseek_unlocked()
- ftell()
- ftell_unlocked()
- rewind()
- rewind_unlocked()

Using fseek() to seek past the end of a memory file extends the file using null characters. This may cause z/OS XL C/C++ to attempt to allocate more storage than is available as it tries to extend the memory file.

When you use the fseek() function with memory files, it supports byte offsets from SEEK_SET, SEEK_CUR, and SEEK_END.

All file positions from ftell() are relative byte offsets from the beginning of the file. fseek() supports these values as offsets from SEEK_SET.

fgetpos(), fseek(), and ftell() handle ungetc() characters unless you have set the _EDC_COMPAT environment variable, in which case fgetpos() and fseek() do not. See Chapter 32, “Using environment variables,” on page 467 for more information about _EDC_COMPAT. If in handling these characters, if the current position goes beyond the start of the file, fgetpos() returns the EOF value, and ftell() returns -1.

fgetpos() values generated by code from previous releases of the z/OS XL C/C++ compiler are not supported by fsetpos().
Closing files

Use the fclose() library function to close a regular or hiperspace memory file. See z/OS XL C/C++ Runtime Library Reference for more information on this library function. z/OS XL C/C++ automatically closes memory files at the termination of the C root main environment.

Performance tips

You should use hiperspace memory files instead of regular memory files when they will be large (1MB or greater).

Regular memory files perform more efficiently if large amounts of data (10K or more) are written in one request (that is, if you pass 10K or more of data to the fwrite() function). You should use fopen("*", "type=memory") both to generate a name for a memory file and to open the file instead of calling fopen() with a name returned by tmpnam(). You can acquire the file's generated name by using fldata().

Removing memory files

The memory file remains accessible until the file is removed by the remove() or clrmemf() library functions or until the root program has terminated. You cannot remove an open memory file, except when you use clrmemf(). See z/OS XL C/C++ Runtime Library Reference for more information on these library functions.

fldata() behavior

The fldata() function is used to retrieve information about an open stream; it has the following format:

```
int fldata(FILE *file, char *filename, fldata_t *info);
```

The name of the file is returned in filename and other information is returned in the fldata_t structure, shown in Figure 33 on page 213. Values specific to this category of I/O are shown in the comment beside the structure element. Additional notes pertaining to this category of I/O follow. For more information on the fldata() function, refer to z/OS XL C/C++ Runtime Library Reference.
struct __fileData {
    unsigned int __recfmF : 1, /* always on */
    __recfmV : 1, /* always off */
    __recfmU : 1, /* always off */
    __recfmS : 1, /* always off */
    __recfmBlk : 1, /* always off */
    __recfmSAs : 1, /* always off */
    __recfmM : 1, /* always off */
    __dsorgPO : 1, /* N/A -- always off */
    __dsorgPOsmem : 1, /* N/A -- always off */
    __dsorgPOsd : 1, /* N/A -- always off */
    __dsorgPOps : 1, /* N/A -- always off */
    __dsorgPOconcat : 1, /* N/A -- always off */
    __dsorgMem : 1, /* */
    __dsorgHiper : 1, /* */
    __dsorgTemp : 1, /* N/A -- always off */
    __dsorgVsam : 1, /* N/A -- always off */
    __dsorgHfs : 1, /* N/A -- always off */
    __openmode : 2, /* __BINARY */
    __modeflag : 4, /* combination of: */
    /* __READ */
    /* __WRITE */
    /* __APPEND */
    /* __UPDATE */
    __dsorgDSE : 1, /* N/A -- always off */
    __reserve : 8; /* */
    __device_t __device; /* one of: */
    /* __MEMORY */
    /* __HIPERSPACE */
    unsigned long __blksize, /* */
    __maxreclen; /* */
    unsigned short __vsamtype; /* N/A */
    unsigned long __vsamkeylen; /* N/A */
    unsigned long __vsamRKP; /* N/A */
    char * __dsname; /* */
    unsigned int __reserve4; /* */
};

typedef struct __fileData fldata_t;

Figure 33. fldata() structure

Notes:
1. The filename is the fully qualified version of the filename specified on the fopen() or freopen() function call. There are no quotation marks. However, if the filename specified on the fopen() or freopen() function call begins with an *, a unique filename is generated in the format ((n)), where n is an integer.
2. The __dsorgMem bit will be set on only for regular memory files.
3. The __dsorgHiper bit will be set on only for hiperspace memory files.
4. The __dsname is identical to the filename value.

Example program

The following examples show the use of a memory file. Program CCNGMF3 [Figure 34 on page 214] creates a memory file, calls program CCNGMF4 [Figure 35 on page 214], and redirects the output of the called program to the memory file. When control returns to the first program, the program reads and prints the string in the memory file.

For more information on the system() library function, see z/OS XL C/C++ Runtime Library Reference.
Figure 34. Memory file example, part 1

/* this example demonstrates the use of a memory file */
/* part 1 of 2-other file is CCNGMF4 */
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
int main(void)
{
    FILE *fp;
    char(buffer[20];
    char *rc;
    /* Open the memory file to create it */
    if ((fp = fopen("PROG.DAT","wb+",type=memory")) != NULL)
    {
        /* Close the memory file so that it can be used as stdout */
        fclose(fp);
        /* Call CCNGMF4 and redirect its output to memory file */
        /* CCNGMF4 must be an executable MODULE */
        system("CCNGMF4 >PROG.DAT");
        /* Now print the string contained in the file */
        fp = fopen("PROG.DAT","rb");
        rc = fgets(buffer,sizeof(buffer),fp);
        if (rc != NULL)
        {
            perror(" Error reading from file ");
            exit(99);
        }
        printf("%s", buffer);
    }
    return(0);
}

Figure 35. Memory file example, part 2

redirects the output of the called program to the memory file.

Figure 35. Memory file example, part 2

/* this example demonstrates the use of a memory file */
/* part 2 of 2-other file is CCNGMF3 */
#include <stdio.h>
#include <stdlib.h>
int main(void)
{
    char item[] = "Hello World\n";
    int rc;
    /* Write the data to the stdout which, at this point, has been
       redirected to the memory file */
    rc = fputs(item,stdout);
    if (rc == EOF) {
        perror("Error putting to file ");
        exit(99);
    }
    printf("%s", item);
    return(0);
}
Chapter 15. Performing CICS Transaction Server I/O operations

Restriction: This chapter does not apply to AMODE 64.

z/OS XL C/C++ under CICS Transaction Server for z/OS (CICS TS) supports only three kinds of I/O:

CICS I/O

z/OS XL C/C++ applications can access the CICS I/O commands through the CICS command level interface.

Files

Memory files are the only type of file that z/OS XL C/C++ supports under CICS. Hiperspace files are not supported. VSAM files can be accessed through the CICS command level interface.

CICS data queues

Under CICS, z/OS XL C/C++ implements the standard output (stdout) and standard error (stderr) streams as CICS transient data queues. These data queues must be defined in the CICS Destination Control table (DCT) by the CICS system administrator before the CICS cold start. Output from all users’ transactions that use stdout (or stderr) is written to the queue in the order of occurrence.

To help differentiate the output, place a user’s terminal name, the CICS transaction identifier, and the time at the beginning of each line printed to the queue. The queues are as follows:

<table>
<thead>
<tr>
<th>Stream</th>
<th>Queue</th>
</tr>
</thead>
<tbody>
<tr>
<td>stdout</td>
<td>CESO</td>
</tr>
<tr>
<td>stderr</td>
<td>CESE</td>
</tr>
<tr>
<td>stdin</td>
<td>Not supported</td>
</tr>
</tbody>
</table>

To access any other queues, you must use the command level interface.

Note: If you are using the C++ I/O stream classes, the standard stream cout maps to stdout, which maps to CESO. The standard stream cerr and clog both map to stderr, which maps to CESE. The standard stream cin is not supported under CICS.

For more general information about C++ I/O streaming, see Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23. For more detailed information, see Standard C++ Library Reference, which discusses the Standard C++ I/O stream classes.

For information about using z/OS XL C/C++ and z/OS XL C/C++ under CICS TS, see Chapter 52, “Using the CICS Transaction Server (CICS TS),” on page 879. For information on using wide characters in the CICS TS environment, see Chapter 8, “z/OS XL C Support for the double-byte character set,” on page 53.
Chapter 16. Language Environment Message file operations

This chapter describes input and output with the z/OS Language Environment message file. This file is write-only. That is, it is nonreadable and nonseekable.

Restriction: This chapter does not apply to AMODE 64. There is no MSGFILE runtime option in AMODE 64. In AMODE 64, the stderr stream does not get directed to the Language Environment message file. Anything that would normally go to the Language Environment message file is now directed to the C stderr stream, including when stderr is directed to stdout. For more information on AMODE 64 see Chapter 23, “z/OS 64-bit environment,” on page 325.

The default open mode for the z/OS Language Environment message file is text. Binary and record I/O modes are not supported.

This chapter also describes C I/O streams as they can be used within C++ programs. If you want to use the C++ I/O stream classes instead, see Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23 for general information. For more detailed information, see Standard C++ Library Reference, which discusses the Standard C++ I/O stream classes.

The standard stream stderr defaults to using the z/OS Language Environment message file. stderr will be directed to file descriptor 2, which is typically your terminal if you are running under one of the z/OS UNIX shells. There are some exceptions, however:

- If the application has allocated the ddname in the MSGFILE(ddname) runtime parameter, your output will go there. The default is MSGFILE(SYSOUT).
- If the application has issued one of the POSIX exec() functions, or it is running in an address space created by the POSIX fork() function and the application has not dynamically allocated a ddname for MSGFILE, then the default is to use file descriptor 2, if one exists. If it doesn’t, then the default is to create a message file in the user’s current working directory. The message file will have the name that is specified on the message file runtime option, the default being SYS0UT.

Opening files

The default is for stderr to go to the message file automatically. The message file is available only as stderr; you cannot use the fopen() or freopen() library function to open it.

- freopen() with the null string (""") as filename string will fail.
- Record format (RECFM) is always treated as undefined (U). Logical record length (LRECL) is always treated as 255 (the maximum length defined by z/OS Language Environment message file system write interface).

Reading from files

The z/OS Language Environment message file is nonreadable.
Writing to files

- Data written to the z/OS Language Environment message file is always appended to the end of the file.
- When the data written is longer than 255 bytes, it is written to the z/OS Language Environment message file 255 bytes at a time, with the last write possibly less than 255 bytes. No truncation will occur.
- When the output data is shorter than the actual LRECL of the z/OS Language Environment message file, it is padded with blank characters by the z/OS Language Environment system write interface.
- When the output data is longer than the actual LRECL of the z/OS Language Environment message file, it is split into multiple records by the z/OS Language Environment system write interface. The z/OS Language Environment system write interface splits the output data at the last blank before the LRECL-th byte, and begins writing the next record with the first non-blank character. Note that if there are no blanks in the first LRECL bytes (DBCS for instance), the z/OS Language Environment system write interface splits the output data at the LRECL-th byte. It also closes off any DBCS string on the first record with a X'0F' character, and begins the DBCS string on the next record with a X'0E' character.
- The hex characters X'0E' and X'0F' have special meaning to the z/OS Language Environment system write interface. The z/OS Language Environment system write interface removes adjacent pairs of these characters (normalization).
- You can set up a SIGIOERR handler to catch system write errors. See Chapter 18, "Debugging I/O programs," on page 223 for more information.

Flushing buffers

The fflush() function has no effect on the z/OS Language Environment message file.

Repositioning within files

The ftell(), fgetpos(), fseek(), and fsetpos() functions are not allowed, because z/OS Language Environment message file is a nonseekable file. The frewind() function only resets error flags.

You cannot call fseek() on stderr when it is mapped to MSGFILE (the default routing of stderr).

Closing files

Do not use the fclose() library function to close the z/OS Language Environment message file. z/OS XL C/C++ automatically closes files on normal program termination and attempts to do so under abnormal program termination or abend.
Chapter 17. CELQPIPI MSGRTN file operations

Restriction: This chapter only applies to AMODE 64 when using preinitialization services.

If the CELQPIPI MSGRTN service routine is specified and the standard stream stderr has not been redirected, it defaults to using the CELQPIPI MSGRTN. The remainder of this chapter describes the behavior of the standard stream stderr when used in the application.

The CELQPIPI MSGRTN file is write-only. That is, the file is nonreadable and nonseekable. The mode for this file is text append. Binary and record I/O modes are not supported.

Opening files

The default behavior is that standard stream stderr will go to the CELQPIPI MSGRTN. You cannot use the fopen() or freopen() library functions to open or reopen the CELQPIPI MSGRTN.

- Using fopen() to assign a stream to stderr directs stderr away from the CELQPIPI MSGRTN.
- A call to freopen() with the null string ("") as the filename string in an attempt to reopen the CELQPIPI MSGRTN using a different mode will fail.
- Record format (RECFM) is always treated as undefined (U). Logical record length (LRECL) is always treated as 255, which is the maximum length defined by the write interface of the CELQPIPI MSGRTN file system.

Reading from files

The CELQPIPI MSGRTN file is nonreadable.

Writing to files

- Data written to the CELQPIPI MSGRTN file is always appended to the end of the file.
- When the data written is longer than 255 bytes, it is written to the CELQPIPI MSGRTN file 255 bytes at a time, with the last write possibly less than 255 bytes. No truncation will occur.
- When the output data is shorter than the actual LRECL of the CELQPIPI MSGRTN file, it is padded with blank characters by the z/OS Language Environment system write interface.

Flushing buffers

The fflush() function has no effect on the CELQPIPI MSGRTN file.

Repositioning within files

The ftell(), fgetpos(), fseek(), and fsetpos() functions are not allowed, because CELQPIPI MSGRTN file is nonseekable. The rewind() function only resets error flags.
Closing files

Do not use the fclose() library function to close the CELQPIPI MSGRTN file. z/OS XL C/C++ automatically closes files on normal program termination and attempts to do so under abnormal program termination or abend.

fldata() behavior

The fldata() function is used to retrieve information about an open stream. The name of the file is returned in filename and other information is returned in the fldata_t structure, shown in Figure 36. Values specific to this category of I/O are shown in the comment beside the structure element. For more information about the fldata() function, see z/OS XL C/C++ Runtime Library Reference.

```c
struct __fileData {
    unsigned int __recfmF : 1, /* */
    __recfmV : 1, /* */
    __recfmU : 1, /* always on */
    __recfmS : 1, /* */
    __recfmBlk : 1, /* */
    __recfmASA : 1, /* */
    __recfmM : 1, /* */
    __dsorgPO : 1, /* */
    __dsorgPDSmem : 1, /* */
    __dsorgPDSdir : 1, /* */
    __dsorgPS : 1, /* always on */
    __dsorgConcat : 1, /* */
    __dsorgMem : 1, /* */
    __dsorgHiper : 1, /* */
    __dsorgTemp : 1, /* */
    __dsorgVSAM : 1, /* */
    __dsorgHFS : 1, /* */
    __openmode : 2, /* __TEXT */
    __modelflag : 4, /* __APPEND */
    __dsorgPOSet : 1, /* */
    __vsamRLS : 3, /* */
    __vsamEA : 1, /* */
    __reserve2 : 4; /* */
    __device_t __device; /* __MSGRTN */
    unsigned long __blksize, /* 255 */
    __maxreclen; /* 255 */
    union {
        struct {
            unsigned short __vsam_type; /* */
            unsigned long __vsam_keylen; /* */
            unsigned long __vsam_RKP; /* */
        } __vsam;
        struct {
            unsigned char __disk_access_method; /* */
            unsigned char __disk_noseek_to_seek; /* */
            long __disk_reserve[2]; /* */
        } __disk;
        struct {
            char* __dsname; /* */
            unsigned int __reserve4; /* */
        } __device_specific;
    }
};
typedef struct __fileData fldata_t;
```

Figure 36. fldata() structure
**fldata() example**

Figure 37 example shows the retrieval of the file name in `filename` from the open stream pointed to by `stderr` that maps to the CELQPIPI MSGRTN file.

```c
#include <stdio.h>

int main(void) {
    FILE *stream;
    char filename[100];
    fldata_t fileinfo;
    int rc;

    stream = stderr;
    rc = fldata(stream, filename, &fileinfo);
    if (rc != 0)
        printf("fldata failed\n");
    else
        printf("filename is %s\n",filename);
}
```

**Figure 37. fldata() example**

The program in Figure 37 produces the following output:

filename is ((MSGRTN))

The example in Figure 38 shows the use of the CELQPIPI MSGRTN file as the default `stderr`.

```c
#include <stdio.h>
#include <errno.h>

int main(void) {
    FILE *stream;

    stream = stderr;

    fprintf(stream, "fprintf: Output redirects to the CELQPIPI MSGRTN file.\n");
    errno = ETIME;
    Perror("perror: Output redirects to the CELQPIPI MSGRTN file.");
}
```

**Figure 38. CELQPIPI MSGRTN example**
Chapter 18. Debugging I/O programs

This chapter will help you locate and diagnose problems in programs that use input and output. It discusses several diagnostic methods specific to I/O. Diagnostic methods for I/O errors include:

- Using return codes from I/O functions
- Using errno values and the associated perror() message
- Using the __amrc structure
- Using the __amrc2 structure

The information provided with the return code of I/O functions and with the perror() message associated with errno values may help you locate the source of errors and the reason for program failure. Because return codes and errno values do not exist for every possible system I/O failure, return codes and errno values are not useful for diagnosing all I/O errors. This chapter discusses the use of the __amrc structure and the __amrc2 structure. For information on return codes from I/O functions see z/OS XL C/C++ Runtime Library Reference. For information on errno values and the associated perror() message see z/OS Language Environment Debugging Guide.

Using the __amrc structure

__amrc is a structure defined in stdio.h (when the compile-time option LANGLVL(EXTENDED) or LANGLVL(LIBEXT) is in effect) to help you determine errors resulting from an I/O operation. This structure is changed during system I/O and some C specific error situations. When looking at __amrc, be sure to copy the structure into a temporary structure of __amrc type since any I/O function calls will change the value of __amrc. Figure 39 shows the __amrc structure as it appears in stdio.h.

Note: __amrc is not used to record I/O errors in UNIX file system files.

```c
#ifndef __TARGET_LIB__ >= __EDC_LE
typedef struct __amrctype {
#else
typedef struct {
#endif
    union {
        int __error; /* error from OPEN/CLOSE, GENCB/MODCB/TESTCB/SHOWCB */
        struct {
            /* abend code when errno set to EABEND */
            unsigned short __syscode, /* system abend code */
            __rc; /* return code */
        } __abend;
    } __code;
#endif

__amrc structure (Part 1 of 2)

Figure 39. __amrc structure
union {...} __code

The error or warning value from an I/O operation is in either __error, __abend, __feedback, or __alloc. You must look at __last_op to determine how to interpret the __code union.

__error contains the return code from the system macro or utility. Refer to Table 34 on page 227 for further information.

This struct contains the abend code when errno is set to indicate a
recoverable I/O abend. __syscode is the system abend code and __rc is the
return code. For more information on the abend codes, see the System
Codes manual as listed in z/OS V2R2 Information Roadmap. The macros
__abendcode() and __rsncode() may be set to the abend code and reason
code of a TSO CLIST or command when invoked with system().

__feedback
This struct is used for VSAM only. The __rc stores the VSAM register 15,
__fdbk stores the VSAM error code or reason code, and __RBA stores the
RBA after some operations.

__alloc
This struct contains errors during fopen() or freopen() calls when
defining files to the system using SVC 99. See the Systems Macros manual,
as listed in z/OS V2R2 Information Roadmap, for more information on these
fields as set by SVC 99.

__RBA
This is the RBA value returned by VSAM after an ESDS or KSDS record is
written out. For an RRDS, it is the calculated value from the record number.
It may be used in subsequent calls to flocate(). The __amrc.__RBA field is
defined as an unsigned int, and therefore will only contain a 4-byte RBA
value. This field will be set to -1 when the RBA is beyond 4GB in an
extended addressable VSAM data set. In this case, the __XRBA field should
be used.

__last_op
Contains a value that indicates the last I/O operation being performed by
z/OS XL C/C++ at the time the error occurred. These values are shown in
Table 34 on page 227.

__msg
This may contain the system error messages from read or write operations
emitted from the BSAM SYNADAF macro instruction. This field will not
always be filled. If you print this field using the %s format, you should
print the string starting at the sixth position because of possible null
characters found in the first 6 characters. Special messages for PDSEs are
contained in the positions 136 through 184. See the Data Administration
manual as listed in z/OS V2R2 Information Roadmap for more information.
This field is used by the SIGIOERR handler.

__rplfdbwd
Contains feedback information related to a VSAM RLS failure. This is the
feedback code from the IFGRPL control block.

__XRBA
This is the 8 byte relative byte address returned by VSAM after an ESDS or
KSDS record is written out. For an RRDS, it is the calculated value from
the record number. It may be used in subsequent calls to flocate().

__amrc.noseek_to_seek
Contains the reason for the switch from QSAM (noseek) to BSAM with
NOTE and P01WT macros requested (seek) by the XL C/C++ Runtime
Library. This field is set when system-level I/O macro processing triggers
an ABEND condition. The macro name values (defined in stdio.h) for this
field are as follows:

<table>
<thead>
<tr>
<th>Macro</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>__AM_BSAM_NOSWITCH</td>
<td>No switch was made.</td>
</tr>
<tr>
<td>Macro</td>
<td>Definition</td>
</tr>
<tr>
<td>-----------------------------</td>
<td>------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>__AM_BSAM_UPDATE</td>
<td>Data set is open for update</td>
</tr>
<tr>
<td>__AM_BSAM_BSAMWRITE</td>
<td>Data set is already open for write (or update) in the same C process</td>
</tr>
<tr>
<td>__AM_BSAM_FBS_APPEND</td>
<td>Data set is recfm=FBS and open for append</td>
</tr>
<tr>
<td>__AM_BSAM_LRECLX</td>
<td>Data set is recfm=LRECLX (used for VBS data sets where records span the largest blocksize allowed on the device)</td>
</tr>
<tr>
<td>__AM_BSAM_PARTITIONED_DIRECTORY</td>
<td>Data set is the directory for a regular or extended partitioned data set</td>
</tr>
<tr>
<td>__AM_BSAM_PARTITIONED_INDIRECT</td>
<td>Data set is a member of a partitioned data set, and the member name was not specified at allocation</td>
</tr>
</tbody>
</table>

Sample program CCNGDI1 demonstrates how to print the __amrc structure after an error has occurred to get information that may help you to diagnose an I/O error. The program writes to a file until it is full. When the file is full, the program fails. Following the I/O failure, the program makes a copy of the __amrc structure, and prints the number of successful writes to the file, the errno, the __last_op code, the abend system code and the return code.

```c
/* this example demonstrates how to print the __amrc structure */
#include <stdio.h>
#include <errno.h>
#include <stdlib.h>
#include <string.h>

int main(void) {  
    FILE *fp;  
    __amrc_type save_amrc;  
    char buffer[80];  
    int i = 0;  

    /* open an MVS binary file */
    fp = fopen("testfull.file","wb, recfm=F, lrecl=80");
    if (fp == NULL) exit(99);
    memset(buffer, 'A', 80);  

    /* write to MVS file until it runs out of extents */  
    while (fwrite(buffer, 1, 80, fp) == 80)  
        ++i;  

    save_amrc = __amrc; /* need copy of __amrc structure */
    printf("number of successful fwrites of 80 bytes = \%d\n", i);  

Example of printing the __amrc structure (Part 1 of 2)  
```

Figure 40. Example of printing the __amrc structure
Example of printing the __amrc structure (Part 2 of 2)

Using the __amrc2 structure

The __amrc2 structure is an extension of __amrc. Only 2 fields are defined for __amrc2. Like the __amrc structure, __amrc2 is changed during system I/O and some C specific error situations. Figure 41 shows the __amrc2 structure as it appears in stdio.h.

Note: See "Using the SIGIOERR signal" on page 231 for information on restrictions that exist when comparing file pointers if you are using the __amrc2 structure.

```
struct {
  int __error2;
  FILE *__fileptr;
  int __reserved[6];
}
```

Figure 41. __amrc2 structure

1. This field is a secondary error code that is used to store the reason code from specific macros. The __last_op codes that can be returned to __amrc2 are __BSAM_STOW, __BSAM_BLDL, __IO_LOCATE, __IO_RENAME, __IO_CATALOG and __IO_UNCATALOG. For information on the macros associated with these codes, see Table 34. For more information about the macros, see z/OS DFSMSdfp Diagnosis.

2. This field, __fileptr, of the __amrc2 structure is used by the signal SIGIOERR to pass back a FILE pointer that can then be passed to fldata() to get the name of the file causing the error. The __amrc2__fileptr will be NULL if a SIGIOERR is raised before the file has been successfully opened.

Using __last_op codes

The __last_op field is the most important of the __amrc fields. It defines the last I/O operation z/OS XL C/C++ was performing at the time of the I/O error. You should note that the structure is neither cleared nor set by non-I/O operations so querying this field outside of a SIGIOERR handler should only be done immediately after I/O operations. Table 34 lists __last_op codes you may receive and where to look for further information.

<table>
<thead>
<tr>
<th>Code</th>
<th>More Information</th>
</tr>
</thead>
<tbody>
<tr>
<td>__BSAM_BLDL</td>
<td>Sets __error with return code from OS BLDL macro.</td>
</tr>
<tr>
<td>__BSAM_CLOSE</td>
<td>Sets __error with return code from OS CLOSE macro.</td>
</tr>
<tr>
<td>Code</td>
<td>More Information</td>
</tr>
<tr>
<td>------------------</td>
<td>--------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>_BSAM_CLOSE_T</td>
<td>Sets _error with return code from OS CLOSE TYPE=T.</td>
</tr>
<tr>
<td>_BSAM_NOTE</td>
<td>NOTE returned 0 unexpectedly, no return code.</td>
</tr>
<tr>
<td>_BSAM_OPEN</td>
<td>Sets _error with return code from OS OPEN macro.</td>
</tr>
<tr>
<td>_BSAM_POINT</td>
<td>This will not appear as an error lastop.</td>
</tr>
<tr>
<td>_BSAM_READ</td>
<td>No return code (either _abend (errno == 92) or _msg (errno == 66) filled in).</td>
</tr>
<tr>
<td>_BSAM_STOW</td>
<td>Sets _error with return code from OS STOW macro.</td>
</tr>
<tr>
<td>_BSAM_WRITE</td>
<td>No return code (either _abend (errno == 92) or _msg (errno == 65) filled in).</td>
</tr>
<tr>
<td>_C_CANNOT_EXTEND</td>
<td>This occurs when an attempt is made to extend a file that allows writing, but cannot be extended. Typically, this is a member of a partitioned data set being opened for update.</td>
</tr>
<tr>
<td>_C_DBCS_SI_TRUNCATE</td>
<td>This occurs only when there was not enough room to start a DBCS string and data was written anyway, with an SI to end it. Cannot happen if MB_CUR_MAX is 1.</td>
</tr>
<tr>
<td>_C_DBCS_SO_TRUNCATE</td>
<td>This occurs when there is not enough room in a record to start any DBCS string or else when a redundant SO is written to the file before an SI. Cannot happen if MB_CUR_MAX is 1.</td>
</tr>
<tr>
<td>_C_DBCS_TRUNCATE</td>
<td>This occurs when writing DBCS data to a text file and there is no room left in a physical record for anymore double byte characters. A new-line is not acceptable at this point. Truncation will continue to occur until an SI is written or the file position is moved. Cannot happen if MB_CUR_MAX is 1.</td>
</tr>
<tr>
<td>_C_DBCS_UNEVEN</td>
<td>This occurs when an SI is written before the last double byte character is completed, thereby forcing z/OS XL C/C++ to fill in the last byte of the DBCS string with a padding byte X'FE'. Cannot happen if MB_CUR_MAX is 1.</td>
</tr>
<tr>
<td>_C_FCBCHECK</td>
<td>Set when z/OS XL C/C++ FCB is corrupted. This is due to a pointer corruption somewhere. File cannot be used after this.</td>
</tr>
<tr>
<td>_C_TRUNCATE</td>
<td>Set when z/OS XL C/C++ truncates output data. Usually this is data written to a text file with no newline such that the record fills up to capacity and subsequent characters cannot be written. For a record I/O file this refers to an fwrite() writing more data than the record can hold. Truncation is always of rightmost data. There is no return code.</td>
</tr>
<tr>
<td>_HSP_CREATE</td>
<td>Indicates last op was a DSPSERV CREATE to create a hiperspace for a hiperspace memory file. If CREATE fails, stores abend code in _amrc._code._abend._syscode, reason code in _amrc._code._abend._rc.</td>
</tr>
<tr>
<td>_HSP_DELETE</td>
<td>Indicates last op was a DSPSERV DELETE to delete a hiperspace for a hiperspace memory file during termination. If DELETE fails, stores abend code in _amrc._code._abend._syscode, reason code in _amrc._code._abend._rc.</td>
</tr>
<tr>
<td>_HSP_EXTEND</td>
<td>Indicates last op was a HSPSERV EXTEND during a write to a hiperspace. If EXTEND fails, stores abend code in _amrc._code._abend._syscode, reason code in _amrc._code._abend._rc.</td>
</tr>
</tbody>
</table>
Table 34. __last_op codes and diagnosis information (continued)

<table>
<thead>
<tr>
<th>Code</th>
<th>More Information</th>
</tr>
</thead>
<tbody>
<tr>
<td>__HSP_READ</td>
<td>Indicates last op was a HSPSERV READ from a hiperspace. If READ fails, stores abend code in __amrc.__code.__abend.__syscode, reason code in __amrc.__code.__abend.__rc.</td>
</tr>
<tr>
<td>__HSP_WRITE</td>
<td>Indicates last op was a HSPSERV WRITE to a hiperspace. If WRITE fails, stores abend code in __amrc.__code.__abend.__syscode, reason code in __amrc.__code.__abend.__rc.</td>
</tr>
<tr>
<td>__IO_CATALOG</td>
<td>Sets __error with return code from I/O CAMLST CAT. The associated macro is CATALOG.</td>
</tr>
<tr>
<td>__IO_DEVTYPE</td>
<td>Sets __error with return code from I/O DEVTYPE macro.</td>
</tr>
<tr>
<td>__IO_INIT</td>
<td>Will never be seen by SIGIOERR exit value given at initialization.</td>
</tr>
<tr>
<td>__IO_LOCATE</td>
<td>Sets __error with return code from I/O CAMLST LOCATE.</td>
</tr>
<tr>
<td>__IO_OBTAIN</td>
<td>Sets __error with return code from I/O CAMLST OBTAIN.</td>
</tr>
<tr>
<td>__IO_RENAME</td>
<td>Sets __error with return code from I/O CAMLST RENAME.</td>
</tr>
<tr>
<td>__IO_TRKCALC</td>
<td>Sets __error with return code from I/O TRKCALC macro.</td>
</tr>
<tr>
<td>__IO_UNCATALOG</td>
<td>Sets __error with return code from I/O CAMLST UNCAT. The associated macro is CATALOG.</td>
</tr>
<tr>
<td>__LFS_CLOSE</td>
<td>Sets __error with reason code from UNIX file system services. Reason code from UNIX file system services must be broken up. The low order 2 bytes can be looked up in z/OS UNIX System Services Programming: Assembler Callable Services Reference.</td>
</tr>
<tr>
<td>__LFS_FSTAT</td>
<td>Sets __error with reason code from UNIX file system services. Reason code from UNIX file system services must be broken up. The low order 2 bytes can be looked up in z/OS UNIX System Services Programming: Assembler Callable Services Reference.</td>
</tr>
<tr>
<td>__LFS_LSEEK</td>
<td>Sets __error with reason code from UNIX file system services. Reason code from UNIX file system services must be broken up. The low order 2 bytes can be looked up in z/OS UNIX System Services Programming: Assembler Callable Services Reference.</td>
</tr>
<tr>
<td>__LFS_OPEN</td>
<td>Sets __error with reason code from UNIX file system services. Reason code from UNIX file system services must be broken up. The low order 2 bytes can be looked up in z/OS UNIX System Services Programming: Assembler Callable Services Reference.</td>
</tr>
<tr>
<td>__LFS_READ</td>
<td>Sets __error with reason code from UNIX file system services. Reason code from UNIX file system services must be broken up. The low order 2 bytes can be looked up in z/OS UNIX System Services Programming: Assembler Callable Services Reference.</td>
</tr>
<tr>
<td>__LFS_STAT</td>
<td>Sets __error with reason code from UNIX file system services. Reason code from UNIX file system services must be broken up. The low order 2 bytes can be looked up in z/OS UNIX System Services Programming: Assembler Callable Services Reference.</td>
</tr>
<tr>
<td>__LFS_WRITE</td>
<td>Sets __error with reason code from UNIX file system services. Reason code from UNIX file system services must be broken up. The low order 2 bytes can be looked up in z/OS UNIX System Services Programming: Assembler Callable Services Reference.</td>
</tr>
<tr>
<td>__OS_CLOSE</td>
<td>Sets __error to result of OS CLOSE macro.</td>
</tr>
<tr>
<td>__OS_OPEN</td>
<td>Sets __error to result of OS OPEN macro.</td>
</tr>
<tr>
<td>Code</td>
<td>More Information</td>
</tr>
<tr>
<td>--------------------</td>
<td>-----------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>__QSAM_FREEPOOL</td>
<td>This is an intermediate operation. You will only see this if an I/O abend occurred.</td>
</tr>
<tr>
<td>__QSAM_GET</td>
<td>_error is not set (if abend (errno == 92), __abend is set, otherwise if read error (errno == 66), look at __msg.</td>
</tr>
<tr>
<td>__QSAM_PUT</td>
<td>_error is not set (if abend (errno == 92), __abend is set, otherwise if write error (errno == 65), look at __msg.</td>
</tr>
<tr>
<td>__QSAM_TRUNC</td>
<td>This is an intermediate operation. You will only see this if an I/O abend occurred.</td>
</tr>
<tr>
<td>__SVC99_ALLOC</td>
<td>Sets __alloc structure with info and error codes from SVC 99 allocation.</td>
</tr>
<tr>
<td>__SVC99_ALLOC_NEW</td>
<td>Sets __alloc structure with info and error codes from SVC 99 allocation of NEW file.</td>
</tr>
<tr>
<td>__SVC99_UNALLOC</td>
<td>Sets __alloc structure with info and error codes from SVC 99 unallocation. The __QSAM_CLOSE and __QSAM_OPEN codes do not exist. They should be __OS_CLOSE and __OS_OPEN instead.</td>
</tr>
<tr>
<td>__TGET_READ</td>
<td>Sets __error with return code from TSO TGET macro.</td>
</tr>
<tr>
<td>__TPUT_WRITE</td>
<td>Sets __error with return code from TSO TPUT macro.</td>
</tr>
<tr>
<td>__VSAM_CLOSE</td>
<td>Set when the last op was a low level VSAM CLOSE; if the CLOSE fails, sets __rc and __fdbk in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_ENDREQ</td>
<td>Set when the last op was a low level VSAM ENDREQ; if the ENDREQ fails, sets __rc and __fdbk in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_ERASE</td>
<td>Set when the last op was a low level VSAM ERASE; if the ERASE fails, sets __rc and __fdbk in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_GENCB</td>
<td>Set when a low level VSAM GENCB macro fails, sets __rc and __fdbk fields in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_GET</td>
<td>Set when the last op was a low level VSAM GET; if the GET fails, sets __rc and __fdbk in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_MODCB</td>
<td>Set when a low level VSAM MODCB macro fails, sets __rc and __fdbk fields in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_OPEN_ESDS</td>
<td>Does not indicate an error; set when the low level VSAM OPEN succeeds, and the file type is ESDS.</td>
</tr>
<tr>
<td>__VSAM_OPEN_ESDS_PATH</td>
<td>Does not indicate an error; set when the low level VSAM OPEN succeeds, and the file type is ESDS.</td>
</tr>
<tr>
<td>__VSAM_OPEN_FAIL</td>
<td>Set when a low level VSAM OPEN fails, sets __rc and __fdbk fields in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_OPEN_KSDS</td>
<td>Does not indicate an error; set when the low level VSAM OPEN succeeds, and the file type is ESDS.</td>
</tr>
<tr>
<td>__VSAM_OPEN_KSDS_PATH</td>
<td>Does not indicate an error; set when the low level VSAM OPEN succeeds, and the file type is ESDS.</td>
</tr>
<tr>
<td>__VSAM_OPEN_RRDS</td>
<td>Does not indicate an error; set when the low level VSAM OPEN succeeds, and the file type is ESDS.</td>
</tr>
<tr>
<td>__VSAM_POINT</td>
<td>Set when the last op was a low level VSAM POINT; if the POINT fails, sets __rc and __fdbk in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_PUT</td>
<td>Set when the last op was a low level VSAM PUT; if the PUT fails, sets __rc and __fdbk in the __amrc struct.</td>
</tr>
<tr>
<td>__VSAM_SHOWCB</td>
<td>Set when a low level VSAM SHOWCB macro fails, sets __rc and __fdbk fields in the __amrc struct.</td>
</tr>
</tbody>
</table>
Table 34. _last_op codes and diagnosis information  (continued)

<table>
<thead>
<tr>
<th>Code</th>
<th>More Information</th>
</tr>
</thead>
<tbody>
<tr>
<td>__VSAM_TESTCB</td>
<td>Set when a low level VSAM TESTCB macro fails, sets __rc and __fdbk fields in the __amrc struct.</td>
</tr>
</tbody>
</table>

Using the SIGIOERR signal

SIGIOERR is a signal used by the library to pass control to an error handler when an I/O error occurs. The default action for this signal is SIG_IGN. Setting up a SIGIOERR handler is like setting up any other error handler. Example program CCNGDI2 [Figure 42 on page 232] adds a SIGIOERR handler to the example shown in Figure 40 on page 226. Note the way fldata() and the __amrc2 field __fileptr are used to get the name of the file that caused the error.
```c
#include <stdio.h>
#include <signal.h>
#include <errno.h>
#include <stdlib.h>
#include <string.h>
#ifdef __cplusplus
extern "C" {
#endif
void iohdlr(int);
#ifdef __cplusplus
}
#endif

int main(void) {
    FILE *fp;
    char buffer[80];
    int i = 0;

    signal(SIGIOERR, iohdlr);
    /* open an MVS binary file */
    fp = fopen("testfull.file","wb, recfm=F, lrecl=80");
    if (fp == NULL) exit(99);
    memset(buffer, 'A', 80);
    /* write to MVS file until it runs out of extents */
    while (fwrite(buffer, 1, 80, fp) == 80)
        ++i;
    printf("number of successful fwrites of 80 bytes = \n", i);
    return 0;
}

void iohdlr (int signum) {
    __amrc_type save_amrc;
    __amrc2_type save_amrc2;
    char filename[FILENAME_MAX];
    fldata_t info;
}

Example of using SIGIOERR (Part 1 of 2)

Figure 42. Example of using SIGIOERR
```
save_amrc = *__amrc; /* need copy of __amrc structure */
save_amrc2 = *__amrc2; /* need copy of __amrc2 structure */

/* get name of file causing error from fldata */
if (fldata(save_amrc2.__fileptr, filename, &info) == 0)
    printf("error on file %s\n", filename);
    perror("io handler"); /* give errno message */
    printf("lastop=%d syscode=%x rc=%d\n",
            save_amrc.__last_op,
            save_amrc.__code.__abend.__syscode,
            save_amrc.__code.__abend.__rc);
    signal(SIGIOERR, iohdlr);
}

Example of using SIGIOERR (Part 2 of 2)

When control is given to a SIGIOERR handler, the __amrc2 structure field __fileptr will be filled in with a file pointer. The __amrc2 __fileptr will be NULL if a SIGIOERR is raised before the file has been successfully opened. The only operation permitted on the file pointer is fldata(). This operation can be used to extract information about the file that caused the error. Other than freopen() and fclose(), all I/O operations will fail since the file pointer is marked invalid. Do not issue freopen() or fclose() in a SIGIOERR handler that returns control. This will result in unpredictable behavior, likely an abend.

If you choose not to return from the handler, the file is still locked from all operations except fldata(), freopen(), or fclose(). The file is considered open and can prevent other incorrect access, such as an MVS sequential file opened more than once for a write. Like all other files, the file is closed automatically at program termination if it has not been closed explicitly already.

When you exit a SIGIOERR handler and do not return, the state of the file at closing is indeterminate. The state of the file is indeterminate because certain control block fields are not set correctly at the point of error and they do not get corrected unless you return from the handler.

For example, if your handler were invoked due to a truncation error and you performed a longjmp() out of your SIGIOERR handler, the file in error would remain open, yet inaccessible to all I/O functions other than fldata(), fclose(), and freopen(). If you were to close the file or it was closed at termination of the program, it is still likely that the record that was truncated will not appear in the final file.

You should be aware that for a standard stream passed across a system() call, the state of the file will be indeterminate even after you return to the parent program. For this reason, you should not jump out of a SIGIOERR handler. For further information on system() calls and standard streams, see Chapter 9, "Using C and C++ standard streams and redirection," on page 63.

I/O with files other than the file causing the error is perfectly valid within a SIGIOERR handler. For example, it is valid to call printf() in your SIGIOERR handler if the file causing the error is not stdout. Comparing the incoming file pointer to the standard streams is not a reliable mechanism of detecting whether any of the standard streams are in error. This is because the file pointer in some cases is only a pointer to a file structure that points to the same __file as the...
stream supplied by you. The FILE pointers will not be equal if compared, but a
comparison of the __file fields of the corresponding FILE pointers will be. See the
stdio.h header file for details of type FILE.

If stdout or stderr are the originating files of a SIGIOERR, you should open a
special log file in your handler to issue messages about the error.

---

File I/O trace

The file I/O trace is an EBCDIC encoded trace that can be used as a debugging aid
for file I/O failures. The files that are traced, the level of detail provided by the
trace, and the trace table size can be controlled with the environment variable
_EDC_IO_TRACE. For more information about _EDC_IO_TRACE, see
"_EDC_IO_TRACE" on page 495. Figure 43 shows the result of running a file I/O
application with the displayed environment variable setting.

---

Locating the file I/O trace

If your application is running under TSO or batch, and an EDCTRACE DD is not
specified, Language Environment writes the trace to the batch log (SYSOUT=* by
default). You can change the SYSOUT class by specifying an EDCTRACE DD, or
by setting the environment variable, _CEE_DMPTARG=SYSOUT(x), where x is the
preferred SYSOUT class.
If your application is running under z/OS UNIX and is either running in an address space that you issued a fork() to, or if it is invoked by one of the exec family of functions, the trace is written to the UNIX file system. Language Environment writes the trace to one of the following directories in the specified order:

1. The directory found in environment variable _CEE_DMPTARG, if the directory is found.
2. The current working directory, as long as the directory is writable and the EDCTRACE path name does not exceed 1024 characters.
3. The directory found in environment variable TMPDIR, which is an environment variable that indicates the location of a temporary directory if it is not /tmp.
4. The /tmp directory.

The name of the file uses the following format:

/path/EDCTRACE.Date.Time.Pid

- **path**: Path determined from the previous algorithm.
- **Date**: Date that the trace is taken, appearing in the format YYYYMMDD. For example, 20071122 is for November 22, 2007.
- **Time**: Time that the trace is taken, appearing in the format HHMMSS. For example, 115601 is for 11:56:01 a.m.
- **Pid**: Process ID in which the application is running when the trace is taken.
Part 3. Interlanguage Calls with z/OS XL C/C++

This part describes z/OS XL C/C++ considerations about interlanguage calls in the z/OS Language Environment. For complete information about interlanguage calls (ILC) with z/OS XL C/C++ and z/OS Language Environment, refer to z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications.

- Chapter 19, “Using Linkage Specifications in C or C++,” on page 239
- Chapter 20, “Combining C or C++ and Assembler programs,” on page 245
Chapter 19. Using Linkage Specifications in C or C++

This information describes how you can make calls between C or C++ programs and assembler, COBOL, PL/I, or FORTRAN programs, or other C or C++ programs. For complete information on making interlanguage calls to and from C or C++, see z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications.

With XPLINK compilation, the linkage and parameter-passing mechanisms for C and C++ are identical. If you link to a C function from a C++ program, you should still specify extern "C" to avoid name mangling. For more information about XPLINK, see z/OS Language Environment Programming Guide.

Syntax for Linkage in C or C++

You can specify one of the following linkage types:

<table>
<thead>
<tr>
<th>Linkage Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>C</td>
<td>C linkage (C++ only)</td>
</tr>
<tr>
<td>C++</td>
<td>C++ linkage (C++ only, the default for C++)</td>
</tr>
<tr>
<td>COBOL</td>
<td>Previously used for linkage to COBOL routines. Maintained for compatibility with COBOL/370 and VS COBOL II. With newer COBOL products, use the REFERENCE, OS, or C linkage type instead.</td>
</tr>
<tr>
<td>FORTRAN</td>
<td>FORTRAN linkage</td>
</tr>
<tr>
<td>OS</td>
<td>Operating System linkage</td>
</tr>
<tr>
<td>OS_DOWNSTACK</td>
<td>XPLINK-enabled operating system linkage</td>
</tr>
<tr>
<td>OS_NOSTACK</td>
<td>Minimal operating system linkage (for use with XPLINK)</td>
</tr>
<tr>
<td>OS_UPSTACK</td>
<td>Complete operating system linkage (for use with XPLINK)</td>
</tr>
<tr>
<td>OS31_NOSTACK</td>
<td>Same as OS_NOSTACK</td>
</tr>
<tr>
<td>PLI</td>
<td>Maintained for compatibility with PL/I products prior to the Enterprise PL/I for z/OS product. With newer PL/I products use the C linkage type instead.</td>
</tr>
<tr>
<td>REFERENCE</td>
<td>A Language Environment reference linkage that has the same syntax and semantics with and without XPLINK. Unlike OS linkage, REFERENCE linkage is not affected by the OSCALL suboption of XPLINK. It is equivalent to OS_DOWNSTACK in XPLINK mode and OS_UPSTACK in non-XPLINK mode.</td>
</tr>
</tbody>
</table>

Syntax for Linkage in C

You can create linkages between C and other languages by using linkage specifications with the following #pragma linkage directive, where identifier specifies the name of the function and linkage specifies the linkage associated with the function.

```c
#pragma linkage(identifier, linkage)
```
Syntax for Linkage in C++

You can create linkages between C++ and other languages by using linkage specifications with the following syntax, where `linkage` specifies the linkage associated with the function. If z/OS XL C++ does not recognize the linkage type, it uses C linkage.

```
extern "linkage" { [declaration-list] }
extern "linkage" declaration

declaration-list:
    declaration
declaration-list declaration
```

Kinds of Linkage used by C or C++ Interlanguage Programs

Table 35 describes the kinds of linkage used by C++ interlanguage programs.

<table>
<thead>
<tr>
<th>What calls or is called by a C or C++ program</th>
<th>Linkage used</th>
<th>Description of linkage</th>
<th>C++ Example</th>
</tr>
</thead>
<tbody>
<tr>
<td>GDDM, ISPF, or non-Language Environment conforming assembler</td>
<td>OS</td>
<td>Basic linkage defined by the operating system. OS Linkage allows integer, pointer, and floating point return types. Use of OS linkage with assembler is detailed in &quot;Specifying linkage for C or C++ to Assembler on page 246.</td>
<td>extern &quot;OS&quot; { ... }</td>
</tr>
<tr>
<td>Language Environment conforming assembler,</td>
<td>OS_UPSTACK</td>
<td>This is the same as OS linkage in NOXPLINK-compiled programs. It is declared this way by the caller when the caller is XPLINK-compiled. The compiler will call glue code to transition from the XPLINK caller to the non-XPLINK callee. Also, see the OSCALL suboption of the XPLINK option in z/OS XL C/C++ User’s Guide.</td>
<td>extern &quot;OS_UPSTACK&quot; { ... }</td>
</tr>
<tr>
<td>NOXPLINK-compiled C or C++ declared with OS linkage</td>
<td>OS_NOSTACK,</td>
<td>The compiler does not generate any glue code for this call. It provides the called program with a 72-byte save area pointed to by Register 13, as does OS_UPSTACK, but the save area may not be initialized. In particular, the Language Environment Next Available Byte (NAB) field may not be present. On entry to the called function, Register 15 contains the entry point address and Register 14 contains the return address. Register 1 points to an OS-style argument list. Typically a program would declare an operating system or subsystem assembler routine with this linkage, where such a routine was not Language Environment enabled.</td>
<td>OS_NOSTACK</td>
</tr>
</tbody>
</table>
### Table 35. Linkage used by C or C++ Interlanguage Programs (continued)

<table>
<thead>
<tr>
<th>What calls or is called by a C or C++ program</th>
<th>Linkage used</th>
<th>Description of linkage</th>
<th>C++ Example</th>
</tr>
</thead>
<tbody>
<tr>
<td>XPLINK-compiled C or C++ using OS_DOWNSTACK</td>
<td>OS_DOWNSTACK</td>
<td>As with OS linkage in NOXPLINK-compiled C or C++, the parameters are passed by reference rather than by value. However, parameter and stack management use XPLINK conventions. Also, see the OSCALL suboption of the XPLINK option in z/OS XL C/C++ User’s Guide.</td>
<td>extern &quot;OS_DOWNSTACK&quot; { ... }</td>
</tr>
</tbody>
</table>

The following programs, using by-reference parameter passing:
- XPLINK-compiled C/C++ programs calling XPLINK functions (C, C++, or Language Environment conforming assembler)
- NOXPLINK-compiled C/C++ programs calling NOXPLINK functions (C, C++, or Language Environment conforming assembler)

A Language Environment conforming stack frame is always provided. This is not affected by the OSCALL suboption of XPLINK.

| PL/I                                          | PLI              | Modification of OS linkage. It forces the compiler to read and write parameter lists using PL/I linkage conventions. This linkage type extends OS linkage by allowing structures as return types. (When the return type is a structure, the caller allocates a buffer large enough to receive the returned structure and passes it, by reference, as a hidden final argument.)
|                                               |                  | This linkage type is maintained for compatibility with PL/I products prior to the Enterprise PL/I for z/OS product. With newer PL/I products use the C linkage type instead. | extern "PLI" { ... }                            |

REFERENCE: This is the same as OS_DOWNSTACK linkage in XPLINK-compiled programs and OS_UPSTACK in NOXPLINK-compiled programs. Use this for Language Environment-conforming assembler linkage.

extern "REFERENCE" { ... }
Table 35. Linkage used by C or C++ Interlanguage Programs (continued)

<table>
<thead>
<tr>
<th>What calls or is called by a</th>
<th>Linkage used</th>
<th>Description of linkage</th>
<th>C++ Example</th>
</tr>
</thead>
<tbody>
<tr>
<td>C or C++ program</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>COBOL</td>
<td>COBOL</td>
<td>Forces the compiler to read and write parameter lists using COBOL linkage conventions. All calls from C++ to COBOL must be void functions. This linkage type is maintained for compatibility with COBOL/370 and VS COBOL II. With newer COBOL products, you can call COBOL functions with the REFERENCE and OS linkage types, which allow integer return types. If the COBOL routine receives parameters by value (a pragmaless call), you can use the C linkage type.</td>
<td>extern &quot;COBOL&quot; { ... }</td>
</tr>
<tr>
<td>FORTRAN</td>
<td>FORTRAN</td>
<td>Forces the compiler to read and write parameter lists using FORTRAN linkage conventions.</td>
<td>extern &quot;FORTRAN&quot; { ... }</td>
</tr>
<tr>
<td>C</td>
<td>C</td>
<td>Use in C++ to force the compiler to read and write parameter lists using C linkage conventions. C code and the Data Window Services (DWS) product both use C linkage. With XPLINK, C and C++ use the same linkage conventions. When this linkage is specified in C++ code, the specified function is known by its function name alone rather than its name and argument types. It cannot be overloaded.</td>
<td>extern &quot;C&quot; { ... }</td>
</tr>
</tbody>
</table>

Using Linkage Specifications in C++

In the following example, a function is prototyped in a piece of C++ code and uses, by default, C++ linkage.

```cpp
void CXX_FUNC (int); // C++ linkage
```

Note that C++ is case-sensitive, but PL/I, COBOL, assembler, and FORTRAN are not. In these languages, external names are mapped to uppercase. To ensure that external names match across interlanguage calls, code the names in uppercase in the C++ program, supply an appropriate #pragma map specification, or use the NOLONGNAME compiler option. This will truncate and uppercase names for functions without C++ linkage.

To reference functions defined in other languages, you should use a linkage specification with a literal string that is one of the following:

- C
- COBOL
- FORTRAN
- OS
- OS_DOWNSTACK
- OS_NOSTACK

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For example, the following specification declares the two functions ASMFUNC1 and ASMFUNC2 to have operating system linkage. The function names are case-sensitive and must match the definition exactly. You should also limit identifiers to 8 or fewer characters.

```c
extern "OS" {
    int ASMFUNC1(void);
    int ASMFUNC2(int);
}
```

Use the reference type parameter (type&) in C++ prototypes if the called language does not support pass-by-value parameters or if the called routine expects a parameter to be passed by reference.

**Note:** To have your program be callable by any of these other languages, include an `extern` declaration for the function that the other language will call.
Chapter 20. Combining C or C++ and Assembler programs

This chapter describes how to communicate between z/OS XL C/C++ and assembler programs. To write assembler code that can be called from z/OS XL C/C++, use the prolog and epilog macros described in this chapter. For more information about how the z/OS Language Environment works with assembler, see z/OS Language Environment Programming Guide, and z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications.

z/OS Language Environment provides a set of assembler macros for use with 64–bit assembler programs. For information about writing 64–bit assembler programs see z/OS V2R1.0 Language Environment Programming Guide for 64-bit Virtual Addressing Mode.

Access to z/OS UNIX is intended to be through the z/OS UNIX XL C/C++ runtime library only. The z/OS XL C/C++ compiler does not support the direct use of z/OS UNIX callable services such as the assembler interfaces. You should not directly use z/OS UNIX callable services from your z/OS XL C/C++ application programs, because problems can occur with the processing of the following:
- Signals
- Library transfers
- fork()
- exec()
- Threads

There are comparable z/OS XL C/C++ runtime library functions for most z/OS UNIX callable services, and you should use those instead. Do not call assembler programs that access z/OS UNIX callable services.

Establishing the z/OS XL C/C++ environment

Before you can call a C or C++ function from assembler, you must establish a suitable environment. To establish the environment, do one of the following:
- Call the assembler program from within the C or C++ program (from main() or another function). Since the assembler call is from within the C or C++ program, the environment has already been established. It is often simplest to call the assembler using OS linkage conventions.

Note: In this , "OS linkages" and "OS linkage" conventions refer to the following group of specifications: OS, OS_UPSTACK, OS_DOWNSTACK, OS_NOSTACK, OS31_NOSTACK and REFERENCE. "OS" is used in syntax diagrams and examples as a representative specification. These specifications use different stack conventions. For more information on these specifications, see Chapter 19, "Using Linkage Specifications in C or C++,” on page 239.
- Use preinitialization to set up the z/OS Language Environment. See “Retaining the C environment using preinitialization” on page 258 for information.
- Use the Language Environment CEEENTRY prolog macro with MAIN=YES specified so that z/OS Language Environment is initialized.

Once you are in the assembler program, you can call other C or C++ programs from the assembler.
Specifying linkage for C or C++ to Assembler

The process for specifying the linkage to assembler differs for C and for C++. In C, a #pragma linkage directive is used, while in C++ a linkage specifier is used.

- Under C, a #pragma linkage directive enables the compiler to generate and accept parameter lists, using a linkage convention known as OS linkage. Although functionally different, both calling an assembler routine and being called by one are handled by the same #pragma. Its format is shown below, where identifier is the name of the assembler function to be called from C or the C function to be called from assembler. The #pragma linkage directive must occur before the call to the entry point.

  #pragma linkage(identifier, OS)

- Under C++, a linkage specifier enables the compiler to generate and accept parameter lists, using a linkage convention known as OS linkage. Although functionally different, both calling an assembler routine and being called by one are handled by the same linkage specifier. The format of the linkage specifier is shown below, where flux desc is the name of the OS entry point:

  extern "OS" {
    fn1 desc;
    fn2 desc;
    ...
  }

Note: For C and C++, in XPLINK compiled code, the OS_UPSTACK and OS_NOSTACK (or OS31_NOSTACK) linkages are used for declaring the linkage convention of a routine that the C or C++ code is calling. You cannot define C or C++ entry points as having OS_NOSTACK linkage. You define C or C++ entry points with OS_UPSTACK linkage by compiling the translation units containing them with the NOXPLINK compiler option. In NOXPLINK compiled code, the OS_DOWNSTACK linkage is used to declare the linkage convention for a routine that the C or C++ code is calling. You define C or C++ entry points with OS_DOWNSTACK linkage by compiling the translation units containing them with the XPLINK compiler option.

Just as C (or C++) linkage programs can call OS linkage programs, OS linkage programs can call C linkage programs. An example of C linkage calling OS linkage, which in turn calls C linkage (in this case, one of the z/OS XL C/C++ library functions) is shown in Figure 48 on page 255.

In general, any type that can be passed between C and assembler can also be passed between C++ and assembler. However, if a C++ class that uses features not available to assembler (such as virtual functions, virtual base classes, private and protected data, or static data members) is passed to assembler, the results will be undefined.

Note: In C++, a structure is just a class declared with the keyword struct. Its members and base classes are public by default. A union is a class declared with the keyword union its members are public by default, and it holds only one member at a time.

Parameter lists for OS linkage

A parameter list for OS linkage is a list of pointers. The most significant bit of the last parameter in the parameter list is turned on by the compiler when the list is created.
If a parameter is an address-type parameter, the address itself is directly stored into the parameter list. Otherwise, a copy is created for a value parameter and the address of this copy is stored into the parameter list.

The type of a parameter is specified by the prototype of a function. In the absence of a prototype, the creation of a parameter list is determined by the types of the actual parameters passed to the function. Figure 44 shows an example of the parameter list for OS linkage.

In the list, the first and third parameters are value parameters, and the second is an address parameter.

```
R1
   ptr of P1 copy
   P2
   ptr of P3 copy
   ...
   copy of P1
   copy of P3
```

Figure 44. Example of parameter lists For OS linkages

**XPLINK Assembler**

The XPLINK support provided by the assembler macros EDCXPRLG and EDCXEPLG allows XPLINK C and C++ code to call routines that can be coded for performance, or to perform a function that can not be readily done in C/C++. The EDCXCALL macro allows XPLINK assembler to call routines in the same program object, or in a DLL. The following z/OS Language Environment books provide more information on XPLINK that may be useful to assembler programmers:

- **z/OS Language Environment Programming Guide** — provides an overview of XPLINK and what it means to the application programmer. It also describes the Language Environment assembler support, including the CEEPDDA and CEEPLDA macros, which can be used to define and reference data from assembler.
- **z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications** — provides information on how assembler routines interact with routines coded in other high level languages.
- **z/OS Language Environment Debugging Guide** — provides details on XPLINK, including information on building parameter lists for calling other XPLINK routines.

Coding XPLINK assembler routines differs from traditional non-XPLINK assembler in the following ways:

- You use the EDCXPRLG and EDCXEPLG macros for entry/exit code, and the EDCXCALL macro to call other routines. These are documented in the section "Using standard macros" on page 249.
- You use the following XPLINK register conventions within the XPLINK assembler routine:
- XPLINK parameter passing conventions: Registers 1, 2, and 3 are used to pass up to the first 3 integral values, and floating point registers will be used to pass floating point parameters.

- XPLINK DSA format: Note that the stack register (reg 4) is “biased”. This means that you must add 2K (2048) to the stack register to get the actual start of the current routine’s DSA. The z/OS Language Environment mapping macro CEEDSA contains a mapping of the XPLINK DSA, including the 2K bias (CEEDSAHP_BIAS). The caller’s registers are saved in the DSA obtained by the callee. The callee’s parameters (other than those passed in registers, if any), are built in the argument list in the callers DSA, and addressed there directly by the callee. There is no indirect access to the parameters via Register 1 as in OS linkage.

- While EDCXPRLG and EDCXEPLG allow Language Environment conforming XPLINK assembler routines to be written, another alternative for XPLINK C/C++ callers is to designate the linkage as OS31_NOSTACK. For more information on OS31_NOSTACK see Chapter 19, “Using Linkage Specifications in C or C++,” on page 239. When the C/C++ caller designates the assembler routine as OS31_NOSTACK linkage, the assembler code can be written without using EDCXPRLG or EDCXEPLG (or any other Language Environment prolog or epilog macros). This can only be done when the assembler code has no dynamic stack storage requirements. With OS31_NOSTACK, standard OS linkage rules apply:
  - Register 1 will be used to point to the parameter list.
  - Register 13 will point to an 18 word savearea, provided to the callee for saving and restoring registers.
  - Register 14 will be the return address for branching back to the caller.
  - Register 15 will contain the address of the callee.

Table 36 shows the layout of the XPLINK interface. See z/OS Language Environment Vendor Interfaces for additional information about register usage and conventions, especially for details about passing parameters with XPLINK. For information on the registers which are saved in the register savearea of the XPLINK stack frame see z/OS Language Environment Programming Guide.

| Table 36. Comparison of non-XPLINK and XPLINK register conventions |
|----------------|----------------|
| **Non-XPLINK** | **XPLINK**      |
| Stack Pointer  | Reg 13          |
| Return Address | Reg 14          |
| Entry point on entry | Reg 15         |
| Environment    | Reg 0 (writeable static) |
| CAA Address    | Reg 12          |
| Input Parameter List | address in R1 |
| Return code    | Reg 15          |
| Start address of callee’s stack frame | Caller’s NAB value |
| End address of callee’s stack frame | Caller’s NAB value + DSA size |
Table 36. Comparison of non-XPLINK and XPLINK register conventions (continued)

<table>
<thead>
<tr>
<th>Where caller's registers are saved</th>
<th>Non-XPLINK</th>
<th>XPLINK</th>
</tr>
</thead>
<tbody>
<tr>
<td>R0-R12 saved in caller's stack frame</td>
<td>• R0 not saved, not preserved</td>
<td></td>
</tr>
<tr>
<td>R13 saved in callee's stack frame</td>
<td>• R3 not saved, not preserved</td>
<td></td>
</tr>
<tr>
<td>R14-R15 saved in caller's stack frame</td>
<td>• R4 not saved, recalculated (or saved, restored)</td>
<td></td>
</tr>
<tr>
<td>R0 not saved, not preserved</td>
<td>• R5 not saved, not preserved</td>
<td></td>
</tr>
<tr>
<td>R1-R3 not saved, not preserved</td>
<td>• R6 saved in callee's stack frame, not restored</td>
<td></td>
</tr>
<tr>
<td>R4 not saved, recalculated (or saved, restored)</td>
<td>• R7-R15 saved in callee's stack frame (R7 is the return register and is not guaranteed to be restored)</td>
<td></td>
</tr>
</tbody>
</table>

Using standard macros

To communicate properly, assembler routines must preserve the use of certain registers and particular storage areas, in a way that is consistent with code from the C or C++ compiler. z/OS XL C/C++ provides macros for use with assembler routines. These macros are in CEE.SCEEMAC. The High-Level Assembler for MVS & VM & VSE must be used when assembling with these macros. The macros are:

- **EDCPRLG**
  - Generates the prolog for non-XPLINK assembler code
- **EDCEPIL**
  - Generates the epilog for non-XPLINK assembler code
- **EDCXPRLG**
  - Generates the prolog for XPLINK assembler code
- **EDCXCALL**
  - Generates a call from XPLINK assembler code
- **EDCXEPLG**
  - Generates the epilog for XPLINK assembler code
- **EDCDSAD**
  - Accesses automatic memory in the non-XPLINK stack. For the XPLINK stack, use the CEEDSA macro, described in z/OS Language Environment Programming Guide.

EDCPRLG, the old version of EDCPRLG, is shipped for compatibility with Version 1 of C/370 and is unchanged. However, you should use EDCPRLG if you can.

The advantage of writing assembler code using these macros is that the assembler routine will then participate fully in the z/OS XL C/C++ environment, enabling the assembler routine to call z/OS XL C/C++ functions. The macros also manage automatic storage, and make the assembler code easier to debug because the z/OS Language Environment control blocks for the assembler function will be displayed in a formatted traceback or dump. See the Debug Tool documentation, which is available at http://www-01.ibm.com/software/awdtools/debugtool/library/, for further information on z/OS Language Environment tracebacks and dumps.

Non-XPLINK assembler prolog

Use the EDCPRLG macro to generate non-XPLINK assembler prolog code at the start of assembler routines.
name is inserted in the prolog. It is used in the processing of certain exception conditions and is useful in debugging and in reading memory dumps. If name is absent, the name of the current CSECT is used.

**USRDSAL=ulen**

Is used only when automatic storage (in bytes) is needed. To address this storage, see the EDCDSAD macro description. The ulen value is the requested length of the user space in the DSA.

**BASEREG=register**

Designates the required base register. The macro generates code needed for setting the value of the register and for establishing addressability. The default is Register 3. If register equals NONE, no code is generated for establishing addressability.

**DSALEN=dlen**

Is the total requested length of the DSA. The default is 120. If fewer than 120 bytes are requested, 120 bytes are allocated. If both dlen and ulen are specified, then the greater of dlen or ulen+120 is allocated. If DSALEN=NONE is specified, no code is generated for DSA storage allocation, and R13 will still point to the caller's DSA. Therefore, you should not use the EDCEPIL macro to terminate the assembler routine. Instead, you have to restore the registers yourself from the current DSA. To do this, you can use an assembler instruction such as

```
LM 14,12,12(R13)
BR 14
```

You should not use EDCDSAD to access automatic memory if you have specified DSALEN=NONE, since DSECT is addressable using R13.

### Non-XPLINK assembler epilog

Use the EDCEPIL macro to generate non-XPLINK assembler epilog code at the end of assembler routines. Do not use this macro in conjunction with an EDCPRLG macro that specifies DSALEN=NONE.

**name** is the optional name operand, which then becomes the label on the exit from this code. The name does not have to match the prolog.

### XPLINK Assembler prolog

Use the EDCXPRLG macro to generate XPLINK assembler prolog code at the start of assembler routines.
name  If ENTNAME=epname is specified then name is used as the name of the
XPLINK entry marker, else name is the name of the entry point and name#C
is used as the name of the XPLINK entry marker.

DSASIZE=len
Specifies automatic storage requirements (in bytes). Specify a len of 0 if the
XPLINK assembler routine is a leaf routine with no automatic storage
requirements. XPLINK leaf routines must preserve registers 4, 6, and 7
throughout their execution. This is a required parameter, the minimum size
of an XPLINK DSA (80 bytes) or more must be specified if DSASIZE is not
zero. The length will be rounded up, if necessary, to a multiple of 32-bytes.

PARMWRDS=numwrds
Specifies the number of 4-byte words in the input parameter list. If this is
omitted, then the routine will be treated as vararg, and it will adversely
affect performance if the call to this routine results in a stack overflow. This
parameter is required if mixing XPLINK and non-XPLINK routines so that
the glue code that switches between linkage conventions on a call can
correctly pass the parameters. If this is omitted, then a call from a
non-XPLINK caller to an XPLINK Assembler routine will abend with
message CEE3584E.

ENTNAME=epname
Is the optional name of the XPLINK assembler routine entry point.

BASEREG=register
Designates the required base register. The macro generates code needed for
setting the value of the register and for establishing addressability. The
default is register 8. If register equals NONE, no code is generated for
establishing addressability.

PSECT=pname
Is the name to be assigned to the XPLINK assembler routine PSECT area.
For more information about the PSECT area see HLASM Language Reference.

GT2KSTK=YES
If GT2KSTK=YES is specified, then an unconditional “large stack frame”
prolog will be used that checks for the XPLINK stack floor in the CAA,
instead of depending on the write-protected guard page. This parameter
must be specified if the len on the DSASIZE parameter is greater than 2048
(i.e. 2K).

EXPORT=NO
If EXPORT=NO is specified, then this function is not exported. In this case,
this function can be called only from other functions that are link-edited in
the same program object with this function.

If EXPORT=YES is specified, then this function is to be exported when
link-edited into a DLL. With this function exported from the DLL, it can be
called from functions outside of the containing program object. If you want
the exported name to be a long name and/or mixed case, follow the EDCXPRLG macro with an ALIAS statement. For example:

```
EDCXCALL entry-name [, (parm1, ...)] WORKREG=reg
```

name Optional label beginning in column 1.

**entry-name**

Specifies the entry name of the program to be given control. This entry name can reside in the same program object, or can be an exported DLL function.

[, (parm1, ...)]

One or more parameters to be passed to the called program. The parameters are copied to the argument area in the calling program’s DSA, and then GPRs 1, 2, and 3 are loaded with the first three words of this argument area. Sufficient space must be reserved in the caller’s argument area to contain the largest possible parameter list. A minimum of 4 words (16 bytes) must always be allocated for the argument area. Use the

**Note:** If you specify EXPORT=YES, then you must use the GOFF assembler option. For the entry point to be available as an exported DLL function, you must specify the DYNAM(DLL) binder option, and the resulting program object must reside in a PDSE or the UNIX file system.

### XPLINK Call

Use the EDCXCALL macro to pass control from an XPLINK assembler program to a control section at a specified entry point. It is meant to be used in conjunction with the EDCXPRLG and EDCXEPLG macros. The target of EDCXCALL can be resolved either statically (link-edited with the same program object) or dynamically (imported from a DLL).

The EDCXCALL macro does not generate any return codes. Return information may be placed in GPR 3 (and possibly GPRs 2 and 1, or the Floating Point Registers) by the called program, as specified by XPLINK linkage conventions. The EDCXCALL macro does not support extended return types. For more information, refer to **z/OS Language Environment Vendor Interfaces**.

GPRs 0, 1, 2, 3, 5, 6, and 7 are not preserved by this macro.
DSASIZE= parameter on the EDCXPRLG prolog macro to ensure that the calling program’s DSA is large enough. At this time, the EDCXCALL macro only supports passing parameters by reference.

WORKREG=
A numeric value representing a general purpose register between 8 and 15, inclusive, that can be used as a work register by this macro. Its contents will not be preserved.

Notes:
1. This macro requires that the calling routine’s XPLINK environment address is in register 5 (as it was when the routine was first invoked).
2. This macro requires that a PSECT was defined by the EDCXPRLG prolog macro.
3. This macro requires the GOFF assembler option.
4. This macro requires the binder to link-edit, and the RENT and DYNAM(DLL) binder options. You will also need the CASE(MIXED) binder option if the entry-name is mixed case.
5. The output from the binder must be a PM3 (or higher) format program object, and therefore must reside in either a PDSE or the UNIX file system.

Figure 46 shows an XPLINK assembler example (program CCNGCA9) that calls an XPLINK routine named Xif1 where no parameters are passed.

Figure 46. Call to an XPLINK routine with no parameters

* Call to an XPLINK routine with no parameters
ADLAXIF1 EDCXPRLG DSASIZE=DSASZ,PSECT=ADLAXIFP
* R3 EQU 3 RETURN VALUE
* WTO ‘ADLAXIF1: Calling imported XPLINK function Xif1’, X ROUTCDE=11
* EDCXCALL Xif1,WORKREG=10
* SR R3,R3 RETURN DS 0H
* EDCXEPLG
* LTORG
CEEDSAHP CEEDSA SECTYPE=XPLINK
MINARGA DS 4F
DSASZ EQU +-CEEDSAHP_FIXED
END ADLAXIF1

Figure 46. Call to an XPLINK routine with no parameters

Figure 46 (program CCNGCA10) is an XPLINK assembler example that calls a function with 5 parameters.
XPLINK Assembler epilog

Use the EDCXEPLG macro to generate XPLINK assembler epilog code at the end of assembler routines. This macro must always be used with a matching EDCXPRILG macro, even if the EDCXPRILG macro specified DSASIZE=0.

```
* Call to an XPLINK routine with 5 parameters
ADLAXIF7 EDCXPRLG DSASIZE=DSASZ,PSECT=ADLAXIFP
*
R3 EQU 3  RETURN VALUE
*
  WTO 'ADLAXIF7: Calling imported XPLINK function Xif7 passing parameters (15,33,"Hello world",45.2,9).', X
  ROUTCDE=11
*  EDCXCALL Xif7,(PARM1,PARM2,PARM3,PARM4,PARM5),WORKREG=10
*  SR R3,R3
RETURN DS 0H
EDCXEPLG
*
LTORG
PARM1 DC FL4'15'
PARM2 DC FL2'33'
PARM3 DC 'Hello world'
PARM4 DC X'00'
PARM5 DC D'45.2'
CEEDSAHP CEEDSA SECTYPE=XPLINK
ARGAREA DS 5F
DSASZ EQU *CEEDSAHP_FIXED
END ADLAXIF7

Figure 47. Call to an XPLINK routine with 5 parameters
```

Accessing automatic memory in the non-XPLINK stack

Use the EDCDSAD macro to access automatic memory in the non-XPLINK stack. Automatic memory is reserved using the USRDSAL, or the DSASLEN operand of the EDCPRILG macro. The length of the allocated area is derived from the `ulen` and/or `dlen` values specified on the EDCPRILG macro. EDCDSAD generates a DSECT, which reserves space for the stack frame needed for the C or C++ environment.
name  Is the optional name operand, which then becomes the name of the generated DSECT.

The DSECT is addressable using Register 13. Register 13 is initialized by the prolog code. If you have specified DSALEN=NONE with EDCPRLG you should not use EDCDSAD.

The Language Environment mapping macro CEEDSA can be used to map a DSA, either non-XPLINK or XPLINK or both.

There are other SECTYPE operands. SECTYPE=XPLINK will only produce an XPLINK DSA mapping. For more information on CEEDSA see z/OS Language Environment Programming Guide.

Calling C code from Assembler — C example

This section shows samples of how to C code from assembler. There are three parts to this example.

The first code example (CCNGCA4) shown in Figure 48 is a trivial C routine that establishes the C runtime environment.

```c
/* this example demonstrates C/Assembler ILC */
/* part 1 of 3 (other files are CCNGCA2, CCNGCA5) */
/* in this example, the code in CCNGCA4 invokes CCNGCA2, */
/* which in turn invokes CCNGCA5 */
/* you can use EDCCBG to do the compile and bind, but */
/* you must include the objects from CCNGCA2 and CCNGCA5 */

#pragma linkage(CALLPRTF, OS)

int main(void) {
    CALLPRTF();
    return(0);
}
```

Figure 48. Establishing the C runtime environment

The second part, shown in Figure 49 on page 256 is the assembler routine (CNGCA2). It calls an intermediate C function that invokes a runtime library function.
Finally in this example (CCNGCA5), the intermediate C routine calls a runtime library function, as shown in Figure 50.

The following C++ example shows how to call library routines from assembler. There are three parts to this example.

The first part (CCNGCA1), shown in Figure 51 on page 257, is a trivial XL C/C++ routine that establishes the XL C/C++ runtime environment. It uses extern OS to indicate the OS linkage and calls the assembler routine.
The second part (CCNGCA2), shown in Figure 52, is the assembler routine. It calls an intermediate XL C/C++ routine that invokes a runtime library function.

```
// this example demonstrates C++/Assembler ILC
// part 1 of 3 (other files are CCNGCA2, CCNGCA3)
extern "OS" int CALLPRTF(void);
int main(void) {
    CALLPRTF();
}
```

Figure 51. Establishing the XL C/C++ runtime environment

The second part (CCNGCA2), shown in Figure 52, is the assembler routine. It calls an intermediate XL C/C++ routine that invokes a runtime library function.

```
* this example demonstrates ILC with Assembler (part 2 of 3)
CALLPRTF CSECT
   EDCPRLG
   LA  1,ADDR_BLK parameter address block in r1
   L   15,=V(@PRINTF4) address of routine
   BALR 14,15 call it
   EDEPIL
ADDR_BLK DC A(FMTSTR) parameter address block with...
   DC A(X'00000000'+INTVAL) ..high bit on the last address
FMTSTR DC C'Sample formatting string'
   DC C' which includes an int -- %d --'
   DC ALL(NEWLINE,NEWLINE)
   DC C'and two newline characters'
   DC ALL(NULL)
* INTVAL DC F'222' The integer value displayed
* NULL EQU X'00' C NULL character
NEWLINE EQU X'15' C \n character
END
```

Figure 52. Calling an intermediate XL C/C++ function from Assembler using OS linkage

The third part of the example (CCNGCA3), shown in Figure 53, is an intermediate XL C/C++ routine that calls a runtime library function.

```
// this example demonstrates XL C/C++/Assembler ILC
// part 3 of 3 (other files are CCNGCA1, CCNGCA2)

// This routine is an interface between assembler code
// and the runtime library function printf(). OS linkage
// will not tolerate C-style variable length parameter lists,
// so this routine is specific to a formatting string
// and a single 4-byte substitution parameter. It's
// specified as an int here.
#include <stdio.h>
#pragma map(_printf4, "PRINTF4")

extern "OS" int _printf4(char *str,int i) {
    return printf(str,i); // call runtime library function
}
```

Figure 53. Intermediate XL C/C++ routine calling a runtime library function
Register content at entry to a non-XPLINK ASM routine using OS linkage

When control is passed to an assembler routine that uses OS linkage, the contents of the registers are as follows:

R0  Undefined.
R1  Points to the parameter list. The parameter list consists of a vector of addresses, each of which points to an actual parameter. The address of the last parameter has its high-order bit set on, to indicate the end of the list.
R2 to R11  Undefined.
R12  Points to an internal control block. It can be used by the called routine but must be restored to its entry value if it calls a routine that expects z/OS Language Environment.
R13  Points to the caller’s DSA. Part of the DSA is used by EDCPRLG and EDCEPIL to save and restore registers. EDCPRLG can change R13 so that it points to the called routine’s DSA from the caller’s DSA.
R14  The return address.
R15  The address of the entry point being called.

Register content at exit from a non-XPLINK ASM routine to z/OS XL C/C++

Registers have the following content when control returns to the point of call; all other floating point registers are undefined:

R0  Undefined.
R1  Undefined.
R2 to R13  Must be restored to entry values. This is done by EDCEPIL and EDCPRLG.
R14  Return address.
R15  Return value for integer types (long int, short int, char) and pointer types. Otherwise set to 0.
FP0  Returns value for float or double parameters.
FP0  Returns value if long double is passed.
FP2  Returns value if long double is passed.

Note: When in FLOAT(AFP) mode the callee must save and restore FPR’s 8 through 15.

Retaining the C environment using preinitialization

If an assembler routine called the same C or C++ program repeatedly, the creation and termination of the C/C++ environment for each call would be inefficient. The solution is to create the C/C++ environment only once by preinitializing the C or C++ program. The Language Environment preinitialization (CEEPIPI) services are the strategic form of preinitialization. For information on the Language
Environment preinitialization (CEEPPI) services, see z/OS Language Environment Programming Guide. This section discusses the z/OS XL C preinitialization interface only for reasons of compatibility.

Notes:
1. This information pertains only to users of C programs.
2. XPLINK applications are not supported under Preinitialized Compatibility Interface (PICI) environments.
3. POSIX(ON) is not supported under PICI environments.
4. AMODE 64 applications are not supported under PICI environments.

If you are calling a C program multiple times from an assembler program, you can establish the C environment and then repeatedly invoke the C program using the already established C environment. You incur the overhead of initializing and terminating the C environment only once instead of every time you invoke the C program.

Because C detects programs that can be preinitialized dynamically during initialization, you do not have to recompile the program or link-edit it again.

To maintain the C environment, you start the program with the C entry CEESTART, and pass a special Extended Parameter List that indicates that the program is to be preinitialized.

When you use preinitialization, you are initializing the library yourself with the INIT call and terminating it yourself with the TERM call. In a non-preinitialized program, the library closes any files you left open and releases storage. It does not do this in a preinitialized program. Therefore, for every invocation of your preinitialized program, you must release all allocated resources as follows:
- Close all files that were opened
- Free all allocated storage
- Release all fetched modules

If you do not release all allocated resources, you will waste memory.

**Setting up the interface for preinitializable programs**

The interface for preinitializing programs is shown in [Figure 54 on page 260](#).
The LL field is a halfword containing the value of 16. The halfword that follows must contain 0 (zero).

The Request field is 8 characters that can contain the following values; no other values are valid.

'INIT'

Initializes the C environment and, returns two tokens that represent the
environment, but does not run the program. Token 1 and token 2 must both have the value of zero on an INIT call; otherwise, preinitialization fails.

You can initialize only one C environment at a time. However, you can make the sequence of calls to INIT, CALL, and TERM more than once.

CALL

Runs the C program using the environment established by the INIT request, and exits from the environment when the program completes. The CALL request uses the two tokens that were returned by the INIT request so that C can recognize the proper environment.

You can also initialize and call a C program by passing the CALL parameter with two zero tokens. The C program processes this request as an INIT followed by a CALL. You can still call the program repeatedly, but you should pass the two zero tokens only on the first call. Once the C environment is initialized, the values of the tokens are changed, and must not be modified on any subsequent calls.

Calling a C program other than the one used to initialize the C environment is not supported, especially if write-able static is needed by the program being called. This is because write-able static was allocated and initialized based upon the program used to initialize the C environment.

TERM

Terminates the C environment but does not run the program. The program used to terminate the C environment should be the same as the program used to initialize the C environment. Usage of a different program to terminate the C environment is unsupported.

EXECUTE

Performs INIT, CALL, and TERM in succession.

The Extended PLIST address field is a pointer to the Extended Parameter List (EPL). The EPL is a vector of fullwords that consists of:

Length of extended parameter list
The length includes the 4 bytes for the length field. Valid decimal values are 20, 28, and 32.

First and second C environment tokens
These tokens are automatically returned during initialization; or, you can use zeros for them when requesting a preinitialized CALL, and the effect is that both an INIT and a CALL are performed.

Pointer to your program parameters
The layout of the parameters is shown in Figure 54 on page 260 Interface for Preinitialization Programs. If no parameter is specified, use a fullword of zeros.

Pointer to your runtime options
To point to the character string of runtime options, refer to Figure 54 on page 260. The character string consists of a halfword LL field that contains the length of the list of runtime options, followed by the actual list of runtime options.

Pointer to an alternative main
This field is not supported in C. However, if you want to use the seventh or eighth fields, use a full word of zeros as a place holder.

Pointer to the service vector
If you want certain services (such as load and delete) to be carried out by
Request modifier code

When your request is INIT, CALL, or EXECUTE, you can specify any of the following request modifier codes:

0  Does not change the request.
1  Loads all common library modules as part of the preinitialized environment.
2  Loads all common and C library modules as part of the preinitialized environment.
3  Reinitializes the environment. If the environment is already established, frees all HEAP storage and any ISA overflow segments. Do not use this code if subsequent calls depend on storage that is still being allocated by previous calls.
4  Allows you to create more than one environment. The new environment is chained with existing request modifier 4 environments or a batch environment, where possible, so that C memory file sharing among the environments is possible. Details on chaining and C memory file sharing support are covered in "Multiple preinitialization compatibility interface C environments" on page 270.

The user-supplied service routine vector is not supported when you use request modifier value 4 in the extended parameter list. Do not code this if you are using the service routine vector. If you do, an abnormal end will occur.

5  Allows you to create more than one environment. The new environment is separated from other environments which may already exist. This environment does not support sharing of C memory files with other preinitialization compatibility interface environments.

When your request is TERM, you can specify either of the following request modifier codes:

0  Does not change the request.
1  Forces termination. Ends the C environment without any of the usual checks. Code this field only when you cannot request normal termination. You must ensure that the environment you are forcing to end is not in use.

The length you specify in the first field of the extended parameter list makes it known whether you have specified a request modifier code or not.

Runtime options are applied only at initialization and remain until termination. You must code PLIST(MVS) in the called C program in order for the preinitialization to work.

The options ARGPARSE|NOARGPARSE have no effect on preinitialized programs. The assembler program has to provide parameters in the form expected by the C program. Thus, if the C program is coded for the NOARGPARSE option, the argc should be set to 2, and parameters passed as a single string.
Preinitializing a C program

Figure 55 on page 264 is a sample preinitialized C program that shows how to do
the following:

• Establish the C environment using an INIT request
• Pass runtime parameters to the C initialization routine
• Set up a parameter to the C program
• Repeatedly call a C program using the CALL request
• Communicate from the C program to the driving program using a return code
• End the C program using the TERM request

The parameters it expects are the file name in argv[1] and the return code in argv[2]. The C program printf()s the value of the return code, writes a record to the file name, and decrements the value in return code.

The assembler program that drives the C program establishes the C environment and repeatedly invokes the C program, initially passing a value of 5 in the return code. When the return code set by the C program is zero, the assembler program terminates the C environment and exits.

Program CCNGCA6 (Figure 55 on page 264) does not include the logic that would verify the correctness of any of the invocations. Such logic is imperative for proper operations.
CCNGCA6 TITLE 'TESTING PREINITIALIZED C PROGRAMS'

***-------------------------------------------------------------
*** this example shows how to preinitialize a C program
*** part 1 of 3 (other files are CCNGCA7 and CCNGCA8)
*** Function: Demonstrate the use of Preinitialized C programs
*** Requests used: INIT, CALL, TERM
*** Parameters to C program: FILE_NAME, RUN_INDEX
*** Return from C Program: RUN_INDEX
***-------------------------------------------------------------

CCNGCA6 CSECT
CCNGCA6 RMODE ANY
CCNGCA6 AMODE ANY
EXTRN CEESTART C Program Entry
STM R14,R12,12(R13) Save registers
BALR R3,0 Set base register
USING *,R3 Establish addressability
ST R13,SVAR+4 Set back chain
LA R13,SVAR Set this module's save area

***-------------------------------------------------------------
*** Initialize
***-------------------------------------------------------------
P_INIT DS 0H
MVC P_RQ,INIT Set INIT as the request
LA R1,PALIPT Load Parameter pointer
L R15,CEP Load C Entry Point
BALR R14,R15 Invoke C Program

***-------------------------------------------------------------
*** The C environment has been established.
*** Parameters include RUN_INDEX which will be counted down
*** by the C program. When the RUN_INDEX is zero, termination
*** will be requested.
*** The following code will set up C program parameters and
*** CALL request, invoke the C program and test for termination.
***-------------------------------------------------------------

LA R1,PGPAPT Pointer to C program parameters
ST R1,EP_PGPAP ... to extended parameter list
DO_CALL DS 0H
MVC P_RQ,CALL set up CALL request
LA R1,PALIPT set parameter pointer
L R15,CEP set entry point
BALR R14,R15 invoke C program
L R0,RUN_INDEX Test Return Code
LTR R0,R0
BNZ DO_CALL Repeat CALL

***-------------------------------------------------------------
*** C requested termination.
*** Set up TERM request and terminate the environment
***-------------------------------------------------------------

DO_TERM DS 0H
MVC P_RQ,TERM set up TERM request
SR R1,R1 mark no parameters
ST R1,EP_PGPAP
LA R1,PALIPT set parameter pointer
L R15,CEP set entry point
BALR R14,R15 invoke termination

Preinitializinga C program (CCNGCA6) (Part 1 of 3)

Figure 55. Preinitializing a C program (CCNGCA6)
Preinitializing a C program (CCNGCA6) (Part 2 of 3)
Preinitializing a C program (CCNGCA6) (Part 3 of 3)

Program CCNGCA7 (Figure 56) shows how to use the preinitializable program.

_FILE *fp; /* File to be written to */
int *ptr_run; /* Pointer to the "run index" */
char *fmsg; /* a pointer to the "fetched function msg" */
char fname[MAX_FNAME+1]; /* name of the function to be fetched */
i int fetch_rc; /* Return value of function invocation */
f_ptr fetch_ptr; /* Function pointer to fetched function */

/* Get the pointer to the "run index" */
ptr_run = (int *)argv[2];
if ((fp = fopen(argv[1],"a")) == NULL) {
    printf("Cannot open file %s\n",argv[1]);
    *ptr_run = 0; /* Set to zero so it won't be called again */
    return(0); /* Return to Assembler program */
}

Using the preinitializable program (CCNGCA7) (Part 1 of 2)
/* Write the record to the file */
fprintf(fp,"Run index was %d.
",*ptr_run);

/* Allocate the message returned from the fetched function */
if (ffmsg=(char *)malloc(MAX_MSG + 1) == NULL)
  printf("ERROR -- malloc returned NULL\n");

/* fetch the function */
fetch_ptr = (f_ptr) fetch("MYFUNC");
if (fetch_ptr == NULL)
  printf("ERROR - Fetch returned a null pointer\n");

/* execute the function */
fetch_rc = fetch_ptr(*ptr_run, ffmsg); /* Write the function msg to file */
fprintf(fp,"%s
",ffmsg);

/* Tell the user the value of the "run index" */
printf("Run index was %d.
",*ptr_run);

/* Decrement the "run index" */
(*ptr_run)--;

/* Remember to close all opened files */
fclose(fp);

/* Remember to free all allocated storage */
free( fname );

/* Remember to release all fetched modules */
release((void(*)())fetch_ptr);

/* Return to Assembler program */
return(0);
}

Using the preinitializable program (CCNGCA7) (Part 2 of 2)

Finally, Figure 57 shows sample program CCNGCA8.

/* this example shows how to use a preinitializable program */
/* part 3 of 3 (other files are CCNGCA6 & CCNGCA7) */
#include <string.h>
#pragma linkage(fetched, fetchable)

int fetched(int run_index, char *ffmsg) {
  sprintf(ffmsg,"Welcome to myfunc: Run index was %d.*,run_index);
  return(0);
}

Figure 57. Using the preinitializable program (CCNGCA8)

Return codes
Preinitialized programs do not put their return codes in R15. If the address of the return code is required, specify a parameter. Figure 55 on page 264 shows how you can use the RUN_INDEX parameter to evaluate the address of a return code.
User exits in preinitializable programs
C invokes user exits when initialization and termination are actually performed. That is, the initialization user exit is invoked during the INIT request or the CALL with the zero token request. Similarly, the termination user exit is called only during the TERM request.

Runtime options
If runtime options are specified in the assembler program, the C program must be compiled with EXECOPS in effect. EXECOPS is the default.

Calling a preinitializable program
Figure 58 on page 269 shows sample JCL to run a preinitializable program in the z/OS environment.
JCL for running a preinitializable C program (Part 1 of 2)

Figure 58. JCL for running a preinitializable C program
Multiple preinitialization compatibility interface C environments

To establish multiple Preinitialized Compatibility Interface (PICI) environments, you must specify either request modifier 4 or request modifier 5 in the extended parameter list (EPL) at environment initialization.

Request modifier 4 environment characteristics

Use request modifier 4 to establish an environment which is tolerant of an existing environment. When a request modifier 4 environment is dormant, it is immune to creation or termination of other environments.

Environments created using request modifier 4 normally intend to share C memory files, but it is not required for the application to take advantage of this support. A new environment of this type is chained to the currently active environment that supports chaining, or it will set up a dummy environment which supports chaining. This allows for C memory files to be shared.

The sharing of C memory files across request modifier 4 environments is only supported within the boundary of the application. There are really only two types of applications where request modifier 4 environments are involved. The first type is a set of pure request modifier 4 environments; there are no batch environments. The second type allows a single batch environment. In the second type, the batch environment must be the first initialized and the last terminated.

If starting with non z/OS Language Environment enabled assembler, the first request modifier 4 environment creates a dummy environment (z/OS Language Environment region-level control blocks) in addition to its own. The dummy environment remains pointed to by the TCB when the initialization is complete. The next initialization using request modifier 4 recognizes an existing environment that supports chaining and the new environment will be chained. This permits the two environments to share C memory files. Request modifier 4 environments in this model can be initialized and terminated in any order.

If starting with a batch environment (for example, COBOL, PL/I or C), which supports chaining by default, and during execution within that environment a call is made to an assembler routine which initializes a request modifier 4 environment, the z/OS Language Environment batch environment is recognized and the new environment will be chained. This allows an initial batch environment to share C memory files with the request modifier 4 environment. Request modifier 4
environments in this model can be initialized and terminated in any order, but all request modifier environments must be terminated before the batch environment is terminated.

Notes:

1. When a batch environment is chained with request modifier 4 environments, the z/OS Language Environment batch environment must be the first environment that is initialized and the last environment that is terminated. All request modifier 4 environments initialized within the scope of a batch environment must be terminated prior to exiting the batch environment. Failure to do so will leave the request modifier 4 environments in a state such that attempted call or termination requests will result in unpredictable behavior.

2. Initialization of a request modifier 4 environment while running in a non-sharable environment, such as a request modifier 5 environment, causes the new request modifier 4 environment to be non-sharable.

Sharing C memory files with request modifier 4 environments: You can use request modifier 4 to create multiple Preinitialized Compatibility Interface (PICI) C environments. When you create a new request modifier 4 environment, it is chained under certain circumstances to the current environment.

The following list identifies the specific features that are or are not supported in the multiple PICI C environment scenario:

- C memory files will be shared across all C environments (as long as at least one C environment exists) that are on the chain. This includes all PICI C environments that are initialized and possibly an initial batch C environment.

- Because the PICI C environments are chained, initialization and termination of these PICI C environments can be performed in any order. The chaining also requires that the C runtime library treat each PICI C environment as equal. In C runtime library terms, each PICI C environment is considered a root enclave (depth=0).

- Because there can be multiple C root enclaves, sharing of C standard streams across the C root enclaves exhibits a special behavior. When a C standard stream is referenced for the first time, its definition is made available to each of the C root enclaves.

- C standard streams are inherited across the system() call boundary. When a PICI C environment is initialized from a nested enclave, it does not inherit the standard streams of the nested enclave. Instead, it shares the C standard stream definitions at the root level.

- C regular (nonmemory, nonstandard stream) files are also shared across the PICI C environments.

- Nested C enclaves are created using the system() call. The depth is relative to the root enclave that owns the system() call chain. You can have two C enclaves, other than the C root enclaves, with the same depth. You can do this by calling one of the PICI C environments from a nested enclave and then using system() in the PICI C environment.

- C regular (nonmemory, nonstandard stream) files opened in a system() call enclave are closed automatically when the enclave ends.

- C regular (nonmemory, nonstandard stream) files that are opened in a PICI C environment root enclave are not closed automatically until the PICI C environment ends. Before returning to the caller, you should close streams that are opened by the PICI C environment. If you do not, undefined behavior can occur.
- C memory files are not removed until the last PICI C environment is ended.
- The clrmemf() function will only remove C memory files created within the scope of the C root enclave from which the function is called.
- When a PICI C environment is called, flushing of open streams is not performed automatically as it is when you use the system() call.
- This function is not supported under CICS.
- This function is not supported under System Programming C (SP C).
- Use of POSIX(ON) is not supported with this feature.

**Request modifier 5 environment characteristics**
Use request modifier 5 to establish an environment that is tolerant of an existing environment. When a request modifier 5 environment is dormant, it is immune to creation or termination of other environments. Request modifier 5 environments cannot share C memory files with other environments. Each environment of this type is created as a separate entity, not connected to any other environment. Request modifier 5 environments can be initialized and terminated in any order.

**Restrictions on using batch environments with preinitialization compatibility interface C environments**
If a batch environment is to participate in C memory file sharing, such as with a request modifier 4 environment, then the batch environment must be the first environment created and the last one terminated. All PICI environments initialized within the scope of the batch environment must be terminated before the batch environment is terminated. This is required because the PICI environment shares control blocks that belong to the batch environment. If the batch environment is terminated, storage for those control blocks is released. Attempts to use or terminate a PICI environment after the batch environment has terminated will result in unpredictable behavior.

**Behaviors when mixing request modifier 4 and request modifier 5**
While running in a request modifier 5 environment, initializing another environment with request modifier 4 creates a new environment that is separated from the rest. The new environment will not be able to share C memory files with any other request modifier 4 environment that may already exist.

While running in a request modifier 4 environment, initialization of a request modifier 5 environment creates a new environment that is separated from the rest. If the new request modifier 5 environment is within the scope of a batch environment, this new environment does not need to be terminated before the batch environment is terminated.

**Using the service vector and associated routines**
The service vector is a list of addresses of user-supplied service routines. The interface requirements for each of the service routines that you can supply, including sample routines for some of the services, are provided in the following sections.

**Using the service vector**
If you want certain services like load and delete to be carried out by other programs supplied by you (instead of, for example, by the LOAD and DELETE macros), you must place the address of your service vector in the seventh fullword field of the extended parameter list. Define the service vector according to the pattern shown in the following example. Although you need not use labels identical to these, you must use the same order. The address of your load routine
is "fourth", and the address of your free-storage routine is "seventh".

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>SRV_COUNT DS F</td>
<td>Count of fields defined</td>
<td></td>
</tr>
<tr>
<td>SRV_USER_WORD DS F</td>
<td>User-defined word</td>
<td></td>
</tr>
<tr>
<td>SRV_WORKAREA DS A</td>
<td>Addr of work area for DSAs etc</td>
<td></td>
</tr>
<tr>
<td>SRV_LOAD DS A</td>
<td>Addr of load routine</td>
<td></td>
</tr>
<tr>
<td>SRV_DELETE DS A</td>
<td>Addr of delete routine</td>
<td></td>
</tr>
<tr>
<td>SRV_GETSTOR DS A</td>
<td>Addr of get-storage routine</td>
<td></td>
</tr>
<tr>
<td>SRV_FREESTOR DS A</td>
<td>Addr of free-storage routine</td>
<td></td>
</tr>
<tr>
<td>SRV_EXCEP_RTR DS A</td>
<td>Addr of exception router</td>
<td></td>
</tr>
<tr>
<td>SRV_ATTN_RTR DS A</td>
<td>Addr of attention router</td>
<td></td>
</tr>
<tr>
<td>SRV_MSG_RTR DS A</td>
<td>Addr of message router</td>
<td></td>
</tr>
</tbody>
</table>

Some other constraints apply:
- You cannot omit any fields on the template that precede the last one you specify from your definition of the service vector. You can supply zeros for the ones you want ignored.
- The field count does not count itself. The maximum value is, therefore, 9.
- You must specify an address in the work area field if you specify addresses in any of the subsequent fields.
- This work area must begin on a doubleword boundary and start with a fullword that specifies its length. This length must be at least 256 bytes.
- For the load and delete routines, you cannot specify one of the pair without the other; if one of these two fields contains a value of zero, the other is automatically ignored. The same is true for the get-storage and free-storage pair.
- If you specify the get-storage and free-storage services, you must also specify the load and delete services.

You must supply any service routines pointed to in your service vector. When called, these service routines require the following:
- Register 13 points to a standard 18-fullword save area.
- Register 1 points to a list of addresses of parameters available to the routine.
- The third parameter in the list must be the address of the user word you specified in the second field of the service vector.

The parameters available to each routine, and the return and reason codes that each routine uses, are shown in the following section. The parameter addresses are passed in the same order in which the parameters are listed.

**Load service routine**

The load routine loads named modules. The LOAD macro usually provides this service. The parameters passed to the load routine are shown in Table 37.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address of module name</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Length of name</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>User word</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>(Reserved field)</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>Address of load point</td>
<td>DS A</td>
<td>Output</td>
</tr>
<tr>
<td>Size of module</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>
Table 37. Load service routine parameters (continued)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>

The name length must not be zero. You can ignore the reserved field. It will contain zeros. The load routine can set the following return/reason codes:

- 0/0 successful
- 4/4 unsuccessful — module loaded above line when in AMODE 24
- 8/4 unsuccessful — load failed
- 16/4 unrecoverable error occurred

**Delete service routine**

The delete routine deletes named modules. The `DELETE` macro usually provides this service. The parameters passed to the delete routine are shown in Table 38.

Table 38. Delete service routine parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address of module name</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Length of name</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>User word</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>(Reserved field)</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>

The name length must not be zero. You can ignore the reserved field. It will contain zeros. Every delete action must have a corresponding load action, and the task that does the load must also do the delete. Counts of deletes and loads performed must be maintained by the service routines.

The delete routine can set the following return/reason codes:

- 0/0 successful
- 8/4 unsuccessful — delete failed
- 16/4 unrecoverable error occurred

**Get-storage service routine**

The get-storage routine obtains storage. The `GETMAIN` macro usually provides this service. The parameters passed to the get-storage routine are shown in Table 39.

Table 39. Get-storage service routine parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Amount desired</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>Subpool number</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>User word</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Flags</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>Address of obtained storage</td>
<td>DS A</td>
<td>Output</td>
</tr>
<tr>
<td>Amount obtained</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>
### Table 39. Get-storage service routine parameters (continued)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>

The get-storage routine can set the following return/reason codes:

- **0/0** successful
- **4/4** unsuccessful — the storage could not be obtained
- **16/4** unrecoverable error occurred.

**Note:** If this routine does not preserve the high registers across the call, Language Environment may not preserve the high registers of the assembler driver program across the call to Language Environment.

### Free-storage service routine

The free-storage routine frees storage. The **FREEMAIN** macro usually provides this service. The parameters passed to the free-storage routine are shown in **Table 40**.

### Table 40. Free-storage service routine parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Amount to be freed</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>Subpool number</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>User word</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Address of storage</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>

The free-storage routine can set the following return/reason codes:

- **0/0** successful
- **16/4** unrecoverable error occurred

**Note:** If this routine does not preserve the high registers across the call, Language Environment may not preserve the high registers of the assembler driver program across the call to Language Environment.

### Exception router service routine

The exception router traps and routes exceptions. The **ESTAE** and **ESPIE** macros usually provide this service. The parameters passed to the exception router are shown in **Table 41**.

### Table 41. Exception router service routine parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address of exception handler</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Environment token</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>User word</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Abend flags</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>Check flags</td>
<td>DS F</td>
<td>Input</td>
</tr>
</tbody>
</table>
During initialization, if the ESTAE and/or ESPIE options are in effect, the common library puts the address of the common library exception handler in the first field of the above parameter list, and sets the environment token field to a value that is passed on to the exception handler. It also sets abend and check flags as appropriate, and then calls your exception router to establish an exception handler.

The meaning of the bits in the abend flags are given by the following structure:

```c
struct {
    struct {
        unsigned short abends : 1, /*control for system abends*/
        reserved : 15;
    } system;
    struct {
        unsigned short abends : 1, /*control for user abends*/
        reserved : 15;
    } user;
} abendflags;
```

The meaning of the bits in the check flags are given by the following structure:

```c
struct {
    struct {
        unsigned short reserved : 1,
        operation : 1,
        privileged_operation : 1,
        execute : 1,
        protection : 1,
        addressing : 1,
        specification : 1,
        data : 1,
        fixed_overflow : 1,
        fixed_divide : 1,
        decimal_overflow : 1,
        decimal_divide : 1,
        exponent_overflow : 1,
        exponent_divide : 1,
        significance : 1,
        float_divide : 1;
    } type;
    unsigned short reserved;
} checkflags;
```

The exception router service routine can set the following return/reason codes:

- **0/0** successful
- **4/4** unsuccessful — the exit could not be (de)-established
- **16/4** unrecoverable error occurred

**Notes:**
1. If the passed-in SDWA from the PICI exception router service routine to the common library exception handler does not contain valid high registers, the
"HR_VALID" flag bit in the Machine State "FLAGS" field will be off, indicating that the saved high registers are not valid.

2. If a nested enclave ends because of an unhandled condition and a 4094-40 ABEND is declared, the high registers may not be valid in the Machine State that contains information about the 4094-40 ABEND.

3. If registers in the passed-in SDWA at the time of interrupt (in the SDWAGRVS field) are not appropriate or recognizable, and Language Environment saves the registers from the SDWASRSV field in the Machine State instead, the high registers may not be valid in the Machine State.

**Attention router service routine**

The attention router traps and routes attention interrupts. The STAX macro usually provides this service. The parameters passed to the attention router are shown in Table 42.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address of attention router</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Environmental token</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>User word</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>

The attention router routine can set the following return/reason codes:

- 0/0 successful
- 4/4 unsuccessful — the exit could not be (de)-established
- 16/4 unrecoverable error occurred

When an attention interrupt occurs, your attention router must invoke the attention handler. Use the address in the attention handler field passing the parameters shown in Table 43.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Environment token</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>

The return/reason codes upon return from the attention handler are:

- 0/0 The attention interrupt has been or will be handled

If an attention interrupt occurs in the attention handler or when an attention handler is not started, your attention router should ignore the attention interrupt.

**Message router service routine**

The message router routes messages written by the runtime library. These messages are usually written to the Language Environment Message File. The parameters passed to the message router are shown in Table 44 on page 278.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Environment token</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>
Table 44. Message router service routine parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>ASM Attributes</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address of message</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Message length in bytes</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>User word</td>
<td>DS A</td>
<td>Input</td>
</tr>
<tr>
<td>Line length</td>
<td>DS F</td>
<td>Input</td>
</tr>
<tr>
<td>Return code</td>
<td>DS F</td>
<td>Output</td>
</tr>
<tr>
<td>Reason code</td>
<td>DS F</td>
<td>Output</td>
</tr>
</tbody>
</table>

If the address of the message is zero, your message router is expected to return the size of the line to which messages are written (in the length field). The length field allows messages to be formatted correctly, for example, broken at blanks. The message routine must use the following return/reason codes:

0/0    successful
16/4    unrecoverable error occurred
Part 4. Coding: Advanced Topics

This part contains the following coding topics:

- Chapter 21, “Building and using Dynamic Link Libraries (DLLs),” on page 281
- Chapter 22, “Building complex DLLs,” on page 301
- Chapter 23, “z/OS 64-bit environment,” on page 325
- Chapter 24, “Using threads in z/OS UNIX applications,” on page 353
- Chapter 25, “Reentrancy in z/OS XL C/C++,” on page 369
- Chapter 26, “Using decimal data types in C,” on page 377
- Chapter 27, “IEEE Floating-Point,” on page 397
- Chapter 28, “Handling error conditions, exceptions, and signals,” on page 403
- Chapter 29, “Network communications under UNIX System Services,” on page 425
- Chapter 30, “Interprocess communication using z/OS UNIX,” on page 453
- Chapter 31, “Using templates in C++ programs,” on page 457
- Chapter 32, “Using environment variables,” on page 467
- Chapter 33, “Using hardware built-in functions,” on page 505
- Chapter 36, “ANSI C/C++ 98 applications and C99,” on page 677
- Chapter 38, “Saved compile-time options information,” on page 687
Chapter 21. Building and using Dynamic Link Libraries (DLLs)

A dynamic link library (DLL) is a collection of one or more functions or variables in an executable module that is executable or accessible from a separate application module. In an application without DLLs, all external function and variable references are resolved statically at bind time. In a DLL application, external function and variable references are resolved dynamically at run time.

This chapter defines DLL concepts and shows how to build simple DLLs. Chapter 22, “Building complex DLLs,” on page 301 shows how to build complex DLLs and discusses some of the compatibility issues of DLLs.

There are two types of DLLs: simple and complex. A simple DLL contains only DLL code in which special code sequences are generated by the compiler for referencing functions and external variables, and using function pointers. With these code sequences, a DLL application can reference imported functions and imported variables from a DLL as easily as it can non-imported ones.

A complex DLL contains mixed code, that is, some DLL code and some non-DLL code. A typical complex DLL would contain some C++ code, which is always DLL code, and some C object modules compiled with the NODLL compiler option bound together.

The object code generated by the z/OS XL C++ compiler is always DLL code. Also, the object code generated by the z/OS XL C compiler with either the DLL compiler option or the XPLINK compiler option is DLL code. Other types of object code are non-DLL code. For more information about compiler options for DLLs, see the z/OS XL C/C++ User’s Guide.

XPLINK compiled code and non-XPLINK compiled code cannot be statically mixed (with the exception of OS_UPSTACK and OS_NOSTACK (or OS31_NOSTACK) linkages). The XPLINK compiled code can only be bound together with other XPLINK-compiled code. You can mix non-XPLINK compiled DLLs with XPLINK compiled DLLs (the same is true for routines which you load with fetch()). The z/OS XL C++ runtime library manages the transitions between the two different linkage styles across the DLL and fetch() boundaries.

Notes:

1. There is inherent performance degradation when the z/OS XL C++ runtime library transitions across these boundaries. In order for your application to perform well, these transitions should be made infrequently. When using XPLINK, recompile all parts of the application with the XPLINK compiler option wherever possible.

2. As of z/OS V1R9, all support for the C/C++ IBM Open Class® Library is removed. For new code and enhancements to existing applications, the Standard C++ Library should be used.
Support for DLLs

DLL support is available for applications running under the following systems:

- z/OS batch
- CICS
- IMS
- TSO
- z/OS UNIX

It is not available for applications running under SPC, CSP or MTF.

**Note:** All potential DLL executable modules are registered in the CICS PPT control table in the CICS environment and are invoked at run time.

### DLL concepts and terms

[Table 45](#) summarizes important concepts and terminology about DLLs.

#### Table 45. Summary of DLL concepts and terms

<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Application</td>
<td>All the code executed from the time an executable program module is invoked until that program, and any programs it directly or indirectly calls, is terminated.</td>
</tr>
<tr>
<td>DLL</td>
<td>An executable module that exports functions, variable definitions, or both, to other DLLs or DLL applications.</td>
</tr>
<tr>
<td>DLL application</td>
<td>An application that references imported functions, imported variables, or both, from other DLLs.</td>
</tr>
<tr>
<td>DLL code</td>
<td>Object code resulting when C source code is compiled with the DLL or XPLINK compiler options. C++ code is always DLL code.</td>
</tr>
</tbody>
</table>
| Executable program (or executable module) | A file that can be loaded and executed on the computer. z/OS supports two types:  
  **Load module**  
  An executable residing in a PDS.  
  **Program object**  
  An executable residing in a PDSE or in the UNIX file system. |
| Exported functions or variables | Functions or variables that are defined in one executable module and can be referenced from another executable module. When an exported function or variable is referenced within the executable module that defines it, the exported function or variable is also non-imported. |
| Function descriptor           | An internal control block containing information needed by compiled code to call a function.                                              |
| Imported functions and variables | Functions and variables that are not defined in the executable module where the reference is made, but are defined in a referenced DLL.   |
| Non-imported functions and variables | Functions and variables that are defined in the same executable module where a reference to them is made.                          |
| Object code (or object module) | A file output from a compiler after processing a source code module, which can subsequently be used to build an executable program module. |
| Source code (or source module) | A file containing a program written in a programming language.                                                                           |
Table 45. Summary of DLL concepts and terms (continued)

<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Variable descriptor</td>
<td>An internal control block containing information about the variable needed by compiled code.</td>
</tr>
<tr>
<td>Writable Static Area (WSA)</td>
<td>An area of memory that is modifiable during program execution. Typically, this area contains global variables and function and variable descriptors for DLLs.</td>
</tr>
<tr>
<td>XPLINK application</td>
<td>An application that is made up of C and/or C++ object modules that were compiled with the XPLINK compiler option. XPLINK applications are always DLL applications. Since the C/C++ runtime library for XPLINK is packaged as a DLL, any XPLINK executable module that calls a C/C++ runtime library is also importing from a DLL.</td>
</tr>
<tr>
<td>XPLINK code</td>
<td>Object code resulting when C or C++ source code is compiled with the XPLINK compiler option. XPLINK code is always DLL code.</td>
</tr>
</tbody>
</table>

**Loading a DLL**

A DLL is loaded implicitly when an application references an imported variable or calls an imported function. DLLs can be explicitly loaded by calling `d11load()` or `dlopen()`. Due to optimizations performed, the DLL implicit load point may be moved and the DLL will be loaded only if the actual reference occurs.

**Loading a DLL implicitly**

When an application uses functions or variables defined in a DLL, the compiled code loads the DLL. This implicit load is transparent to the application. The load establishes the required references to functions and variables in the DLL by updating the control information contained in function and variable descriptors.

If the DLL contains static classes, constructors are run when the DLL is loaded. This loading may occur before `main();` in this case, the corresponding destructors are run once when `main()` returns.

To implicitly load a DLL, do one of the following:
1. Statically initialize a variable pointer to the address of an exported DLL variable.
2. Reference a function pointer that points to an exported function.
3. Call an exported function.
4. Reference (use, modify, or take the address of) an exported variable.
5. Call through a function pointer that points to an exported function.

In the first situation, the DLL is loaded before `main()` is invoked, and if the DLL contains C++ code, constructors are run before `main()` is invoked. In the other situations, the DLL loading may be delayed until the time of the implicit call, although optimization may move this load earlier.

If the DLL application references (imports) an exported DLL variable, that DLL may be implicitly loaded before that DLL application is invoked (not necessarily before `main()` is invoked). With XPLINK, the DLL will always be implicitly loaded before invoking the DLL application that references (imports) a DLL variable or takes the address of a DLL function.
Note: When a DLL is loaded, its writable static is initialized. If the DLL load module contains C++ code, static constructors are run once at initial load time, and static destructors are run once at program termination. Static destructors are run in the reverse order of the static constructors.

Loading a DLL explicitly

The use of DLLs can also be explicitly controlled by the application code at the source level. The application uses explicit source-level calls to one or more runtime services to connect the reference to the definition. The connections for the reference and the definition are made at run time.

The DLL application writer can explicitly call the following runtime services:

- `dllload()` which loads the DLL and returns a handle to be used in future references to this DLL
- `dllqueryfn()` which obtains a pointer to a DLL function
- `dllqueryvar()` which obtains a pointer to a DLL variable
- `dllfree()` which frees a DLL loaded with `dllload()`

The following runtime services are also available as part of the Single UNIX Specification, Version 3:

- `dlopen()`, which loads the DLL and returns a handle to be used in future references to this DLL
- `dlsym()`, which obtains a pointer to an exported function or exported variable
- `dlclose()`, which frees a DLL that was loaded with `dlopen()`
- `dlerror()`, which returns information about the last DLL failure on this thread that occurred in one of the `dlopen()` family of functions

While you can use both families of explicit DLL services in a single application, you cannot mix usage across those families. So a handle returned by `dllload()` can only be used with `dllqueryfn()`, `dllqueryvar()`, or `dllfree()`. And a handle returned by `dlopen()` can only be used with `dlsym()` and `dlclose()`.

Because the `dlopen()` family of functions is part of the Single UNIX Specification, Version 3, it should be used in new applications whenever cross-platform portability is a concern.

For more information about the runtime services, see z/OS XL C/C++ Runtime Library Reference.

To explicitly call a DLL in your application:

- Determine the names of the exported functions and variables that you want to use. You can get this information from the DLL provider's documentation or by looking at the definition side-deck file that came with the DLL. A definition side-deck is a directive file that contains an IMPORT control statement for each function and variable exported by that DLL.
- If you are using the `dllload()` family of functions, include the DLL header file `<dll.h>` in your application. If you are using the `dlopen()` family of functions, include the DLL header file `<dlfcn.h>` in your application.
- Compile your source as usual.
- Bind your object with the binder using the same AMODE value as the DLL.
Note: You do not need to bind with the definition side-deck if you are calling the DLL explicitly with the runtime services, since there are no references from the source code to function or variable names in the DLL, for the binder to resolve. Therefore the DLL will not be loaded until you explicitly load it with the dllload() or dlopen() runtime service.

Examples of explicit use of a DLL in an application

The following examples show explicit use of a DLL in an application. The first example in Figure 59 uses the dllload() family of functions.

```c
#include <dll.h>
#include <stdio.h>
#include <string.h>
#ifdef __cplusplus
extern "C" {
#endif

typedef int (DLL_FN)(void);
#ifdef __cplusplus
}
#endif
#define FUNCTION "FUNCTION"
#define VARIABLE "VARIABLE"

static void Syntax(const char* progName) {
    fprintf(stderr, "Syntax: %s <DLL-name> <type> <identifier>
    where
    <DLL-name> is the DLL to load,
    <type> can be one of FUNCTION or VARIABLE
    and <identifier> is the function or variable
    to reference
", progName);
    return;
}

main(int argc, char* argv[]) {
    int value;
    int* varPtr;
    char* dll;
    char* type;
    char* id;
    dllhandle* dllHandle;
    if (argc != 4) {
        Syntax(argv[0]);
        return(4);
    }
    dll = argv[1];
    type = argv[2];
    id = argv[3];
    dllHandle = dllload(dll);
    if (dllHandle == NULL) {
        perror("DLL-Load");
        fprintf(stderr, "Load of DLL %s failed
", dll);
        return(8);
    }
}

Explicit use of a DLL in an application using the dllload() family of functions (Part 1 of 2)

Figure 59. Explicit use of a DLL in an application using the dllload() family of functions
if (strcmp(type, FUNCTION)) {
    if (strcmp(type, VARIABLE)) {
        fprintf(stderr,
            "Type specified was not " FUNCTION " or " VARIABLE "\n";
        Syntax(argv[0]);
        return(8);
    }
    /*
     * variable request, so get address of variable
     */
    varPtr = (int*)dllqueryvar(dllHandle, id);
    if (varPtr == NULL) {
        perror("DLL-Query-Var");
        fprintf(stderr, "Variable %s not exported from %s\n", id, dll);
        return(8);
    }
    value = *varPtr;
    printf("Variable %s has a value of %d\n", id, value);
} else {
    /*
     * function request, so get function descriptor and call it
     */
    DLL_FN* fn = (DLL_FN*) dllqueryfn(dllHandle, id);
    if (fn == NULL) {
        perror("DLL-Query-Fn");
        fprintf(stderr, "Function %s() not exported from %s\n", id, dll);
        return(8);
    }
    value = fn();
    printf("Result of call to %s() is %d\n", id, value);
    dllfree(dllHandle);
    return(0);
}

Explicit use of a DLL in an application using the dllload() family of functions (Part 2 of 2)

Figure 60 on page 287 shows an example that uses the dlopen() family of functions.
#define _UNIX03_SOURCE
#include <dlfcn.h>
#include <stdio.h>
#include <string.h>
#ifdef __cplusplus
extern "C" {
#endif

typedef int (DLL_FN)(void);
#ifdef __cplusplus
}
#endif
#define FUNCTION "FUNCTION"
#define VARIABLE "VARIABLE"

static void Syntax(const char* progName) {
    fprintf(stderr, "Syntax: %s <DLL-name> <type> <identifier>\n"    where\n    <DLL-name> is the DLL to open,\n    <type> can be one of FUNCTION or VARIABLE,\n    and <identifier> is the symbol to reference\n    (either a function or variable, as determined by"
    <type>)\n", progName);
    return;
}

main(int argc, char* argv[]) {
    int value;
    void* symPtr;
    char* dll;
    char* type;
    char* id;
    void* dllHandle;

    if (argc != 4) {
        Syntax(argv[0]);
        return(4);
    }

    dll = argv[1];
    type = argv[2];
    id = argv[3];
    dllHandle = dlopen(dll, 0);
    if (dllHandle == NULL) {
        fprintf(stderr, "dlopen() of DLL %s failed: %s\n", dll, dlerror());
        return(8);
    }

    Explicit use of a DLL in an application using the dlopen() family of functions (Part 1 of 2)

    Figure 60. Explicit use of a DLL in an application using the dlopen() family of functions
get address of symbol (may be either function or variable)

```c
symPtr = (int*)dlsym(dllHandle, id);
if (symPtr == NULL) {
    fprintf(stderr, "dlsym() error: symbol %s not exported from %s: %s\n", id, dll, dlerror());
    return(8);
}
if (strcmp(type, FUNCTION)) {
    if (strcmp(type, VARIABLE)) {
        fprintf(stderr, "Type specified was not " FUNCTION " or " VARIABLE "\n";
        Syntax(argv[0]);
        return(8);
    }
    /*
     * variable request, so display its value
     */
    value = *(int *)symPtr;
    printf("Variable %s has a value of %d\n", id, value);
} else {
    /*
     * function request, so call it and display its return value
     */
    value = ((DLL_FN *)symPtr)();
    printf("Result of call to %s() is %d\n", id, value);
} dlclose(dllHandle);
return(0);
```

Explicit use of a DLL in an application using the dlopen() family of functions (Part 2 of 2)

Managing the use of DLLs when running DLL applications

This section describes how z/OS XL C/C++ manages loading, sharing and freeing DLLs when you run a DLL application.

Loading DLLs

When you load a DLL for the first time, either implicitly or by an explicit dllload() or dlopen(), writable static is initialized. If the DLL is written in C++ and contains static objects, then their constructors are run.

You can load DLLs from a UNIX file system as well as from conventional data sets. The following list specifies the order of a search for unambiguous and ambiguous file names.

- **Unambiguous file names**
  - If the file has an unambiguous z/OS UNIX file system name (it starts with a ./ or contains a /), the file is searched for only in the UNIX file system.
  - If the file has an unambiguous MVS name, and starts with two slashes (//), the file is only searched for in MVS.

- **Ambiguous file names**
  For ambiguous cases, the settings for POSIX are checked.
  - When specifying the POSIX(ON) runtime option, the runtime library attempts to load the DLL as follows:
1. An attempt is made to load the DLL from the UNIX file system. This is done using the system service BPX1LOD. For more information on this service, see z/OS UNIX System Services Programming: Assembler Callable Services Reference.

   If the environment variable LIBPATH is set, each directory listed will be searched for the DLL. See Chapter 32, “Using environment variables,” on page 467 for information on LIBPATH. Otherwise the current directory will be searched for the DLL. Note that a search for the DLL in the UNIX file system is case-sensitive.

   - If the DLL is found and contains an external link name of eight characters or less, the uppercase external link name is used to attempt a LOAD from the caller’s MVS load library search order. If the DLL is not found or the external link name is more than eight characters, then the load fails.

   - If the DLL is found and its sticky bit is on, any suffix is stripped off. Next, the name is converted to uppercase, and the base DLL name is used to attempt a LOAD from the caller’s MVS load library search order. If the DLL is not found or the base DLL name is more than eight characters, the version of the DLL in the UNIX file system is loaded.

   - If the DLL is found and does not fall into one of the previous two cases, a load from the UNIX file system is attempted.

2. If the DLL could not be loaded from the UNIX file system, an attempt is made to load the DLL from the caller’s MVS load library search order. This is done by calling the LOAD service with the DLL name, which must be eight characters or less (it will be converted to uppercase). LOAD searches for it in the following sequence:

   a. Runtime library services (if active)
   b. Job Pack Area (JPA)
   c. TASKLIB
   d. STEPLIB or JOBLIB. If both are allocated, the system searches STEPLIB and ignores JOBLIB.
   e. LPA
   f. Libraries in the linklist

   For more information, see z/OS MVS Initialization and Tuning Guide.

   • When POSIX(0FF) is specified the sequence is reversed.

   - An attempt to load the DLL is made from the caller’s MVS load library search order.

   - If the DLL could not be loaded from the caller’s MVS load library then an attempt is made to load the DLL from the UNIX file system.

Recommendation: All DLLs used by an application should be referred to by unique names, whether ambiguous or not. Using multiple names for the same DLL (eg. aliases or symlinks) may result in a decrease in DLL load performance. The use of UNIX file system symbolic links by themselves will not degrade performance, as long as the application refers to the DLL solely through the symbolic link name. To help ensure this, when building an application with implicit DLL references always use the same side deck for each DLL. Also, make sure that explicit DLL references with dl1oad() or dl1open() specify the same DLL name (case matters for UNIX file system loads).

Changing the search order for DLLs while the application is running (eg. changing LIBPATH) may result in errors if ambiguous file names are used.
Sharing DLLs

DLLs are shared at the enclave level (as defined by the z/OS Language Environment). A referenced DLL is loaded only once per enclave and only one copy of the writable static is created or maintained per DLL per enclave. Thus, one copy of a DLL serves all modules in an enclave regardless of whether the DLL is loaded implicitly or explicitly. You can access the same DLL within an enclave both implicitly and by explicit runtime services.

All accesses to a variable in a DLL in an enclave refer to the only copy of that variable. All accesses to a function in a DLL in an enclave refer to the only copy of that function.

Although only one copy of a DLL is maintained per enclave, multiple logical loads are counted and used to determine when the DLL can be deleted. For a given DLL in a given enclave, there is one logical load for each explicit dllload() or dlopen() request. DLLs that are referenced implicitly may be logically loaded at application initialization time if the application references any data exported by the DLL, or the logical load may occur during the first implicit call to a function exported by the DLL.

DLLs are not shared in a nested enclave environment. Only the enclave that loaded the DLL can access functions and variables.

Freeing DLLs

You can free explicitly loaded DLLs with a dllfree() or dlclose() request. This request is optional because the DLLs are automatically deleted by the runtime library when the enclave is terminated.

Implicitly loaded DLLs cannot be deleted from the DLL application code. They are deleted by the runtime library at enclave termination. Therefore, if a DLL has been both explicitly and implicitly loaded, the DLL can only be deleted by the run time when the enclave is terminated.

Creating a DLL or a DLL application

Building a DLL or a DLL application is similar to creating a C or C++ application. It involves the following steps:
1. Writing your source code
2. Compiling your source code
3. Binding your object modules

Building a simple DLL

This section shows how to build a simple DLL in C and C++, using techniques that export externally-linked functions and variables to DLL users. These techniques include:

- The #pragma export directive
- The _Export keyword
- The EXPORTALL compiler option

Both the _Export keyword and the export directive are used to specify functions and variables.
The EXPORTALL compiler option is used to export all defined functions and variables. Using the EXPORTALL compiler option means that all defined functions and variables are accessible by all users of the given DLL.

Notes:
1. If the EXPORTALL compiler option is used, then neither #pragma export nor _Export is required in your code.
2. Exporting all functions and variables has a performance penalty, especially when the IPA compiler option is used to build the DLL.

For more information, see:
- The EXPORTALL compiler option in z/OS XL C/C++ User's Guide
- The _Export keyword in z/OS XL C/C++ Language Reference
- The export directive in z/OS XL C/C++ User's Guide

Example of building a simple C DLL
To build a simple C DLL, use the #pragma export directive to export specific external functions and variables as shown in [Figure 61](#).

```c
#pragma export(bopen)
#pragma export(bclose)
#pragma export(bread)
#pragma export(bwrite)
int bopen(const char* file, const char* mode) {
  ... 
}
int bclose(int) { 
  ... 
}
int bread(int bytes) { 
  ... 
}
int bwrite(int bytes) { 
  ... 
}
#pragma export(berror)
int berror;
char buffer[1024];
... 
```

*Figure 61. Using #pragma export to create a DLL executable module named BASICIO*

This example exports the functions bopen(), bclose(), bread(), bwrite(), and the variable berror. The variable buffer is not exported.

Compiling with the EXPORTALL compiler option would export all the functions and the buffer variable.

Example of building a simple C++ DLL
To build a simple C++ DLL, use the _Export keyword or the #pragma export directive to export specific external functions and variables. Ensure that classes and class members are exported correctly, especially if they use templates.

For example, [Figure 62 on page 292](#) shows how to create a DLL executable module named triangle using the #pragma export directive. This example exports the functions getarea(), getperim(), the static member objectCount, and the...
constructor for class triangle.

class triangle
{
    public:
        static int objectCount;
        getarea();
        getperim();
        triangle( void);
    #pragma export(triangle::objectCount)
    #pragma export(triangle::getarea())
    #pragma export(triangle::getperim())
    #pragma export(triangle::triangle( void))
};

Figure 62. Using #pragma export to create the triangle DLL executable module

Similarly, Figure 63 shows how to create a DLL executable module named triangle using the _Export keyword:

class triangle
{
    public:
        static int _Export objectCount;
        double _Export getarea();
        double _Export getperim();
        _Export triangle::triangle( void);
    };

Figure 63. Using _Export to create the triangle DLL executable module

There are some restrictions when using the _Export keyword.
• Do not inline the function if you apply the _Export keyword to the function declaration, as in Figure 63
• Always export constructors and destructors

If you apply the _Export keyword to a class, then it automatically exports the static members, defined functions, constructors, and destructors of that class, as shown in the following example. This behavior is the same as using the EXPORTALL compiler option.

class triangle
{
    public:
        static int objectCount;
        double getarea();
        double getperim();
        triangle( void);
    };

Compiling your code

For C source code compiled without using the DLL or XPLINK compiler options, that code cannot reference (import) functions or variables that are exported by a DLL. NODLL is the default when compiling C source code, and the XPLINK compiler option is not used. C source code compiled with the DLL or XPLINK compiler options, and all C++ source code, can reference exported functions and variables.
Source code that can reference exported functions and variables is called DLL application code. It need not itself be a DLL, in that it may not itself export any functions or variables.

When compiling DLL application source code, the compiler generates object code in such a way that references to external functions and variables can be resolved statically or dynamically (that is, resolved to a DLL). If you are uncertain whether non-XPLINK C source code references a DLL, you should specify the DLL or XPLINK compiler options. Compiling source code as DLL application code eliminates the potential compatibility problems that may occur when binding DLL application code with non-DLL application code. See Chapter 22, “Building complex DLLs,” on page 301 for more information on compatibility issues.

The decision to use XPLINK needs to be made independently from the decision to build a DLL application. While XPLINK compiled code is always DLL application code, the XPLINK and non-XPLINK function call linkages are different. There is DLL compatibility for XPLINK and non-XPLINK at the DLL boundary, but XPLINK and non-XPLINK object modules cannot be mixed in the same DLL. Also, there is a performance penalty when transitioning between XPLINK and non-XPLINK DLLs (and vice versa). It is best to have a DLL application made up of all XPLINK or all non-XPLINK executable modules to the extent that is possible. For more information on XPLINK, see “Using the XPLINK option” on page 731.

**Binding your code**

When creating a DLL, the binder automatically creates a definition side-deck that describes the functions and the variables that can be imported by DLL applications. You must provide the generated definition side-deck to all users of the DLL. Any DLL application that implicitly loads the DLL must include the definition side-deck when they bind. For information about creating a side-deck, refer to “Binding z/OS XL C/C++ programs” in z/OS XL C/C++ User’s Guide.

**Note:** You can choose to store your DLL in a PDS load library, but only if it is non-XPLINK. Otherwise, it must be stored in a PDSE load library or in the UNIX file system. To target a PDS load library, prelink and link your code rather than using the binder. For information on prelinking and linking, see Prelinker and linkage editor options in z/OS XL C/C++ User’s Guide.

When binding the C object module as shown in Figure 61 on page 291, the binder generates the following definition side-deck:

```
IMPORT CODE,BASICIO,'bopen'
IMPORT CODE,BASICIO,'bclose'
IMPORT CODE,BASICIO,'bread'
IMPORT CODE,BASICIO,'bwrite'
IMPORT DATA,BASICIO,'berror'
```

**Note:** You should also provide a header file containing the prototypes for exported functions and external variable declarations for exported variables.

When binding the C++ object modules shown in Figure 62 on page 292, the binder generates the following definition side-deck:
You can edit the definition side-deck to remove any functions and variables that you do not want to export. You must maintain the file as a binary file with fixed format and a record length of 80 bytes. Also, use proper binder continuation rules if the IMPORT statement spans multiple lines, and you change the length of the statement. In the above example, if you do not want to expose getperim(), remove the control statement IMPORT CODE,TRIANGLE,'getperim__8triangleFv' from the definition side-deck.

Notes:
1. Removing functions and variables from the definition side-deck does not minimize the performance impact caused by specifying the EXPORTALL compiler option.
2. Editing the side-deck is not recommended. If the DLL name needs to be changed, you should bind using the appropriate name. Instead of using the EXPORTALL compiler option, you should remove unnecessary IMPORT statements by using explicit #pragma export statements or _Export directives.

The definition side-deck contains mangled names of exported C++ functions, such as getarea__8triangleFv. To find the original function or variable name in your source module, review the compiler listing, the binder map, or use the CXXFILT utility, if you do not have access to the listings. This will permit you to see both the mangled and demangled names. For more information, see filter utility in z/OS XL C/C++ User’s Guide.

Building a simple DLL application

A simple DLL application contains object modules that are made up of only DLL-code. The application may consist of multiple source modules. Some of the source modules may contain references to imported functions, imported variables, or both.

Steps for using an implicitly loaded DLL in your simple DLL application

About this task

Perform the following steps to use an implicitly loaded DLL (sometimes called a load-on-call DLL) in your simple DLL application:

Procedure
1. Write your code as you would if the functions were statically bound.
2. Compile as follows:
   - Compile your non-XPLINK application C source files with the following compiler options:
     - DLL
     - RENT
     - LONGNAME
These options instruct the compiler to generate special code when calling functions and referencing external variables. If you are using z/OS UNIX, RENT and LONGNAME are already the defaults, so compile as:

c89 -W c,DLL ...

- Compile your C++ source files normally. A C++ application is always DLL code.
- For XPLINK, compile your C and C++ source files with the XPLINK compiler option. XPLINK compiled C and C++ source is always DLL code.

3. Bind your object modules as follows:

- If you are using z/OS Batch, use the IBM-supplied procedure when you bind your object modules. You must chose the appropriate procedures for XPLINK or non-XPLINK.
- If you are not using the IBM-supplied procedure, specify the RENT, DYNAM(DLL), and CASE(MIXED) binder options when you bind your object modules.

**Note:** XPLINK and non-XPLINK use different z/OS Language Environment libraries, and XPLINK requires the C runtime library side-deck for resolution of C runtime library function calls. For more information, see “Planning to Link-Edit and Run” in z/OS Language Environment Programming Guide.

- If you are using z/OS UNIX specify the following option for the bind step for c89 or c++.

c89 -W l,DLL

If you are using XPLINK, also add the XPLINK option, so that the c89 utility will use the correct z/OS Language Environment libraries and side-decks:

c89 -W l,DLL,XPLINK ...

- Include the definition side-deck from the DLL provider in the set of object modules to bind. The binder uses the definition side-deck to resolve references to functions and variables defined in the DLL. If you are referencing multiple DLLs, you must include multiple definition side-decks.

**Note:** Definition side-decks can not be resolved by automatic library call (autocall) processing, so you must specify an INCLUDE statement to explicitly include a definition side-deck for each referenced DLL.

**Results**

The following code fragment illustrates how an application can use the DLL described previously. Compile normally and bind with the definition side-deck provided with the TRIANGLE DLL.

```c
extern int getarea(); /* function prototype */
main () {
    ...
    getarea(); /* imported function reference */
}
```

See [Figure 64 on page 297](#) for a summary of the processing steps required for the application (and related DLLs).
Creating and using DLLs

Figure 64 on page 297 summarizes the use of DLLs for both the DLL provider and for the writer of applications that use them. In this example, application ABC is referencing functions and variables from two DLLs, XYZ and PQR. The connection between DLL preparation and application preparation is shown. Each DLL shown contains a single compilation unit. The same general scheme applies for DLLs composed of multiple compilation units, except that they have multiple compiles and a single bind for each DLL. For simplicity, this example assumes the following:

- ABC does not export variables or functions.
- XYZ and PQR do not use other DLLs.
- The application is completely non-XPLINK and written in C.
Consider the following restrictions when creating DLLs and DLL applications:

- The entry point for a DLL must be either z/OS XL C/C++ or Language Environment conforming. An entry point is considered Language Environment conforming if it includes CEESTART or if it was compiled using a Language Environment conforming compiler.
Note: If the entry point for a DLL does not meet either of the above conditions, Language Environment issues an error and terminates the application.

- In a DLL application that contains `main()`, `main()` cannot be exported.
- The AMODE of a DLL application must be the same as the AMODE of the DLL that it calls.
- DLL facilities are not available:
  - Under MTB, CSP or SPC
  - To application programs with `main()` written in PL/I that dynamically call z/OS XL C functions
- You cannot implicitly or explicitly perform a physical load of a DLL while running C++ static destructors. However, a logical load of a DLL (meaning that the DLL has previously been loaded into the enclave) is allowed from a static destructor. In this case, references from the load module containing the static destructor to the previously-loaded DLL are resolved.
- If a DLL contains static objects, the constructors are called during DLL load. ISO C++ requires that the global objects must be defined within the same compilation unit, but does not specify any order for these to be called; hence the objects are constructed in the order that they are defined. z/OS XL C/C++ enhances the standard behavior by providing `#pragma priority` to control the construction order for all global objects within the same execution load module. For more information, see the `#pragma priority` in z/OS XL C/C++ Language Reference for the details of this pragma. A DLL is one execution load module and the `#pragma priority` allows you to control global object construction within a single DLL. On the other hand, you still have no control over the initialization order across different DLLs, or across a DLL application and the DLLs it references. If such order is important, the DLL provider has to define a protocol for applications to follow so that the interaction between the DLL and the applications happens in the required manner. The protocol must be part of the DLL interface design. Take note of the restriction in the previous bullet when defining such a protocol. A simple example would be requiring an application to call a `setup()` function, which is exported by a DLL, before any other references to the same DLL are made. More elaborate designs are possible. The techniques for controlling static initialization are well-discussed in C++ literature; you can reference, for example, Item 47 of Scott Meyers's *Effective C++, 50 Specific Ways to Improve Your Programs and Designs.*
- You cannot use the functions `set_new_handler()` or `set_unexpected()` in a DLL if the DLL application is expected to invoke the new handler or unexpected function routines.
- When using the explicit DLL functions in a multithreaded environment, avoid any situation where one thread frees a DLL while another thread calls any of the DLL functions. For example, this situation occurs when a `main()` function uses `d1lload()` or `d1open()` to load a DLL, and then creates a thread that uses the `ftw()` function. The `ftw()` target function routine is in the DLL. If the `main()` function uses `d1lfree()` or `dlclose()` to free the DLL, but the created thread uses `ftw()` at any point, you will get an abend.
  
  To avoid a situation where one thread frees a DLL while another thread calls a DLL function, do either of the following:
  - Do not free any DLLs by using `d1lfree()` or `dlclose()` (the z/OS Language Environment will free them when the enclave is terminated).
  - Have the `main()` function call `d1lfree()` or `dlclose()` only after all threads have been terminated.
- For DLLs to be processed by IPA, they must contain at least one function or method. Data-only DLLs will result in a compilation error.
Use of circular DLLs may result in unpredictable behavior related to the initialization of non-local static objects. For example, if a static constructor (being run as part of loading DLL "A") causes another DLL "B" to be loaded, then DLL "B" (or any other DLLs that "B" causes to be loaded before static constructors for DLL "A" have completed) cannot expect non-local static objects in "A" to be initialized (that is what static constructors do). You should ensure that non-local static objects are initialized before they are used, by coding techniques such as counters or by placing the static objects inside functions.

DLLs are enclave-level resources and, when opening and closing DLLs in a multithreaded environment, an application must control DLL load ordering with its own serialization mechanism to avoid unpredictable results.

**Example:** Unless the application controls the order of DLL loads, unpredictable results can occur when different threads perform the following operations at the same time:

- One thread uses a global symbol object handle, obtained via `dlopen()`, to search for a symbol whose name has been defined in various DLLs with different values.
- Another thread closes the DLL that defines the symbol whose value is being sought.

**Improving performance**

This section contains some hints on using DLLs efficiently. Effective use of DLLs may improve the performance of your application. Following are some suggestions that may improve performance:

- If you are using a particular DLL frequently across multiple address spaces, the DLL can be installed in the LPA or ELPA. When the DLL resides in a PDSE, the dynamic LPA services should be used (this will always be the case for XPLINK applications). Installing in the LPA/ELPA may give you the performance benefits of a single rather than multiple load of the DLL.

- When writing XPLINK applications, avoid frequent calls from XPLINK to non-XPLINK DLLs, and vice-versa. These transitions are expensive, so you should build as much of the application as possible as either XPLINK or non-XPLINK. When there is a relatively large amount of function calls compared to the rest of the code, the performance of an XPLINK application can be significantly better than non-XPLINK. It is acceptable to make calls between XPLINK and non-XPLINK, when a relatively large amount of processing will be done once the call is made.

- Be sure to specify the RENT option when you bind your code. Otherwise, each load of a DLL results in a separately loaded DLL with its own writable static. Besides the performance implications of this, you are likely to get incorrect results if the DLL exports variables (data).

- Group external variables into one external structure.

- When using z/OS UNIX avoid unnecessary load attempts.

  z/OS Language Environment supports loading a DLL residing in the UNIX file system or a data set. However, the location from which it tries to load the DLL first varies depending whether your application runs with the runtime option POSIX(ON) or POSIX(OFF).

  If your application runs with POSIX(ON), z/OS Language Environment tries to load the DLL from the UNIX file system first. If your DLL is a data set member, you can avoid searching the UNIX file system directories. To direct a DLL search to a data set, prefix the DLL name with two slashes (`//`), as shown in the following example.

  //MYDLL
If your application runs with POSIX(OFF), z/OS Language Environment tries to load your DLL from a data set. If your DLL is a UNIX file system file, you can avoid searching a data set. To direct a DLL search to the UNIX file system, prefix the DLL name with a period and slash (/), as shown in the following example.

./mydll

**Note:** DLL names are case sensitive in the UNIX file system. If you specify the wrong case for your DLL that resides in the UNIX file system, it will not be found in the UNIX file system.

- For IPA, you should only export subprograms (functions and C++ methods) or variables that you need for the interface to the final DLL. If you export subprograms or variables unnecessarily (for example, by using the EXPORTALL option), you severely limit IPA optimization. In this case, global variable coalescing and pruning of unreachable or 100% inlined code does not occur. To be processed by IPA, DLLs must contain at least one subprogram. Attempts to process a data-only DLL will result in a compilation error.

- The suboption NOCALLBACKANY of the compiler option DLL is more efficient than the CALLBACKANY suboption. The CALLBACKANY option calls z/OS Language Environment at run time. This runtime service enables direct function calls. Direct function calls are function calls through function pointers that point to actual function entry points rather than function descriptors. The use of CALLBACKANY will result in extra overhead at every occurrence of a call through a function pointer. This is unnecessary if the calls are not direct function calls.
Chapter 22. Building complex DLLs

Before you attempt to build complex DLLs, it is important to understand the differences between the terms DLL, DLL code, and DLL application.

A **DLL** (Dynamic Link Library) is a file containing executable code and data bound to a program at run time. The code and data in a DLL can be shared by several applications simultaneously. It is important to note that compiling code with the DLL option does not mean that the produced executable will be a DLL. To create a DLL, you must use the `#pragma export` or EXPORTALL compiler option.

**DLL code** is code that can use a DLL. The following are DLL code:
- C++ code
- C code compiled using the DLL or XPLINK option

Code written in languages other than C++ and compiled without the DLL or XPLINK option is non-DLL code.

A **DLL application** is an application that can use exported functions or variables that are bound with DLL code. All of the source files that make up a DLL application do not need to be compiled with the DLL or XPLINK option, only the source files that reference exported functions and exported global variables.

If you link DLL code with non-DLL code, the resulting DLL or DLL application is called **complex**. You might compile your code as non-DLL for the following reasons:
- Source modules do not use C or C++.
- To prevent problems which occur when a non-DLL function pointer call uses DLL code. This problem takes place when a function makes a call through a function pointer that points to a function entry rather than a function descriptor.

For complex DLLs and DLL applications that you compile without XPLINK, you can use the CBA suboption of the DLL|NODLL compiler option. With this suboption, a call is made, through a function pointer, to the z/OS Language Environment, for each function call, at run time. This call eliminates the error that would occur when a non-DLL function pointer passes a value to DLL code.

**Note:** In this book, unless otherwise specified, all references to the DLL|NODLL compiler option assume suboption NOCBA. For more information, see the [DLL compiler option](z/OS XL C/C++ User’s Guide).

If you specify the XPLINK compiler option, the CBA and NOCBA suboptions of DLL and NODLL are ignored.

There are two ways to combine XPLINK and non-XPLINK code in the same application:
- Compile each entire DLL with XPLINK or without XPLINK. The only interaction between XPLINK and non-XPLINK code occurs at a DLL or `fetch()` boundary.
- Use the `OS_UPSTACK`, `OS_NOSTACK`, and `OS31_NOSTACK` linkage directive. For more information, see the description of the `linkage` pragma in *z/OS XL C/C++ Language Reference.*
The steps for creating a complex DLL or DLL application are:
1. Determining how to compile your source modules.
2. Modifying the source modules that do not meet all the DLL rules.
3. Compiling the source modules to produce DLL code and non-DLL code as
determined in the previous steps.
4. Binding your DLL or DLL application.

The focus of this chapter is step 1 and step 2. You perform step 3 the same way
you would for any other C or C++ application. “Binding your code” on page 293
explains step 4.

**Rules for compiling source code with XPLINK**

This section provides guidelines for compiling with the XPLINK and NOXPLINK
compiler options. See [XPLINK](#) in z/OS XL C/C++ User’s Guide for the details of this
option.

**XPLINK applications**

XPLINK provides compatibility with non-XPLINK functions when calls are made
across executable modules, using either the DLL or fetch() call mechanism. You
should make a reference from XPLINK code into non-XPLINK code only if the
reference is by an imported function or variable, or the function pointer is a
parameter into the XPLINK code. This prevents incompatible references to a
non-XPLINK function entry point.

Non-XPLINK code can expose a function entry point directly to the XPLINK code:
- as a global variable
- as part of a structure that is passed as a parameter
- by passing an explicit return value

A function pointer from a non-XPLINK application can be used as a callback by
passing it as an argument into the XPLINK function, or as a member of a structure
that is itself an argument to the XPLINK function.

Prior to z/OS V1R8, a function entry point from a non-XPLINK application only
could be passed explicitly as an argument into a XPLINK function. This restriction
did not apply if you used the compiler option XPLINK(CALLBACK) or the
__callback qualifier where any such function pointers were used. Existing DLLs
compiled using one of these options do not need to be recompiled. The use of
these options can only be discontinued if the owner of the XPLink-compiled DLL
is certain that any non-XPLink-compiled DLL callers have been recompiled with
z/OS XL C/C++ V1R8 targeting z/OS Language Environment V1R8 or later, and
those applications are targetted for and running on z/OS Language Environment
V1R8 or later.

Also, note the following restrictions:
- DLLs must be created using the binder.
- C/C++ source modules must be compiled code using the DLL and GOFF
  options without the XPLink or LP64 option.
- Non-XPLink assembler DLLs are not supported.
Modifying noncompliant source

For each function pointer, make sure that one of the following is true:

- The function pointer is passed as a parameter to the XPLINK code.
- The indirectly-referenced function pointer was imported by this DLL.
- The indirectly-referenced function pointer was imported by another XPLINK or non-XPLINK DLL.

Non-XPLINK applications

To create a complex DLL or DLL application, you must comply with the following rules that dictate how you compile source modules. The first decision you must make is how you should compile your code. You determine whether to compile with either the DLL or NODLL compiler option based on whether or not your code references any other DLLs. Even if your code is a DLL, it is safe to compile your code with the NODLL compiler option if your code does not reference other DLLs.

The second decision you must make is whether to compile with the default compiler suboption for DLL | NODLL, which is NOCBA, or use the alternative suboption CBA. This decision is based upon your knowledge of the code you reference. If you are sure that you do not reference any function calls through function pointers that point to a function entry rather than a function descriptor, use the NOCBA suboption. Otherwise, you should use the CBA suboption.

As of V2R4 of OS/390® C/C++, use the following options to ensure that you do not have undefined results as a result of the function pointer pointing to a function entry rather than a function descriptor:

1. Compile your source module with the CBA suboption of DLL | NODLL. This option inserts extra code whenever you have a function call through a function pointer. The inserted code invokes a runtime service of z/OS Language Environment which enables direct function calls through C/C++ function pointers. Direct function calls are function calls through function pointers that point to actual function entry points rather than function descriptors. The drawback of this method is that your code will run slower. This occurs because whenever you have function calls through function pointers z/OS Language Environment is called at run time to enable direct function calls. See Figure 73 on page 312 for an example of the CBA suboption and an explanation of what the called z/OS Language Environment routine does at run time when using the CBA suboption.

2. Compile your C source module with the NOCBA suboption of DLL | NODLL. This option has the benefit of faster running but with more restrictions placed on your coding style. If you do not follow the restrictions, your code may behave unpredictably. See “DLL restrictions” on page 297 for more information.

Compile your C source modules as DLL when:

1. Your source module calls imported functions or imported variables by name.
2. Your source module contains a comparison of function pointers that may be DLL function pointers.

The comparisons shown in “Function pointer comparison in non-DLL code” on page 314 are undefined. To obtain valid comparisons, compile the source modules as DLL code.

3. Your source module may pass a function pointer to DLL code through a parameter or a return value.
If the sort() routine in Figure 72 on page 311 is compiled as DLL code instead of non-DLL code, non-DLL applications can no longer call it. To be able to call the DLL code version of sort(), the original non-DLL application must be recompiled as DLL code.

4. Your source module may define a global function pointer and another source module changes it.

Consider the example programs shown in Table 46. You have the following two options when compiling them.

a. If source module 1 is compiled as DLL code, source module 2 must also be compiled as DLL code.

b. Alternately, you can compile source module 1 as DLL and source module 2 as NODLL(CBA).

### Table 46. Example programs to demonstrate compiling options

<table>
<thead>
<tr>
<th>Source module 1</th>
<th>Source module 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>void (*fp)(void); extern void goo (void); void main() { goo(); (<em>fp); /!</em> call hello function */}</td>
<td>#include &lt;stdio.h&gt; extern void (*fp)(void); void hello(void) { printf(&quot;hello\n&quot;); } void goo(void) { fp = hello;</td>
</tr>
</tbody>
</table>

Table 47 summarizes some of the ways that you could compile the two source modules and list the results. Both modules are linked into a single executable.

### Table 47. Examples of how to compile two source modules and list result

<table>
<thead>
<tr>
<th>How Modules Were Compiled</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Source module 1 NODLL(NOCBA) Source module 2 DLL(NOCBA)</td>
<td>fp contains a function descriptor. Execution of fp will succeed because it is valid to the address of a function descriptor.</td>
</tr>
<tr>
<td>Source module 1 DLL(NOCBA) Source module 2 NODLL(NOCBA)</td>
<td>fp contains the address of hello. The execution of fp would abend because source module 1 expects fp to contain a function descriptor for hello.</td>
</tr>
<tr>
<td>Source module 1 DLL(CBA) Source module 2 DLL(NOCBA)</td>
<td>fp contains a function descriptor. The generated code will function correctly. It will run slower than if the source modules were compiled as DLL(NOCBA) because it will use Language Environment to make the function call.</td>
</tr>
<tr>
<td>Source module 1 NODLL(CBA) Source module 2 DLL(NOCBA)</td>
<td>A call to Language Environment made by the function call through the function pointer prevents a problem that would have occurred had a direct function call been made.</td>
</tr>
</tbody>
</table>

If you do not use the DLL compiler option, and your source module calls imported functions or imported variables by name, there will be unresolved references to these variables and functions at bind time. A DLL or DLL application that does not comply with these rules may produce undefined runtime behavior. For a detailed explanation of incompatibilities between DLL and non-DLL code, see “Compatibility issues between DLL and non-DLL code” on page 305.
Modifying noncompliant source

Sometimes source modules of a complex DLL or DLL application do not simultaneously meet all the DLL rules. These rules are documented in the section “Rules for compiling source code with XPLINK” on page 302. When these situations occur, you can use the following methods to solve the problem:

- Use the CBA suboption.
- Rewrite the source in C. Only C source can be compiled as either DLL or non-DLL code. C++ source code is always DLL code.
- Split a C source module in two so that one of the new files is compiled as DLL code and the other is compiled as non-DLL code.

**Note:** In rare cases, you may have to split a function into two functions before you can successfully split the file.

An example of noncompliant source is a C++ source module that contains a function call through a pointer that may be either a DLL pointer to a function descriptor or a direct function pointer. Convert it to C code and compile as non-DLL code or, preferably, as DLL(CBA) and recompile.

Compatibility issues between DLL and non-DLL code

This section describes the differences between DLL code and non-DLL code, and discusses the related compatibility issues for linking them to create complex DLLs.

**Note:** This section does not apply to XPLINK applications. XPLINK code is always DLL code.

Table 48 and Figure 65 on page 306 illustrate DLL code referencing functions and variables.

<table>
<thead>
<tr>
<th>Function or Variable</th>
<th>DLL</th>
</tr>
</thead>
<tbody>
<tr>
<td>Imported Functions</td>
<td>A function descriptor is created by the binder. The descriptor is in the WSA class and contains the address of the function and the address of the writable static area associated with that function. The function address and the address of the WSA associated with the function is resolved when the DLL is loaded.</td>
</tr>
<tr>
<td>Nonimported Functions</td>
<td>Also called through the function descriptor but the function address is resolved at link time.</td>
</tr>
<tr>
<td>Imported Variables</td>
<td>A variable descriptor is created in the WSA by the binder. It contains addressing information for accessing an imported variable. The address is resolved when the DLL is loaded.</td>
</tr>
<tr>
<td>Nonimported Variables</td>
<td>Direct access</td>
</tr>
</tbody>
</table>
**Pointer assignment**

In DLL code and non-DLL code, the actual address of a variable is assigned to a variable pointer. A valid variable pointer always points to the variable itself and causes no compatibility problems.

**Function pointers**

In non-DLL code, the actual address of a nonimported function is assigned to a function pointer. In DLL code, the address of a function descriptor is assigned to a function pointer.

If you assign the address of an imported function to a pointer in non-DLL code, the link step will fail with an unresolved reference. In a complex DLL or DLL application, a pointer to a function descriptor may be passed to non-DLL code. A direct function pointer (pointer to a function entry point) may be passed to DLL code. A parameter, a return value, or an external variable can pass a function pointer or an external variable.
In a complex DLL or DLL application, a function pointer may point either to a function descriptor or to a function entry, depending on the origin of the code. The different ways of dereferencing a function pointer causes the compatibility problem in linking DLL code with non-DLL code.

In Figure 66, 1 assigns the address of the descriptor for the imported function \( f \) to \( fp \). 2 assigns the address of the imported variable \( x \) to \( xp \). 3 assigns the address of the descriptor for the nonimported function \( g \) to \( gp \). 4 assigns the address of the non-imported variable \( y \) to \( yp \).

In Figure 67 on page 308, 1 causes a bind error because the assignment to \( fp \) is undefined. 2 causes a binder error because the assignment to \( xp \) is undefined. 3 assigns \( gp \) to the address of the nonimported function \( g \). 4 assigns the address of the nonimported variable \( y \) to \( yp \).
DLL function pointer call in non-DLL code

Because z/OS XL C/C++ supports a DLL function pointer call in non-DLL code, you are able to create a DLL to support both DLL and non-DLL applications. The z/OS XL C/C++ compiler inserts glue code at the beginning of a function descriptor to allow branching to a function descriptor. Glue code is special code that enables function pointer calls from non-DLL code to DLL code, including XPLINK code.

A function pointer in non-DLL code points to the function entry and a function pointer call branches to the function address. However, a DLL function pointer points to a function descriptor. A call made through this pointer in non-DLL code results in branching to the descriptor.

z/OS XL C/C++ executes a DLL function pointer call in non-DLL code by branching to the descriptor and executing the glue code that invokes the actual function.
The following examples and Figure 72 on page 311 show a DLL function pointer call in non-DLL code, where a simplified sort() routine is used. Note that the sort() routine compiled as non-DLL code can be called from both a DLL application and a non-DLL application.

C example

File 1 and File 2 are bound together to create application A. File 1 is compiled with the NODLL option. File 2 is compiled with the DLL option (so that it can call the DLL function sort()). File 3 is compiled as DLL to create application B. Application A and B can both call the imported function sort() from the DLL in file 4.

Figure 68 shows how a file (File 1) of a complex DLL application is compiled with the NODLL option.

typedef int CmpFP(int, int);
void sort(int* arr, int size, CmpFP*); /* sort routine in DLL */
void callsort(int* arr, int size, CmpFP* fp); /* routine compiled as DLL */
/* which can call DLL */
/* routine sort() */

int comp(int e1, int e2) {
    if (e1 == e2) {
        return(0);
    } else if (e1 < e2) {
        return(-1);
    } else {
        return(1);
    }
}

main() {
    CmpFP* fp = comp;
    int a[2] = {2,1};
    callsort(a, 2, fp);
    return(0);
}

Figure 68. File 1. Application A

Figure 69 shows how a file (File 2) of a complex DLL application is compiled with the DLL option.

typedef int CmpFP(int, int);
void sort(int* arr, int size, CmpFP*); /* sort routine in DLL */
void callsort(int* arr, int size, CmpFP* fp) {
    sort(arr, size, fp);
}

Figure 69. File 2. Application A

Figure 70 on page 310 shows how a simple DLL application is compiled with the DLL option.
Figure 71 shows how a DLL is compiled with the NODLL option. File 4 is compiled as NODLL and bound into a DLL. The function sort() will be exported to users of the DLL.

```c
int comp(int e1, int e2) {
    if (e1 == e2)
        return(0);
    else if (e1 < e2)
        return(-1);
    else
        return(1);
}
int (*fp)(int e1, int e2);
main() {
    int a[2] = {2, 1};
    fp = comp; /* assign function address */
    sort(a, 2, fp); /* call sort */
}
```

Figure 70. File 3. Application B

Typedef int CmpFP(int, int);
int sort(int* arr, int size, CmpFP* fp) {
    int i,j,temp,rc;
    for (i=0; i<size; ++i) {
        for (j=1; j<size-1; ++j) {
            rc = fp(arr[j-1], arr[j]); /* call 'fp' which may be DLL or no-DLL code */
            if (rc > 0) {
                temp = arr[j];
                arr[j] = arr[j-1];
                arr[j-1] = temp;
            }
        }
    }
    return(0);
}
#pragma export(sort)

Figure 71. File 4. DLL

Non-DLL function pointers can only safely be passed to a DLL if the function referenced is naturally reentrant, that is, it is C code compiled with the RENT compiler option, or is C code with no global or static variables. See the discussion on the CBA option to see how to make a DLL that can be called by applications that pass constructed reentrant function pointers.
Non-DLL function pointer call in DLL(CBA) code

Figure 73 on page 312 illustrates one situation where you could use the CBA suboption. In the example, the DLL provider provides stub routines which the application programmer can bind with their applications. These stub routines allow an application programmer to use a DLL without recompiling the application with the DLL option. This is an important consideration for library providers that want to move from a static version of a library to a dynamic one. Stub routines are not mandatory, however if they are provided, the application programmer only needs to rebind, but not recompile the application. If stub routines are not provided by the DLL provider, the application programmer must recompile the application.
In the previous example, the DLL provider:
- Compiles the DLL parts as either DLL(CBA) or NODLL(CBA).
- Exports function `dllsort()` for use by other applications.
- Binds the DLL to produce a DLL executable module and a DLL definition side-deck.
- Creates a stub function for every function exported from the DLL. The stub function calls a corresponding function in the DLL. This routine is compiled with the DLL option. The stub functions are provided to the application programmer in a static library to be bound with the application.

The Application Programmer:
- Codes the program using any of the following compiler options;
  - DLL
  - NODLL
  - RENT
  - NORENT
- Calls the stub routines, not the exported functions.

The stub routines must be called because the application programmer may have compiled his code with the NODLL compiler option. Otherwise, references to the DLL functions will be unresolved at bind time. Providing the stub routines allows an application programmer to use a DLL without recompiling the application with the DLL option. This is an important consideration for library

Figure 73. DLL function pointer call in non-DLL code

In the previous example, the DLL provider:
- Compiles the DLL parts as either DLL(CBA) or NODLL(CBA).
- Exports function `dllsort()` for use by other applications.
- Binds the DLL to produce a DLL executable module and a DLL definition side-deck.
- Creates a stub function for every function exported from the DLL. The stub function calls a corresponding function in the DLL. This routine is compiled with the DLL option. The stub functions are provided to the application programmer in a static library to be bound with the application.

The Application Programmer:
- Codes the program using any of the following compiler options;
  - DLL
  - NODLL
  - RENT
  - NORENT
- Calls the stub routines, not the exported functions.

The stub routines must be called because the application programmer may have compiled his code with the NODLL compiler option. Otherwise, references to the DLL functions will be unresolved at bind time. Providing the stub routines allows an application programmer to use a DLL without recompiling the application with the DLL option. This is an important consideration for library
providers that want to move from a static version of a library to a dynamic one. Providing stub routines requires the application programmer to rebind but not recompile the application.

- Statically binds the definition side-deck, provided by the DLL provider, and the stub routines with their program.
- Binds the DLL to produce a DLL executable module and a DLL definition side-deck
- Creates a stub function for every function exported from the DLL. The stub function calls the DLL directly

The reference keys in Figure 73 on page 312 illustrate the sequence of events. Note that in 3, the user does not explicitly make a call to Language Environment. The generated code for the fp function call makes the call to z/OS Language Environment. z/OS Language Environment does the following at point 4 in the figure:

- Saves the DLL environment
- Establishes the application environment
- Branches to the user's function
- Reestablishes the DLL environment after execution of the function
- Returns control to the DLL.

**Non-DLL function pointer call in DLL code**

In DLL code, it is assumed that a function pointer points to a function descriptor. A function pointer call is made by first obtaining the function address through dereferencing the pointer; and then, branching to the function entry. When a non-DLL function pointer is passed to DLL code, it points directly to the function entry. An attempt to dereference through such a pointer produces an undefined function address. The subsequent branching to the undefined address may result in an exception.

The following is an example of passing a non-DLL function pointer to DLL code using an external variable. Its behavior is undefined as shown in Figure 74.

```c
#include <stdio.h>
extern void (*fp)(void);
void hello(void) {
    printf("hello\n");
}
void goo(void) {
    fp = hello; /* assign address of hello, to fp */
    /* (refer to Figure 67 on page 308). */
}
```

---

**Figure 74. C non-DLL code**

Figure 75 on page 314 shows how dereferencing through a pointer produces an undefined function address in C.
Figure 76 shows how dereferencing through a pointer produces an undefined function address in C++.

Function pointer comparison in non-DLL code

In non-DLL code, the results of the following function pointer comparisons are undefined:

- Comparing a DLL function pointer to a non-DLL function pointer
- Comparing a DLL function pointer to another DLL function pointer
- Comparing a DLL function pointer to a constant function address

Comparing a DLL function pointer to a non-DLL function pointer

In Figure 78 on page 315, both the DLL function pointer and the non-DLL function pointer point to the same function; but the pointers, when compared, are unequal.
Example of comparing a DLL function pointer to a non-DLL function pointer using C

In the examples shown in Figure 79 and Figure 80, DLL code and non-DLL code can reside either in the same executable file or in different executable files.

Example of comparing a DLL function pointer to another DLL function pointer

The example in Figure 84 on page 316 compares addresses of function descriptors. In the following examples, both of the DLL function pointers point to the same function, but they compare unequal.

Comparison of two DLL function pointers in non-DLL code

The following example shows a comparison of two DLL function pointers in non-DLL code. In this example, File 1 (Figure 81 on page 316) and File 2 (Figure 82 on page 316) reside in different executable modules. File 3 (Figure 83 on page 316) can reside in the same executable module as File 1 or File 2 or it can reside in a different executable module. In all cases, the addresses of the function descriptors will not compare equally.
```c
#include <stdio.h>
extern int goo(int (*fp1)(const char *, ...));
main ()
{
    int (*fp)(const char *, ...);
    fp = printf; /* assign address of a descriptor that */
    /* points to printf. */
    if (goo(fp))
        printf("Test result is undefined\n");
}
```

Figure 81. File 1 C DLL code

```c
#include <stdio.h>
extern int foo(int (*fp1)(const char *, ...),
    int (*fp2)(const char *, ...));
int goo(int (*fp1)(const char *, ...))
{
    int (*fp2)(const char *, ...);
    fp2 = printf; /* assign address of a different */
    /* descriptor that points to printf. */
    return (foo(fp1, fp2));
}
```

Figure 82. File 2 C DLL code

```c
int foo(int (*fp1)(const char *, ...),
    int (*fp2)(const char *, ...))
{
    if (fp1 == fp2) /* comparing the addresses of two */
        /* descriptors results in unequal. */
        return(0);
    else
        return(1);
}
```

Figure 83. File 3 C non-DLL code

![Diagram showing comparison of two DLL function pointers in non-DLL code](image-url)

Figure 84. Comparison of two DLL function pointers in non-DLL code
Comparing a DLL function pointer to a constant function address other than NULL

Here, you are comparing the constant function address to an address of a function descriptor.

Note: Comparing a DLL function pointer to NULL is well defined, because when a pointer variable is initialized to NULL in DLL code, it has a value zero.

Function pointer comparison in DLL code

In XPLINK code, function pointers are compared using the address of the descriptor. No special considerations, such as dereferencing, are required to initialize the function pointer prior to comparison. Function descriptors are guaranteed to be unique throughout the XPLINK application for a particular function, so this comparison of function descriptor addresses will yield the correct results even if the function pointer is passed between executable modules within the XPLINK application. The remainder of this section does not apply to XPLINK applications.

In non-XPLINK DLL code, a function pointer must be NULL before it is compared. For a non-NULL pointer, the pointer is further dereferenced to obtain the function address that is used for the comparison. For an uninitialized function pointer that has a non-zero value, the dereference can cause an exception to occur. This happens if the storage that the uninitialized pointer points to is read-protected.

Usually, comparing uninitialized function pointers results in undefined behavior. You must initialize a function pointer to NULL or the function address (from source view). Two examples follow.

Figure 85 on page 318 shows undefined comparison in DLL code (C or C++).
Figure 86 shows that, when fp1 points to a read-protected memory block, an exception occurs.

```c
#include <stdio.h>
int (*fp2)(const char *, ...) /* Initialize to point to the */
    = printf; /* descriptor for printf */
int goo(void);
int (*fp2)(void) = goo;
int goo(void) {
    int (*fp1)(void);
    if (fp1 == fp2)
        return (0);
    else
        return (1);
}
void check_fp(void (*fp)()) {
    /* exception likely when -1 is dereferenced below */
    if (fp == (void (*)())-1)
        printf("Found terminator\n");
    else
        fp();
}
void dummy() {
    printf("In function\n");
}
main() {
    void (*fa[2])();
    int i;
    fa[0] = dummy;
    fa[1] = (void (*)())-1;
    for(i=0;i<2;i++)
        check_fp(fa[i]);
}
```

Figure 85. Undefined comparison in DLL code (C or C++)

Figure 86 shows that, when fp1 points to a read-protected memory block, an exception occurs.

![Diagram](image)

Figure 86. Comparison of function pointers in DLL code (C or C++)

Figure 87 on page 319 is an example of valid comparisons in DLL code.
Using DLLs that call each other

An application can use DLLs that call each other. There are two methods for building these applications, as illustrated in the examples that follow:

- In the first method, the loop is broken by manually creating IMPORT statements for the referenced DLLs, when binding one of the DLLs (CCNGA2D3).
- In the second method, an initial bind is done on CCNGA2D3 using the binder NCAL parameter, which will be done again after the referenced DLLs are built.

In both cases, the result is that the side-deck is produced for CCNGA2D3, so that the DLLs that reference CCNGA2D3 can be built.

The CCNGA2 application (Figure 88 on page 320) imports functions and variables from three DLLs: (Figure 89 on page 320, Figure 90 on page 321, and Figure 91 on page 321). It is an example of an application that uses DLLs that call each other.

```c
#include <stdio.h>
int (*fp1)(const char *, ...); /* An extern variable is implicitly*/
    /* initialized to zero */
    /* if it has not been explicitly */
    /* initialized in source. */

int (*fp2)(const char *, ...) /* Initialize to point to the */
    = printf; /* descriptor for printf */

int foo(void) {
    if (fp1 != fp2 )
        return (0);
    else
        return (1);
}
```

Figure 87. Valid comparisons in DLL code (C or C++)
Figure 89 shows application CCNGA2D1, which imports functions from Figure 90 on page 321 and Figure 91 on page 321.

```c
#include <stdlib.h>

extern int var1_d1; /*imported from CCNGA2D1 */
extern int func1_d1(int); /*imported from CCNGA2D1 */

extern int var1_d2; /*imported from CCNGA2D2 */
extern int func1_d2(int); /*imported from CCNGA2D2 */

extern int var1_d3; /*imported from CCNGA2D3 */
extern int func1_d3(int); /*imported from CCNGA2D3 */

int main() {
    int rc = 0;
    printf("+-CCNGA2::main() starting \n");
    /* ref DLL1 */
    if (var1_d1 == 100) {
        printf("| var1_d1=<%d>
", var1_d1);
        func1_d1(var1_d1);
    }
    /* ref DLL2 */
    if (var1_d2 == 200) {
        printf("| var1_d2=<%d>
", var1_d2);
        func1_d2(var1_d2);
    }
    /* ref DLL3 */
    if (var1_d3 == 300) {
        printf("| var1_d3=<%d>
", var1_d3);
        func1_d3(var1_d3);
    }
    printf("+-CCNGA2::main() Ending \n");
}
```

Figure 88. Application CCNGA2

Figure 89 shows application CCNGA2D1, which imports functions from Figure 90 on page 321 and Figure 91 on page 321.

```c
#include <stdio.h>

int func1_d1(); /* A function to be externalized */
int var1_d1 = 100; /* export this variable */

extern int func1_d2(int); /*imported from CCNGA2D2 */
extern int func1_d3(int); /*imported from CCNGA2D3 */

int func1_d1 (int input)
{
    int rc2 = 0;
    int rc3 = 0;
    printf("| +-CCNGA2D1() func1_d1() starting. Input is %d\n", input);
    rc2 = func1_d2(200);
    rc3 = func1_d3(300);
    printf("| | func1_d1() dll1 - rc2=<%d> rc3=<%d>\n", rc2, rc3);
    printf("| +-CCNGA2D1() func1_d1() ending. \n");
}
```

Figure 89. Application CCNGA2D1

Figure 90 on page 321 shows application CCNGA2D2, which imports a function from Figure 91 on page 321.
Application CCNGA2D3 (Figure 91) imports variables from Figure 89 on page 320 and Figure 90.

The first method uses the JCL in Figure 92 on page 322. The following processing occurs:

1. CCNGA2D3 is compiled and bound to create a DLL. The binder uses the control cards supplied through SYSIN to import variables from CCNGA2D1 and CCNGA2D2. The binder also generates a side-deck CCNGA2D3 that is used in the following steps.

2. CCNGA2D2 is compiled and bound to create a DLL. The binder uses the control cards supplied through SYSIN to include the side-deck from CCNGA2D3. The following steps use the binder which generates the side-deck CCNGA2D2.

3. CCNGA2D1 is compiled and bound to create a DLL. The binder uses the control cards supplied through SYSIN to include the side-decks from CCNGA2D2 and CCNGA2D3. The following steps show the binder generating the side-deck CCNGA2D1.

4. CCNGA2 is compiled, bound, and run. The binder uses the control statements supplied through SYSIN to include the side-decks from CCNGA2D1, CCNGA2D2, and CCNGA2D3.

```c
#include <stdio.h>

int func1_d2();    /* A function to be externalized */
int var1_d2 = 200;
extern int func1_d3(int); /* import this function */

int func1_d2 (int input)
{
    int rc3 = 0;
    printf("| | +-CCNGA2D2() func1_d2() starting. Input is %d\n", input);
    rc3 = func1_d3(300);
    printf("| | | func1_d2() dll2 - rc3=<%d>\n", rc3);
    printf("| | +-CCNGA2D2() func1_d2() ending\n");
}
```

```
#include <stdio.h>

int func1_d3();    /* A function to be externalized */
int var1_d3 = 300;
extern int var1_d1; /* imported variable from CCNGA2D1 */
extern int var1_d2; /* imported variable from CCNGA2D2 */

int func1_d3 (int input)
{
    printf("| | | +-CCNGA2D3()-func1_d3() starting. Input is %d\n", input);
    printf("| | | | value of var1_d1=%d var1_d2=%d\n", var1_d1, var1_d2);
    printf("| | | +-CCNGA2D3()-func1_d3() ending\n");
}
```

Figure 90. Application CCNGA2D2

Application CCNGA2D3 (Figure 91) imports variables from Figure 89 on page 320 and Figure 90.

Figure 91. Application CCNGA2D3

The first method uses the JCL in Figure 92 on page 322. The following processing occurs:

1. CCNGA2D3 is compiled and bound to create a DLL. The binder uses the control cards supplied through SYSIN to import variables from CCNGA2D1 and CCNGA2D2. The binder also generates a side-deck CCNGA2D3 that is used in the following steps.

2. CCNGA2D2 is compiled and bound to create a DLL. The binder uses the control cards supplied through SYSIN to include the side-deck from CCNGA2D3. The following steps use the binder which generates the side-deck CCNGA2D2.

3. CCNGA2D1 is compiled and bound to create a DLL. The binder uses the control cards supplied through SYSIN to include the side-decks from CCNGA2D2 and CCNGA2D3. The following steps show the binder generating the side-deck CCNGA2D1.

4. CCNGA2 is compiled, bound, and run. The binder uses the control statements supplied through SYSIN to include the side-decks from CCNGA2D1, CCNGA2D2, and CCNGA2D3.
The second method uses the JCL in Figure 93 on page 323. The following processing occurs:

1. Once compiled, the object module CCNGA2D2 is saved for the following steps.
2. CCNGA2D1 is compiled, the object module is saved for the following steps.
3. CCNGA2D3 is compiled and bound to generate the side-deck and the object module is not used in the following steps. The load module for this step is not saved, as it is not being used. The load module for CCNGA2D3 is generated at a later step.

4. CCNGA2D2 is bound to create a DLL. The binder takes as input the object module CCNGA2D2 and the side-deck CCNGA2D3. It also generates the side-deck CCNGA2D2 that is used in the following steps.

5. CCNGA2D1 is bound to create a DLL. The binder takes as input the object module CCNGA2D1 and the side-decks CCNGA2D3 and CCNGA2D2. It also generates the side-deck CCNGA2D1 that is used in the following steps.

6. CCNGA2D3 is bound to create a DLL. The binder takes as input the object module CCNGA2D3 and the side-decks CCNGA2D1 and CCNGA2D2. It also generates the side-deck CCNGA2D3 that is used in the following step.

7. CCNGA2 is compiled, bound, and run. The binder takes as input the object module CCNGA2 and the side-decks CCNGA2D1, CCNGA2D2, and CCNGA2D3.

//jobcard information...
//PROC JCLLIB ORDER=(CBC.SCCNPRC, CEE.SCEEPROC)
//* CDLL2: -Compile CCNGA2D2
//* CDLL2 EXEC EDCC,INFILE='CBC.SCCNSAM(CCNGA2D2)',
//  OUTFILE='myid.OBJ(CCNGA2D2),DISP=SHR',
//  CPARM='SO,LIST,DLL,EXPO,RENT,LONG'
//*
//* CDLL1: -Compile CCNGA2D1
//* CDLL1 EXEC EDCC,INFILE='CBC.SCCNSAM(CCNGA2D1)',
//  OUTFILE='myid.OBJ(CCNGA2D1),DISP=SHR',
//  CPARM='SO,LIST,DLL,EXPO,RENT,LONG'
//*
//* CBDDL3: -Compile and bind CCNGA2D3 with NCAL
//* -Generate the side-deck CCNGA2D3
//* -The load module will not be kept, as it will not be
//* used
//*
//* CBDDL3 EXEC EDCCB,INFILE='CBC.SCCNSAM(CCNGA2D3)',
//  CPARM='SO,LIST,DLL,EXPO,RENT,LONG',
//  BPARM='NCAL'
//  COMPIL.SYSLIN DD DSN=myid.OBJ(CCNGA2D3),DISP=SHR
//  BIND.SYSLIN DD DSN=myid.OBJ(CCNGA2D3),DISP=SHR
//  BIND.SYSIN DD *
//  INCLUDE OBJ(CCNGA2D2)
//  INCLUDE OBJ(CCNGA2D1)
//  NAME CCNGA2D3(R)
//*
//  BIND.SYDEFSD DD DSN=myid.IMPORT(CCNGA2D3),DISP=SHR
//  BIND.OBJ DD DSN=myid.OBJ,DISP=SHR
//*

CCNGA2M2 (Part 1 of 2)

Figure 93. CCNGA2M2

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CCNGA2M2 (Part 2 of 2)
Chapter 23. z/OS 64-bit environment

Implementation of the 64-bit environment has not changed the default behavior of the compiler; the default compilation environment is 32-bit, which is specified by the ILP32 compiler option.

The compiler changes the behavior of code only when compiling for the 64-bit environment, which is specified by the LP64 compiler option.

Differences between the ILP32 and LP64 environments

The ILP32 and LP64 environments are differentiated by:

- Addressing capability
- Data model

ILP32 and LP64 addressing capabilities

Table 49 shows the differences in addressing capabilities that are available in each environment. 31-bit refers to the addressing mode, or AMODE. In z/OS XL C/C++, pointer sizes in this mode are always 4 bytes. In AMODE 31, 31 bits of the pointer are used to form the address, which is defined by the term “31-bit addressing mode”. Occasionally, we also use the term “32-bit mode”. Strictly speaking, 31-bit is an architectural characteristic referring to the addressing capability, while 32-bit is a programming language aspect referring to the data model. The latter is also referred to as ILP32 (int-long-pointer 32). When there is no ambiguity, we use the term “32-bit mode”.

Table 49. Comparison of ILP32 and LP64 addressing capabilities

<table>
<thead>
<tr>
<th>ILP32 (32-bit environment)</th>
<th>LP64 (64-bit environment)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2 GB of address space</td>
<td>1 million TB of address space</td>
</tr>
<tr>
<td>31-bit execution mode</td>
<td>64-bit execution mode</td>
</tr>
</tbody>
</table>

ILP32 and LP64 data models and data type sizes

Table 50 compares data models and data type sizes of ILP32 and LP64 environments.

Table 50. Comparison of ILP32 and LP64 data models

<table>
<thead>
<tr>
<th>ILP32 (32-bit environment)</th>
<th>LP64 (64-bit environment)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data model ILP32 (32-bit pointer)</td>
<td>Data model LP64 (64-bit pointer)</td>
</tr>
<tr>
<td>int, long, ptr, and off_t are all 32 bits (4 bytes) in size.</td>
<td>int is 32 bits in size. long, ptr, and off_t are all 64 bits (8 bytes) in size.</td>
</tr>
</tbody>
</table>

The 32-bit data model for z/OS XL C/C++ compilers is ILP32 plus long long. This data model uses the 4/4/4 data type size model and includes a long long type. Table 51 compares the type sizes for the different models.

LP64 is the 64-bit data model chosen by the Aspen working group (formed by X/OPEN and a consortium of hardware vendors). LP64 is short for long-pointer
It is commonly referred to as the 4/8/8 data type size model and includes the integer/long/pointer type sizes, measured in bytes.

Table 51. ILP32 and LP64 type size comparisons for signed and unsigned data types

<table>
<thead>
<tr>
<th>Data Type</th>
<th>32-bit sizes (in bytes)</th>
<th>64-bit sizes (in bytes)</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>char</td>
<td>1</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>short</td>
<td>2</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>int</td>
<td>4</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>long</td>
<td>4</td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>long long</td>
<td>8</td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>float</td>
<td>4</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>8</td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>long double</td>
<td>16</td>
<td>16</td>
<td></td>
</tr>
<tr>
<td>pointer</td>
<td>4</td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>wchar_t</td>
<td>2</td>
<td>4</td>
<td>Other UNIX platforms usually have wchar_t 4 bytes for both 32-bit and 64-bit mode.</td>
</tr>
<tr>
<td>size_t</td>
<td>4</td>
<td>8</td>
<td>This is an unsigned type.</td>
</tr>
<tr>
<td>ptrdiff_t</td>
<td>4</td>
<td>8</td>
<td>This is a signed type.</td>
</tr>
</tbody>
</table>

Advantages and disadvantages of the LP64 environment

A major advantage of using a 64-bit environment is the increase in the virtual addressing space. A 64-bit program can handle large tables as arrays without putting temporary files in secondary storage. LP64 provides:

- 64-bit addressing with 8-byte pointers
- Large object support (8-byte longs)
- Backward compatibility (4-byte integers)

Note: Integers are the same size under the ILP32 and LP64 data models.

LP64 application performance and program size

You can use the 64-bit address space to dramatically improve the performance of applications that manipulate large amounts of data, whether the data is be created within the application or obtained from files. Generally, the performance gain comes from the fact that the 64-bit application can contain the data in its 64-bit address space (either created in data structures or mapped into memory), when it would not have fit into a 32-bit address space. The data would need to be multiple GBs in size or larger to show this benefit.

If the same source code is used to create a 32-bit and a 64-bit application, the 64-bit application will typically be larger than the 32-bit application. The 64-bit application is unlikely to run faster than the 32-bit application unless it makes use of the larger 64-bit addressability. Because most C programs are pointer-intensive, a 64-bit application can be close to twice as large as a 32-bit application, depending on how many global pointers and longs are declared. A 64-bit C++ program uses almost twice the data as a 32-bit C++ program, due to the large number of pointers the compiler uses to implement virtual function tables, objects, templates, and so
That is why the appropriate choice is to create a 32-bit application, unless 64-bit addressability is required by the application or can be used to dramatically improve its performance.

Attention: Even though the address space is increased significantly, the amount of hardware physical memory is still limited by your installation. Data that is not immediately required by the program is subject to system paging. Programs that use large data tables therefore require a large amount of paging space. For example, if a program requires 3 GB of address space, the system must have 3 GB of paging space. 64-bit applications might require paging I/O tuning to accommodate the large data handling benefit.

**LP64 restrictions**

The following restrictions apply under LP64:

- The ILP32 statement `type=memory(hiperspace)` is treated as `type=memory` under LP64.
  
  Hiperspace memory files are treated as regular memory files in a 64-bit environment. All behavior is the same as for regular memory files.

- The IMS and CICS environments are not supported under LP64.
  References to these environments are valid under ILP32 only.

- User-supplied buffers are ignored for all but UNIX file system files under LP64.
  References to user-supplied buffers are valid under ILP32 only.

- Under 64-bit data models, pointer sizes are always 64 bits.
  The C Standard does not provide a mechanism for specifying mixed pointer size. However, it might be necessary to specify the size of a pointer type to help migrate a 32-bit application (for example, when libraries share a common header between 32-bit and 64-bit applications).

**Migrating applications from ILP32 to LP64**

This section describes:

- [When to migrate applications to LP64](#)
- Pre-migration checklist
- Post-migration checklist

**When to migrate applications to LP64**

The LP64 strategy is to strike a balance between maximizing the robustness of 64-bit capabilities while minimizing the effort of migrating many programs.

Typically, a 32-bit application should be ported only if either of the following is true:

- It is required by a DLL or a supporting utility
- It must have 64-bit addressability

This is because:

- Porting programs to a 64-bit environment presents a modest technical effort where good coding practices are used. Poor coding practices greatly increase the programming effort.

- There is no clear performance advantage to recompiling an existing 32-bit program in 64-bit mode. In fact, a small slowdown is possible. This is due to:
  - An increase in module size because instructions are larger
An increase in size of the writable static area (WSA) and the stack because pointers and longs are larger.

Issues related to runtime requirements (for example, when you port a program that is compiled with NORENT and NODLL to a 64-bit environment, you must code the program to use the RENT and DLL options, which are required in the 64-bit environment).

Checklist for ILP32-to-LP64 pre-migration activities

Use the following checklist prior to migrating an application from ILP32 to LP64. After migration, test the code and confirm that its behavior is the same under LP64 as it was under ILP32. If you see any difference, debug the code and use the checklist again.

1. Search the source code for patterns that might indicate migration issues. These include:
   - printf specifiers that involve long data types
   - 0xffffffff
   - 2147483647
2. Verify that all functions are properly prototyped.
   
   Note: The C compiler assumes that an unprototyped function returns the int type. This could cause undesirable behavior under LP64 while remaining undetectable under ILP32.

3. Examine all types to determine whether the types should be 4-byte or 8-byte.
   - For system types, the type will be the appropriate size for use with library/system calls.
   - For user-defined types:
     - 4-byte types should be defined based upon int or unsigned int or some system type that is 4 bytes long under LP64.
     - 8-byte types should be defined based upon long or unsigned long or some system type that is 8 bytes long.
4. Change all types to the chosen type.

   Note: When doing so, examine all arithmetic calculations to make sure that expansion and truncation of data values is done appropriately. Make sure that no assumption is made that pointer values will fit into integer types.

5. Use the INFO compiler option to identify the following potential problems:
   - Functions not prototyped - Function prototypes allow the compiler to check for mismatched parameters.
   - Functions not prototyped - Return parameter mis-matched, especially when the code expects a pointer. (For example, malloc and family)
   - Assignment of a long or a pointer to an int - This type of assignment could cause truncation. Even assignments with an explicit cast will be flagged.
   - Assignment of an int to a pointer - If the pointer is referenced it might be invalid.

Checklist for ILP32-to-LP64 post-migration activities

After migrating a program, test the code and confirm that its behavior is the same under LP64 as it was under ILP32. Use the following checklist to test the code. If you see any difference, debug the code and use the pre-migration checklist again.

1. Verify that all output produced is contained in the 4-byte range.
If this is not possible, then any other application using this data needs to be
ported to LP64 or, at least, be made 8-byte-aware.

2. Verify that any user-provided process containing the wchar_t type definition
did not produce unexpected results.

UNIX wchar_t data types are typically defined as four bytes under both 32-bit
and 64-bit environments. The size difference applies to the ILP32 model, not the
LP64 model. The new environment was an opportunity to increase the size for
future development. Because wchar_t is a type definition, user-provided
methods are a likely problem area. A carefully-written application should not
require changes.

Using compiler diagnostics to ensure portability of code

This section describes:

- Using the INFO option to ensure that numbers are suffixed
- Using the WARN64 option to identify potential portability problems

Using the INFO option to ensure that numbers are suffixed

The INFO C and C++ option provides general diagnostics about program code and
is not specific to migrations from ILP32 to LP64. Before migrating, use the
appropriate option to ensure that the following items have been expunged from
the code:

- Functions not prototyped - Function prototypes allow the compiler to check for
  mismatched parameters.
- Functions not prototyped - Return parameter mis-matched, especially when the
code expects a pointer. (For example, malloc and family)
- Assignment of a long or a pointer to an int - This type of assignment could
cause truncation. Even assignments with an explicit cast will be flagged.
- Assignment of an int to a pointer - If the pointer is referenced it might be
  invalid.

Table 52. Example of diagnostic messages generated from code that is not ready to be
migrated from ILP32 to LP64

<table>
<thead>
<tr>
<th>Source</th>
<th>1 #include &lt;stdio.h&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>2 #include &lt;limits.h&gt;</td>
</tr>
<tr>
<td></td>
<td>3</td>
</tr>
<tr>
<td></td>
<td>5</td>
</tr>
<tr>
<td></td>
<td>6</td>
</tr>
<tr>
<td></td>
<td>7</td>
</tr>
<tr>
<td></td>
<td>8</td>
</tr>
<tr>
<td></td>
<td>10</td>
</tr>
<tr>
<td></td>
<td>11</td>
</tr>
<tr>
<td></td>
<td>12</td>
</tr>
<tr>
<td></td>
<td>13</td>
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<td>14</td>
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<td>15</td>
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<td>16</td>
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<td></td>
<td>17</td>
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<tr>
<td></td>
<td>18</td>
</tr>
<tr>
<td></td>
<td>19</td>
</tr>
<tr>
<td></td>
<td>20</td>
</tr>
<tr>
<td></td>
<td>21</td>
</tr>
</tbody>
</table>
Table 52. Example of diagnostic messages generated from code that is not ready to be migrated from ILP32 to LP64 (continued)

<table>
<thead>
<tr>
<th>Output:</th>
<th>WARNING CCN3304 sample.c:9 No function prototype was given for boo.</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>INFORMATIONAL CCN3419 sample.c:11 Converting 4294967295 to type long int does not preserve its value.</td>
</tr>
<tr>
<td></td>
<td>INFORMATIONAL CCN3438 sample.c:14 The value of the variable foo_i may be used before being set.</td>
</tr>
<tr>
<td></td>
<td>INFORMATIONAL CCN3491 sample.c:17 The automatic variable foo_pt is set but never referenced.</td>
</tr>
<tr>
<td></td>
<td>WARNING CCN3343 sample.c:19 Redeclaration of boo differs from the declaration on line 9 of /home/ts43218/sample2.c.</td>
</tr>
<tr>
<td></td>
<td>INFORMATIONAL CCN3050 sample.c:19 Return type long in the redeclaration is not compatible with the previous return type int.</td>
</tr>
<tr>
<td></td>
<td>INFORMATIONAL CCN3470 sample.c:21 Function main should return int, not void.</td>
</tr>
</tbody>
</table>

Note: Lines 9, 11 and 14 are affected by porting the code to LP64.

Using the WARN64 option to identify potential portability problems

Under ILP32, both int and long data types are 32 bits in size. Because of this coincidence, these types might have been used interchangeably. As shown in Table 51 on page 326, the data type long is 8 bytes in length under LP64.

A general guideline is to review the existing use of long data types throughout the source code. If the values to be held in such variables, fields, and parameters will fit in the range of [-231...231-1] or [0...232-1], then it is probably best to use int or unsigned int instead. Also, review the use of the size_t type (used in many subroutines), since its type is defined as unsigned long.

When you migrate a program from ILP32 to LP64, the data model differences might result in unexpected behavior at execution time. Under LP64, the size of pointers and long data types are 8 bytes, which can lead to conversion or truncation problems. The WARN64 option can be used to detect these portability errors.

The WARN64 option provides general diagnostics about program code that might behave differently under ILP32 and LP64. However the checking is not exhaustive. Use it to look for potential migration problems, such as the following common problems:

- Truncation due to explicit or implicit conversion of long types into int types
- Unexpected results due to explicit or implicit conversion of int types into long types
- Invalid memory references due to explicit conversion by cast operations of pointer types into int types
- Invalid memory references due to explicit conversion by cast operations of int types into pointer types
- Problems due to explicit or implicit conversion of constants into long types
- Problems due to explicit or implicit conversion by cast operations of constants into pointer types
There are a few problems that `WARN64` cannot find. For example, unions that use longs or pointers that work under ILP32 might not work under LP64.

```c
union {
    int *p; /* 32 bits / 64 bits */
    int i; /* 32 bits / 32 bits */
};

union {
    double d; /* 64 bits / 64 bits */
    long l[2]; /* 64 bits / 128 bits */
};
```

### ILP32-to-LP64 portability issues

Before migrating applications, consider the following:

- The sizes of the `long`, `pointer` and `wchar_t` types are different under LP64 than they are under ILP32. You must check application behavior, especially if the logic depends on data size.
- Data model differences can result in unexpected behavior at execution time. Under LP64, the size of pointers and long data type are 8 bytes long. This can lead to conversion or truncation problems.

**Note:** You can use the `WARN64` option to help detect these portability errors. See “Using the `WARN64` option to identify potential portability problems” on page 330.

- A migration issue can exist if the program assumes that `int`, `long` and `pointer` type are all the same size. The number of cases where program logic relies on this assumption varies from application to application, depending on the coding style and functionality of the application.

**Note:** Most unexpected behaviors occur at the limits of a type's value range.

- 32-bit applications that rely implicitly on internal data representations (for example, those that cast a float pointer to an integer pointer, then manipulate the bit patterns directly and encode such knowledge directly into the program logic) can be difficult to migrate. In this case, certain assumptions are made about the internal structure of a float representation and the size of `int`.
- Code must be checked to ensure that any shifting and masking operations that manipulate long integers still work properly with a 64-bit long.
- Input and output file dependencies are relevant when you migrate an application that is in the middle of a pipeline of applications, where each application reads the previous application's output as input, and then passes its output to the next application in the pipe. Before migrating one of these applications to a 64-bit environment, you must verify that the output will not produce values outside of the 32-bit range. Typically, once an application is ported to a 64-bit environment, all downstream applications (that is, any application that depends on output from the ported application) must be ported to a 64-bit environment.
- Extending functions is sometimes included as part of a migration project to exploit the benefit and to justify the cost of migrating to a 64-bit environment. You might have to change code for using expanded limits after extending functions.
• You cannot mix 32-bit and 64-bit object files during binding. The only object file format supported under LP64 bit is GOFF, and the only linkage convention is XPLINK.

**IPA(LINK) option and exploitation of 64-bit virtual memory**

As of z/OS V1R8 XL C/C++, IPA(LINK) makes use of 64-bit virtual memory, which will cause an XL C/C++ compiler ABEND if there is insufficient storage. The default MEMLIMIT system parameter size in the SMFPRMx parmlib member should be at least 3000 MB. The default MEMLIMIT value takes effect whenever the job does not specify one of the following:

- MEMLIMIT in the JCL JOB or EXEC statement
- REGION=0 in the JCL

**Note:** The MEMLIMIT value specified in an IEFUSI exit routine overrides all other MEMLIMIT settings.

The z/OS UNIX System Services `ulimit` command can be used to set the MEMLIMIT default. For information, see *z/OS UNIX System Services Command Reference*. For additional information about the MEMLIMIT system parameter, see *z/OS MVS Programming: Extended Addressability Guide*.

As of z/OS V1R8 XL C/C++, the EDCI, EDCXI, EDCQI, CBCI, CBCXI, and CBCQI cataloged procedures, which are used for IPA Link, contain the variable IMEMLIM, which can be used to override the default MEMLIMIT value.

**Availability of suboptions**

Table 53 shows a comparison of the compiler and runtime options that are available in each environment. For example, if you are developing a program to run in either a 32-bit or a 64-bit environment, you must code it to ensure that the high-performance linkage (XPLINK) option is in effect regardless of whether the program is running under ILP32 or LP64.

*Table 53. Comparison of ILP32 and LP64 processing and runtime options*

<table>
<thead>
<tr>
<th>ILP32 (32-bit environment)</th>
<th>LP64 (64-bit environment)</th>
</tr>
</thead>
<tbody>
<tr>
<td>XPLINK or non-XPLINK</td>
<td>XPLINK only</td>
</tr>
<tr>
<td>32-bit dynamic linked libraries (DLLs)</td>
<td>64-bit DLLs</td>
</tr>
</tbody>
</table>

**Potential changes in structure size and alignment**

The LP64 specification changes the size and alignment of certain structure elements, which affects the size of the structure itself. In general, all structures that use long integers and pointers must be checked for size and alignment dependencies.

It is not possible to share a data structure between 32-bit and 64-bit processes, unless the structure is devoid of pointer and long types. Unions that attempt to share long and int types (or overlay pointers onto int types) will be aligned differently or will be corrupted. For example, the virtual function table pointer, inherent in many C++ objects, is a pointer and will change the size and alignment of many C++ objects. In addition, the size and composition of the compiler-generated virtual function table will change.
Note: The issue of changing structure size and alignment should not be a problem unless the program makes assumptions about the size and/or composition of structures.

**z/OS basic rule of alignment**
The basic rule of alignment in z/OS is that a data structure is aligned in accordance with its size and the strictest alignment requirement for its largest member. An 8-byte alignment is more stringent than a 4-byte alignment. In other words, members that can be placed on a 4-byte boundary can also be placed on an 8-byte boundary, but not vice versa.

Note: The only exception is a *long double*, which is always aligned on an 8-byte boundary.

You can satisfy the rule of alignment by inserting pad members both between members and at the end of a structure, so that the overall size of the structure is a multiple of the structure's alignment.

**Examples of structure alignment differences under ILP32 and LP64**
This section provides examples of three structures that illustrate the impact of the ILP32 and LP64 programming environments on structure size and alignment.

In accordance with the z/OS rule of alignment (see "z/OS basic rule of alignment"), the length of each data member produced by the source code depends on the runtime environment, as shown in Table 54.

| Table 54. Comparison of data structure member lengths produced from the same code |
| Source: #include <stdio.h> |
| int main(void) { |
| struct li{ |
| long la; |
| int ia; |
| } li; |
| struct lii{ |
| long la; |
| int ia; |
| int ib; |
| } lii; |
| struct ili{ |
| int ia; |
| long la; |
| int ib; |
| } ili; |
| printf("length li = %d\n",sizeof(li)); |
| printf("length lii = %d\n",sizeof(lii)); |
| printf("length ili = %d\n",sizeof(ili)); |
| } |
| **ILP32 member lengths:** |
| length li = 8 | 1 |
| length lii = 12 | 3 |
| length ili = 12 | 3 |
| **LP64 member lengths:** |
| length li = 16 | 2 |
| length lii = 16 | 3 |
| length ili = 24 | 3 |
Table 54. Comparison of data structure member lengths produced from the same code (continued)

Notes:
1. In a 32-bit environment, both int and long int have 4-byte alignments, so each of these members is aligned on 4-byte boundary. In accordance with the z/OS rule of alignment, the structure as a whole has a 4-byte alignment. The size of struct li is 8 bytes. See Figure 94 on page 335.
2. In a 64-bit environment, int has a 4-byte alignment and long int has an 8-byte alignment. In accordance with the z/OS rule of alignment, the structure as a whole has an 8-byte alignment. See Figure 94 on page 335.
3. The struct lii and the struct ili have the same members, but in a different member order. See Figure 95 on page 336 and Figure 96 on page 337. Because of the padding differences in each environment:
   • Under ILP32:
     – The size of struct lii is 12 bytes (4-byte long + 4-byte int + 4-byte int)
     – The size of struct ili is 12 bytes (4-byte int + 4-byte long + 4-byte int)
   • Under LP64:
     – The size of struct lii is 16 bytes (8-byte long + 4-byte int + 4-byte int)
     – The size of struct ili is 24 bytes (4-byte int + 4-byte pad + 8-byte long + 4-byte int + 4-byte pad)

The ILP32 and LP64 alignments for the structs defined by the code shown in Table 54 on page 333 are compared in Figure 94 on page 335, Figure 95 on page 336, and Figure 96 on page 337.

Figure 94 on page 335 compares how struct li is aligned under ILP32 and LP64. The structure has two members:
• The first (member la) is of type long
• The second (member ia) is of type int

Under ILP32, each member is 4 bytes long and is aligned on a 4-byte boundary, making the structure 8 bytes long. Under LP64, member la is 8 bytes long and is aligned on an 8-byte boundary. Member ia is 4 bytes long, so the compiler inserts 4 padding bytes to ensure that the structure is aligned to the strictest alignment requirement for its largest member. Then, the structure can be used as part of an array under LP64.
Figure 95 on page 336 and Figure 96 on page 337 show structures that have the same members, but in a different order. Compare these figures to see how the order of the members impacts the size of the structures in each environment.

Figure 95 on page 336 compares how \texttt{struct li} is aligned under ILP32 versus LP64. \texttt{struct li} has three members:

- The first (member \texttt{la}) is of type \texttt{long}
- The second (member \texttt{ia}) and third (member \texttt{ib}) are of type \texttt{int}

Under ILP32, each member is 4 bytes long and is aligned on a 4-byte boundary, making the structure 12 bytes long. Under LP64, member \texttt{ia} is 8 bytes long and is aligned on an 8-byte boundary. Member \texttt{ia} and member \texttt{ib} are each 4 bytes long, so the structure is 16 bytes long and can align on an 8-byte boundary without padding.
Figure 96 on page 337 compares how struct ili is aligned under ILP32 and LP64.

struct ili has three members:

- The first (member ia) is of type int
- The second (member la) is of type long
- The third (member ib) is of type int

Under ILP32, each member is 4 bytes long and is aligned on a 4-byte boundary, making the structure 12 bytes long. Under LP64, the compiler inserts padding after both member ia and member ib, so that each member with padding is 8 bytes long (member la is already 8 bytes long) and are aligned on 8-byte boundaries. The structure is 24 bytes long.
Data type assignment differences under ILP32 and LP64

Under ILP32, int, long and pointer types have the same size and can be freely assigned to one another.

Under LP64, all pointer types are 8 bytes in size. Assigning pointers to int types and back again can result in an invalid address, and passing pointers to a function that expects an int type will result in truncation. For example, the following statement show an incorrect assignment.

```c
int i;
int *p;
i = (int)p;
```

Note: The problem is harder to detect when casts are used. Although there is no warning message, the problem still exists.

Avoid making any of the following assumptions:
• A pointer type or a C long type can fit into a C integer type.
• A type that is derived from a pointer type can fit into a type derived from an integer type.
• The number of bits in a C long type object is assumed, especially when shifting bits or doing bitwise operations.
• A C integer can be passed to an unprototyped long or pointer parameter.
• A function that is not a prototype can return a pointer or long.
Portability issues with data types long and int

Under LP64, types long and int are not interchangeable. The long type (and types derived from it) is 64 bits in size.

You should consider all types related to the long and unsigned long types. For example, size_t, used in many subroutines, is defined under LP64 as unsigned long.

Because of the difference in size for int and long under LP64, conversions to long from other integral types might be executed differently that it was under ILP32.

Example of possible change of result after conversion from signed number to unsigned long: When a signed char, signed short, or signed int is converted to unsigned long, sign extension might result in a different unsigned value in 64-bit mode. The example in Table 55 will yield 4294967295 (0xffffffff) under ILP32 but 18446744073709551615 (0xffffffffffffffff) under LP64, because of sign extension.

Table 55. Example of possible change of result after conversion from signed number to unsigned long

| Source: | `#include<stdio.h>`  
| | `void foo(int i)`  
| | `{`  
| | `unsigned long l = i;`  
| | `printf("%lu (0x%lx)\n", l, l);`  
| | `}`  
| | `void main()`  
| | `{`  
| | `foo(-1);`  
| | `}`  
| Compiler options: | `cc -Wc,"flag(i),warn64" -c warn2.c`  
| Output: | `INFORMATIONAL CCN3743 ./warn2.c:4 64-bit portability: possible change of result through conversion of int type into unsigned long int type.`

Example of possible change of result after conversion from unsigned int variable to signed long: When an unsigned int variable with values greater than INT_MAX is converted to signed long, the results depend on whether the application is executed under ILP32 or under LP64. In the example in Table 56:

- Under ILP32, the value INT_MAX+1 will wrap around and yield -2147483648 (0x80000000)
- Under LP64, the value INT_MAX+1 can be represented by an 8-byte signed long and will result in the correct value 2147483648 (0x80000000)

Table 56. Example of possible change of result after conversion from unsigned int variable to signed long

| Source: | `#include<stdio.h>`  
| | `#include<limits.h>`  
| | `void foo(unsigned int i)`  
| | `{`  
| | `long l = i;`  
| | `printf("%ld (0x%lx)\n", l, l);`  
| | `}`  
| | `void main()`  
| | `{`  
| | `foo(INT_MAX + 1);`  
| | `}`
Table 56. Example of possible change of result after conversion from unsigned int variable to signed long (continued)

<table>
<thead>
<tr>
<th>Compiler options</th>
<th>cc -Wc,&quot;flag(i),warn64&quot; -c warn3.c</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output</td>
<td>INFORMATIONAL CCN3743 ./warn3.c:5 64-bit portability: possible change of result through conversion of unsigned int type into long int type.</td>
</tr>
</tbody>
</table>

Example of possible change of result after conversion from signed long long variable to signed long:

When a signed long long variable with values either greater than UINT_MAX or less than 0 is converted to unsigned long, truncation will not occur under LP64. The example in Table 57 will yield:

- 4294967295 (0xffffffff) 0 (0x0) under ILP32
- 18446744073709551615 (0xffffffffffffffff) 4294967296 (0x100000000) under LP64

Table 57. Example of possible change of result after conversion from signed long long variable to signed long

Source:
```c
#include<stdio.h>
#include<limits.h>
void foo(signed long long ll)
{
    unsigned long l = ll;
    printf("%lu (0x%lx)\n", l, l);
}
void main()
{
    foo(-l);
    foo(UINT_MAX + llll);
}
```

Compiler options: cc -Wc,"flag(i),warn64" -c warn4.c

Output: INFORMATIONAL CCN3743 ./warn4.c:564-bit portability: possible change of result through conversion of long long int type into unsigned long int type.

Example of possible change of result after conversion from unsigned long long variable to unsigned long:

Under LP64, when an unsigned long long variable with values greater than UINT_MAX is converted to unsigned long, truncation will not occur.

Table 58. Example of possible change of result after conversion from unsigned long long variable to unsigned long

Source:
```c
#include<stdio.h>
#include<limits.h>
void foo(unsigned long long ll)
{
    unsigned long l = ll;
    printf("%ld (0x%lx)\n", l, l);
}
void main()
{
    foo(UINT_MAX + llll);
}
```

ILP32 output: 0 (0x0)

Note: The higher order word is truncated.
Table 58. Example of possible change of result after conversion from unsigned long long variable to unsigned long (continued)

<table>
<thead>
<tr>
<th>LP64 output:</th>
<th>4294967296 (0x100000000)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Note:</td>
<td>There is no truncation.</td>
</tr>
</tbody>
</table>

Example of possible change of result after conversion from signed long long variable to signed long: Under LP64, when a signed long long variable with values less than INT_MIN or greater than INT_MAX is converted to signed long, truncation does not occur.

Table 59. Example of possible change of result after conversion from signed long long variable to signed long

| Source: | #include<stdio.h>  
#include<limits.h>  
void foo(signed long long ll)  
{  
signed long l = ll;  
printf("%ld (0x%lx)\n", l, l);  
}  
void main()  
{  
foo(INT_MIN - 1ll);  
foo(INT_MAX + 1ll);  
} |
| Compiler options: | cc -Wc,"flag(i),warn64" -c warn5.c |
| ILP32 output: | INFORMATIONAL CCN3743 ./warn5.c:5 64-bit portability: possible change of result through conversion of long int type into long int type.  
2147483647 (0xffffffff)  
-2147483648 (0x80000000) |
| Note: | The higher order word is truncated. |
| LP64 output: | INFORMATIONAL CCN3743 ./warn5.c:5 64-bit portability: possible change of result through conversion of long int type into long int type.  
-2147483649 (0xfffffffff)  
2147483648 (0x80000000) |
| Note: | There is no truncation. |

Example of possible change of result after conversion from unsigned long long variable to signed long: Under LP64, when an unsigned long long variable with values greater than INT_MAX is converted to signed long, truncation does not occur.
Table 60. Example of possible change of result after conversion from unsigned long long variable to signed long

Source:
```c
#include<stdio.h>
#include<limits.h>

void foo(unsigned long long ll)
{
    signed long l=ll;
    printf("%ld (0x%lx)\n", l, l);
}

void main()
{
    foo(INT_MAX + 1ull);
}
```

Compiler options:
```c
cc -Wc,"flag(i),warn64" -c warn6.c
```

ILP32 output:
```
INFORMATIONAL CCN3743 ./warn6.c:5 64-bit portability: possible change of result through conversion of unsigned long long int type into long int type.
-2147483648 (0x80000000)
Note: The value INT_MAX+1ull will wrap around.
```

LP64 output:
```
INFORMATIONAL CCN3743 ./warn6.c:5 64-bit portability: possible change of result through conversion of unsigned long long int type into long int type.
2147483648 (0x80000000)
Note: The value INT_MAX+1ull can be represented by an 8-byte signed long and will result in the correct value.
```

**Pointer declarations when 32-bit and 64-bit applications share header files**

In 64-bit data models, pointer sizes are always 64 bits. There is no standard language syntax for specifying mixed pointer size. However, it might be necessary to specify the size of a pointer type to help migrate a 32-bit application (for example, when libraries share a common header between 32-bit and 64-bit applications).

The z/OS XL C/C++ compiler reserves two pointer size qualifiers:
- `__ptr32`
- `__ptr64`

The size qualifier `__ptr64` is not currently used; it is reserved so that a program cannot use it. The size qualifier `__ptr32` declares a pointer to be 32 bits in size. This is ignored under ILP32.

Examples of pointer declarations that can be made under LP64:

```c
int * __ptr32 p; /* 32-bit pointer */ [1, 3]
int * r; /* 64-bit pointer, default to the model's size */ [4]
int * __ptr32 const q; /* 32-bit const pointer */ [1, 2, 3]
```

Notes:
1. The qualifier qualifies the `*` before it.
2. `q` is a 32-bit constant pointer to an integer.
3. When __ptr32 is used, the program expects that the address of the pointer variable is less than or equal to 31 bits. You might need to ensure this by calling a special runtime function, such as the Language Environment runtime function __malloc31. You can call __malloc31 whenever you use your own assembler routine to get storage, and want to keep the addresses in structures and unions to a length of four bytes.

4. If a pointer declaration does not have the size qualifier, it defaults to the size of the data model.

**Potential pointer corruption**

When porting a program from ILP32 to LP64, be aware of the following potential problems:

- An invalid address might be the result of either of the following actions:
  - Assigning an integer (4 bytes) or a 4-byte hexadecimal constant to a pointer type variable (8 bytes)
  - Casting a pointer to an integer type

  *Note:* An invalid address causes errors when the pointer is dereferenced.

- If you compare an integer to a pointer, you might get unexpected results.

- Data truncation might result if you convert pointers to signed or unsigned integers with the expectation that the pointer value will be preserved.

- If return values of functions that return pointers are assigned to an integer type, those return values will be truncated.

- If code assumes that pointers and integers are the same size (in an arithmetic context), there will be problems. Pointer arithmetic is often a source of problems when migrating code. The ISO C and C++ standards dictate that incrementing a pointer adds the size of the data type to which it points to the pointer value. For example, if the variable p is a pointer to long, the operation (p+1) increments the value of p by 4 bytes (in 32-bit mode) or by 8 bytes (in 64-bit mode). Therefore, casts between long* and int* are problematic because of the size differences between pointer objects (32 bits versus 64 bits).

**Potentially incorrect pointer-to-int and int-to-pointer conversions**

Before porting code, it is important to test the ILP32 code to determine if any code paths would have incorrect results under LP64. For example:

- When a pointer is explicitly converted to an integer, truncation of the high-order word occurs.

- When an integer is explicitly converted to a pointer, the pointer might not be correct, which could result in invalid memory access when the pointer is dereferenced.

*Table 61. Example of source code that explicitly converts an integer to a pointer*

```
#include <stdio.h>
#include <stdlib.h>

int main()
{
    int i, *p, *q;
    p = (int*)malloc(sizeof(int));
    i = (int)p;
    q = (int*)i;
    p[0] = 55;
    printf("p = %p q = %p\n", p, q);
    printf("p[0] = %d q[0] = %d\n", p[0], q[0]);
}
```
Table 61. Example of source code that explicitly converts an integer to a pointer (continued)

<table>
<thead>
<tr>
<th>Compiler options:</th>
<th>c89 -Wc,&quot;flag(i),warn64&quot; -c warn7.c</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output:</td>
<td>INFORMATIONAL CCN3744 ./warn7.c:7 64-bit portability: possible truncation of pointer through conversion of pointer type into int type.</td>
</tr>
<tr>
<td></td>
<td>INFORMATIONAL CCN3745 ./warn7.c:8 64-bit portability: possible incorrect pointer through conversion of int type into pointer.</td>
</tr>
</tbody>
</table>

Notes:
1. Under ILP32, the pointers p and q are pointing to the same memory location.
2. Under LP64, the pointer q is likely pointing to an invalid address, which could result in a segmentation fault when q is dereferenced.
3. Warning messages are generated for invalid conversions, as shown in Table 61 on page 342.

Potential truncation problem with a pointer cast conversion
As Table 62 shows, truncation problems can occur when converting between 64-bit and 32-bit data objects. Because int and long are both 32 bits under ILP32, a mixed assignment or conversion between these data types did not represent any problem. However, under LP64, a mixed assignment or conversion does present problems because long is larger in size than int. Without an explicit cast, the compiler is unable to determine whether the narrowing of assignment is intended. If the value l is always within the range representable by an int, or if the truncation is intended by design, use an explicit cast to silent the WARN64 message that you will receive for this code.

Table 62. Example of truncation problem with a pointer cast conversion

<table>
<thead>
<tr>
<th>Source:</th>
<th>void foo(long l)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>{ int i = l; }</td>
</tr>
<tr>
<td>Compiler options:</td>
<td>cc -Wc,&quot;flag(i),warn64&quot; -c warn1.c</td>
</tr>
<tr>
<td>Output:</td>
<td>WARNING CCN3742 ./warn1.c:3 64-bit portability: possible loss of digits through conversion of long int type into int type.</td>
</tr>
</tbody>
</table>

Potential loss of data in constant expressions
A loss of data can occur in some constant expressions because of lack of precision. These types of problems are very hard to find and might be unnoticed. It is possible to write data-neutral code that can be compiled under both ILP32 and LP64.

When coding constant expressions, you must be very explicit about specifying types and use the constant suffixes {u,U,l,L,ll,LL} to specify types, as shown in Table 63 on page 344. You could also use casts to specify the type of a constant expression.

It is especially important to code constant expressions carefully when you are porting programs to a 64-bit environment because integer constants might have different types when compiled in 64-bit mode. The ISO C and C++ standards state that the type of an integer constant, depending on its format and suffix, is the first (that is, smallest) type in the corresponding list that will hold the value. The
number of leading zeros does not influence the type selection. Table 63 describes
the type of an integer constant according to the ISO standards.

Table 63. Type of an integer constant

<table>
<thead>
<tr>
<th>Suffix</th>
<th>Decimal constant</th>
<th>Octal or hexadecimal constant</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsuffixed</td>
<td>int</td>
<td>int</td>
</tr>
<tr>
<td></td>
<td>long</td>
<td>unsigned int</td>
</tr>
<tr>
<td></td>
<td>unsigned long</td>
<td>long</td>
</tr>
<tr>
<td>u or U</td>
<td>unsigned int</td>
<td>unsigned int</td>
</tr>
<tr>
<td></td>
<td>unsigned long</td>
<td>unsigned long</td>
</tr>
<tr>
<td>I or L</td>
<td>long</td>
<td>long</td>
</tr>
<tr>
<td></td>
<td>unsigned long</td>
<td>unsigned long</td>
</tr>
<tr>
<td>Both u or U and I or L</td>
<td>unsigned long</td>
<td>unsigned long</td>
</tr>
<tr>
<td>II or LL</td>
<td>long</td>
<td>long</td>
</tr>
<tr>
<td></td>
<td>unsigned long</td>
<td>unsigned long long</td>
</tr>
<tr>
<td>Both u or U and II or LL</td>
<td>unsigned long long</td>
<td>unsigned long long</td>
</tr>
</tbody>
</table>

Note: Under LP64, a change in the type of a constant in an expression might cause
unexpected results because `long` is equal to `long long`. For example, an unsuffixed
hexadecimal constant that can be represented only by an `unsigned long` in 32-bit
mode can fit within a `long` in 64-bit mode.

Data alignment problems when structures are shared

Modern processor designs usually require data in memory to be aligned to their
natural boundaries, in order to gain the best possible performance. In most cases,
the compiler ensures proper alignment by inserting padding bytes immediately in
front of the misaligned data. Although the padding bytes do not affect the integrity
of the data, they might result in an unexpected layout, which affects the size of
structures and unions.

Because both pointer size and long size are doubled in 64-bit mode, structures and
unions containing them as members are larger than they are in 32-bit mode.

Attention: The example in Table 64 is for illustrative purposes only. Sharing
pointers between 32-bit and 64-bit processes is not recommended and will likely
yield incorrect results.

Table 64. An attempt to share pointers between 32-bit and 64-bit processes

```
#include <stdio.h>
#include <stddef.h>
int main()
{
  struct T {
    char c;
    int *p;
    short s;
  } t;
  printf("sizeof(t) = %d\n", sizeof(t));
  printf("offsetof(t, c) = %d sizeof(c) = %d\n",
         offsetof(struct T, c), sizeof(t.c));
  printf("offsetof(t, p) = %d sizeof(p) = %d\n",
         offsetof(struct T, p), sizeof(t.p));
  printf("offsetof(t, s) = %d sizeof(s) = %d\n",
         offsetof(struct T, s), sizeof(t.s));
}  
```
Table 64. An attempt to share pointers between 32-bit and 64-bit processes (continued)

<table>
<thead>
<tr>
<th></th>
<th>ILP32 output:</th>
<th></th>
<th>LP64 output:</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>sizeof(t) = 12</td>
<td></td>
<td>sizeof(t) = 24</td>
<td></td>
</tr>
<tr>
<td></td>
<td>offsetof(t, c) = 0</td>
<td>sizeof(c) = 1</td>
<td>offsetof(t, c) = 0</td>
<td>sizeof(c) = 1</td>
</tr>
<tr>
<td></td>
<td>offsetof(t, p) = 4</td>
<td>sizeof(p) = 4</td>
<td>offsetof(t, p) = 8</td>
<td>sizeof(p) = 8</td>
</tr>
<tr>
<td></td>
<td>offsetof(t, s) = 8</td>
<td>sizeof(s) = 2</td>
<td>offsetof(t, s) = 16</td>
<td>sizeof(s) = 2</td>
</tr>
</tbody>
</table>

Notes:

1. When the source is compiled and executed under ILP32, the result indicates that paddings have been inserted before the member p, and after the member s. Three padding bytes have been inserted before the member p to ensure that p is aligned to its natural 4-byte boundary. The alignment of the structure itself is the alignment of its strictest member. In this example, it is a 4-byte alignment because the member p has the strictest alignment. Two padding bytes are inserted at the end of the structure to make the total size of the structure a multiple of 4 bytes. This is required so that if you declare an array of this structure, each element of the array will be aligned properly.

2. When the source is compiled and executed under LP64, the size of the structure doubles because additional padding is required to force the member p to fall on a natural alignment boundary of 8-bytes.

Figure 97 on page 346 illustrates how the compiler treats the source code shown in Table 64 on page 344 under ILP32 and LP64. Because the pointer is a different size in each environment, they are aligned on different boundaries. This means that if the code is compiled under both ILP32 and LP64, there are likely to be alignment problems. Figure 98 on page 350 illustrates the solution, which is to define pad members of type character that prevent the possibility of data misalignment. Table 67 on page 349 shows the necessary modifications to the code in Table 64 on page 344.

If the structure in Table 64 on page 344 is shared or exchanged among 32-bit and 64-bit processes, the data fields (and padding) of one environment will not match the expectations of the other, as shown in Figure 97 on page 346.
Portability issues with unsuffixed numbers

When porting code, be aware that:
- Unsuffixed constants are more likely to become 8 bytes long if they are in hexadecimal.
- All constants that can impact any constant assignment must be explicitly suffixed.

Example of unexpected behavior resulting from use of unsuffixed numbers

This causes some operations, such as one that compares sizeof(4294967295) to another value, to return 8. If you add the suffix U to the number (4294967295U), the compiler can parse it as unsigned int.

Table 65. Example of unexpected behavior resulting from use of unsuffixed numbers

Source:
```c
#include <stdio.h>
#include <limits.h>
void main(void) {
    long l = LONG_MAX;
    printf("size(2147483647) = %d\n",sizeof(2147483647));
    printf("size(2147483648) = %d\n",sizeof(2147483648));
    printf("size(4294967295U) = %d\n",sizeof(4294967295U));
    printf("size(-1) = %d\n",sizeof(-1));
    printf("size(-1L) = %d\n",sizeof(-1L));
    printf("LONG_MAX = %d\n",l);
} 
```
Table 65. Example of unexpected behavior resulting from use of unsuffixed numbers (continued)

ILP32 output:

size(2147483647) = 4  
size(2147483648) = 4  
size(4294967295U) = 4  
size(-1) = 4  
size(-1L) = 4  
LONG_MAX = 2147483647

LP64 output:

size(2147483647) = 4  
size(2147483648) = 8  
size(4294967295U) = 4  
size(-1) = 4  
size(-1L) = 8  
LONG_MAX = -1

Example of how a suffix causes the compiler to parse the number differently under ILP32 than under LP64

Example: A number like 4294967295 (UINT_MAX), when parsed by the compiler, will be
- An unsigned long under ILP32
- A signed long under LP64

Using a LONG_MAX macro in a printf subroutine

The printf subroutine format string for a 64-bit integer is different than the string used for a 32-bit integer. Programs that do these conversions must use the proper format specifier.

Under LP64, you must also consider the maximum number of digits of the long and unsigned long types. The ULONG_MAX is twenty digits long, and the LONG_MAX is nineteen digits.

In Table 66, the code assumes that the long type is the same size as the int type (as it would be under ILP32). That is, %d is used instead of %ld.

Table 66. Example of using LONG_MAX macros in a printf subroutine

| Source: | #include <stdio.h>  
| int main(void) {  
| printf("LONG_MAX( d) = %ld\n",LONG_MAX);  
| printf("LONG_MAX( x) = %x\n",LONG_MAX);  
| printf("LONG_MAX(1u) = %lu\n",LONG_MAX);  
| printf("LONG_MAX(1x) = %lx\n",LONG_MAX);  
| } |
| LONG_MAX value: | 9,223,372,036,854,775,807 |
| Output: | LONG_MAX( d) = -1  
| LONG_MAX( x) = ffffffff  
| LONG_MAX(1u) = 9223372036854775807  
| LONG_MAX(1x) = 7fffffffffffffff |

Notes:
1. Under LP64:
   - %ld must be used
   - %x will give incorrect results and must be replaced by %p or %1x
2. A similar example would produce the same results for an unsigned long with a ULONG_MAX value of 18,446,744,073,709,551,615.
Programming for portability between ILP32 and LP64

When you want to program for portability between the ILP32 and LP64 environments, you can use the following strategies:

- Header files to provide type definitions
- Suffixes and explicit types to prevent unexpected behavior
- Defining pad members to avoid data alignment problems
- Prototypes to avoid debugging problems
- Conditional compiler directive for preprocessor macro selection
- Converters
- Locales

Using header files to provide type definitions

The header file `inttypes.h` provides type definitions for integer types that are guaranteed to have a specific size (for example, `int32_t` and `int64_t`, and their unsigned variations). Consider using those type definitions if your program code relies on types with specific sizes.

There are many ways to use headers to handle code that is portable between ILP32 and LP64. You can minimize the amount of conditional compilation code and avoid having totally different sections of code for a ILP32 and LP64 structure definitions if you adopt a coding convention that suits your environment.

If you provide a library to your application users and ship header files that define the application programming interface of the library, consider shipping a single set of headers that can support both 32-bit and 64-bit versions of your library. You can use the type definitions in `inttypes.h`. For example, if you are currently shipping 32-bit versions of your header files, you could:

- Replace all fields of type `long` with type `int32_t` (or another 32-bit type)
- Similarly replace all fields for the unsigned variation
- If you cannot let a 64-bit application use a 64-bit pointer for a field, use the `__ptr32` qualifier.

Using suffixes and explicit types to prevent unexpected behavior

The C language limit (in `limits.h`) is different under LP64 than it is under ILP32. As the following example shows, you can prevent unexpected behavior by an application by using suffixes and explicit types with all numbers.

```c
#ifndef _LP64
#define LONG_MAX (9223372036854775807L)
#define LONG_MIN (-LONG_MAX - 1)
#define ULONG_MAX (18446744073709551615U)
#else
#define LONG_MAX INT_MAX
#define LONG_MIN INT_MIN
#define ULONG_MAX (UINT_MAX)
#endif /* _LP64 */
```

Note: The output for LONG_MAX is not really -1. The reason for the -1 is that:

- The printf subroutine handles it as an integer
- `(LONG_MAX == (int)LONG_MAX)` returns a negative value
Defining pad members to avoid data alignment problems

If you want to allow the structure to be shared, you might be able to reorder the fields in the data structure to get the alignments in both 32-bit and 64-bit environments to match (as shown in Table 54 on page 333), depending on the data types used in the structure and the way in which the structure as a whole is used (for example, whether the structure is used as a member of another structure or as an array).

If you are unable to reorder the members of a structure, or if reordering alone cannot provide correct alignment, you can define paddings that force the members of the structure to fall on their natural boundaries regardless of whether it is compiled under ILP32 or LP64. A conditional compilation section is required whenever a structure uses data types that have different sizes in 32-bit and 64-bit environments.

The example in Table 67 shows how the source code in Table 64 on page 344 can be modified to avoid the data alignment problem.

Table 67. Example of source code that successfully shares pointers between ILP32 and LP64 programs

| Source: | struct T {  
|        |   char c;  
|        |   short s;  
|        |   #if !defined(_LP64)  
|        |     char pad1[size];  
|        |   #endif  
|        |   int *p;  
|        |   #if !defined(_LP64)  
|        |     char pad2[size];  
|        |   #endif  
<table>
<thead>
<tr>
<th></th>
<th>} t</th>
</tr>
</thead>
</table>
| ILP32/LP64 size and member layout: | sizeof(t) = 16  
| | offsetof(t, c) = 0 sizeof(c) = 1  
| | offsetof(t, s) = 2 sizeof(s) = 2  
| | offsetof(t, p) = 8 sizeof(p) = 4 |

Figure 98 on page 350 shows the member layout of the structure with user-defined padding. Because the pointer is a different size in each environment, it is aligned on different a boundary in each environment. This means that if the code is compiled under both ILP32 and LP64, there are likely to be alignment problems. This figure illustrates the solution, which is to define pad members of type character that prevent the possibility of data misalignment.

Note: When inserting paddings into structures, use an array of characters. The natural alignment of a character is 1-byte, which means that it can reside anywhere in memory.
Using prototypes to avoid debugging problems

You can avoid complex debugging problems by ensuring that all functions are prototyped.

The C language provides a default prototype. If a function is not prototyped, it defaults to a function which returns an integer and has no information about the parameters.

The C++ language does not provide a default and always requires a prototype. However, C++ has an implicit integer return type extension for legacy code.

A common problem is that the default return type of `int` might not remain the same size as an associated pointer. For example, the function `malloc()` can cause truncation when an unprototyped function returns a pointer. This is because an unprototyped function is assumed to return an `int` (4 bytes).
Using a conditional compiler directive for preprocessor macro selection
When the compiler is invoked with the LP64 option, the preprocessor macro _LP64 is defined. When the compiler is invoked with the ILP32 option, the macro _ILP32 is defined.

You can use a conditional compiler directive such as #if defined _LP64 or #ifdef _LP64 to select lines of code (such as printf statements) that are appropriate for the data model that is invoked.

Using converters under ILP32 or LP64
Both table-driven converters (such as EDCGNXLT proc) and indirect UCS-2 converters (such as the uconvdef UNIX System Services utility) function the same in both 32-bit and 64-bit environments. The naming convention requires that dataset member names must begin with CEQ.

Notes:
1. GENXLT converters are shipped only in data sets.
2. The converter objects that are shipped with z/OS V2R2 allow existing applications to work at a basic level only. You might need to build customized objects.

Using locales under ILP32 or LP64
The locale objects that are shipped with z/OS V2R2 allow existing applications to work at a basic level only. You might need to build customized objects.

Customized 64-bit locales
If you need to create 64-bit locales, you must use the UNIX System Services localedef utility with the new -6 compiler option.
• If the locales are dataset members, they must have the CEQ prefix.
• If the locales are zFS-resident or UNIX file system-resident, they must have the .lp64 suffix.

Note: There is no batch or TSO LOCALDEF support for 64-bit locales.

Old SAA locales
Old SAA locales (such as EDC$FRAN) are not supported by the LP64 model.
Chapter 24. Using threads in z/OS UNIX applications

A thread is a single flow of control within a process. The following section describes some of the advantages of using multiple threads within a single process, and functions that can be used to maintain this environment.

Models and requirements

Threads are efficient in applications that allow them to take advantage of any underlying parallelism available in the host environment. This underlying parallelism in the host can be exploited either by forking a process and creating a new address space, or by using multiple threads within a single process. There are advantages and disadvantages to both techniques, but it primarily comes down to a compromise between the efficiency of using multiple threads versus the security of working in separate address spaces. The POSIX(ON) runtime option must be specified to use threads.

Functions

Table 68 lists the functions provided to implement a multi-threaded application.

Table 68. Functions used in creating multi-threaded applications

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_create()</td>
<td>Create a thread</td>
</tr>
<tr>
<td>pthread_join()</td>
<td>Wait for thread termination</td>
</tr>
<tr>
<td>pthread_exit()</td>
<td>Terminate a thread normally</td>
</tr>
<tr>
<td>pthread_detach()</td>
<td>Detach a thread</td>
</tr>
<tr>
<td>pthread_self()</td>
<td>Get your thread ID</td>
</tr>
<tr>
<td>pthread_equal()</td>
<td>Compare thread IDs</td>
</tr>
<tr>
<td>pthread_once()</td>
<td>Run a function once per process</td>
</tr>
<tr>
<td>pthread_yield()</td>
<td>Yield the processor</td>
</tr>
</tbody>
</table>

Creating a thread

To use a thread you must first create a thread attribute object with the pthread_attr_init() function. A thread attribute object defines the modifiable characteristics that a thread may have. Refer to the description of pthread_attr_init() in z/OS XL C/C++ Runtime Library Reference for a list of the attributes and their default values. When the thread attribute object has been created, you may use the functions listed in Table 69 to change the default attributes.

Table 69. Functions to change default attributes

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_attr_init()</td>
<td>Initialize a thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_destroy()</td>
<td>Delete a thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_getguardsize()</td>
<td>Gets the threadstack guardsize from the thread attribute object</td>
</tr>
</tbody>
</table>
Table 69. Functions to change default attributes (continued)

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_attr_setguardsize()</td>
<td>Sets the threadstack guardsize in the thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_getschedparam()</td>
<td>Gets the schedparam from the thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_setschedparam()</td>
<td>Sets the schedparam in the thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_getstack()</td>
<td>Gets the stacksize and base storage address of application-managed stack</td>
</tr>
<tr>
<td>pthread_attr_setstack()</td>
<td>Sets the stacksize and base storage address of application-managed stack</td>
</tr>
<tr>
<td>pthread_attr_getstacksize()</td>
<td>Gets the stacksize for thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_setstacksize()</td>
<td>Sets the stacksize for thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_getdetachstate()</td>
<td>Returns current value of detachstate for thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_setdetachstate()</td>
<td>Alters the current detachstate of thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_getweight_np()</td>
<td>Obtains the current weight of thread setting</td>
</tr>
<tr>
<td>pthread_attr_setweight_np()</td>
<td>Alters the current weight of thread setting</td>
</tr>
<tr>
<td>pthread_attr_getsynctype_np()</td>
<td>Returns the current synctype setting of thread attribute object</td>
</tr>
<tr>
<td>pthread_attr_setsynctype_np()</td>
<td>Alters the synctype setting of thread attribute object</td>
</tr>
</tbody>
</table>

The attribute object is only used when the thread is created. You can reuse it to create other threads with the same attributes, or you can modify it to create threads with other attributes. You can delete the attribute object with the pthread_attr_destroy() function.

After you create the thread attribute object, you can then create the thread with the pthread_create() function.

When a daughter thread is created, the function specified on the pthread_create() as the start routine begins to execute concurrently with the thread that issued the pthread_create(). It may use the pthread_self() function to determine its thread ID. The daughter thread will continue to execute until a pthread_exit() is issued, or the start routine ends. The function that issued the pthread_create() resumes as soon as the daughter thread is created. The daughter thread ID is returned on a successful pthread_create(). This thread ID, for example, can be used to send a signal to the daughter thread using pthread_kill() or it can be used in pthread_join() to cause the initiating thread to wait for the daughter thread to end.

Table 70 lists functions that can be used to control the behavior of the individual threads in a multi-threaded application. Refer to z/OS XL C/C++ Runtime Library Reference for more information on these functions.

Table 70. Functions used to control individual threads in a multi-threaded environment

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_equal()</td>
<td>Compares two thread IDs</td>
</tr>
<tr>
<td>pthread_yield()</td>
<td>Allows threads to give up control</td>
</tr>
</tbody>
</table>
Synchronization primitives

This section covers the control of multiple threads that may share resources. In order to maintain the integrity of these resources, a method must exist for the threads to communicate their use of, or need to use, a resource. The threads can be within a common process or in different processes.

Models

Mutexes, condition variables, and read-write locks are used to communicate between threads. These constructs may be used to synchronize the threads themselves, or they can also be used to serialize access to common data objects shared by the threads.

- The mutex, which is the simple type of lock, is exclusive. If a thread has a mutex locked, the next thread that tries to acquire the same mutex is put in a wait state. This is beneficial when you want to serialize access to a resource. This might cause contention however if several threads are waiting for a thread to unlock a mutex. Therefore, this form of locking is used more for short durations. If the mutex is a shared mutex, it must be obtained in shared memory accessible among the cooperating processes.

A thread in mutex wait will not be interrupted by a signal.

- A condition variable provides a mechanism by which a thread can suspend execution when it finds some condition untrue, and wait until another thread makes the condition true. For example, threads could use a condition variable to insure that only one thread at a time had write access to a data set.

Threads in condition wait can be interrupted by signals.

- A read-write lock can allow many threads to have simultaneous read-only access to data while allowing only one thread at a time to have write access. The read-write lock must be allocated in memory that is writable. If the read-write lock is a shared read-write lock, it must be obtained in shared memory accessible among the cooperating processes.

Functions

Table 71 lists functions that allow for synchronization between threads.

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_mutex_init()</td>
<td>Initialize a Mutex</td>
</tr>
<tr>
<td>pthread_mutex_destroy()</td>
<td>Destroy a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_init()</td>
<td>Initialize Default Attribute Object for a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_destroy()</td>
<td>Destroy Attribute Object for a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_getkind_np()</td>
<td>Get Kind Attribute for a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_setkind_np()</td>
<td>Set Kind Attribute for a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_gettype()</td>
<td>Get Type Attribute for a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_settype()</td>
<td>Set Type Attribute for a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_getpshared()</td>
<td>Get Process-shared Attribute for a Mutex</td>
</tr>
<tr>
<td>pthread_mutexattr_setpshared()</td>
<td>Set Process-shared Attribute for a Mutex</td>
</tr>
<tr>
<td>pthread_mutex_lock()</td>
<td>Acquire a Mutex Lock</td>
</tr>
<tr>
<td>pthread_mutex_unlock()</td>
<td>Release a Mutex Lock</td>
</tr>
<tr>
<td>pthread_mutex_trylock()</td>
<td>Allows lock to be tested</td>
</tr>
<tr>
<td>pthread_cond_init()</td>
<td>Initialize a Condition Variable</td>
</tr>
</tbody>
</table>
### Table 71. Functions that allow for synchronization between threads (continued)

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_cond_destroy()</td>
<td>Destroy a Condition Variable</td>
</tr>
<tr>
<td>pthread_condattr_init()</td>
<td>Initialize Default Attribute Object for a Condition Variable</td>
</tr>
<tr>
<td>pthread_condattr_destroy()</td>
<td>Destroy Attributes Object for a Condition Variable</td>
</tr>
<tr>
<td>pthread_condattr_getkind_np()</td>
<td>Get Attribute for Condition Variable object</td>
</tr>
<tr>
<td>pthread_condattr_setkind_np()</td>
<td>Set Attribute for Condition Variable object</td>
</tr>
<tr>
<td>pthread_condattr_getpshared()</td>
<td>Get the Process-shared Condition Variable Attribute</td>
</tr>
<tr>
<td>pthread_condattr_setpshared()</td>
<td>Set the Process-shared Condition Variable Attribute</td>
</tr>
<tr>
<td>pthread_cond_wait()</td>
<td>Wait for a Condition Variable</td>
</tr>
<tr>
<td>pthread_cond_timedwait()</td>
<td>Timed wait for a Condition Variable</td>
</tr>
<tr>
<td>pthread_cond_signal()</td>
<td>Signal a Condition Variable</td>
</tr>
<tr>
<td>pthread_cond_broadcast()</td>
<td>Broadcast a Condition Variable</td>
</tr>
<tr>
<td>pthread_rwlock_init()</td>
<td>Initialize a Read-Write Lock</td>
</tr>
<tr>
<td>pthread_rwlock_destroy()</td>
<td>Destroy a Read-Write Lock</td>
</tr>
<tr>
<td>pthread_rwlock_rdlock()</td>
<td>Wait for a Read Lock</td>
</tr>
<tr>
<td>pthread_rwlock_tryrdlock()</td>
<td>Allows Read Lock to be Tested</td>
</tr>
<tr>
<td>pthread_rwlock_trywrlock()</td>
<td>Allows Read-Write Lock to be Tested</td>
</tr>
<tr>
<td>pthread_rwlock_unlock()</td>
<td>Release a Read-Write Lock</td>
</tr>
<tr>
<td>pthread_rwlock_wrlock()</td>
<td>Wait for a Read-Write Lock</td>
</tr>
<tr>
<td>pthread_rwlockattr_init()</td>
<td>Initialize Default Attribute Object for a Read-Write Lock</td>
</tr>
<tr>
<td>pthread_rwlockattr_destroy()</td>
<td>Destroy Attribute Object for a Read-Write Lock</td>
</tr>
<tr>
<td>pthread_rwlockattr_getpshared()</td>
<td>Get Process-shared Attribute for a Read-Write Lock</td>
</tr>
<tr>
<td>pthread_rwlockattr_setpshared()</td>
<td>Set Process-shared Attribute for a Read-Write Lock</td>
</tr>
</tbody>
</table>

### Creating a mutex

To use the mutex lock you must first create a mutex attribute object with the `pthread_mutexattr_init()` function. A mutex attribute object defines the modifiable characteristics that a mutex may have. Refer to the description of `pthread_mutexattr_init()` in `z/OS XL C/C++ Runtime Library Reference` for a list of these attributes and their defaults.

After the mutex attribute object has been created, you can use the following functions to change the default attributes.

- `pthread_mutexattr_getkind_np()`
- `pthread_mutexattr_setkind_np()`
- `pthread_mutexattr_gettype()`
- `pthread_mutexattr_settype()`
- `pthread_mutexattr_getpshared()`
- `pthread_mutexattr_setpshared()`
The mutex attribute object is used only when creating the mutex. It can be used to create other mutexes with the same attributes or modified to create mutexes with different attributes. You can delete a mutex attribute object with the `pthread_mutexattr_destroy()` function.

After the mutex attribute object has been created, the mutex can be created with the `pthread_mutex_init()` function.

While using mutexes as the locking device, the following functions can be used:

- `pthread_mutex_lock()`
- `pthread_mutex_unlock()`
- `pthread_mutex_trylock()`

To remove the mutex, use the `pthread_mutex_destroy()` function.

**Note:** Before freeing up the storage containing the `pthread_mutexattr_t` object, be sure to destroy it by calling `pthread_mutexattr_destroy()`. If the `pthread_mutexattr_t` object is not destroyed before the storage is reused, the results are undefined.

**Creating a condition variable**

Before creating a condition variable, you need to create a mutex (as shown above), then you must use the `pthread_condattr_init()` function to create a condition variable attribute object. This attribute object, like the mutex attribute object, defines the modifiable characteristics that a condition variable may have. Refer to the description of `pthread_condattr_init()` in *z/OS XL C/C++ Runtime Library Reference* for a list of these attributes and their defaults.

After the condition variable attribute object has been created, you may use the following functions to change the default attributes:

- `pthread_condattr_getkind_np()`
- `pthread_condattr_setkind_np()`
- `pthread_condattr_getpshared()`
- `pthread_condattr_setpshared()`

The condition variable attribute object is used only when creating the condition variable. It can be used to create other condition variables with the same attributes or modified to create condition variables with different attributes. You can delete a condition variable attribute object with the `pthread_condattr_destroy()` function.

After a condition variable attribute object has been created, the condition variable itself can be created with the `pthread_cond_init()` function.

Condition variables can then be used as a synchronization primitive using the following functions:

- `pthread_cond_wait()`
- `pthread_cond_timedwait()`
- `pthread_cond_signal()`
- `pthread_cond_broadcast()`

The condition variable can be removed with the `pthread_cond_destroy()` function.
Creating a read-write lock

To use a read-write lock you must first create a read-write attribute object with the `pthread_rwlockattr_init()` function. A read-write attribute object defines the modifiable characteristics that a read-write lock may have. Refer to the description of `pthread_rwlockattr_init()` in z/OS XL C/C++ Runtime Library Reference for a list of these attributes and their defaults.

After the read-write lock attribute object has been created, you can use the following functions to change the default attributes.

- `pthread_rwlockattr_getpshared()`  
- `pthread_rwlockattr_setpshared()`

The read-write lock attribute object is used only when creating the read-write lock. It can be used to create other read-write locks with the same attributes or modified to create read-write locks with different attributes. You can delete a read-write attribute object with the `pthread_rwlockattr_destroy()` function.

After the read-write attribute has been created, the read-write lock can be created with the `pthread_rwlock_init()` function.

While using read-write locks as the locking device, the following functions can be used:

- `pthread_rwlock_rdlock()`  
- `pthread_rwlock_tryrdlock()`  
- `pthread_rwlock_wrlock()`  
- `pthread_rwlock_trywrlock()`  
- `pthread_rwlock_unlock()`

To remove the read-write lock, use the `pthread_rwlock_destroy()` function.

Thread-specific data

While all threads can access the same memory, it is sometimes desirable to have data that is logically local to a specific thread. The key/value mechanism provides for global (process-wide) keys with value bindings that are unique to a thread.

You can also use the `pthread_tag_np()` function to set and query 65 bytes of thread tag data associated with the caller's thread.

Model

The key/value mechanism associates a data key with each data item. When the association is made, the key identifies the data item with a particular thread. This data key is a transparent data object of type `pthread_key_t`. The contents of this key are not exposed to the user.

The user gets a key by issuing the `pthread_key_create()` function. One of the arguments on the `pthread_key_create()` function is a pointer to a local variable of type `pthread_key_t`. This variable is then used with the `pthread_setspecific()` function to establish a unique key value.

`pthread_key_create()` creates a unique identifier (a key) that is visible to all of the threads in a process. This data key is returned to the caller of `pthread_key_create()`. Threads can associate a thread unique data item with this key using the `pthread_setspecific()` call. A thread can get its unique data value for a key using the `pthread_getspecific()` call. In addition, a key can have an
optional "destructor" routine associated with it. This routine is executed during thread termination and is passed the value of the key for the thread being terminated. A typical use of a key and destructor is to have storage obtained by a thread using malloc() and returned within the destructor at thread termination by using free().

pthread_key_delete() deletes a thread-specific data key. Once a key has been deleted, it may not be passed to pthread_getspecific() or pthread_setspecific(). Any destructor function associated with the key when it was created will no longer be called. The application must perform any cleanup needed for values associated with the key.

Functions

Table 72 lists functions that are used with thread-specific data.

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_key_create()</td>
<td>Create a thread-specific data key</td>
</tr>
<tr>
<td>pthread_key_delete()</td>
<td>Delete a thread-specific data key</td>
</tr>
<tr>
<td>pthread_getspecific()</td>
<td>Retrieve the value associated with a thread-specific key</td>
</tr>
<tr>
<td>pthread_setspecific()</td>
<td>Associate a value with a thread-specific key</td>
</tr>
<tr>
<td>pthread_tag_np()</td>
<td>Set and query the contents of the calling thread's tag data</td>
</tr>
</tbody>
</table>

Creating thread-specific data

Figure 99 on page 360 shows the example program CCNGTH1, which uses thread-specific data to insure that storage acquired by a specific thread is freed when the thread ends.
Signals

Each thread has an associated signal mask. The signal mask contains a flag for each signal defined by the system. The flag determines which signals are to be blocked from being delivered to a particular thread.

Unlike the signal mask, there is one signal action per signal for all of the threads in the process. Some signal functions work on the process level, having an impact on multiple threads, while others work on the thread level, and only affect one particular thread. For example, the function kill() operates at the process level, whereas the functions pthread_kill() and sigwait() operate at the thread level.

The following are some other signal functions that operate on the process level and can influence multiple threads:

- alarm()
- bsd_signal()
- kill()
- killpg()
- raise()
Generates a signal

A signal can be generated explicitly with the `raise()`, `kill()`, `killpg()`, or `pthread_kill()` functions or implicitly with functions such as `alarm()` or by the system when certain events occur. In all cases, the signal will be directed to a specific thread running in a process.

The two primary functions for controlling signals are `sigaction()` and `sigprocmask()`. `sigaction()` also includes `bsd_signal()`, `signal()`, and `sigset()`.

**sigaction()**

`sigaction()` specifies the action when a signal is processed by the system. This function is process-scoped instead of thread-specific. When a signal is generated for a process, the state of each thread within that process determines which thread is affected. The three types of signal actions are:

- **catcher**: Specifies the address of a function that will get control when the signal is delivered
- **SIG_DFL**: Specifies that the system should perform default processing when this signal type is generated
- **SIG_IGN**: Specifies that the system should ignore all signals of this type.

**Attention**: If a signal whose default action is to terminate is delivered to a thread running in a process where there are multiple threads running, and no signal catcher is designated for the signal, the entire process is terminated. You can avoid this by blocking each of the terminating signals, or by establishing a signal catcher for each of them.

In a multi-threaded application, when a signal is generated by a function or action that is not thread specific, and the process has some threads set up for signals and some threads that are not set up for signals, then the kernel’s signal processing determines which thread has the most interest in the signal.

The following is a list of signal interest rules in their order of priority:

1. When threads are found in a `sigwait()` for this signal type, the signal is delivered to the first thread found in a `sigwait()`.
2. When all threads are blocking this signal type, the signal is left pending in the kernel at the process level. The `sigpending` function moves blocked pending signals at the process level to the thread level.
3. When all of the following are true:
   - One or more threads are set up for signals
   - All threads set up for signals have the signal blocked
   - A thread not set up for signals has not blocked the signal

The signal is left pending in the kernel on the first thread set up for signals. The signal remains pending on that thread until the thread unblocks the signal.
4. When the signal action is to catch, the signal is delivered to one of the threads that has the signal unblocked.

**sigprocmask()**

`sigprocmask()` specifies a way to control which set of signals interrupt a specific thread. Because `sigprocmask()` is thread-scoped, it blocks the signal for only the thread that issues the function.

**Thread cancellation**

When multiple threads are running in a process, thread cancellation permits one thread to cancel another thread in that process. This is done with the `pthread_cancel()` function, which causes the system to generate a cancel interrupt and direct it to the thread specified on the `pthread_cancel()`. Each thread can control how the system generates this cancel interrupt by altering the interrupt state and type.

A thread may have the following interrupt states, in descending order of control:

**disabled**

For short code sequences, the entire code sequence can be disabled to prevent cancel interrupts. The `pthread_setintr()` and `pthread_setcancelstate()` functions enable or disable cancel interrupts in this manner.

**controlled**

For larger code sequences where you want some control over the interrupts but cannot be entirely disabled, set the interrupt type to controlled/deferred and the interrupt state to enabled. The `pthread_setintrtype()` and `pthread_setcanceltype()` functions allow for this type of managed interrupt delivery by introducing the concept of cancellation points.

Cancellation points consist of calls to a limited set of library functions, documented below.

The user program can implicitly or explicitly solicit interrupts by invoking one of the library functions in the set of cancellation points, thus allowing the user to control the points within their application where a cancel may occur.

**asynchronous**

For code sequences where you do not need any control over the interrupt, set `pthread_setintr()`/`pthread_setcancelstate()` to enable and `pthread_setintrtype()`/`pthread_setcanceltype()` to asynchronous. This will allow cancel interrupts to occur at any point within your program.

For example, if you have a critical code section (a sequence of code that needs to complete), you would turn cancel off or prevent the sequence from being interrupted. If the code is relatively long, consider running using the control interrupt and as long as the critical code section doesn't contain any of the functions that are considered cancellation points, it will not be unexpectedly canceled.

For C++, destructors for automatic objects on the stack are run when a thread is cancelled. The stack is unwound and the destructors are run in reverse order.
Cancellation Points
The library functions listed in Table 73 and any of their callers, will introduce cancellation points into a thread’s execution.

Table 73. Cancellation point summary

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>accept()</td>
<td>aio_suspend()</td>
</tr>
<tr>
<td>creat()</td>
<td>fsync()</td>
</tr>
<tr>
<td>getpmsg()</td>
<td>msync()</td>
</tr>
<tr>
<td>pause()</td>
<td>read()</td>
</tr>
<tr>
<td>pwrite()</td>
<td>recv()</td>
</tr>
<tr>
<td>recvfrom()</td>
<td>select()</td>
</tr>
<tr>
<td>sendmsg()</td>
<td>sigpause()</td>
</tr>
<tr>
<td>sigtimedwait()</td>
<td>tcdrain()</td>
</tr>
<tr>
<td>wait()</td>
<td>waitpid()</td>
</tr>
<tr>
<td>writev()</td>
<td>write()</td>
</tr>
</tbody>
</table>

Functions
Table 74 lists functions that are used to control the cancellability of a thread.

Table 74. Functions used to control cancellability

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>pthread_cancel()</td>
<td>Cancel a thread</td>
</tr>
<tr>
<td>pthread_setintr()</td>
<td>Set thread cancellability state</td>
</tr>
<tr>
<td>pthread_setintrtype()</td>
<td>Set thread cancellability type</td>
</tr>
<tr>
<td>pthread_testintr()</td>
<td>Establish a cancellability point</td>
</tr>
<tr>
<td>pthread_setcancelstate()</td>
<td>Set thread cancellability state</td>
</tr>
<tr>
<td>pthread_setcanceltype()</td>
<td>Set thread cancellability type</td>
</tr>
<tr>
<td>pthread_testcancel()</td>
<td>Establish a cancellability point</td>
</tr>
</tbody>
</table>

Cancelling a thread
Three possible scenarios may cancel a thread, one for each of the interrupt states of the thread being canceled.

- One thread issues `pthread_cancel()` to another thread whose cancellability state is enabled and controlled. In this case the thread being canceled continues to run until it reaches an appropriate cancellation point. When the thread is eventually cancelled, just prior to termination of the thread, any cleanup handlers which have been pushed and not yet popped will be executed. Then if the thread has any thread-specific data, the destructor functions associated with this data will be executed.

- One thread issues `pthread_cancel()` to another thread whose interruption state is enabled and asynchronous. In this case the thread being canceled is terminated immediately, after any cleanup handlers and thread-specific data destructor functions are executed, as in the first scenario.

- One thread issues `pthread_cancel()` to another thread whose interruption state is disabled. In this case the cancel request is ignored and the thread being canceled continues to run normally.

In the first two interrupt states, the caller of `pthread_cancel()` may get control back before the thread is actually canceled.
Cleanup for threads

Cleanup handlers are routines written by the user that include any special processing the user finds necessary for termination of a thread. As the user’s routine executes, it pushes cleanup handlers on to a stack. As the thread continues to run and the routine progresses, these cleanup handlers can be taken off of the stack by the user’s routine.

A list or stack of cleanup handlers is maintained for each thread. When the thread ends, all pushed but not yet popped cleanup routines are popped from the cleanup stack and executed in last-in-first-out (LIFO) order. This occurs when the thread:

- Calls `pthread_exit()`
- Does a return from or reaches the end of the start routine (that gets controls as a result of a `pthread_create()`)
- Is canceled because of a `pthread_cancel()`.

The first thread in a process to call `pthread_create()` becomes the initial pthread-creating task (IPT). When exiting back to the operating system from the IPT, the caller may receive an A03 abend if any pthread_created tasks are still running. These tasks may still be running even if the IPT has called `pthread_join()` for all the threads that it created. To avoid the A03 abend, the IPT should call `_exit()` when it is ready to return to the operating system. `_exit()` ends the IPT and all of its pthread_created subtasks without causing an A03 abend to occur.

Functions

Table 75 lists functions that are used for thread cleanup.

<table>
<thead>
<tr>
<th>Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>pthread_cleanup_push()</code></td>
<td>Establish a cleanup handler</td>
</tr>
<tr>
<td><code>pthread_cleanup_pop()</code></td>
<td>Remove a cleanup handler</td>
</tr>
</tbody>
</table>

Thread stack attributes

Three attributes allow POSIX applications to control their threads’ stack usage: stackaddr, stacksize, and guardsize.

The stackaddr attribute contains the address of application-provided storage to be used as the initial stack segment. This storage is referred to as an "application-managed stack".

The stacksize attribute controls the size of the stack. In an SUSv3 application, calls to `pthread_attr_setstacksize()` or `pthread_attr_setstack()` must provide a stacksize of at least PTHREAD_STACK_MIN. If not provided, the initial increment size is derived from the STACK64/THREADSTACK64 runtime options in AMODE 64, or STACK/THREADSTACK otherwise.

When used in conjunction with application-managed stack, the size of the storage must be a multiple 4K on ILP32 (AMODE31) and 1M on L64 (AMODE64), and at least PTHREAD_STACK_MIN in length.

For portability, `pthread_attr_getguardsize()` and `pthread_attr_setguardsize()` may modify the guardsize in the thread attribute object, but the guardsize attribute is not honored on z/OS for system-managed stack. In the case of application-managed stack, guarding is an application responsibility.
The guardsize attribute is not honored on z/OS.

When a thread is created using an attribute object with a stackaddr attribute set, behavior is undefined if the application ever accesses the same storage again, except through normal stack access in that thread. An attribute object with stackaddr attribute set may not be used more than once, unless it is destroyed and re-initialized, or its stackaddr attribute changed.

Behaviors and restrictions in z/OS UNIX applications

The following are implementation-specified behaviors and restrictions that apply to the XL C/C++ library functions when running a multi-threaded z/OS UNIX application.

Using threads with MVS files

MVS files that are opened by data-set names or ddnames are thread-specific in the following ways:

MVS files opened in update mode where repositioning functions are used after the files have been extended are also restricted to the owning thread. This is because a reposition might need to reopen the read DCB in order to be able to see the new EOF marker. The runtime library does not enforce this restriction.

Multivolume data sets, files that are part of a concatenated ddname, and hiperspace memory files are further restricted in multithreaded applications. All I/O operations are restricted to the thread on which the file is opened.

When standard streams are directed to MVS files, they are governed by the previous restrictions. Standard streams are directed to MVS files in one of two ways:

- By default when a main() program is run from the TSO ready prompt or by a JCL EXEC PGM= statement, that is, whenever it is not initiated by the exec() function. This is regardless of whether you are running with POSIX(ON) or POSIX(OFF). In these cases, the owning thread is the initial processing thread (IPT), the thread on which main() is executed.
- By explicit action when the user redirects the streams by using command line redirection, fopen(), or freopen(). The thread that is redirected (the IPT, if you are using command line redirection) becomes the owning thread of the particular standard stream. The usual MVS file thread affinity restrictions outlined above apply until the end of program or until the stream is redirected to the UNIX file system.

Any operation that violates these restrictions causes SIGIOERR to be raised and errno to be set with the following associated message:

EDC5024I: An attempt was made to close a file that had been opened on another thread.

All MVS files opened from a given thread and still open when the thread is terminated are closed automatically by the library during thread termination.

Having more than one writer use separate file pointers to a single data set or ddname is prohibited as always, regardless of whether the file pointers are used from multiple threads or a single thread.
Note: These restrictions specifically do not apply to UNIX file system. All opens and closes by the C library that result in calls to an underlying access method for a given MVS file must occur on the same thread. Therefore, the following specific functions are prohibited from any thread except the owning thread (the one that does the initial fopen()) of the file:

- fclose()
- freopen()
- rewind()

Multithreaded I/O

The getc(), getchar(), putc(), and putchar() functions have two versions, one that is defined in the header file, stdio.h, which is a macro and the other which is an actual library routine. The macros have better performance than their respective function versions, but these macros are not thread safe, so in a multithreaded application where _OPEN_THREADS feature test macro is defined, the macro version of these functions are not exposed. Instead, the library functions are used. This is done to ensure thread safety while multiple threads are executing.

The getc_unlocked(), getchar_unlocked(), putc_unlocked(), and putchar_unlocked() functions and macros are functionally equivalent to the getc(), getchar(), putc(), and putchar() functions and macros. These functions and macros can safely be used in a multi-thread environment if and only if called from a thread that owns the FILE* object, such as after a successful call to flockfile() or ftrylockfile().

Use of the getc_unlocked(), getchar_unlocked(), putc_unlocked(), or putchar_unlocked() functions can have unpredictable behavior when used on a thread that has not locked the file.

It is the application's responsibility to prevent deadlocks or looping. For example, deadlock or looping may occur if a FILE* object is closed, or a thread is terminated, before relinquishing all locked FILE* objects.

Thread-scoped functions

Thread-scoped functions are functions that execute independently on each thread without sharing intermediate state information across threads. For example, strtok() preserves pointers to tokens independently on each thread, regardless of the fact that multiple threads may be examining the same string in a strtok() operation. Some examples of thread-scoped functions are:

- strtok()
- rand(), srand()
- mblen(), mbtowc()
- strerror()
- asctime(), ctime(), gmtime(), localtime()
- clock()

The following are examples of process-scoped functions, which means that a call to these functions on one thread influences the results of calls to the same function on another thread. For example, tmpnam() is required to return a unique name for every invocation during the life of the process, regardless of which thread issues the call.

- tmpnam()
Unsafe thread functions

The following functions are not thread-safe. In a multithreaded application, therefore, they should only be used before the first invocation of pthread_create().

- `setlocale()` - (returns NULL if issued after pthread_create())
- `tzset()`

Fetched functions and writable statics

Fetched functions are recorded globally at the process level. Therefore, a function fetched from one thread can be executed from any thread.

Module boundary crossings are thread-scoped. Writable statics have a scope between process and thread. They are process-scoped except that module crossings are thread-scoped. This means that:

- All threads initially inherit the writable statics of the creating thread at the time of the creation.
- When any thread executes a function pointer supplied by the `fetch()` function and crosses a module boundary, only that thread has access to the writable statics of the fetched module.

MTF and z/OS UNIX threading

MTF is not supported from applications running under POSIX(ON). A return value of EWRONGOS is issued when running in a POSIX(ON) environment. An application that requires multithreading must either use MTF with POSIX(OFF) or pthread_create() with POSIX(ON).

Thread queuing function

The thread queuing function allows you to control whether or not threads should be queued up while waiting for TCBs to become available. You can accomplish this by switching the synctype attribute of a thread between synchronous and asynchronous mode. With synchronous mode for example, if a process can only have 50 TCBs active at any one time, then only 50 threads can be created. The 51st thread create results in an error. With asynchronous mode, however, you can set the synctype attribute for a thread such that the 51st thread is created. This thread will not start until one of the other threads finishes and releases a TCB.

Functions that relate to the ability to control thread queuing are:

- `pthread_set_limit_np()`
- `pthread_attr_getsynctype_np()`
- `pthread_attr_setsynctype_np()`

Thread scheduling

You can use the `pthread_attr_setweight_np()` and `pthread_attr_setsynctype_np()` functions to establish priorities for threads. The `pthread_attr_setweight_np()` threadweight variable can be set to the following:
Each thread runs on a task. When the current thread exits, the task waits for another thread to do a pthread_create(). The new thread runs on that task.

The task is attached on pthread_create() and terminates when the thread exits. When the thread exits, the associated task can no longer request threads to process, and full MVS EOT resource manager cleanup occurs.

You can use the pthread_addt_setsynctype_np() function to set the __PTATASYNCHRONOUS value. This enables you to create more threads than there are TCBs available. For example, you could run 50 TCBs and create hundreds of threads. The kernel queues the threads until a task is available. This frees your application from managing the work. While a thread is queued and not executing on an MVS task, you can still interact with the thread via pthread functions, such as pthread_join() and pthread_kill().

iconv() family of functions

The conversion descriptor returned from a successful iconv_open() may be used safely within a single thread for conversion purposes. It may, however, be opened on one thread (iconv_open()), closed on another thread (iconv_close()), and used on a third thread (iconv()). However, it is the user’s responsibility to ensure operations are synchronized if they are used across multiple threads.

Note: The iconv_open() function tolerates converter names without a dash in the name for all converter names containing dashes. For example, iconv_open() tolerates the name IBM1047 for the IBM-1047 converter.
Chapter 25. Reentrancy in z/OS XL C/C++

This information describes the concept of reentrancy. It tells you how to use reentrancy in C programs to help make your programs more efficient, and how C++ achieves constructed reentrancy.

Reentrant programs are structured to allow multiple users to share a single copy of an executable module or to use an executable module repeatedly without reloading. C and C++ achieve reentrancy by splitting your program into two parts, which are maintained in separate areas of memory until the program terminates:

- The first part, which consists of executable code and constant data, does not change during program execution.
- The second part contains persistent data that can be altered. This part includes the dynamic storage area (DSA) and a piece of storage known as the writable static area.

For XPLINK, the writable static area is further logically subdivided into areas called environments. Environments are optional, and each function can have its own environment. When an XPLINK function is called, the caller must load general purpose register 5 with the address of the environment of the called function before control is given to the entry point of the called function.

If the program is installed in the Link Pack Area (LPA) or Extended Link Pack Area (ELPA) of your operating system, only a single copy of the first (constant or reentrant) part exists within a single address space. This occurs regardless of the number of users that are running the program simultaneously. This reentrant part may be shared across address spaces or across sessions. In this case, the executable module is loaded only once. Separate concurrent invocations of the program share or reenter the same copy of the write-protected executable module. If the program is not installed in the LPA or ELPA area, each invocation receives a private copy of the code part, but this copy may not be write-protected.

The modifiable writable static part of the program contains:

- All program variables with the static storage class
- All program variables receiving the extern storage class
- All writable strings
- All function linkage descriptors for all referenced DLL functions
- Function linkage descriptors for all referenced DLL functions that are used by multiple compilation units in the program, but are not imported (XPLINK, RENT)
- All variable pointers for imported variables (non-XPLINK)
- All function pointers for imported functions (XPLINK, RENT)
- All variable linkage descriptors to reference imported variables (non-XPLINK)

Each user running the program receives a private copy of the second (data or non-reentrant) part. This part, the data area, is modifiable by each user.

The code part of the program contains:

- Executable instructions
- Read-only constants
Global objects compiled with the #pragma variable(identifier, NORENT)

Note: The ROCONST compiler option implicitly inserts a #pragma variable(identifier, NORENT) for const qualified variables.

Natural or constructed reentrancy

Natural reentrancy

C programs that contain no references to the writable static objects listed in a previous section have natural reentrancy. You do not need to compile naturally reentrant C programs with the RENT compiler option or bind them with the binder.

Constructed reentrancy

C++ programs, and C programs that contain references to writable static objects, can have constructed reentrancy. You must bind these programs with the binder. For C programs, you must use the RENT compiler option.

If you use the XPLINK option, RENT is the default. If you override this default by specifying NORENT, any parts of the program that are normally stored in the writable static area go instead into a static area. If this static area is write-protected, you will get a runtime failure because the function pointers for imported functions cannot be modified to point to the function when the DLL containing the function is loaded and the function address determined. For programs that are both XPLINK and NORENT, all functions must be statically bound or explicitly loaded (dllload(), or fetch()).

Limitations of constructed reentrancy for C programs

Even if a C program is large and will have more than one user at the same time, there are also these limitations to consider:

• The binder is required for code that you compile with XPLINK.
• If the prelinker, rather than the binder, will process code that is compiled with NOXPLINK, RENT:
  – The resultant load module referring to the writable area cannot be reprocessed.
  – The resultant program may reside in a PDS.
• If the binder is used, and not the prelinker, the resultant program must reside in a PDSE or UNIX file system. If a PDSE member should be installed into LPA or ELPA, it can only be installed into dynamic LPA.
• A system programmer can install only the shared portion of your program in the LPA or ELPA of your operating system.

Controlling external static in C programs

Certain program variables with the extern storage class may be constant and never written. If this is the case, every user does not need to have a separate copy of these variables. In addition, there may be a need to share constant program variables between C and another language.

You can force an external variable to be the part of the program that includes executable code and constant data by using the #pragma variable(varname, NORENT) directive. The program fragment in Figure 100 on page 371 illustrates how this is accomplished.
In this example, the source file is compiled with the RENT option. The external variable rates are included in the executable code because #pragma variable(rates, NORENT) is specified. The variable totals are included with the writable static. Each user has a copy of the array totals, and the array rates are shared among all users of the program.

The #pragma variable(varname, NORENT) does not apply to, and has no effect on, program variables with the static storage class. Program variables with the static storage class are always included in the writable static. An informational message will appear if you do try to write to a non-reentrant variable when you specify the CHECKOUT compiler option.

When specifying #pragma variable(varname, NORENT), ensure that this variable is never written; if it is written, program exceptions or unpredictable program behavior may result. In addition, you must include #pragma variable(varname, NORENT) in every source file where the variable is referenced or defined. It is good practice to put these pragmas in a common header file.

Note: You can also use the keyword const to ensure that a variable is not written. See the const type qualifier in z/OS XL C/C++ Language Reference for more information.

The ROCONST compiler option has the same effect as specifying the #pragma variable (var_name, NORENT) for all constant variables (i.e. const qualified variables). The option gives the compiler the choice of allocating const variables outside of the Writable Static Area (WSA). For more information, see ROCONST | NORCONST in z/OS XL C/C++ User’s Guide.

Controlling writable strings

In a large number of C programs, character strings may be constant and never written to. If this is the case, every user does not need a separate copy of these strings.

You can force all strings in a given source file to be the part of the program that includes executable code and constant data by using #pragma strings(readonly) or the ROSTRING compiler option. Figure 101 on page 372 illustrates one way to make the strings constant.

Figure 101 on page 372 shows a sample program (CCNGRE1) that makes strings constant. The string "hello world\n" is included with the executable code because #pragma strings(readonly) is specified. This can yield a performance and storage benefit.
Ensure that you do not write to read-only strings. The following code tries to overwrite the literal string "abcd" because 'chrs' is just a pointer:
```
char chrs[] = "abcd";
memcpy(chrs,"ABCD",4);
```
Program exceptions or unpredictable program behavior may result if you attempt to write to a string constant.

The ROSTRING compiler option has the same effect as #pragma strings(readonly) in the program source. For more information, see ROSTRING | NOROSTRING in z/OS XL C/C++ User’s Guide.

Controlling the memory area in C++

In C++, some objects may be constant and never modified. If your program is reentrant, having such objects exist in the code part is a storage and performance benefit.

As a programmer, you control where objects with global names and string literals exist. You can use the #pragma variable(objname, NORENT) directive to specify that the memory for an object with a global name is to be in the code area. You can use the ROCONST compiler option to specify that all const variables go into the code area.

In Figure 102, the variable RATES exists in the executable code area because #pragma variable(RATES, NORENT) has been specified. The variable totals exists in writable static area. All users have their own copies of the array totals, but the array RATES is shared among all users of the program.

When you specify #pragma variable(objname,NORENT) for an object, and the program is to be reentrant, you must ensure that this object is never modified, even by constructors or destructors. Program exceptions or unpredictable behavior may result. Also, you must include #pragma variable(objname,NORENT) in every
source file where the object is referenced or defined. Otherwise, the compiler will generate inconsistent addressing for the object, sometimes in the code area and sometimes in the writable static area.

**Controlling where string literals exist in C++ code**

In z/OS XL C/C++, the string literals exist in the code part by default, and are not modifiable if the code is reentrant. In a large number of programs, string literals may be constant. In this case, every user does not need a separate copy of these strings.

By using the `#pragma strings(writable)` directive, you can ensure that the string literals for that compilation unit will exist in the writable static area and be modifiable. Figure 103, which shows sample program CCNGRE2, illustrates how to make the string literals modifiable.

```c
/* this example demonstrates how to make string literals modifiable */

#pragma strings(writable)
#include <iostream.h>
int main(void)
{
    char * s;
    s = "wall\n"; // point to string literal
    *(s+3) = 'k'; // modify string literal
    cout << s; // output "walk\n"
}
```

---

**Figure 103. How to Make String Literals Modifiable**

In this example, the string "wall\n" will exist in the writable static area because `#pragma strings(writable)` is specified. This modifies the fourth character.

**Using writable static in Assembler code**

Programming in C or C++ can eliminate most of the need to code in assembler. However, in cases where you must code in assembler, you may have a need to modify data in the writable static area of a C or C++ program, from within an assembler program.

**Notes:**

1. To call assembler from C++, you must use extern "OS" as documented in Chapter 19, “Using Linkage Specifications in C or C++,” on page 239.

2. The following macros, and access to writable static data from assembler are not supported for XPLINK programs.
   - EDCDXD
   - EDCLA
   - EDCDPLNK

One way to modify data in the writable static area is to pass the address of the writable static data item as a parameter to the assembler program. This may be difficult in some cases. The following assembler macros makes this easier:

   - EDCDXD
   - EDCLA
   - EDCDPLNK
These are in CEE.SCEEMAC(EDCDXD,EDCLA,EDCPLNK). The restriction on the names of writable static objects accessible in assembler code is that they are S-names. This means that they may be at most 8 characters long and may contain only characters allowed in external names by the assembler code.

The macro EDCDXD declares a writable static data item. EDCLA loads the address of the writable static data item into a register. Using the EDCLA macro in assembler code necessitates coding EDCDXD as well.

The EDCPLNK macro defines reference writable static data with the z/OS binder. This macro must appear before the first executable control section is initiated in the assembler source module. If there is more than one assembler source program in the input file, EDCPLNK must precede every assembler source program in any input file that defines or references writable static data. Figure 104 illustrates their use.

In this example, the external variable TBLDSA is declared using the EDCDXD macro. The size value of 0F (zero fullwords) indicates that DSA will be treated as an extern declaration in C or C++. Because TBLDSA is an extern declaration and not a definition, DSA must be defined in another C, C++, or assembler program. The EDCLA macro loads the general purpose register 1 with the address of DSA, which exists in the writable static area.

The external variable TBDLSA is declared using the EDCDXD macro. It is defined because its size is 20F (20 fullwords or 80 bytes) and corresponds to an external data definition in C or C++. When the program starts, TBDLSA is initialized to zero. Because TBDLSA is an external data definition, there should not be another definition of it in a C++, C, or assembler program.

When these macros are used, these pseudo-registers cannot be used within the same assembler program.
There are no assembler macros for static initialization of a variable with a nonzero value. You can do this by defining and initializing the variable in C or C++ and making an extern declaration for it in the assembler program. In the example assembler program, DSA is declared this way.

Figure 105 shows sample program CCNGRE4, which illustrates how to call the assembler program in Figure 104 on page 374.

```c
/* this example shows how to reference objects in the writable */
/* static area, from assembler code */
/* part 2 of 2 (other file is CCNGRE3) */
#include <stdio.h>
#ifdef __cplusplus
extern "OS" {
#endif
void GETDSA(void); /* assembler routine modifies DSA */
#ifdef __cplusplus
}
#endif
const int sz = 20; /* maximum call depth */
extern void * TBLDSA[sz]; /* defined in assembler program */
void * DSA; /* define it here, source name */
/* same as assembler name */

/* call yourself deeper and deeper */
/* save DSA pointers as you go */
void deeper( int i )
{
    if (i >= sz) /* if deep enough just return */
        return;
    GETDSA(); /* assign value to DSA */
    TBLDSA[i] = DSA; /* save value in table */
    deeper(i+1); /* go deeper in call chain */
}

int main(void) {
    int i;
    deeper(0);
    for(i=0; i<sz; i++)
        printf("depth %3d, DSA was at %p\n", i, TBLDSA[i]);
    return 0;
}
```

Figure 105. Referencing objects in the writable static area, Part 2
Chapter 26. Using decimal data types in C

This information refers to fixed-point decimal data types as decimal data types. The decimal data type is an extension of the ANSI C language definition. When using the decimal data types, you must include the decimal.h header file in your source code. That header file specifies the value of DEC_DIG, which sets the maximum length allowed for expressions, in significant digits, including integral and fractional parts.

Decimal data types are available only if the LANGLVL is EXTENDED by specifying the LANGLVL(EXTENDED) compiler option. For more information, see LANGLVL in z/OS XL C/C++ User’s Guide.

You can use decimal data types to represent large numbers accurately, especially in business and commercial applications for financial calculations. You can pass decimal arguments in function calls and in define macros. You can also declare decimal variables, data type definitions, arrays, structures, and unions that have decimal members.

When you use decimal variables, the following operators apply:

- Arithmetic
- Relational
- Assignment
- Comma
- Conditional
- Equality
- Logical
- Primary
- Unary

Decimal data type declarations

Use the type specifier decimal(n,p) to declare decimal variables and initialize them with fixed-point decimal constants. The decimal() macro is defined in <decimal.h>. The decimal(n,p) type specifier designates a decimal number with n digits and p decimal places. In this specifier, n is the total number of digits for the integral and decimal parts combined and p is the number of digits for the decimal part only. For example, decimal(5,2) represents a number, such as 123.45, where n=5 and p=2. Specifying the value for p is optional. If not specified, p has a default value of 0. n and p have a range of allowed values according to the following rules:

\[ p \leq n \]
\[ 1 \leq n \leq \text{DEC_DIG} \]
\[ 0 \leq p \leq \text{DEC_PRECISION} \]

Note: The header file decimal.h defines DEC_DIG (the maximum number of digits n) and DEC_PRECISION (the maximum precision p). Currently, there is a limit of a maximum of 31 digits.
Declaring fixed-point decimal constants

The syntax for fixed-point decimal constants is shown in Table 76.

Table 76. Declarations of fixed-point decimal constants

<table>
<thead>
<tr>
<th>Data type</th>
<th>Syntax</th>
</tr>
</thead>
<tbody>
<tr>
<td>fixed-point-decimal-constant</td>
<td>Use the following format:</td>
</tr>
<tr>
<td></td>
<td>fractional-constant fixed-point-decimal-suffix</td>
</tr>
<tr>
<td>fractional-constant</td>
<td>Use any one of the following formats:</td>
</tr>
<tr>
<td></td>
<td>digit-sequence . digit-sequence</td>
</tr>
<tr>
<td></td>
<td>. digit-sequence</td>
</tr>
<tr>
<td></td>
<td>digit-sequence</td>
</tr>
<tr>
<td>digit-sequence</td>
<td>Use any one of the following formats:</td>
</tr>
<tr>
<td></td>
<td>digit</td>
</tr>
<tr>
<td></td>
<td>digit-sequence digit</td>
</tr>
<tr>
<td>fixed-point-decimal-suffix</td>
<td>Use any one of the following formats:</td>
</tr>
<tr>
<td></td>
<td>D</td>
</tr>
<tr>
<td></td>
<td>d</td>
</tr>
</tbody>
</table>

A fixed-point decimal constant has a numeric part and a suffix that specifies its data type. The components of the numeric part may include a digit sequence representing the integral part, followed by a decimal point (.), followed by a digit sequence representing the fractional part. Either the integral part, the fractional part, or both are present.

Each fixed-point decimal constant has the attributes number of digits (digits) and number of decimal places (precision). Leading or trailing zeros are not discarded when the digits and the precision are determined.

Table 77 gives examples of fixed-point decimal constants and their corresponding attributes:

Table 77. Examples of Fixed-Point decimal constants and their attributes

<table>
<thead>
<tr>
<th>Fixed-Point Decimal Constant</th>
<th>(digits, precision)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1234567890123456D</td>
<td>(16, 0)</td>
</tr>
<tr>
<td>1234567812345678D</td>
<td>(16, 8)</td>
</tr>
<tr>
<td>12345678.d</td>
<td>(8, 0)</td>
</tr>
<tr>
<td>.1234567890d</td>
<td>(10, 10)</td>
</tr>
<tr>
<td>12345.99d</td>
<td>(7, 2)</td>
</tr>
<tr>
<td>000123.990d</td>
<td>(9, 3)</td>
</tr>
<tr>
<td>0.00D</td>
<td>(3, 2)</td>
</tr>
</tbody>
</table>

Declaring decimal variables

The following example shows how you can declare a variable as a decimal data type:
x  can have values between -99999999.99D and +99999999.99D
y and z  can have values between -9999D and +9999D
ptr  pointer to type decimal(18,10)
arr  array of 100 elements, where each element is of type decimal(8,2)

The syntax for the decimal data type specifier is as follows:

```
Syntax

decimal ( constant-expression , constant-expression )
```

The constant-expression is evaluated as a positive integral constant expression.
Specifying a second constant-expression is optional. If left out, the default value is 0.
Decimal variables decimal(n,0) and decimal(n) are type-compatible.

### Defining decimal-type constants

Use the following numerical limits to define the decimal-type constant value in assignments and expressions. The decimal.h header file contains these predefined values.

- The smallest number that is valid for a decimal data type
  
  DEC_MIN
  
  \(-9999999999999999999999999999999\)D

- The largest positive number that is valid for a decimal data type
  
  DEC_MAX
  
  \(+9999999999999999999999999999999\)D

- The smallest number greater than zero that is valid for a decimal data type
  
  DEC_EPSILON
  
  \(.000000000000000000000000000000001\)D

- Maximum number of significant digits that decimal data types can hold
  
  DEC_DIG

  31

- Maximum number of decimal places that decimal data types can hold
  
  DEC_PRECISION

  31
Using operators on decimal data types

You can use arithmetic, relational, assignment, comma, conditional, equality, logical, primary, and unary cast operators on a decimal data type. Conversions follow these arithmetic conversion rules:

- First, if the type of either operand is long double, the other operand becomes long double.
- Otherwise, if the type of either operand is double, the other operand becomes double.
- Otherwise, if the type of either operand is float, the other operand becomes float.
- Otherwise, if the type of either operand is decimal, the other operand becomes decimal.
- Otherwise, the integral promotions are performed on both operands. Then the following rules are applied:
  - If the type of either operand is unsigned long int, the other operand becomes unsigned long int.
  - Otherwise, if the type of one operand is long int and the other is unsigned int, the operand of type unsigned int is converted to long int, if the long int can represent all values of an unsigned int. If a long int cannot represent all the values of an unsigned int, both operands become unsigned long int.
  - Otherwise, if the type of either operand is long int, the other operand becomes long int.
  - Otherwise, if the type of either operand is unsigned int, the other operand becomes unsigned int.
  - Otherwise, the type of both operands is int.

Arithmetic operators

[Figure 106 on page 381] shows how to use arithmetic operators, and then describes certain arithmetic, assignment, unary, and cast operators in more detail. It summarizes how to add, subtract, multiply and divide decimal variables.
Additive operators
Additive and multiplicative operators follow the arithmetic conversion rules defined in “Using operators on decimal data types” on page 380.

Note: For performance reasons, generating negative zero is possible.

Refer to “Intermediate results” on page 382 for details on how to get the conversion type during alignment of the decimal point.

Relational operators
Relational operators follow the arithmetic conversion rules defined in “Using operators on decimal data types” on page 380.

Figure 107 on page 382 shows you how to use a relational expression less than (<) for decimals. In this example, decimal data types are compared with other arithmetic data types (integer, float, double, long double). In addition, the implicit conversion of the decimal data types is performed using the arithmetic conversion rules in “Converting decimal types” on page 385. Leading zeros in the example are shown to indicate the number of digits in the decimal data type. You do not need to enter leading zeros in your decimal data type variable initialization. Refer to “Intermediate results” on page 382 for details on how to get the conversion type during alignment of the decimal point.
Equality operators

Equality operators follow the arithmetic conversions defined in "Using operators on decimal data types" on page 380. Where the operands have data types and values suitable for the relational operators, the semantics for relational operators applies.

Note: Positive zero and negative zero compare equal. In the following example, the expression always evaluates to TRUE:

\(-0.00d == +0.00000d\)

Refer to "Intermediate results" for details on how to get the conversion type during alignment of the decimal point.

Conditional operators

Conditional operators follow the arithmetic conversions defined in "Using operators on decimal data types" on page 380. If both the second and third operands have an arithmetic data type, the usual arithmetic conversions are performed to bring them to a common data type. If both operands are decimal data types, the operands are converted to the conversion type and the result has that data type.

Refer to "Intermediate results" for details on how to get the conversion type during alignment of the decimal point.

Intermediate results

Use one of the following tables to calculate the size of the result. The tables summarize the intermediate expression results with the four basic arithmetic operators and conditional operators when applied to the decimal data types. Most of the time, you can use Table 78 on page 383 to calculate the size of the result. It assumes no overflow. If overflow occurs, use Table 79 on page 383 to determine the resulting data type.
Both tables assume the following:
- x has data type `decimal(n₁, p₁)`
- y has data type `decimal(n₂, p₂)`
- `decimal(n, p)` is the resulting data type

<table>
<thead>
<tr>
<th>Expression</th>
<th>(n, p)</th>
</tr>
</thead>
<tbody>
<tr>
<td>x * y</td>
<td>n = n₁ + n₂ p = p₁ + p₂</td>
</tr>
<tr>
<td>x / y</td>
<td>n = DEC_DIG p = DEC_DIG - ((n₁ - p₁) + p₂)</td>
</tr>
<tr>
<td>x + y</td>
<td>p = max(p₁, p₂) n = max(n₁ - p₁, n₂ - p₂) + p + 1</td>
</tr>
<tr>
<td>x - y</td>
<td>same rule as addition</td>
</tr>
<tr>
<td>z ? x : y</td>
<td>p = max(p₁, p₂) n = max(n₁ - p₁, n₂ - p₂) + p</td>
</tr>
</tbody>
</table>

You can use Table 79 to calculate the size of the result, whether there is an overflow or not.

<table>
<thead>
<tr>
<th>Expression</th>
<th>(n, p)</th>
</tr>
</thead>
<tbody>
<tr>
<td>x * y</td>
<td>n = min(n₁ + n₂, DEC_DIG) p = min(p₁ + p₂, DEC_DIG - min(n₁ - p₁) + (n₂ - p₂), DEC_DIG)</td>
</tr>
<tr>
<td>x / y</td>
<td>n = DEC_DIG p = max(DEC_DIG - ((n₁ - p₁) + p₂), 0)</td>
</tr>
<tr>
<td>x + y</td>
<td>ir = min(max(n₁ - p₁, n₂ - p₂) + 1, DEC_DIG) p = min(max(p₁, p₂), DEC_DIG - ) n = ir + p</td>
</tr>
<tr>
<td>x - y</td>
<td>same rule as addition</td>
</tr>
<tr>
<td>z ? x : y</td>
<td>ir = max(n₁ - p₁, n₂ - p₂) p = min(max(p₁, p₂), DEC_DIG - ir) n = ir + p</td>
</tr>
</tbody>
</table>

If overflow occurs in n or p, a compile-time warning message is issued and the decimal places are truncated. As much of the integral part is reserved as possible. If the integral part is truncated as an expression in the static or extern initialization, an error message is issued. If the integral part is truncated inside the block scope, a warning is issued. On each operation, the complete result is calculated before truncation occurs.

**Assignment operators**

Assignment operators follow the arithmetic conversion rules defined in "Using operators on decimal data types" on page 380. When values are assigned, an SIGFPE exception may be raised if the operands contain values that are not valid.

**Unary operators**

Use the following unary operators to determine the digits in a decimal data type:
- `sizeof` Determines the total number of bytes occupied by the decimal data type
- `digitsof` Determines the number of digits (n)
precisionof operator

Determines the number of decimal digits \((p)\)

**sizeof operator**

When you use the `sizeof` operator with `decimal(n,p)`, the result is an integer constant. The `sizeof` operator returns the total number of bytes occupied by the decimal data type.

Each decimal digit occupies a halfbyte. In addition, a halfbyte represents the sign. The number of bytes used by `decimal(n,p)` is the smallest whole number greater than or equal to \((n + 1)/2\), that is, `sizeof(decimal(n,p)) = ceil((n + 1)/2)`. The `sizeof` result is calculated using this method because the z/OS XL C compiler uses packed decimal to implement decimal data types.

`sizeof` operator returns the total number of bytes occupied by the decimal data type.

**Figure 108** shows an example of getting the total number of bytes occupied by the decimal data type.

```c
int y;
decimal (5, 2) x;
y = sizeof x; /* This would be calculated to be 3 bytes*/
    /* (5+1)/2 = 3. */
```

**Figure 108. Getting the total number of bytes occupied by the decimal data type**

**digitsof operator**

When you use the `digitsof` operator with a decimal type, the result is an integer constant. The `digitsof` operator returns the number of significant digits \((n)\) in a decimal type.

`digitsof` operator returns the number of significant digits \((n)\) in a decimal type.

**Figure 109** shows an example of getting the total number of digits in the decimal data type. This example gives you the number of digits \((n)\) in a decimal type.

```c
decimal (5, 2) x;
int n;
int n = digitsof x; /* the result is n=5 */
```

**Figure 109. Getting the total number of digits in the decimal data type**

**Note:** Apply `digitsof` only to a decimal type.

**precisionof operator**

When you use the `precisionof` operator with a decimal type, the result is an integer constant. The `precisionof` operator tells you the number of decimal digits \((p)\) of the decimal type.

`precisionof` operator returns the number of decimal digits \((p)\) of the decimal type.

**Figure 110 on page 385** shows an example of getting the number of decimal digits in the decimal data type. This example gives you the number of decimal digits \((p)\) of the decimal data type.
Note: Apply precisionof only to a decimal data type.

cast operator
You can use the cast operator convert the following types explicitly:

- Decimal types to decimal types
- Decimal types to and from floating-point types
- Decimal types to and from integer types

Notes:
1. When you are explicitly casting to a decimal type, the discarding of the leading nonzero digits does not cause an exception at run time. For more information about suppressing compiler messages and runtime exceptions, refer to "Converting decimal types."
2. An implicit conversion to a decimal type with an even number of digits may not clear the pad digit, but an explicit cast will clear the pad digit.

Summary of operators used with decimal types
Table 80 summarizes all of the operators that can be used with decimal types.

<table>
<thead>
<tr>
<th>Operator Name</th>
<th>Associativity</th>
<th>Operators</th>
</tr>
</thead>
<tbody>
<tr>
<td>Primary</td>
<td>left to right</td>
<td>()</td>
</tr>
<tr>
<td>Unary</td>
<td>right to left</td>
<td>++ -- + - ! &amp; ( typename ) sizeof digitsof precisionof cast</td>
</tr>
<tr>
<td>Multiplicative</td>
<td>left to right</td>
<td>* /</td>
</tr>
<tr>
<td>Additive</td>
<td>left to right</td>
<td>+ -</td>
</tr>
<tr>
<td>Relational</td>
<td>left to right</td>
<td>&lt; &gt; &lt;= &gt;=</td>
</tr>
<tr>
<td>Equality</td>
<td>left to right</td>
<td>== !=</td>
</tr>
<tr>
<td>Conditional</td>
<td>right to left</td>
<td>? :</td>
</tr>
<tr>
<td>Assignment</td>
<td>right to left</td>
<td>= += -= *= /=</td>
</tr>
<tr>
<td>Comma</td>
<td>left to right</td>
<td>,</td>
</tr>
</tbody>
</table>

Converting decimal types
The z/OS XL C compiler implicitly converts the following types:

- Decimal types to decimal types
- Decimal types to and from floating-point types
- Decimal types to and from integer types

Converting decimal types to decimal types
If the value of the decimal type to be converted is within the range of values that can be represented exactly, the value of the decimal type is not changed.
If the value of the decimal type to be converted is outside the range of values that can be represented, the value of the decimal type is truncated. Truncation may occur on either the integral part or the fractional part or both.

When truncation occurs on the fractional part, no compile-time message or runtime exception occurs.

When truncation occurs on the integral part, a compile-time message, a runtime exception, or both, are generated as follows:
- In the initialization of static or external variables
  - Compile-time error if nonzero digits are truncated in the integral part
- In the initialization of automatic variables, an assignment or function call with prototype
  - Checkout warning at compile time
  - Runtime exception SIGFPE may occur if nonzero digits are truncated in the integral part at run time.

**Note:** An explicit cast is used to suppress compile-time messages and runtime exceptions. A runtime exception may occur if any leading nonzero digits are discarded and the operation is not an explicit cast operation.

In the following examples:
- *message* represents a compile-time message.
- *exception* represents a runtime exception (that is, SIGFPE is raised).

![Figure 111](image) shows an example of fractional part that cannot be represented.
Conversion of one decimal object to another decimal object with smaller precision involves truncation on the right of the decimal point.

```c
#include <decimal.h>

void func(void)
void dec_func(decimal( 7, 1 ));
decimal( 7, 4 ) x = 123.4567D;
decimal( 7, 1 ) y;
decimal( 7, 1 ) z = 123.4567D; /* z = 000123.4D <-- No message, */
   /* No exception */
void func(void)
   decimal( 7, 1 ) a = 123.45670; /* a = 000123.4 <-- No message, */
      /* No exception */
y = x;     /* y = 000123.40  <-- No message, No exception */
y = 123.45670; /* y = 000123.40  <-- No message, No exception */
dec_func(x); /* <-- No message, No exception */
```

**Figure 111. Fractional part cannot be represented**

![Figure 112 on page 387](image) shows an example of an integral part that cannot be represented. Conversion of one decimal object to another decimal object with fewer digits involves truncation on the left of the decimal point.
Converting decimal types to and from integer types

The following topics provide examples and information that is useful when you are converting decimal data types to or from integer data types:

- "Conversion to integer types"
- "Conversion from integer types" on page 388

Conversion to integer types

When a value of decimal type is converted to integer type, the fractional part is discarded. If the value of the integral part cannot be represented by the integer type, the behavior is undefined.

When a negative decimal type is converted to an unsigned integer type, the conversion proceeds as though these steps are followed:

1. The decimal type is converted to a signed integer type with the same size as the unsigned integer type.
2. The signed integer type is converted to the unsigned integer type.

Figure 113 is an example of a conversion to integer type.

```
int i = 1234.5678d;     /* i = 1234 */
int j = -789d;          /* j = -789 */
int k = 9876543210d;    /* k is undefined */
```

Figure 113. Conversion to integer type
Conversion from integer types

When a value of integer type is implicitly converted to decimal type, the integer type is converted to type decimal(10,0).

When a value of integer type is explicitly converted to decimal type, the conversion proceeds as though these two steps are followed:
1. The integer type is converted to type decimal(10,0). A runtime exception can never occur in this step.
2. Type decimal(10,0) is then converted to decimal(n,p). All rules for decimal type to decimal type conversion apply in this step.

An unsigned integer type is converted to a positive decimal value.

If the value of the integral part cannot be represented by the decimal type, the behavior is undefined.

Figure 114 is an example of conversion from integer type.

```c
#include <decimal.h>
decimal(10,2) pd01 = 1234; /* pd01 = 00001234.00d */
decimal(5,0) pd02 = 987654; /* compile-time error */
int main(void) {
    decimal(5,0) pd03 = 987654; /* runtime exception */
    decimal(13,4) pd04;
    /* The number 321 is converted to decimal(10,0) before the */
    /* addition is performed. */
    pd04 = 1234.56d + 321; /* pd04 = 000001555.5600d */
}
```

Figure 114. Conversion from integral type

Converting decimal data types to and from floating-point data types

The following topics provide examples and information that is useful when you are converting decimal data types to or from floating-point data types:

- Conversion to floating-point types
- Conversion from floating-point data types

Conversion to floating-point types

The result of the conversion might not be exact due to:
- The limitations of significant digits in different floating-point types
- The degree to which a value can be stored exactly in a floating-point type
- The loss of precision during conversion

Figure 115 on page 389 is an example of conversion to floating-point type. The content of each floating-point type variable depends on their limitation of significant digits that are specified in <float.h>.
Conversion from floating-point data types

When a value of floating-point type is converted to decimal type and the value being converted cannot be represented by the decimal type, the result is rounded towards zero. If the value of the floating-point type to be converted is within the range of values that can be represented, but cannot be represented exactly, the result is also rounded towards zero. The result retains as much value as possible. When any leading nonzero digits are suppressed and the operation is not an explicit cast operation, a decimal overflow exception occurs at run time and an SIGFPE exception is raised.

When a conversion from a floating-point type is made with static or external variable initialization, a compile-time error message is issued.

The result of the conversion may not be exact because the internal representation of System/370 floating-point instructions is hexadecimal based if FLOAT(HEX) mode is used. The mapping between the two representations is not one-to-one, even when the value of a float type is within the range of the decimal type. Figure 116 is an example of conversion from floating-point type.

```
#include <decimal.h>

decimal(10,2) pd11 = 1234.0; /* pd11 = 00001234.00d */
decimal(5,0) pd12 = 987654.0; /* compile-time error */

int main(void) {
    decimal(5,0) pd13 = 987654.0; /* runtime exception */
    decimal(13,4) pd14 = 12.34567890; /* fractional part is truncated */
}
```

Figure 116. Conversion from floating-point type

Calling functions with decimal data types

There are no default argument promotions on arguments that have type decimal when the called function does not include a prototype. If the expression for the called function has a type that includes a prototype, the behavior is as documented in ANSI, with the exception of prototype with an ellipsis (...). If the prototype ends with an ellipsis (...), default argument promotions are not performed on arguments with decimal types.

A function may change the values of its parameters, but these changes cannot affect the values of the arguments. However, it is possible to pass a pointer to a decimal object, and the function may change the value of the decimal object to which it points.

Using library functions

You can use variable arguments and I/O operations with decimals.
Using variable arguments with decimal data types

You can use the va_arg macro with a decimal type decimal(\(n,p\)). Each invocation of va_arg modifies arg_ptr so that the values of successive arguments are returned in turn.

\[
\text{var_type va_arg( va_list arg_ptr, var_type );}
\]

Formatting input and output operations with decimal data types

Use the printf() family of functions to print the value of a decimal type:

- fprintf()
- printf()
- sprintf()
- vsprintf()
- vfprintf()
- vprintf()
- va_arg()

Use the scanf() family of functions to read the value of a decimal type:

- fscanf()
- scanf()
- sscanf()

The conversion specifier for decimal types is one of the following:

\[
\%D(n,p) \\
\%D(n) \\
\%D(n)
\]

For more information about these functions and their keywords, see the z/OS XL C/C++ Runtime Library Reference.

Validating decimal values

It is possible to have nonvalid representation of decimal value stored in memory, such as input from file or overlay memory. If the nonvalid decimal value is used in an operation or assignment, the result may not be as expected. A built-in function can be used to report whether the decimal representation is valid or not. The function call can be in the following form:

\[
\text{status = decchk( x );}
\]

The built-in function decchk() accepts a decimal-type expression as argument and returns a status value of type int. The status can be interpreted as follows:

- 0: Valid decimal representation value (including nonpreferred but valid sign, A-F)
- 1: Leftmost halfbyte is not zero in a decimal-type number that has an even number of digits (for example, 123 is stored in decimal(2,0))
- 2: Incorrect digits (not 0-9)
- 4: Incorrect sign (not A-F)

Macro define names for function return status (in <decimal.h>):
The function return status is the OR of all errors that were detected.

See the z/OS XL C/C++ Runtime Library Reference for more information on the `decchk()` library function.

**Fixing sign variables**

A built-in function can be used to fix nonpreferred sign variables. The function call can be in the following form:

```c
x = decfix ( x );
```

The built-in function `decfix()` accepts a decimal-type expression as argument and returns a decimal value that has the same size (that is, same decimal types) and same value as the argument, but with the correct preferred sign. The function does not change the content of the argument. See the z/OS XL C/C++ Runtime Library Reference for more information on the `decfix()` library function.

**Returning decimal absolute values**

The built-in function `decabs()` accepts a decimal-type expression as argument and returns the absolute value of the decimal argument (the same decimal type as the argument, and the same magnitude, but positive). The function does not change the content of the argument.

The function call can be in the following form:

```c
y = decabs ( x );
```

See the z/OS XL C/C++ Runtime Library Reference for more information on the `decabs()` library function.
Programming examples

Programming examples CCNGDC3 and CCNGDC4 are shipped with the compiler.

Figure 117 (CCNGDC3) shows an example of using the decimal type.

```c
/*
  this example demonstrates the use of the decimal type */
/* always include decimal.h when decimal type is used */

#include <decimal.h>

/* Declares a decimal(10,2) variable */
decimal(10,2) pd01;

/* Declares a decimal(15,4) variable and initializes it with the */
/* value 1234.56d */
decimal(15,4) pd02 = 1234.56d;

/* Structure that has decimal-related members */
struct pdec
{
  /* members' data types */
  int m;       /* - integer */
  decimal(23,10) pd03; /* - decimal(23,10) */
  decimal(10,2) pd04[3]; /* - array of decimal(10,2) */
  decimal(10,2) *pd05; /* - pointer to decimal(10,2) */
}
pd06,
  *pd07 = &pd06; /* pd07 points to pd06 */

/* Array of decimal(31,30) */
decimal(31,30) pd08[2];

/* Prototype for function that accepts decimal(10,2) and int as */
/* arguments and has return type decimal(25,5) */
decimal(25,5) product(decimal(10,2), int);

decimal(5,2) PdCnt; /* decimal loop counter */
int i;

int main(void)
{
  pd01 = -789.45d; /* simple assignment */
pd06.m = digitsof(pd06.pd03) + precisionof(pd02); /* 23 + 4 */
pd06.pd03 = sizeof(pd01);
pd06.pd04[0] = pd02 + pd01; /* decimal addition */
*(pd06.pd04 + 1) = (decimal(10,2)) product(pd07->pd04[0], pd07->m);
pd07->pd04[2] = product(pd07->pd04[0], pd07->pd04[1]);
pd07->pd05 = &pd01; /* taking the address of a */
  /* decimal variable */
/* These two statements are different */
pd08[0] = 1 / 3d;
pd08[1] = 1d / 3d;

  printf("pd01 = %D(10,2)\n", pd01);
  printf("pd02 = %.*D(+,+)\n", 20, 5, digitsof(pd02), precisionof(pd02), pd02);
  printf("pd06.m = %d, pd07->m = %d\n", pd06.m, pd07->m);
  printf("pd06.pd03 = %d(23,10), pd07->pd03 = %D(23,10)\n",
         pd06.pd03, pd07->pd03);

Decimal type — Example 1 (Part 1 of 2)

Figure 117. Decimal type — Example 1
/* You will get an infinite loop if floating type is */
/* used instead of the decimal types. */
for (PdCnt = 0.0d; PdCnt != 3.6d; PdCnt += 1.2d)
{
    i = PdCnt / 1.2d;
    printf("pd06.pd04[%d] = %D(10,2), \n        pd07->pd04[%d] = %D(10,2)\n", 
        i, i, pd06.pd04[i], i, pd07->pd04[i]);
}
printf("*(pd06.pd05) = %D(10,2), *(pd07->pd05) = %D(10,2)\n", 
    *(pd06.pd05), *(pd07->pd05));
printf("pd08[0] = %D(31,30)\n", pd08[0]);
printf("pd08[1] = %D(31,30)\n", pd08[1]);
return(0);

/* Function definition for product() */
decimal(25,5) product(decimal(10,2) v1, int v2)
{
    /* The following happens in the return statement */
    /* - v2 is converted to decimal(10,0) */
    /* - after the multiplication, the expression has resulting */
    /* type decimal(20,2) (i.e. (10,2) * (10,0) ==> (20,2)) */
    /* - the result is then converted implicitly to decimal(25,5) */
    /* before it is returned */
    return( v1 * v2 );
}

Decimal type — Example 1 (Part 2 of 2)

Figure 118 shows the output produced by Figure 117 on page 392

Figure 118. Output produced by CCNGDC3

Figure 119 on page 394 shows another sample program (CCNGDC4) that also uses decimal type.
Decimal exception handling

z/OS XL C decimal instructions produce the following exceptions that are unique to decimal operations:

- Data exception (interrupt code hex '7')
  This may be caused by nonvalid sign or digit codes in a packed decimal number operated on by packed decimal instructions, for example, ADD DECIMAL or COMPAR DE CIMAL.
  When an operation is performed on decimal operands and the assignment is not through an explicit cast operation, the following situations cause runtime exceptions at execution time and SIGFPE is raised.

- Decimal-overflow exception (interrupt code hex 'A')
  This exception may be caused when nonzero digits are lost because the destination field in a decimal operation is too short to contain the result.

Notes:

1. Decimal overflow conditions are supported for System Programming Calls only with the runtime library.
2. The following unhandled decimal overflow message is the same for both decimal overflow and fixed overflow conditions:
   CEE3210S The system detected a Decimal-overflow exception.
However, because the fixed overflow condition is normally disabled (masked) and is ignored at run time, fixed overflow conditions should not occur.

- Decimal-divide exception (interrupt code hex 'B')
  This exception may be caused when, in decimal division, the divisor is zero, or the quotient exceeds the specified data-field size. The decimal divide is indicated if the sign codes of both the divisor and dividend are valid, and if the digit or digits used in establishing the exception are valid.

  **Note:** The following unhandled divide message does not distinguish between a decimal-divide condition and a fixed divide-by-zero condition:

  CEE3211S The system detected a Decimal-divide exception.

Both are mapped into the same error message.

### `printf()` and `scanf()` and format validation

A decimal exception might be produced by the `printf()` family when processing an nonvalid decimal operand. This may result in abnormal termination of your program with the runtime message:

- Under z/OS:
  CEE3207S The system detected a Data exception.
- Under CICS:
  EDCK007 ABEND=8097 Data Exception

You must ensure that valid packed decimal data is present when attempting to use `printf()` or `scanf()` with runtime library decimal routines. No additional validation is performed on decimal to ensure format correctness. Use the `decchk()` routine to validate decimal data operands in such circumstances.

### Additional considerations

- When the operands of a decimal operation contain nonvalid digits, the result is undefined, and a runtime exception can occur. To validate a decimal number, call the `decchk()` built-in function in your code.
- Code should be written in a manner that does not depend on the ability of the runtime library to recover from a decimal overflow exception.
- In a multiprocessor configuration, decimal operations cannot be used safely to update a shared storage location when the possibility exists that another processor may also be updating that location. This possibility arises because the bytes of a decimal operand are not necessarily accessed concurrently.
- If a decimal exception occurs in user code or library routines, the expected results of the instruction causing the exception or the library routine where the exception occurred are undefined. The results produced by the library routine's execution are also undefined.
- If a SIGFPE handler is coded to handle decimal exceptions, it should reenable itself before resuming normal execution or recovery from the error. This reestablishes the exception environment and is consistent with good programming practice.

### Error messages

If an overflow occurs at run time, the exception handler issues the following runtime error messages:

IBM482I 'ONCODE'=0310 'FIXEDOVERFLOW' CONDITION RAISED
Unhandled exception. This result may be produced in a C-only environment only for decimal overflow conditions. Fixed-point overflow exception is not allowed in the Program Mask.

**Note:** The Program Mask in the Program Status Word (PSW) is enabled for decimal overflow exceptions.

IBM301I 'ONCODE'=0320 'ZERODIVIDE' CONDITION RAISED

Unhandled decimal or fixed overflow. Fixed overflow is normally masked and ignored at C run time, but it may occur in interlanguage calls.

IBM537I 'ONCODE'=8097 DATA EXCEPTION

Unhandled data exception

The error messages for FIXEDOVERFLOW and ZERODIVIDE mean that either the fixed-point overflow condition or the decimal overflow condition has caused the condition reported.

Under CICS, decimal overflow condition exceptions are supported in CICS with C and the following runtime message is produced:

EDCK017 ABEND=0320 Fixed or Decimal Overflow

**Decimal exceptions and Assembler interlanguage calls**

Calls to an assembly language procedure or function assume that the called routine will save and restore the value of the Program Mask if the routine alters it. Ensure that the Program Mask is preserved across an assembler language interface. If it is not preserved, the recognition of subsequent decimal overflow exceptions in C code will be unpredictable.
Chapter 27. IEEE Floating-Point

Starting with OS/390 V2R6 (including the Language Environment and C/C++ components), support was added for IEEE binary floating-point (IEEE floating-point) as defined by the ANSI/IEEE Standard 754-1985, IEEE Standard for Binary Floating-Point Arithmetic. For more information on floating-point support, see:

- z/Architecture Principles of Operation
- z/OS XL C/C++ User’s Guide
- z/OS XL C/C++ Language Reference
- z/OS XL C/C++ Runtime Library Reference
- z/OS Language Environment Vendor Interfaces

Starting with z/OS V1R9 (including the Language Environment and C/C++ components), support was added for IEEE decimal floating-point, as defined by the ANSI/IEEE Standard P754/D0.15.3, IEEE Standard for Floating-Point Arithmetic.

Floating-point numbers

The format of floating-point numbers can be either base 16 S/390® hexadecimal format, base 2 IEEE-754 binary format, or base 10 IEEE-754 decimal format. The formats are based on three operand lengths for hexadecimal and binary: short (32 bits), long (64 bits), and extended (128 bits). The formats are also based on three operand lengths for decimal: _Decimal32 (32 bits), _Decimal64 (64 bits), and _Decimal128 (128 bits).

A floating-point operand may be numeric or, for binary and decimal floating-point only, positive or negative infinity, or nonnumeric (Not a Number, or NaN). A floating-point number, has three components: a sign bit, a signed binary exponent, and a significand. The significand consists of an implicit unit digit to the left of an implied radix point, and an explicit fraction field to the right. The significand digits are based on the radix, 2 (for binary floating-point), 10 (for decimal floating-point), or 16 (for hexadecimal floating-point). The magnitude (an unsigned value) of the number is the product of the significand and the radix raised to the power of the exponent. The number is positive or negative depending on whether the sign bit is zero or one, respectively. A nonnumeric binary or decimal floating-point operand also has a sign bit, signed exponent, and fraction field.

Hexadecimal floating-point operands have formats that provide for exponents that specify powers of the radix 16 and significands that are hexadecimal numbers. The exponent range is the same for the short, long, and extended formats. The results of most operations on hexadecimal floating-point data are truncated to fit into the target format, but there are instructions available to round the result when converting to a narrower format. For hexadecimal floating-point operands, the implicit unit digit of the significand is always zero. Because the value if the significand and fraction are the same, hexadecimal floating-point operations are described in terms of the fraction, and the term significand is not used.

Binary floating-point operands have formats which provide for exponents that specify powers of the radix 2 and significands that are binary numbers. The
exponent range differs for different formats, the range being greater for the longer formats. In the long and extended formats, the exponent range is significantly greater for binary floating-point data than for hexadecimal floating-point data. The results of operations performed on binary floating-point data are rounded automatically to fit into the target format; the manner of rounding is determined by a program-settable rounding mode.

Decimal floating-point operands have formats that provide for exponents that specify powers of the radix 10 and significands that are decimal numbers. The exponent range differs for different formats, the range being greater for the longer formats. The results of operations performed on decimal floating-point data are rounded automatically to fit into the target format; the manner of rounding is determined by a program-settable rounding mode.

C/C++ compiler support

The C/C++ compiler provides a FL0AT option to select the format of floating-point numbers produced in a compile unit. The FL0AT option allows you to select either IEEE binary floating-point or hexadecimal floating-point format. For details on the z/OS XL C/C++ support, see the description of the FL0AT option in z/OS XL C/C++ User’s Guide. In addition, two related sub-options, ARCH(3) and TUNE(3), support IEEE binary floating-point data. Refer to the ARCHITECTURE and TUNE compiler options in z/OS XL C/C++ User’s Guide for details.

The z/OS XL C/C++ Language Reference contains additional information on floating-point in the following sections:

- Floating Point Literals
- Floating-Point Variables
- Floating-Point Conversions
- Floating-Point Standards

Notes:

1. You must have OS/390 Release 6 or higher to use the IEEE binary floating-point instructions. In Release 6, the base control program (BCP) is enhanced to support the new IEEE binary floating-point hardware in the IBM S/390 Generation 5 Server. This enables programs running on OS/390 Release 6 to use the IEEE binary floating-point instructions and 16 floating-point registers. In addition, the BCP provides simulation support for all the new floating-point hardware instructions. This enables applications that make light use of IEEE binary floating-point, and can tolerate the overhead of software simulation, to execute on OS/390 V2R6 without requiring an IBM S/390 Generation 5 Server.

2. The terms binary floating-point and IEEE binary floating-point are used interchangeably. The abbreviations BFP and HFP, which are used in some function names, refer to binary floating-point and hexadecimal floating-point respectively.

3. Under hexadecimal floating-point format, the rounding mode is set to round toward 0. Under IEEE binary floating-point format, the rounding mode is set to round toward the nearest integer.
Using IEEE floating-point

IEEE binary floating-point is provided primarily to enhance interoperability and portability between IBM System z and other platforms. It is anticipated that IEEE binary floating-point will be most commonly used for new and ported applications. Customers should not migrate existing applications that use hexadecimal floating-point to IEEE binary floating-point, unless there is a specific reason.

IBM does not suggest mixing Binary and Hexadecimal floating-point formats in an application. However, for applications which must handle both formats, the C/C++ runtime library does offer some support. Reference information for IEEE binary floating-point can also be found in z/OS XL C/C++ Language Reference.

You should use IEEE binary floating-point in the following situations:

- You deal with data that are already in IEEE binary floating-point format
- You need the increased exponent range (see z/OS XL C/C++ Language Reference for information on exponent ranges with IEEE-754 floating-point)
- You want the changes in programming paradigm provided by infinities and NaN (Not a Number)

For more information about the IEEE format, refer to the IEEE 754-1985 IEEE Standard for Binary Floating-Point Arithmetic.

When you use IEEE binary floating-point, make sure that you are in the same rounding mode at compile time (specified by the ROUND(mode) option), as at run time. Entire compilation units will be compiled with the same rounding mode throughout the compilation. If you switch runtime rounding modes inside a function, your results may vary depending upon the optimization level used and other characteristics of your code; switch rounding mode inside functions with caution.

If you have existing data in hexadecimal floating-point (the original base 16 S/390 hexadecimal floating-point format), and have no need to communicate these data to platforms that do not support this format, there is no reason for you to change to IEEE binary floating-point format.

Applications that mix the two formats are not supported.

IEEE binary and decimal floating-point are fully supported in a CICS environment only if CICS TS Version 4 or later is in use.

For information on the C/C++ functions that support floating-point, see the functions listed in Table 81. For more information, see z/OS XL C/C++ Runtime Library Reference.

<table>
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<th>Table 81. C/C++ functions that support floating-point</th>
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Table 81. C/C++ functions that support floating-point (continued)

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In z/OS Language Environment Vendor Interfaces, the chapter on C/C++ Special Purpose Interfaces for IEEE Floating-Point provides information on the following functions.

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Table 82. Special purpose C/C++ functions that support floating-point
Chapter 28. Handling error conditions, exceptions, and signals

This chapter discusses how to handle error conditions, exceptions, and signals with z/OS XL C/C++. It describes how to establish, enable and raise a signal, and provides a list of signals supported by z/OS XL C/C++.

In 31-bit applications, there are two basic ways to handle program checks and ABENDs:
- POSIX or ANSI signals (SIGABND, SIGFPE, SIGILL, SIGSEGV)
- User condition handlers registered using CEEHDLR interface or the USRHDLR runtime option.

In 31-bit applications, z/OS Language Environment uses a stack-based model to handle error conditions. This environment establishes a last-in, first-out (LIFO) queue of 0 or more user condition handlers for each stack frame. The z/OS Language Environment condition handler calls the user condition handler at each stack frame to handle error conditions when they are detected. For more information about the callable services in z/OS Language Environment, refer to “Handling signals using Language Environment callable services” on page 409.

In AMODE 64 applications, user condition handlers are not available. The basic ways to handle program checks and ABENDs in AMODE 64 applications are:
- POSIX or ANSI signals (SIGABND, SIGFPE, SIGILL, SIGSEGV)
- Exception handlers registered using the __set_exception_handler() C runtime library function. See “AMODE 64 exception handlers” on page 407 for more information.

The C error handling approach using signals is supported in a z/OS XL C/C++ program, but there are some restrictions (refer to “Handling C software exceptions under C++” on page 404). See “Signal handlers” on page 408 for more information.

C++ exception handling is supported in all z/OS environments that are supported by C++ (including CICS and IMS); you must run your application with the TRAP(ON) runtime option. To turn off C++ exception handling, use the compiler option N0EXH. For more information on this compiler option, see z/OS XL C/C++ User’s Guide.

Note: If C++ exception handling is turned off you will get code which runs faster but is not ANSI conformant.

This chapter also describes some aspects of C++ object-oriented exception handling. The object-oriented approach uses the try, throw, and catch mechanism. Refer to z/OS XL C/C++ Language Reference for a complete description. Some library functions (abort(), atexit(), exit(), setjmp() and longjmp()) are affected by C++ exception handling; refer to z/OS XL C/C++ Runtime Library Reference for more information.
Handling C software exceptions under C++

Using the C and C++ condition handling schemes together in a C++ program may result in undefined behavior. This applies to the use of try, throw and catch with signal() and raise(), with z/OS Language Environment condition handlers such as CEEHDLR, or with CICS HANDLE ABEND under CICS in 31-bit mode. The behavior with respect to running destructors for automatic objects is undefined, due to control being transferred to non-C++ exception handlers (such as signal handlers) and stacks being collapsed. If a C software exception is not handled and results in program termination, the behavior for destructors for static non-local objects will also be undefined.

With z/OS UNIX, in a multithreaded environment, z/OS XL C++ exception stacks are managed on a per-thread basis. This means an exception thrown on one thread cannot be caught on another thread, including the IPT where main() was started. If the exception is not handled by the thread from which it was thrown, then the terminate() function is called.

Handling hardware exceptions under C++

You cannot use try, throw, and catch to handle hardware exceptions.

If a hardware exception resulting in abnormal termination occurs in a z/OS XL C++ program, destructors for static and automatic objects are not run. If a hardware exception occurs, and a handler was registered for the exception using signal(), the behavior of destructors for automatic objects is undefined.

Tracebacks under C++

A traceback is not produced if a thrown object was caught and handled.

If an object is thrown, and no catch clauses exist that will handle the thrown object, the program will call terminate(). By default, terminate() calls abort(), and the traceback produced will show that this has occurred. The traceback will not show the point from which the object was originally thrown. Instead, it will show that the object was thrown from the last encountered catch clause.

In sample routine CCNGCH1, sub1() throws object a. Because sub1() does not have any catch clauses to handle a, C++ attempts to find a suitable catch clause in the calling sub function, and then in the main function. Because no catch clauses can be found to handle object a, the traceback will show that object a was thrown from main().
If an object is thrown and a catch clause catches but then rethrows that object, or throws another object, and no catch clauses exist for the rethrown or subsequently thrown object, the traceback starts at the point from which the rethrow or subsequent throw occurred. The first object thrown is considered to have been caught and handled.

In sample routine CCNGCH2 (Figure 122 on page 406), the traceback would show that the testeh function rethrows an integer. Because there is no catch clause to handle the rethrown integer, the traceback will also show that terminate() and then abort() were called.

/* example of C++ exception handling */

#include <iostream.h>
#include <stdlib.h>

class A {
  int i;
  public:
    A(int j) { i = j; cout << "A ctor: i= " << i << 'n'; }
    A() { cout << "A dtor: i= " << i << 'n'; }
};
class B {
  char c;
  public:
    B(char d) { c = d; cout << "B ctor: c= " << c << 'n'; }
    B() { cout << "B dtor: c= " << c << 'n'; }
};

void sub(void);
void sub1(void);

main() {
  try {
    sub();
  } catch(int i) { cout << "caught an integer" << 'n'; }
  catch(char c) { cout << "caught a character" << 'n'; } exit(55);
  }

void sub() {
  try {
    sub1();
  } catch(double d) { cout << "caught a double" << 'n'; }
  catch(float f) { cout << "caught a float" << 'n'; } return;
  }

void sub1() {
  A a(3001);
  try {
    throw(a);
  } catch(B b) { cout << "caught a B object" << 'n'; }
  catch(short s) { cout << "caught a short" << 'n'; } return;
}

Figure 121. Example illustrating C++ exception handling/traceback

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/* example of C++ exception handling */

#include <iostream.h>
#include <stdlib.h>

int testeh(void);

class A {
    int i;
    public:
        A(int j) { i = j; cout << "A ctor: i= " << i << '\n'; }  
        A() { cout << "A dtor: i= " << i << '\n'; }  
};

class B {
    char c;
    public:
        B(char d) { c = d; cout << "B ctor: c= " << c << '\n'; }  
        B() { cout << "B dtor: c= " << c << '\n'; }  
};

A static A(333);
B static B('z');

void sub();

main() {
    sub();
    return(55);
}

void sub() {
    A c(3001);
    try {
        cout << "calling testeh" << '\n';
        testeh(); // int will be rethrown from testeh()
    }
    // no catch clauses for the rethrown int
    catch(char c) { cout << "caught char" << '\n'; }
    catch(short s) { cout << "caught short s= " << s << '\n'; }
    cout << "this line should not be printed" << '\n';
    return;
}

testeh() {
    A a(2001), a1(1001);
    B b('k');
    short k=12;
    int j=0, i=0;
    try {
        cout << "testeh running" << '\n';
        throw (6); // first throw: an int
    } catch(char c) { cout << "testeh caught char" << '\n'; }  
    catch(int j) { cout << "testeh caught int j= " << j << '\n';
        try { // int should be caught here
            cout << "testeh again rethrowing" << '\n';
            throw; // rethrow the int
        } catch(char d) { cout << "char d caught" << '\n'; }
    }
    cout << "this line should not be printed" << '\n';
    return(0);
}
AMODE 64 exception handlers

In AMODE 64 applications, exception handlers are registered using the __set_exception_handler() C runtime library function. When no exception handler is registered, program checks and ABENDs cause POSIX/ANSI signals to be raised. These signals can be caught by user-written signal catchers, where suitable recovery can be done. When an exception handler is registered, no signal is generated when a program check or ABEND occurs. Instead, the active exception handler is invoked. Since program checks and ABENDs do not generate signals, the blocked/unblocked/ignored/caught settings for SIGABND, SIGFPE, SIGILL, and SIGSEGV make no difference. When an exception handler is active, all non-program-check and non-ABEND signal processing still occurs as described by POSIX or ANSI. Only signals normally generated by program checks or ABENDs are suppressed.

Scope and nesting of exception handlers

Exceptions handlers apply only to the thread they are registered on. In a multi-threaded application, it is possible to have a mixture of threads, some with exception handlers registered, and some without. Program checks and ABENDs occurring on threads without active exception handlers cause the usual ANSI/POSIX signal generation. Program checks and ABENDs occurring on threads with active exception handlers will bypass signal generation and will cause the active exception handler to be invoked.

Exception handlers are also stack-frame based, much like 31-bit user condition handlers. If function a() registers an exception handler, future program checks and ABENDs will drive that handler, until the handler is de-registered. This includes program checks occurring in a() (after the registration), and in any called functions. Function a() can deregister the handler using __reset_exception_handler(). After this is done, program checks and ABENDs once again cause signals to be raised. If function a() returns without calling __reset_exception_handler() to deregister its handler, the handler will be automatically removed when a() returns.

If function a() registers handler ah(), and calls function b(), program checks and ABENDs in b() will also go to ah(). However, b() can register its own handler, bh(), in which case any program checks and ABENDs in b() or any functions it calls will go to bh(). Exception handlers can be nested in this way as deep as required. If they are not explicitly deregistered by calling __reset_exception_handler(), they are automatically removed when the registering function returns. They are also removed, whenever a longjump-type function (longjmp(), _longjmp(), siglongjmp(), setcontext(), or C++ throw) causes control to jump back past the function that registered the handler. (Example: a() registers handler ah(), and calls b(), which registers handler bh(), and calls c(). Function c() longjumps back into a(). In this case, bh() will be removed, but ah() will remain.)

Note: Whenever a program check or ABEND occurs, no more than one exception handler will ever be driven, even when several nested handlers have been registered. The active handler is the one that was most recently registered, and not de-registered/removed. It will usually be the handler registered by the most deeply-nested routine at the time of the program check or ABEND.

During C++ throw processing, as the Language Environment stack is unwound and destructors for automatic C++ object are invoked, handlers registered by more-deeply nested functions are temporarily bypassed, in case program checks or ABENDs occur in the destructors. Example: a() registers handler ah(), and calls b().
Function b() has a dynamic object with destructor bd(). Function b() calls c(), which has a dynamic object with destructor cd(), and it registers handler ch(). Function c() then calls d(), which registers handler dh(), and then throws a C++ exception that will eventually get caught back in a(). As the C++ destructors are run, program checks/ABENDs in cd() go to handler ch(), and program checks/ABENDs in bd() go to ah(). By the time control resumes in the catch clause in a(), dh() and ch() are gone, and ah() is the active exception handler. This same type of exception handler scoping occurs after pthread_exit() is called and all outstanding C++ dynamic destructors still left on the stack are run.

If a program does pthread_exit() while an exception handler is active, that exception handler remains active while any pthread_keycreate() destructor routines and any pthread_cleanup_push() routines are invoked. These routines can register their own exception handlers, too, if required.

When atexit() routines or C++ static destructors are run, any active exception handlers at the time of the exit() or pthread_exit() have already been removed. If these routines need recovery, they can register their own exception handlers.

**Handling exceptions**

When the active exception handler is called after a program check or ABEND, it receives a pointer to the CIB (Condition Information Block) for the error. It can examine the CIB and associated MCH (Machine Check Handler record) to determine what the error is. The handler can fix up whatever is required or take dumps, etc. When it is finished, the only valid things it can do are:

- Long jump back to some earlier pre-defined recovery point (any of the several longjump-type functions may be used -- longjmp(), _longjmp(), siglongjmp(), setcontext(), or C++ throw.)
- Issue exit() or _exit()
- Issue pthread_exit()
- Issue __cabend(), abort(), etc

What it cannot do is return. If it returns, the system will automatically do pthread_exit(-1) if POSIX(ON) is in effect, or exit(-1) if not.

When the active exception handler is given control, the handler is suspended, along with all other handlers already registered. This means that any future program checks/ABENDs will cause the usual signal processing to occur. The active handler is re-enabled once it longjumps back. If it exits or returns, it is not re-activated, and termination starts with no active exception handler. If an exception handler needs exception handling recovery for its own program checks or ABENDs, it must register its own exception handler. As usual, this new handler will become active, and will get control for any program checks/ABENDs occurring in the outer exception handler or any routines it calls.

**Signal handlers**

The basis for error handling in z/OS UNIX XL C/C++ application programs is the generation, delivery, and handling of signals. Signals can be generated and delivered as a result of system events or application programming. You can code your application program to generate and send signals and to handle and respond to signals delivered to it.

Two types of signal handling are supported for catching signals: ANSI C and POSIX.1. Each of these has standard signal delivery rules, which are discussed in

Handling signals with POSIX(OFF) using signal() and raise()

The z/OS XL C environment provides two functions that alter the signal handling capabilities available in the runtime environment: signal() and raise(). The signal() function registers a condition handler and the raise() function raises the condition.

In general, for C++ programs you are encouraged to use try, throw, and catch to perform exception handling. However, you can also use the z/OS XL C signal() and raise() functions.

You can use the signal() function to perform one of the following actions:

- Ignore the condition. For example, use the SIG_IGN condition to specify signal(SIGFPE, SIG_IGN).
- Reset the Global Error Table for default handling. For example, use the SIG_DFL condition to specify signal(SIGSEGV, SIG_DFL).
- Register a function to handle the specific condition. For example, pass a pointer to a function for the specific condition with signal(SIGILL, cfunc1). The function registered for signal() must be declared with C linkage.

Handling signals using Language Environment callable services

In 31-bit mode, you can set up user signal handlers with the z/OS Language Environment condition handling services. Some of the z/OS Language Environment callable services available for condition handling are:

CEEHDLR

- Register a user-written condition handler.

CEEHDLU

- Remove a registered user-written condition handler.

CEESGL

- Raise z/OS Language Environment condition.

In addition, with z/OS Language Environment, when an exception occurs after an interlanguage call, the exception may be handled where it occurs, or percolated to its caller (written in any z/OS Language Environment-conforming language), or promoted. For more information on how to handle exceptions under the z/OS Language Environment condition handling model, refer to z/OS Language Environment Programming Guide.

Specific considerations for C and C++ under z/OS Language Environment:

1. The TRAP runtime option (equivalent to the former C/370 runtime options SPIE and STAE) determines how the z/OS Language Environment condition manager is to act upon error conditions and program interrupts. If the TRAP(OFF) runtime option is in effect, conditions detected by the operating system, often due to machine interrupts, will not be handled by the z/OS Language Environment environment and thus cannot be handled by a z/OS XL C/C++ program.
Note: TRAP(OFF) only blocks the handling of hardware (program checks) and operating system (abend) conditions. It does not block software conditions such as those that are associated with a raise or CEESGL (31-bit mode). Any conditions that are blocked because of TRAP(OFF) are not presented to any handlers (whether registered by a signal or by CEEHDLR). In particular, even for TRAP(OFF), conditions that are initiated by a signal or by CEESGL (31-bit mode) are presented to handlers registered by either signal() or CEEHDLR.

The use of the TRAP(OFF) option is not recommended; refer to z/OS Language Environment Programming Reference for more information.

2. You can use the ERRCOUNT runtime option to specify how many errors are to be tolerated during the execution of your program before an abend occurs. The counter is incremented by one for every severity 2, 3, or 4 condition that occurs. Both hardware-generated and software-generated signals increment the counter.

If your C++ program uses try, throw, and catch, it is recommended that you specify either ERRCOUNT(0) (31-bit mode), which allows an unlimited number of errors, or ERRCOUNT(n) (31-bit mode), where n is a fairly high number. This is because z/OS XL C++ generates a severity 3 condition for each thrown object. In addition, each catch clause has the potential to rethrow an object or to throw a new object. In a large C++ program, many conditions can be generated as a result of objects being thrown, and thus the ERRCOUNT can be exceeded if the value used for it is too low. The default used for ERRCOUNT is usually a low number.

Note: The z/OS XL C++ registered condition handlers (those registered by signal() and raise()), are activated after the z/OS Language Environment registered condition handlers for the current stack frame are activated. This means that if there are condition handlers for both z/OS XL C++ and z/OS Language Environment, the z/OS Language Environment handlers are activated first.

Combining C++ condition handling (using try, throw, and catch), with z/OS Language Environment condition handling may result in undefined behavior.

Handling signals using z/OS UNIX with POSIX(ON)

z/OS UNIX signal processing allows flags to control the behavior of signal processing. Using these flags, you can simulate these signals and a wide variety of other signals such as ANSI, POSIX.1, and BSD.

ANSI C has the following standard signal delivery rules:
- Traditionally, signal actions are established only through the signal().
- During signal delivery, the signal action is reset to SIG_DFL before the user signal action catcher function receives control.
- During signal delivery to a user signal catcher function, the signal mask is not changed.

POSIX.1 has the following standard signal delivery rules:
- Signal actions are typically established through the sigaction() function. With the addition of XPG4 support, there are a number of new flags that have been defined for sigaction() that extend its flexibility.
- During signal delivery, the signal action is not changed.
- During signal delivery to a user signal catcher function, the signal mask is changed to the union of:
  - The signal mask at the time of the interruption
A signal mask that blocks the signal type being delivered
The signal mask is restored when the signal catcher function returns.

BSD signals for the most part are consistent with the POSIX rules above except for the following:

- BSD signal mask is a 31-bit mask whereas the z/OS UNIX signal mask is an AMODE 64 mask. The relationship of the bits to specific signals is not the same. Therefore, we recommend you change to use the sigset manipulation functions, such as, sigadd(), sigdelete(), sigempty().
- Traditionally, for BSD to generate a signal action, the signal() function was used. However, because the signal() function is used in ANSI, BSD applications should be changed to use the bsd_signal() function.
- During signal delivery, the signal action is not changed.
- During signal delivery to a user signal catcher function, the signal mask is changed to the union of:
  - The signal mask at the time of the interruption
  - The signal mask specified in the sa_mask field of the sigaction() function
The signal mask is restored once the signal catcher function returns.

For compatibility, z/OS XL C/C++ supports the three standards listed above, and additional functions provided by XPG4.

Under z/OS XL C/C++, the primary function for establishing signal action is the sigaction() function. However, there are a number of other functions that you can use to effect signal processing. All signal types are accessible regardless of the function used to establish the signal action.

Table 83 includes functions that will establish a signal handler for a signal action.

<table>
<thead>
<tr>
<th>BSD Function</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>bsd_signal()</td>
<td>BSD version of signal()</td>
</tr>
<tr>
<td>sigaction()</td>
<td>Examine and/or change a signal action</td>
</tr>
<tr>
<td>sigignore()</td>
<td>Set disposition to ignore a signal</td>
</tr>
<tr>
<td>sigset()</td>
<td>Change a signal action and/or a thread's signal mask</td>
</tr>
<tr>
<td>signal()</td>
<td>Specify signal handling</td>
</tr>
</tbody>
</table>

Table 84 lists other signal-related functions.

<table>
<thead>
<tr>
<th>Signal Related Functions</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>abort()</td>
<td>Stop a program</td>
</tr>
<tr>
<td>kill()</td>
<td>Send a signal to a process</td>
</tr>
<tr>
<td>pthread_kill()</td>
<td>Send a signal to a thread</td>
</tr>
<tr>
<td>raise()</td>
<td>Send a signal to yourself</td>
</tr>
<tr>
<td>sigaddset()</td>
<td>Add a signal to a signal set</td>
</tr>
<tr>
<td>sigdelset()</td>
<td>Delete a signal from a signal set</td>
</tr>
<tr>
<td>sigemptyset()</td>
<td>Initialize a signal set to exclude all signals</td>
</tr>
<tr>
<td>sigfillset()</td>
<td>Initialize a signal set to include all signals</td>
</tr>
</tbody>
</table>

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Table 84. Other signal-related functions (continued)

<table>
<thead>
<tr>
<th>Signal Related Functions</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>sighold()</td>
<td>Add a signal to a thread's signal mask</td>
</tr>
<tr>
<td>siginterrupt()</td>
<td>Allow signals to interrupt functions</td>
</tr>
<tr>
<td>sigismember()</td>
<td>Test if a signal is in a signal set</td>
</tr>
<tr>
<td>sigpause()</td>
<td>Unblock a signal and wait for a signal</td>
</tr>
<tr>
<td>sigprocmask()</td>
<td>Examine and/or change a thread’s signal mask</td>
</tr>
<tr>
<td>sigqueue()</td>
<td>Queue a signal to a process</td>
</tr>
<tr>
<td>sigrelse()</td>
<td>Remove a signal from a thread’s signal mask</td>
</tr>
<tr>
<td>sigstack()</td>
<td>Set and/or get signal stack context</td>
</tr>
<tr>
<td>sigaltstack()</td>
<td>Set and/or get signal alternate stack context</td>
</tr>
<tr>
<td>sigsuspend()</td>
<td>Change mask and suspend the thread</td>
</tr>
<tr>
<td>sigwait()</td>
<td>Wait for asynchronous signal</td>
</tr>
<tr>
<td>sigpending()</td>
<td>Examine pending signals</td>
</tr>
<tr>
<td>sigtimedwait()</td>
<td>Wait for queued signals</td>
</tr>
<tr>
<td>sigwaitinfo()</td>
<td>Wait for queued signals</td>
</tr>
</tbody>
</table>

Asynchronous signal delivery under z/OS UNIX

Your z/OS UNIX application program might require its active processes to be able to react and respond to events occurring in the system or resulting from the actions of other processes communicating with its processes. One way of accomplishing such interprocess communication is for you to code your application program to identify signal conditions and determine how to react or respond when a signal condition is received from another application process.

Before you attempt to code your z/OS UNIX C/C++ application program to deliver and handle signals, you should identify all the processes that might cause signal conditions to be received by your application program's processes. You also need to know which signal condition codes are valid for your z/OS UNIX C/C++ application program and where the signal.h header file will be located and available to your application program. Your system programmer or the application program's designer should provide this information.

Note: Signal condition codes are defined in the signal.h include file.

A signal is a mechanism by which a process can be notified of, or affected by, an event occurring in the system. Examples of such events include hardware exceptions and specific actions by processes. The term signal also refers to an event itself.

The POSIX.1-defined sigaction() function allows a calling application process to examine a specific signal condition and specify the processing action to be associated with it.

You can code your application program to use the sigaction() function in different ways. Two simplistic examples of using signals within z/OS UNIX C/C++ application programs follow:

1. A process is forked but the process is aborted if the signal handler receives an incorrect value.
2. A request is received from a client process to provide information from a database. The server process is a single point of access to the database.

If coded properly for handling and delivering interprocess signals, your application program can receive signals from other processes and interpret those signals such that the appropriate processing procedure occurs for each specific signal condition received. Your application program also can send signals and wait for responses to signal handling events from other application processes. Note that signals are not the best method of interprocess communication, because they can easily be lost if more than one is delivered at the same time. You may want to use other methods of interprocess communication, such as pipes, message queues, shared memory, or semaphores.

For descriptions of the supported z/OS XL C/C++ signal handling functions, see z/OS XL C/C++ Runtime Library Reference.

Note: If your z/OS UNIX C/C++ application program calls a program written in a high-level language other than z/OS UNIX C/C++, you need to disable signal handling to block all signals from the z/OS UNIX C/C++ application program. If the called program encounters a program interrupt check situation, the results are unpredictable.

**C signal handling features under z/OS XL C/C++**

The terms used to describe implementation features and concepts are:

- Establishing a signal handler
- Enabling a signal
- Interrupting a program
- Raising a signal

**Establishing a signal handler**

A signal handler for a signal, sig_num, becomes established when `signal(sig_num, sig_handler)` is executed. (Two values of `sig_handler` are reserved: SIG_IGN and SIG_DFL. They are special values that establish the action taken.) `sig_handler` is a pointer to a function to be called when the signal is raised. This function is also known as a *signal handler*. Under C++, the signal handler function must have C linkage, by declaring it as extern "C". Under C, the function must be written in C with the default linkage in effect. That is, `sig_handler` cannot have OS, PLI, C++, or COBOL linkage. The signal handler for the signal ceases to be established when:

- The signal is explicitly reset to the system default by using `signal(sig_num, SIG_DFL)`.
- You indicate that a signal is to be ignored by using `signal(sig_num, SIG_IGN)`.
- The signal is implicitly reset to the system default when the signal is raised. When `sig_handler` is called, signal handling is reset to the default as if an implicit `signal(sig_num, SIG_DFL)` had been executed. Depending on the purpose of the signal handler, you may want to reestablish the signal from within the signal handler.
- Under C, a loaded executable is deleted using the `release()` function and a signal handler for the signal resides in the executable. In this case, default handling will be reset for all the affected signals.
- A DLL module is explicitly loaded using `dlldload()`, a function pointer in that module is obtained using `dlldqueryfn()`, a signal handler is establishing using that function, and the DLL module is then explicitly deleted using `dlldfree()`. Default handling will be reset for the affected signal.
Note: A C signal handler can be written in C, or can be written in C++ and declared as extern "C" so that it has C linkage.

Enabling a signal
A signal is enabled when the occurrence of the condition will result in either the execution of an established signal handler or the default system response. The signal is disabled when the occurrence is to be ignored, such as, when the signal action is SIG_IGN. This can be done by making the call signal(sig_num, SIG_IGN). Using z/OS UNIX with POSIX(ON), SIG_IGN may be set with several other functions, such as, sigaction(). In addition to changing the signal action to SIG_IGN, the signal can be enabled or disabled (blocked) using the sigprocmask() function.

Interrupting a program
Program interrupts or errors detected by the hardware and identified to the program by operating system mechanisms are known as hardware signals. For example, the hardware can detect a divide by zero and this result can be raised to the program.

Raising a signal
Signals that are explicitly raised by the user, by using the raise() function or using z/OS UNIX with POSIX(ON) using the kill(), killpg(), or pthread_kill() functions, are known as software signals.

Identifying hardware and software signals
The following signals are a list of signals supported with z/OS XL C/C++ under POSIX(OFF):

SIGABND
   System abend.

SIGABRT
   Abnormal termination (software only).

SIGFPE
   Erroneous arithmetic operation (hardware and software).

SIGILL
   Invalid object module (hardware and software).

SIGINT
   Interactive attention interrupt by raise() (software only).

SIGIOERR
   Serious software error such as a system read or write. You can assign a signal handler to determine the file in which the error occurs or whether the condition is an abort or abend. This minimizes the time required to locate the source of a serious error.

SIGSEGV
   Invalid access to memory (hardware and software).

SIGTERM
   Termination request sent to program (software only).

SIGUSR1
   Reserved for user (software only).

SIGUSR2
   Reserved for user (software only).
The following signals are a list of signals supported with z/OS XL C/C++ under POSIX(ON):

SIGABND
System abend.

SIGABRT
Abnormal termination (software only).

SIGALRM
Asynchronous timeout signal generated as a result of an alarm().

SIGBUS
Bus error.

SIGCHLD
Child process terminated or stopped.

SIGCLD
Child process terminated or stopped.

SIGCONT
Continue execution, if stopped.

SIGDANGER
Shutdown imminent.

SIGDUMP
Take a SYSMDUMP.

SIGFPE
Erroneous arithmetic operation (hardware and software).

SIGHUP
Hangup, when a controlling terminal is suspended or the controlling process ended.

SIGILL
Invalid object module (hardware and software).

SIGINT
Asynchronous CNTL-C from one of the z/OS UNIX shells or a software generated signal.

SIGIO
Completion of input or output.

SIGIOERR
Serious software error such as a system read or write. Assign a signal handler to determine the file in which the error occurs or whether the condition is an abort or abend. Minimize the time required to locate the source of a system error.

SIGKILL
An unconditional terminating signal.

SIGPIPE
Write on a pipe with no one to read it.

SIGPOLL
Pollable event.

SIGPROF
Profiling timer expired.
SIGQUIT
   Terminal quit signal.

SIGSEGV
   Invalid access to memory (hardware and software).

SIGSTOP
   The process is stopped.

SIGSYS
   Bad system call.

SIGTERM
   Termination request sent to program (software only).

SIGTHCONT
   The specific thread is resumed.

SIGTHSTOP
   The specific thread is stopped.

SIGTRACE
   UNIX System Services syscall trace toggle signal.

SIGTRAP
   Debugger event.

SIGTSTP
   Terminal stop signal.

SIGTTIN
   Background process attempting read.

SIGTTOU
   Background process attempting write.

SIGURG
   High bandwidth is available at a socket.

SIGUSR1
   Reserved for user (software only).

SIGUSR2
   Reserved for user (software only).

SIGVTALRM
   Virtual timer expired.

SIGWINCH
   Window size has changed.

SIGXCPU
   CPU time limit exceeded.

SIGXFSZ
   File size limit exceeded.

The applicable hardware signals or exceptions are listed in Table 85 on page 417. It also lists those hardware exceptions that are not supported (for example, fixed-point overflow) and are masked.

The applicable software signals or exceptions that are supported with POSIX(OFF) are listed in Table 86 on page 417 (see Table 87 on page 419 for the POSIX(ON) signals).
### Table 85. Hardware exceptions - Default runtime messages and system actions

<table>
<thead>
<tr>
<th>C Signal</th>
<th>Hardware Exception</th>
<th>Default Runtime Message with z/OS Language Environment</th>
<th>Default System Action with z/OS Language Environment Library</th>
</tr>
</thead>
<tbody>
<tr>
<td>SIGILL</td>
<td>Operation exception</td>
<td>CEE3201</td>
<td>Abnormal termination MVS rc=3000</td>
</tr>
<tr>
<td></td>
<td>Privileged operation exception</td>
<td>CEE3202</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Execute exception</td>
<td>CEE3203</td>
<td></td>
</tr>
<tr>
<td>SIGSEGV</td>
<td>Protection exception</td>
<td>CEE3204</td>
<td>Abnormal termination MVS rc=3000</td>
</tr>
<tr>
<td></td>
<td>Addressing exception</td>
<td>CEE3205</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Specification exception</td>
<td>CEE3206</td>
<td></td>
</tr>
<tr>
<td>SIGFPE</td>
<td>Data exception</td>
<td>CEE3207</td>
<td>Abnormal termination MVS rc=3000</td>
</tr>
<tr>
<td></td>
<td>Fixed-point divide</td>
<td>CEE3209</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Decimal overflow (for C only)</td>
<td>CEE3210</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Decimal divide</td>
<td>CEE3211</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Exponent overflow</td>
<td>CEE3212</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Floating point divide</td>
<td>CEE3215</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Compare and Trap Data Exception</td>
<td>CEE3234</td>
<td></td>
</tr>
</tbody>
</table>

**Note:** Under TSO, SIGINT will not be raised if you press the attention key. It must be raised using `raise()`.

The default runtime program mask is enabled for decimal overflow exceptions.

### Table 86 shows software signals with POSIX(OFF) or exceptions, their origin, default runtime messages and default system actions.

### Table 86. Software exceptions - Default runtime messages and system actions with POSIX(OFF)

<table>
<thead>
<tr>
<th>C Signal</th>
<th>Software Exception</th>
<th>Default Runtime Message with z/OS Language Environment</th>
<th>Default System Action with z/OS Language Environment Library</th>
</tr>
</thead>
<tbody>
<tr>
<td>SIGFPE</td>
<td><code>raise(SIGFPE)</code></td>
<td>EDC6000</td>
<td>Abnormal Termination MVS rc=3000</td>
</tr>
<tr>
<td>SIGILL</td>
<td><code>raise(SIGILL)</code></td>
<td>EDC6001</td>
<td>Abnormal Termination MVS rc=3000</td>
</tr>
<tr>
<td>SIGSEGV</td>
<td><code>raise(SIGSEGV)</code></td>
<td>EDC6002</td>
<td>Abnormal Termination MVS rc=3000</td>
</tr>
<tr>
<td>SIGFPE</td>
<td><code>raise(SIGFPE)</code></td>
<td>EDC6002</td>
<td>Abnormal Termination MVS rc=3000</td>
</tr>
<tr>
<td>SIGABND</td>
<td><code>raise(SIGABND)</code></td>
<td>EDC6003</td>
<td>Abnormal Termination MVS rc=3000</td>
</tr>
<tr>
<td>SIGTERM</td>
<td><code>raise(SIGTERM)</code></td>
<td>EDC6004</td>
<td>Abnormal Termination MVS rc=3000</td>
</tr>
<tr>
<td>SIGINT</td>
<td><code>raise(SIGINT)</code></td>
<td>EDC6005</td>
<td>Abnormal Termination MVS rc=3000</td>
</tr>
</tbody>
</table>
Table 86. Software exceptions - Default runtime messages and system actions with POSIX(OFF) (continued)

<table>
<thead>
<tr>
<th>C Signal</th>
<th>Software Exception</th>
<th>Default Runtime Message with z/OS Language Environment</th>
<th>Default System Action with z/OS Language Environment Library</th>
</tr>
</thead>
<tbody>
<tr>
<td>SIGABRT</td>
<td>raise(SIGABRT)</td>
<td>EDC6006 Abnormal Termination MVS rc=2000</td>
<td></td>
</tr>
<tr>
<td>SIGUSR1</td>
<td>raise(SIGUSR1)</td>
<td>EDC6007 Abnormal Termination MVS rc=3000</td>
<td></td>
</tr>
<tr>
<td>SIGUSR2</td>
<td>raise(SIGUSR2)</td>
<td>EDC6008 Abnormal Termination MVS rc=3000</td>
<td></td>
</tr>
<tr>
<td>SIGIOERR</td>
<td>raise(SIGIOERR)</td>
<td>EDC6009 Signal is ignored</td>
<td></td>
</tr>
</tbody>
</table>

**SIGABND considerations**
When the SIGABND signal is registered with an address of a C handler using the signal() function, control cannot resume at the instruction following the abend or the invocation of raise() with SIGABND. If the C signal handler is returned, the abend is percolated and the default behavior occurs. The longjmp() or exit() function can be invoked from the handler to control the behavior.

If SIG_IGN is the specified action for SIGABND and an abend occurs (or SIGABND was raised), the abend will not be ignored because a resume cannot occur. The abend will percolate and the default action will occur.

Two macros are available in signal.h header file that provide information about an abend. The __abendcode() macro returns the abend that occurred and __rsncode() returns the corresponding reason code for the abend. These values are available in a C signal handler that has been registered with the SIGABND signal. If you are looking for the abend and reason codes, using these macros, they should only be checked when in a signal handler. The values returned by the __abendcode() and __rsncode() macros are undefined if the macros are used outside a registered signal handler.

**SIGIOERR considerations**
When the SIGIOERR signal is raised, codes for the last operation will be set in the __amrc structure to aid you in error diagnosis.

**Default handling of signals**
The runtime environment performs default handling of a given signal unless the signal is established (signal(sig_num, sig_handler)) or the signal is disabled (signal(sig_num, SIG_IGN)). A user can set or reset default handling by coding signal(sig_num, SIG_DFL).

The default handling depends upon the signal that was raised. For more information about the default handling of a given signal, see Table 85 on page 417, Table 86 on page 417, and Table 87 on page 419.

**Using z/OS UNIX:** Table 87 on page 419 describes the default actions for signals that may be delivered to C/C++ application programs running POSIX(ON).
### Table 87. Default signal processing with POSIX(ON)

<table>
<thead>
<tr>
<th>Signal</th>
<th>Default Action</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SIGABND</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5204, and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system. If the signal is generated as a result of an abend condition, as opposed to being software generated by a <em>raise()</em> or <em>pthread_kill()</em> function, the CEE5204 message is issued along with a trace-back message indicating a user function was in control when the abend occurred.</td>
</tr>
<tr>
<td><strong>SIGABRT</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5207 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td><strong>SIGALRM</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5214 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td><strong>SIGCHLD</strong></td>
<td>The signal is ignored.</td>
</tr>
<tr>
<td><strong>SIGCLD</strong></td>
<td>The signal is ignored.</td>
</tr>
<tr>
<td><strong>SIGCONT</strong></td>
<td>The process is continued if it was stopped. Otherwise, the signal is ignored.</td>
</tr>
<tr>
<td><strong>SIGDANGER</strong></td>
<td>The signal is ignored.</td>
</tr>
<tr>
<td><strong>SIGDUMP</strong></td>
<td>The system will obtain a user address space dump.</td>
</tr>
<tr>
<td><strong>SIGFPE</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5201, and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system. If the signal is generated as a result of an abend condition, as opposed to being software generated by a <em>raise()</em> or <em>pthread_kill()</em> function, the CEE5201 message is issued along with a trace-back message indicating a user function was in control when the abend occurred.</td>
</tr>
<tr>
<td><strong>SIGHUP</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5210 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td><strong>SIGILL</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5202, and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system. If the signal is generated as a result of an abend condition, as opposed to being software generated by a <em>raise()</em> or <em>pthread_kill()</em> function, the CEE5202 message is issued along with a trace-back message indicating a user function was in control when the abend occurred.</td>
</tr>
<tr>
<td><strong>SIGINT</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5206 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td><strong>SIGIO</strong></td>
<td>The signal is ignored.</td>
</tr>
<tr>
<td><strong>SIGIOERR</strong></td>
<td>The signal is ignored. In a POSIX application running on z/OS UNIX SIGIOERR is not supported directly by the kernel. Instead, z/OS XL C/C++ maps SIGIOERR to SIGIO. Any application using SIGIOERR should not also use SIGIO.</td>
</tr>
<tr>
<td><strong>SIGKILL</strong></td>
<td>End the process with no z/OS XL C/C++ runtime cleanup.</td>
</tr>
<tr>
<td><strong>SIGPIPE</strong></td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5213 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>Signal</td>
<td>Default Action</td>
</tr>
<tr>
<td>----------</td>
<td>-------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>SIGQUIT</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5220 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGSEGV</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5203 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGSTOP</td>
<td>The process is stopped.</td>
</tr>
<tr>
<td>SIGTERM</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5205 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGTHCONT</td>
<td>The specific thread is resumed.</td>
</tr>
<tr>
<td>SIGTHSTOP</td>
<td>The specific thread is stopped.</td>
</tr>
<tr>
<td>SIGTRACE</td>
<td>The UNIX System Services syscall trace is toggled.</td>
</tr>
<tr>
<td>SIGTRAP</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5222 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGTSTP</td>
<td>The process is stopped.</td>
</tr>
<tr>
<td>SIGTTIN</td>
<td>The process is stopped.</td>
</tr>
<tr>
<td>SIGTTOU</td>
<td>The process is stopped.</td>
</tr>
<tr>
<td>SIGUSR1</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5208 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system. In past releases, the default action for this signal was to ignore the signal.</td>
</tr>
<tr>
<td>SIGUSR2</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5209 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system. In past releases, the default action for this signal was to ignore the signal.</td>
</tr>
<tr>
<td>SIGPOLL</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5225 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGURG</td>
<td>The signal is ignored.</td>
</tr>
<tr>
<td>SIGBUS</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5227 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGSYS</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5228 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGWINCH</td>
<td>The signal is ignored.</td>
</tr>
</tbody>
</table>
Table 87. Default signal processing with POSIX(ON) (continued)

<table>
<thead>
<tr>
<th>Signal</th>
<th>Default Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>SIGXCPU</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5230 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGXFSZ</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5231 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGVTALRM</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5232 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
<tr>
<td>SIGPROF</td>
<td>Clean up the z/OS XL C/C++ runtime library, issue message CEE5233 and end the process. The signal exit status is returned to the parent process if it is waiting for a child process to end. If the program is not running in a forked process, so that no parent process exists to return the signal status to, the return code 3000 is returned to the system.</td>
</tr>
</tbody>
</table>

**Dubbed Process:** A process that is not from a call to a fork() function or to a program main() function through an exec() function.

*Summary of C error handling:*

**Procedure**

1. Signal is raised. Is SIG_IGN set for the signal? Or is the signal blocked?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 2</td>
</tr>
<tr>
<td>No</td>
<td>See 3</td>
</tr>
</tbody>
</table>

2. Is the signal for a SIGABND?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 3</td>
</tr>
<tr>
<td>No</td>
<td>See 4</td>
</tr>
</tbody>
</table>

3. 
   a. Condition is percolated for default behavior.

4. 
   a. Resume at the next instruction.

5. 
   a. Continue at 6

6. Is the signal asynchronous (or previously blocked)?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 7</td>
</tr>
<tr>
<td>No</td>
<td>See 12 on page 422</td>
</tr>
</tbody>
</table>

7. Is a C handler established for the signal?
8. Was the C handler established by `signal()` or `sigaction()` with the `SA_OLD_STYLE` or `SA_RESETHAND` flag set?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 9</td>
</tr>
<tr>
<td>No</td>
<td>See 10</td>
</tr>
</tbody>
</table>

9. Run C handler using ANSI rules and transfer control to the next instruction following asynchronous interrupt.

10. Run C handler using POSIX rules and transfer control to the next instruction following the asynchronous interrupt.

11. Perform default processing.

12. Is z/OS Language Environment user handler registered?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 13</td>
</tr>
<tr>
<td>No</td>
<td>See 14</td>
</tr>
</tbody>
</table>

13. Run z/OS Language Environment user handler. The handler can resume, percolate or promote the signal. See z/OS Language Environment Programming Guide for more details.

14. Is a C handler established for the signal by `signal()` or `sigaction()` with the `SA_OLD_STYLE` or `SA_RESETHAND` flag set?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 15</td>
</tr>
<tr>
<td>No</td>
<td>See 16</td>
</tr>
</tbody>
</table>

15. Run C handler using ANSI rules and resume at the next instruction.

16. Continue at 17

17. At stack frame 0?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 18</td>
</tr>
<tr>
<td>No</td>
<td>See 21 on page 423</td>
</tr>
</tbody>
</table>

18. Was a C handler established?
<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 19</td>
</tr>
<tr>
<td>No</td>
<td>See 20</td>
</tr>
</tbody>
</table>

19.  
   a. Run C handler using POSIX signal delivery rules and resume at next instruction.

20.  
   a. Perform default processing.

21.  
   a. Default handling for the signal and percolate to next stack frame.

Signal considerations using z/OS UNIX: The following restrictions and inconsistencies exist for z/OS UNIX XL C/C++ application program signal handling:

- Signal processing is blocked by the kernel when an application program is running on a request block (RB) other than the one the main() routine was started on.

- An application program should not use the longjmp() function to exit from a signal catcher established through the use of sigaction(). The sigsetjmp() and siglongjmp() functions should be used instead of setjmp() and longjmp(). The longjmp() function can be used if the signal() function was used to established the signal catcher.

- An application program must not use the macro versions of the getc(), putc(), getchar(), and putchar() functions to perform I/O to the same file from an asynchronous signal catcher function.

- Floating point registers are saved before a call to the signal catcher function and restored when the signal catcher returns. This is done for all signals.

- For z/OS UNIX XL C/C++ application programs, the errno value is saved before a call to the signal catcher function and restored when the signal catcher returns.

Example of C signal handling under z/OS XL C or z/OS XL C++

In example program CCNGEC1 (Figure 123 on page 424), the call to signal() in main() establishes the function signal handler to process the interrupt signal when it occurs. An error value returned from this call to signal() causes the program to end with a printed error message. The signal handler function asks you to enter a y or Y from the keyboard if you want to halt the program. Entering any other character causes the program to resume operation.
/ * this example demonstrates signal handling */

#include <stdio.h>
#include <signal.h>
#include <stdlib.h>

#ifdef __cplusplus /* __cplusplus is implicitly defined when */
  extern "C" { /* the program is compiled with the z/OS C++ */
#endif /* compiler */

void handler(int);

#ifdef __cplusplus
}
#endif

int main(void) {
  if (signal(SIGINT, handler) == SIG_ERR) {
    perror("Could not set SIGINT");
    abort();
  }
  /* add code here if desired */
  raise(SIGINT);
  /* add code here if desired */
  return(0);
}

void handler(int sig_num) {
  char ch;

  signal(SIGINT, handler);
  printf("End processing\n");
  ch = getchar();
  if (ch == 'y' || ch == 'Y')
    exit(0);
}

Figure 123. Example illustrating signal handling
Chapter 29. Network communications under UNIX System Services

This chapter discusses interprocess communication, including MVS Sockets for z/OS UNIX and the X/Open Transport Interface (XTI) for z/OS UNIX and the internetworking involved.

Many products today supply a socket interface. The types of application programming interfaces (APIs) for the sockets which will be covered in this chapter are:

- X/Open Socket
- Berkeley Socket

If you are running with some other socket API, this material will not necessarily apply.

Your z/OS UNIX XL C/C++ application program can take advantage of sockets or XTI to communicate with a related application (server or client).

The X/Open Transport Interface (XTI) defines an independent transport service interface that allows multiple users to communicate at the transport level of the OSI reference model. More information can be found at the end of this chapter.

Understanding z/OS UNIX sockets and internetworking

z/OS UNIX provides support for an enhanced version of an industry-accepted protocol for client/server communication known as sockets. The three types of application programming interfaces (API), for the sockets which will be covered in this chapter are:

- X/Open Socket: The API type of socket as defined by X/Open in XPG4.2.
- Berkeley Socket: The socket API that represents a migration path for programs coded under the HOT1120 and HOT1130 elements. It allows use of the BSD4.3 interface and function in the X/Open environment. Its purpose is to expedite the porting of existing BSD4.3 applications.

The z/OS UNIX socket API provides support for both UNIX domain sockets and Internet domain sockets. UNIX domain sockets, or local sockets, allow interprocess communication within MVS independent of TCP/IP. Local sockets behave like traditional UNIX-domain sockets and allow processes to communicate with one another on a single system. Internet sockets allow application programs to communicate with others in the network using TCP/IP.

This chapter provides some background information about z/OS UNIX sockets and about network communication in general. It is intended to provide an overview of the programming concepts associated with using z/OS UNIX sockets and network communication.

For information about using the socket API, see z/OS XL C/C++ Runtime Library Reference.
Basics of network communication

This section looks at network communication from a very high level and defines some terms used throughout the book. For more detailed information on z/OS network communication and TCP/IP sockets, see z/OS V2R2.0 Communications Server: IP Configuration Guide and z/OS V2R2.0 Communications Server: IP Programmer’s Guide and Reference. For more detailed information on IPv6 network communication and AF_INET6 sockets, see z/OS V2R2.0 Communications Server: IPv6 Network and Appl Design Guide.

Network communication, or internetworking, defines a set of protocols (that is, rules and standards) that allow application programs to talk with each other without regard to the hardware and operating systems where they are run. Internetworking allows application programs to communicate independently of their physical network connections.

The internetworking technology called TCP/IP is named after its two main protocols: Transmission Control Protocol (TCP) and Internet Protocol (IP). To understand TCP/IP, you should be familiar with the following terms:

client A process that requests services on the network.

server A process that responds to a request for service from a client.

datagram The basic unit of information, consisting of one or more data packets, which are passed across an Internet at the transport level.

packet The unit or block of a data transaction between a computer and its network. A packet usually contains a network header, at least one high-level protocol header, and data blocks. Generally, the format of data blocks does not affect how packets are handled. Packets are the exchange medium used at the Internetwork layer to send data through the network.

Transport protocols for sockets

A protocol is a set of rules or standards that each host must follow to allow other hosts to receive and interpret messages sent to them. There are two general types of transport protocols:

• A connectionless protocol is a protocol that treats each datagram as independent from all others. Each datagram must contain all the information required for its delivery.

  An example of such a protocol is User Datagram Protocol (UDP). UDP is a datagram-level protocol built directly on the IP layer and used for application-to-application programs on a TCP/IP host. UDP does not guarantee data delivery, and is therefore considered unreliable. Application programs that require reliable delivery of streams of data should use TCP.

• A connection-oriented protocol requires that hosts establish a logical connection with each other before communication can take place. This connection is sometimes called a virtual circuit, although the actual data flow uses a packet-switching network. A connection-oriented exchange includes three phases:

  1. Start the connection
  2. Transfer data
  3. End the connection

  An example of such a protocol is Transmission Control Protocol (TCP). TCP provides a reliable vehicle for delivering packets between hosts on an Internet.
TCP breaks a stream of data into datagrams, sends each one individually using IP, and reassembles the datagrams at the destination node. If any datagrams are lost or damaged during transmission, TCP detects this and retransmits the missing datagrams. The data stream that is received is therefore a reliable copy of the original.

These types of protocols are illustrated in Figure 125 on page 436 and in Figure 126 on page 437.

**What is a socket?**

A *socket* can be thought of as an endpoint in a two-way communication channel. Socket routines create the communication channel, and the channel is used to send data between application programs either locally or over networks. Each socket within the network has a unique name associated with it called a *socket descriptor*—a fullword integer that designates a socket and allows application programs to refer to it when needed.

Using an electrical analogy, you can think of the communication channel as the electrical wire with its plug and think of the port, or socket, as the electrical socket or outlet, as shown in Figure 124.

![Figure 124. An electrical analogy showing the socket concept](image)

This figure shows many application programs running on a client and many application programs on a server. When the client starts a socket call, a socket connection is made between an application on the client and an application on the server.

Another analogy used to describe socket communication is a telephone conversation. Dialing a phone number from your telephone is similar to starting a socket call. The telephone switching unit knows where to logically make the correct switch to complete the call at the remote location. During your telephone conversation, this connection is present and information is exchanged. After you hang up, the connection is broken and you must start it again. The client uses the `socket()` function call to start the logical switch mechanism to connect to the server.
As with file access, user processes ask the operating system to create a socket when one is needed. The system returns an integer, the socket descriptor (sd), that the application uses every time it wants to refer to that socket. The main difference between sockets and files is that the operating system binds file descriptors to a file or device when the open() call creates the file descriptor. With sockets, application programs can choose to either specify the destination each time they use the socket—for example, when sending datagrams—or to bind the destination address to the socket.

Sockets behave in some respects like UNIX files or devices, so they can be used with such traditional operations as read() or write(). For example, after two application programs create sockets and open a connection between them, one program can use write() to send a stream of data, and the other can use read() to receive it. Because each file or socket has a unique descriptor, the system knows exactly where to send and to receive the data.

You can wait on a socket using the following asynchronous I/O functions:
- aio_read() - Asynchronous read from a socket
- aio_write() - Asynchronous write to a socket
- aio_cancel() - Cancel an asynchronous I/O request
- aio_suspend() - Wait for an asynchronous I/O request
- aio_error() - Retrieve error status for an asynchronous I/O operation
- aio_return() - Retrieve return status for an asynchronous I/O operation

You can suspend the invoking thread until a specified asynchronous I/O event, timeout, or signal occurs. These functions are described in z/OS XL C/C++ Runtime Library Reference.

z/OS UNIX Socket families
In z/OS UNIX, the following socket families are supported:
- UNIX Domain Sockets, known as local sockets, which are part of the UNIX Address Family (AF_UNIX)
- Internet Protocol Sockets, which are part of the Internet Address Family (AF_INET for IPv4 and AF_INET6 for IPv6)

AF_UNIX sockets provide communication between processes on a single system. This socket family supports two types of sockets—stream and datagram sockets. These socket types are described in the next section.

AF_INET and AF_INET6 sockets provide a means of communicating between application programs that are on different systems using the Transport Control Protocol provided by a TCP/IP product. This socket family supports both stream and datagram sockets. Each of these socket types is described in the next section.

z/OS UNIX Socket types
The z/OS UNIX socket API provides application programs with a network interface that hides the details of the physical network. The socket API supports both stream sockets and datagram sockets, each providing different services for application programs. Stream and datagram sockets interface to the transport layer protocols, UDP and TCP. You choose the appropriate interface for an application.

Stream sockets
Stream sockets act like streams of information. There are no boundaries between data, so communicating processes must agree on their own mechanism to
distinguish information. Usually, the process sending information sends the length of the data, followed by the data itself. The process receiving information reads the length and then loops, accepting data until all of it has been transferred. Stream sockets guarantee delivery of the data in the order it was sent and without duplication. The stream socket interface defines a reliable connection-oriented service. Data is sent without errors or duplication and is received in the same order as it is sent. Flow control is built in, to avoid data overruns. No boundaries are imposed on the data; the data is considered to be a stream of bytes.

Stream sockets are more common, because the burden of transferring the data reliably is handled by the system rather than by the application.

**Datagram sockets**

The datagram socket interface defines a connectionless service. Datagrams are sent as independent packets. The service provides no guarantees; data can be lost or duplicated, and datagrams can arrive out of order. The size of a datagram is limited to the size that can be sent in a single transaction. No disassembly and reassembly of packets is performed.

**Guidelines for using socket types**

This section describes criteria to help you choose the appropriate socket type for an application program.

If you are communicating with an existing application program, you must use the same protocols as the existing application program. For example, if you communicate with an application that uses TCP, you must use stream sockets. For other application programs, you should consider the following factors:

- **Reliability.** Stream sockets provide the most reliable connection. Datagram sockets are unreliable, because packets can be discarded, corrupted, or duplicated during transmission. This may be acceptable if the application program does not require reliability, or if the application program implements the reliability on top of the sockets interface. The trade-off is the increased performance available with datagram sockets.

- **Performance.** The overhead associated with reliability, flow control, packet reassembly, and connection maintenance degrade the performance of stream sockets in comparison with datagram sockets.

- **Data transfer.** Datagram sockets impose a limit on the amount of data transferred in a single transaction. If you send less than 2048 bytes at a time, use datagram sockets. As the amount of data in a single transaction increases, use stream sockets.

**Addressing within sockets**

The following sections describe the different ways to address within the socket API.

**Address families**

Address families define different styles of addressing. All hosts in the same address family use the same scheme for addressing socket endpoints. z/OS UNIX supports three address families—AF_INET, AF_INET6, and AF_UNIX. The AF_INET and AF_INET6 address families define addressing in the IP domain. The AF_UNIX address family defines addressing in the z/OS UNIX domain. In the z/OS UNIX domain, address spaces can use the socket interface to communicate with other address spaces on the same host.
Note: In this case, the z/OS UNIX domain is used in much the same way as the UNIX domain on other UNIX-type systems.

Socket address
A socket address is defined by the `sockaddr` structure in the `sys/socket.h` include file. The structure has three fields, as shown in the following example:

```c
struct sockaddr {
    unsigned char sa_len;
    unsigned char sa_family;
    char sa_data[14]; /* variable length data */
};
```

The `sa_len` field contains the length of the `sa_data` field. The `sa_family` field contains the address family. It is `AF_INET` or `AF_INET6` for the Internet domain and `AF_UNIX` for the UNIX domain. The `sa_data` field is different for each address family. Each address family defines its own structure, which can be overlaid on the `sockaddr` structure. See "Addressing within the AF_INET domain" on page 431 and "Addressing within the AF_INET6 domain" on page 431 for more information about the Internet domain, and "Addressing within the AF_UNIX domain" on page 432 for more information about the UNIX domain.

Internet addresses
Internet addresses represent a network interface. Every Internet address within an administered AF_INET domain must be unique. On the other hand, it is not necessary that every host have a unique Internet address; in fact, a host has as many Internet addresses as it has network interfaces.

Ports
A port is used to distinguish between different application programs using the same network interface. It is an additional qualifier used by the system software to get data to the correct application program. Physically, a port is a 16-bit integer. Some ports are reserved for particular application programs or protocols and are called well-known ports.

Network byte order
Ports and addresses are usually specified to calls using the network byte ordering convention. This convention is a method of sorting bytes under specific machine architectures. There are two common methods:

- Big-endian byte ordering places the most significant byte first. This method is used in IBM mainframe processors.
- Little-endian byte ordering places the least significant byte first. This method is used in Intel microprocessors.

Using network byte ordering for data exchanged between hosts allows hosts using different architectures to exchange address information. See references in figures Figure 128 on page 438, Figure 129 on page 439 and Figure 131 on page 440 for examples of using the `htons()` call to put ports into network byte order. For more information about network byte order, see z/OS XL C/C++ Runtime Library Reference.

Note: The socket interface does not handle application program data byte ordering differences. Application program writers must handle byte order differences themselves.
Addressing within the AF_INET domain

A socket address in the Internet address family comprises the following fields: the address family (AF_INET), an Internet address, the length of that Internet address, a port, and a character array. The structure of the Internet socket address is defined by the following sockaddr_in structure, which is found in the netinet/in.h include file:

```c
struct in_addr {
    ip_addr_t s_addr;
}

struct sockaddr_in {
    struct in_addr sin_addr;
    short sin_port;
    char sin_zero[8];
    char sin_family;
    int sin_len;
};
```

- `sin_len` set to the length of the sockaddr_in structure
- `sin_family` set to AF_INET T
- `sin_port` port used by the application program, in network byte order
- `sin_zero` field should be set to all zeros

Addressing within the AF_INET6 domain

A socket address in the Internet address family comprises the following fields: the address family (AF_INET6), an Internet address, the length of that Internet address, a port, flow information, and scope information. The structure of the Internet socket address is defined by the following sockaddr_in6 structure, which is found in the netinet/in.h include file:

```c
struct in6_addr {
    union {
        uint8_t _S6_u8[16];
        uint32_t _S6_u32[4];
    } _S6_un;
};
#define s6_addr _S6_un._S6_u8

struct sockaddr_in6 {
    uint8_t sin6_len;
    sa_family_t sin6_family;
    in_port_t sin6_port;
    uint32_t sin6_flowinfo;
    struct in6_addr sin6_addr;
    uint32_t sin6_scope_id;
};
```

- `sin6_len` Set to the length of the sockaddr_in6 structure
- `sin6_family` Set to AF_INET
- `sin6_port` Port used by the application program, in network byte order
sin6_flowinfo
32-bit field that contains the traffic class and the flow label

sin6_addr
a single in6_addr structure, which holds one 128-bit IPv6 address stored in network byte order

sin6_scope_id
a 32 bit integer that identifies a set of interfaces as appropriate for the scope of the address carried in the sin6_addr field.

Note: IPv6 structures are exposed by defining the _OPEN_SYS.SOCK_IPV6 feature test macro.

Addressing within the AF_UNIX domain
A socket address in the AF_UNIX address family is comprised of three fields: the length of the following pathname, the address family (AF_UNIX), and the pathname itself. The structure of an AF_UNIX socket address is defined as follows:

```
struct sockaddr_un {
    unsigned char sun_len;
    unsigned char sun_family;
    char sun_path[108]; /* pathname */
};
```

This structure is defined in the sockaddr_un structure found in sys/un.h include file. The sun_len contains the length of the pathname in sun_path; sun_family field is set to AF_UNIX; and sun_path contains the null-terminated pathname.

The conversation
The client and server exchange data using a number of functions. They can send data using send(), sendto(), sendmsg(), write(), or writev(). They can receive data using recv(), recvfrom(), recvmsg(), read(), or readv(). The following is an example of the send() and recv() call:

```
send(s, addr_of_data, len_of_data, 0);
recv(s, addr_of_buffer, len_of_buffer, 0);
```

The send() and recv() function calls specify the sockets on which to communicate, the address in memory of the buffer that contains, or will contain, the data (addr_of_data, addr_of_buffer), the size of this buffer (len_of_data, len_of_buffer), and a flag that tells how the data is to be sent. Using the flag 0 tells TCP/IP to transfer the data normally. The server uses the socket that is returned from the accept() call.

These functions return the amount of data that was either sent or received. Because stream sockets send and receive information in streams of data, it can take more than one call to send() or recv() to transfer all the data. It is up to the client and server to agree on some mechanism of signaling that all the data has been transferred.

When the conversation is over, both the client and server call the close() function to end the connection. The close() function also deallocates the socket, freeing its space in the table of connections. To end a connection with a specific client, the server closes the socket returned by accept(). If the server closes its original
socket, it can no longer accept new connections, but it can still converse with the clients it is connected to. The following is an example of the close() call:

```c
close(s);
```

**The server perspective**

Before the server can accept any connections with clients, it must register itself with TCP/IP and “listen” for client requests on a specific port.

**Allocation with socket()**

The server must first allocate a socket. This socket provides an endpoint that clients connect to.

A socket is actually an index into a table of connections, so socket numbers are usually assigned in ascending order. In the C language, the programmer calls the `socket()` function to allocate a new socket, as shown in the following example:

```c
s = socket(AF_INET, SOCK_STREAM, 0);
```

The `socket()` function requires the address family (AF_INET), the type of socket (SOCK_STREAM), and the particular networking protocol to use (when 0 is specified, the system automatically uses the appropriate protocol for the specified socket type). A new socket is allocated and returned.

**bind()**

At this point, an entry in the table of communications has been reserved for your application program. However, the socket has no port or IP address associated with it until you use the `bind()` function, which requires the following:

- The socket the server was just given
- The number of the port on which the server wishes to provide its service
- The IP address of the network connection on which the server is listening (to understand what is meant by “listening”, see “listen()”)

In C language, the server puts the port number and IP address into a `sockaddr_in` structure, passing it and the socket to the `bind()` function. For example:

```c
bind(s, (struct sockaddr *)&server, sizeof(struct sockaddr_in));
```

**listen()**

After the bind, the server has specified a particular IP address and port. Now it must notify the system that it intends to listen for connections on this socket. In C, the `listen()` function puts the socket into passive open mode and allocates a backlog queue of pending connections. In passive open mode, the socket is open for clients to contact. For example:

```c
listen(s, backlog_number);
```

The server gives the socket on which it will be listening and the number of requests that can be queued (known as the `backlog_number`). If a connection request arrives before the server can process it, the request is queued until the server is ready.
accept()

Up to this point, the server has allocated a socket, bound the socket to an IP address and port, and issued a passive open. The next step is for the server actually to establish a connection with a client. The accept() call blocks the server until a connection request arrives, or, if there are connection requests in the backlog queue, until a connection is established with the first client in the queue. The following is an example of the accept() call:

```c
client_sock = accept(s, &clientaddr, &addrlen);
```

The server passes its socket to the accept() call. When the connection is established, the accept() call returns a new socket representing the connection with the client. When the server wishes to communicate with the client or end the connection, it uses this new socket, client_sock. The original socket s is now ready to accept connections with other clients. The original socket is still allocated, bound, and opened passively. To accept another connection, the server calls accept() again. By repeatedly calling accept(), the server can establish almost any number of connections at once.

select()

The server is now ready to start handling requests on this port from any client with the server's IP address and port number. Up to this point, it has been assumed that the server will be handling only one socket. However, an application program is not limited to one socket. Typically, a server listens for clients on a particular socket but allocates a new socket for each client it handles. For maximum performance, a server should operate only on those sockets that are ready for communication. The select() call allows an application program to test for activity on a group of sockets.

**Note:** The select() function can also be used with other descriptors, such as file descriptors, pipes, or character special files.

To allow you to test any number of sockets with just a single call to select(), place the sockets to test into a bit set, passing the bit set to the select() call. A bit set is a string of bits where each possible member of the set is represented by a 0 or a 1. If the member's bit is 0, the member is not in the set. If the member's bit is 1, the member is in the set. Sockets are actually small integers. If socket 3 is a member of a bit set, then the bit that represents it is set to 1 (on).

In C, the functions to manipulate the bit sets are the following:

- **FD_SET**
  Sets the bit corresponding to a socket

- **FD_ISSET**
  Tests whether the bit corresponding to a socket is set or cleared

- **FD_ZERO**
  Clears the whole bit set

- **FD_CLR**
  Clears a bit within the bit set

To be active, a socket is ready for reading data or for writing data, or an exceptional condition may have occurred. Therefore, the server can specify three bit sets of sockets in its call to the select() function: one bit set for sockets on which to receive data; another for sockets on which to write data; and any sockets with exception conditions. The select() call tests each socket in each bit set for activity and returns only those sockets that are active.
A server that processes many clients at the same time can easily be written so that it processes only those clients that are ready for activity.

**The client perspective**

The client first issues the `socket()` function call to allocate a socket on which to communicate:

```c
s = socket(AF_INET, SOCK_STREAM, 0);
```

To connect to the server, the client places the port number and the IP address of the server into a `sockaddr_in` structure. If the client does not know the server's IP address, but does know the server's host name, the `gethostbyname()` function or the `getaddrinfo()` function is called to translate the host name into its IP address. The client then calls `connect()`. The following is an example of the `connect()` call:

```c
connect(s, (struct sockaddr *)&server, sizeof(struct sockaddr_in));
```

When the connection is established, the client uses its socket to communicate with the server.

**A typical TCP socket session**

You can use TCP sockets for both passive (server) and active (client) processes. Whereas some functions are necessary for both types, some are role-specific. After you make a connection, it exists until one of the following has occurred:

- The socket is closed by client or server
- A shutdown is performed by client or server for both read and write
- The socket is unconnected using a blank `sockaddr` structure with another `connect()` call to the socket

During the connection, data is either delivered or an error code is returned by TCP/IP.

See Figure 125 on page 436 for the general sequence of calls to be followed for most socket routines using TCP, or stream sockets.
A typical UDP socket session

User Datagram Protocol (UDP) socket processes, unlike TCP socket processes, are not clearly distinguished by server and client roles. The distinction is between connected and unconnected sockets. An unconnected socket can be used to communicate with any host; but a connected socket, because it has a dedicated destination, can send data to, and receive data from, only one host.

Both connected and unconnected sockets send their data over the network without verification. Consequently, after a packet has been accepted by the UDP interface, the arrival and integrity of the packet cannot be guaranteed.

See [Figure 126 on page 437] for the general sequence of calls to be followed for most socket routines using UDP, or datagram, sockets.
Locating the server’s port

In the client/server model, the server provides a resource by listening for clients on a particular port. Such application programs as FTP, SMTP, and Telnet listen on a well-known port—a port assigned for use to a specific application program or protocol. However, for your own client/server application programs, you need a method of assigning port numbers to represent the services you intend to provide. An easy method of defining services and their ports is to enter them into the /etc/services file or the tcpip.ETC.SERVICES data set. In C, the programmer uses the getservbyname() function or getaddrinfo() function to determine the port for a particular service. If the port number for a particular service changes, only the /etc/services file or the tcpip.ETC.SERVICES data set must be modified.

Note: TCP/IP is shipped with a tcpip.ETC.SERVICES file containing such well-known services as FTP, SMTP, and Telnet.

Network application example

The following example illustrates using socket functions in a network application program. The steps are written using many of the basic socket functions, C socket syntax, and conventions described in this book.

1. First, an application program must get a socket descriptor using the socket() call, as in the example listed in Figure 127 on page 438. For a complete
The code fragment in Figure 127 allocates a socket descriptor \( s \) in the Internet address family. The \textit{domain} parameter is a constant that specifies the domain where the communication is taking place. A \textit{domain} is the collection of application programs using the same addressing convention. z/OS UNIX supports three domains: AF_INET, AF_INET6, and AF_UNIX. The \textit{type} parameter is a constant that specifies the type of socket, which can be SOCK_STREAM, or SOCK_DGRAM.

The \textit{protocol} parameter is a constant that specifies the protocol to use. For AF_INET, it can be set to IPPROTO_UDP for SOCK_DGRAM and IPPROTO_TCP for SOCK_STREAM. Passing 0 chooses the default protocol. If successful, the \texttt{socket()} call returns a positive integer socket descriptor. For AF_UNIX, the protocol parameter \textit{must} be 0. These values are defined in thenetinet/in.h include file.

2. After an application program has a socket descriptor, it can explicitly bind a unique address to the socket, as in the example listed in Figure 128. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

```c
#include <sys/socket.h>

int s;

s = socket(AF_INET, SOCK_STREAM, 0);
```

**Figure 127. An application using socket()**

This example binds socket descriptor \( s \) to the address 129.5.24.1 and port 1024 in the Internet domain. Servers must bind to an address and port to become accessible to the network. The example in Figure 128 shows two useful utility routines:

- \texttt{inet_addr()} takes an IPv4 Internet address in dotted-decimal form and returns it in network byte order. Note that the \texttt{inet_pton()} function can take either an IPv4 or IPv6 Internet address in its standard text presentation form and return it in its numeric binary form. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

```c
int bind(int s, struct sockaddr *name, int namelen);

int rc;

struct sockaddr_in myname;

memset(&myname, 0, sizeof(myname));

myname.sin_family = AF_INET;

myname.sin_addr = inet_addr("129.5.24.1");

myname.sin_port = htons(1024);

rc = bind(s, (struct sockaddr *) &myname, sizeof(myname));
```

**Figure 128. An application using bind()**
htons() takes a port number in host byte order and returns the port in network byte order. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

Figure 129 shows another example of the bind() call. It uses the utility routine gethostbyname() to find the Internet address of the host, rather than using inet_addr() with a specific address.

```c
int bind(int s, struct sockaddr_in name, int namelen);... int rc;
int s;
char *hostname = "myhost";
struct sockaddr_in myname;
struct hostent *hp;
hp = gethostbyname(hostname);
/*clear the structure to be sure that the sin_zero field is clear*/
memset(&myname,0,sizeof(myname));
myname.sin_family = AF_INET;
myname.sin_addr.s_addr = *((ip_addr_t*)hp->h_addr);
myname.sin_port = htons(1024);
rc = bind(s,(struct sockaddr *)&myname, sizeof(myname));
```

Figure 129. A bind() function using gethostbyname()

3. After binding to a socket, a server that uses stream sockets must indicate its readiness to accept connections from clients. The server does this with the listen() call, as illustrated in the example in Figure 130.

```c
int listen(int s, int backlog);... int rc;
int s;
int rc;...
rc = listen(s, 5);
```

Figure 130. An application using listen()

The listen() call tells the TCP/IP address space that the server is ready to begin accepting connections, and that a maximum of five connection requests can be queued for the server. Additional requests are ignored. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

4. Clients using stream sockets begin a connection request by calling connect(), as shown in Figure 131 on page 440.
The `connect()` call attempts to connect socket descriptor `s` to the server with an address `servername`. This could be the server that was used in the previous `bind()` example. The connect request is completed immediately and returns control to the caller, regardless of the server accepting the connection. After a successful return, the socket descriptor `s` is associated with the connection to the server. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

5. Servers using stream sockets accept a connection request with the `accept()` call, as shown in the example listed in Figure 132.

```
int connect(int s, struct sockaddr *name, int namelen);
...;
int s;
struct sockaddr_in servername;
int rc;
...
memset(&servername, 0,sizeof(servername));
servername.sin_family = AF_INET;
servername.sin_addr = inet_addr("129.5.24.1");
servername.sin_port = htons(1024);
...
rc = connect(s, (struct sockaddr *) &servername, sizeof(servername));
```

Figure 131. An application using `connect()`

The `connect()` call attempts to connect socket descriptor `s` to the server with an address `servername`. This could be the server that was used in the previous `bind()` example. The connect request is completed immediately and returns control to the caller, regardless of the server accepting the connection. After a successful return, the socket descriptor `s` is associated with the connection to the server. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

5. Servers using stream sockets accept a connection request with the `accept()` call, as shown in the example listed in Figure 132.

```
int accept(int s, struct sockaddr *addr, int *addrlen);
...;
int clientsocket;
int s;
struct sockaddr clientaddress;
int addrlen;
...
addrlen = sizeof(clientaddress);
...
clientsocket = accept(s, &clientaddress, &addrlen);
```

Figure 132. An application using `accept()`

When a connection request is accepted on socket descriptor `s`, the name of the client and length of the client name are returned, along with a new socket descriptor. The new socket descriptor is associated with the client that began the connection, and `s` is again available to accept new connections. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

6. Clients and servers have many calls from which to choose for data transfer. The `read()` and `write()`, `readv()` and `writev()`, and `send()` and `recv()` calls can be used only on sockets that are in the connected state. The `sendto()` and `recvfrom()`, and `sendmsg()` and `recvmsg()` calls can be used at any time on datagram sockets. The example listed in Figure 133 on page 441 illustrates the use of `send()` and `recv()`.
The example in Figure 133 shows an application program sending data on a connected socket and receiving data in response. The flags field can be used to specify additional options to `send()` or `recv()`, such as sending out-of-band data. For more information see z/OS XL C/C++ Runtime Library Reference.

7. If the socket is not in a connected state, additional address information must be passed to `sendto()` and can be optionally returned from `recvfrom()`. An example of the use of the `sendto()` and `recvfrom()` calls is listed in Figure 134.

The `sendto()` and `recvfrom()` calls take additional parameters that allow the caller to specify the recipient of the data or to be notified of the sender of the data. For more information see z/OS XL C/C++ Runtime Library Reference.

8. The `writev()`, `readv()`, `sendmsg()`, and `recvmsg()` calls provide the additional features of *scatter and gather data*—two related operations where data is received and stored in multiple buffers (scatter data), and then taken from...
multiple buffers and transmitted (gather data). Scattered data can reside in multiple data buffers. The `writev()` and `sendmsg()` calls gather the scattered data and send it. The `readv()` and `recvmsg()` calls receive data and scatter it into multiple buffers.

9. Applications can handle multiple descriptors. In such situations, use the `select()` call to determine the descriptors that have data to be read, those that are ready for data to be written, and those that have pending exceptional conditions. An example of how the `select()` call is used is listed in Figure 135.

```c
fd_set readsocks;
fd_set writesocks;
fd_set exceptsocks;
struct timeval timeout;
int number_of_sockets;
int number_found;
:
/* number_of_sockets previously set to the socket number of largest * integer value. * Clear masks out. */
FD_ZERO(&readsocks);; FD_ZERO(&writesocks); FD_ZERO(&exceptsocks);
/* Set masks for socket s only */
FD_SET(s, &readsocks)
FD_SET(s, &writesocks)
FD_SET(s, &exceptsocks)
:
/* go into select wait for 5 minutes waiting for socket s to become ready or the timer has popped*/
rc = select(number_of_sockets+1,
    &readsocks, &writesocks, &exceptsocks, &timeout);
:
/* Check rc for condition set upon exiting select */
number_found = select(number_of_sockets,
    &readsocks, &writesocks, &exceptsocks, &timeout);
```

Figure 135. An application using `select()`

In this example, the application program uses bit sets to indicate that the sockets are being tested for certain conditions and also indicates a timeout. If the timeout parameter is NULL, the `select()` call blocks until a socket becomes ready. If the timeout parameter is nonzero, `select()` waits up to this amount of time for at least one socket to become ready on the indicated conditions. This is useful for application programs servicing multiple connections that cannot afford to block, waiting for data on one connection. For a complete description, see z/OS XL C/C++ Runtime Library Reference.

10. In addition to `select()`, application programs can use the `ioctl()` or `fcntl()` calls to help perform asynchronous (nonblocking) socket operations. An example of the use of the `ioctl()` call is listed in Figure 136 on page 443.
This example causes the socket descriptor \( s \) to be placed into nonblocking mode. When this socket is passed as a parameter to calls that would block, such as `recv()` when data is not present, it causes the call to return with an error code, and the global `errno` value is set to `EWOULDBLOCK`. Setting the mode of the socket to be nonblocking allows an application program to continue processing without becoming blocked. For a complete description, see \( z/OS \) XL C/C++ Runtime Library Reference.

11. A socket descriptor, \( s \), is deallocated with the `close()` call. Figure 137 shows an example. For a complete description, see \( z/OS \) XL C/C++ Runtime Library Reference.

```c
int close(int s);
... int s;
int rc;
rc = close(s);
```

**Figure 137. An application using close()**

**Using common INET**

With Common INET (CINET), you have the capability to define up to 32 AF_INET or dual AF_INET/AF_INET6 transport providers or stacks. The stacks can all be active at the same time. The information for modifying BPXPRMxx and bringing up Common INET is in \( z/OS \) UNIX System Services Planning.

For a server that you want to be able to listen to all of the available stacks at the same time, specify `INADDR_ANY` and it will be listening to all at once. Note that for an IPv6 server, `IN6ADDR_ANY` can be specified allowing the server to listen for IPv4 and IPv6 connections from all stacks.

The \( z/OS \) UNIX Common INET layer performs a multiplexing/demultiplexing function when more than one stack is activated under \( z/OS \) UNIX. Each stack has its own home IP addresses and when a program binds to a specific IP address that socket becomes associated with the one stack that is that IP address. When a program binds to `NADDR_ANY` (\( 0.0.0.0 \)) or `IN6ADDR_ANY (::)`, the socket remains available to all the stacks.
There are three ways that an INADDR_ANY or IN6ADDR_ANY program can associate itself with a single stack:

- **Call setibmopt(IBMTCP_IMAGE)** - This sets a process so all future socket() calls create sockets with only the one specified stack.
- **The _BPXK_SETIBMOPT_TRANSPORT environment variable can be used in the PARM= parameter of an MVS started proc to effectively issue a SETIBMOPT outside of the program.**
- **Call ioctl(SIOCSETRTTD)** - This associates an existing socket with the one specified stack, removing the others.

Also, you should be able to set up things so gethostbyname() or getaddrinfo() returns the home IP address of the local TCP/IP you are interested. With that, you can issue a specific bind() to that IP address. This may not be useful though, if that stack has multiple IP addresses and you really want to use INADDR_ANY to service all of them. Applications can bind to IN6ADDR_ANY to service both IPv4 and IPv6 clients when TCP/IP is enabled for IPv6.

### Compiling and binding

This section describes how to bind, load, and run z/OS XL C programs containing z/OS UNIX sockets. This information is specific to the z/OS UNIX application program interface and assumes that you are familiar with the information on compiling and binding z/OS UNIX application programs in z/OS XL C/C++ Programming Guide and z/OS Language Environment Programming Guide. C++ programs can also use z/OS UNIX sockets, but C++ programs cannot use Berkley Sockets, they must always use X/Open Sockets.

You compile and bind your sockets application program in the same way as for any other C language program. The process is shown conceptually in Figure 138 on page 445. You must make sure that the z/OS UNIX socket application programs have access to the files they need to compile and bind.
As shown, whether an application program’s I/O request is targeted at the network (TCP/IP) or at a file, the z/OS UNIX logical file system (LFS) will route the request to the appropriate physical file system (PFS).

If your C language statements contain information, such as sequence numbers, which are not part of the input for the z/OS XL C compiler, you must include the following pragma directive in your program:

```
#pragma margins(1,72)
```

Note: In order to use AF_INET sockets, you must have release 3.1 or a later level of TCP/IP installed on your system. In order to use AF_INET6 sockets, you must have release z/OS V1R4 or later of TCP/IP installed on your system.

### Using TCP/IP APIs

If you will be using the TCP/IP socket API, also called non-Berkeley sockets, you will need to read and understand this section.

When a XL C/C++ application program running under z/OS UNIX needs to communicate with another program that is running simultaneously, it needs to
exploit, from within itself, both z/OS UNIX POSIX.1 and one or more of the following application programming interfaces (APIs) provided with the IBM product TCP/IP:

- Socket APIs
  - C sockets
  - Inter-User Communication Vehicle (IUCV) sockets
- X Window System interface
- remote procedure call (RPC)

With the exception of described restrictions, you can code z/OS UNIX XL C/C++ application programs to take advantage of the documented APIs available as part of the Communications Server IP.

z/OS UNIX application programs can use socket API calls from the TCP/IP product to access UNIX file system files or MVS data sets, communicate with other systems running TCP/IP, or establish communication with and request services from a workstation system acting as an X Windows server.

**Note:** For UNIX file system file access to TCP/IP, the TCP/IP socket API calls must be used instead of the POSIX file access functions to preserve the uniqueness of file descriptors in the UNIX file system.

Before you attempt to code your application program to use TCP/IP APIs, you should understand the X Windows protocol running on the workstations that will be used as application clients. You will also need to know how to invoke X Windows to create a connection to the server on the workstation or z/OS system.

### Restrictions for using z/OS TCP/IP API with z/OS UNIX

The restrictions can be grouped into categories:

- **Header Files**

  *Header file conflicts between TCP/IP and z/OS XL C/C++.* z/OS XL C/C++ and TCP/IP have header files with the same name and overlapping function. For example, both have a `types.h` file. If you use TCP/IP API functions in your application but the z/OS XL C/C++ header file is searched for and used, the TCP/IP function does not work as intended.

  You can circumvent this problem by developing your application program with separate compilation source files for TCP/IP function and normal z/OS XL C/C++ function. You can then compile the TCP/IP source files separately from the normal z/OS XL C/C++ source files. Use the `c89 -I` option to point to the MVS data sets to search for the TCP/IP header files. Finally, you can bind all the application object files together to produce the application executable file. For the bind step, use the `c89 -l` option to point to the correct TCP/IP libraries on MVS. For example:

  ```c
  c89 -I "//tcpip.sezacmac" pgm.c -l "//tcpip.sezarnt1" ...
  ```

- **TCP/IP socket API.** Both z/OS UNIX POSIX.1-defined support and the TCP/IP for z/OS socket API use a small subset of common function calls that cannot be resolved correctly between them:
  - `close()`
  - `fcntl()`
  - `read()`
  - `write()`
Use of these calls should be reserved for one or the other, but not both, of these programming interfaces. For example, if an application program is written to use the open(), close(), read(), and write() functions for z/OS TCP/IP socket communication, it cannot use them for UNIX file system file access. z/OS XL C/C++ stream I/O functions (fopen(), fclose(), fread(), and fwrite()) must be used for UNIX file system file access. See z/OS V2R2.0 Communications Server: IP Sockets Application Programming Interface Guide and Reference for more information.

- **Creating child processes.** Generally speaking, an application program cannot have a parent process open resources—in this case sockets—and then support those resources for a child process created through a fork() function or in a process following use of an exec function. The new child process does not inherit sockets from the parent process if forked. If the child process needs sockets, it must request TCP/IP for z/OS socket support independently of the parent process. In fact, if a child process is to be forked by an application program using TCP/IP sockets under z/OS UNIX, all MVS resources to be opened should be opened by the child process rather than by the parent process.

- **TCP/IP configuration file access.** An application executable file that uses TCP/IP APIs and was bound with the c89 utility cannot locate the necessary TCP/IP configuration files, because they reside in MVS sequential data sets rather than in UNIX file system files.

To circumvent this problem, have the system programmer copy the TCP/IP configuration data sets into the root directory exactly as shown:

```
OPUT 'tcpip.tcpip.data' 'etc/resolv.conf' text
```

Copy the address of the name server, the name, and the domain name from tcpip.HOST.LOCAL to etc\hosts. You should not copy the entire file directly because you only need the address and name. The entry in the etc\hosts file follows the BSD format. The case of the filenames and the use of the quote characters as part of the name are significant. Use the TSO/E OPUT command to copy the MVS sequential data sets to the root directory. (Placing files in the root file system requires superuser authority.)

- **Program reentrancy.** The TCP/IP sockets and X Windows reentrant libraries must have a special C370LIB-directory member created for them before an application program using TCP/IP functions can be bound. The system administrator must run the C370LIB DIR function against the reentrant libraries to create it. The system administrator must do this once per library for an MVS system.

Specify the TCP/IP libraries to search on the c89 utility when binding the application program. For example:

```
c89 -l"/tcpip.sezacmac" pgm.c -l "'/tcpip.sezarnt1" ... 
```

For information on C370LIB, see z/OS XL C/C++ User's Guide.

## Using z/OS UNIX sockets

To compile, each z/OS UNIX socket application program must have access to the following z/OS C include files in an MVS PDS or in the UNIX file system directory:

- CEE.SCEEH.H /usr/include
- CEE.SCEEH.ARPA.H /usr/include/arpa
- CEE.SCEEH.NET.H /usr/include/net
- CEE.SCEEH.NETINET.H /usr/include/netinet
- CEE.SCEEH.SYS.H /usr/include/sys

**Note:** The data set prefix for each of the previous files must match the name used at your installation. CEE is the default for z/OS Language Environment.
For Berkeley SOCKETS or X/OPEN SOCKETS, all you need are the z/OS C include files.

**Note:** The data set prefix for each of these files must match the name used at your installation. CEE is the default for the z/OS XL C library.

You must compile your application program using all include files in order to access the entire z/OS UNIX socket API. To compile a program written using a particular API, you must include certain files specific to that API even though your program may not require all of them.

See z/OS XL C/C++ Runtime Library Reference, which lists the header files that must be included for each type API. They may be different for Berkeley Sockets and X/Open sockets.

The following list describes the files that each z/OS UNIX socket application program must have access to in order to bind:

- CEE.SCEELKED contains stub routines in the link library that are used to resolve external references to z/OS XL C and z/OS UNIX socket APIs.
- CEE.SCEELKEX contains LONGNAME stub routine object modules for a large portion of the Language Environment function library, including the z/OS C and z/OS UNIX socket APIs. When you IPA Link your application program, place the SCEELKEX library ahead of the SCEELKED Load Module library in the search order. This preserves long runtime function names in the object module and listings generated by IPA Link. When you bind your application program, place the SCEELKEX library ahead of the SCEELKED Load Module library in the search order. This preserves long runtime function names in the executable module and listings generated by the binder.
- CEE.SCEERUN contains the z/OS XL C and z/OS UNIX socket runtime libraries.

### Compiling under MVS batch for Berkeley sockets

You can use several methods to compile, bind, and run your sockets program. This section describes one way to compile and bind your C source program, under MVS batch, using the IBM-supplied EDCCB cataloged procedure.

**Note:** If you are planning on developing your application as a C++ application and use sockets, you must use Xopen Sockets for your application. See section “Compiling under MVS batch for X/Open sockets” on page 449 for more information.

### Sample cataloged procedure additions and changes

The following steps describe how to compile, and bind your program. For more information about the z/OS XL C/C++ cataloged procedures refer to the z/OS XL C/C++ User’s Guide.

You must make changes to the cataloged procedure, which is supplied with z/OS XL C/C++ Compiler. After you select the procedure you want to use from those available in the XL C/C++ supplied data set, CBC.SCCNPRC, you modify it. For example, if you choose EDCC then you modify it as follows:

1. Change the CPARM parameters to:

   ```bash
   CPARM='DEF(MVS,_OE_SOCKETS,_POSIX1_SOURCE=1),RENT,LO',
   ```
RENT is the reentrant option and LONGNAME is the long name option. You must specify these options to use POSIX functions read(), write(), fcntl(), and close() that are all included in z/OS XL C.

You must specify the feature test macro, _POSIX1_SOURCE=1 to access the read(), write(), fcntl(), and close() functions in the z/OS XL C include files. Or, if you choose to access all z/OS UNIX POSIX functions supported by z/OS XL C, you can specify the _OPEN_SYS feature test macro. The _OE_Sockets feature test macro exposes the socket-related definitions in all of the include files. For information on binding C code compiled with the RENT and LONGNAME options, see z/OS XL C/C++ User’s Guide.

2. To run your program under TSO/E, type the following:

   CALL 'USER.MYPROG.LOAD(PROGRAM1)' 'POSIX(ON)/'

   This loads the runtime library from CEE.SCEERUN and/or SCEERUN2.
   To use the POSIX z/OS XL C functions, you must either specify the runtime option POSIX(ON), or include the following statement in your C source program:

   #pragma runopts(POSIX(ON))

   The z/OS XL C/C++ Runtime Library Reference identifies the POSIX z/OS XL C functions, in the standards information at the beginning of each function description.

**Compiling under MVS batch with X windows for Berkeley sockets**

If you are using z/OS UNIX sockets with the latest announced release level of TCP/IP X Windows, and compiling and binding under MVS batch, you must bind your application program with the latest announced release level of TCP/IP X Windows libraries that are enabled for use with z/OS UNIX sockets.

For a complete discussion of compiling and binding z/OS UNIX sockets with TCP/IP, see z/OS V2R2.0 Communications Server: IP Programmer’s Guide and Reference.

**Compiling using the c89 utility for Berkeley sockets**

If you want to use the c89 utility to compile and bind your program, you must use the following define options on the c89 command:

   -D MVS
   -D _OE_SOCKETS

   For more information about compiling and binding, see z/OS XL C/C++ User’s Guide.

**Compiling using c89 with X Windows**

See z/OS V2R2.0 Communications Server: IP Programmer’s Guide and Reference for a complete discussion of compiling and binding with X Windows.

**Compiling under MVS batch for X/Open sockets**

You can use several methods to compile, bind, and run your sockets program. This section describes one way to compile and link-edit your C source program, under MVS batch, using the IBM-supplied EDCCB cataloged procedure.

**Sample cataloged procedure additions and changes**

The following steps describe how to compile, bind, and run your program. For more information about the z/OS XL C/C++ cataloged procedures refer to the z/OS XL C/C++ User’s Guide.
You must make changes to the cataloged procedure, which is supplied with z/OS XL C/C++ Compiler. After you select the procedure you want to use from those available in the XL C/C++ supplied data set, CBC.SCCNPRC, you modify it. For example, if you choose EDCCB then you modify it as follows:

1. Change the CPARM parameters to:

   ```
   CPARM='DEF(MVS,_XOPEN_SOURCE_EXTENDED=1,_POSIX1_SOURCE=1),
   RENT,LO',
   
   RENT is the reentrant option and LO is the long name option. You must specify these options to use POSIX functions read(), write(), fcntl(), and close() that are all included in z/OS XL C.
   
   You must specify the feature test macro, _POSIX1_SOURCE=1 to access the read(), write(), fcntl(), and close() functions in the z/OS XL C include files.
   
   Or, if you choose to access all z/OS UNIX POSIX functions supported by z/OS XL C, you can specify the _OPEN_SYS feature test macro. The _XOPEN_SOURCE_EXTENDED feature test macro exposes the socket-related definitions in all of the include files.
   
   Note: Because you are now required to compile with the RENT and LONGNAME options, you must bind your sockets application with the z/OS binder.
   
2. To run your program under TSO/E, type the following:

   ```
   CALL 'USER.MYPROG.LOAD(PROGRAM1)' 'POSIX(ON)/'
   
   To use the POSIX z/OS XL C functions, you **must** either specify the runtime option POSIX(ON), or include the following statement in your C source program:

   ```
   #pragma runopts(POSIX(ON))
   ```

Using API data sets and files for sockets

- CEE.SCEELKED contains stub routines in the link library that are used to resolve external references to z/OS XL C and z/OS UNIX socket APIs.
- CEE.SCEELKEX contains LONGNAME stub routine object modules for a large portion of the Language Environment function library, including the z/OS C and z/OS UNIX socket APIs. When you IPA Link or bind your application program, place the SCEELKEX library ahead of the SCEELKED Load Module library in the search order. This preserves long runtime function names in the object module and listings generated by IPA Link or the binder.
- CEE.SCEERUN contains the z/OS XL C and z/OS UNIX socket runtime libraries.

Notes:

1. The data set prefix for each the previous files must match the name used at your installation. CEE is the default for z/OS Language Environment.
2. Applications developed for Open Sockets can continue to use the linkage editor but cannot be compiled.

Understanding the X/Open Transport Interface (XTI)

The X/Open Transport Interface (XTI) specification defines an independent transport-service interface that allows multiple users to communicate at the transport level of the OSI reference model. Transport-layer protocols support the following characteristics:

- connection establishment
- state change support
- event handling
Although all transport-layer protocols support these characteristics, they vary in their level of support and their interpretation of format.

### Transport endpoints

A transport endpoint specifies a communication path between a transport user and a specific transport provider, which is identified by a local file descriptor (fd). When a user opens a transport endpoint, a local file descriptor fd is returned which identifies the endpoint. A transport provider is defined to be the transport protocol that provides the services of the transport layer. All requests to the transport provider must pass through a transport endpoint. The file descriptor fd is returned by the function `t_open()` and is used as an argument to the subsequent functions to identify the transport endpoint. A transport endpoint can support only one established transport connection at a time.

To be active, a transport endpoint must have a transport address associated with it by the `t_bind()` function. A transport connection is characterized by the association of two active endpoints, made by using the transport connection establishment functions `t_listen()`, `t_accept()`, `t_connect()`, and `t_rcvconnect()`.

### Transport providers for X/Open Transport Interface

The transport layer may comprise one or more transport providers at the same time. The identifier parameter of the transport provider passed to the `t_open()` function determines the required transport provider. To keep the applications portable, the identifier parameter of the transport provider should not be hard-coded into the application source code.

Currently, the only valid value for the identifier parameter for the `t_open()` function is `/dev/tcp`, indicating the TCP transport provider. Even though no device with this pathname actually exists, the library uses this value to determine which transport provider to use.

### General restrictions for z/OS UNIX

The following restrictions apply when you use XTI under z/OS UNIX.

- The file descriptor number must not exceed the limit of 65535 for XTI endpoints.
- If an endpoint is being shared among multiple processes, events such as `T_LISTEN`, `T_DATA`, and `T_EXDATA`, can be consumed by another process in the time between calls to `t_look()` and `t_rcv()` or `t_accept()`. In order to avoid processes not being aware of events occurring on endpoints, you should provide explicit synchronization mechanisms between processes.
- If an endpoint is shared:
  - The process that issues the `t_listen()` should also issue for the pending connection `t_accept()`.
  - If any other process accesses the endpoint in the time between the listen and the accept, the behavior is undefined. In order to avoid this, you should provide explicit synchronization between processes.
- If a process dies while an endpoint it was accessing is in T_INCON state, it is impossible for any other sharing endpoints to bring it out of that state.
- If access to endpoints is shared, the participating processes are responsible for serialization of access to the endpoints. If no synchronization is performed, the behavior is undefined.
- Functions are thread-safed; therefore, no two threads in a process can manipulate an endpoint at the same time. Serialization of access to endpoints beyond this level is the responsibility of the threads sharing the endpoint.
Chapter 30. Interprocess communication using z/OS UNIX

z/OS UNIX offers software vendors and customers several ways for programming processes to communicate:
- Message queues
- Semaphores
- Shared memory
- Memory mapping
- Issuing TSO commands from a shell

These forms of interprocess communication extend the possibilities provided by the simpler forms of communication: pipes, named pipes or FIFOs, signals, and sockets. Like these forms, message queues, semaphores, and shared memory are used for communication between processes. (Sockets are the most common form of interprocess communication across different systems.) For more information on these communication forms, see z/OS UNIX System Services Planning.

Message queues

XPG4 provides a set of C functions that allow processes to communicate through one or more message queues in an operating system’s kernel. A process can create, read from, or write to a message queue. Each message is identified with a “type” number, a length value, and data (if the length is greater than 0).

A message can be read from a queue based on its type rather than on its order of arrival. Multiple processes can share the same queue. For example, a server process can handle messages from a number of client processes and associate a particular message type with a particular client process. Or the message type can be used to assign a priority in which a message should be dequeued and handled.

A common client/server implementation on the same system uses two message queues for communication between client and server. An inbound message queue allows group write access and limits read access to the server. An outbound message queue allows universal read access and limits write access to the server. This implementation allows users to place invalid messages on the inbound queue or remove messages belonging to another process from the outbound queue. To solve this problem, you can use two new z/OS message queue types, ipc_SndTypePID and ipc_RcvTypePID to enforce source and destination process identification.

Create the inbound queue to the server with ipc_SndTypePID and the outbound queue from the server with ipc_RcvTypePID. This arrangement guarantees that the server knows the process ID of the client, and that the client is the only process that can receive the server’s returned message. The server can also issue msgrcv() with TYPE=0 to see if any messages belong to process IDs that have gone away. Security checks on clients are not needed, since clients are unable to receive messages intended for another process.

The ipc_PL0 constants provide possible message queue performance improvements based on workload. For information on the ipc_PL0 constants, see the msgget() function in the z/OS XL C/C++ Runtime Library Reference.
Semaphores

Semaphores, unlike message queues and pipes, are not used for exchanging data, but as a means of synchronizing operations among processes. A semaphore value is stored in the kernel and then set, read, and reset by sharing processes according to some defined scheme. A semaphore is created or an existing one is located with the `semget()` function. Typical uses include resource counting, file locking, and the serialization of shared memory.

A semaphore can have a single value or a set of values; each value can be binary (0 or 1) or a larger value, depending on the implementation. For each value in a set, the kernel keeps track of the process ID that did the last operation on that value, the number of processes waiting for the value to increase, and the number of processes waiting for the value to become 0.

If you define a semaphore set without any special flags, `semop()` processing obtains a kernel latch to serialize the semaphore set for each `semop()` or `semctl()` call. The more semaphores you define in the semaphore set, the higher the probability that you will experience contention on the semaphore latch. One alternative is to define multiple semaphore sets with fewer semaphores in each set. To get the least amount of latch contention, define a single semaphore in each semaphore set.

z/OS has added the `__IPC_BINSEM` option to `semget()`. The `__IPC_BINSEM` option provides significant performance improvement on `semop()` processing. `__IPC_BINSEM` can only be specified if you use the semaphore as a binary semaphore and do not specify `UNDO` on any `semop()` calls. `__IPC_BINSEM` also allows `semop()` to use special hardware instructions to further reduce contention. With `__IPC_BINSEM`, you can define many semaphores in a semaphore set without impacting performance.

Shared memory

Shared memory provides an efficient way for multiple processes to share data (for example, control information that all processes require access to). Commonly, the processes use semaphores to take turns getting access to the shared memory. For example, a server process can use a semaphore to lock a shared memory area, then update the area with new control information, use a semaphore to unlock the shared memory area, and then notify sharing processes. Each client process sharing the information can then use a semaphore to lock the area, read it, and then unlock it again for access by other sharing processes.

Processes can also use shared mutexes and shared read-write locks to communicate. For more information on mutexes and read-write locks see “Synchronization primitives” on page 355.

Memory mapping

In z/OS, a programmer can arrange to transparently map into a UNIX file system file process storage.

The use of memory mapping can reduce the number of disk accesses required when randomly accessing a file.

The related `mmap()`, `mprotect()`, `msync()`, and `munmap()` functions that provide memory mapping are part of the X/OPEN CAE Specification.
TSO commands from a shell

In z/OS UNIX, users of the z/OS UNIX shells can issue TSO/E commands. The user simply enters the shell command tso, followed by a TSO command string. The user can specify whether the TSO command is to be run through the shell (in which case the output will be displayed on the screen) or through a TSO environment (in which case the command output will be written to the defined standard output). For more information about running the command through the shell or through a TSO environment, see z/OS UNIX System Services Command Reference.
Chapter 31. Using templates in C++ programs

In C++, you can use a template to declare and define a set of related:

- Classes (including structs)
- Functions
- Static data members of template classes

Within an application, you can instantiate the same template multiple times with the same arguments or with different arguments. If you use the same arguments, the repeated instantiations are redundant. These redundant instantiations increase compilation time, increase the size of the executable, and deliver no benefit.

There are several basic approaches to the problem of redundant instantiations:

Control implicit instantiation in the source code

To use this approach, you can use either of the following methods:

- Concentrate implicit instantiations of a specialization
  Organize your source code so that object files contain fewer instances of each required instantiation and fewer unused instantiations. This is the least usable approach, because you must know where each template is defined and where each template instantiation is required.

- Use explicit instantiation declarations (C++11 only)
  Support for explicit instantiation declarations can be enabled by setting the LANGLEVEL(EXTENDED) or LANGLEVEL(EXTENDED0X) compiler group suboptions. Explicit instantiation declarations give you the ability to suppress implicit instantiation of templates. This helps reduce the collective size of the object files. It may also reduce the size of the final executable if the suppressed symbol definitions are meant to be found in a shared library, or if the system linker is unable to always remove additional definitions of a symbol. This approach is described in "Using explicit instantiation declarations (C++11 only)" on page 462.

Store instantiations in an include directory

Use the TEMPINC compiler option. If the template header and the template definition file have the required structure (described in "Using the TEMPINC compiler option" on page 458), each template instantiation is stored in a template include directory. If the compiler is asked to instantiate the same template again with the same arguments, it uses the stored version instead. This is the default.

Store instantiation information in a registry

Use the TEMPLATEREGISTRY compiler option. Information about each template instantiation is stored in a template registry. If the compiler is asked to instantiate the same template again with the same arguments, it points to the instantiation in the first object file instead.

The TEMPLATEREGISTRY compiler option provides the benefits of the TEMPINC compiler option but does not require a specific structure for the template header and the template definition file.

Note: The NOTEMPINC and TEMPLATEREGISTRY compiler options are mutually exclusive.
Using the TEMPINC compiler option

To use TEMPINC, you must structure your application as follows:

- Declare your class templates and function templates in template declaration files. This file must have the same file name as the template definition file and an extension or LLQ of .h. In the following example, the template declaration file is named stack.h.

  You can identify a template declaration file in either of the following ways:
  - In the UNIX file system: /usr/src/stack.h
  - In a PDS: MYUSERID.USER.H(STACK)

- For each template declaration file, create a template definition file. This file must have the same file name as the template declaration file and an extension or LLQ of .c. For a class template, this file defines all of the member functions and static data members. For a function template, this file defines the function.

  You can identify a template definition file in either of the following ways:
  - In the UNIX file system: /usr/src/stack.c
  - In a PDS: MYUSERID.USER.C(STACK)

- In your source program, specify an #include statement for each template declaration file.

- In each template declaration file, conditionally include the corresponding template definition file if the __TEMPINC__ macro is not defined.

  This produces the following results:
  - Whenever you compile with NOTEMPINC, the template definition file is included.
  - Whenever you compile with TEMPINC, the compiler does not include the template definition file. Instead, the compiler looks for a file with the same name as the template declaration file and extension .c the first time it needs a particular instantiation. If the compiler subsequently needs the same instantiation, it uses the copy stored in the template include directory.

TEMPINC example

This section contains example files and compilation code examples that show how to use the TEMPINC compiler option. The following types of files are shown:

- Two source files: stackadd.cpp and stackops.cpp
- A template declaration file: stack.h
- The corresponding template definition file: stack.c
- A function prototype: stackops.h

In this example section, note that:
1. Both source files include the template declaration file stack.h
2. Both source files include the function prototype stackops.h
3. The template declaration file conditionally includes the template definition file stack.c if it is compiled with NOTEMPINC.

Figure 139 on page 459 shows the first source file, stackadd.cpp.
```cpp
#include <iostream.h>
#include "stack.h"        // 1
#include "stackops.h"     // 2

main() {
    Stack<int, 50> s;      // create a stack of ints
    int left=10, right=20;
    int sum;
    s.push(left);          // push 10 on the stack
    s.push(right);         // push 20 on the stack
    add(s);                // pop the 2 numbers off the stack
    sum = s.pop();         // pop the sum off the stack
    cout << "The sum of: " << left << " and: " << right << " is: " << sum << endl;
    return(0);
}
```

**Figure 139. stackadd.cpp file (cntmp3.cpp)**

**Figure 140** is the source file, stackops.cpp.

```cpp
#include "stack.h"        // 1
#include "stackops.h"     // 2

void add(Stack<int, 50>& s) {
    int tot = s.pop() + s.pop();
    s.push(tot);
    return;
}
```

**Figure 140. stackops.cpp file (cntmp4.cpp)**

**Figure 141** shows stack.h, which is the template declaration file.

```cpp
#ifndef STACK_H
#define STACK_H

template <class Item, int size> class Stack {
    public:
        void push(Item item); // Push operator
        Item pop();          // Pop operator
        int isEmpty(){
            return (top==0); // Returns true if empty, otherwise false
        }
    Stack() { top = 0; } // Constructor defined inline
    private:
        Item stack[size];  // The stack of items
        int top;            // Index to top of stack
};
#endif
```

**Figure 141. stack.h file (cntmp2.h)**

**Figure 142 on page 460** shows stack.c, which is the template definition file.
The stackops.h file (Figure 143) contains the prototype for the add function, which is used in both stackadd.cpp and stackops.cpp.

```c
void add(Stack<int, 50>& s);
```

Figure 143. stackops.h File (cntmp5.h)

Figure 144 contains the JCL to compile the source files; this JCL does the following:
1. Compiles both compilation units and creates the TEMPINC destination, which is a sequential file with the following data set name MYUSERID.TEMPINC
2. Compiles the template instantiation file in the TEMPINC destination.

```c
//stack.c
template <class Item, int size>
    void Stack<Item,size>::push(Item item) {
        if (top <= size) throw size;
        stack[top++] = item;
    }
template <class Item, int size>
    Item Stack<Item,size>::pop() {
        if (top <= 0) throw size;
        Item item = stack[--top];
        return(item);
    }
```

Figure 142. stack.c file (cntmp1.c)

Figure 144 contains the JCL to compile the source files; this JCL does the following:
1. Compiles both compilation units and creates the TEMPINC destination, which is a sequential file with the following data set name MYUSERID.TEMPINC
2. Compiles the template instantiation file in the TEMPINC destination.

```c
//CC EXEC CBCC,
// INFILE='MYUSERID.USER.CPP(STACKADD)',
// OUTFILE='MYUSERID.USER.OBJ(STACKADD),DISP=SHR',
// CPARM='LSEARCH(USER.+)'                        
//-----                                
//CC EXEC CBCC,
// INFILE='MYUSERID.USER.CPP(STACKOPS)',
// OUTFILE='MYUSERID.USER.OBJ(STACKOPS),DISP=SHR',
// CPARM='LSEARCH(USER.+)'                        
//-----                                
//CC EXEC CBCC,
// INFILE='MYUSERID.TEMPINC',
// OUTFILE='MYUSERID.USER.OBJ,DISP=SHR',
// CPARM='LSEARCH(USER.+)'                        
//-----                                
//BIND EXEC CBCBG,
// INFILE='MYUSERID.USER.OBJ(STACKADD)',
// OUTFILE='MYUSERID.USER.OBJ,DISP=SHR'
//BIND.OBJ DD DSN=MYUSERID.USER.OBJ,DISP=SHR
//BIND.SYSIN DD +
//   INCLUDE OBJ(STACKOPS)
//   INCLUDE OBJ(STACK)
//*/
```

Figure 144. JCL to compile source Files and TEMPINC destination

Figure 145 on page 461 shows the syntax of how to compile the program within the z/OS shell.
Regenerating the template instantiation file
The compiler builds a template instantiation file, in the UNIX file system tempinc directory or the TEMPINC PDS, corresponding to each template declaration file. With each compilation, the compiler may add information to the file but it never removes information from the file.

As you develop your program, you may remove template function references or reorganize your program so that the template instantiation files become obsolete. You can periodically delete the TEMPINC destination and recompile your program.

TEMPINC considerations for shared libraries
In a traditional application development environment, different applications can share both source files and compiled files. When you use templates, applications can share source files but cannot share compiled files.

If you use TEMPINC:
• Each application must have its own tempinc destination.
• You must compile all of the files for the application, even if some of the files have already been compiled for another application.

Under MVS or z/OS UNIX System Services, you can easily assign a separate tempinc PDS or directory for each application.

Using the TEMPLATEDEPTH compiler option
To instantiate a large number of nested templates, you can specify the instantiation depth of recursively instantiated templates with the TEMPLATEDEPTH compiler option. By specifying a value between 1 and INT_MAX as the suboption of the TEMPLATEDEPTH compiler option, you can control the maximum number of recursively instantiated template specializations that are processed by the compiler.

The default of the option is TEMPLATEDEPTH(300).

Using the TEMPLATEREGISTRY compiler option
Unlike TEMPINC, the TEMPLATEREGISTRY compiler option does not impose specific requirements on the organization of your source code. Any program that compiles successfully with NOTEMPINC will compile with TEMPLATEREGISTRY.

The template registry uses "first come first served" algorithm:
• When a program references a new instantiation for the first time, it is instantiated in the compilation unit in which it occurs.
• When another compilation unit references the same instantiation, it is not instantiated. Thus, only one copy is generated for the entire program.
The instantiation information is stored in a template registry file. You must use the same template registry file for the entire program. Two programs cannot share a template registry file.

The default file name for the template registry file is `templreg` in the UNIX file system and `TEMPLREG` in batch (a sequential file), but you can specify any other valid file name to override this default. When cleaning your program build environment before starting a fresh or scratch build, you must delete the registry file along with the old object files.

### Recompiling related compilation units

If two compilation units, A and B, reference the same instantiation, the `TEMPLATEREGISTRY` compiler option has the following effect:

- If you compile A first, the object file A contains the code for the instantiation.
- When you later compile B, the object file for B contains a reference to the object file A.
- If you later change A so that it no longer references this instantiation, the reference in object B would produce an unresolved symbol error. When you recompile A, the compiler detects this problem and handles it as follows:
  - If the `TEMPLATERECOMPILE` compiler option is in effect, the compiler automatically recompiles B using the same compiler options that were specified for A.
  - If the `NOTEMPLATERECOMPILE` compiler option is in effect, the compiler issues a warning and you must manually recompile B.

### Switching from TEMPINC to TEMPLATEREGISTRY

Because the `TEMPLATEREGISTRY` compiler option does not impose any restrictions on the file structure of your application, it has less administrative overhead than `TEMPINC`. You can make the switch as follows:

- If your application compiles successfully with both `TEMPINC` and `NOTEMPINC`, you do not need to make any changes.
- If your application compiles successfully with `TEMPINC` but not with `NOTEMPINC`, you must change it so that it will compile successfully with `NOTEMPINC`. In each template declaration file, conditionally include the corresponding template definition file if the `__TEMPINC__` macro is not defined. This is illustrated in "TEMPINC example" on page 458.

### Using explicit instantiation declarations (C++11 only)

Syntactically, an explicit instantiation declaration is an explicit instantiation definition preceded by the `extern` keyword. This C++11 feature is controlled by the `LANGLVL(EXTENDED)` or `LANGLVL(EXTENDED0X)` compiler group suboptions, or by individual suboptions `LANGLVL(EXTERNTEMPLATE)` and `LANGLVL(NOEXTERNTEMPLATE)`. When multiple `LANGLVL` suboptions are applied, the last one wins. For example, the support for explicit instantiation declaration is disabled when `LANGLVL(NOEXTERNTEMPLATE)` is set. The default settings for `LANGLVL(EXTERNTEMPLATE)` are as follows:

<table>
<thead>
<tr>
<th>compat366</th>
<th>strict98</th>
<th>extended</th>
<th>extended0x</th>
</tr>
</thead>
<tbody>
<tr>
<td>N</td>
<td>N</td>
<td>Y</td>
<td>Y</td>
</tr>
</tbody>
</table>
There are several things to be considered when using explicit instantiation declarations:

1. (IBM extension) An explicit instantiation declaration of a class template specialization does not cause implicit instantiation of said specialization.

2. If, in a translation unit, a user-defined inline function is subject to an explicit instantiation declaration and not subject to an explicit instantiation definition:
   • implicit instantiation of said function will still occur regardless of whether it will be inlined or not.
   • (IBM extension) no out-of-line copy of the function will be generated in that translation unit regardless of whether compiler option KEEPINLINES is enabled or not.

   **Note:** This does not limit the behavior for functions implicitly generated by the compiler. Implicitly declared special members such as the default constructor, copy constructor, destructor and copy assignment operator are inline and the compiler may instantiate them. In particular, out-of-line copies may be generated.

3. Degradation of the amount of inlining achieved on functions that are not "inline" and are subject to explicit instantiation declarations may occur.

4. When a non-pure virtual member function is subject to an explicit instantiation declaration, either directly or through its class, the virtual member function must be subject to an explicit instantiation definition somewhere in the entire program or an unresolved symbol error may result at link time.

5. When implicit instantiation of a class template specialization is allowed, the user program must be written as if a use requiring the implicit instantiation of all virtual member functions of that class specialization occurs or an unresolved symbol error for a virtual member function may result at link time.

6. When implicit instantiation of a class template specialization is allowed and the specialization is subject to explicit instantiation declaration, the class template specialization must be subject to an explicit instantiation definition somewhere in the user program or an unresolved symbol error may result at link time.

The following compiler options interact with explicit instantiation declarations:

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>INLINE</td>
<td>All functions, subject to explicit instantiation declaration or not, will be considered for inlining.</td>
</tr>
<tr>
<td>TEMPINC, TEMPLATEREGISTRY</td>
<td>Explicit instantiation declarations are honored. Referenced specializations that are subject to explicit instantiation declaration but not subject to explicit instantiation definition in a translation unit will not be instantiated because of that translation unit.</td>
</tr>
</tbody>
</table>

The following IBM language extensions interact with explicit instantiation declarations:

<table>
<thead>
<tr>
<th>Pragma Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>#pragma instantiate</td>
<td>Semantically the same as an explicit instantiation definition.</td>
</tr>
<tr>
<td>#pragma do_not_instantiate</td>
<td>This pragma provides a subset of the functionality of standard C++ explicit instantiation declarations. It is provided for backwards compatibility purposes only. New applications should use standard C++11 explicit instantiation declarations.</td>
</tr>
</tbody>
</table>
Examples of explicit instantiation declarations

Figure 146 shows a simple and typical use of explicit instantiation declarations. The header (sample1.h) contains explicit instantiation declaration. One translation unit (sample1a.C) contains explicit instantiation definition. Another translation unit (sample1b.C) can use the specialization without having the specialization instantiated multiple times.

```c
sample1.h:
# include "sample1.h"

template <typename T, T val>
union A {
  T foo();
};

template <class T, T val>
T A<T, val>::foo(void) {
  return val;
}

sample1a.C:

template union A<int, 55>;

sample1b.C:

template union A<int, 55>;

int main(void) {
  return A<int, 55>().foo();
}
```

Figure 146. Simple and typical use of explicit instantiation declarations

Figure 147 on page 465 shows an erroneous case. That is, an explicit instantiation declaration of virtual member function foo() is present; but, the explicit instantiation definition of the function is not found.
sample2.C:

template <typename T, T val>
struct A {
    virtual T foo();
    virtual T bar();
};

extern template int A<int, 55>::foo();

template <class T, T val>
T A<T, val>::foo(void) {
    return val;
}

template <class T, T val>
T A<T, val>::bar(void) {
    return val;
}

int main(void) {
    return A<int, 55>().bar();
}

Figure 147. Erroneous use of explicit instantiation declarations
Chapter 32. Using environment variables

This chapter describes environment variables that affect the z/OS XL C/C++ environment. You can use environment variables to define the characteristics of a specific environment. They may be set, retrieved, and used during the execution of a z/OS XL C/C++ program.

The following environment variables affect the z/OS XL C/C++ environment if they are on when an application program runs. The variables that begin with _EDC_ and _CEE_ are described in detail in “Environment variables specific to the z/OS XL C/C++ library” on page 477. See “Locale source files” on page 964 for more information on the locale-related environment variables.

Note: The settings of these variables affect your environment even if you are using the C++ I/O stream classes. For more detailed information on I/O streaming and the Standard C++ I/O stream classes, see Standard C++ Library Reference. For information on environment variables used in z/OS UNIX System Services, see z/OS UNIX System Services Command Reference and z/OS V2R2.0 UNIX System Services User’s Guide.

_BIDIATTR

Used to specify the attributes which will determine the way the bidirectional layout transformation takes place, as shown in the following example. If _BIDIATTR is not specified or contains erroneous values, the default values will be used. For a detailed description of the bidirectional layout transformation, see Chapter 66, “Bidirectional language support,” on page 1065.

```
export _BIDIATTR="@ls typeoftext=visual:implicit, orientation=ltr:ltr,
numerals=national:national"
```

_BIDION

Used to specify if iconv will perform bidirectional layout transformation beside the basic main function (code page conversion). The value of this variable is either set to TRUE to activate the bidirectional layout transformation, or FALSE to prevent the bidirectional layout transformation. If this variable is not defined in the environment it defaults to FALSE.

_BPXK_AUTOCVT

Activates or deactivates automatic text conversion of tagged UNIX file system files. The value of this environment variable is interrogated during initialization of the C main(), and at each pthread initialization in order to set the autoconversion state for the thread. The autoconversion state for the thread is looked at by the logical file system (LFS) when determining if automatic text conversion should be performed during read/write operations to tagged UNIX file system files.

The default autoconversion state is unset, meaning that the LFS must look to the BPXPRMxx AUTOCVT parameter, which is ON, OFF, or ALL. When set to a valid value, this environment variable overrides the BPXPRMxx AUTOCVT parameter.

Restriction: When _BPXK_AUTOCVT is ON, automatic conversion can only take place between IBM-1047 and ISO8859-1 code sets. Other CCSID
pairs are not supported for automatic text conversion. To request automatic conversion for any CCSID pairs that Unicode service supports, set _BPXK_AUTOCVT to ALL.

During main() initialization, the following behavior is defined for this environment variable:

**Setting Autoconversion State for the Thread**

**ON** Activates the automatic conversion of tagged files for Enhanced ASCII. This affects conversion for I/O for regular, pipe, and character special files that are tagged.

**OFF** Deactivates the automatic conversion of tagged files.

**ALL** Activates the automatic conversion of tagged files that are supported by z/OS UNICODE. This affects conversion for I/O for regular and pipe files that are tagged. If the conversion is between EBCDIC and ASCII, it also affects conversion for I/O for character special files.

<other>
Treated as unset. Autoconversion defers to BPXPRMxx AUTOCVT parameter.

Changing the value of this environment variable using setenv(), putenv(), or clearenv() during execution of the application will behave in the following manner:

- Ignored after the first pthread create, although getenv() might show otherwise. The autoconversion state will remain unchanged.
- Deleting or clearing the environment variable, or setting the value to an invalid value before the first pthread create will change the autoconversion state to unset.
- Has no effect on initially untagged UNIX file system files that have already been opened using fopen() or freopen() on the current thread and FILETAG(AUTOCVT) is in effect. These files were specifically marked, or not marked, for automatic text conversion, at the file descriptor level, at the time they were opened. The text conversion state for the already opened file descriptors depended on whether or not autoconversion for the thread was activated or deactivated at the time of the open.
- The standard streams may have already been setup for automatic text conversion, before the main() begins execution, using EBCDIC CCSID 1047 as the File CCSID. Therefore, changing the autoconversion state using one of these methods will not affect the standard streams. Specifically, an application running with ASCII CCSID 819 as the Program CCSID will continue to have text conversion with the standard streams.

Changing the value of this environment variable using any other mechanism is ignored, although getenv() might show otherwise. You can use setenv() with a value of NULL to delete an environment variable.

**_BPXK_CCSIDS**
Defines the EBCDIC<->ASCII pair of coded character set IDs (CCSIDS) to be used when converting text data, and for automatic tagging new or empty UNIX file system files. The syntax of the environment variable value is as follows, where e is the EBCDIC CCSID and a is the ASCII CCSID.
Language Environment C/C++ applications will initialize with the default IBM-1047<->ISO8859-1 pair. This is equivalent to specifying:

```c
_BPXK_CCSIDS=(1047,819)
```

before running the application.

The value of this environment variable is interrogated during initialization of the C `main()`, and at each pthread initialization in order to set the Program CCSID for the thread. For the `main()`, the Program CCSID is set to the ASCII value of the pair when the `main()` is part of an ASCII compile unit, otherwise it is set to the EBCDIC value of the pair. The Program CCSID for a thread is set based on the compiled codeset of the thread start routine. When ASCII, the ASCII value of the CCSID pair is used, else the EBCDIC value.

**Note:** Starting from z/OS V2R1, environment variable `_BPXK_PCCSID` is introduced to represent Program CCSID. The behavior of `_BPXK_CCSIDS` of the existing programs will not be affected unless `_BPXK_PCCSID` is set. If both `_BPXK_CCSIDS` and `_BPXK_PCCSID` are set before a program runs, `_BPXK_PCCSID` is used as the initial value of program CCSID. When a program is running, the CCSID of a thread can be affected by calling `setenv()` or `putenv()` with either of the two environment variables.

Changing the value of this environment variable using `setenv()`, `putenv()`, or `clearenv()` during execution of the application will behave in the following manner:

- Ignored after the first pthread create, although `getenv()` might show otherwise. The current CCSID pair used for conversion & tagging purposes will remain unchanged.
- Deleting or clearing the environment variable before the first pthread create will result in the default CCSID pair (1047,819) being used for conversion and tagging purposes.
- Using improper syntax before the first pthread create will result in the CCSID pair being set to (0,0). This will prevent any further conversion.
- Has no effect on initially untagged new or empty UNIX file system files that have already been opened using `fopen()`, `fropen()`, or `popen()` on the current thread and `FILETAG(AUTOTAG)` is in effect. These files were setup for tagging upon first write at the time they were opened. The File CCSID was set to what the Program CCSID was at the time of the open.
- The standard streams may have already been setup for automatic text conversion, before the `main()` begins execution, using EBCDIC CCSID 1047 as the File CCSID, therefore changing the CCSID pair using one of these methods will not affect the standard streams.

**Note:** Changing the value of this environment variable using any other mechanism is ignored, although `getenv()` might show otherwise. You can use `setenv()` with a value of NULL to delete an environment variable.

**_BPXK_PCCSID**

Identifies the program CCSID for the running thread or user. It can be used to override the internal default of 1047 (EBCDIC). Any value between 0 and 65535 can be assigned. However, to avoid any subsequent errors, only values that are supported by Unicode Services can be used. Setting or unsetting this variable has no effect when translation for a file has started. When unset, the internal value of the program CCSID reverts back to the default of 1047.
_BPXK_SIGDANGER
Set to either YES or NO, this variable modifies the process termination
mechanism used during UNIX System Services Shutdown. During
Shutdown the kernel sends a signal to each non-permanent non-blocking
process. If _BPXK_SIGDANGER is not in the environment, or if its value is
not YES, then SIGTERM is sent to these processes. If _BPXK_SIGDANGER
is present in the environment and has the value YES then signal
SIGDANGER will be sent instead of SIGTERM. The default action for
SIGTERM is to terminate the process, but the default action for
SIGDANGER is to ignore the signal. The application may register a
SIGDANGER signal catcher function to handle shutdowns. If the process
does not end in a short while after being sent the first signal, the kernel
will send SIGKILL to the process. If the process does not end in a short
while after the second signal is sent, the process will be brought down
using CALLRTM ABTERM=YES.

Note: The program should not use the environ external variable to put this
or any other "_BPXK_" environment variable into its own environment.
The Kernel will not be told about the environment variable setting when it
is added to the environment this way. The program should use an environ
pointer to put this variable into the environment of a new process created
with spawn() or exec(). In this case the kernel will notice _BPXK_
environment variables being created for a new program image. In addition,
the kernel will correctly detect _BPXK_ environment variables generated
into child processes created via fork() and spawn().

_CEE_DLLLOAD_XPCOMPAT
Used to indicate whether certain 31 bit XPLINK DLL application
initialization compatibility behaviors should be disabled.

_CEE_DMPTARG
Used to specify the directory in which Language Environment dumps
(CEEDUMPs) are written for applications that are running as the result of
a fork, exec, or spawn. This environment variable is ignored if the
application is not run as a result of a fork, exec, or spawn. Additionally
_CEE_DMPTARG can be used to direct the CEEDUMPs output to a
specific sysout class.

_CEE_ENVFILE
Used to specify a file from which to read environment variables.

_CEE_ENVFILE_COMMENT
Used to define the comment character to be checked for when z/OS XL
C/C++ reads subsequent records from the file.

_CEE_ENVFILE_CONTINUATION
Used to define the continuation character to be checked for when z/OS XL
C/C++ reads subsequent records from the file.

_CEE_ENVFILE_S
Used to specify a file from which to read environment variables, stripping
trailing white space from each NAME=VALUE line read.

_CEE_HEAP_MANAGER
Used to specify the DLL name for the Vendor Heap Manager to be used
during execution of the application.

_CEE_REALLOC_CONTROL
Used to specify the lower bound for the tolerance percentage to be applied
and specify the percentage that the storage request will be increased if the request is greater than or equal to the lower bound specified.

CEED_RUNOPTS
Used to specify Language Environment runtime options to a program invoked by using one of the exec functions, such as a program which is invoked from one of the z/OS UNIX shells.

_EDC_ADD_ERRNO2
Appends errno2 information to the output of perror() and strerror().

_EDC_ANSI_OPEN_DEFAULT
Affects the characteristics of MVS text files opened with the default attributes.

_EDC_AUTOCVT_BINARY
If automatic file conversion is enabled (_BPXK_AUTOCVT=ON and running with FILETAG(AUTOCVT) runtime option), this environment variable activates or deactivates automatic conversion of untagged UNIX file system files opened in binary mode and not opened for record I/O.

_EDC_BYTE_SEEK
Specifies that fseek() and ftell() should use relative byte offsets.

_EDC_CLEAR_SCREEN
Affects the behavior of output text terminal files.

_EDC_COMPAT
Specifies that C/C++ should use specific functional behavior from previous releases of C/370.

_EDC_CONTEXT_GUARD
Allows the user to control the method used to handle the guard page for AMODE 64 user context stacks.

_EDC_C99_NAN
Sets the binary floating-point representation behavior of infinite value and Not a Number for the printf family of functions

_EDC_DLL_DIAG
Indicates if additional DLL diagnostic information should be generated upon failure for the following DLL functions: dlopen(), dlclose(), dllqueryfn(), dllqueryvar(), dlscopy(), dllfree(), and dllclose().
_EDC_DLL_DIAG has no effect on implicit DLLs. If _EDC_DLL_DIAG is not set by the user, it will default to QUIET.

_EDC_EOVERFLOW
Sets the behavior of the ftell(), fseek(), fstat(), lstat(), stat(), and mmap() functions. By default these functions will not check for the EOVERFLOW error condition. Setting _EDC_EOVERFLOW to YES enables testing for this condition, and, if overflow is detected, setting errno to EOVERFLOW and returning an error.

_EDC_ERRNO_DIAG
Indicates if additional diagnostic information should be generated, when the perror() or strerror() functions are called to produce an error message.

_EDC_FLUSH_STDOUT_PIPE
Flushes the stdout stream when the stdin stream is being read. Both stdin and stdout must be pipes.
_EDC_FLUSH_STDOUT_SOCKET
Flushes the stdout stream when the stdin stream is being read. Both stdin and stdout must be sockets.

_EDC_GLOBALSTREAMS
Allows the C standard streams stdin, stdout and stderr to have global behavior. _EDC_GLOBALSTREAMS is not supported in AMODE 64.

_EDC_IEEEV1_COMPATIBILITY_ENV
Used to access original versions of the fdlibm functions when the value of _EDC_IEEEV1_COMPATIBILITY_ENV is set to ON.

_EDC_IO_ABEND
Controls if the runtime library should attempt to recover from an abend issued during OS I/O processing.

_EDC_IO_TRACE
Indicates which files to perform file I/O tracing on, the level of detail to provide for file I/O tracing, and the trace buffer size to use for each file.

_EDC_POPEN
Specifies that popen() uses spawn() instead of fork().

_EDC_PTHREAD_BACKOUT
Controls the behavior of threads in abnormal termination by determining whether to call Resource Recovery Services to backout in-flight units of recovery.

_EDC_PTHREAD_YIELD
Used to control when pthread_yield() and sched_yield() will allow a thread to give up control of a processor so that another thread may have the opportunity to run.

_EDC_PTHREAD_YIELD_MAX
Allows a user program to define the max yield (wait) time for a particular thread.

_EDC_PUTENV_COPY
Copies the putenv() string into storage owned by Language Environment.

_EDC_RRDS_HIDE_KEY
 Relevant for VSAM RRDS files opened in record mode. Enables calls to fread() that specify a pointer to a character string and do not append the Relative Record Number to the beginning of the string.

_EDC_STOR_INCREMENT
Sets the size of increments to the internal library storage subpool acquired above the 16M line. _EDC_STOR_INCREMENT is not supported in AMODE 64 applications. In AMODE 64 applications, this environment variable is replaced by the IOHEAP64 runtime option.

_EDC_STOR_INCREMENT_B
Sets the size of increments to the internal library storage subpool acquired below the 16M line. _EDC_STOR_INCREMENT_B is not supported in AMODE 64 applications. In AMODE 64 applications, this environment variable is replaced by the IOHEAP64 runtime option.

_EDC_STOR_INITIAL
Sets the initial size of the internal library storage subpool acquired above the 16M line. _EDC_STOR_INITIAL is not supported in AMODE 64 applications. In AMODE 64 applications, this environment variable is replaced by the IOHEAP64 runtime option.
_EDC_STOR_INITIAL_B
Sets the initial size of the internal library storage subpool acquired below
the 16M line. _EDC_STOR_INITIAL_B is not supported in AMODE 64
applications. In AMODE 64 applications, this environment variable is
replaced by the IOHEAP64 runtime option.

_EDC_STRPTM_STD
Indicates changes to strftime() that are provided for UNIX standard
compliance.

_EDC_SUSV3
Indicates behavioral changes that are provided for SUSV3 compliance in an
error path. The affected interfaces are typically setting errno to values that
were not used before and, in some cases, returning failure for conditions
that had not been tested before SUSV3. By default the affected interfaces
will not check for these conditions. When the value of _EDC_SUSV3 is set
to 1, the SUSV3 behavior is enabled. When the value of _EDC_SUSV3 is set
to 2, all the behaviors protected by _EDC_SUSV3=1 are exposed, and pole
error related behaviors specified by SUSV3 will be enabled.

_EDC_UMASK_DFLT
Allows the user to control how the C library sets the default umask used
when the program runs.

_EDC_ZERO_RECLEN
Enables processing of zero-length records in an MVS data set opened in
variable format.

_ICONV_MODE
Selects the behavior mode for iconv_open(), iconv(), and iconv_close() family of functions.

_ICONV_TECHNIQUE
Determines the conversion technique used by Unicode Conversion
Services. For more information regarding the Unicode conversion Services value, see z/OS Unicode Services User’s Guide and Reference.

_ICONV_UCS2
Tells iconv_open(Y, X) what type of conversion method to setup when
there is a choice between "direct" conversion from X to Y and "indirect" X
to UCS-2 to Y. This variable is ignored when using Unicode Conversion Services.

_ICONV_UCS2_PREFIX
Tells iconv_open() what z/OS dataset name prefix to use to find UCS-2 tables if they cannot be found in the HFS. This variable is ignored when using Unicode Conversion Services.

LANG
Determines the locale to use for the locale categories when neither the
LC_ALL environment variable nor the individual locale environment
variables specify locale information. This environment variable does not
interact with the language setting for messages.

LC_ALL
Determine the locale to be used to override any values for locale categories
specified by the settings of the LANG environment variable or any
individual locale environment variables.
**LC_COLLATE**
Determines the behavior of ranges, equivalence classes, and multicharacter collating elements.

**LC_CTYPE**
Determines the locale for the interpretation of byte sequences of text data as characters (for example, single-byte versus multibyte characters in arguments and input files).

**LC_MESSAGES**
Determines the language in which messages are to be written.

**LC_MONETARY**
Determines the locale category for monetary-related numeric formatting information.

**LC_NUMERIC**
Determines the locale category for numeric formatting (for example, thousands separator and radix character) information.

**LC_TIME**
Determines the locale category for date and time formatting information.

**LC_TOD**
Determines the locale category for time of day and Daylight Savings Time formatting information.

**LIBPATH**
Allows an absolute or relative pathname to be searched when loading a DLL. If the input filename contains a slash (/), it is used as is to locate the DLL. If the input filename does not contain a slash, then LIBPATH is used to determine the pathname to load. LIBPATH specifies a list of directories separated by colons. If the LIBPATH begins or ends with a colon, then the working directory is also searched first or last, depending on the position of the stand-alone colon. The "::" specification can only occur at the beginning or end of the list of directories. If you are running POSIX(ON), then UNIX file system is searched first followed by MVS. If you are running POSIX(OFF), then MVS is searched first followed by UNIX file system. This double search can be avoided by using unambiguous DLL names.

**LOCPATH**
Tells the setlocale() function the name of the directory in the UNIX file system from which to load the locale object files. It specifies a colon separated list of UNIX file system directories.

If LOCPATH is defined, setlocale() searches UNIX file system directories in the order specified by LOCPATH for locale object files it requires. Locale object files in the UNIX file system are produced by the localedef utility running under z/OS UNIX.

If LOCPATH is not defined and setlocale() is called by a POSIX program, setlocale() looks in the default UNIX file system locale directory, /usr/lib/nls/locale, for locale object files it requires. If setlocale() does not find a locale object it requires in the UNIX file system, it converts the locale name to a PDS member name and searches locale PDS load libraries associated with the program calling setlocale().

**Note:** XPLINK locales have an .xplink suffix added to the end of the locale name. For more information about XPLINK locale names, see "Locale naming conventions" on page 994.
**PATH** The set of UNIX file system directories that some z/OS XL C/C++
functions, such as EXECVP, use in trying to locate an executable. The
directories are separated by a colon (:) delimiter. If the pathname contains a
slash, the PATH environment variable will not be used.

**__POSIX_SYSTEM**
Determines the behavior of the system() function when the POSIX(ON)
runtime option has been specified. If __POSIX_SYSTEM=NO, then system() behaves as in Language Environment/370 1.2: it creates a nested enclave within the same process as the invoker (allowing such things as sharing of memory files). Otherwise, system() performs a fork() and exec(), and the target program runs in a separate process (preventing such things as sharing of memory files).

**Restriction:** __POSIX_SYSTEM=NO is not supported in AMODE 64 applications.

**__POSIX_TMPNAM**
Determines the behavior of the tmpnam() function when the POSIX(ON) runtime option has been specified. If the __POSIX_TMPNAM environment variable is set to NO, tmpnam() behaves as if it was called under POSIX(OFF). Otherwise, tmpnam() generates a unique file name in the UNIX file system.

**STEPLIB**
Determines the STEPLIB environment that is created for an executable file. It can be a sequence of MVS data set names separated by a colon (:), or can contain the value CURRENT or NONE. If you do not want a STEPLIB environment propagated to the environment of the executable file, specify NONE. The STEPLIB environment variable defaults to the value CURRENT, which will propagate your current environment to that of the executable file. See z/OS UNIX System Services Command Reference for more information on the use of the STEPLIB variable and changing the search order for z/OS programs.

**TZ or _TZ**
Time zone information. The TZ and _TZ environment variables are typically set when you start a shell session, either through /etc/profile or .profile in your home directory. For more information, see Chapter 62, “Customizing a time zone,” on page 1013.

---

### Working with environment variables

The following library functions affect environment variables:

- setenv()
- clearenv()
- getenv()
- __getenv()
- putenv()
- unsetenv()

The setenv() function adds, changes, and deletes environment variables in the environment variable table. The getenv() function retrieves the values from the table. If it does not find an environment variable, getenv() returns NULL. The clearenv() function clears the environment variable table, and resets to default behavior the actions affected by z/OS XL C/C++-specific environment variables. The unsetenv() function deletes environment variables from the table.
The __getenv() function behaves almost the same as getenv() except getenv() returns the address of the environment variable value string that has been copied into a buffer, whereas __getenv() returns the address of the actual value string in the environment variable array. Because the value is not buffered, __getenv() cannot be used in a multithreaded application or in a single threaded application where the function setenv() changes the value of the variables.

The putenv() function provides a subset of the function of setenv() and is provided for convenience in porting UNIX applications. putenv(env_var) is the same as setenv(var_name, var_value, i) where env_var represents the string var_name=var_value.

For a complete description of these functions, refer to z/OS XL C/C++ Runtime Library Reference.

Environment variables may be set any time in an application program or user exit. You can use the exit routine CEEBINT to set environment variables through calls to setenv(). For more information on the z/OS Language Environment user exit CEEBINT, refer to “Using runtime user exits in z/OS Language Environment” on page 837. You can also set environment variables by using the ENVAR runtime option. The syntax for this option is as follows:

ENVAR("1st_var=1st_value", "2nd_var=2nd_value")

For more information on this runtime option, refer to z/OS Language Environment Programming Reference.

Specifying the _CEE_ENVFILE or _CEE_ENVFILE_S environment variable with a filename on the ENVAR option enables you to read more environment variables from that file. See "Environment variables specific to the z/OS XL C/C++ library" on page 477 for more information about _CEE_ENVFILE and _CEE_ENVFILE_S.

Environment variables set with the setenv() function exist only for the life of the program, and are not saved before program termination. Child programs are initialized with the environment variables of the parent. However, environment variables set by a child program are not propagated back to the parent upon termination of the child program.

Note: If you are running with POSIX(ON), environment variables are copied from a parent process to a child process when a fork() function is called, and are inherited by the new process image when an EXEC function is called.

When a parent process invokes a child process by using system(), using the ANSI form of the system function, the child receives its environment variables from the value of the ENVAR runtime option specified on the invocation of system(). For example:

system("PGM=CHILD,PARM='ENVAR(ABC=5)/'");

Naming conventions
Avoid the following when creating names for environment variables:
= Not valid and will generate an error message.
_CBC_ Reserved for z/OS XL C/C++ specific environment variables.
_CCN_ Reserved for z/OS XL C/C++ specific environment variables.
Reserved for z/OS XL C/C++ specific environment variables.

Reserved for z/OS XL C/C++ specific environment variables used with z/OS Language Environment. See "Environment variables specific to the z/OS XL C/C++ library" for more information.

Reserved for z/OS XL C/C++ specific environment variables used in the kernel. See the spawn callable service in z/OS UNIX System Services Programming: Assembler Callable Services Reference for more information.

DBCS characters
Multibyte and DBCS characters should not be used in environment variable names. Their use can result in unpredictable behavior. Multibyte and DBCS characters are allowed in environment variable values; however, the values are not validated, and redundant shifts are not removed.

white space
Blank spaces are valid characters and should be used carefully in environment variable names and values. For example, setenv(" my name"," David ",1) sets the environment variable <space>my<space>name to <space><space>David. A call to getenv("my name"); returns NULL indicating that the variable was not found. You must specifically query getenv(" my name") to retrieve the value of " David".

The environment variable names are case-sensitive. The empty string is a valid environment variable name.

Note: In general, it is a good idea to avoid special characters, and to use portable names containing just upper and lower case alphabetics, numerics, and underscore characters. Environment variable names containing certain special characters, such as slash (/), are not propagated by the z/OS UNIX shells. Therefore, these variable names are not available to a program called using the POSIX system() function.

Environment variables specific to the z/OS XL C/C++ library
The following z/OS XL C/C++ specific environment variables are supported to provide various functions. z/OS XL C/C++ variables have the prefix _CEE_ or _EDC_. You should not use these prefixes to name your own variables.

- _CEE_DLLLOAD_XPCOMPAT
- _CEE_DMPTARG
- _CEE_ENVFILE
- _CEE_ENVFILE_COMMENT
- _CEE_ENVFILE_CONTINUATION
- _CEE_ENVFILE_S
- _CEE_HEAP_MANAGER
- _CEE_REALLOC_CONTROL
- _CEE_RUNOPTS
- _EDC_ADD_ERRNO2
- _EDC_ANSI_OPEN_DEFAULT
- _EDC_AUTOCVT_BINARY
- _EDC_BYTE_SEEK
- _EDC_CLEAR_SCREEN
- _EDC_COMPAT
• _EDC_CONTEXT_GUARD
• _EDC_C99_NAN
• _EDC_DLL_DIAG
• _EDC_EOVERFLOW
• _EDC_ERRNO_DIAG
• _EDC_FLUSH_STDOUT_PIPE
• _EDC_FLUSH_STDOUT_SOCKET
• _EDC_GLOBAL_STREAMS
• _EDC_IEEEV1_COMPATIBILITY_ENV
• _EDC_IO_ABEND
• _EDC_IO_TRACE
• _EDC_POPEN
• _EDC_PTHREAD_BACKOUT
• _EDC_PTHREAD_YIELD
• _EDC_PTHREAD_YIELD_MAX
• _EDC_PUTENV_COPY
• _EDC_RRDS_HIDE_KEY
• _EDC_STOR_INCREMENT
• _EDC_STOR_INCREMENT_B
• _EDC_STOR_INITIAL
• _EDC_STOR_INITIAL_B
• _EDC_STRPTM_STD
• _EDC_SUSV3
• _EDC_UMASK_DFLT
• _EDC_ZERO_RECLEN

There are no default settings for the environment variables that begin with _EDC_.

There are, however, default actions that occur if these environment variables are
undefined or are set to invalid values. See the descriptions of each variable below.

The z/OS XL C/C++ specific environment variables may be set with the setenv() function.

__CEE_DLLLOAD_XPCOMPAT__

Used to indicate if certain 31-bit XPLINK DLL application initialization
compatibility behaviors should be disabled.

This environment variable should only be used for applications that do not run
properly when migrating from one release to another. While the correct runtime
behavior is in the current release, this environment variable provides compatibility
support for existing programs. The need to use these settings indicates incorrect
programming within the application (for example, reliance on a particular order of
C++ static construction across all DLLs that comprise the application). When
possible, you should correct the application rather than use this environment
variable.

0 Always the most current behavior (e.g. no compatibility behavior enabled).
This is identical to the behavior when __CEE_DLLLOAD_XPCOMPAT__ is not set.
1 Disable static initialization prerequisite XPLINK DLL load ordering introduced in z/OS V1R6.

2 Disable non-XPLINK to XPLINK DLL function pointer compatibility introduced in z/OS V1R8.

3 Disable both static initialization prerequisite XPLINK DLL load ordering, and non-XPLINK to XPLINK DLL function pointer compatibility. (Disables both behaviors 1 and 2.)

z/OS Language Environment converts the specified string value to a signed integer, and interprets this value as a bit mask to determine which functions to use in compatibility mode. This allows any combination of compatibility behaviors to be specified.

Here are some examples of how you might set this environment variable:

- **z/OS UNIX:** export _CEE_DLLLOAD_XPCOMPAT=1 Disable behavior 1
- **Batch/TSO command line:** ENVAR("_CEE_DLLLOAD_XPCOMPAT=3") Disable behaviors 1 and 2

**Note:** Any change to the _CEE_DLLLOAD_XPCOMPAT environment variable after the application enclave has already been initialized, will not have any effect on the current application enclave.

For information about XPLINK function pointer compatibility see [XPLINK applications](#) on page 302.

**_CEE_DMPTARG**

You can use this variable in two ways:

1. To specify the directory in which Language Environment dumps (CEEDUMPs) are written for applications that are running as the result of a fork, exec, or spawn.
   - This environment variable is ignored if the application is not run as a result of a fork, exec, or spawn. When _CEE_DMPTARG is set in one of these environments, its value is used as the directory name in which to place CEEDUMPs.
   - If in a shell, you set the environment variable as follows. Language Environment dumps will be written to directory /u/userid/dmpdir.
     ```
     export _CEE_DMPTARG=/u/userid/dmpdir
     ```
   - If in a shell, you set the environment variable as follows. In this case, Language Environment dumps will be written to directory "cwd"/dmpdir, where "cwd" is the current working directory.
     ```
     export _CEE_DMPTARG=dmpdir
     ```

2. To direct the CEEDUMPs output to a specific sysout class.
   - When Language Environment dumps (CEEDUMPS) are produced as a result of running a job, by default they will be written to the default sysout class. You can use _CEE_DMPTARG to direct the CEEDUMPS output to a specific sysout class by using this environment variable as follows, where x is the output class.
     ```
     _CEE_DMPTARG=SYSOUT(x)
     ```
   - You can also use the CEEDUMP runtime option to specify a sysout class for dynamically allocated Language environment dump reports. In addition to a sysout class, this runtime option allows you to specify a form-name. See z/OS Language Environment Programming Reference for further information about the CEEDUMP runtime option.”
See z/OS Language Environment Debugging Guide and z/OS V2R1.0 Language Environment Programming Guide for 64-bit Virtual Addressing Mode for additional information about _CEE_DMPTARG.

**_CEE_ENVFILE**

Enables a list of environment variables to be set from a specified file. This environment variable only takes effect when it is set through the runtime option ENVAR on initialization of a parent program. When _CEE_ENVFILE is defined under these conditions, its value is taken as the name of the file to be used. For example, to read the ddname MYVARS, you would call your program with the ENVAR runtime option, as follows:

```
ENVAR("_CEE_ENVFILE=DD:MYVARS")
```

When you set the environment variables with a file in the UNIX file system, you need to use the absolute path to specify the file. For example, if the absolute path of the file is `/u/DPGRoss/ootest/tsthello/ENV`, you would call your program with the ENVAR runtime option as follows:

```
ENVAR("_CEE_ENVFILE=/u/DPGRoss/ootest/tsthello/ENV")
```

The specified file is opened as a variable length record file. For an MVS data set, the data set must be allocated with RECFM=V. RECFM=VBS must not be used because environment variables may not be contained in spanned records. RECFM=F is not suggested because RECFM=F enables padding with blanks, and the blanks are counted when calculating the size of the line. Each record consists of NAME=VALUE. For example, a file with the following two records:

```
_EDC_RRDS_HIDE_KEY=Y
World_Champions=New_York_Yankees
```

would set the environment variable _EDC_RRDS_HIDE_KEY to the value Y, and the environment variable World_Champions to the value New_York_Yankees.

**Notes:**

1. Using _CEE_ENVFILE to set environment variables through a file is not supported under CICS.
2. z/OS Language Environment searches for an equal sign to delimit the environment variable from its value. If an equal sign is not found, the environment variable is skipped and the rest of the text is treated as comments.
3. Each record of the file is processed independently from any other record in the file. Data within a record is used exactly as input with no substitution. A file containing:

```
FRED=WILMA
FRED=$FRED:BAMBAM
```

will result in the environment variable FRED being set to $FRED:BAMBAM, rather than to WILMA:BAMBAM as would be the case if the same statements were processed by a UNIX shell.

**_CEE_ENVFILE_COMMENT**

Defines the comment character to be checked for when subsequent records are read from the file. _CEE_ENVFILE_COMMENT is defined within the file specified by the _CEE_ENVFILE or _CEE_ENVFILE_S environment variable. The comment character used is the first character after the = and it must not be a space character, as determined by the isspace() macro.
In the following example, the comment character is defined as *.

```plaintext
_CEE_ENVFILE_COMMENT=*  
* This is a Comment  
NAME1=VALUE1
```

**Notes:**
1. Comments cannot be placed within a set of continuation lines.
2. If _CEE_ENVFILE_COMMENT is encountered when the file is read, it is only used to define the comment character; the keyword is not added to the environment.

---

**_CEE_ENVFILE_CONTINUATION_**

Defines the continuation character to be checked for when subsequent records are read from the file. _CEE_ENVFILE_CONTINUATION_ is defined within the file specified by the _CEE_ENVFILE_ or _CEE_ENVFILE_S_ environment variable. The continuation character used is the first character after the = and it must not be a space character, as determined by the `isspace()` macro.

When a continuation character is defined and a name=value sequence is found, where the last non-whitespace character matches the continuation character, the next line of the file is read and appended to value. If the last non-whitespace character of the updated value matches the continuation character, the next line of the file is read and appended to value. This continues until the last non-whitespace character does not match the continuation character and then the name and value pair are set into the environment.

In the following example, the continuation character is defined as `. With this in place, the STEPLIB keyword defined on the next line is defined to have a value that spans multiple lines. When queried by the application, the value of STEPLIB is CEE.SCEERUN2:CEE.SCEERUN:MY.LOADLIB.

```plaintext
_CEE_ENVFILE_CONTINUATION=\
STEPLIB=CEE.SCEERUN2:\
CEE.SCEERUN:\
MY.LOADLIB
```

**Notes:**
1. If _CEE_ENVFILE_CONTINUATION_ is encountered when the file is read, it is only used to define the continuation character; _CEE_ENVFILE_CONTINUATION_ is not added to the environment.
2. The name= portion of the name=value sequence cannot exceed one line.
3. The length of the value is limited only by the memory available to read, concatenate the lines, and set the variable into the environment.

---

**_CEE_ENVFILE_S_**

Enables a list of environment variables to be set from a specified file, stripping trailing white space from each NAME=VALUE line read. This environment variable only takes effect when it is set through the runtime option ENVAR on initialization of a parent program.

When _CEE_ENVFILE_S_ is defined under this condition, its value specifies the name of the file to be used. For example, to read the ddname MYVARS, you would call your program with the ENVAR runtime option as follows:

```plaintext
ENVAR("_CEE_ENVFILE_S=DD:MYVARS")
```
When you set the environment variables with a file in the UNIX file system, you need to use the absolute path to specify the file. For example, if the absolute path of the file is `/u/DPGROSS/ootest/tsthello/ENV`, you would call your program with the ENVAR runtime option as follows:

```c
ENVAR("_CEE_ENVFILE_S=/u/DPGROSS/ootest/tsthello/ENV")
```

For an MVS data set, the data set can be allocated with any record format except RECFM=VBS, because environment variables may not be contained in spanned records. Each record consists of NAME=VALUE. For example, a file with the following two records:

```
_EDC_RRDS_HIDE_KEY=Y
World_Champions=New_York_Yankees
```

would set the environment variable `_EDC_RRDS_HIDE_KEY` to the value `Y`, and the environment variable `World_Champions` to the value `New_York_Yankees`.

**Notes:**

1. Using `_CEE_ENVFILE_S` to set environment variables through a file is not supported under CICS.
2. z/OS Language Environment searches for an equal sign to delimit the environment variable from its value. If an equal sign is not found, the environment variable is skipped and the rest of the text is treated as comments.
3. Both environment variables `_CEE_ENVFILE` and `_CEE_ENVFILE_S` can be specified. `_CEE_ENVFILE_S` takes precedence, meaning it is processed second in sequence.
4. Each record of the file is processed independently from any other record in the file. Data within a record is used exactly as input with no substitution (other than trailing white space is ignored). A file containing:

```
FRED=WILMA
FRED=$FRED:BAMBAM
```

will result in the environment variable `FRED` being set to `$FRED:BAMBAM`, rather than to `WILMA:BAMBAM` as would be the case if the same statements were processed by a UNIX shell.

**_CEE_HEAP_MANAGER**

Specifies the name of the Vendor Heap Manager (VHM) DLL that will be used to manage the user heap. You set the environment variable as follows:

```c
_CEE_HEAP_MANAGER=dllname
```

This environment variable must be set using one of the following mechanisms:

- ENVAR runtime option
- Inside the file specified by the `_CEE_ENVFILE` or `_CEE_ENVFILE_S` environment variable.

Either of these mechanisms is before any user code gets control. This means prior to the HLL user exit, static constructors, and/or main getting control. Setting of this environment variable once the user code has begun execution will not activate the VHM, but the value of the environment variable will be updated.

See z/OS Language Environment Vendor Interfaces for more information on the Vendor Heap Manager support.
_CEE_REALLOC_CONTROL

_CEE_REALLOC_CONTROL has two parameters. The first parameter specifies the lower bound for the tolerance percentage to be applied. This variable reflects the number of bytes that will cause the realloc() control feature to be activated. For instance, if an application issues a malloc() to request storage and a subsequent realloc() to change the size of that storage allocation, this parameter determines whether the request will be increased - with the intent that subsequent reallocations will not require additional storage be obtained and data copied.

The second parameter specifies the percentage that the storage request will be increased if the request is greater than or equal to the lower bound specified in the first parameter.

The format of the environment variable is:

_CEE_REALLOC_CONTROL=bound,percentage

bound - a, aK, ak, in which a is an integer.

percentage - p, which is an integer between 0 and 100. The default value is 0, which means that this feature is not in use.

Attempting to reallocate storage to a new size of near 2GB while this environment variable is set may cause realloc() to report that a negative new size was provided as input.

Note: The following examples use storage sizes that are for illustration purposes only. The sizes are examples and do not reflect any storage rounding that might occur.

The following example shows this control feature being used within a loop and how an allocation of a new storage element can be eliminated:

_CEE_REALLOC_CONTROL=100,20

/* an example in C*/
char * buffer;
size_t buffsize;
Int i;
buffsize = 100;
buffer = malloc(buffsize);
for ( i = 0; i <= 2; ++i ) {
buffsize += 10;
buffer = realloc(buffer,buffsize);
}

for ( i = 0; i <= 2; ++i ) {
buffsize -= 10;
buffer = realloc(buffer,buffsize);
}

Because the realloc() request is greater than the lower bound, the first pass through the first loop results in a new buffer with the same contents as before but within a storage element of size 132 (110+(110*.20)) and buffsize=110. All the data in the first buffer (100 bytes) is copied to the second (new) buffer.

The second and third pass through the first loop issue the same realloc, but result in no action being taken because the new buffsize of 120 and then 130 allows the requested storage to remain within the current allocation of 132 bytes, even if both
requests are greater than the lower bound. Therefore, allocation of new storage elements and copies of data are eliminated.

Additionally, the first two paths through the second loop also result in no action because they result in a buffsize less than the current allocation and can also fit within the current allocation.

The last path through the second loop results in a new buffer of buffsize 100. Although this request is also less than the current allocation and fits in the current allocation, the assumption is that no tolerance ever occurred because the requested size plus the increase have resulted in a storage allocation less than the current allocation.

In other words, if realloc control feature is relevant (the requested storage allocation is greater than the lower bound), the rules are:

- If the (realloc) request is equal to the current allocation, use the same buffer location and size (do nothing).
- If the request is greater than the current allocation, get a new buffer of size (request + tolerance).
- If the request is lower than the current allocation and the current allocation is greater than (request + tolerance), assume tolerance never applied before and get a new buffer of size requested.
- If the request is lower than the current allocation and the current allocation is not greater than (request + tolerance), use the same buffer and size (do nothing)

_CEE_RUNOPTS

Used to specify invocation Language Environment runtime options for programs invoked using one of the exec family of functions. Mechanisms for setting the value of the _CEE_RUNOPTS environment variable include using the export command within the z/OS UNIX shell, or using the setenv() or putenv() functions within a C/C++ application. The runtime options set from the _CEE_RUNOPTS environment variable value that become active in the invoked program are known as invocation command runtime options.

Note: For this description, the exec family of functions includes the spawn family of functions.

The format of the environment variable is as follows, where value is a null-terminated character string of Language Environment runtime options.

_CEE_RUNOPTS=value

For example, you could specify the following to set the value of the environment variable within the z/OS UNIX shell.

export _CEE_RUNOPTS="stack(,,any,) termthdact(dump)"

The _CEE_RUNOPTS environment variable has a unique behavior. It can be unset, or modified, but will be re-created or added to across an exec to effect the propagation of invocation Language Environment runtime options. This behavior is designed specifically to allow runtime options such as TRACE to take effect for parts of an application which are not invoked directly by the user. Without this behavior, the external TRACE option could not be propagated to parts of an application that are executed using one of the exec family of functions.
At the time of the exec, any active invocation command runtime option settings, not already explicitly part of the _CEE_RUNOPTS environment variable, are added to its value. This new value for the _CEE_RUNOPTS environment variable is passed to the exec target to be used as invocation Language Environment runtime options for the invoked program. Thus, all invocation runtime options, those specified with the _CEE_RUNOPTS environment variable and those already active, are propagated across the exec.

When the _CEE_RUNOPTS environment variable is not defined at the time of the exec, but there are other active invocation command runtime options, it will be re-created with its value set to represent the active invocation command runtime option settings. This unique behavior, where the _CEE_RUNOPTS environment variable is added to, or re-created, across an exec, can cause unexpected results when the user attempts to unset (clear) the environment variable, or modify its value.

Figure 148 demonstrates this behavior. We enter the z/OS UNIX shell through OMVS, and a sub-shell is created using one of the exec family of functions. The propagation of the _CEE_RUNOPTS environment variable takes place across creation of the sub-shell.

```
/u/carbone>echo $_CEE_RUNOPTS
POSIX(ON) 1
/u/carbone>/bin/sh 2
/u/carbone>echo $_CEE_RUNOPTS
POSIX(ON) 3
/u/carbone>unset _CEE_RUNOPTS 4
/u/carbone>echo $_CEE_RUNOPTS
5
/u/carbone>env | grep _CEE_RUN
_CEE_RUNOPTS=POS(ON) 6
/u/carbone>echo $_CEE_RUNOPTS
6
/u/carbone>export _CEE_RUNOPTS="ABTERMENC(RETCODE)"
/u/carbone>echo $_CEE_RUNOPTS
7
ABTERMENC(RETCODE)
/u/carbone>env | grep _CEE_RUN
_CEE_RUNOPTS=ABTERMENC(RETCODE) POS(ON) 8
/u/carbone>/bin/sh 9
/u/carbone>echo $_CEE_RUNOPTS
ABTERMENC(RETCODE) POS(ON) 9
/u/carbone>unset _CEE_RUNOPTS 10
/u/carbone>echo $_CEE_RUNOPTS
11
/u/carbone>env | grep _CEE_RUN
_CEE_RUNOPTS=ABTERMENC(RETCODE) POS(ON) 12
/u/carbone>
```

**Figure 148. _CEE_RUNOPTS behaviour**

**Notes:**
1. The current value of the _CEE_RUNOPTS environment variable happens to be POSIX(ON).
2. Using /bin/sh to create a sub-shell will go through the process where the _CEE_RUNOPTS environment variable is added to, or re-created, across the exec.
3. Displaying the value of the _CEE_RUNOPTS environment variable using echo in the sub-shell shows that no other invocation command runtime options were in effect at the time of the exec, since the value of the environment variable is unchanged (there were no runtime options to add).
4. Using unset to clear the _CEE_RUNOPTS environment variable does remove it from the sub-shell environment, as shown with the echo command, but it does not change the fact that POSIX(ON) is the active invocation command runtime option in the sub-shell.

5. To see this, we use the env | grep _CEE_RUNOPTS command. The env is the target of an exec. We know that the _CEE_RUNOPTS environment variable is re-created across the exec from the active invocation command runtime options. And as you can see, the value shows as POS(ON). During re-creation, Language Environment uses the minimum abbreviations for the runtime options when re-creating or adding to the _CEE_RUNOPTS environment variable.

6. When the env returns, the _CEE_RUNOPTS environment variable is still unset in the sub-shell as seen using the echo command.

7. We now use export to set a different value for the _CEE_RUNOPTS environment variable in the sub-shell. We see the value using the echo command.

8. Using the env | grep _CEE_RUNOPTS command again, we see the behavior where the active invocation command runtime options are added to the current value of the _CEE_RUNOPTS environment variable.

9. The rest of the example creates a second sub-shell and shows that the _CEE_RUNOPTS environment variable in the sub-shell was added to across the exec of the sub-shell. And again, using unset does not change the active invocation command runtime options.

_EDC_ADD_ERRNO2

Controls whether or not errno2 is appended to the output of perror(), strerror(), and strerror_r(). The errno2 might be set by the z/OS XL C/C++ runtime library, z/OS UNIX callable services, or other callable services. The errno2 is intended for diagnostic display purposes only and it is not a programming interface.

The variable _EDC_ADD_ERRNO2 is not set by default. When the variable _EDC_ADD_ERRNO2 is not set, errno2 is added to perror() messages, but not to messages retrieved by using strerror() or strerror_r(). When _EDC_ADD_ERRNO2 is set to 1, errno2 is added to perror(), strerror(), and strerror_r() messages. For all other values of _EDC_ADD_ERRNO2, errno2 is not added. For example, for perror(), if errno was 121, the default behavior might produce the following message "EDC5121I Invalid argument. (errno2=0x0C0F8402)."

_EDC_ADD_ERRNO2 is set to zero with the command:

```
setenv("_EDC_ADD_ERRNO2","0",1);
```

It is suggested that applications run with _EDC_ADD_ERRNO2 not being set. This causes errno2 to be added only to perror() messages.

If an application is using strerror() or strerror_r() to retrieve messages associated with an error number, usually a saved errno value, it is suggested that errno2 also be saved by using __errno2() at the time when errno is saved. The application can then process the retrieved message and saved errno2 value as a pair.

**Note:** Not all functions set errno2 when errno is set. In the cases where errno2 is not set, the errno2 might be a residual value. You might use the __err2ad() function to clear errno2 to reduce the possibility of a residual value being returned.
_EDC_ANSI_OPEN_DEFAULT

Affects the characteristics of MVS text files opened with the default attributes. Issuing the following command causes text files opened with the default characteristics to be opened with a record format of FIXED and a logical record length of 254 in accordance with the ANSI standard for C.

```
setenv("_EDC_ANSI_OPEN_DEFAULT","Y",1);
```

When this environment variable is not specified and a text file is created without its record format or LRECL defined, then the default is a variable record format.

_EDC_AUTOCVT_BINARY

If automatic file conversion is enabled (_BPXK_AUTOCVT=ON and running with FILETAG(AUTOCVT) runtime option), this environment variable activates or deactivates automatic conversion of untagged UNIX file system files opened in binary mode and not opened for record I/O.

The value of this environment variable is checked every time a UNIX file system file is opened. If automatic file conversion is enabled and _EDC_AUTOCVT_BINARY=YES, an untagged file opened in binary mode will trigger the file to be automatically converted from the program CCSID to the EBCDIC CCSID as specified by the _BPXK_CCSIDS environment variable. If _BPXK_CCSIDS is not set, a default CCSID pair is used. See _BPXK_CCSIDS environment variable for additional details.

_EDC_AUTOCVT_BINARY can be set to the following values to set the conversion state for binary files.

**NO (default)**

If automatic file conversion is enabled, an untagged file opened in binary mode will not trigger the file to be automatically converted from the program CCSID to the EBCDIC CCSID as specified by the _BPXK_CCSIDS environment variable. If _BPXK_CCSIDS is not set, a default CCSID pair is used. See _BPXK_CCSIDS environment variable for additional details. An untagged file opened in text mode will not be affected.

**YES**

If automatic file conversion is enabled, an untagged file opened in binary mode and not opened for record I/O will trigger the file to be automatically converted from the program CCSID to the EBCDIC CCSID as specified by the _BPXK_CCSIDS environment variable. If _BPXK_CCSIDS is not set, a default CCSID pair is used. See _BPXK_CCSIDS environment variable for additional details.

**Note:** If this environment variable is not set, the default behavior is chosen, which is the same as _EDC_AUTOCVT_BINARY=NO. Because this environment variable is checked on every file open, an application can pick up the changes to this environment variable by closing and then re-opening the file at execution time. The application itself does not need to be restarted.

_EDC_BYTE_SEEK

Indicates to z/OS XL C/C++ that, for all binary files, ftell() should return relative byte offsets, and fseek() should use relative byte offsets as input. The default behavior is for only binary files with a fixed record format to support relative byte offsets. _EDC_BYTE_SEEK is set with the command:

```
setenv("_EDC_BYTE_SEEK","Y",1);
```
**_EDC_CLEAR_SCREEN_**

Applies to output text terminal files. _EDC_CLEAR_SCREEN_ is set with the command:

```
setenv("_EDC_CLEAR_SCREEN","Y",1);
```

When _EDC_CLEAR_SCREEN_ is set, writing a \f (form feed) character to a text terminal sends all preceding unwritten data in the terminal buffer to the screen, and then clears the screen.

When _EDC_CLEAR_SCREEN_ in not set, writing a \f (form feed) character to a text terminal results in the character being treated as a non-control character. The character is written to the terminal buffer as \f.

**_EDC_COMPAT_**

Indicates to z/OS XL C/C++ that it should use old functional behavior for various items in code ported from old releases of C/370. These functional items are specified by the value of the environment variable. _EDC_COMPAT_ is set with the following command, where x is an integer:

```
setenv("_EDC_COMPAT","x",1);
```

z/OS XL C/C++ converts the string "x" into its decimal integer equivalent, and treats this value as a bit mask to determine which functions to use in compatibility mode. The following table interprets the least significant bit as bit zero.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Function</th>
<th>Affected</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>ungetc()</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>ftell()</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>fclose()</td>
<td></td>
</tr>
<tr>
<td>3 through 31</td>
<td>Unused</td>
<td></td>
</tr>
</tbody>
</table>

For this release, calls to fseek() with an offset of SEEK_CUR, fgetpos(), and fflush() take into account characters pushed back with the ungetc() library function. You must set the _EDC_COMPAT_ environment variable for ungetc() if you want these functions to ignore ungetc() characters as they did in old C/370 code.

For ftell(), z/OS XL C/C++ uses an encoding scheme that varies according to the attributes of the underlying data set. You must set the _EDC_COMPAT_ environment variable for ftell() if you want to use encoded ftell() values generated in old C/370 code.

You can set _EDC_COMPAT_ to indicate that fclose() should not unallocate the SYSOUT=** data set when it is closing "*" data sets created under batch. This is to ensure that such data sets can be concatenated with the Job Log, if their attributes are compatible.

Here are some examples of how you can set _EDC_COMPAT_:

- `setenv("_EDC_COMPAT","1",1)`; invokes old ungetc() behavior.
- `setenv("_EDC_COMPAT","2",1)`; invokes old ftell() behavior.
- `setenv("_EDC_COMPAT","3",1)`; invokes both old ungetc() behavior and old ftell() behavior.
- `setenv("_EDC_COMPAT","4",1)`; invokes old behavior for spool data sets created by opening "*" in MVS or IMS batch.
_EDC_CONTEXT_GUARD

Allows the user to control the method used to handle the guard page for AMODE 64 user context stacks.

When the value of _EDC_CONTEXT_GUARD is set to ACTIVE, the guard page for a user context stack is guarded each time the context is given control and unguarded each time the context gives up control. This is the default behavior when the value of _EDC_CONTEXT_GUARD is not set.

When the value of _EDC_CONTEXT_GUARD is set to INUSE, the guard page for a user context stack is guarded the first time the context is given control and unguarded when the context has run to completion, that is, when the function specified on the call to makecontext() returns or exits. This method of handling the guard page might provide better performance but comes with the following restrictions:

- The storage for user context stacks must be allocated from the heap.
- The storage for a user context stack cannot be reused or freed until the context runs to completion.

The _EDC_CONTEXT_GUARD environment variable can be set with the function:

```c
setenv("_EDC_CONTEXT_GUARD","INUSE", 1);
```

**Note:** The setting of this environment variable is only effective if it is done before the first call to makecontext().

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACTIVE</td>
<td>The user context stack is only guarded when the context is active. This is the default value.</td>
</tr>
<tr>
<td>INUSE</td>
<td>The user context stack is guarded the entire time that the context is in use.</td>
</tr>
</tbody>
</table>

_EDC_C99_NAN

Sets the binary floating-point representation of infinite value and Not a Number for the printf family of functions as follows:

- When the value of _EDC_C99_NAN is set to YES, then the printf family of functions use C99 compliant behavior. C99 defines the representation of infinity and Not a Number as INF, and NAN (for E, F, G, and A conversion specifiers) or inf and nan (for e, f, g, and a conversion specifiers). In C99 compliant behavior, the case of the string will be the same as the case of the conversion specifier that was used.

- When the value of _EDC_C99_NAN is not set, or set to a value other than YES, then the representation of infinity and Not a Number is INF and NaN.

The _EDC_C99_NAN environment variable can be set with the function:

```c
setenv("_EDC_C99_NAN","YES", 1);
```

_EDC_DLL_DIAG

Indicates if additional DLL diagnostic information should be generated upon failure for the following DLL functions: dllload(), dlopen(), dllqueryfn(), dllqueryvar(), dsym(), dl1free(), and dlclose(). _EDC_DLL_DIAG has no effect on implicit DLLs. If _EDC_DLL_DIAG is not set by the user, it will default to QUIET.
_EDC_DLL_DIAG can be set with the following command, where x is a string.
setenv("_EDC_DLL_DIAG","x",1);

Acceptable values for x are as follows:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MSG</td>
<td>Issue DLL error messages to the Language Environment message file.</td>
</tr>
<tr>
<td>TRACE</td>
<td>Issue all DLL error messages to the Language Environment message file and call the ctrace() function to produce a traceback for each error.</td>
</tr>
<tr>
<td>SIGNAL</td>
<td>Issue all DLL error messages to the Language Environment message file, call the ctrace() function to produce a traceback for each error, and signal a condition for each error's feedback code.</td>
</tr>
<tr>
<td>QUIET</td>
<td>Turn off all _EDC_DLL_DIAG error diagnostics; this is the default setting.</td>
</tr>
</tbody>
</table>

The _EDC_DLL_DIAG values must be specified in capital letters in order to be recognized. See z/OS XL C/C++ Runtime Library Reference for details on the level of diagnostic information provided by ctrace().

There is currently no way to intercept a signaled DLL condition in AMODE 64; therefore, termination is bound to happen if SIGNAL is in effect.

The following list shows examples of how to use _EDC_DLL_DIAG.

- Issue a DLL error message for DLL errors.
  setenv("_EDC_DLL_DIAG","MSG",1);
- Issue a DLL error message and call the ctrace() function for DLL errors.
  setenv("_EDC_DLL_DIAG","TRACE",1);
- Issue a DLL error message, call the ctrace() function, and signal a condition for DLL errors.
  setenv("_EDC_DLL_DIAG","SIGNAL",1);
- Turn off _EDC_DLL_DIAG error diagnostics.
  setenv("_EDC_DLL_DIAG","QUIET",1);

_EDC_EOVERFLOW

Sets the behavior of the ftell(), fseek(), fstat(), lstat(), stat(), and mmap() functions. By default these functions will not check for the EOVERFLOW error condition. Setting _EDC_EOVERFLOW to YES enables testing for this condition, and, if overflow is detected, setting errno to EOVERFLOW and returning an error. The _EDC_EOVERFLOW environment variable can be set with the function:
setenv("_EDC_EOVERFLOW","YES",1);

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>YES</td>
<td>Check for EOVERFLOW error conditions.</td>
</tr>
<tr>
<td>&lt;other&gt;</td>
<td>Ignore setting of EOVERFLOW; this is the default. Equivalent to unsetting the environment variable.</td>
</tr>
</tbody>
</table>
_EDC_ERRNO_DIAG

Indicates if additional diagnostic information should be generated, when the perror() or strerror() functions are called to produce an error message. This environment variable also controls how much additional information is produced. _EDC_ERRNO_DIAG is set with the following command, where x is an integer and y is a list of integer errno values, for which additional diagnostic information is desired.

```
setenv("_EDC_ERRNO_DIAG","x,y",1);
```

The list of errno values must be separated by commas. If the y value is omitted, then additional diagnostic information is generated for all errno values. If a non-numeric errno value is found in y, it is treated as 0. Acceptable values for x are as follows:

- **0** No additional diagnostic information is generated (This is the default if _EDC_ERRNO_DIAG is not set).
- **1** The ctrace() function is called to generate additional diagnostic information.
- **2** The csnap() function is called to generate additional diagnostic information.
- **3** The cdump() function is called to generate additional diagnostic information.

See z/OS XL C/C++ Runtime Library Reference for details on the level of diagnostic information provided by the above functions.

The following list shows examples of how to use this environment variable.

- No additional diagnostic information is produced.
  ```
  setenv("_EDC_ERRNO_DIAG","0",1);
  ```
- The ctrace() function is called for any errno when perror() or strerror() are called.
  ```
  setenv("_EDC_ERRNO_DIAG","1",1);
  ```
- The csnap() function is called only when errno equals 121 when perror() or strerror() are called.
  ```
  setenv("_EDC_ERRNO_DIAG","2,121",1);
  ```
- The cdump() function is called only when errno equals either 121 or 129 when perror() or strerror() are called.
  ```
  setenv("_EDC_ERRNO_DIAG","3,121,129",1);
  ```

_EDC_FLUSH_STDOUT_PIPE

Instructs the C Runtime Library to flush the stdout stream when the stdin stream is being read from. Both stdin and stdout must be pipes. _EDC_FLUSH_STDOUT_PIPE is set with the command:

```
setenv("_EDC_FLUSH_STDOUT_PIPE","YES",1);
```

The purpose of this environment variable is to better facilitate communication between two processes that use pipes. The child process is using stdin for the read end of one pipe and stdout for the write end of a different pipe. The parent process has the opposite ends of the pipes.

Note the following usage notes and examples:
The child process wants to send a prompt to the parent process and then read the response. The parent process must see the prompt, capture a response, and then send the response back to the child.

If the child process sends the prompt without a trailing newline or without calling `fflush`, the prompt is never placed into the pipe for the parent process to read. The child process then tries to read the response from `stdin`. The application hangs, which means that the parent process cannot read the prompt that it needs to respond to and the child process cannot read the response from the parent process.

With the environment variable set to YES, the read from `stdin` will flush the `stdout` buffer. This allows the parent process to see the prompt, respond, and then send the response back to the child process who is waiting on the read. After the data comes back from the parent process, the child process reads the response and continues.

**Note:** The parent process must do a read by using `read()` from the pipe so that it can receive whatever data might be there without having to wait for a specific number of bytes or a newline character. Functions like `fread()` and `fgets()` will hang unless the child process wrote enough bytes or the newline character to `stdout`.

**_EDC_FLUSH_STDOUT_SOCKET_**

Instructs the C Runtime Library to flush the `stdout` stream when the `stdin` stream is being read from. Both `stdin` and `stdout` must be sockets.

`_EDC_FLUSH_STDOUT_SOCKET` is set with the command:

```
setenv("_EDC_FLUSH_STDOUT_SOCKET","YES",1);
```

The purpose of this environment variable is to better facilitate communication between two processes that use sockets. The child process is using `stdin` for the read end of one socket and `stdout` for the write end of a different socket. The parent process has the opposite ends of the sockets.

Note the following usage notes and examples:

• The child process wants to send a prompt to the parent process and then read the response. The parent process must see the prompt, capture a response, and then send the response back to the child process.

• If the child sends the prompt without a trailing newline or without calling `fflush`, the prompt is never placed into the socket for the parent process to read. The child then tries to read the response from `stdin`. The application hangs, which means that the parent process cannot read the prompt that it needs to respond to and the child process cannot read the response from the parent.

• With the environment variable set to YES, the read from `stdin` will flush the `stdout` buffer. This allows the parent to see the prompt, respond, then send the response back to the child who is waiting on the read. After the data comes back from the parent, the child reads the response and continues.

**Note:** The parent process must do a read by using `read()` from the socket so that it can receive whatever data might be there without having to wait for a specific number of bytes or a newline character. Functions like `fread()` and `fgets()` will hang unless the child wrote enough bytes or the newline character to `stdout`. 
_EDC_GLOBAL_STREAMS

Used during initialization of the first C main in the environment to allow the C standard streams stdin, stdout, and stderr to have global behavior. The environment variable settings and standard streams using the global behavior, are as follows:

Setting Standard streams using global behavior
0 none
1 stderr
2 stdout
3 stderr,stdout
4 stdin
5 stderr,stdin
6 stdout,stdin
7 stderr,stdout,stdin

Note: The first C main would include any Pre-Init Compatibility Interface initialization.

You can use one of the following methods to set the environment variable _EDC_GLOBAL_STREAMS:

- CEEBXITA assembler user exit
  You can modify the sample CSECT and assemble and link with the application. The runtime options specified in the CEEBXITA assembler user exit override all other sources of runtime options except those that are specified as NONOVR. These options are honored only during initialization of the first enclave.
- ENVAR(_EDC_GLOBAL_STREAMS=<setting>)
  You can call your program with the ENVAR runtime option. This overrides the application defaults specified using CEEUOPT or the #pragma runopts directive.
- #pragma runopts(ENVAR(_EDC_GLOBAL_STREAMS=<setting>))
  Use the #pragma runopts directive in your application source code.
- CEEUOPT application defaults
  Modify the sample CSECT and assemble and link with the application. This overrides corresponding overrideable system-level or region-level default options.

Notes:
1. _EDC_GLOBAL_STREAMS is not supported in AMODE 64.
2. Attempts to set this environment variable in the file specified by the _CEE_ENVFILE or _CEE_ENVFILE_S environment variable are ignored. The standard streams are initialized before that file is read.
3. You cannot use the CEEBINT user exit to set this environment variable. The CEEBINT user exit gets control after the standard streams have been initialized.

_EDC_IEEEV1_COMPATIBILITY_ENV

In 1999, the C/C++ Runtime Library provided IEEE754 floating-point arithmetic support in support of IBM’s Java™ group. The Java language had a bit-wise requirement for its math library, meaning that all platforms needed to produce the same results as Sun Microsystems’ fdlibm (Freely Distributed LIBM) library. Therefore, Sun Microsystems’ fdlibm code was ported to the C/C++ Runtime Library to provide IEEE754 floating-point arithmetic support. Subsequent to the C/C++ Runtime Library’s 1999 release of IEEE754 floating-point math support,
IBM’s Java group provided their own support of IEEE754 floating point arithmetic and no longer use the C/C++ Runtime Library for this support.

Beginning in z/OS V1R9, a subset of the original fdlibm functions are being replaced by new versions that are designed to provide improved performance and accuracy. The new versions of these functions are replaced at the existing entry points. However, as a migration aid, IBM has provided new entry points for the original fdlibm versions. Applications that take no action will automatically use the updated functions. There are two methods for accessing the original functions.

The first method is through an environment variable, described here, that can be used by applications that do one of the following:

- Do not include <math.h>.
- Include <math.h> and define the _FP_MODE_VARIABLE feature test macro.

Either of the above will cause the application to be running in what is called "variable" mode with respect to floating-point math functions called within the compile unit.

The second method is through the _IEEEV1_COMPATIBILITY feature test macro and is used for applications that include <math.h> and do not define the _FP_MODE_VARIABLE feature test macro. See z/OS XL C/C++ Runtime Library Reference for more details.

If the application conforms to the rules of the first method, then this environment variable can be used to access the original fdlibm versions of the functions shown in Table 88.

<table>
<thead>
<tr>
<th>acos()</th>
<th>acosh()</th>
<th>asin()</th>
<th>asinh()</th>
<th>atan()</th>
<th>atanh()</th>
<th>atan2()</th>
</tr>
</thead>
<tbody>
<tr>
<td>cbrt()</td>
<td>cos()</td>
<td>cosh()</td>
<td>erf()</td>
<td>erfc()</td>
<td>exp()</td>
<td>expm1()</td>
</tr>
<tr>
<td>gamma()</td>
<td>hypot()</td>
<td>lgamma()</td>
<td>log()</td>
<td>log1p()</td>
<td>log10()</td>
<td>pow()</td>
</tr>
<tr>
<td>rint()</td>
<td>sin()</td>
<td>sinh()</td>
<td>tan()</td>
<td>tanh()</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

This environment variable will only take effect if the application is running in "variable" mode. The following list shows the acceptable values of the environment variable and the behavior for each value:

- **ON**  Original versions of fdlibm functions are used.
- **other values**  The new versions of the functions are used. This is the default.

If the application has used __fp_setmode() to switch over to hexadecimal floating-point mode, the hexadecimal versions of the functions will be called no matter the setting of the environment variable.

---

**_EDC_IO_ABEND_**

When an abend condition arises during OS I/O processing, the zOS XL C/C++ runtime library ignores the condition, if possible. When the abend condition cannot be ignored, the abend is issued. This environment variable controls if the runtime library should attempt to recover from an abend issued during OS I/O processing. The acceptable values for the environment variable are as follows:

- **ABEND**  Specifies that the runtime library is to ignore abend conditions that can be...
ignored and that the runtime library should not attempt to recover from an
abend issued during OS I/O processing. When an abend is issued during OS
I/O processing, Language Environment condition handling semantics take
effect. The only methods available for the application to attempt to recover are
to write a Language Environment condition handler or a SIGABND signal
handler. If this environment value is not set or if a value other than ABEND or
RECOVER is specified, this is the default behavior.

**RECOVER**

Specifies that the runtime library is to ignore abend conditions that can be
ignored and also that the runtime library should attempt to recover from an
abend issued during OS I/O processing. If the library can recover, then control
will be returned to the application as a failing return value, with errno set to
92 and diagnostic information in the __amrc structure. If the library cannot
recover, Language Environment condition handling semantics take effect.

**Notes:**

1. The value is not case sensitive.
2. When a stream is opened, the current setting of the environment variable
defines the behavior for the life of the open stream, unless overridden by the
abend keyword specified in the modestring on the fopen() or freopen() call.
3. Changes to the environment variable do not affect existing open streams.
4. This environment variable has no effect for SPC applications.

For more information about error handling during I/O operations, refer to
Chapter 10, “Performing OS I/O operations,” on page 83.

The following example show one method to set this environment variable.

```c
setenv("_EDC_IO_ABEND", "RECOVER", 1);
```

**_EDC_IO_TRACE**

Indicates which files to perform file I/O tracing on, the level of detail to provide
for file I/O tracing, and the trace buffer size to use for each file. The
_EDC_IO_TRACE format is:

```
_EDC_IO_TRACE=(Filter,Detail,Buffer Size)
```

The three values (Filter, Detail, Buffer Size) must be surrounded by parenthesis and
delimited by commas. Values that are left blank use the default setting for that
value.

**Value**  **Description**

Filter  Indicates which files to trace.

```
//DD:filter
  Trace will include the DD names matching the specified filter string.

//filter
  Trace will include the MVS data sets matching the specified filter
  string. Member names of partitioned data sets cannot be matched
  without the use of a wildcard.

filter
  Trace will include the Unix files matching the specified filter string.

//DD:*
  Trace will include all DD names.
```
/*
 * Trace will include all MVS data sets. This is the default setting.
 */

/* Trace will include all Unix files. */

* Trace will include all MVS data sets and Unix files.

**Detail**
Indicates the level of detail provided by the trace.

0  No tracing will be performed. This is the default setting.

1  First level tracing will be performed. The trace includes the following information:
   • The file being traced.
   • The trace detail level and buffer size.
   • Details describing how the file was opened (the function called and parameters passed).
   • Formatted file data returned from fldata().
   • The file pointer address.
   • The DD name, if applicable.
   • The function flow details for entry to externally documented file I/O functions.

2  Second level tracing will be performed. The trace includes everything that the first level tracing includes, except that the function flow details will be for entry to externally documented and internal slot, exit, OS, and open file I/O functions.

**Buffer Size**
Indicates the buffer size to use for each file's function flow details.

**sizeK**
Specifies the size of each file's trace buffer, where size is a number specified in kilobytes. The default buffer size is 16KB.

**sizeM**
Specifies the size of each file's trace buffer, where size is a number specified in megabytes.

**Notes:**
1. The wildcard character (*) can be used alone or as a part of a filter. If it is used as a part of a filter, it must be located at the end of the filter string.
2. The Unix file filter must either be a fully qualified name or a file name with no slashes.
3. If the trace buffer size is used up, the trace buffer will wrap, overwriting function flow details only.
4. The usage of setenv() with _EDC_IO_TRACE only has an effect on future files that are opened.

The following examples show different ways you can use this environment variable.

- The following examples demonstrate two different ways to trace the default of all MVS data sets, using level 1 tracing and the default trace table size:
  export _EDC_IO_TRACE=(,1,)
  setenv("_EDC_IO_TRACE",",(1),1");
- The following examples demonstrate two different ways to trace the UNIX file named posix.data, using level 1 tracing and the default trace table size:
The following examples demonstrate two different ways to trace all MVS data sets with names that begin with POSIX.DATA, using level 1 tracing and the default trace table size:

- export _EDC_IO_TRACE=(//POSIX.DATA*,1,)
- setenv("_EDC_IO_TRACE","(//POSIX.DATA*,1)",1);

- The following examples demonstrate two different ways to trace all MVS data sets with names that begin with POSIX.DATA, using level 1 tracing and size 24K trace tables:
- export _EDC_IO_TRACE=(//POSIX.DATA*,1,24K)
- setenv("_EDC_IO_TRACE","(//POSIX.DATA*,1,24K)",1);

_EDC_OPEN_CONCAT

Enables users to control if the C library can recognize that a data set is concatenated or not on fopen().

By default, a concatenated data set can only be recognized when it is opened by DDNAME, but it cannot be recognized when it is opened by the data set name. The acceptable value for the _EDC_OPEN_CONCAT environment variable is:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>The C library is able to recognize that the data set is concatenated or not when it is opened by the data set name. With this setting, repositioning operations upon a GDG data set opened by its base name will be based on the beginning of the GDG base.</td>
</tr>
</tbody>
</table>

The _EDC_OPEN_CONCAT environment variable can be set with the following function:

```c
setenv("_EDC_OPEN_CONCAT","1",1);
```

_EDC_POPEN

Sets the behavior of the popen() function. When the value of _EDC_POPEN is set to FORK, popen() uses fork() to create the child process. When the value of _EDC_POPEN is set to SPAWN, popen() uses spawn() to create the child process. If the value of _EDC_POPEN is not set, the default behavior is for popen() to use fork() to create the child process.

The _EDC_POPEN environment variable can be set with the function

```c
setenv("_EDC_POPEN","SPAWN",1);
```

_EDC_PTHREAD_BACKOUT

Determines the Language Environment thread abnormal termination behavior. When the value of _EDC_PTHREAD_BACKOUT is set to YES, Language Environment requests backout processing from the Resource Recovery Services component for in-flight units of recovery. The request is made only when an abend or program check is the reason for termination and Resource Recovery Services are active in the environment.

Requests for backout will not occur for any other value of _EDC_PTHREAD_BACKOUT. The default behavior is equivalent to setting _EDC_PTHREAD_BACKOUT = NO.
**_EDC_PTHREAD_YIELD_**

Used to control when pthread_yield() and sched_yield() will allow a thread to give up control of a processor so that another thread may have the opportunity to run. Possible values for _EDC_PTHREAD_YIELD:

- **0**  
  Control of the processor is released immediately.

- **-1**  
  Use an internal timing algorithm to determine if the processor should be released. This is the default.

- **-2**  
  Take the machine speed into account when determining if the processor should be released.

**other negative values**

Invalid. The default (-1) will be used.

**Notes:**

1. _EDC_PTHREAD_YIELD_ may be changed by setenv() while the application is running. All threads will use the new value.
2. The use of _EDC_PTHREAD_YIELD=-2 is suggested.

Examples of setting _EDC_PTHREAD_YIELD:

- export _EDC_PTHREAD_YIELD=-1
- set the ENVAR("_EDC_PTHREAD_YIELD=-2") runtime option

**_EDC_PTHREAD_YIELD_MAX_**

This environment variable allows a user program to define the max yield (wait) time for a particular thread. It is used to configure the speed at which the pthread_yield() and sched_yield() functions release a processor to enable another thread to run. In some cases, such as in highly-threaded applications, improved performance may result by using this environment variable to reduce the default max wait time.

**Value**  
**Description**

- **positive value**  
  An integer value to set the maximum yield time allowable for a pthread to wait. This value represents microseconds (1/1000 of a millisecond).

  **Note:** Values above 32000 (which is the current max default) and values less than or equal to zero will be ignored.

Examples of setting _EDC_PTHREAD_YIELD_MAX:

- This example results in wait times starting at 10 milliseconds, doubling on every successive wait (as it always has) up to a maximum of 20 milliseconds for every wait after that.
  
  ENVAR("_EDC_PTHREAD_YIELD_MAX=20000")  
  (and _EDC_PTHREAD_YIELD=-1)

- This example results in wait times starting at an interval determined by the hardware processor speed, and doubling at every successive wait for a maximum wait of 1000 microseconds.
  
  ENVAR("_EDC_PTHREAD_YIELD_MAX=1000")  
  (and _EDC_PTHREAD_YIELD=-2)

- This example will result in wait times starting at 1 microsecond, doubling on every successive wait up to a maximum of 1 millisecond.
  
  ENVAR("_EDC_PTHREAD_YIELD_MAX=1000")  
  (and _EDC_PTHREAD_YIELD=4096)
Note: A positive integer specified in _EDC_PTHREAD_YIELD determines the initial Time Unit a thread will wait for; in this example, 4096 is equivalent to 1 microsecond.

- This example results in wait times that start at 10 milliseconds and remain at that wait time for every successive wait, because the starting yield time is much longer than the intended maximum wait time.

ENVAR("_EDC_PTHREAD_YIELD_MAX=10")
(and _EDC_PTHREAD_YIELD=-1)

_EDC_PUTENV_COPY

Sets the behavior of the putenv() function. When the value of _EDC_PUTENV_COPY is set to YES, the putenv() string is copied into storage owned by Language Environment. When the value of _EDC_PUTENV_COPY is not set, or set to a value other than YES, then the putenv() string is placed directly into the environment, so altering the string will change the environment.

The _EDC_PUTENV_COPY environment variable can be set with the function

setenv("_EDC_PUTENV_COPY","YES", 1);

Notes:
1. Changes to z/OS specific environment variables beginning with _BPXK_, _CEE_ or _EDC_ may not be processed if the environment variable is updated directly rather than by using setenv() or putenv(). Results are unpredictable if these type of environment variables are updated directly.
2. For ASCII applications, the users string will be placed into the environment. However, updates should only be made with setenv() or putenv(). Results are unpredictable if the environment variable is updated directly.
3. If the user manually changes the environment, storage associated with the original environment may never be freed.
4. The __putenv_la() function will always make a copy of the user string and perform as though _EDC_PUTENV_COPY=YES were specified.
5. _EDC_PUTENV_COPY may be updated during the life of the application by setenv(), putenv() or clearenv(). This will affect the behavior of any subsequent call to putenv(), however it will not change the state of existing environment variables. putenv() may be used to update _EDC_PUTENV_COPY. The behavior requested will not take effect until the next putenv() call.

_EDC_RRDS_HIDE_KEY

Applies to VSAM RRDS files opened in record mode. When this environment variable is set, you can call fread() with a pointer to a character string, and the Relative Record Number is not appended to the beginning of the record. The _EDC_RRDS_HIDE_KEY environment variable is set with the command

setenv("_EDC_RRDS_HIDE_KEY","Y", 1);

By default, when you open a VSAM record in record mode, the fread() function is called with the RRDS record structure, and the record is preceded by the Relative Record Number.

_EDC_STOR_INCREMENT

Sets the size of increments to the internal library storage subpool acquired above the 16M line. By default, when the storage subpool is filled, its size is incremented by 8K. When _EDC_STOR_INCREMENT is set, its value string is translated to its decimal integer equivalent. This integer is then the new setting of the subpool.
storage increment size. The setting of this environment variable is only effective if it is done before the first I/O in the enclave.

The _EDC_STOR_INCREMENT value must be greater than zero, and must be a multiple of 4K. If the value is less than zero, the default setting of 8K is used. If the value is not a multiple of 4K, then it is rounded up to the next 4K interval. If _EDC_STOR_INCREMENT is set to an invalid value that must be modified internally to be divisible by 4K, this modification is not reflected in the character string that appears in the environment variable table.

Consider the case where `setenv()` is called as follows:
```
setenv("_EDC_STOR_INCREMENT","9000",1);
```
Internally, the storage subpool increment value is set to 12288 (that is, 12K). However, the following subsequent call returns "9000", as set by the call to `setenv()`.
```
getenv("_EDC_STOR_INCREMENT");
```

Note: _EDC_STOR_INCREMENT is not supported in AMODE 64. In AMODE 64 this environment variable is replaced by the IOHEAP64 runtime option.

_EDC_STOR_INCREMENT_B

Sets the increment size of an internal library storage subpool acquired below the 16M line. By default, when the below the line storage subpool is filled, its size is incremented by 4K. When _EDC_STOR_INCREMENT_B is set, its value string is translated to the decimal equivalent. These integers are then used as the new settings of the below subpool storage increment sizes. The setting of this environment variable is only effective if it is done before the first I/O in the enclave.

Consider the case where `setenv()` is called from CEEBINT (with the CEEBINT user exit linked to the application) as follows:
```
setenv("_EDC_STOR_INCREMENT_B","1000",1);
```
Internally, the storage subpool acquired from 24-bit storage will be 4096 (or 4K). However, the following subsequent call returns "1000", as set by the call to `setenv()`.
```
getenv("_EDC_STOR_INCREMENT_B");
```

Note: _EDC_STOR_INCREMENT_B is not supported in AMODE 64. In AMODE 64, this environment variable is replaced by the IOHEAP64 runtime option.

_EDC_STORE_INITIAL

Sets the initial size of the internal library storage subpool acquired above the line. The default subpool storage size is 12K. When _EDC_STORE_INITIAL is set, its value string is translated to its decimal integer equivalent. This integer is then the new setting of the subpool storage increment size. The setting of this environment variable is only effective if it is done before the first I/O in the enclave.

The _EDC_STORE_INITIAL value must be greater than zero, and must be a multiple of 4K. If the value is less than zero, the default setting of 12K is used. If the value is not a multiple of 4K, then it is rounded up to the next 4K interval. If _EDC_STORE_INITIAL is set to an invalid value that must be modified internally to be divisible by 4K, this modification is not reflected in the character string that appears in the environment variable table.
Consider the case where \texttt{setenv()} is called from \texttt{CEEBIN}T as follows, and the \texttt{CEEBIN}T user exit linked to the application:

\begin{verbatim}
    setenv("_EDC_STORE_INITIAL","16000",1);
\end{verbatim}

Internally, the storage subpool is initialized to 16384 (that is, 16K). However, the subsequent call, shown in the following example, returns "16000", as set by the \texttt{setenv()} call:

\begin{verbatim}
    getenv("_EDC_STORE_INITIAL");
\end{verbatim}

\textbf{Note:} \texttt{_EDC_STORE_INITIAL} is not supported in AMODE 64. In AMODE 64, this environment variable is replaced by the IOHEAP64 runtime option.

\texttt{_EDC_STOR_INITIAL_B}

Sets the initial size of an internal library storage subpool acquired below the 16M line. The default below the line subpool storage size is 4K. When \texttt{_EDC_STOR_INITIAL_B} is set, its value string is translated to the decimal integer equivalent. This integer is then used as the new setting of the above the line subpool storage initial size. The setting of this environment variable is only effective if it is done before the first I/O in the enclave.

Consider the case where \texttt{setenv()} is called from \texttt{CEEBIN}T as follows, and with the \texttt{CEEBIN}T user exit linked to the application.

\begin{verbatim}
    setenv("_EDC_STOR_INITIAL_B","1000",1);
\end{verbatim}

Internally, the storage subpool acquired from 24-bit storage will be set to 4096 (that is, 4K). However, the subsequent call \texttt{getenv("_EDC_STOR_INITIAL_B")}; returns "1000", as set by the \texttt{setenv()} call.

\textbf{Note:} \texttt{_EDC_STOR_INITIAL_B} is not supported in AMODE 64. In AMODE 64, this environment variable is replaced by the IOHEAP64 runtime option.

\texttt{_EDC_STRPTM_STD}

Indicates changes to \texttt{strptime()} that are provided for UNIX standard compliance. It would affect the behavior of the following conversion specifier of the \texttt{strptime()} function:

\texttt{%Y} When the value of \texttt{_EDC_STRPTM_STD} is set to 1, at most 4 digits will be consumed. When the value of \texttt{_EDC_STRPTM_STD} is set to other values or unset, more than 4 digits might be consumed, and if the generated value is greater than 9999, this function fails.

\texttt{_EDC_SUSV3}

Indicates behavioral changes that are provided for SUSV3 compliance in an error path. The affected interfaces are typically setting \texttt{errno} to values that were not used before and, in some cases, returning failure for conditions that had not been tested before SUSV3. By default the affected interfaces will not check for these conditions. When the value of \texttt{_EDC_SUSV3} is set to 1, the SUSV3 behavior is enabled. When the value of \texttt{_EDC_SUSV3} is set to 2, all the behaviors protected by \texttt{_EDC_SUSV3}=1 are exposed, and pole error related behaviors specified by SUSV3 will be enabled.

For the use of \texttt{_EDC_SUSV3} in individual interface, see \textit{z/OS XL C/C++ Runtime Library Reference}. The functions that are affected by the \texttt{_EDC_SUSV3} environment variable are:
When _EDC_SUS3 = 1 or _EDC_SUS3 = 2:
setenv(), readdir(), getnameinfo(), and tcgetsid()

When _EDC_SUS3 = 2:
log(), logf(), logl(), log10(), log10f(), log10l(), log1p(), log1pf(),
log1pl(), log2(), log2f(), log2l(), pow(), and powl()

The _EDC_SUSV3 environment variable can be set with the function:
setenv("_EDC_SUSV3","1",1);

1 Enables SUSV3 behavior for setenv(), readdir(), getnameinfo(), and
tcgetsid().

2 Also enables SUSV3 behavior for log(), logf(), logl(), log10(), log10f(),
log10l(), log1p(), log1pf(), log1pl(), log2(), log2f(), log2l(), pow(),
and powl().

_EDC_UMASK_DFLT

Allows the user to control how the C library sets the default umask used when the
program runs. If z/OS UNIX services are available, the possible values of the
_EDC_UMASK_DFLT environment variable are:
• NO - the library will not change the value
• a valid octal value - the library sets this as the default
• any other value - the library uses 022 octal as the value.

_EDC_ZERO_RECLEN

Allows processing of zero-length records in an MVS Variable file opened in either
record or text mode. For more information, see Chapter 10, "Performing OS I/O
operations," on page 83. _EDC_ZERO_RECLEN is set with the command:
setenv("_EDC_ZERO_RECLEN","Y",1);

This environment variable has no effect on streams based on UNIX file system
files. You can always read and write zero-byte records in UNIX file system files.

Propagating environment variables

Figure 149 on page 503 shows a sample program (CCNGEV1) that sets the
environment variable _EDC_ANSI_OPEN_DEFAULT. A child program is then initiated by
a system call. This example shows that environment variables are propagated
forward, but not backward.
Figure 149. Environment variables example-Part 1

Figure 150 is another sample program (CCNGEV2) to show how environment variables are propagated.

/* this example shows how environment variables are propagated */
/* part 1 of 2-other file is CCNGEV2 */

#include <stdio.h>
#include <stdlib.h>

int main(void) {
    char *x;

    /* set the environment variable _EDC_ANSI_OPEN_DEFAULT */
    setenv("_EDC_ANSI_OPEN_DEFAULT","Y",1);

    /* set x to the current value of _EDC_ANSI_OPEN_DEFAULT */
    x = getenv("_EDC_ANSI_OPEN_DEFAULT");

    printf("ccngev1 _EDC_ANSI_OPEN_DEFAULT = %s\n", 
           (x != NULL) ? x : "undefined");

    /* call the child program */
    system("ccngev2");

    /* set x to the current value of _EDC_ANSI_OPEN_DEFAULT */
    x = getenv("_EDC_ANSI_OPEN_DEFAULT");

    printf("ccngev2 _EDC_ANSI_OPEN_DEFAULT = %s\n", 
           (x != NULL) ? x : "undefined");

    return(0);
}

Figure 150. Environment variables example-Part 2

The preceding program produces the following output:
cbcgev1 _EDC_ANSI_OPEN_DEFAULT = Y
ccngev2 _EDC_ANSI_OPEN_DEFAULT = Y
ccngev2 _EDC_ANSI_OPEN_DEFAULT = undefined
ccngev1 _EDC_ANSI_OPEN_DEFAULT = Y
Chapter 33. Using hardware built-in functions

This section assumes the user has knowledge of assembler opcodes and assembler programming.

A built-in function is inline code that is generated in place of an actual function call. The hardware built-in functions send requests to the compiler to use instructions that are not typically generated by the compiler. Extra instructions are generated to load the parameters for the operation and to store the result. These functions require that the LANGLVL not be set to ANSI. For more information about a given instruction, refer to the z/Architecture Principles of Operation.

Notes:
1. Using a built-in hardware instruction does not guarantee that a hardware instruction will be generated. The compiler can decide that it is not necessary to generate the code.
2. In some cases, the instruction will be generated as data before it is executed via an EX instruction. This occurs whenever a parameter:
   a. Must be put in a mask or displacement field.
   b. Is specified as a non-literal instead of a literal.

It is more efficient to execute the target instruction for a hardware built-in function without generating an EX instruction. If possible, some parameters of the built-in functions should be specified as literal for better performance. For examples, see Table 98 on page 529.

General instructions

General hardware built-in functions are intended to provide access to general purpose instructions that are not normally generated by the compiler. For more information on these instructions, see chapter 7 of the z/Architecture Principles of Operation.

Note: Before you use any of the instructions listed in Table 90 on page 507 in your program, you must include the builtins.h header file (unless the instructions are otherwise specified) and compile the program with the LANGLVL(EXTENDED) option or the LANGLVL(LIBEXT) option.

Table 89. Standard general-instruction prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __cds1(void* Op1, void* Op2, void* Op3) &lt;br&gt; Note: The user must include stdlib.h to use this built-in function. It is similar to cds() but does not explicitly set the type to be swapped in the prototype.</td>
<td>CDS 0p1,0p3,0p2D(Op2B)</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>int __cdsg(void* Op1, void* Op2, void* Op3) &lt;br&gt; Note: The user must include stdlib.h to use this built-in function. It is similar to cdsg() but does not explicitly set the type to be swapped in the prototype.</td>
<td>CDGS 0p1,0p3,0p2D(Op2B)</td>
<td>ARCH(5) with LP64</td>
</tr>
<tr>
<td>int __cs1(void* Op1, void* Op2, void* Op3) &lt;br&gt; Note: The user must include stdlib.h to use this built-in function. It is similar to cs() but does not explicitly set the type to be swapped in the prototype.</td>
<td>CS 0p1,0p3,0p2D(Op2B)</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>
Table 89. Standard general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>int __csg(void* Op1, void* Op2, void* Op3)</code></td>
<td>CSG Op1,Op3,Op2D(Op2B)</td>
<td>ARCH(5) with LP64</td>
</tr>
<tr>
<td><strong>Note:</strong> The user must include <code>stdlib.h</code> to use this built-in function. It is similar to <code>csg()</code> but does not explicitly set the type to be swapped in the prototype.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>void __dcbf(const void* Op2)</code></td>
<td>PFD M1,Op2</td>
<td>ARCH(8)</td>
</tr>
<tr>
<td>It releases the cache line containing the specified address (Op2) from all accesses.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>void __dcbst(const void* Op2)</code></td>
<td>PFD M1,Op2</td>
<td>ARCH(8)</td>
</tr>
<tr>
<td>It releases the cache line containing the specified address (Op2) from store access and retains the data in the cache line for fetch access.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>void __dcbt(const void* Op2)</code></td>
<td>PFD M1,Op2</td>
<td>ARCH(8)</td>
</tr>
<tr>
<td>It prefetches the cache line containing the specified address (Op2) into the cache for fetch access.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>void __dcbtst(const void* Op2)</code></td>
<td>PFD M1,Op2</td>
<td>ARCH(8)</td>
</tr>
<tr>
<td>It prefetches the cache line containing the specified address (Op2) into the cache for store access.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><code>void __pack (unsigned char* Op1, unsigned char len1, unsigned char* Op2, unsigned char len2)</code></td>
<td>PACK Op1D(len1,Op1B),Op2D(len2,Op2B)</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>• The format of <code>op2</code> is changed from zoned to signed-packed-decimal, and the result is placed at <code>op1</code> location.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• <code>op2</code> is treated as having the zoned format. The numeric bits of each byte are treated as a digit. The zone bits are ignored, except the zone bits in the rightmost byte, which are treated as a sign.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• The sign and digits are moved unchanged to <code>op1</code> and are not checked for valid codes. The sign is placed in the rightmost four bit positions of the rightmost byte of the result field, and the digits are placed adjacent to the sign and to each other in the remainder of the result field.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• The result is obtained as if the operands were processed right to left. When necessary, <code>op2</code> is considered to be extended on the left with zeros. If <code>op1</code> field is too short to contain all digits of <code>op2</code>, the remaining leftmost portion of <code>op2</code> is ignored. Access exceptions for the unused portion of <code>op2</code> may or may not be indicated.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• <code>len1</code> specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand). The length must be in the range 0 to 15.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• <code>len2</code> specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the second operand). The length must be in the range 0 to 15.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Table 89. Standard general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>void __tr (unsigned char *Op1, const unsigned char *Op2, unsigned char len)</td>
<td>TR 0p1D(len,Op1B),0p2D(Op2B)</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

- The bytes of op1 are used as eight-bit arguments to reference a list designated by the address of op2. Each function byte selected from the list replaces the corresponding argument in op1.
- len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand used in the machine instruction.
- The bytes of op1 are selected one by one for translation, proceeding left to right. Each argument byte is added to the initial op2 address. The addition is performed following the rules for address arithmetic, with the argument byte treated as an eight-bit unsigned binary integer and extended with zeros on the left. The sum is used as the address of the function byte, which then replaces the original argument byte.
- The operation proceeds until the op1 field is exhausted. The list is not altered unless an overlap occurs.
- When the operands overlap, the result is obtained as if each result byte were stored immediately after fetching the corresponding function byte.

Table 90. Built-in general-instruction prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
</table>
| int __clcle(char *op1, unsigned long op1_len, unsigned char op2, char *op3, unsigned long op3_len); | L R2, Op1  
L R3, Op1_len  
L R4, Op3  
L R5, Op3_len  
CLCLE R2, R4, Op2D(Op2B) | ARCH(2) |

Operands:
- op1 and op1_len represent the first operand in the hardware instruction.
- op3 and op3_len represent the third operand in the hardware instruction.
- op2 specifies the number of bytes to pad the shorter operand on the right.

If the LP64 compiler option is in effect, the op1_len and op3_len operands are 64-bit unsigned integers. Otherwise, op1_len and op3_len are 32-bit unsigned integers. The return value is the condition code set by the CLCLE instruction.

Note: When the condition code is 3, the condition is handled by the compiler-generated code.
### Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __clclu(unsigned short *op1, unsigned long op1_len, unsigned short op2, unsigned short *op3, unsigned long op3_len);</td>
<td>L R2, Op1 L R3, Op1_len L R4, Op3 L R5, Op3_len CLCLU R2, R4, Op2D(Op2B)</td>
<td>ARCH(6)</td>
</tr>
</tbody>
</table>

**Operands:**
- `op1` and `op1_len` represent the first operand in the hardware instruction.
- `op2` specifies the number of bytes to pad the first operand on the right, in the event that it is shorter than the third operand.
- `op3` and `op3_len` represent the third operand in the hardware instruction.

**Conditions:**
- If the LP64 compiler option is in effect, the `op1_len` and `op3_len` operands are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.
- If the operand values are odd numbers, a specification exception will be triggered by the hardware.

The return value is the condition code set by the CLCLU instruction.

**Note:** When the condition code is 3, the condition is handled by the compiler-generated code.

| int __cu12(unsigned short *op1, unsigned long op1_len, char *op2, unsigned long op2_len, char **invalid_utf8, unsigned char mask); | L R2, Op1 L R3, Op1_len L R4, Op2 L R5, Op2_len CU12 R2, R4, Mask | ARCH(7) |

**Operands:**
- `op1` and `op1_len` represent the first operand in the hardware instruction. `op1` points to the storage location for receiving the converted UTF-16 characters.
- `op2` and `op2_len` represent the second operand in the hardware instruction. `op2` points to the source UTF-8 characters.
- `invalid_utf8` points to a pointer field for receiving the address of the invalid UTF-8 character in the source when the condition code is “2”.
- `mask` specifies the mask encoded in the machine instruction; it must be a literal value of either 0 or 1.

**Note:** If option LP64 is specified, both `op1_len` and `op2_len` are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.

The return value is the condition code set by the CU12 instruction.

**Note:** When the condition code is 3, the condition is handled by the compiler-generated code.
Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __cu14 (unsigned int *op1, unsigned long op1_len, char *op2, unsigned long op2_len, unsigned char **invalid_utf8, unsigned char mask);</td>
<td>L R2, Op1 L R3, Op1_len L R4, Op2 L R5, Op2_len CU14 R2, R4, Mask ST *invalid_utf8,R4</td>
<td>ARCH(7)</td>
</tr>
</tbody>
</table>

Operands:
- op1 and op1_len represent the first operand in the hardware instruction. op1 points to the storage location for receiving the converted UTF-32 characters.
- op2 and op2_len represent the second operand in the hardware instruction. op2 points to the source UTF-8 characters.
- invalid_utf8 points to a pointer field for receiving the address of the invalid UTF-8 character in the source when the condition code is “2”.
- mask specifies the mask encoded in the machine instruction; it must be a literal value of either 0 or 1.

Note: If option LP64 is specified, both op1_len and op2_len are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.

The return value is the condition code set by the CU14 instruction.

Note: When the condition code is 3, the condition is handled by the compiler-generated code.

| int __cu21(char *op1, unsigned long op1_len, unsigned short *op2, unsigned long op2_len, unsigned char mask); | L R2, Op1 L R3, Op1_len L R4, Op2 L R5, Op2_len CU21 R2, R4, Mask | ARCH(7) |

Operands:
- op1 and op1_len represent the first operand in the hardware instruction. op1 points to the storage location for receiving the converted UTF-8 characters.
- op2 and op2_len represent the second operand in the hardware instruction. op2 points to the source 2-byte Unicode characters.
- mask specifies the mask encoded in the machine instruction; it must be a literal value of either 0 or 1.

Note: If option LP64 is specified, both op1_len and op2_len are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.

The return value is the condition code set by the CU21 instruction.

Note: When the condition code is 3, the condition is handled by the compiler-generated code.
Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __cu24(unsigned int *op1,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>unsigned long op1_len,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>unsigned short *op2,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>unsigned long op2_len,</td>
<td></td>
<td></td>
</tr>
<tr>
<td>unsigned char mask);</td>
<td></td>
<td></td>
</tr>
<tr>
<td>L R2, Op1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>L R3, Op1_len</td>
<td></td>
<td></td>
</tr>
<tr>
<td>L R4, Op2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>L R5, Op2_len</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CU21 R2, R4, Mask</td>
<td></td>
<td></td>
</tr>
<tr>
<td>ARCH(7)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Operands:
- op1 and op1_len represent the first operand in the hardware instruction. op1 points to the storage location for receiving the converted UTF-32 characters.
- op2 and op2_len represent the second operand in the hardware instruction. op2 points to the source UTF-16 characters.
- mask specifies the mask encoded in the machine instruction; it must be a literal value of either 0 or 1.

**Note:** If option LP64 is specified, both op1_len and op2_len are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.

The return value is the condition code set by the CU24 instruction.

**Note:** When the condition code is 3, the condition is handled by the compiler-generated code.

| int __cu41(char *op1, |
| unsigned long op1_len, |
| unsigned int *op2, |
| unsigned long op2_len, |
| unsigned int **invalid_utf32); |
| L R2, Op1 |
| L R3, Op1_len |
| L R4, Op2 |
| L R5, Op2_len |
| CU41 R2, R4 |
| ST *invalid_utf32,R4 |
| ARCH(7) |

Operands:
- op1 and op1_len represent the first operand in the hardware instruction. op1 points to the storage location for receiving the converted UTF-8 characters.
- op2 and op2_len represent the second operand in the hardware instruction. op2 points to the source UTF-32 characters.
- invalid_utf32 points to a pointer field for receiving the address of the invalid UTF-32 character in the source when the condition code is "2."

**Note:** If option LP64 is specified, both op1_len and op2_len are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers. The return value is the condition code set by the CU41 instruction.

**Note:** When the condition code is 3, the condition is handled by the compiler-generated code.
<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __cu42(unsigned short *op1, unsigned long op1_len, unsigned int *op2, unsigned long op2_len, unsigned int **invalid_utf32);</td>
<td>L R2, Op1 L R3, Op1_len L R4, Op2 L R5, Op2_len CU42 R2, R4 ST *invalid_utf32, R4</td>
<td>ARCH(7)</td>
</tr>
</tbody>
</table>

Operands:
- op1 and op1_len represent the first operand in the hardware instruction. op1 points to the storage location for receiving the converted UTF-16 characters.
- op2 and op2_len represent the second operand in the hardware instruction. op2 points to the source UTF-32 characters.
- invalid_utf32 points to a pointer field for receiving the address of the invalid UTF-32 character in the source when the condition code is ”2”.

**Note:** If option LP64 is specified, both op1_len and op2_len are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.

The return value is the condition code set by the CU42 instruction.

**Note:** When the condition code is 3, the condition is handled by the compiler-generated code.

| int __cvb(char *op2); | CVB R1, Op2D(Op2X, Op2B) | ARCH(0) |

op2 points to an 8-byte storage area that contains a valid packed-decimal value. The return value is the converted 32-bit signed binary integer.

| long long __cvbg(char *op2); | CVBG R1, Op2D(Op2X, Op2B) | ARCH(5) |

Operands: op2 points to a 16-byte storage area that contains a valid packed-decimal value.

The return value is the converted 64-bit signed binary integer.

| void __cvd(int op1, char *op2); | CVD Op1, Op2D(Op2X, Op2B) | ARCH(0) |

- op1 is a 32-bit signed binary integer value that gets converted into a packed-decimal value.
- op2 points to an 8-byte storage area that receives the converted packed-decimal value.

| void __cvdg(long long op1, char *op2); | CVDG Op1, Op2D(Op2X, Op2B) | ARCH(5) |

- op1 is a 64-bit signed binary integer value that gets converted into a packed-decimal value.
- op2 points to a 16-byte storage area that receives the converted packed-decimal value.

| int __lad(int* op1, int op3, int* op2) | L R3, Op3 LAA R1, R3, Op2D(Op2B) ST R1, *Op1 | ARCH(9) |

**Note:**
- Return value corresponds to the condition code set by LAA.
- The location pointed to by op2 must be word aligned for __lad. Otherwise, a specification exception is recognized.
<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
</table>
| int __ladg(long* op1, long op3, long* op2)  
Note:  
• Return value corresponds to the condition code set by LAAG.  
• The location pointed to by op2 must be double-word aligned for __ladg. Otherwise, a specification exception is recognized. | LG R3, Op3  
LAAG R1, R3, Op2D(Op2B)  
STG R1, *Op1 | ARCH(9) with LP64 |
| int __ladl(unsigned int* op1, unsigned int op3, unsigned int* op2)  
Note:  
• Return value corresponds to the condition code set by LAAL.  
• The location pointed to by op2 must be word aligned for __ladl. Otherwise, a specification exception is recognized. | L R3, Op3  
LAAL R1, R3, Op2D(Op2B)  
ST R1, *Op1 | ARCH(9) |
| int __ladlg(unsigned long* op1, unsigned long op3, unsigned long* op2)  
Note:  
• Return value corresponds to the condition code set by LAALG.  
• The location pointed to by op2 must be double-word aligned for __ladlg. Otherwise, a specification exception is recognized. | LG R3, Op3  
LAALG R1, R3, Op2D(Op2B)  
STG R1, *Op1 | ARCH(9) with LP64 |
| int __lan(unsigned int* op1, unsigned int op3, unsigned int* op2)  
Note:  
• Return value corresponds to the condition code set by LAN.  
• The location pointed to by op2 must be word aligned for __lan. Otherwise, a specification exception is recognized. | L R3, Op3  
LAN R1, R3, Op2D(Op2B)  
ST R1, *Op1 | ARCH(9) |
| int __lang(unsigned long* op1, unsigned long op3, unsigned long* op2)  
Note:  
• Return value corresponds to the condition code set by LANG.  
• The location pointed to by op2 must be double-word aligned for __lang. Otherwise, a specification exception is recognized. | LG R3, Op3  
LANG R1, R3, Op2D(Op2B)  
STG R1, *Op1 | ARCH(9) with LP64 |
| int __lao(unsigned int* op1, unsigned int op3, unsigned int* op2)  
Note:  
• Return value corresponds to the condition code set by LAO.  
• The location pointed to by op2 must be word aligned for __lao. Otherwise, a specification exception is recognized. | L R3, Op3  
LAO R1, R3, Op2D(Op2B)  
ST R1, *Op1 | ARCH(9) |
| int __laog(unsigned long* op1, unsigned long op3, unsigned long* op2)  
Note:  
• Return value corresponds to the condition code set by LAOG.  
• The location pointed to by op2 must be double-word aligned for __laog. Otherwise, a specification exception is recognized. | LG R3, Op3  
LAOG R1, R3, Op2D(Op2B)  
STG R1, *Op1 | ARCH(9) with LP64 |
| int __lax(unsigned int* op1, unsigned int op3, unsigned int* op2)  
Note:  
• Return value corresponds to the condition code set by LAX.  
• The location pointed to by op2 must be word aligned for __lax. Otherwise, a specification exception is recognized. | L R3, Op3  
LAX R1, R3, Op2D(Op2B)  
ST R1, *Op1 | ARCH(9) |
### Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td><em><em>int __laxg(unsigned long</em> op1, unsigned long op3, unsigned long</em> op2)**&lt;br&gt;Note:</td>
<td></td>
<td>ARCH(9) with LP64</td>
</tr>
<tr>
<td>• Return value corresponds to the condition code set by LAXG.</td>
<td>LG R3, Op3&lt;br&gt;LAXG R1, R3, Op2D(Op2B)&lt;br&gt;STG R1, *Op1</td>
<td></td>
</tr>
<tr>
<td>• The location pointed to by op2 must be double-word aligned for __laxg. Otherwise, a specification exception is recognized.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>*<em>unsigned int __lcbb(const void</em> op2, unsigned short boundary)**&lt;br&gt;Operands:</td>
<td></td>
<td>ARCH(11)</td>
</tr>
<tr>
<td>• op2 represents the second operand in the hardware instruction.</td>
<td>LCBB R1, Op2D(Op2X, Op2B), BoundaryM</td>
<td></td>
</tr>
<tr>
<td>• boundary represents the boundary to encode in the hardware instruction. It must be a literal value of either 64, 128, 256, 512, 1024, 2048, or 4096.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the first operand set by the LCBB instruction. The first operand contains the number of bytes to load from the second operand location without crossing the specified block boundary. If the number of bytes is greater than 16, sixteen is placed in the first operand.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><em><em>int __lpd(unsigned int</em> op3, unsigned int</em> op4, unsigned int* op1, unsigned int* op2)**&lt;br&gt;Note:</td>
<td></td>
<td>ARCH(9)</td>
</tr>
<tr>
<td>• The locations pointed to by op1 and op2 must be word aligned for __lpd. Otherwise, a specification exception is recognized.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><em><em>int __lpdg(unsigned long</em> op3, unsigned long</em> op4, unsigned long* op1, unsigned long* op2)**&lt;br&gt;Note:</td>
<td></td>
<td>ARCH(9) with LP64</td>
</tr>
<tr>
<td>• The locations pointed to by op1 and op2 must be double-word aligned for __lpdg. Otherwise, a specification exception is recognized.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>unsigned int __lrv(unsigned int *Op)</strong>&lt;br&gt;The return value is the result.</td>
<td>LRV R1, OpD(OpX,OpR)</td>
<td>ARCH(4)</td>
</tr>
<tr>
<td><strong>unsigned long __lrvg(unsigned long *Op)</strong>&lt;br&gt;The return value is the result.</td>
<td>LRVG R1, OpD(OpX,OpR)</td>
<td>ARCH(5) with LP64</td>
</tr>
<tr>
<td><strong>unsigned short __lrvh(unsigned short *Op)</strong>&lt;br&gt;The return value is the result.</td>
<td>LRVH R1, OpD(OpX,OpR)</td>
<td>ARCH(4)</td>
</tr>
</tbody>
</table>
Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>int __mvcl(char *op1, int __mvcl(char *op1,</code></td>
<td>L R2, Op1</td>
<td>ARCH(2)</td>
</tr>
<tr>
<td><code>unsigned long op1_len,</code></td>
<td>L R3, Op1_len</td>
<td></td>
</tr>
<tr>
<td><code>unsigned char op2, char *op3,</code></td>
<td>L R4, Op3</td>
<td></td>
</tr>
<tr>
<td><code>unsigned long op3_len);</code></td>
<td>L R5, Op3_len</td>
<td></td>
</tr>
<tr>
<td><strong>Operands:</strong></td>
<td><strong>MVCE R2, R4, Op2D(Op2B)</strong></td>
<td></td>
</tr>
<tr>
<td>• op1 and op1_len represent the first operand in the hardware instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op3 and op3_len represent the third operand in the hardware instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op2 specifies the byte for padding the first operand on the right, in the event that it is shorter than the third operand.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Conditions:</strong> If the LP64 compiler option is in effect, the op1_len and op3_len operands are 64-bit unsigned integers. Otherwise, op1_len and op3_len are 32-bit unsigned integers. The return value is the condition code set by the MVCLE instruction. <strong>Note:</strong> When the condition code is 3, the condition is handled by the compiler-generated code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Notes:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1. If the operand values are odd numbers, a specification exception will be triggered by the hardware.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2. If the LP64 compiler option is in effect, the op1_len and op3_len operands are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the condition code set by the MVCLE instruction. <strong>Note:</strong> When the condition code is 3, the condition is handled by the compiler-generated code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Operands:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op1 and op1_len represent the first operand in the hardware instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op2 specifies padding the first operand with 2 bytes if it is shorter than the third operand.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op3 and op3_len represent the third operand in the hardware instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Notes:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1. If the operand values are odd numbers, a specification exception will be triggered by the hardware.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2. If the LP64 compiler option is in effect, the op1_len and op3_len operands are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the condition code set by the MVCLU instruction. <strong>Note:</strong> When the condition code is 3, the condition is handled by the compiler-generated code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Operands:</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Each operand is processed left to right. When the operands overlap, the result is obtained as if the operands were processed one byte at a time and each result byte were stored immediately after fetching the necessary operand bytes.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand).</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
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</tr>
</tbody>
</table>

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<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __oc (unsigned char *OP1, unsigned char *OP2, unsigned char length)</td>
<td>OC Op1D(len,Op1B),Op2D(Op2B)</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>Operands:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• Each operand is processed left to right. When the operands overlap, the result</td>
<td></td>
<td></td>
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<tr>
<td>is obtained as if the operands were processed one byte at a time and each result</td>
<td></td>
<td></td>
</tr>
<tr>
<td>byte were stored immediately after fetching the necessary operand bytes.</td>
<td></td>
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</tr>
<tr>
<td>• len specifies the length encoded in the machine instruction (that is, the</td>
<td></td>
<td></td>
</tr>
<tr>
<td>number of additional bytes to the right of the first operand).</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

| void __pack (unsigned char *OP1, unsigned char len1, unsigned char *OP2, unsigned  | PACK                         | ARCH(0)  |
| char len2)                                                                         | Op1D(len1,Op1B),Op2D(len2,Op2B)|          |
| Operands:                                                                         |                              |          |
| • The format of op2 is changed from zoned to signed-packed-decimal, and the result |                              |          |
|   is placed at op1 location.                                                       |                              |          |
| • op2 is treated as having the zoned format. The numeric bits of each byte are   |                              |          |
|   treated as a digit. The zone bits are ignored, except the zone bits in the      |                              |          |
|   rightmost byte, which are treated as a sign.                                     |                              |          |
| • The sign and digits are moved unchanged to op1 and are not checked for valid    |                              |          |
|   codes. The sign is placed in the rightmost four bit positions of the rightmost   |                              |          |
|   byte of the result field, and the digits are placed adjacent to the sign and to  |                              |          |
|   each other in the remainder of the result field.                                 |                              |          |
| • The result is obtained as if the operands were processed right to left. When    |                              |          |
|   necessary, op2 is considered to be extended on the left with zeros. If op1 field |                              |          |
|   is too short to contain all digits of op2, the remaining leftmost portion of op2 |                              |          |
|   is ignored. Access exceptions for the unused portion of op2 may or may not be   |                              |          |
|   indicated.                                                                       |                              |          |
| • len1 specifies the length encoded in the machine instruction (that is, the      |                              |          |
|   number of additional bytes to the right of the first operand). The length must   |                              |          |
|   be in the range 0 to 15.                                                        |                              |          |
| • len2 specifies the length encoded in the machine instruction (that is, the      |                              |          |
|   number of additional bytes to the right of the second operand). The length must  |                              |          |
|   be in the range 0 to 15.                                                        |                              |          |

| void __pka(char *op1, char *op2, unsigned char op2_len);                          | PKA                           | ARCH(6)  |
| • op1 points to a 16-byte storage area. The packed string is stored in the       | Op1D(Op1B),Op2D(Op2_len,Op2B) |          |
|   storage addressed by op1.                                                      |                              |          |
| • op2 points to an ASCII string to be packed by the operation.                    |                              |          |
| • op2_len specifies the length encoded in the machine instruction (that is, the   |                              |          |
|   number of additional bytes to the right of the second operand).                |                              |          |
| **Notes:**                                                                        |                              |          |
| 1. If op2_len is not between 0 and 31, a specification exception will be          |                              |          |
|   triggered by the hardware.                                                      |                              |          |
| 2. If op2_len is not a literal, the compiler will issue an EX instruction that    |                              |          |
|   executes a target PKA instruction with op2_len encoded in the register used by  |                              |          |
|   the EX instruction.                                                             |                              |          |
Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
</table>
| void __pku(char *op1, unsigned short *op2, unsigned char op2_len);  
- op1 points to a 16-byte storage area. The packed string is stored in the storage addressed by op1.  
- op2 points to Unicode Basic Latin character string to be packed by the operation.  
- op2_len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the second operand.  
**Notes:**  
1. If op2_len is not an odd number between 0 and 63, a specification exception will be triggered by the hardware.  
2. If op2_len is not a literal, the compiler will issue an EX instruction that executes a target PKU instruction with op2_len encoded in the register used by the EX instruction. | PKU Op1D(Op1B),  
Op2D(Op2_len, Op2B) | ARCH(6) |
| unsigned long __popcnt(unsigned long op);  
The population count instruction counts the number of bits set in each byte of a register. It then sets the corresponding byte of the result register to reflect the count.  
The instruction operates on all 64-bits of a register and thus clobbers the upper half of a register in 32-bit mode. Volatile registers R0, R1, or R15 are used for the instruction in 32-bit mode with NOHGPR. | POPCNT R1, op | ARCH(9) |
| int __srstu(unsigned short *op1,  
unsigned short *op2,  
unsigned short pattern,  
unsigned short **found_char);  
Operands:  
- op1 represents the first operand in the hardware instruction, it points at the first 2-byte character after the end of the second operand.  
- op2 represents the second operand in the hardware instruction, it points at the start of a 2-byte character string.  
- pattern is the 2-byte character to be searched for.  
- found_char points to a pointer field for receiving the address of the 2-byte character that was found in the second operand.  
The return value is the condition code set by the SRSTU instruction.  
**Note:** When the condition code is 3, the condition is handled by the compiler-generated code. | L GR0, pattern  
L R1, Op1  
SRSTU R1, Op2  
ST *found_char, R1 | ARCH(7) |
| int __stck(unsigned long long *Op1)  
The return value is the condition code. | STCK Op1D(Op1B) | ARCH(0) |
| int __stcke(void *Op1)  
The return value is the condition code. | STCKE Op1D(Op1B) | ARCH(4) |
| int __stckf(unsigned long long *Op1)  
The return value is the condition code. | STCKF Op1D(Op1B) | ARCH(7) |
| void __strv(unsigned int Op1, unsigned int *Op2)  
The return value is the condition code. | STRV R1, Op2D(Op2X,Op2R) | ARCH(4) |
### Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>void __strvg(unsigned long Op1, unsigned long *Op2)</td>
<td>STRVG R1, Op2D(Op2X,Op2R)</td>
<td>ARCH(5) with LP64</td>
</tr>
<tr>
<td>void __strvh(unsigned short Op1,unsigned short *Op2)</td>
<td>STRVH R1, Op2D(Op2X,Op2R)</td>
<td>ARCH(4)</td>
</tr>
<tr>
<td>void __tr (unsigned char *Op1, const unsigned char *Op2, unsigned char len)</td>
<td>TR Op1D(len,Op1B),Op2D(Op2B)</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

**Operands:**
- The bytes of Op1 are used as eight-bit arguments to reference a list designated by the address of Op2. Each function byte selected from the list replaces the corresponding argument in Op1.
- len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand used in the machine instruction.
- The bytes of Op1 are selected one by one for translation, proceeding left to right. Each argument byte is added to the initial Op2 address. The addition is performed following the rules for address arithmetic, with the argument byte treated as an eight-bit unsigned binary integer and extended with zeros on the left. The sum is used as the address of the function byte, which then replaces the original argument byte.
- The operation proceeds until the Op1 field is exhausted. The list is not altered unless an overlap occurs.
- When the operands overlap, the result is obtained as if each result byte were stored immediately after fetching the corresponding function byte.

```c
int __tre(char *op1, unsigned long op1_len, char *op2, unsigned char test_char);
```

**Operands:**
- op1 represents the first operand in the hardware instruction. It points to the byte string that needs to be translated.
- op1_len specifies the length of the first operand.
  **Note:** If the LP64 compiler option is in effect, the op1_len operand is a 64-bit unsigned integer. Otherwise it is a 32-bit unsigned integer.
- op2 represents the second operand in the hardware instruction. It points to a 256-byte translation table.
- test_char specifies the terminating character in the first operand for stopping the operation.

The return value is the condition code set by the TRE instruction.
  **Note:** When the condition code is 3, the condition is handled by the compiler-generated code.
<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
</table>
| int _troo (char *op1, char *op2, unsigned long op2_len, char *tr_table, unsigned char test_char, unsigned char mask); | L GR0, test_char  
L GR1, tr_table  
L R2, Op1  
L R3, Op2_len  
TROO R2, Op2, Mask | ARCH(7) |

Operands:
- op1 represents the first operand in the hardware instruction.
- op2 and op2_len represent the second operand in the hardware instruction.
- Notes: If option LP64 is specified, op2_len is a 64-bit unsigned integer and the length of the first operand is considered the same as that of the second operand. If option LP64 is not specified, both operands are 32-bit unsigned integers.
- tr_table points to a 256-byte translation table on a double-word boundary.
- Notes: It is the user’s responsibility to provide a double-word aligned translation table.
- test_char specifies a 1-byte function character that can be coded in the translation table for stopping the operation.
- mask specifies the mask encoded in the machine instruction; it must be a literal value of either 0 or 1.

The return value is the condition code set by the TROO instruction.
- Notes: When the condition code is 3, the condition is handled by the compiler-generated code.

| int _trot(unsigned short *op1, char *op2, unsigned long op2_len, char *tr_table, unsigned short test_char, unsigned char mask); | L GR0, test_char  
L GR1, tr_table  
L R2, Op1  
L R3, Op2_len  
TROT R2, Op2, Mask | ARCH(7) |

Operands:
- op1 represents the first operand in the hardware instruction.
- op2 and op2_len represent the second operand in the hardware instruction.
- Notes: If option LP64 is specified, op2_len is a 64-bit unsigned integer and the length of the first operand is considered the same as that of the second operand. Otherwise, both operands are 32-bit unsigned integers.
- tr_table points to a 512-byte translation table on a double-word boundary.
- Notes: It is the user’s responsibility to provide a double-word aligned translation table.
- test_char specifies a 2-byte function character that can be coded in the translation table for stopping the operation.
- mask specifies the mask encoded in the machine instruction; it must be a literal value of either 0 or 1.

The return value is the condition code set by the TROT instruction.
- Notes: When the condition code is 3, the condition is handled by the compiler-generated code.
<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>int __trto(char *op1, unsigned short *op2, unsigned long op2_len, char *tr_table, char test_char, unsigned char mask);</code></td>
<td><code>L GR0, test_char</code>&lt;br&gt;<code>L GR1, tr_table</code>&lt;br&gt;<code>L R2, Op1</code>&lt;br&gt;<code>L R3, Op2_len</code>&lt;br&gt;<code>TRTO R2, Op2, Mask</code></td>
<td>ARCH(7)</td>
</tr>
</tbody>
</table>

Operands:
- `op1` represents the first operand in the hardware instruction.
- `op2` and `op2_len` represent the second operand in the hardware instruction.
- `tr_table` points to a 64-KB translation table on a double-word boundary.
  
  **Note:** It is the user’s responsibility to provide a double-word aligned translation table.
- `test_char` specifies a 1-byte function character, that can be coded in the translation table, for stopping the operation.
- `mask` specifies the mask encoded in the machine instruction; it must be a literal value of either 0 or 1.

**Note:** If option LP64 is specified, both `op1_len` and `op2_len` are 64-bit unsigned integers. Otherwise they are 32-bit unsigned integers.

The return value is the condition code set by the TROT instruction.

**Note:** When the condition code is 3, the condition is handled by the compiler-generated code.

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>int __trt(unsigned char *OP1, const unsigned char *OP2, unsigned char len, unsigned char *R2, unsigned char **R1)</code></td>
<td><code>TRT Op1D(len,Op1B),Op2D(Op2B)</code></td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

Operands:
- The bytes of `op1` are used as eight-bit arguments to select function bytes from a list designated by the address of `op2`. The first nonzero function byte is inserted in general register 2, and the related argument address in general register 1.
- `len` specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand used in the machine instruction).
- The bytes of `op1` are selected one by one for translation, proceeding left to right. `op1` remains unchanged in storage. Calculation of the address of the function byte is performed as in the __tr instruction. The function byte retrieved from the list is inspected for a value of zero.
- When the function byte is zero, the operation proceeds with the next byte of `op1`.
- When the function byte is nonzero, the operation is completed by inserting the function byte in general register 2 and the related argument address in general register 1. Either condition code 1 or 2 is set, depending on whether the argument byte is the rightmost byte of `op1`. Condition code 1 is set if one or more argument bytes remain to be translated. Condition code 2 is set if no more argument bytes remain.

The return value is the condition code.
### Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int _trtr (unsigned char *op1,</td>
<td>TRTR Op1D(length, Op1B),</td>
<td>ARCH(7)</td>
</tr>
<tr>
<td>const unsigned char *op2,</td>
<td>Op2D(Op2B)</td>
<td></td>
</tr>
<tr>
<td>unsigned char length,</td>
<td>ST +R2, GR2</td>
<td></td>
</tr>
<tr>
<td>unsigned char *R2,</td>
<td>ST +R1, GR1</td>
<td></td>
</tr>
<tr>
<td>unsigned char **R1);</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operands:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op1 represents the first operand in the hardware instruction; it</td>
<td></td>
<td></td>
</tr>
<tr>
<td>points to the last byte of the byte string to be translated and tested.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op2 represents the second operand in the hardware instruction; it points to a</td>
<td></td>
<td></td>
</tr>
<tr>
<td>256-byte table.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• length specifies the length encoded in the machine instruction (that is, the</td>
<td></td>
<td></td>
</tr>
<tr>
<td>number of additional bytes to the left of the first operand used in the machine</td>
<td></td>
<td></td>
</tr>
<tr>
<td>instruction; the value is between 0 and 255).</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Note:</strong> When length is not specified as a literal, an EX instruction is</td>
<td></td>
<td></td>
</tr>
<tr>
<td>generated to execute a target TRTR instruction with length encoded in the</td>
<td></td>
<td></td>
</tr>
<tr>
<td>register used by the EX instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• R2 points to a one-byte storage for receiving the function byte in GPR 2 when</td>
<td></td>
<td></td>
</tr>
<tr>
<td>the condition code is nonzero.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• R1 points to a pointer field for receiving the address in GPR 1 when the</td>
<td></td>
<td></td>
</tr>
<tr>
<td>condition code is nonzero.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the condition code set by the TRTR instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __trtt(unsigned short *op1,</td>
<td>L GR0, test_char</td>
<td>ARCH(7)</td>
</tr>
<tr>
<td>unsigned short *op2,</td>
<td>L GR1, tr_table</td>
<td></td>
</tr>
<tr>
<td>unsigned long op2_len,</td>
<td>L R2, Op1</td>
<td></td>
</tr>
<tr>
<td>char*tr_table,</td>
<td>L R3, Op2_len</td>
<td></td>
</tr>
<tr>
<td>unsigned short test_char,</td>
<td>TRTT R2, Op2, Mask</td>
<td></td>
</tr>
<tr>
<td>unsigned char mask);</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operands:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op1 represents the first operand in the hardware instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• op2 and op2_len represent the second operand in the hardware instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Note:</strong> If option LP64 is specified, op2_len is a 64-bit unsigned integer and the</td>
<td></td>
<td></td>
</tr>
<tr>
<td>length of the first operand is considered the same as that of the second</td>
<td></td>
<td></td>
</tr>
<tr>
<td>operand. Otherwise, both operands are 32-bit unsigned integers.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• tr_table points to a 128-KB translation table on a double-word boundary.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Note:</strong> It is the user’s responsibility to provide a double-word aligned</td>
<td></td>
<td></td>
</tr>
<tr>
<td>translation table.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• test_char specifies a 2-byte function character that can be coded in the</td>
<td></td>
<td></td>
</tr>
<tr>
<td>translation table for stopping the operation.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>• mask specifies the mask encoded in the machine instruction; it must be a literal</td>
<td></td>
<td></td>
</tr>
<tr>
<td>value of either 0 or 1.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the condition code set by the TRTT instruction.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Note:</strong> When the condition code is 3, the condition is handled by the compiler-</td>
<td></td>
<td></td>
</tr>
<tr>
<td>generated code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PROTOTYPE and Notes</td>
<td>Sample Pseudo Assembly</td>
<td>MIN ARCH</td>
</tr>
<tr>
<td>---------------------</td>
<td>------------------------</td>
<td>---------</td>
</tr>
</tbody>
</table>
| `void __unpk (unsigned char *OP1, unsigned char len1, unsigned char *OP2, unsigned char len2)` | `UNPK
Op1D(len1,Op1B),Op2D(len2,Op2B)` | ARCH(0) |

Operands:
- The format of `op2` is changed from signed-packed-decimal to zoned, and the result is placed at `op1` location.
- `op2` is treated as having the signed-packed-decimal format. Its digits and sign are placed unchanged in `op1` location, using the zoned format. Zone bits with coding of 1111 are supplied for all bytes except the rightmost byte, the zone of which receives the sign of `op2`. The sign and digits are not checked for valid codes.
- `op2` is treated as having the signed-packed-decimal format. Its digits and sign are placed unchanged in `op1` location, using the zoned format. Zone bits with coding of 1111 are supplied for all bytes except the rightmost byte, the zone of which receives the sign of `op2`. The sign and digits are not checked for valid codes.
- The result is obtained as if the operands were processed right to left. When necessary, `op2` is considered to be extended on the left with zeros. If `op1` field is too short to contain all digits of `op2`, the remaining leftmost portion of `op2` is ignored. Access exceptions for the unused portion of `op2` may or may not be indicated.
- `len1` specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand). The length must be in the range 0 to 15.
- `len2` specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the second operand). The length must be in the range 0 to 15.

| int __unpka(char *op1, unsigned char op1_len, char *op2); | `UNPKA Op1D(0p1_len, Op1B),
Op2D(Op2B)` | ARCH(6) |

Operands:
- `op1` points to a maximum 32-byte storage area to receive the unpacked data from the second operand.
- `op1_len` specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand).

**Note:** If `op1_len` is not a literal, the compiler will issue an EX instruction that executes a target UNPKA instruction with `op1_len` encoded in the register used by the EX instruction.
- `op2` points to a 16-byte data string that represents 31 digits and a sign.

The return value is the condition code set by the UNPKA instruction.
Table 90. Built-in general-instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __unpku(unsigned short *op1, unsigned char op1_len, char *op2);</td>
<td>UNPKU Op1D(Op1_len, Op1B), Op2D(Op2B)</td>
<td>ARCH(6)</td>
</tr>
</tbody>
</table>

Observe:
- op1 points to a maximum 64-byte storage area to receive the unpacked data from the second operand.
- op1_len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand).

Notes:
1. If op1_len is not a literal, the compiler will issue an EX instruction that executes a target UNPKU instruction with op1_len encoded in the register used by the EX instruction.
2. If op1_len is not an odd number between 0 and 63, a specification exception will be triggered by the hardware.

*op2 points to a 16-byte data string that represents 31 digits and a sign.

The return value is the condition code set by the UNPKU instruction.

| int __xc (unsigned char *Op1, unsigned char *Op2, unsigned char length) | XC Op1D(len,Op1B),Op2D(Op2B) | ARCH(0) |

Observe:
- Each operand is processed left to right. When the operands overlap, the result is obtained as if the operands were processed one byte at a time and each result byte were stored immediately after fetching the necessary operand bytes.
- len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand).

The return value is the condition code.

**PLO - Perform Locked Operation available in ARCH(5)**

With the PLO instruction, you can perform the following atomic read-modify-write operations:
- compare and load
- compare and swap
- double compare and swap
- compare swap and store
- compare swap and double store
- compare swap and triple store

To perform a particular operation, the PLO requires an address to a lock, a function code that specifies the operation to be performed and the relevant operands. Each PLO operation has four built-in functions associated with it. The functions take 32-bit, 64-bit, and 128-bit operands. Applications written with built-ins that take 64-bit or 128-bit operands need to be compiled and linked with LP64 option. In other words, PLO built-ins that end with the letter G, GR(64-bit operands), or X(128 bit operands) need to be compiled with LP64 option. For
example, for the "compare and load" interface, the functions __plo_CLGR,
__plo_CLG, and __plo_CLX need to be compiled with LP64 option.

The function prototypes, associated types, and helper macros will be declared in
builtins.h header file. The argument names and order in the function prototypes
attempt to reflect the description of the hardware instructions in z/Architecture
Principles of Operation. A brief description is provided for each function prototype,
data types, and helper macros.

Note: For every 8-byte PLO operation, there are two interfaces, for example,
__plo_DSCG and __plo_DCSGR. The distinction between these two prototypes is
that the former uses a parameter list to receive all its arguments.

All the atomic read-modify-write operations require a memory location, which is to
be used as a lock and is the first argument for all the prototypes. The return type
for all the functions is a signed integer, which returns the condition code set by the
PLO instruction.

Note: There is no AR mode support. You need to enable support for the unsigned
long long type to use the PLO interface. You also need to enable 64 bit mode
compilation when using PLO built-ins that take 64-bit or 128-bit operands.

Associated types and helper macros
For certain function codes, the PLO instruction takes the address to a parameter
list that contains all the operands needed to perform the specified operation. The
parameter list is a contiguous region in memory where the operands are stored.
The parameter list has to be double word aligned, and for each atomic operation
the layout of the operands in the list is different. All unused fields in the
parameter list have to contain zeros.

To simplify the setup of the parameter list, an interface is provided to setup the
parameter list prior to passing it to any of the built-in functions. The macros and
the types are defined in builtins.h header file.
#define __PLO_PARAM_LIST_MAX_SIZE 18
typedef unsigned long long __plo_plist[ __PLO_PARAM_LIST_MAX_SIZE ]

//Compare and Load
#define __PLO_CL 0
#define __PLO_CLG 1
#define __PLO_CLGR 2
#define __PLO_CLX 3

//Compare and Swap
#define __PLO_CS 4
#define __PLO_CSG 5
#define __PLO_CSGR 6
#define __PLO_CSX 7

//Double Compare and Swap
#define __PLO_DCS 8
#define __PLO_DCSG 9
#define __PLO_DCSGR 10
#define __PLO_DCSX 11

//Compare Swap and Store
#define __PLO_CSST 12
#define __PLO_CSSTG 13
#define __PLO_CSSTGR 14
#define __PLO_CSSTX 15
//Compare Swap and Double Store
#define __PLO_CSDST 16
#define __PLO_CSDSTG 17
#define __PLO_CSDSTGR 18
#define __PLO_CSDSTX 19

//Compare Swap and Triple Store
#define __PLO_CSTST 20
#define __PLO_CSTSTG 21
#define __PLO_CSTSTGR 22
#define __PLO_CSTSTX 23

An array of fixed size is defined to correspond to the largest size the parameter list can have, and various function codes are defined.

Table 91 describes the helper macros.

<table>
<thead>
<tr>
<th>Helper Macros</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>_PLO_INIT_PARAM_LIST(param_list)</td>
<td>Helper macro to initialize the parameter list and must be called prior to loading the parameter list with any values.</td>
</tr>
<tr>
<td>_PLO_PUTVAL_PARAM_LIST4(function_code, param_list, uint_op1c, uint_op1r, uint_op3, uint_op4_ptr, uint_op5, uint_op6_ptr, uint_op7, uint_op8_ptr)</td>
<td>Helper macro to setup the parameter list for read-modify write operations on 32 bit operands. The macro takes the function code for the operation that will be performed on the parameter list, a superset of the operands that might be required and the parameter list itself.</td>
</tr>
<tr>
<td>_PLO_PUTVAL_PARAM_LIST8(function_code, param_list, ulonglong_op1c, ulonglong_op1r, ulonglong_op3, ulonglong_op3c, ulonglong_op3r, ulonglong_op4_ptr, ulonglong_op5, ulonglong_op6_ptr, ulonglong_op7, ulonglong_op8_ptr)</td>
<td>Helper macro to setup the parameter list for read-modify write operations on 64-bit operands.</td>
</tr>
<tr>
<td>_PLO_PUTVAL_PARAM_LIST16(function_code, param_list, ulonglong_op1c_ptr, ulonglong_op1r_ptr, ulonglong_op3_ptr, ulonglong_op3c_ptr, ulonglong_op3r_ptr, ulonglong_op4_ptr, ulonglong_op5_ptr, ulonglong_op6_ptr, ulonglong_op7_ptr, ulonglong_op8_ptr)</td>
<td>Helper macro to setup the parameter list for 128 bit operands. Note that for 128 bit operands, pointers are taken to a 16 byte region in memory as arguments.</td>
</tr>
</tbody>
</table>
Table 91. PLO helper macros (continued)

<table>
<thead>
<tr>
<th>Helper Macros</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>__PLO_GETVAL_PARAM_LIST8(function_code, param_list, ulonglong_op1c, ulonglong_op3, ulonglong_op3c)</td>
<td>Helper macro to read 64-bit values that are updated by the execution of a PLO operation from the parameter list.</td>
</tr>
<tr>
<td>__PLO_GETVAL_PARAM_LIST16(function_code, param_list, ulonglong_op1c_ptr, ulonglong_op3_ptr, ulonglong_op3c_ptr)</td>
<td>Helper macro to read 128-bit values that are updated by the execution of a PLO operation from the parameter list.</td>
</tr>
</tbody>
</table>

**Compare and Load**

Table 92 describes the prototypes for compare and load operations.

Table 92. Compare and load prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __plo_CL(void * lock, unsigned int * op1c, unsigned int * op3, unsigned int * op4);</td>
<td>L GR1, lock L GR0, function_code(0 or 2) L R1, *op1c L R3, *op3 PLO R1, R3, op2, op4 ST *op3, R3 ST *op1c, R1</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CLGR(void * lock, unsigned long long * op1c, unsigned long long * op3, unsigned long long * op4);</td>
<td>L GR1, lock L GR0, function_code(1 or 3) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CLG (void * lock, unsigned long long* op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code(1 or 3) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CLX (void * lock, void* op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code(1 or 3) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
</tbody>
</table>

**Compare and Swap**

Table 93 describes the prototypes for compare and swap operations.

Table 93. Compare and swap prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __plo_CS(void * lock, unsigned int * op1c, unsigned int op1r, unsigned int * op2);</td>
<td>L GR1, lock L GR0, function_code(4 or 6) L R1, *op1c L R1+1, op1r PLO R1, op2 ST R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSGR(void * lock, unsigned long long * op1c, unsigned long long op1r, unsigned long long * op2);</td>
<td>L GR1, lock L GR0, function_code(4 or 6) L R1, *op1c L R1+1, op1r PLO R1, op2 ST R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CLG (void * lock, unsigned long long* op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code(1 or 3) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CLX (void * lock, void* op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code(1 or 3) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
</tbody>
</table>
### Table 93. Compare and swap prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __plo_CSG (void * lock, unsigned long long * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (5 or 7) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSX (void * lock, void * op2, void * param_list);</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note:** "void * param_list" is a pointer to the parameter list that is discussed in section *Associated types and helper macros.*

---

### Double Compare and Swap

Table 94 describes the prototypes for double compare and swap operations.

### Table 94. Double compare and swap prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __plo_DCS (void * lock, unsigned int * op1c, unsigned int op1r, unsigned int * op2, unsigned int * op3c, unsigned int op3r, unsigned int * op4);</td>
<td>L GR1, lock L GR0, function_code (8 or 10) L R1, *op1c L R1+1, op1r L R3, *op3c L R3+1, op3r PLO R1,R3, op2,op4 ST R1, *op1c ST R3, *op3c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_DCSGR (void * lock, unsigned long long * op1c, unsigned long long op1r, unsigned long long * op2, unsigned long long * op3c, unsigned long long op3r, unsigned long long * op4);</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __plo_DCSG (void * lock, unsigned long long * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (9 or 11) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_DCSX (void * lock, void * op2, void * param_list);</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note:** "void * param_list" is a pointer to the parameter list that is discussed in section *Associated types and helper macros.*

---

### Compare and Swap and Store

Table 95 on page 527 describes the prototypes for compare and swap and store operations.
### Table 95. Compare and swap and store prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __plo_CSST (void * lock, unsigned int * op1c, unsigned int op1r, unsigned int * op2, unsigned int op3, unsigned int * op4);</td>
<td>L GR1, lock L GR0, function_code (12 or 14) L R1, *op1c L R1+1, op1r L R3, op3 PLO R1,R3,op2,op4 ST R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSSTGR (void * lock, unsigned long long * op1c, unsigned long long op1r, unsigned long long * op2, unsigned long long op3, unsigned long long * op4);</td>
<td>L GR1, lock L GR0, function_code (13 or 15) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSST (void * lock, unsigned long long * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (16 or 18) L R1, *op1c L R1+1, op1r PLO R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSSTX (void * lock, void * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (17 or 19) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
</tbody>
</table>

**Note:** "void * param_list" is a pointer to the parameter list that is discussed in section Associated types and helper macros.

---

### Compare and Swap and Double Store

Table 96 describes the prototypes for compare, swap, and double store operations.

### Table 96. Compare swap and double store prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __plo_CSDST (void * lock, unsigned int * op1c, unsigned int op1r, unsigned int * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (16 or 18) L R1, *op1c L R1+1, op1r PLO R1, op2, param_list ST R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSDSTGR(void * lock, unsigned long long * op1c, unsigned long long op1r, unsigned long long * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (17 or 19) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSDSTG (void * lock, unsigned long long * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (16 or 18) L R1, *op1c L R1+1, op1r PLO R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int __plo_CSDSTX(void * lock, void * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (17 or 19) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
</tbody>
</table>

**Note:** "void * param_list" is a pointer to the parameter list that is discussed in section Associated types and helper macros.

---

### Compare and Swap and Triple Store

Table 97 on page 528 describes the prototypes for compare and swap and triple store operations.
### Decimal instructions

Hardware packed-decimal instructions are available to C/C++ programs in the form of built-in functions. These hardware built-in functions are intended to provide access to decimal instructions that are not normally generated by the compiler.

Decimal instructions of SS format carry one or two length fields. Each length field is encoded with a binary length, that is the actual length - 1. In the function prototypes, the length parameters need to be specified as the actual length - 1. Argument names and order reflects the description of the hardware instructions in *z/Architecture Principles of Operation* (that is, op1, op2, op3, etc.) Additional arguments provide required information for setting up the actual hardware instruction. For detailed description of each decimal instruction, see *Chapter 8. Decimal Instructions* of the *z/Architecture Principles of Operation*.

If you want to use any of the decimal functions, your program must include *builtins.h* and be compiled with either the LANGLVL(EXTENDED) option or the LANGLVL(LIBEXT) option.

---

**Table 97. Compare and swap and triple store prototypes**

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int _plo_CSTST (void * lock, unsigned int * op1c, unsigned int op1r, unsigned int * op2, void * param_list);</td>
<td>L GR1, lock L GR0, function_code (20 or 22) L R1, *op1c L R1+1, op1r PLO R1, op2, param_list ST R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int _plo_CSTSTGR(void * lock, unsigned long long * op1c, unsigned long long op1r, unsigned long long * op2, void * param_list);</td>
<td>L GR1 lock L GR0 function_code (20 or 22) L R1, *op1c L R1+1, op1r PLO R1, op2, param_list ST R1, *op1c</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int _plo_CSTSTG (void * lock, unsigned long long * op2, void * param_list);</td>
<td>L GR1 lock L GR0 function_code (21 or 23) PLO op2, param_list</td>
<td>ARCH(5)</td>
</tr>
<tr>
<td>int _plo_CSTSTX (void * lock, void *op2, void * param_list);</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Note:** "void * param_list" is a pointer to the parameter list that is discussed in section *Associated types and helper macros*.  

---

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*z/OS V2R2 XL C/C++ Programming Guide*
### Table 98. Decimal instruction prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __ap (unsigned char *op1, unsigned char len1, unsigned char *op2, unsigned char len2 );</td>
<td>AP Op1D(len1, Op1B), Op2D(len2, Op2B)</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

Operands:
- op1 represents the first operand in the hardware instruction. It points to the first operand location. The result replaces the first operand.
- len1 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand). The value is between 0 and 15.
- op2 represents the second operand in the hardware instruction. It points to the second operand location.
- len2 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the second operand). The value is between 0 and 15.

**Note:** When either len1 or len2 is not specified as a literal, an EX instruction is generated to execute a target AP instruction with length encoded in the register used by the EX instruction.

The return value is the condition code set by the AP instruction.

---

| int __cp (unsigned char *op1, unsigned char len1, unsigned char *op2, unsigned char len2 ); | CP Op1D(len1, Op1B), Op2D(len2, Op2B) | ARCH(0) |

Operands:
- op1 represents the first operand in the hardware instruction. It points to the first operand location.
- len1 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand). The value is between 0 and 15.
- op2 represents the second operand in the hardware instruction. It points to the second operand location.
- len2 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the second operand). The value is between 0 and 15.

**Note:** When either len1 or len2 is not specified as a literal, an EX instruction is generated to execute a target CP instruction with length encoded in the register used by the EX instruction.

The return value is the condition code set by the CP instruction.
Table 98. Decimal instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>void __dp (unsigned char *op1, unsigned char len1, unsigned char *op2, unsigned char len2 );</td>
<td>DP Op1D(len1, Op1B), Op2D(len2, Op2B)</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

Operands:
- op1 represents the first operand (dividend) in the hardware instruction. It points to the first operand location. The result replaces the first operand. The quotient is placed leftmost in this location. The number of bytes in the quotient field is equal to the difference between the dividend and divisor lengths (len1 - len2). The remainder is placed rightmost in this location and has a length equal to the divisor length len2.
- len1 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand). The value must be greater than len2 and not greater than 15.
- op2 represents the second operand (divisor) in the hardware instruction. It points to the second operand location.
- len2 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the second operand). The value is between 0 and 7 and must be less than the value of len1.

Note: When either len1 or len2 is not specified as a literal, an EX instruction is generated to execute a target DP instruction with length encoded in the register used by the EX instruction.

| int __ed (unsigned char *OP1, unsigned char *OP2, unsigned char length); | ED Op1D(len1,Op1B), Op2D(Op2B) | ARCH(0) |

Operands:
- op2 (the source), which normally contains one or more decimal numbers in the signed-packed-decimal or unsigned-packed-decimal format, is changed to the zoned format and modified under the control of op1 (the pattern). The edited result replaces op1.
- len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand).
- The length of op2 is determined by the operation according to the contents of the pattern. The leftmost four bits of each source byte must specify a decimal-digit code (0000-1001); a sign code (1010-1111) is recognized as a data exception. The rightmost four bits may specify either a sign code or a decimal-digit code. Access and data exceptions are recognized only for those bytes in op2 which are actually required.

The return value is the condition code.
### Table 98. Decimal instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __edmk (unsigned char *OP1, unsigned char *OP2, unsigned char length, unsigned char **R1);</td>
<td>EDMK Op1D(len,Op1B), Op2D(Op2B)</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

**Operands:**
- OP2 (the source), which normally contains one or more decimal numbers in the signed-packed-decimal or unsigned-packed-decimal format, is changed to the zoned format and modified under the control of OP1 (the pattern). The edited result replaces OP1.
- length specifies the length encoded in the machine instruction (that is, the number of additional bytes to the right of the first operand).
- __edmk is identical to __ed except for the additional function of inserting the address of the result byte in general register 1 if the result byte is a zoned source digit and the significance indicator was off before the examination. If no result byte meets the criteria, general register 1 remains unchanged; if more than one result byte meets the criteria, the address of the rightmost such result byte is inserted.
- In the 24-bit addressing mode, the address replaces bits 40-63 of general register 1, and bits 0-39 of the register are not changed. In the 31-bit addressing mode, the address replaces bits 33-63 of general register 1, bit 32 of the register is set to zero, and bits 0-31 of the register remain unchanged. In the 64-bit addressing mode, the address replaces bits 0-63 of general register 1.

The return value is the condition code.

| void __mp (unsigned char *op1, unsigned char len1, unsigned char *op2, unsigned char len2 ); | MP Op1D(len1, Op1B), Op2D(len2, Op2B) | ARCH(0) |

**Operands:**
- op1 represents the first operand (multiplicand) in the hardware instruction. It points to the first operand location. The result replaces the first operand. The multiplicand must have at least as many bytes of leftmost zeros as the number of bytes in the multiplier.
- len1 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand). The value must be greater than len2 and not greater than 15.
- op2 represents the second operand (multiplier) in the hardware instruction. It points to the second operand location.
- len2 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the second operand). The value is between 0 and 7 and must be less than the value of len1.

**Note:** When either len1 or len2 is not specified as a literal, an EX instruction is generated to execute a target MP instruction with length encoded in the register used by the EX instruction.
### Table 98. Decimal instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __sp (unsigned char *op1, unsigned char len1, unsigned char *op2, unsigned char len2 );</td>
<td>SP Op1D(len1, Op1B), Op2D(len2, Op2B)</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

**Operands:**
- op1 represents the first operand in the hardware instruction. It points to the first operand location. The result replaces the first operand.
- len1 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand). The value is between 0 and 15.
- op2 represents the second operand in the hardware instruction. It points to the source location.
- len2 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the second operand). The value is between 0 and 15. **Note:** When either len1 or len2 is not specified as a literal, an EX instruction is generated to execute a target SP instruction with length encoded in the register used by the EX instruction.

The return value is the condition code set by the SP instruction.

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __srp (unsigned char *op1, unsigned char len1, signed char op2, unsigned char op3 );</td>
<td>SRP Op1D(len1, Op1B), Op2D(op2), Op3</td>
<td>ARCH(0)</td>
</tr>
</tbody>
</table>

**Operands:**
- op1 represents the first operand in the hardware instruction. It points to the source location. The result replaces the first operand.
- len1 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand). The value is between 0 and 15.
- op2 represents the second operand in the hardware instruction. It is a shift value between -32 and 31. Positive shift values specify shifting to the left. Negative shift values specify shifting to the right.
- op3 represents the third operand in the hardware instruction. It is used as a decimal rounding digit. **Note:** When either len1 or op3 is not specified as a literal, an EX instruction is generated to execute a target SRP instruction with len1 or op3 encoded in the register used by the EX instruction.

The return value is the condition code set by the SRP instruction.
Table 98. Decimal instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __tp(char *op1, unsigned char op1_len);</td>
<td>TP OpiD(Op1_len, Op1B)</td>
<td>ARCH(6)</td>
</tr>
</tbody>
</table>

Operands:
- op1 points to a byte string to be tested for a valid packed-decimal value.
- op1_len specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the first operand used in the machine instruction). The value is between 0 and 15.

Note: When op1_len is not specified as a literal, an EX instruction is generated to execute a target TP instruction with op1_len encoded in the register used by the EX instruction.

The return value is the condition code set by the TP instruction.

| int __zap (unsigned char *op1, unsigned char len1, unsigned char *op2, unsigned char len2 ); | ZAP OpiD(len1, Op1B), Op2D(len2, Op2B) | ARCH(0) |

Operands:
- op1 represents the first operand in the hardware instruction. It points to the location to receive the result.
- len1 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the sign byte of the first operand). The value is between 0 and 15.

Note: When len1 is not specified as a literal, an EX instruction is generated to execute a target ZAP instruction with len1 encoded in the register used by the EX instruction.
- op2 represents the second operand in the hardware instruction. It points to the start location.
- len2 specifies the length encoded in the machine instruction (that is, the number of additional bytes to the left of the sign byte of the second operand). The value is between 0 and 15.

Note: When len2 is not specified as a literal, an EX instruction is generated to execute a target ZAP instruction with len2 encoded in the register used by the EX instruction.

The return value is the condition code set by the ZAP instruction.

Floating-point support instructions

These functions are intended to help convert between the two floating point formats. For more information on these instructions, see chapter 9 of z/Architecture Principles of Operation.

If you want to use any of the following instructions, your program must include the builtins.h header file and be compiled with LANGLVL(EXTENDED) or LANGLVL(LIBEXT).

Table 99. Floating-point instruction prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __tbdr(double *Op1, int M3, double Op2)</td>
<td>TBDR F1,M3,Op2 LDR +Op1,F1</td>
<td>ARCH(3)</td>
</tr>
</tbody>
</table>

The return value is the condition code.
### Decimal floating-point built-in functions

Decimal floating-point built-in functions are provided for each DFP hardware instruction. XL C/C++ developers can use the decimal floating-point built-in functions and macros, or named constants, by calling the functions with appropriate parameters. It is not necessary to include a header file before using decimal floating-point built-in functions. They will be automatically defined by the compiler when DFP is enabled.

All decimal floating-point built-in functions require a hardware level of at least ARCH(7).

Single precision support is limited, as noted in Table 100.

#### Table 100. Decimal floating-point instruction prototypes for IEEE operations

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>_Decimal32 __d32_abs (_Decimal32);</td>
<td>These functions return the absolute value of the parameter.</td>
</tr>
<tr>
<td>_Decimal64 __d64_abs (_Decimal64);</td>
<td></td>
</tr>
<tr>
<td>_Decimal128 __d128_abs (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>Note: Also see functions that return the negative absolute value and functions that return the absolute value of the first parameter with the sign of the second parameter</td>
<td></td>
</tr>
<tr>
<td>_Decimal32 __d32_copysign</td>
<td>These functions return the absolute value of the first parameter, with the sign of the second parameter.</td>
</tr>
<tr>
<td>(_Decimal32 exponent_and_fraction, _Decimal32 sign);</td>
<td></td>
</tr>
<tr>
<td>_Decimal64 __d64_copysign</td>
<td></td>
</tr>
<tr>
<td>(_Decimal64 exponent_and_fraction, _Decimal64 sign);</td>
<td></td>
</tr>
<tr>
<td>_Decimal128 __d128_copysign</td>
<td></td>
</tr>
<tr>
<td>(_Decimal128 exponent_and_fraction, _Decimal128 sign);</td>
<td></td>
</tr>
<tr>
<td>_Decimal32 __d32_sNaN (void);</td>
<td>These functions create quiet or signaling NaNs of the specified precision, with positive signs and zero payloads.</td>
</tr>
<tr>
<td>_Decimal64 __d64_sNaN (void);</td>
<td></td>
</tr>
<tr>
<td>_Decimal128 __d128_sNaN (void);</td>
<td></td>
</tr>
<tr>
<td>_Decimal32 __d32_qNaN (void);</td>
<td></td>
</tr>
<tr>
<td>_Decimal64 __d64_qNaN (void);</td>
<td></td>
</tr>
<tr>
<td>_Decimal128 __d128_qNaN (void);</td>
<td></td>
</tr>
</tbody>
</table>
### Table 100. Decimal floating-point instruction prototypes for IEEE operations (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>_Decimal64 __d64_integral (_Decimal64);</code></td>
<td>These functions round a decimal floating point value to an integer value in decimal floating point format; any digits after the decimal point are discarded. The current rounding mode is used.</td>
</tr>
<tr>
<td><code>_Decimal128 __d128_integral (_Decimal128);</code></td>
<td></td>
</tr>
<tr>
<td><code>_Decimal64 __d64_integral_no_inexact (_Decimal64);</code></td>
<td></td>
</tr>
<tr>
<td><code>_Decimal128 __d128_integral_no_inexact (_Decimal128);</code></td>
<td></td>
</tr>
<tr>
<td>The functions <code>__d64_integral</code> and <code>__d128_integral</code> allow an inexact exception. The instruction M4 bit 21 is set to 0.</td>
<td></td>
</tr>
<tr>
<td>The functions <code>__d64_integral_no_inexact</code> and <code>__d128_integral_no_inexact</code> suppress any inexact exception. The instruction M4 bit 21 is set to 1.</td>
<td></td>
</tr>
<tr>
<td>All these functions set the instruction M4 bit 20 to 0. If the input is a signaling NaN it is converted to a quiet NaN.</td>
<td></td>
</tr>
<tr>
<td><code>_Decimal64 __d64_quantize (_Decimal64, _Decimal64, long round_mode);</code></td>
<td>These functions return the arithmetic value of the first parameter, with the exponent adjusted to match the second parameter. They can temporarily override the current rounding mode and use the specified rounding mode.</td>
</tr>
<tr>
<td><code>_Decimal128 __d128_quantize (_Decimal128, _Decimal128, long round_mode);</code></td>
<td></td>
</tr>
<tr>
<td>The round_mode parameter must be a compile-time constant expression. Use either of the following:</td>
<td></td>
</tr>
<tr>
<td>• DFP_ROUND_USING_CURRENT_MODE (8) to use the current rounding mode.</td>
<td></td>
</tr>
<tr>
<td>• One of the values that can be set by __dfp_set_round_mode to temporarily override the current rounding mode. See &quot;Definitions that support FPC register-rounding macros&quot; on page 542.</td>
<td></td>
</tr>
<tr>
<td><code>bool __d64_same_quantum (_Decimal64, _Decimal64);</code></td>
<td>These functions compare the exponents of two parameters. If the exponents are the same, the functions return &quot;true&quot;.</td>
</tr>
<tr>
<td><code>bool __d128_same_quantum (_Decimal128, _Decimal128);</code></td>
<td></td>
</tr>
<tr>
<td><code>long __d64_compare_signaling (_Decimal64, _Decimal64);</code></td>
<td>These functions compare two decimal floating-point values. Unlike a comparison using standard equality or relational operators, they also raise an Invalid Operation exception when either operand is either a quiet NaN or a signaling NaN.</td>
</tr>
<tr>
<td><code>long __d128_compare_signaling (_Decimal128, _Decimal128);</code></td>
<td></td>
</tr>
</tbody>
</table>
Table 100. Decimal floating-point instruction prototypes for IEEE operations (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>long long __d64_to_long_long (_Decimal64);</td>
<td>These functions convert a 64-bit signed binary integer with decimal floating point value.</td>
</tr>
<tr>
<td>long long __d128_to_long_long (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>long long __d64_to_long_long_rounding (_Decimal64, long round_mode);</td>
<td></td>
</tr>
<tr>
<td>long long __d128_to_long_long_rounding (_Decimal128, long round_mode);</td>
<td></td>
</tr>
<tr>
<td>The functions __d64_to_long_long ( ) and __d128_to_long_long ( ) use the current decimal rounding mode, while a cast always rounds towards zero.</td>
<td></td>
</tr>
<tr>
<td>The functions __d64_to_long_long_rounding ( ) and __d128_to_long_long_rounding ( ) can temporarily override the current rounding mode and use the specified rounding mode.</td>
<td></td>
</tr>
<tr>
<td>The round_mode parameter must be a compile-time constant expression. Use either of the following:</td>
<td></td>
</tr>
<tr>
<td>• DFP_ROUND_USING_CURRENT_MODE (8) to use the current rounding mode.</td>
<td></td>
</tr>
<tr>
<td>• One of the values that can be set by __dfp_set_round_mode to temporarily override the current rounding mode. See “Definitions that support FPC register-rounding macros” on page 542.</td>
<td></td>
</tr>
<tr>
<td>unsigned long __dfp_get_round_mode (void);</td>
<td>This function gets the current decimal rounding mode from the z/Architecture FPC register.</td>
</tr>
<tr>
<td>Note: See “Definitions that support FPC register-rounding macros” on page 542</td>
<td></td>
</tr>
<tr>
<td>void __dfp_set_round_mode (unsigned long round_mode);</td>
<td>This function sets the specified decimal rounding mode in the z/Architecture FPC register, making it the current mode.</td>
</tr>
<tr>
<td>If the rounding mode is changed within a function, it must be restored before the function returns.</td>
<td></td>
</tr>
<tr>
<td>Note: See “Definitions that support FPC register-rounding macros” on page 542</td>
<td></td>
</tr>
</tbody>
</table>

Table 101. Decimal floating-point instruction prototypes for IEEE operations

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>bool __d32_isfinite (_Decimal32);</td>
<td>These functions return &quot;true&quot; if the parameter is not positive or negative infinity, and is not a NaN.</td>
</tr>
<tr>
<td>bool __d64_isfinite (_Decimal64);</td>
<td></td>
</tr>
<tr>
<td>bool __d128_isfinite (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>bool __d32_isinf (_Decimal32);</td>
<td>These functions return &quot;true&quot; if the parameter is positive or negative infinity.</td>
</tr>
<tr>
<td>bool __d64_isinf (_Decimal64);</td>
<td></td>
</tr>
<tr>
<td>bool __d128_isinf (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>bool __d32_isnormal (_Decimal32);</td>
<td>These functions return &quot;true&quot; if the parameter is in the normal range, not a subnormal, infinity or NaN.</td>
</tr>
<tr>
<td>bool __d64_isnormal (_Decimal64);</td>
<td></td>
</tr>
<tr>
<td>bool __d128_isnormal (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>bool __d32_issignaling (_Decimal32);</td>
<td>These functions return &quot;true&quot; if the parameter is positive or negative signaling NaN.</td>
</tr>
<tr>
<td>bool __d64_issignaling (_Decimal64);</td>
<td></td>
</tr>
<tr>
<td>bool __d128_issignaling (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>bool __d32_issigned (_Decimal32);</td>
<td>These instructions return &quot;true&quot; if the parameter is negative, including negative zero, negative infinity and negative NaN.</td>
</tr>
<tr>
<td>bool __d64_issigned (_Decimal64);</td>
<td></td>
</tr>
<tr>
<td>bool __d128_issigned (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>bool __d32_issubnormal (_Decimal32);</td>
<td>These functions return &quot;true&quot; if the parameter is a subnormal.</td>
</tr>
<tr>
<td>bool __d64_issubnormal (_Decimal64);</td>
<td></td>
</tr>
<tr>
<td>bool __d128_issubnormal (_Decimal128);</td>
<td></td>
</tr>
</tbody>
</table>
### Table 101. Decimal floating-point instruction prototypes for IEEE...is operations (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>bool __d32_iszero (Decimal32);</td>
<td>These functions return &quot;true&quot; if the parameter is positive or negative zero.</td>
</tr>
<tr>
<td>bool __d64_iszero (Decimal64);</td>
<td></td>
</tr>
<tr>
<td>bool __d128_iszero (Decimal128);</td>
<td></td>
</tr>
</tbody>
</table>

### Table 102. Decimal floating-point instruction prototypes for IBM Instructions

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>_Decimal32 __d32_nabs (Decimal32);</td>
<td>These functions return the negative of the absolute value of the parameter.</td>
</tr>
<tr>
<td>_Decimal64 __d64_nabs (Decimal64);</td>
<td></td>
</tr>
<tr>
<td>_Decimal128 __d128_nabs (Decimal128);</td>
<td></td>
</tr>
</tbody>
</table>

**Note:** Also see functions that return the absolute value and functions that return the absolute value of the first parameter with the sign of the second parameter.

| long long __d32_to_gpr (Decimal32); | These functions transfer a value from an FPR or FPR pair to a GPR, GPR pair, or four GPRs. |
| long long __d64_to_gpr (Decimal64); |
| void __d128_to_gprs (Decimal128, long long *upper, long long *lower); |

**Note:** Also see functions that transfer a value from GPRs.

| _Decimal32 __gpr_to_d32 (long long); | These functions transfer a value from a GPR, GPR pair, or four GPRs to an FPR or FPR pair. |
| _Decimal64 __gpr_to_d64 (long long); |
| _Decimal128 __gprs_to_d128 (long long upper, long long lower); |

**Note:** Also see functions that transfer a value to GPRs.

| _Decimal32 __d64_round_to_d32 (_Decimal64, unsigned long round_mode, bool suppress_invalid); | These functions convert a value to a narrower format, with rounding control and invalid exception control that is unavailable when using a cast. |
| _Decimal64 __d128_round_to_d64 (_Decimal128, unsigned long round_mode, bool suppress_invalid); |

The round_mode parameter must be a compile-time constant expression. Use either of the following:

- DFP_ROUND_USING_CURRENT_MODE (8) to use the current rounding mode.
- One of the values that can be set by __dfp_set_round_mode to temporarily override the current rounding mode. See "Definitions that support FPC register-rounding macros" on page 542.

If the input value is a signaling NaN, and:

- If suppress_invalid is false, the result will be a quiet NaN and an invalid operation exception will be raised.
- If suppress_invalid is true, the result will be a signaling NaN and no exception will be raised.
Table 102. Decimal floating-point instruction prototypes for IBM Instructions (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>long long __d64_to_signed_BCD (_Decimal64, bool CF);</code></td>
<td>These functions convert the lower digits of the parameter to signed packed format.</td>
</tr>
<tr>
<td><code>void __d128_to_signed_BCD (_Decimal128, bool CorF, unsigned long long *upper, unsigned long long *lower);</code></td>
<td></td>
</tr>
<tr>
<td><code>__d64_to_signed_BCD</code> produces 15 decimal digits followed by a decimal sign in a 64-bit result.</td>
<td></td>
</tr>
<tr>
<td><code>__d128_to_signed_BCD</code> produces 31 decimal digits followed by a decimal sign in a 128-bit result.</td>
<td></td>
</tr>
<tr>
<td>Negative values will be given the sign 0xD.</td>
<td></td>
</tr>
<tr>
<td>If CorF is false, positive values will be given the sign 0xC.</td>
<td></td>
</tr>
<tr>
<td>If CorF is true, positive values will be given the sign 0xF.</td>
<td></td>
</tr>
<tr>
<td><code>_Decimal64 __signed_BCD_to_d64 (signed long long);</code></td>
<td>These functions convert signed packed decimal to decimal floating point.</td>
</tr>
<tr>
<td><code>_Decimal128 __signed_BCD_to_d128 (signed long long upper, signed long long lower);</code></td>
<td></td>
</tr>
<tr>
<td>The signs 0xA, 0xC, 0xE, and 0xF will be treated as positive, and 0xB and 0xD as negative.</td>
<td></td>
</tr>
<tr>
<td><code>__signed_BCD_to_d64</code> converts 15 decimal digits followed by a decimal sign in a 64-bit input.</td>
<td></td>
</tr>
<tr>
<td><code>__signed_BCD_to_d128</code> converts 31 decimal digits followed by a decimal sign in a 128-bit input.</td>
<td></td>
</tr>
<tr>
<td><code>_Decimal64 __unsigned_BCD_to_d64 (unsigned long long);</code></td>
<td>These functions convert the lower digits of the parameter to unsigned packed format.</td>
</tr>
<tr>
<td><code>_Decimal128 __unsigned_BCD_to_d128 (unsigned long long upper, unsigned long long lower);</code></td>
<td></td>
</tr>
<tr>
<td><code>__unsigned_BCD_to_d64</code> converts 16 decimal digits with no sign in a 64-bit input.</td>
<td></td>
</tr>
<tr>
<td><code>__unsigned_BCD_to_d128</code> converts 32 decimal digits with no sign in a 128-bit input.</td>
<td></td>
</tr>
<tr>
<td><code>_Decimal64 _d64_reround (_Decimal64, unsigned long number_of_digits, unsigned long round_mode);</code></td>
<td>These functions round a value to fewer digits. They can temporarily override the current rounding mode. For correct rounding, the input value must have been calculated using ROUND_TO_PREPARE_FOR SHORTER_PRECISION. See “Definitions that support FPC register-rounding macros” on page 542.</td>
</tr>
<tr>
<td><code>_Decimal128 _d128_reround (_Decimal128, unsigned long number_of_digits, unsigned long round_mode);</code></td>
<td></td>
</tr>
<tr>
<td>PROTOTYPE and Notes</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------</td>
<td>-------------</td>
</tr>
<tr>
<td>__d64_insert_biased_exponent (_Decimal64, long biased_exponent);</td>
<td>These functions return the digits and sign of the first parameter with the biased exponent of the second parameter, with special values for infinity, quiet NaN, or signaling NaN.</td>
</tr>
<tr>
<td>__d128_insert_biased_exponent (_Decimal128, long biased_exponent);</td>
<td></td>
</tr>
<tr>
<td><strong>Notes:</strong></td>
<td></td>
</tr>
<tr>
<td>1. Also see the functions that return the exponent of a specified parameter</td>
<td></td>
</tr>
<tr>
<td>2. For the type definitions of infinity, quiet NaN, or signaling NaN, see “Biased exponent definitions” on page 542.</td>
<td></td>
</tr>
</tbody>
</table>

| __d64_shift_left (_Decimal64, unsigned long number_of_digits); | These functions return the parameter with the coefficient shifted to the left. The sign and exponent are unchanged. The shift count must be in the 0-to-63 range; otherwise the result is undefined. |
| __d128_shift_left (_Decimal128, unsigned long number_of_digits); | |
| **Note:** Also see functions that return the parameter with the coefficient shifted to the right | |

| __d64_shift_right (_Decimal64, unsigned long number_of_digits); | These functions return the parameter with the coefficient shifted to the right. The sign and exponent are unchanged. The shift count must be in the 0-to-63 range; otherwise the result is undefined. |
| __d128_shift_right (_Decimal128, unsigned long number_of_digits); | |
| **Note:** Also see functions that return the parameter with the coefficient shifted to the left | |

| __d32_test_data_class (_Decimal32, unsigned long data_class_mask); | These functions determine whether a parameter is in a defined data class or a set of data classes, by testing its exponent and sign. |
| __d64_test_data_class (_Decimal64, unsigned long data_class_mask); | |
| __d128_test_data_class (_Decimal128, unsigned long data_class_mask); | |

These functions:
- Determine the exponent type (zero, subnormal, normal, infinity, quiet NaN or signaling NaN) and sign of the value.
- Return a long integer that indicates whether the exponent matches the mask specifications. If there is a match, the function returns "1"; if there is no match, the function returns "0".
**Note:** The mask must be a constant expression at compile time. See “Test Data Class masks” on page 543.

Also see test data group functions.
<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>long __d32_test_data_group (_Decimal32, unsigned long data_group_mask);</td>
<td>These functions determine whether a parameter is in a defined data group or set of data groups, by testing its exponent, sign and first digit.</td>
</tr>
<tr>
<td>long __d64_test_data_group (_Decimal64, unsigned long data_group_mask);</td>
<td></td>
</tr>
<tr>
<td>long __d128_test_data_group (_Decimal128, unsigned long data_group_mask);</td>
<td></td>
</tr>
<tr>
<td>These functions: • Determine the exponent type (safe zero, subnormal, normal with no leading zero, or an infinity or NaN), as well as the sign and first digit of the parameter. Notes: 1. A &quot;safe zero&quot; has leading zero digits and a non-extreme exponent. 2. A &quot;subnormal&quot; can appear as either an extreme non-zero or a safe non-zero. • Return a long integer that indicates whether the exponent matches the mask specifications. If there is a match, the function returns &quot;1&quot;; if there is no match, the function returns &quot;0&quot;. Note: The mask must be a constant expression at compile time. For the statements that define these masks, see “Test Data Group masks” on page 543. Also see the test data class functions.</td>
<td></td>
</tr>
<tr>
<td>long __d64_biased_exponent (_Decimal64);</td>
<td>These functions return the exponent of the parameter as an integer.</td>
</tr>
<tr>
<td>long __d128_biased_exponent (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>Notes: 1. Also see functions that return the digits and sign of the first parameter with the biased exponent of the second parameter 2. See “Biased exponent definitions” on page 542.</td>
<td></td>
</tr>
<tr>
<td>unsigned long long __d64_to_unsigned_BCD (_Decimal64);</td>
<td>These functions convert the lower digits of the parameter to unsigned packed format.</td>
</tr>
<tr>
<td>void __d128_to_unsigned_BCD (_Decimal128, bool CorF, unsigned long long *upper, unsigned long long *lower);</td>
<td></td>
</tr>
<tr>
<td>Positive values will be given the sign 0xC if CorF is false or 0xF if it is true. Negative values will be given the sign 0xD. __d64_to_unsigned_BCD produces 16 decimal digits with no sign in a 64-bit result. __d128_to_unsigned_BCD produces 32 decimal digits with no sign in a 128-bit result. Note: Any digits to the left of those are ignored. To access the ignored digits, use the appropriate d#_shift_right function.</td>
<td></td>
</tr>
<tr>
<td>long __d64_compare_exponents (_Decimal64, _Decimal64);</td>
<td>These functions compare exponents to one another.</td>
</tr>
<tr>
<td>long __d128_compare_exponents (_Decimal128, _Decimal128);</td>
<td></td>
</tr>
<tr>
<td>If both exponents are finite, these return &quot;&lt;0&quot;, &quot;==0&quot; or &quot;&gt;0&quot; to indicate the relation between the exponents. If both exponents are infinite, they return &quot;0&quot;. If one exponent is infinite and the other is finite, they return &quot;-2&quot; (unordered).</td>
<td></td>
</tr>
</tbody>
</table>
Table 102. Decimal floating-point instruction prototypes for IBM Instructions (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>long __d64_extract_significance (_Decimal64);</td>
<td>These functions normally return the number of significant digits in the input value.</td>
</tr>
<tr>
<td>long __d128_extract_significance (_Decimal128);</td>
<td></td>
</tr>
<tr>
<td>void __SFASR (unsigned long);</td>
<td>This function modifies the Floating Point Control (FCP) register, and could raise an exception.</td>
</tr>
</tbody>
</table>

Note: See “Definitions that support FPC register-rounding macros” on page 542.

IBM zEnterprise® EC12 provides hardware instructions for conversions between decimal floating-point and zoned types. When both the DFP and ARCH(10) compiler options are in effect, the following hardware built-in functions are available:

Table 103. Instruction prototypes for conversions between decimal floating-point and zoned types

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>_Decimal64 __cdzt(void* source, unsigned char length, const unsigned char mask);</td>
<td>These functions convert zoned type to decimal floating-point type.</td>
</tr>
<tr>
<td>_Decimal128 __cxzt(void* source, unsigned char length, const unsigned char mask);</td>
<td></td>
</tr>
</tbody>
</table>

The source points to the memory location that contains data in valid zoned format.

The length specifies the length of the source field encoded in the machine instruction. The range of the length value can be "0-15" for __cdzt and "0-33" for __cxzt. When the length value is not a literal, an EX instruction is generated to execute a target CDZT or CXZT instruction.

The mask value provides the M3 value encoded in the machine instruction. The mask value must be provided as a literal.

The return value is the converted decimal floating-point value.
Table 103. Instruction prototypes for conversions between decimal floating-point and zoned types (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>int __czdt(_Decimal64 source, void* result, unsigned char length, const unsigned char mask);</td>
<td>These functions convert decimal floating-point type to zoned type.</td>
</tr>
<tr>
<td>int __czxt(_Decimal128 source, void* result, unsigned char length, const unsigned char mask);</td>
<td></td>
</tr>
</tbody>
</table>

The source contains the decimal floating-point value to be converted.

The result points to the memory location that receives the converted data in zoned format.

The length specifies the number of rightmost digits of the decimal floating-point value to be converted. The length value specifies the length of the result field encoded in the machine instruction in bytes. The range of the length value can be "0-15" for __czdt and "0-33" for __czxt. When the length value is not a literal, an EX instruction is generated to execute a target CZDT or CZXT instruction.

The mask value provides the M3 value encoded in the machine instruction. The mask value must be provided as a literal.

The return value is the condition code set by the instruction.

### Macros for use with decimal floating-point built-in functions

You do not need to include a header file before you can use these macros.

### Definitions that support FPC register-rounding macros

Hardware built-in functions described in Table 100 on page 534 use the specified decimal rounding mode in the z/Architecture FPC register, making it the current mode. Figure 151 lists the statements that define those decimal rounding modes.

```c
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 0
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 1
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 2
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 3
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 4
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 5
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 6
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 7
#define DFP_ROUND_TO_NEAREST_WITH_TIES_TOWARDZERO 8
```

Figure 151. z/Architecture FPC register-rounding mode definitions

**Note:** DFP_ROUND_USING_CURRENT_MODE applies the rounding mode currently set in the z/Architecture FPC register. It is for use in functions that can temporarily override the specified rounding mode.

### Biased exponent definitions

Hardware built-in functions that return biased exponents use special values to identify or specify the exponent type. An exponent type could be integer, infinity, quiet NaN, or signaling NaN. These functions are described in Table 102 on page 537.
Figure 152 lists the statements that define those special values.

```c
#define DFP_BIASED_EXPONENT_Finite 0 /* integer type exponent plus bias */
#define DFP_BIASED_EXPONENT_INFINITY -1
#define DFP_BIASED_EXPONENT_QNAN -2
#define DFP_BIASED_EXPONENT_SNAN -3
```

*Figure 152. Biased exponent type definitions*

**Test Data Class masks**

Test Data Class functions, which test the exponent of a parameter, must be used with at least one Test Data Class mask. Test Data Class functions are described in Table 102 on page 537.

The following supplied masks look for an exponent with a specific type and sign:

- `DFP_Z_DATA_CLASS_POSITIVE_ZERO`
- `DFP_Z_DATA_CLASS_NEGATIVE_ZERO`
- `DFP_Z_DATA_CLASS_POSITIVE_SUBNORMAL`
- `DFP_Z_DATA_CLASS_NEGATIVE_SUBNORMAL`
- `DFP_Z_DATA_CLASS_POSITIVE_NORMAL`
- `DFP_Z_DATA_CLASS_NEGATIVE_NORMAL`
- `DFP_Z_DATA_CLASS_POSITIVE_INFINITY`
- `DFP_Z_DATA_CLASS_NEGATIVE_INFINITY`
- `DFP_Z_DATA_CLASS_POSITIVE_QIANT_NAN`
- `DFP_Z_DATA_CLASS_NEGATIVE_QIANT_NAN`
- `DFP_Z_DATA_CLASS_POSITIVE_SIGNALING_NAN`
- `DFP_Z_DATA_CLASS_NEGATIVE_SIGNALING_NAN`

*Figure 153. Test Data Class masks*

**Note:** A subnormal is also known as *denorm*.

To get a Test Data Class function to perform a desired test more efficiently, OR several of supplied masks together. For example, to determine whether the exponent of a parameter is any positive value, OR the following masks together:

- `DFP_Z_DATA_CLASS_POSITIVE_ZERO`
- `DFP_Z_DATA_CLASS_POSITIVE_SUBNORMAL`
- `DFP_Z_DATA_CLASS_POSITIVE_NORMAL`
- `DFP_Z_DATA_CLASS_POSITIVE_INFINITY`
- `DFP_Z_DATA_CLASS_POSITIVE_QIANT_NAN`
- `DFP_Z_DATA_CLASS_POSITIVE_SIGNALING_NAN`

**Test Data Group masks**

Test Data Group functions, which test the exponent of a parameter, must be used with at least one Test Data Group mask. Test Data Group functions are described in Table 102 on page 537.

The following supplied Test Data Group masks look for an exponent that matches a specific type, sign, and first digit:
DFP_Z_DATA_GROUP_POSITIVE_ZERO_WITH_NONEXTREME_EXPONENT
DFP_Z_DATA_GROUP_NEGATIVE_ZERO_WITH_NONEXTREME_EXPONENT
DFP_Z_DATA_GROUP_POSITIVE_ZERO_WITH_EXTREME_EXPONENT
DFP_Z_DATA_GROUP_NEGATIVE_ZERO_WITH_EXTREME_EXPONENT
DFP_Z_DATA_GROUP_POSITIVE_SUBNORMAL_OR_EXTREME_EXPONENT
DFP_Z_DATA_GROUP_NEGATIVE_SUBNORMAL_OR_EXTREME_EXPONENT
DFP_Z_DATA_GROUP_POSITIVE_NONEXTREME_EXP_LEFTMOST_ZERO
DFP_Z_DATA_GROUP_NEGATIVE_NONEXTREME_EXP_LEFTMOST_ZERO
DFP_Z_DATA_GROUP_POSITIVE_NONEXTREME_EXP_LEFTMOST_NONZERO
DFP_Z_DATA_GROUP_NEGATIVE_NONEXTREME_EXP_LEFTMOST_NONZERO
DFP_Z_DATA_GROUP_POSITIVE_INFINITY_OR_NAN
DFP_Z_DATA_GROUP_NEGATIVE_INFINITY_OR_NAN

Figure 154. Test Data Group masks

To get a Test Group Class function to perform a desired test more efficiently, OR several of supplied masks together. For example, to determine whether a parameter is an extreme exponent, OR the following masks together:

- DFP_Z_DATA_GROUP_POSITIVE_ZERO_WITH_EXTREME_EXPONENT
- DFP_Z_DATA_GROUP_NEGATIVE_ZERO_WITH_EXTREME_EXPONENT

### Hexadecimal floating-point instructions

If the FLOAT(HEX) option is in effect, these functions are intended to generate hexadecimal floating-point instructions. For more information about the instructions themselves, see chapter 18 of *z/Architecture Principles of Operation*.

If you want to use any of the following functions, your program must include `builtins.h` and be compiled with either the LANGLVL(EXTENDED) option or the LANGLVL(LIBEXT) and FLOAT(HEX) options.

**Note:** Some of these instructions also require that the ARCH option is set to a minimum level.

### Table 104. Hexadecimal floating-point instruction prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>int _cfer(int *Op1, int M3, float Op2)</td>
<td>CFER R2,M3,Op2 LR +Op3,R2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int _cfdr(int *Op1, int M3, double Op2)</td>
<td>CFDR R2,M3,Op2 LR +Op3,R2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int _cfxr(int *Op1, int M3, long double Op2)</td>
<td>CFXR R2,M3,Op2 LR +Op3,R2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>float __fier(float Op2)</td>
<td>FIER F1,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>double __fidr(double Op2)</td>
<td>FIDR F1,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>long double __fixr(long double Op2)</td>
<td>FIXR F1,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __lnxr(long double *Op1, long double Op2)</td>
<td>LDR F1,*Op1 LNXR F1,Op2 LDR +Op1,F1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Binary floating-point instructions

These functions are intended to generate binary floating-point instructions. These instructions will only be generated if the FLOAT(IEEE) option is in effect. For more information about the instructions themselves, see chapter 19 of *z/Architecture Principles of Operation*.

If you want to use any of the following functions, your program must include `builtins.h` and be compiled with either the `LANGLVL(EXTENDED)` option or the `LANGLVL(LIBEXT)` and `FLOAT(IEEE)` options.

#### Binary floating-point instruction prototypes

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>int __lndr(double *Op1, double Op2)</code></td>
<td>LDR F1,Op1</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td>LNDR F1,Op2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>LDR +Op1,F1</td>
<td></td>
</tr>
<tr>
<td><code>int __lptr(double *Op1, double Op2)</code></td>
<td>LDR F1,Op1</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td>LPDR F1,Op2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>LDR +Op1,F1</td>
<td></td>
</tr>
<tr>
<td><code>int __lpdr(long double *Op1, long double Op2)</code></td>
<td>LDR F1,Op1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td>LPXR F1,Op2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>LDR +Op1,F1</td>
<td></td>
</tr>
<tr>
<td><code>int __lper(float *Op1, float Op2)</code></td>
<td>LER F1,Op1</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td>LNER F1,Op2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>LER +Op1,F1</td>
<td></td>
</tr>
<tr>
<td><code>float __sqer(float Op2)</code></td>
<td>SQER F1,Op2</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>The return value is the square root.</td>
<td>or above</td>
<td></td>
</tr>
<tr>
<td><code>double __sqdr(double Op2)</code></td>
<td>SQDR F1,Op2</td>
<td>ARCH(0)</td>
</tr>
<tr>
<td>The return value is the square root.</td>
<td>or above</td>
<td></td>
</tr>
<tr>
<td><code>long double __sqxdr(long double Op2)</code></td>
<td>SQXR F1,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the square root.</td>
<td>or above</td>
<td></td>
</tr>
</tbody>
</table>
### Table 105. Binary floating-point instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>float __fiebr(int M3, float Op2)</td>
<td>FIEBR F1,M3,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>double __fidbr(int M3, double Op2)</td>
<td>FIDBR F1,M3,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>long double __fixbr(int M3, long double Op2)</td>
<td>FIXBR F1,M3,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __didbr(double *rem, double *quotient, double Op3, double Op4 int M4)</td>
<td>LDR F1,Op3 DIDBR F1,F3,Op4,M4 LDR *rem,F1 LDR *quotient,F3</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __lndbr(double *Op1, double Op2)</td>
<td>LDR F1,*Op1 LNDBR F1,Op2 LDR *Op1,F1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __lnxbr(long double *Op1, long double Op2)</td>
<td>LDR F1,*Op1 LNXBR F1,Op2 LDR *Op1,F1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __lpdbr(double *Op1, double Op2)</td>
<td>LDR F1,*Op1 LPDBR F1,Op2 LDR *Op1,F1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __lpxbr(long double *Op1, long double Op2)</td>
<td>LDR F1,*Op1 LPXBFR F1,Op2 LDR *Op1,F1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __diebr(float *rem, float *quotient, float Op3, float Op4, int M4)</td>
<td>LER F1,Op3 DIEBR F1,F3,Op4,M4 LER *rem,F1 LER *quotient,F3</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __lnebr(float *Op1, float Op2)</td>
<td>LER F1,*Op1 LNEBR F1,Op2 LER *Op1,F1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>int __lpebr(float *Op1, float Op2)</td>
<td>LER F1,*Op1 LPEBR F1,Op2 LER *Op1,F1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>double __madbr(double Op1, double Op2, double Op3)</td>
<td>MADBR Op1,Op3,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>double __msdbr(double Op1, double Op2, double Op3)</td>
<td>MSDBR Op1,Op3,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>The return value is the condition code.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The return value is the result.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>void __sfpc(int Op1)</td>
<td>SFPC Op1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>Only a constant literal can be passed to this built-in function.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

*Note: See "Definitions that support FPC register-rounding macros" on page 542.*
Table 105. Binary floating-point instruction prototypes (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Sample Pseudo Assembly</th>
<th>MIN ARCH</th>
</tr>
</thead>
<tbody>
<tr>
<td>float __sqebr(float Op2)</td>
<td>SQEBR F1,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>double __sqdbr(double Op2)</td>
<td>SQDBR F1,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>long double __sqxbr(long double Op2)</td>
<td>SQXBR F1,Op2</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>void __srnm(int Op1)</td>
<td>SRNM Op1</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>int __tceb(float Op1, int Op2)</td>
<td>TCEB Op1,Op2(0,0)</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>int __tcdb(double Op1, int Op2)</td>
<td>TCDB Op1,Op2(0,0)</td>
<td>ARCH(3)</td>
</tr>
<tr>
<td>int __tcxb(long double Op1, int Op2)</td>
<td>TCXB Op1,Op2(0,0)</td>
<td>ARCH(3)</td>
</tr>
</tbody>
</table>

Built-in functions for transaction execution

Transactional memory is a model for controlling concurrent memory accesses in the scope of parallel programming. In this model, you can designate a block of instructions or statements to be treated atomically. Such a block is called a transaction.

When a thread of execution executes a transaction, it is seen by other threads as an atomic block. That is, all of the memory operations within the transaction are seen to occur simultaneously. At the end of the transaction, a decision is made to commit or abort the transaction. If the transaction is committed, results are written and the execution moves on. If it is aborted, the execution branches back to the beginning of the transaction and the original register state is restored, except for a single bit to indicate that a failure has occurred. The program can decide to retry or skip the transaction.

For parallel programming, a transaction implementation can be tremendously more efficient than other implementation methods. The following built-in functions provide the ability to mark the beginning and end of transactions, and to diagnose the reasons for failure. All the functions and types here will be defined in builtins.h.
Table 106. Built-in functions for transactional memory

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>long __TM_simple_begin();</td>
<td>These functions start a transaction, a cheap transaction or an expensive one, corresponding to only some debugging capability or full debugging capability.</td>
</tr>
<tr>
<td>long __TM_begin(void* const TM_buff);</td>
<td>The return value is '0' or non-zero indicating success or failure of the transaction.</td>
</tr>
<tr>
<td>The __TM_simple_begin() function leads to the cheap kind of transaction. Cheap transactions have higher performance, but if the transaction fails, the failure information available is only the two-bit cc returned by the tbegin hardware instruction.</td>
<td></td>
</tr>
<tr>
<td>The __TM_begin(const void* TM_buff) function leads to the expensive kind of transaction. The address provided (TM_buff) must be valid. It points to a 256-byte transaction diagnostic block (TDB) containing various debug information. If the transaction fails, the TDB is populated with lots of information.</td>
<td></td>
</tr>
<tr>
<td>Note: Extensive control is provided over what state is saved and restored. These built-ins save all gpr's, and no fpr's or ar's. Using float values or ar-mode is not supported, and the facility of filtering some interrupts is not provided.</td>
<td></td>
</tr>
<tr>
<td>long __TM_end();</td>
<td>This function marks the end of a transaction.</td>
</tr>
<tr>
<td>The return value is non-zero if the thread was not in transactional state before the instruction started, and &quot;0&quot; otherwise.</td>
<td></td>
</tr>
<tr>
<td>void __TM_abort();</td>
<td>These functions abort a transaction with a failure code, or &quot;0&quot; if none is provided.</td>
</tr>
<tr>
<td>void __TM_named_abort(unsigned char const code);</td>
<td>Providing a code enables the named abort functionality. The parameter code is constrained to be 0 &lt;= code &lt;=255.</td>
</tr>
<tr>
<td>void __TM_abort_assist(unsigned int op1);</td>
<td>This function requests assistance from the processor in performing a transaction-abort assist function.</td>
</tr>
<tr>
<td>&quot;op1&quot; specifies the number of times the transaction has aborted.</td>
<td></td>
</tr>
<tr>
<td>long __TM_is_user_abort(void* const TM_buff);</td>
<td>These functions return &quot;1&quot; if the transaction failed due to a user abort instruction, otherwise &quot;0&quot;. The value returned in the parameter code is the code that was passed to the tabort instruction, or &quot;0&quot; if none was passed.</td>
</tr>
<tr>
<td>long __TM_is_named_user_abort(void* const TM_buff, unsigned char* code);</td>
<td>If the TDB specified by TM_buff is valid and the transaction abort code is &gt;=256, return &quot;true&quot; and set code to the transaction abort code minus 256, otherwise return &quot;0&quot;.</td>
</tr>
<tr>
<td>long __TM_is_illegal(void* const TM_buff);</td>
<td>Returns &quot;1&quot; if the TDB specified by TM_buff is valid and the transaction aborted due to trying to do something illegal (an instruction not permitted in transactional mode or some other kind of illegal access.)</td>
</tr>
<tr>
<td>Returns &quot;1&quot; if the TDB specified by TM_buff is valid and the transaction abort code is &quot;11&quot; or &quot;4&quot;.</td>
<td></td>
</tr>
</tbody>
</table>
Table 106. Built-in functions for transactional memory (continued)

<table>
<thead>
<tr>
<th>PROTOTYPE and Notes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>long __TM_is_footprint_exceeded(void* const TM_buff);</td>
<td>Returns &quot;1&quot; if the TDB specified by TM_buff is valid and the transaction aborted due to reaching the maximum number of cache lines, otherwise &quot;0&quot;. Returns &quot;1&quot; if the TDB pointed at by TM_buff is valid and the transaction abort code is &quot;7&quot; or &quot;8&quot;, otherwise returns &quot;0&quot;.</td>
</tr>
<tr>
<td>long __TM_nesting_depth(void* const TM_buff);</td>
<td>Returns the current nesting depth. If the thread is not in transactional mode, returns the depth at which the most recent transaction aborted, or &quot;0&quot; if it is completed successfully.</td>
</tr>
<tr>
<td>long __TM_is_nested_too_deep(void* const TM_buff);</td>
<td>Returns &quot;1&quot; if the transaction aborted due to reaching the maximum nesting depth. Returns &quot;1&quot; if the TDB pointed at by TM_buff is valid and the transaction abort code is &quot;13&quot;.</td>
</tr>
<tr>
<td>long __TM_is_conflict(void* const TM_buff);</td>
<td>Returns &quot;1&quot; if the transaction aborted due to a conflict. Returns &quot;1&quot; if the TDB pointed at by TM_buff is valid and the transaction abort code is &quot;9&quot; or &quot;10&quot;, otherwise returns &quot;0&quot;.</td>
</tr>
<tr>
<td>long __TM_is_failure_persistent(long const result);</td>
<td>Returns &quot;1&quot; if the transaction aborted due to a reason that is persistent. Returns &quot;1&quot; if result==3 (result should be the CC value returned by tbegin, which is stored in the int return value of tbegin), otherwise returns &quot;0&quot;.</td>
</tr>
<tr>
<td>long __TM_failure_address(void* const TM_buff);</td>
<td>Returns the code address at which the most recent transaction aborted. For 64 bit: returns the fourth doubleword of the TDB. For 31 bit or 24 bit: returns the rightmost word of the TDB.</td>
</tr>
<tr>
<td>long long __TM_failure_code(void* const TM_buff);</td>
<td>Returns the raw failure code. Returns bytes 8-15 of the TDB.</td>
</tr>
<tr>
<td>void __TM_non_transactional_store(void* const addr, long long const value);</td>
<td>This function indicates that 8 bytes provided by value are stored at the address pointed at by addr. The store is non-transactional.</td>
</tr>
</tbody>
</table>
Chapter 34. Hardware model and feature built-ins

The set of built-in functions identify the target hardware model and its individual features. If you have code sections that are customized for a specific hardware, you can use these built-in functions to perform a fast and efficient safety check prior to entering the customized sections.

Note: You need to add the CBC.SCCNOBJ data set to the binder SYSLIB for the resolution of these built-in functions.

**Hardware model built-in**

```c
void __builtin_cpu_init (void);
```

This built-in function checks the hardware model. It must be called at most once prior to invoking the `__builtin_cpu_is` and `__builtin_cpu_supports` built-ins.

**Hardware feature built-in**

```c
int __builtin_cpu_supports(const char* feature);
```

This built-in function returns a positive integer if the runtime CPU supports the specified feature, or returns 0 otherwise. If `__builtin_cpu_is` has not been called, this built-in function returns 0. The supported feature are:

- "longdisplacemnt"
- "etf2"
- "etf3"
- "dfp"
- "prefetch"
- "storeclockfast"
- "loadstoreoncond"
- "popcount"
- "interlocked"
- "tx"
- "dfpzoned"
- "vector128"
- "5" through "11"

**Hardware CPU built-in**

```c
int __builtin_cpu_is(const char* cpumodel);
```

This built-in function returns a positive integer if the runtime CPU supports the specified feature, or returns 0 otherwise. Supported CPU is one of the models associated with "5", "6", "7", "8", "9", "10", and "11".

**Example**

The following example shows how to use these built-in functions in source code:

```c
#include <stdio.h>
#include <builtins.h>
```
int main()
{
    __builtin_cpu_init();
    if (__builtin_cpu_supports("dfp"))
        #pragma arch_section(7)
        ....
        return SUCCESS;
}
Chapter 35. Using vector programming support

XL C/C++ V2R1M1 web deliverable for z/OS 2.1 includes vector programming support for programmers by making use of the Vector Facility for z/Architecture.

The compiler supports vector processing technologies through language extensions, based on the Altivec Programming Interface specification with suitable changes and extensions.

This chapter describes IBM XL C/C++ language extensions for vector processing support, including compiler options, vector data types and operators, macro, and built-in functions.

Options

The vector language extensions are enabled only when all of the following conditions are met:

- The ARCH(11) option is specified.
- The FLOAT(AFP(NOVOаблицITE)) option is in effect.
- The VECTOR option is specified.
- The TARGET(zOSV2R1) option or higher level is specified.

Notes:

- The VECTOR option requires z/OS V2R1 (or newer versions) with IBM z Systems z13 (or newer hardware) support.
- The VECTOR option implies LANGlvl(LONGLONG), which enables the vector bool long long, vector signed long long, vector unsigned long long, __vector bool long long, __vector signed long long, and __vector unsigned long long data types.
- The vector double and __vector double data types are only available with FLOAT(IEEE).

For more information about these compiler options, see z/OS XL C/C++ User’s Guide.

Macro

The __VEC__ macro is introduced for the vector processing support, which indicates support for vector data types. The predefined value of __VEC__ is 10205.

Vector data types

XL C/C++ V2R1M1 web deliverable for z/OS V2R1 includes vector programming support, which provides an efficient and expressive mechanism for programmers to make use of the Vector Facility for z/Architecture from the C and C++ programming languages. This section describes the supported vector data types.

In this syntax, type qualifiers and storage class specifiers can precede the keyword vector (or its alternative spelling, __vector) in a declaration. Most of the legal forms of the syntax are captured in the following diagram. Some variations have been omitted from the diagram for the sake of clarity: type qualifiers such as const
and storage class specifiers such as static can appear in any order within the declaration, as long as neither immediately follows the keyword vector (or __vector).

**Vector declaration syntax**

```
vector Bool char
__vector signed short
unsigned int
long long
double
```

**Notes:**
1. The keyword __vector is recognized with the option VECTOR, regardless of its suboptions.
2. The keyword vector is recognized with option VECTOR(TYPE).
3. The keyword bool is recognized as a valid type specifier only when preceded by the keyword vector or __vector.
4. Duplicate type specifiers are ignored in a vector declaration context.
5. The vector double and __vector double data types are only available with FLOAT(IEEE). The use of vector double or __vector double without FLOAT(IEEE) would result in a syntax error on the declaration.
6. The vector bool long long, vector signed long long, vector unsigned long long, __vector bool long long, __vector signed long long, and __vector unsigned long long data types are only available with LANGLVL(LONGLONG), which is implied by the VECTOR option.

The following table lists the supported vector data types, the size and possible values for each type.

<table>
<thead>
<tr>
<th>Type</th>
<th>Interpretation of content</th>
<th>Range of values</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>16 unsigned char</td>
<td>0..255</td>
</tr>
<tr>
<td>vector signed char</td>
<td>16 signed char</td>
<td>-128..127</td>
</tr>
<tr>
<td>vector bool char</td>
<td>16 unsigned char</td>
<td>0 (FALSE), 255 (TRUE)</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>8 unsigned short</td>
<td>0..65535</td>
</tr>
<tr>
<td>vector unsigned short int</td>
<td></td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>8 signed short</td>
<td>-32768..32767</td>
</tr>
<tr>
<td>vector signed short int</td>
<td></td>
<td></td>
</tr>
<tr>
<td>vector bool short</td>
<td>8 unsigned short</td>
<td>0 (FALSE), 65535 (TRUE)</td>
</tr>
<tr>
<td>vector bool short int</td>
<td></td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>4 unsigned int</td>
<td>0..2^31-1</td>
</tr>
</tbody>
</table>
### Table 107. Vector data types (continued)

<table>
<thead>
<tr>
<th>Type</th>
<th>Interpretation of content</th>
<th>Range of values</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed int</td>
<td>4 signed int</td>
<td>(-2^{31}..2^{31}-1)</td>
</tr>
<tr>
<td>vector bool int</td>
<td>4 unsigned int</td>
<td>0 (FALSE), (2^{32}-1) (TRUE)</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>2 unsigned long long</td>
<td>(0..2^{64}-1)</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>2 signed long long</td>
<td>(-2^{63}..2^{63}-1)</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>2 unsigned long long</td>
<td>0 (FALSE), (2^{64}-1) (TRUE)</td>
</tr>
<tr>
<td>vector double</td>
<td>2 double</td>
<td>IEEE-754 double (64 bit) precision floating-point values</td>
</tr>
</tbody>
</table>

All vector types are aligned on an 8-byte boundary. An aggregate that contains one or more vector types is aligned on an 8-byte boundary, and padded, if necessary, so that each member of vector type is also 8-byte aligned.

### Language extensions

The C/C++ language is extended to support expressions and operations that are required to act on vector data types.

#### Vector literals

A vector literal is a constant expression for which the value is interpreted as a vector type. The data type of a vector literal is represented by a parenthesized vector type, and its value is a set of constant expressions that represent the vector elements and are enclosed in parentheses or braces. When all vector elements have the same value, the value of the literal can be represented by a single constant expression. You can initialize vector types with vector literals.

#### Vector literal syntax

```
<<<(vector_type)\[\{literal_list\}\]>>>  
```

**literal_list:**

```
\[\{constant_expression\}\]  
```

The `vector_type` is a supported vector type; see "Vector data types" on page 553 for a list of these.

The `literal_list` can be either of the following expressions:

- A single expression.
  - If the single expression is enclosed with parentheses, all elements of the vector are initialized to the specified value. If the single expression is enclosed with braces, the first element of the vector is initialized to the specified value, and the remaining elements of the vector are initialized to 0.
- A comma-separated list of expressions. Each element of the vector is initialized to the respectively specified value.
The number of constant expressions is determined by the type of the vector and whether it is enclosed with braces or parentheses.

If the comma-separated list of expressions is enclosed with braces, the number of constant expressions can be equal to or less than the number of elements in the vector. If the number of constant expressions is less than the number of elements in the vector, the values of the unspecified elements are 0.

If the comma-separated list of expressions is enclosed with parentheses, the number of constant expressions must match the number of elements in the vector as follows:

2  For vector unsigned long long, vector signed long long, vector bool long long, and vector double types.
4  For vector unsigned int, vector signed int, and vector bool int types.
8  For vector unsigned short, vector signed short, and vector bool short types.
16 For vector unsigned char, vector signed char, and vector bool char types.

The following table shows the supported vector literals and how the compiler interprets them to determine their values.

### Table 108. Vector literals

<table>
<thead>
<tr>
<th>Syntax</th>
<th>Interpreted by the compiler as</th>
</tr>
</thead>
<tbody>
<tr>
<td>(vector unsigned char)(unsigned int)</td>
<td>A list of 16 unsigned 8-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector unsigned char)(unsigned int, ...)</td>
<td>A list of 16 unsigned 8-bit quantities with the value specified by each of the 16 integers.</td>
</tr>
<tr>
<td>(vector signed char)(int)</td>
<td>A list of 16 signed 8-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector signed char)(int, ...)</td>
<td>A list of 16 signed 8-bit quantities with the value specified by each of the 16 integers.</td>
</tr>
<tr>
<td>(vector bool char)(unsigned int)</td>
<td>A list of 16 unsigned 8-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector bool char)(unsigned int, ...)</td>
<td>A list of 16 unsigned 8-bit quantities with a value specified by each of the 16 integers.</td>
</tr>
<tr>
<td>(vector unsigned short)(unsigned int)</td>
<td>A list of 8 unsigned 16-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector unsigned short)(unsigned int, ...)</td>
<td>A list of 8 unsigned 16-bit quantities with a value specified by each of the 8 integers.</td>
</tr>
<tr>
<td>(vector signed short)(int)</td>
<td>A list of 8 signed 16-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector signed short)(int, ...)</td>
<td>A list of 8 signed 16-bit quantities with a value specified by each of the 8 integers.</td>
</tr>
<tr>
<td>(vector bool short)(unsigned int)</td>
<td>A list of 8 unsigned 16-bit quantities that all have the value of the single integer.</td>
</tr>
</tbody>
</table>
Table 108. Vector literals (continued)

<table>
<thead>
<tr>
<th>Syntax</th>
<th>Interpreted by the compiler as</th>
</tr>
</thead>
<tbody>
<tr>
<td>(vector bool short)(unsigned int, ...)</td>
<td>A list of 8 unsigned 16-bit quantities with a value specified by each of the 8 integers.</td>
</tr>
<tr>
<td>(vector unsigned int)(unsigned int)</td>
<td>A list of 4 unsigned 32-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector unsigned int)(unsigned int, ...)</td>
<td>A list of 4 unsigned 32-bit quantities with a value specified by each of the 4 integers.</td>
</tr>
<tr>
<td>(vector signed int)(int)</td>
<td>A list of 4 signed 32-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector signed int)(int, ...)</td>
<td>A list of 4 signed 32-bit quantities with a value specified by each of the 4 integers.</td>
</tr>
<tr>
<td>(vector bool int)(unsigned int)</td>
<td>A list of 4 unsigned 32-bit quantities that all have the value of the single integer.</td>
</tr>
<tr>
<td>(vector bool int)(unsigned int, ...)</td>
<td>A list of 4 unsigned 32-bit quantities with a value specified by each of the 4 integers.</td>
</tr>
<tr>
<td>(vector unsigned long long)(unsigned long long)</td>
<td>A list of 2 unsigned 64-bit quantities that both have the value of the single long long.</td>
</tr>
<tr>
<td>(vector unsigned long long)(unsigned long long, ...)</td>
<td>A list of 2 unsigned 64-bit quantities specified with a value by each of the 2 unsigned long longs.</td>
</tr>
<tr>
<td>(vector signed long long)(signed long long)</td>
<td>A list of 2 signed 64-bit quantities that both have the value of the single long long.</td>
</tr>
<tr>
<td>(vector signed long long)(signed long long, ...)</td>
<td>A list of 2 signed 64-bit quantities with a value specified by each of the 2 long longs.</td>
</tr>
<tr>
<td>(vector bool long long)(unsigned long long)</td>
<td>A list of 2 boolean 64-bit quantities with a value specified by the single unsigned long long.</td>
</tr>
<tr>
<td>(vector bool long long)(unsigned long long, ...)</td>
<td>A list of 2 boolean 64-bit quantities with a value specified by each of the 2 unsigned long longs.</td>
</tr>
<tr>
<td>(vector double)(double)</td>
<td>A list of 2 64-bit IEEE-754 double-precision floating-point quantities that both have the value of the single double.</td>
</tr>
<tr>
<td>(vector double)(double, double)</td>
<td>A list of 2 64-bit IEEE-754 double-precision floating-point quantities with a value specified by each of the 2 doubles.</td>
</tr>
</tbody>
</table>

**Note:** The value of an element in a vector bool is FALSE if each bit of the element is set to 0 and TRUE if each bit of the element is set to 1.
For example, for an unsigned integer vector type, the literal could be either of the following:

```c
(vector unsigned int)(10) /* initializes all four elements to a value of 10 */
(vector unsigned int)(14, 82, 73, 700) /* initializes the first element
to 14, the second element to 82,
the third element to 73, and the
fourth element to 700 */
```

You can cast vector literals with the Cast operator(). Enclosing the vector literal to be cast in parentheses can improve the readability of the code. For example, you can use the following code to cast a `vector signed int` literal to a `vector unsigned char` literal:

```c
(vector unsigned char)((vector signed int)(-1, -1, 0, 0))
```

**Initialization of vectors**

A vector type can be initialized by a vector literal, or any expression having the same vector type. For example:

```c
vector unsigned int v1;
vector unsigned int v2 = (vector unsigned int)(10);
v1 = v2;
```

A vector type can also be initialized by an initializer list.

**Vector initializer list syntax**

```c
vector_type identifier = ({initializer_list});
```

An initializer list enclosed with parentheses must have the same number of value as the number of elements of the vector type. The number of values in a braced initializer list must be less than or equal to the number of elements of the vector type. Any uninitialized element will be initialized to zero.

The following examples show vector initialization using initializer lists:

```c
vector unsigned int v1 = {1}; // initialize the first element (4 bytes) of v1
   // with 1 and the remaining 3 elements (12 bytes)
   // with zeros

vector unsigned int v2 = {1,2}; // initialize the first element (4 bytes) of v2
   // with 1, the next element (4 bytes) with 2,
   // and the remaining elements (8 bytes) with zeros

vector unsigned int v3 = {1,2,3,4}; // equivalent to the vector literal
   // (vector unsigned int) (1,2,3,4)
```

Unlike vector literals, the values in the initializer list do not have to be constant expressions unless the initialized vector variable has static duration. Thus, the following code is valid:

```c
int i=1;
int function() { return 2; }
int main()
{
   vector unsigned int v1 = {i, function();
   return 0;
}
```
typedef definitions for vector types

With a typedef declaration, you can define your own identifiers that can be used in place of type specifiers.

typedef definitions are extended to handle vector types, provided that vector support is enabled. A vector type can be used in a typedef definition, and the new type name can be used in the usual ways, except for declaring other vectors. In a vector declaration context, a typedef name is disallowed as a type specifier.

The following example illustrates a typical usage of typedef with vector types:

typedef vector unsigned short vushort4;
vushort4 v1;

For more information about typedef declaration, see typedef definitions in z/OS XL C/C++ Language Reference.

Pointers

If you dereference a pointer to a vector data type, the standard behavior of either a load or a copy of the corresponding type is performed.

Pointer arithmetic can be used on vector data types. The result of the operation p+1 is a pointer to the next vector after the vector pointed to by p.

See Pointers in z/OS XL C/C++ Language Reference for general details.

Unary expressions

Some unary expressions are extended for the vector data types.

Unary operators ++ -- + - ~

Vector data types can use some of the unary operators that are used with primitive data types, as outlined in the table below. These operators are not supported at global scope or for objects with static duration, and there is no constant folding. Each element in the vector has the operation applied to it.

<table>
<thead>
<tr>
<th>Operator</th>
<th>Integer vector types</th>
<th>Vector double</th>
<th>Bool vector types</th>
</tr>
</thead>
<tbody>
<tr>
<td>++</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>--</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>+</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>-</td>
<td>Yes (except unsigned vectors)</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>~</td>
<td>Yes</td>
<td>No</td>
<td>Yes</td>
</tr>
</tbody>
</table>

Note: Unary minus operator - on vector double will not cause IEEE exception.

For detailed information about unary operators, see Unary expressions in z/OS XL C/C++ Language Reference.

Address operator &

The & (address) operator can be used on the vector data types. It yields a pointer to the corresponding vector data type. See Address operator & in z/OS XL C/C++ Language Reference for details on the operator.
The __alignof__ operator

The __alignof__ operator is a language extension to C99 and Standard C++ that returns the position to which its operand is aligned. See the __alignof__ operator in the z/OS XL C/C++ Language Reference for details.

The operand of __alignof__ can be a vector type, provided that __vector support is enabled__. For example,

```c
vector unsigned int v1 = (vector unsigned int){10};
vctor unsigned int *pv1 = &v1;
__alignof__(v1); // vector type alignment: 8.
__alignof__(pv1); // dereferenced pointer to vector alignment: 8.
__alignof__(*pv1); // pointer to vector alignment: 4 (with ILP32) or 8 (with LP64)
__alignof__(vector signed char); // vector type alignment: 8.
```

When __attribute__((aligned)) is used to increase the alignment of a variable of vector type, the value that is returned by the __alignof__ operator is the alignment factor that is specified by __attribute__((aligned)).

The sizeof operator

The sizeof operator yields the size in bytes of the operand. See the sizeof operator in the z/OS XL C/C++ Language Reference for details.

The operand of the sizeof operator can be a vector variable, a vector type, or the result of dereferencing a pointer to vector type, provided that __vector support is enabled__. In these cases, the return value of sizeof is always 16. For example,

```c
vector bool int v1;
vector bool int *pv1 = &v1;
sizeof(v1); // vector type: 16.
sizeof(*pv1); // address of vector: 4 (with ILP32) or 8 (with LP64).
sizeof(pv1); // pointer to vector: 4 (with ILP32) or 8 (with LP64).
sizeof(vector double); // vector type: 16.
```

The typeof operator

The typeof operator returns the type of its argument, which can be an expression or a type. See the typeof operator in the z/OS XL C/C++ Language Reference for details.

It is extended to accept a vector type as its operand, when __vector support is enabled__.

The vec_step operator

The vec_step operator takes a vector type operand and returns an integer value representing the amount by which a pointer to a vector element should be incremented in order to move by 16 bytes (the size of a vector), or equivalently, the number of elements in the vector. The following table provides a summary of values by data type.

<table>
<thead>
<tr>
<th>vec_step expression</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_step(vector unsigned char)</td>
<td>16</td>
</tr>
<tr>
<td>vec_step(vector signed char)</td>
<td></td>
</tr>
<tr>
<td>vec_step(vector bool char)</td>
<td></td>
</tr>
</tbody>
</table>
Table 110. Increment value for vec_step by data type (continued)

<table>
<thead>
<tr>
<th>vec_step expression</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_step(vector unsigned short)</td>
<td>8</td>
</tr>
<tr>
<td>vec_step(vector signed short)</td>
<td></td>
</tr>
<tr>
<td>vec_step(vector bool short)</td>
<td></td>
</tr>
<tr>
<td>vec_step(vector unsigned int)</td>
<td>4</td>
</tr>
<tr>
<td>vec_step(vector signed int)</td>
<td></td>
</tr>
<tr>
<td>vec_step(vector bool int)</td>
<td></td>
</tr>
<tr>
<td>vec_step(vector unsigned long long)</td>
<td>2</td>
</tr>
<tr>
<td>vec_step(vector signed long long)</td>
<td></td>
</tr>
<tr>
<td>vec_step(vector bool long long)</td>
<td></td>
</tr>
<tr>
<td>vec_step(vector double)</td>
<td>2</td>
</tr>
</tbody>
</table>

**Binary expressions**

Some binary expressions that are used with primitive data types are extended for the vector data types.

For binary operators, each element has the operation applied to it with the same position element in the second operand. Binary operators also include assignment operators.

Table 111. Binary operators

<table>
<thead>
<tr>
<th>Operator</th>
<th>Integer vector types</th>
<th>Vector double</th>
<th>Bool vector types</th>
</tr>
</thead>
<tbody>
<tr>
<td>+</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>/</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>%</td>
<td>Yes</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>+</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>-</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>&lt;&lt;</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>&gt;&gt;</td>
<td>Yes</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>&amp;</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>^</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>[]</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
</tbody>
</table>

**Notes:**
- The [] operator returns the vector element at the position specified.
- These operators might not be portable.

For relational operators, each element has the operation applied to it with the same position element in the second operand and the results have the AND operator applied to them to get a final result of a single value. The following table provides a summary on the binary operators that can operate on some of the vector data types.
Table 112. Relational operators

<table>
<thead>
<tr>
<th>Operator</th>
<th>Integer vector types</th>
<th>Vector double</th>
<th>Bool vector types</th>
</tr>
</thead>
<tbody>
<tr>
<td>==</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>!=</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>&lt;</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>&gt;</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>&lt;=</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>&gt;=</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
</tbody>
</table>

These operators are not supported at global scope or for objects with static duration, and there is no constant folding.

The following sections provide details on each of the supported binary operators with the vector data types. For general detailed information about binary operators, see Binary expressions in z/OS XL C/C++ Language Reference.

Assignment operator =
An assignment operator stores a value in the object designated by the left operand. If either side of an assignment expression is a vector type, both sides of the expression must be of the same vector type. Therefore, the expression a = b is valid and represents assignment if a and b are of the same vector type. Otherwise, the expression is invalid, and the compiler reports an error about inconsistent data types.

Multiplication operator *
The * (multiplication) operator yields the product of its operands.

Note: This function emulates the operation on vector unsigned long long and vector signed long long.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 113. Accepted vector data types for multiplication operator *

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

Division operator /
The / (division) operator yields the algebraic quotient of its operands.

Note: This function emulates the operation on integer vector types.
The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 114. Accepted vector data types for division operator /

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

Remainder operator %
The % (remainder) operator yields the remainder from the division of the left operand by the right operand.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 115. Accepted vector data types for remainder operator %

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

Addition operator +
The + (addition) operator yields the sum of its operands.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 116. Accepted vector data types for addition operator +

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector bool char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
</tbody>
</table>
### Table 116. Accepted vector data types for addition operator + (continued)

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

### Subtraction operator -

The - (subtraction) operator yields the difference of its operands.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

### Table 117. Accepted vector data types for subtraction operator -

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>
Table 117. Accepted vector data types for subtraction operator - (continued)

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

Bitwise left shift operator <<
The << (bitwise left shift operator) performs a left shift for each element of a vector. Each element of the result vector is the result of left shifting the corresponding element of the left operand by the number of bits specified by the value specified on the right operand, or the value of the corresponding element of the right operand, modulo the number of bits in the element. The bits that are shifted out are replaced by zeros.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 118. Accepted vector data types for bitwise left shift operator <<

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>unsigned long</td>
</tr>
</tbody>
</table>

Bitwise right shift operator >>
The >> (bitwise right shift operator) performs a logical or an algebraic right shift for each element of a vector. Each element of the result vector is the result of right shifting the corresponding element of the left operand by the number of bits
specified by the value of the corresponding element of the right operand, modulo
the number of bits in the element. When the right operand is an unsigned vector
type, the bits that are shifted out are replaced by zeroes. While if the left operand
is a signed vector type, the bits that are shifted out are replaced by copies of the
most significant bit of the element of the left operand.

The following table lists the vector data types accepted as the operands, and the
corresponding returned vector data types:

Table 119. Accepted vector data types for bitwise right shift operator >>

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>unsigned long</td>
</tr>
</tbody>
</table>

Relational less than operator <

The < (relational less than operator) tests whether all elements of the left operand
are less than the corresponding elements of the right operand. The result is 1 if all
elements of the left operand are less than the corresponding elements of the right
operand. Otherwise, the result is 0.

Note: A signed comparison is performed, if either of the operands is a signed
integer vector.

The following table lists the vector data types accepted as the operands:
Table 120. Accepted vector data types for relational less than operator <

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
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<td>vector signed long long</td>
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<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

**Relational greater than operator >**

The > (relational greater than operator) tests whether all elements of the left operand are greater than the corresponding elements of the right operand. The result is 1 if all elements of the left operand are greater than the corresponding elements of the right operand. Otherwise, the result is 0.

**Note:** A signed comparison is performed, if either of the operands is a signed integer vector.

The following table lists the vector data types accepted as the operands:
Table 121. Accepted vector data types for relational greater than operator >

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
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<td>vector signed char</td>
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<td></td>
<td>vector unsigned char</td>
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<td>vector signed long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

**Relational less than or equal to operator <=**

The <= (relational less than or equal to operator) tests whether all elements of the left operand are less than or equal to the corresponding elements of the right operand. The result is 1 if all elements of the left operand are less than or equal to the corresponding elements of the right operand. Otherwise, the result is 0.

**Note:** A signed comparison is performed, if either of the operands is a signed integer vector.

The following table lists the vector data types accepted as the operands:
Table 122. Accepted vector data types for relational less than or equal to operator <=

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
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</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
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<td>vector signed char</td>
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<td>vector unsigned int</td>
<td>vector bool int</td>
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<td>vector unsigned int</td>
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<td>vector bool long long</td>
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<td>vector unsigned long long</td>
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<td>vector double</td>
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</tbody>
</table>

Relational greater than or equal to operator >=
The >= (relational greater than or equal to operator) tests whether all elements of the left operand are greater than or equal to the corresponding elements of the right operand. The result is 1 if all elements of the left operand are greater than or equal to the corresponding elements of the right operand. Otherwise, the result is 0.

Note: A signed comparison is performed, if either of the operands is a signed integer vector.

The following table lists the vector data types accepted as the operands:
### Table 123. Accepted vector data types for relational greater than or equal to operator `>=`

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
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<td>vector unsigned int</td>
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<td>vector unsigned long long</td>
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<tr>
<td>vector double</td>
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</table>

### Equality operator `==`

The `==` (equality operator) tests whether all sets of corresponding elements of the given vectors are equal. The result is 1 if each element of the left operand is equal to the corresponding element of the right operand. Otherwise, the result is 0.

The following table lists the vector data types accepted as the operands:

### Table 124. Accepted vector data types for equality operator `==`

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
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</thead>
<tbody>
<tr>
<td>vector bool char</td>
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</tbody>
</table>
### Table 124. Accepted vector data types for equality operator `==` (continued)

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
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<td>vector bool long long</td>
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<td></td>
<td>vector unsigned long long</td>
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<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

### Inequality operator `!=`

The `!=` (inequality operator) tests whether all sets of corresponding elements of the given vectors are not equal. The result is 1 if each element of the left operand is not equal to the corresponding element of the right operand. Otherwise, the result is 0.

The following table lists the vector data types accepted as the operands:

### Table 125. Accepted vector data types for inequality operator `!=`

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
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<tr>
<td></td>
<td>vector signed char</td>
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<td>vector unsigned char</td>
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<tr>
<td>vector signed char</td>
<td>vector bool char</td>
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<td></td>
<td>vector signed char</td>
</tr>
</tbody>
</table>

Chapter 35. Using vector programming support  571
Table 125. Accepted vector data types for inequality operator != (continued)

<table>
<thead>
<tr>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
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<tr>
<td>vector bool short</td>
<td>vector signed short</td>
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<td>vector signed short</td>
<td>vector bool short</td>
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<td>vector unsigned short</td>
<td>vector bool short</td>
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<td>vector bool int</td>
<td>vector bool int</td>
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<td>vector signed int</td>
<td>vector signed int</td>
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<td>vector unsigned int</td>
<td>vector signed int</td>
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<tr>
<td>vector bool long long</td>
<td>vector signed long long</td>
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<td>vector signed long long</td>
<td>vector signed long long</td>
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<td>vector unsigned long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

Bitwise AND operator &
The & (bitwise AND) operator compares each bit of its first operand to the corresponding bit of the second operand.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 126. Accepted vector data types for bitwise AND operator &

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
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<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
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<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
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<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
</tbody>
</table>
Table 126. Accepted vector data types for bitwise AND operator & (continued)

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed short</td>
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<tr>
<td></td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
</tbody>
</table>

Bitwise exclusive OR operator ^

The ^ (bitwise exclusive OR) operator compares each bit of its first operand to the corresponding bit of the second operand.

Note: vector double will not cause IEEE exception.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 127. Accepted vector data types for bitwise exclusive OR operator ^

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
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<tr>
<td>vector signed char</td>
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<td>vector signed char</td>
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<tr>
<td></td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
</tbody>
</table>
Table 127. Accepted vector data types for bitwise exclusive OR operator ^ (continued)

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector vector bool short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector bool long long</td>
<td>vector double</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector bool long long</td>
</tr>
</tbody>
</table>

Bitwise inclusive OR operator |

The | (bitwise inclusive OR) operator compares the values (in binary format) of each operand and yields a value whose bit pattern shows which bits in either of the operands has the value 1.

Note: vector double will not cause IEEE exception.

The following table lists the vector data types accepted as the operands, and the corresponding returned vector data types:

Table 128. Accepted vector data types for bitwise inclusive OR operator |

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector bool char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector bool char</td>
</tr>
</tbody>
</table>

z/OS V2R2 XL C/C++ Programming Guide
### Table 128. Accepted vector data types for bitwise inclusive OR operator |

<table>
<thead>
<tr>
<th>Result types</th>
<th>Left operand types</th>
<th>Right operand types</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector vector bool short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector bool long long</td>
<td>vector double</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td>vector bool long long</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector double</td>
</tr>
</tbody>
</table>

### Vector subscripting operator []

The [] (subscripting) operator accesses individual elements of a vector data type, similar to how array elements are accessed. The vector data type is followed by a set of square brackets containing the position of the element. The position of the first element is 0. The type of the result is the type of the elements contained in the vector type.

**Note:** If the position specified is outside of the valid range, the behavior is undefined.

Example:
vector unsigned int v1 = {1,2,3,4};
unsigned int u1, u2, u3, u4;
u1 = v1[0]; // u1=1
u2 = v1[1]; // u2=2
u3 = v1[2]; // u3=3
u4 = v1[3]; // u4=4

Note: You can also access and manipulate individual elements of vectors with the following intrinsic functions:
• vec_extract
• vec_insert
• vec_promote
• vec_splats

Cast expressions
The cast operator () is extended to support explicit type conversions from one vector data type to another vector data type. The exact same bit pattern is retained from the cast, and no conversion of the vector elements value takes place.

C++ static_cast is also extended to support type conversions between different vector types, just explicit cast operator ().

Casting between any scalar types and vector types are not allowed. To manipulate a vector element, the vector subscripting operator [], or the set of gather and scatter vector built-in functions should be used.

For more general information about casting, see Cast expression in z/OS XL C/C++ Language Reference.

Compound literal expressions
A compound literal is a postfix expression that provides an unnamed object whose value is given by an initializer list. The C99 language feature allows you to pass parameters to functions without the need for temporary variables.

A static vector variable can be initialized with a compound literal of the same type, provided that all the initializers in the initializer list are constant expressions.

For more general information about compound literal expressions, see Compound literal expressions in z/OS XL C/C++ Language Reference.

Other extensions for vector types
The following runtime library functions are also extended to support vector processing:
• setjmp() — Preserve stack environment
• longjmp() — Restore stack environment
• fprintf(), printf(), sprintf() — Format and write data
• fscanf(), scanf(), sscanf() — Read and format data
• va_arg(), va_copy(), va_end(), va_start() — Access function arguments

For detailed information about these runtime library functions, see z/OS XL C/C++ Runtime Library Reference.
Vector built-in functions

Individual elements of vectors can be accessed and manipulated by using the vector built-in functions. You must enable the vector support to use these built-in functions. This section provides description of the supported vector built-in functions.

This section uses pseudo code description to represent the built-in function syntax, as shown below:
\[ d = \text{builtin\_name}(a, b, c) \]

In the description,
- \( d \) represents the return value of the built-in function.
- \( a, b, \) and \( c \) represent the arguments of the built-in function.
- \( \text{builtin\_name} \) is the name of the built-in function.

For example, the syntax for the built-in function \( \text{vector double} = \text{vec\_xld2}(\text{long}, \text{double}*) \) is represented by \( d = \text{vec\_xld2}(a, b) \).

Allowed data types for the return value and arguments of the built-in functions are provided in the table after the description of the built-in functions.

Header file

To make use of the vector built-in functions, builtins.h must be included.

Note: The vector built-in functions are only visible when vector support is enabled. In addition, the vector built-in functions with vector bool, long long, vector signed long long, or vector unsigned long long require the LANGLVL(LONGLONG) compiler option in effect to be visible, and the vector built-in functions with vector double require the FLOAT(IEEE) compiler option in effect to be visible.

Summary of vector built-in functions

The tables below summarize and categorize the vector built-in functions.

Arithmetic

Table 129. Vector built-in functions for arithmetic

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_abs</td>
<td>Vector Absolute Value</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_add_u128</td>
<td>Vector Add unsigned 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_addc</td>
<td>Vector Add Carryout</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_addc_u128</td>
<td>Vector Add Compute Carryout unsigned 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_adde_u128</td>
<td>Vector Add With Carry unsigned 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_addec_u128</td>
<td>Vector Add With Carry Compute Carry unsigned 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_andc</td>
<td>Vector AND With Complement</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_avg</td>
<td>Vector Average</td>
<td>See detail</td>
</tr>
</tbody>
</table>
### Table 129. Vector built-in functions for arithmetic (continued)

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_checksum</td>
<td>Vector Checksum</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_gfmsum</td>
<td>Vector Galois Field Multiply Sum</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_gfmsum_128</td>
<td>Vector Galois Field Multiply Sum 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_gfmsum_accum</td>
<td>Vector Galois Field Multiply Sum and Accumulate</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_gfmsum_accum_128</td>
<td>Vector Galois Field Multiply Sum and Accumulate 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_madd</td>
<td>Vector Multiply Add</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_max</td>
<td>Vector Maximum</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_meadd</td>
<td>Vector Multiply and Add Even</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_mhadd</td>
<td>Vector Multiply and Add High</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_min</td>
<td>Vector Minimum</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_mladd</td>
<td>Vector Multiply and Add Low</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_moadd</td>
<td>Vector Multiply and Add Odd</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_msub</td>
<td>Vector Multiply Subtract</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_mule</td>
<td>Vector Multiply Even</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_mulh</td>
<td>Vector Multiply High</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_mulo</td>
<td>Vector Multiply Odd</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_nabs</td>
<td>Vector Negative Absolute</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sqrt</td>
<td>Vector Square Root</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sub_u128</td>
<td>Vector Subtract unsigned 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_subc</td>
<td>Vector Subtract Carryout</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_subc_u128</td>
<td>Vector Subtract Carryout unsigned 128-bits</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sube_u128</td>
<td>Vector Subtract with Carryout</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_subec_u128</td>
<td>Vector Subtract with Carryout, Carryout</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sum_u128</td>
<td>Vector Sum Across Quadword</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sum2</td>
<td>Vector Sum Across Doubleword</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sum4</td>
<td>Vector Sum Across Word</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Compare

**Table 130. Vector built-in functions for comparing elements**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_cmpeq</td>
<td>Vector Compare Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpeq_idx</td>
<td>Vector Compare Equal Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpeq_idx_cc</td>
<td>Vector Compare Equal Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpeq_or_0_idx</td>
<td>Vector Compare Equal or Zero Index</td>
<td>See detail</td>
</tr>
</tbody>
</table>
### Table 130. Vector built-in functions for comparing elements (continued)

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_cmpeq_or_0_idx_cc</td>
<td>Vector Compare Equal or Zero Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpge</td>
<td>Vector Compare Greater Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmplt</td>
<td>Vector Compare Less Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpne_idx</td>
<td>Vector Compare Not Equal Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpne_idx_cc</td>
<td>Vector Compare Not Equal Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpne_or_0_idx</td>
<td>Vector Compare Not Equal or Zero Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpne_or_0_idx_cc</td>
<td>Vector Compare Not Equal or Zero Index with Condition Code</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Compare Ranges

**Table 131. Vector built-in functions for comparing ranges**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_cmpnrg</td>
<td>Vector Compare Not in Ranges</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpnrg_cc</td>
<td>Vector Compare Not in Ranges with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpnrg_idx</td>
<td>Vector Compare Not in Ranges Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpnrg_idx_cc</td>
<td>Vector Compare Not in Ranges Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpnrg_or_0_idx</td>
<td>Vector Compare Not in Ranges or Zero Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmpnrg_or_0_idx_cc</td>
<td>Vector Compare Not in Ranges or Zero Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmprg</td>
<td>Vector Compare Ranges</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmprg_cc</td>
<td>Vector Compare Ranges with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmprg_idx</td>
<td>Vector Compare Ranges Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmprg_idx_cc</td>
<td>Vector Compare Ranges Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmprg_or_0_idx</td>
<td>Vector Compare Ranges or Zero Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_cmprg_or_0_idx_cc</td>
<td>Vector Compare Ranges or Zero Index with Condition Code</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Find Any Element

**Table 132. Vector built-in functions for element searching**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_find_any_eq</td>
<td>Vector Find Any Element Equal</td>
<td>See detail</td>
</tr>
</tbody>
</table>
### Table 132. Vector built-in functions for element searching (continued)

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_find_any_eq_cc</td>
<td>Vector Find Any Element Equal with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_eq_idx</td>
<td>Vector Find Any Element Equal Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_eq_idx_cc</td>
<td>Vector Find Any Element Equal Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_eq_or_0_idx</td>
<td>Vector Find Any Element Equal or Zero Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_eq_or_0_idx_cc</td>
<td>Vector Find Any Element Equal or Zero Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_ne</td>
<td>Vector Find Any Element Not Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_ne_cc</td>
<td>Vector Find Any Element Not Equal with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_ne_idx</td>
<td>Vector Find Any Element Not Equal Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_ne_idx_cc</td>
<td>Vector Find Any Element Not Equal Index with Condition Code</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_ne_or_0_idx</td>
<td>Vector Find Any Element Not Equal or Zero Index</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_find_any_ne_or_0_idx_cc</td>
<td>Vector Find Any Element Not Equal or Zero Index with Condition Code</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Gather and Scatter

**Table 133. Vector built-in functions for gathering and scattering elements**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_extract</td>
<td>Vector Extract</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_gather_element</td>
<td>Vector Gather Element</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_insert</td>
<td>Vector Insert</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_insert_and_zero</td>
<td>Vector Insert and Zero</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_perm</td>
<td>Vector Permute</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_permi</td>
<td>Vector Permute Immediate</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_promote</td>
<td>Vector Promote</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_scatter_element</td>
<td>Vector Scatter Element</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sel</td>
<td>Vector Select</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Generate Mask

**Table 134. Vector built-in functions for generating mask**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_genmask</td>
<td>Vector Generate Byte Mask</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_genmasks_8</td>
<td>Vector Generate Mask (Byte)</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_genmasks_16</td>
<td>Vector Generate Mask (Halfword)</td>
<td>See detail</td>
</tr>
</tbody>
</table>
Table 134. Vector built-in functions for generating mask (continued)

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_genmasks_32</td>
<td>Vector Generate Mask (Word)</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_genmasks_64</td>
<td>Vector Generate Mask (Doubleword)</td>
<td>See [detail]</td>
</tr>
</tbody>
</table>

Copy until Zero

Table 135. Vector built-in functions for copying until a zero is encountered

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_cp_until_zero</td>
<td>Vector Copy Until Zero</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_cp_until_zero_cc</td>
<td>Vector Copy Until Zero</td>
<td>See [detail]</td>
</tr>
</tbody>
</table>

Load and Store

Table 136. Vector built-in functions for loading and storing vectors

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_ld2f</td>
<td>Vector Load 2 float</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_load_bdry</td>
<td>Vector Load to Block Boundary</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_load_len</td>
<td>Vector Load with Length</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_load_pair</td>
<td>Vector Load Pair</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_st2f</td>
<td>Vector Store 2 float</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_store_len</td>
<td>Vector Store with Length</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_xld2</td>
<td>Vector Load 2 Doubleword</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_xlw4</td>
<td>Vector Load 4 Word</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_xstd2</td>
<td>Vector Store 2 Doubleword</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_xstw4</td>
<td>Vector Store 4 Word</td>
<td>See [detail]</td>
</tr>
</tbody>
</table>

Logical

Table 137. Vector built-in functions for logical calculation

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_cnlz</td>
<td>Vector Count Leading Zeros</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_cnttz</td>
<td>Vector Count Trailing Zeros</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_nor</td>
<td>Vector NOR</td>
<td>See [detail]</td>
</tr>
<tr>
<td>vec_popcnt</td>
<td>Vector Population Count</td>
<td>See [detail]</td>
</tr>
</tbody>
</table>

Merge

Table 138. Vector built-in functions for merging vectors

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_mergeh</td>
<td>Vector Merge High</td>
<td>See [detail]</td>
</tr>
</tbody>
</table>
### Table 138. Vector built-in functions for merging vectors (continued)

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_mergel</td>
<td>Vector Merge Low</td>
<td>[See detail]</td>
</tr>
</tbody>
</table>

### Pack and Unpack

**Table 139. Vector built-in functions for pack and unpack**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_pack</td>
<td>Vector Pack</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_packs</td>
<td>Vector Pack Saturate</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_packs_cc</td>
<td>Vector Pack Saturate Condition Code</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_packsu</td>
<td>Vector Pack Saturated Unsigned</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_packsu_cc</td>
<td>Vector Pack Saturated Unsigned Condition Code</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_unpackh</td>
<td>Vector Unpack High Element</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_unpackl</td>
<td>Vector Unpack Low Element</td>
<td>[See detail]</td>
</tr>
</tbody>
</table>

### Replicate

**Table 140. Vector built-in functions for replicating vector elements**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_splat</td>
<td>Vector Splat</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_s8</td>
<td>Vector Splat Signed Byte</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_s16</td>
<td>Vector Splat Signed Halfword</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_s32</td>
<td>Vector Splat Signed Word</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_s64</td>
<td>Vector Splat Signed Doubleword</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_u8</td>
<td>Vector Splat Unsigned Byte</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_u16</td>
<td>Vector Splat Unsigned Halfword</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_u32</td>
<td>Vector Splat Unsigned Word</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splat_u64</td>
<td>Vector Splat Doubleword</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_splats</td>
<td>Vector Splats</td>
<td>[See detail]</td>
</tr>
</tbody>
</table>

### Rotate and Shift

**Table 141. Vector built-in functions for rotate and shift**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_rl</td>
<td>Vector Element Rotate Left</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_rl_mask</td>
<td>Vector Element Rotate and Insert Under Mask</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_rli</td>
<td>Vector Element Rotate Left Immediate</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_slb</td>
<td>Vector Shift Left by Byte</td>
<td>[See detail]</td>
</tr>
<tr>
<td>vec_sld</td>
<td>Vector Shift Left Double by Byte</td>
<td>[See detail]</td>
</tr>
</tbody>
</table>
### Table 141. Vector built-in functions for rotate and shift (continued)

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_sldw</td>
<td>Vector Shift Left Double by Word</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sll</td>
<td>Vector Shift Left</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_srab</td>
<td>Vector Shift Right Arithmetic by Byte</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_sral</td>
<td>Vector Shift Right Arithmetic</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_srb</td>
<td>Vector Shift Right by Byte</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_srl</td>
<td>Vector Shift Right</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Rounding and Conversion

**Table 142. Vector built-in functions for rounding and conversion**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_ceil</td>
<td>Vector Ceiling</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_ctd</td>
<td>Vector Convert to Double</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_ctsl</td>
<td>Vector Convert to signed long long</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_ctul</td>
<td>Vector Convert to unsigned long long</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_extend_s64</td>
<td>Vector Sign Extend to Doubleword</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_floor</td>
<td>Vector Floor</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_round</td>
<td>Vector Round to Nearest</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_roundc</td>
<td>Vector Round to Current</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_roundm</td>
<td>Vector Round toward Negative Infinity</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_roundp</td>
<td>Vector Round toward Positive Infinity</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_roundz</td>
<td>Vector Round toward Zero</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_trunc</td>
<td>Vector Truncate</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Test

**Table 143. Vector built-in functions for testing**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_fp_test_data_class</td>
<td>Vector Floating-Point Test Data Class</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_test_mask</td>
<td>Vector Test under Mask</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### All Predicates

**Table 144. Vector built-in functions for searching and comparing all elements**

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_all_eq</td>
<td>All Elements Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_ge</td>
<td>All Elements Greater Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_gt</td>
<td>All Elements Greater Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_le</td>
<td>All Elements Less Than or Equal</td>
<td>See detail</td>
</tr>
</tbody>
</table>
### Table 144. Vector built-in functions for searching and comparing all elements (continued)

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_all_lt</td>
<td>All Elements Less Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_nan</td>
<td>All Elements Not a Number</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_ne</td>
<td>All Elements Not Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_nge</td>
<td>All Elements Not Greater Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_ngr</td>
<td>All Elements Not Greater Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_nle</td>
<td>All Elements Not Less Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_nlt</td>
<td>All Elements Not Less Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_all_numeric</td>
<td>All Elements Numeric</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Any Predicates

### Table 145. Vector built-in functions for searching and comparing any elements

<table>
<thead>
<tr>
<th>Function name</th>
<th>Short name description</th>
<th>More information</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec_any_eq</td>
<td>Any Element Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_ge</td>
<td>Any Element Greater Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_gt</td>
<td>Any Element Greater Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_le</td>
<td>Any Element Less Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_lte</td>
<td>Any Element Less Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_nan</td>
<td>Any Element Not a Number</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_ne</td>
<td>Any Element Not Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_nge</td>
<td>Any Element Not Greater Than or Equal</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_ngt</td>
<td>Any Element Not Greater Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_nlt</td>
<td>Any Element Not Less Than</td>
<td>See detail</td>
</tr>
<tr>
<td>vec_any_numeric</td>
<td>Any Element Numeric</td>
<td>See detail</td>
</tr>
</tbody>
</table>

### Arithmetic

This section describes built-in functions for arithmetic.

#### vec_abs: Vector Absolute Value

\[
d = \text{vec\_abs}(a)
\]

Returns a vector containing the absolute values of the contents of the given vector. The value of each element of the result is the absolute value of the corresponding element of \(a\).

**Note:** vector double will not cause IEEE exception.

#### Table 146. Vector Absolute Value

<table>
<thead>
<tr>
<th>(d)</th>
<th>(a)</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
</tbody>
</table>
Table 146. Vector Absolute Value (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_add_u128: Vector Add unsigned 128-bits**

\[ d = \text{vec_add_u128}(a, b) \]

Adds unsigned quadword values.

The function operates on vectors as 128-bit unsigned integers. It returns low 128 bits of \( a + b \).

Table 147. Vector Add unsigned 128-bits

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
</tbody>
</table>

**vec_addc: Vector Add Carryout**

\[ d = \text{vec_addc}(a, b) \]

Returns a vector containing the carry produced by adding each set of corresponding elements of the given vectors.

Each resulting element is set to 1 if there is a carry, and 0 otherwise.

Table 148. Vector Add Carryout

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

**vec_addc_u128: Vector Add Compute Carryout unsigned 128-bits**

\[ d = \text{vec_addc_u128}(a, b) \]

Gets the carry bit of the 128-bit addition of two quadword values.

This function operates on the vectors as 128-bit unsigned integers. It returns the carry out of \( a + b \).

If there is a carry on the addition, the 127-bit of \( d \) is set to 1, otherwise 0. All other bits of \( d \) are 0.

Table 149. Vector Add Compute Carryout unsigned 128-bits

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
</tbody>
</table>
**vec_adde_u128: Vector Add With Carry unsigned 128-bits**

```c
vec_adde_u128(a, b, c)
```

Adds unsigned quadword values with carry bit from the previous operation.

This function operates on the vectors as 128-bit unsigned integers. It returns low 128 bits of \( a + b + (c \& 1) \).

**Note:** Only the carry bit (127-bit) of \( c \) is used, and the other bits are ignored.

**Table 150. Vector Add With Carry unsigned 128-bits**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector</td>
<td>unsigned char</td>
<td>vector</td>
<td>unsigned char</td>
</tr>
<tr>
<td>char</td>
<td></td>
<td>char</td>
<td></td>
</tr>
</tbody>
</table>

**vec_addec_u128: Vector Add With Carry Compute Carry unsigned 128-bits**

```c
vec_addec_u128(a, b, c)
```

Gets the carry bit of the 128-bit addition of two quadword values with carry bit from a previous operation.

This function operates on the vectors as 128-bit unsigned integers. It returns the carry out of \( a + b + (c \& 1) \).

If there is a carry on this addition, the 127-bit of \( d \) is 1, otherwise 0. All other bits of \( d \) are 0.

**Note:** Only the carry bit (127-bit) of \( c \) is used, and the other bits are ignored.

**Table 151. Vector Add With Carry Compute Carry unsigned 128-bits**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector</td>
<td>unsigned char</td>
<td>vector</td>
<td>unsigned char</td>
</tr>
<tr>
<td>char</td>
<td></td>
<td>char</td>
<td></td>
</tr>
</tbody>
</table>

**vec_andc: Vector AND With Complement**

```c
vec_andc(a, b)
```

Returns the bitwise AND of the first argument \( a \) with the bitwise complement of the second argument \( b \).

**Table 152. Vector AND With Complement**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector</td>
<td>bool char</td>
<td>vector</td>
</tr>
<tr>
<td>char</td>
<td></td>
<td>bool char</td>
</tr>
<tr>
<td>vector</td>
<td>signed char</td>
<td>vector</td>
</tr>
<tr>
<td>signed char</td>
<td></td>
<td>signed char</td>
</tr>
<tr>
<td>vector</td>
<td>unsigned char</td>
<td>vector</td>
</tr>
<tr>
<td>unsigned char</td>
<td></td>
<td>unsigned char</td>
</tr>
<tr>
<td>vector</td>
<td>bool short</td>
<td>vector</td>
</tr>
<tr>
<td>bool short</td>
<td></td>
<td>bool short</td>
</tr>
</tbody>
</table>
Table 152. Vector AND With Complement (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed short</td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector bool long long</td>
<td>vector double</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td>vector bool long long</td>
</tr>
</tbody>
</table>

vec_avg: Vector Average

d = vec_avg(a, b)

Returns a vector containing the average of each set of the corresponding elements of the given vectors.

Table 153. Vector Average

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>
vec_checksum: Vector Checksum
\[ d = \text{vec checksum}(a, b) \]

Returns a vector with the 1-indexed element containing a checksum computed from the summation of all vector elements in \( a \) and the 1-indexed element of \( b \). All other vector elements will be 0.

\( \text{Table 154. Vector Checksum} \)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_gfmsum: Vector Galois Field Multiply Sum
\[ d = \text{vec gfmsum}(a, b) \]

Performs a Galois field multiply sum on each element of the given vectors.

Each element of \( a \) is multiplied in a Galois field with the corresponding element of \( b \). The Galois field has an order of two. This multiplication is similar to standard binary multiplication, but instead of adding the shifted multiplicand it is exclusive ORed. The resulting even-odd pairs of double element-sized products are exclusive ORed with each other and placed in the corresponding double-wide element of the returned vector.

\( \text{Table 155. Vector Galois Field Multiply Sum} \)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_gfmsum_128: Vector Galois Field Multiply Sum 128-bits
\[ d = \text{vec gfmsum}_128(a, b) \]

Performs a Galois field multiply sum on the 2 elements of the given vectors.

Each element of \( a \) is multiplied in a Galois field with the corresponding element of \( b \). The Galois field has an order of two. This multiplication is similar to standard binary multiplication, but instead of adding the shifted multiplicand it is exclusive ORed. The resulting 128-bits products are exclusive ORed with each other and return as a vector unsigned char.

\( \text{Table 156. Vector Galois Field Multiply Sum 128-bits} \)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

vec_gfmsum_accum: Vector Galois Field Multiply Sum and Accumulate
\[ d = \text{vec gfmsum accum}(a, b, c) \]

Performs a Galois field multiply sum and accumulate on each element of the given vectors.
Each element of a is multiplied in a Galois field with the corresponding element of b. The Galois field has an order of two. This multiplication is similar to standard binary multiplication, but instead of adding the shifted multiplicand it is exclusive ORed. The resulting even-odd pairs of double element-sized products are exclusive ORed with each other and exclusive ORed with the corresponding double-wide element of c, and returned by the function.

<table>
<thead>
<tr>
<th>Table 157. Vector Galois Field Multiply Sum and Accumulate</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
</tr>
<tr>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long</td>
</tr>
</tbody>
</table>

**vec_gfmsum_accum_128: Vector Galois Field Multiply Sum and Accumulate 128-bits**

d = vec_gfmsum_accum_128(a, b, c)

Performs a Galois field multiply sum and accumulate on the 2 elements of the given vectors.

Each element of a is multiplied in a Galois field with the corresponding element of b. The Galois field has an order of two. This multiplication is similar to standard binary multiplication, but instead of adding the shifted multiplicand it is exclusive ORed. The resulting 128-bits products are exclusive ORed with each other and exclusive ORed with the 128-bits c, and returned by the function.

<table>
<thead>
<tr>
<th>Table 158. Vector Galois Field Multiply Sum and Accumulate 128-bits</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
</tr>
<tr>
<td>vector unsigned char</td>
</tr>
</tbody>
</table>

**vec_madd: Vector Multiply Add**

d = vec_madd(a, b, c)

Returns a vector containing the results of performing a fused multiply-add operation for each corresponding set of elements of the given vectors. The value of each element of the result is the product of the values of the corresponding elements of a and b, added to the value of the corresponding element of c.

<table>
<thead>
<tr>
<th>Table 159. Vector Multiply Add</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
</tr>
<tr>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_max: Vector Maximum**

d = vec_max(a, b)

Returns a vector containing the maximum value from each set of corresponding elements of the given vectors. The value of each element of the result is the maximum of the values of the corresponding elements of a and b.

This function emulates the operation on vector double.
### Table 160. Vector Maximum

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector bool char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

### vec_meadd: Vector Multiply and Add Even

\[ d = \text{vec_meadd}(a, b, c) \]

Returns a vector containing a double element-sized results of performing a multiply-and-add operation for each of the even-indexed elements on the given vectors. The value of each element is the value of the double element-sized of the product of the values of the even-indexed elements of \( a \) and \( b \), added to the value of the corresponding element of \( c \).

### Table 161. Vector Multiply and Add Even

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>
**vec_mhadd: Vector Multiply and Add High**

\[ d = \text{vec}_\text{mhadd}(a, b, c) \]

Returns a vector containing the most significant ("high") half of the double element-sized results of performing a multiply-and-add operation for each corresponding set of elements of the given vectors. The value of each element of the result is the value of the most significant half of the double element-sized of the product of the values of the corresponding elements of \( a \) and \( b \), added to the value of the corresponding element of \( c \).

**vec_min: Vector Minimum**

\[ d = \text{vec}_\text{min}(a, b) \]

Returns a vector containing the minimum value from each set of corresponding elements of the given vectors. The value of each element of the result is the minimum of the values of the corresponding elements of \( a \) and \( b \).

This function emulates the operation on vector double.
Table 163. Vector Minimum (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
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<tr>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
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<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed long long</td>
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<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
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<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
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<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_mladd: Vector Multiply and Add Low

d = vec_mladd(a, b, c)

Returns a vector containing the least significant ("low") half of the double element-sized results of performing a multiply-and-add operation for each corresponding set of elements of the given vectors. The value of each element of the result is the value of the least significant half of the double element-sized of the product of the values of the corresponding elements of a and b, added to the value of the corresponding element of c.

Table 164. Vector Multiply and Add Low

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
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<tr>
<td></td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
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<tr>
<td>vector signed short</td>
<td>vector unsigned short</td>
<td>vector signed short</td>
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<td></td>
<td>vector signed short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
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<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
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<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
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<tr>
<td></td>
<td>vector signed int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
</tbody>
</table>

vec_moadd: Vector Multiply and Add Odd

d = vec_moadd(a, b, c)

Returns a vector containing a double element-sized results of performing a multiply-and-add operation for each of the odd-indexed elements on the given
vectors. The value of each element is the value of the double element-sized of the product of the values of the odd-indexed elements of a and b, added to the value of the corresponding element of c.

Table 165. Vector Multiply and Add Odd

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned long</td>
<td>vector unsigned int</td>
<td>vector unsigned short</td>
<td>vector unsigned long</td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed long</td>
</tr>
</tbody>
</table>

vec_msub: Vector Multiply Subtract

\[ d = \text{vec_msub}(a, b, c) \]

Returns a vector containing the results of performing a multiply-subtract operation using the given vectors. This function multiplies each element in a by the corresponding element in b, and then subtracts the corresponding element in c from the result.

Table 166. Vector Multiply Subtract

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_mule: Vector Multiply Even

\[ d = \text{vec_mule}(a, b) \]

Returns a vector containing the results of performing a multiply operation for each corresponding set of even-indexed elements of the given vectors, and extended to double element-sized of the elements.

Figure 155. Even multiply of 4 integer elements (16-bit)
Table 167. Vector Multiply Even

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
</tbody>
</table>

vec_mulh: Vector Multiply High

\[ d = \text{vec}_\text{mulh}(a, b) \]

Returns a vector containing the most significant ("high") half of results of performing a multiply operation using the given vectors. This function multiplies corresponding elements in the given vectors, the most significant half of the double element-sized product is assigned to the result of the corresponding elements in the result vector.

Table 168. Vector Multiply High

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
</tbody>
</table>

vec_mulo: Vector Multiply Odd

\[ d = \text{vec}_\text{mulo}(a, b) \]

Returns a vector containing the results of performing a multiply operation for each corresponding set of odd-indexed elements of the given vectors, and extended to double element-sized of the elements.


**Table 169. Vector Multiply Odd**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
</tbody>
</table>

**vec_nabs: Vector Negative Absolute**

d = vec_nabs(a)

Returns a vector containing the results of performing a negative-absolute operation using the given vector. This function computes the absolute value of each element in the given vector and then assigns the negated value of the result to the corresponding elements in the result vector.

**Note:** This built-in function will not cause IEEE exception.

**Table 170. Vector Negative Absolute**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_sqrt: Vector Square Root**

d = vec_sqrt(a)

Returns a vector containing the square root of each element in the given vector.

**Table 171. Vector Square Root**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>
vec_sub_u128: Vector Subtract unsigned 128-bits
\[ d = \text{vec_sub_u128}(a, b) \]
Subtracts unsigned quadword values.

This function operates on the vectors as 128-bit unsigned integers. It returns low 128 bits of \( a - b \).

<table>
<thead>
<tr>
<th>Table 172. Vector Subtract unsigned 128-bits</th>
</tr>
</thead>
<tbody>
<tr>
<td>( d )</td>
</tr>
<tr>
<td>vector unsigned char</td>
</tr>
</tbody>
</table>

vec_subc: Vector Subtract Carryout
\[ d = \text{vec_subc}(a, b) \]
Returns a vector containing the borrow produced by subtracting each of corresponding elements of \( b \) from \( a \).

On each resulting element, the value is 0 if a borrow occurred, or 1 if no borrow occurred.

<table>
<thead>
<tr>
<th>Table 173. Vector Subtract Carryout</th>
</tr>
</thead>
<tbody>
<tr>
<td>( d )</td>
</tr>
<tr>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

vec_subc_u128: Vector Subtract Carryout unsigned 128-bits
\[ d = \text{vec_subc_u128}(a, b) \]
Gets the carry bit of the 128-bit subtraction of two quadword values.

This function operates on the vectors as 128-bit unsigned integers. It returns a vector containing the borrow produced by subtracting \( b \) from \( a \), as unsigned 128-bits integers.

If no borrow occurred, the 127-bit of \( d \) is 1, otherwise 0. All other bits of \( d \) are 0.

<table>
<thead>
<tr>
<th>Table 174. Vector Subtract Carryout unsigned 128-bits</th>
</tr>
</thead>
<tbody>
<tr>
<td>( d )</td>
</tr>
<tr>
<td>vector unsigned char</td>
</tr>
</tbody>
</table>

vec_sube_u128: Vector Subtract with Carryout
\[ d = \text{vec_sube_u128}(a, b, c) \]
Subtracts unsigned quadword values with carry bit from a previous operation.

This function operates on the vectors as 128-bit unsigned integers. It returns a vector containing the result of subtracting of \( b \) from \( a \), and the carryout bit from a previous operation.
Note: Only the borrow indication bit (127-bit) of c is used, and the other bits are ignored.

Table 175. Vector Subtract with Carryout

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec unsigned char</td>
<td>vec unsigned char</td>
<td>vec unsigned char</td>
<td>vec unsigned char</td>
</tr>
</tbody>
</table>

**vec_subec_u128: Vector Subtract with Carryout, Carryout**

\[
d = \text{vec_subec_u128}(a, b, c)
\]

Gets the carry bit of the 128-bit subtraction of two quadword values with carry bit from the previous operation.

It returns a vector containing the carryout produced from the result of subtracting of b from a, and the carryout bit from a previous operation. If no borrow occurred, the 127-bit of d is 1, otherwise 0. All other bits of d are 0.

Note: Only the borrow indication bit (127-bit) of c is used, and the other bits are ignored.

Table 176. Vector Subtract with Carryout, Carryout

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec unsigned char</td>
<td>vec unsigned char</td>
<td>vec unsigned char</td>
<td>vec unsigned char</td>
</tr>
</tbody>
</table>

**vec_sum_u128: Vector Sum Across Quadword**

\[
d = \text{vec_sum_u128}(a, b)
\]

Returns a vector containing the results of performing a sum across all the elements in each of the quadword of vector a, and the rightmost word or doubleword element of the b. The result is an unsigned 128-bit integer. The result vector is obtained as follow:

For vector unsigned int operands:
\[
\]

For vector unsigned long long operands:
\[
d = a[0] + a[1] + b[1]
\]

Table 177. Vector Sum Across Quadword

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vec unsigned char</td>
<td>vec unsigned int</td>
<td>vec unsigned int</td>
</tr>
<tr>
<td>vec unsigned long long</td>
<td>vec unsigned long long</td>
<td>vec unsigned long long</td>
</tr>
</tbody>
</table>

**vec_sum2: Vector Sum Across Doubleword**

\[
d = \text{vec_sum2}(a, b)
\]

Returns a vector containing the results of performing a sum across all the elements in each of the doubleword of vector a, and the rightmost sub-element of the corresponding doubleword of b.
The result vector is obtained as follows:

For vector unsigned short operands:
\[
\]

For vector unsigned int operands:
\[
d[0] = a[0] + a[1] + b[1] \\
\]

Table 178. Vector Sum Across Doubleword

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_sum4: Vector Sum Across Word

\[d = \text{vec}_\text{sum4}(a, b)\]

Returns a vector containing the results of performing a sum across all the elements in each of the word of vector a, and the rightmost sub-element of the corresponding word of a. The result vector is obtained as follow:

For vector unsigned char operands:
\[
\]

For vector unsigned short operands:
\[
d[0] = a[0] + a[1] + b[1] \\
\]
Table 179. Vector Sum Across Word

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
</tbody>
</table>

Compare

This section describes vector built-in functions for comparing elements.

**vec_cmpeq: Vector Compare Equal**

\[ d = \text{vec_cmpeq}(a, b) \]

Returns a vector containing the results of comparing each set of corresponding elements of the given vectors for equality. For each element of the result, the value of each bit is 1 if the corresponding elements of \( a \) and \( b \) are equal. Otherwise, the value of each bit is 0.

Table 180. Vector Compare Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td></td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

**vec_cmpeq_idx: Vector Compare Equal Index**

\[ d = \text{vec_cmpeq_idx}(a, b) \]

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for equality. If the two vectors are not equal, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 181. Vector Compare Equal Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
</tbody>
</table>
Table 181. Vector Compare Equal Index (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_cmpeq_idx_cc: Vector Compare Equal Index with Condition Code

\[
d = \text{vec_cmpeq_idx_cc}(a, b, c)
\]

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for equality. If the two vectors are not equal, the result is 16. \(c\) is set to 1, if there is any elements of \(a\) equals the corresponding element of \(b\), otherwise \(c\) is set to 3.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 182. Vector Compare Equal Index with Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

vec_cmpeq_or_0_idx: Vector Compare Equal or Zero Index

\[
d = \text{vec_cmpeq_or_0_idx}(a, b)
\]

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for equality, and comparing each elements of \(a\) against 0. If the two vectors are not equal, and no elements of \(a\) is 0, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 183. Vector Compare Equal or Zero Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
</tbody>
</table>
### Table 183. Vector Compare Equal or Zero Index (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

**vec_cmpeq_or_0_idx_cc: Vector Compare Equal or Zero Index with Condition Code**

\[
d = \text{vec_cmpeq_or_0_idx_cc}(a, b, c)
\]

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for equality, and comparing each elements of \(a\) against 0. If the two vectors are not equal, and no elements of \(a\) is 0, the result is 16.

\(c\) would be set to one of the following values:
- 0 - if no elements of the 2 vectors are equal, and at least one element from \(a\) with a value of 0.
- 1 - if at least one element of \(a\) equals the corresponding element of \(b\), and no elements of \(a\) has a value of 0.
- 2 - if at least one element of \(a\) equals the corresponding element of \(b\) with an equal value, and there is at least one element from \(a\) has a value of 0.
- 3 - if no element of \(a\) equals the corresponding element of \(b\), and there is no element from \(a\) with a value of 0.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

### Table 184. Vector Compare Equal or Zero Index with Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

**vec_cmpge: Vector Compare Greater Than or Equal**

\[
d = \text{vec_cmpge}(a, b)
\]

Returns a vector containing the results of a greater-than-or-equal-to comparison between each set of corresponding elements of the given vectors. For each element
of the result, the value of each bit is 1 if the value of the corresponding element of a is greater than or equal to the value of the corresponding element of b. Otherwise, the value of each bit is 0.

This function emulates the operation on the integer vectors.

Table 185. Vector Compare Greater Than or Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_cmpgt: Vector Compare Greater Than

\[ d = \text{vec\_cmpgt}(a, b) \]

Returns a vector containing the results of a greater-than comparison between each set of corresponding elements of the given vectors. For each element of the result, the value of each bit is 1 if the value of the corresponding element of a is greater than the value of the corresponding element of b. Otherwise, the value of each bit is 0.

Table 186. Vector Compare Greater Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_cmple: Vector Compare Less Than or Equal

\[ d = \text{vec\_cmple}(a, b) \]

Returns a vector containing the results of a less-than-or-equal-to comparison between each set of corresponding elements of the given vectors. For each element of the result, the value of each bit is 1 if the value of the corresponding element of a is less than or equal to the value of the corresponding element of b. Otherwise, the value of each bit is 0.
Table 187. Vector Compare Less Than or Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_cmplt: Vector Compare Less Than

\[ d = \text{vec_cmplt}(a, b) \]

Returns a vector containing the results of a less-than comparison between each set of corresponding elements of the given vectors. For each element of the result, the value of each bit is 1 if the value of the corresponding element of \( a \) is less than the value of the corresponding element of \( b \). Otherwise, the value of each bit is 0.

This operation emulates the operation on the integer vectors.

Table 188. Vector Compare Less Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_cmpne_idx: Vector Compare Not Equal Index

\[ d = \text{vec_cmpne_idx}(a, b) \]

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for inequality. If the two vectors are equal, the result is 16.

The result is placed into byte element seven of the returned vector, all other bytes are set to 0.

Table 189. Vector Compare Not Equal Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
</tbody>
</table>
Table 189. Vector Compare Not Equal Index (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_cmpne_idx_cc: Vector Compare Not Equal Index with Condition Code

d = vec_cmpne_idx_cc(a, b, c)

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for inequality. If the two vectors are equal, the result is 16.

c is set to the following value:
- 1 - if there is a mismatch and that first element from the 0-index of a is less than the corresponding element of b.
- 2 - if there is a mismatch and that element from the 0-index of a is greater than the corresponding element of b.
- 3 - if the two vectors are equal.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 190. Vector Compare Not Equal Index with Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

vec_cmpne_or_0_idx: Vector Compare Not Equal or Zero Index

d = vec_cmpne_or_0_idx(a, b)

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for inequality, and comparing each elements of a against 0. If the two vectors are equal, and no elements of a is 0, the result is 16.
The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 191. Vector Compare Not Equal or Zero Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_cmpne_or_0_idx_cc: Vector Compare Not Equal or Zero Index with Condition Code

d = vec_cmpne_or_0_idx_cc(a, b, c)

Returns the lowest byte-index of comparing each set of corresponding elements of the given vectors for inequality, and comparing each elements of a against 0. If the two vectors are equal, and no elements of a is 0, the result is 16.

\[ c \]
\[ v_0 \] - if zero is found on an element of a, starting from the 0-index, before there is a mismatch between the corresponding elements of a and b.
\[ v_1 \] - if there is a mismatch, and that first element, from the 0-index, of a is less than the corresponding element of b, and prior to the mismatch a is not 0.
\[ v_2 \] - if there is a mismatch, and that element, from the 0-index, of a is greater than the corresponding element of b, and prior to the mismatch a is not 0.
\[ v_3 \] - if the two vectors are equal, and there is no element from a with a value of 0.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 192. Vector Compare Not Equal or Zero Index with Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>
**Compare Ranges**

This section describes vector built-in functions for comparing ranges.

**vec_cmpnrng: Vector Compare Not in Ranges**

\( d = \text{vec cmpnrng}(a, b, c) \)

Check if each element of \( a \) is not within any of the ranges specified by \( b \) and \( c \). Each even-odd element pairs of \( b \) define values for the limits of the ranges. The corresponding even-odd pairs of elements in \( c \) control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA0000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC0000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE0000000</td>
</tr>
</tbody>
</table>

For each element of the result, the value of each bit is 1 if the corresponding element of \( a \) was not contained in any of the specified ranges. Otherwise, the value of each bit is 0.

*Table 193. Vector Compare Not in Ranges*

```
<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>
```

**Example 1: Comparing 2 ranges**

```c
vector unsigned int a = {11, 22, 33, 44};
vector unsigned int b = {10, 20, 30, 40};
vector unsigned int c = {0x20000000, 0x40000000, 0x20000000,
                         0x40000000}; // {GT, LT, GT, LT}

vector bool int d = vec_cmpnrng(a, b, c);
// d = {0, 0xFFFFFFFF, 0, 0xFFFFFFFF}
```

In this example, each element of \( a \) is checked to be (> 10 AND < 20) OR (> 30 AND < 40).

**Example 2: Comparing a single range, and a specific value**

```c
vector unsigned int a = {11, 22, 33, 30};
vector unsigned int b = {10, 20, 30, 30};
vector unsigned int c = {0x20000000, 0x40000000, 0x80000000,
                         0x80000000};
```
vector bool int d = vec_cmpnrg(a, b, c);
// d = (0, 0xFFFFFFFF, 0xFFFFFFFF, 0)

In this example, each element of a is checked to be (> 10 AND < 20) OR equals to 30.

Example 3: Comparing a single range
vector unsigned int a = {11, 22, 33, 44};
vector unsigned int b = {10, 20, 30, 40};
vector unsigned int c = {0x20000000, 0x40000000, 0x00000000, 0x00000000}; // {GT, LT, X, X}

vector bool int d = vec_cmpnrg(a, b, c);
// d = (0, 0xFFFFFFFF, 0xFFFFFFFF, 0xFFFFFFFF)

In this example, each element of a is checked to be (> 10 AND < 20) only.

vec_cmpnrg_cc: Vector Compare Not in Ranges with Condition Code

e = vec_cmpnrg_cc(a, b, c, d)

Check if each element of a is not within any of the ranges specified by b and c. Each even-odd element pairs of b define values for the limits of the ranges. The corresponding even-odd pairs of elements in c control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA00000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC00000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE00000000</td>
</tr>
</tbody>
</table>

For each element of the result, the value of each bit is 1 if the corresponding element of a was not contained in any of the specified ranges. Otherwise, the value of each bit is 0.

d is set to 1, if there is at least one element of a is found not within any of the ranges. Otherwise, d is set to 3.
**Table 194. Vector Compare Not in Ranges with Condition Code**

<table>
<thead>
<tr>
<th>e</th>
<th>a</th>
<th>b</th>
<th>c</th>
<th>d</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>int *</td>
</tr>
<tr>
<td></td>
<td>char</td>
<td>char</td>
<td>char</td>
<td></td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td></td>
</tr>
<tr>
<td></td>
<td>short</td>
<td>short</td>
<td>short</td>
<td></td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td></td>
</tr>
<tr>
<td></td>
<td>int</td>
<td>int</td>
<td>int</td>
<td></td>
</tr>
</tbody>
</table>

**vec_cmpnrg_idx: Vector Compare Not in Ranges Index**

d = vec_cmpnrg_idx(a, b, c)

Returns the lowest byte-index of the element of a that is not within any of the ranges specified by b and c. Each even-odd element pairs of b define values for the limits of the ranges. The corresponding even-odd pairs of elements in c control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned</th>
<th>for vector unsigned</th>
<th>for vector unsigned</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>char</td>
<td>short</td>
<td>int</td>
</tr>
<tr>
<td>ignore - result of</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>comparison always</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TRUE</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA0000000</td>
</tr>
<tr>
<td>equal</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC0000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE0000000</td>
</tr>
</tbody>
</table>

The result is the lowest byte-index from element of a that is not contained in any of the specified ranges. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

**Table 195. Vector Compare Not in Ranges Index**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
</tr>
<tr>
<td></td>
<td>char</td>
<td>char</td>
<td>char</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
</tr>
<tr>
<td>short</td>
<td>short</td>
<td>short</td>
<td>short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
</tr>
<tr>
<td></td>
<td>int</td>
<td>int</td>
<td>int</td>
</tr>
</tbody>
</table>

Example:

```c
vector unsigned int a = {1, 11, 22, 33};
vector unsigned int b = {10, 20, 30, 40};
vector unsigned int c = {0x20000000, 0x40000000, 0x20000000, 0x40000000}; // {GT, LT, GT, LT}

vector unsigned int d = vec_cmpnrg_idx(a, b, c); // byte 7 of d = 0
```
In this example, each element of \(a\) is tested to be \(\text{NOT}((> 10 \text{ AND } < 20) \text{ OR } (>30 \text{ AND } < 40))\), the first element (byte index 0) is the first element satisfying the condition.

**vec_cmpnrg_idx_cc: Vector Compare Not in Ranges Index with Condition Code**

\[ e = \text{vec\_cmpnrg\_idx\_cc}(a, b, c, d) \]

Returns the lowest byte-index of the element of \(a\) that is not within any of the ranges specified by \(b\) and \(c\). Each even-odd element pairs of \(b\) define values for the limits of the ranges. The corresponding even-odd pairs of elements in \(c\) control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA0000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC0000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE0000000</td>
</tr>
</tbody>
</table>

\(d\) is set to 1, if there is at least one element of \(a\) is found not within any of the ranges. Otherwise, \(d\) is set to 3.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

**Table 196. Vector Compare Not in Ranges Index with Condition Code**

<table>
<thead>
<tr>
<th>(e)</th>
<th>(a)</th>
<th>(b)</th>
<th>(c)</th>
<th>(d)</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

**vec_cmpnrg_or_0_idx: Vector Compare Not in Ranges or Zero Index**

\[ d = \text{vec\_cmpnrg\_or\_0\_idx}(a, b, c) \]

Returns the lowest byte-index of the element of \(a\) that is 0 or not within any of the ranges specified by \(b\) and \(c\). Each even-odd element pairs of \(b\) define values for the limits of the ranges. The corresponding even-odd pairs of elements in \(c\) control how the comparison to be performed, in the following way:
Comparison for vector unsigned char for vector unsigned short for vector unsigned int

ignore - result of comparison always TRUE

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>equal</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA00000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC00000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE00000000</td>
</tr>
</tbody>
</table>

The result is the lowest byte-index from element of a that is 0 or not contained in any of the specified ranges. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 197. Vector Compare Not in Ranges or Zero Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Example:

vector unsigned int a = {11, 33, 0, 22};
vector unsigned int b = {10, 20, 30, 40};
vector unsigned int c = {0x20000000, 0x40000000, 0x20000000, 0x40000000}; // {GT, LT, GT, LT}

vector unsigned int d = vec_cmpnrg_or_0_idx(a, b, c); // byte 7 of d = 8

In this example, each element of a is tested to be (equals 0) OR NOT((> 10 AND < 20) OR (>30 AND < 40)), the third element (byte index 8) is the first element satisfying the condition.

vec_cmpnrg_or_0_idx_cc: Vector Compare Not in Ranges or Zero Index with Condition Code

e = vec_cmpnrg_or_0_idx_cc(a, b, c, d)

Returns the lowest byte-index of the element of a that is 0 or not within any of the ranges specified by b and c. Each even-odd element pairs of b define values for the limits of the ranges. The corresponding even-odd pairs of elements in c control how the comparison to be performed, in the following way:
### Comparison for vector unsigned char for vector unsigned short for vector unsigned int

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA00000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC00000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE00000000</td>
</tr>
</tbody>
</table>

### d is set to one of the following:

- **0** - if 0 was found on an element of a, before an element was not found within the specified range.
- **1** - if no element of a is 0, and there is at least one element of a found not in any of the ranges.
- **2** - if 0 was found on an element of a after an element was found not within the specified range.
- **3** - no element is 0 and found to be not within any of the specified range.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

### Table 198. Vector Compare Not in Ranges or Zero Index with Condition Code

<table>
<thead>
<tr>
<th>e</th>
<th>a</th>
<th>b</th>
<th>c</th>
<th>d</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>int *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

### vec_cmprg: Vector Compare Ranges

\[ d = vec_cmprg(a, b, c) \]

Check if each element of a is within any of the ranges specified by b and c. Each even-odd element pairs of b define values for the limits of the ranges. The corresponding even-odd pairs of elements in c control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
</tbody>
</table>
Comparison for vector unsigned char  
for vector unsigned short  
for vector unsigned int  
greater than 0x20 0x2000 0x20000000  
greater than or equal 0xA0 0xA000 0xA0000000  
less than 0x40 0x4000 0x40000000  
less than and equal 0xC0 0xC000 0xC0000000  
force to FALSE 0xE0 0xE000 0xE0000000

For each element of the result, the value of each bit is 1 if the corresponding element of a was contained in any of the specified ranges. Otherwise, the value of each bit is 0.

Table 199. Vector Compare Ranges

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Example 1: Comparing 2 ranges  
vector unsigned int a = {11, 22, 33, 44};  
vector unsigned int b = {10, 20, 30, 40};  
vector unsigned int c = {0x20000000, 0x40000000, 0x20000000, 0x40000000}; // {GT, LT, GT, LT}  
vector bool int d = vec_cmprg(a, b, c);  // d = {0xFFFFFFFF, 0, 0xFFFFFFFF, 0}  

In this example, each element of a is checked to be (> 10 AND < 20) OR (> 30 AND < 40).

Example 2: Comparing a single range, and a specific value  
vector unsigned int a = {11, 22, 33, 30};  
vector unsigned int b = {10, 20, 30, 30};  
vector unsigned int c = {0x20000000, 0x40000000, 0x80000000, 0x80000000}; // {GT, LT, EQ, EQ}  
vector bool int d = vec_cmprg(a, b, c);  // d = {0xFFFFFFFF, 0, 0, 0xFFFFFFFF}  

In this example, each element of a is checked to be (> 10 AND < 20) OR equals to 30.

Example 3: Comparing a single range  
vector unsigned int a = {11, 22, 33, 44};  
vector unsigned int b = {10, 20, 30, 40};  
vector unsigned int c = {0x20000000, 0x40000000, 0x00000000, 0x00000000}; // {GT, LT, X, X}  
vector bool int d = vec_cmprg(a, b, c);  // d = {0xFFFFFFFF, 0, 0, 0}  

In this example, each element of a is checked to be (> 10 AND < 20) only.
**vec_cmprg_cc: Vector Compare Ranges with Condition Code**

\[ e = \text{vec_cmprg_cc}(a, b, c, d) \]

Check if each element of \( a \) is within any of the ranges specified by \( b \) and \( c \). Each even-odd element pairs of \( b \) define values for the limits of the ranges. The corresponding even-odd pairs of elements in \( c \) control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA00000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC00000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE00000000</td>
</tr>
</tbody>
</table>

For each element of the result, the value of each bit is 1 if the corresponding element of \( a \) was contained in any of the specified ranges. Otherwise, the value of each bit is 0.

\( d \) is set to 1, if there is at least one element of \( a \) found in any of the ranges. Otherwise, \( d \) is set to 3.

*Table 200. Vector Compare Ranges with Condition Code*

<table>
<thead>
<tr>
<th>( e )</th>
<th>( a )</th>
<th>( b )</th>
<th>( c )</th>
<th>( d )</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>int *</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

**vec_cmprg_idx: Vector Compare Ranges Index**

\[ d = \text{vec_cmprg_idx}(a, b, c) \]

Returns the lowest byte-index of the element of \( a \) that is within any of the ranges specified by \( b \) and \( c \). Each even-odd element pairs of \( b \) define values for the limits of the ranges. The corresponding even-odd pairs of elements in \( c \) control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
</tbody>
</table>
### Table 201. Vector Compare Ranges Index

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA0000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC0000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE0000000</td>
</tr>
</tbody>
</table>

The result is the lowest byte-index from element of a that is contained in any of the specified ranges. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

**Example:**

```c
vector unsigned int a = {1, 11, 22, 33};
vext unsigned int b = {10, 20, 30, 40};
vext unsigned int c = {0x20000000, 0x40000000, 0x20000000, 0x40000000}; // {GT, LT, GT, LT}
vext unsigned int d = vec_cmprg_idx(a, b, c); // byte 7 of d = 4
```

In this example, each element of a is tested to be ((> 10 AND < 20) OR (>30 AND < 40)), the second element (byte index 4) is the first element satisfying the condition.

**vec_cmprg_idx_cc: Vector Compare Ranges Index with Condition Code**

```c
e = vec_cmprg_idx_cc(a, b, c, d)
```

Returns the lowest byte-index of the element of a that is within any of the ranges specified by b and c. Each even-odd element pairs of b define values for the limits of the ranges. The corresponding even-odd pairs of elements in c control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
</tbody>
</table>
d is set to 1, if there is at least one element of a found in any of the ranges. Otherwise, d is set to 3.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 202. Vector Compare Ranges Index with Condition Code

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA0000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC0000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE0000000</td>
</tr>
</tbody>
</table>

vec_cmprg_or_0_idx: Vector Compare Ranges or Zero Index

d = vec_cmprg_or_0_idx(a, b, c)

Returns the lowest byte-index of the element of a that is 0 or within any of the ranges specified by b and c. Each even-odd element pairs of b define values for the limits of the ranges. The corresponding even-odd pairs of elements in c control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of comparison always TRUE</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA0000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC0000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE0000000</td>
</tr>
</tbody>
</table>

The result is the lowest byte-index from element of a that is 0 or contained in any of the specified ranges. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.
Table 203. Vector Compare Ranges or Zero Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
</tr>
<tr>
<td>char</td>
<td>char</td>
<td>char</td>
<td>char</td>
</tr>
<tr>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
</tr>
<tr>
<td>short</td>
<td>short</td>
<td>short</td>
<td>short</td>
</tr>
<tr>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
<td>vector unsigned</td>
</tr>
<tr>
<td>int</td>
<td>int</td>
<td>int</td>
<td>int</td>
</tr>
</tbody>
</table>

Example:

```c
vector unsigned int a = {1, 0, 22, 33};
vector unsigned int b = {10, 20, 30, 40};
vector unsigned int c = {0x20000000, 0x40000000, 0x20000000,
                        0x40000000}; // {GT, LT, GT, LT}

vector unsigned int d = vec_cmprg_or_0_idx(a, b, c); // byte 7 of d = 4
```

In this example, each element of `a` is tested to be (equals to 0) OR (>10 AND <5) OR (>30 AND <40), the second element (byte index 4) is the first element satisfying the condition.

**vec_cmprg_or_0_idx_cc: Vector Compare Ranges or Zero Index with Condition Code**

```c
e = vec_cmprg_or_0_idx_cc(a, b, c, d)
```

Returns the lowest byte-index of the element of `a` that is 0 or within any of the ranges specified by `b` and `c`. Each even-odd element pairs of `b` define values for the limits of the ranges. The corresponding even-odd pairs of elements in `c` control how the comparison to be performed, in the following way:

<table>
<thead>
<tr>
<th>Comparison</th>
<th>for vector unsigned char</th>
<th>for vector unsigned short</th>
<th>for vector unsigned int</th>
</tr>
</thead>
<tbody>
<tr>
<td>ignore - result of</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>comparison always</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TRUE</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>equal</td>
<td>0x80</td>
<td>0x8000</td>
<td>0x80000000</td>
</tr>
<tr>
<td>not equal</td>
<td>0x60</td>
<td>0x6000</td>
<td>0x60000000</td>
</tr>
<tr>
<td>greater than</td>
<td>0x20</td>
<td>0x2000</td>
<td>0x20000000</td>
</tr>
<tr>
<td>greater than or equal</td>
<td>0xA0</td>
<td>0xA000</td>
<td>0xA0000000</td>
</tr>
<tr>
<td>less than</td>
<td>0x40</td>
<td>0x4000</td>
<td>0x40000000</td>
</tr>
<tr>
<td>less than and equal</td>
<td>0xC0</td>
<td>0xC000</td>
<td>0xC0000000</td>
</tr>
<tr>
<td>force to FALSE</td>
<td>0xE0</td>
<td>0xE000</td>
<td>0xE0000000</td>
</tr>
</tbody>
</table>

`d` is set to one of the following:

- 0 - if 0 was found on an element of `a`, before an element was found within the specified range.
- 1 - if no element of `a` is 0, and there is at least one element of `a` found in any of the ranges.
- 2 - if 0 was found on an element of `a` after an element was found within the specified range.
- 3 - no element is 0 and found to be within any of the specified range.
The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

**Table 204. Vector Compare Ranges or Zero Index with Condition Code**

<table>
<thead>
<tr>
<th>e</th>
<th>a</th>
<th>b</th>
<th>c</th>
<th>d</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector char</td>
<td>vector char</td>
<td>vector char</td>
<td>vector char</td>
<td>int *</td>
</tr>
<tr>
<td>vector short</td>
<td>vector short</td>
<td>vector short</td>
<td>vector short</td>
<td></td>
</tr>
<tr>
<td>vector int</td>
<td>vector int</td>
<td>vector int</td>
<td>vector int</td>
<td></td>
</tr>
</tbody>
</table>

**Find Any Element**

This section describes vector built-in functions for element searching.

**vec_find_any_eq: Vector Find Any Element Equal**

\[
d = \text{vec\_find\_any\_eq}(a, b)
\]

Find element of \(a\) from any element of \(b\) with an equal value.

For each element of the result, the value of each bit is 1 if the corresponding elements of \(a\) equal any element of \(b\). Otherwise, the value of each bit is 0.

**Table 205. Vector Find Any Element Equal**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector char</td>
<td>vector char</td>
<td>vector char</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Example:

```c
vector signed int a = {1, -2, 3, -4};
vector signed int b = {-5, 3, -7, 8};
vector bool int d = vec_find_any_eq(a, b); // d = {0, 0, 0xFFFFFFFF, 0}
```

**vec_find_any_eq_cc: Vector Find Any Element Equal with Condition Code**

\[
d = \text{vec\_find\_any\_eq\_cc}(a, b, c)
\]

Find element of \(a\) from any element of \(b\) with an equal value.

For each element of the result, the value of each bit is 1 if the corresponding elements of \(a\) equal any element of \(b\). Otherwise, the value of each bit is 0. \(c\) is set to 1, if there is at least one element of \(a\) find a match with \(b\), otherwise \(c\) is set to 3.
Table 206. Vector Find Any Element Equal with Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector bool</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector bool</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td></td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

vec_find_any_eq_idx: Vector Find Any Element Equal Index

d = vec_find_any_eq_idx(a, b)

Find the lowest byte-index of element of a from any element of b with an equal value. The result is the lowest byte-index from element of a, if it is found. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 207. Vector Find Any Element Equal Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Example 1:

vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {5, 3, 7, 8};
vector unsigned int d = vec_find_any_eq_idx(a, b); // byte 7 of d = 8

In this example, the third element (byte index 8) of a was found in the vector b.

Example 2:

vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {5, 6, 7, 8};
vector unsigned int d = vec_find_any_eq_idx(a, b); // byte 7 of d = 16

In this example, no element from a was found in b, so 16 is returned.
vec_find_any_eq_idx_cc: Vector Find Any Element Equal Index with Condition Code
\[ d = \text{vec\_find\_any\_eq\_idx\_cc}(a, b, c) \]

Find the lowest byte-index of element of \( a \) from any element of \( b \) with an equal value. If it is found, the result is the lowest byte-index from element of \( a \), and \( c \) is set to 1. Otherwise, the result is 16, with \( c \) set to 3.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

**Table 208. Vector Find Any Element Equal Index with Condition Code**

<table>
<thead>
<tr>
<th>( d )</th>
<th>a</th>
<th>b</th>
<th>( c )</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

Example 1:
```c
vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {5, 3, 7, 8};
int c = 0;
vector unsigned int d = vec_find_any_eq_idx_cc(a, b, &c); // byte 7 of d = 8, c = 1
```

In this example, the third element (byte index 8) of \( a \) was found in the vector \( b \).

Example 2:
```c
vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {5, 6, 7, 8};
int c = 0;
vector unsigned int d = vec_find_any_eq_idx_cc(a, b, &c); // byte 7 of d = 16, c = 3
```

In this example, the no element from \( a \) was found in \( b \), so 16 is returned.

vec_find_any_eq_or_0_idx: Vector Find Any Element Equal or Zero Index
\[ d = \text{vec\_find\_any\_eq\_or\_0\_idx}(a, b) \]

Find the byte-index of element of \( a \) from any element of \( b \) with an equal value, or the byte-index of element of \( a \) is 0. The result is the lowest byte-index from element of \( a \), if it is found to match those conditions. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.
Table 209. Vector Find Any Element Equal or Zero Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Example:
vector unsigned int a = {1, 2, 0, 4};
vector unsigned int b = {5, 6, 7, 8};

vector unsigned int d = vec_find_any_eq_or_0_idx(a, b); // byte 7 of d = 8

In this example, the first and second elements of a are not found in the vector b, and the third element (byte index 8) is a 0.

vec_find_func.cc: Vector Find Any Element Equal or Zero Index with Condition Code

\[
d = \text{vec\_find\_func\_cc}(a, b, c)
\]

Find the byte-index of element of a from any element of b with an equal value, or the byte-index of element of a is 0. The result is the lowest byte-index from element of a, if it is found to match those conditions. Otherwise, the result is 16.

c would be set to one of the following values:

- 0 - if no element of a matches any element of b with an equal value, and there is at least one element from a with a value of 0.
- 1 - if at least one element of a matches any element of b with an equal value, and no elements of a with a value of 0.
- 2 - if at least one element of a matches any element of b with an equal value, and there is at least one element from a has a value of 0.
- 3 - if no element of a matches any element of b with an equal value, and there is no element from a with a value of 0.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.
Table 210. Vector Find Any Element Equal or Zero Index with Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_find_any_ne: Vector Find Any Element Not Equal

d = vec_find_any_ne(a, b)

Find element of a from any element of b with a not equal value.

For each element of the result, the value of each bit is 1 if the corresponding elements of a does not equal to any element of b. Otherwise, the value of each bit is 0.

Table 211. Vector Find Any Element Not Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Example:

```c
vector signed int a = {1, -2, 3, -4};
vector signed int b = {-5, 3, -7, 8};

vector bool int d = vec_find_any_ne(a, b);
```

// d = {0xFFFFFFFF, 0xFFFFFFFF, 0, 0xFFFFFFFF}

vec_find_any_ne_cc: Vector Find Any Element Not Equal with Condition Code

d = vec_find_any_ne_cc(a, b, c)

Find element of a from any element of b with a not equal value.
For each element of the result, the value of each bit is 1 if the corresponding elements of a does not equal to any element of b. Otherwise, the value of each bit is 0. c is set to 1, if there is at least one element of a didn't find a match with b, otherwise c is set to 3.

Table 212. Vector Find Any Element Not Equal with Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td></td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
<td></td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
<td></td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

vec_find_any_ne_idx: Vector Find Any Element Not Equal Index

\[ d = \text{vec\_find\_any\_ne\_idx}(a, b) \]

Find the lowest byte-index of element of a from any element of b with a not equal value. The result is the lowest byte-index from element of a, if it is found. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

Table 213. Vector Find Any Element Not Equal Index

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

Example 1:

```c
vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {1, 5, 3, 4};
vector unsigned int d = vec_find_any_ne_idx(a, b); // byte 7 of d = 4
```

In this example, the second element (byte index 4) of a was found to be not equal to any element in b.

Example 2:
vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {1, 2, 3, 4};
vector unsigned int d = vec_find_any_ne_idx(a, b); // byte 7 of d = 16

In this example, no element from a was found to be not equal to any element in b, so 16 is returned.

**vec_find_any_ne_idx_cc: Vector Find Any Element Not Equal Index with Condition Code**

\[ d = \text{vec\_find\_any\_ne\_idx\_cc}(a, b, c) \]

Find the lowest byte-index of element of a from any element of b with a not equal value. If it is found, the result is the lowest byte-index from element of a, and c is set to 1. Otherwise, the result is 16, with c set to 3.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td></td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
</tbody>
</table>

Example 1:

vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {1, 5, 3, 4};
int c = 0;
vector unsigned int d = vec_find_any_ne_idx_cc(a, b, c); // byte 7 of d = 4, c = 1

In this example, the second element (byte index 4) of a was found to be not equal to any element in the vector b.

Example 2:

vector unsigned int a = {1, 2, 3, 4};
vector unsigned int b = {1, 2, 3, 4};
int c = 0;
vector unsigned int d = vec_find_any_ne_idx_cc(a, b, c); // byte 7 of d = 16, c = 3

**vec_find_any_ne_or_0_idx: Vector Find Any Element Not Equal or Zero Index**

\[ d = \text{vec\_find\_any\_ne\_or\_0\_idx}(a, b) \]
Find the byte-index of element of a from any element of b with a not equal value, or the byte-index of element of a is 0. The result is the lowest byte-index from element of a, if it is found to match those conditions. Otherwise, the result is 16.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.

**Table 215. Vector Find Any Element Not Equal or Zero Index**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Example:

```c
vector unsigned int a = {1, 2, 0, 4};
vector unsigned int b = {1, 2, 3, 4};

vector unsigned int d = vec_find_any_ne_or_0_idx(a, b); // byte 7 of d = 8
```

In this example, the first and second elements of a are found in the vector b, and the third element (byte index 8) is a 0.

**vec_find_any_ne_or_0_idx_cc: Vector Find Any Element Not Equal or Zero Index with Condition Code**

```c
d = vec_find_any_ne_or_0_idx_cc(a, b, c)
```

Find the byte-index of element of a from any element of b with a not equal value, or the byte-index of element of a is 0. The result is the lowest byte-index from element of a, if it is found to match those conditions. Otherwise, the result is 16.

c would be set to one of the following values:

- 0 - if no element of a matches any element of b with a not equal value, and there is at least one element from a with a value of 0.
- 1 - if at least one element of a matches any element of b with a not equal value, and no elements of a with a value of 0.
- 2 - if at least one element of a matches any element of b with a not equal value, and there is at least one element from a has a value of 0.
- 3 - if no element of a matches any element of b with a not equal value, and there is no element from a with a value of 0.

The result is placed into byte element seven of the returned vector, and all other bytes are set to 0.
Gather and Scatter

This section describes vector built-in functions for gathering and scattering elements.

**vec_extract: Vector Extract**

\[ d = \text{vec_extract}(a, b) \]

Returns the value of element \( b \) from the vector \( a \). This function uses the modulo arithmetic on \( b \) to determine the element number. For example, if \( b \) is out of range, the compiler uses \( b \) modulo the number of elements in the vector to determine the element position.

**Table 217. Vector Extract**

<table>
<thead>
<tr>
<th>( d )</th>
<th>( a )</th>
<th>( b )</th>
<th>( c )</th>
</tr>
</thead>
<tbody>
<tr>
<td>signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>signed int</td>
</tr>
<tr>
<td>unsigned char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>signed short</td>
<td>vector signed short</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>unsigned short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
<tr>
<td>signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
<tr>
<td>unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>vector double</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**vec_gather_element: Vector Gather Element**

\[ e = \text{vec_gather_element}(a, b, c, d) \]

Returns a copy of the vector \( a \) with the value of its element \( d \) replaced by \( *(c+b[d]) \).
**Table 218. Vector Gather Element**

<table>
<thead>
<tr>
<th>e</th>
<th>a</th>
<th>b</th>
<th>c</th>
<th>d</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned int</td>
<td>const signed int *</td>
<td>0-3</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
<td>const unsigned int *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>const signed int *</td>
<td></td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
<td>const signed long long *</td>
<td>0-1</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
<td>const unsigned long long *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>const double *</td>
<td>0-1</td>
</tr>
</tbody>
</table>

Example:

```c
unsigned int a1[10] = {10, 11, 12, 13, 14, 15, 16, 17, 18, 19};
unsigned int a2[10] = {20, 21, 22, 23, 24, 25, 26, 27, 28, 29};
vector unsigned int v1= {1, 2, 3, 4}, v2 = {1, 2, 3, 4};
vector unsigned int v3 = {5 * sizeof(int), 8 * sizeof(int), 9 * sizeof(int), 6 * sizeof(int)};

v1 = vec_gather_element (v1, v3, a1, 0); // v1 = {15, 2, 3, 4}
v2 = vec_gather_element (v2, v3, a2, 0); // v2 = {25, 2, 3, 4}
```

**vec_insert: Vector Insert**

```c
d = vec_insert(a, b, c)
```

Returns a copy of the vector b with the value of its element c replaced by a. This function uses the modulo arithmetic on c to determine the element number. For example, if c is out of range, the compiler uses c modulo the number of elements in the vector to determine the element position.
Table 219. Vector Insert

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>signed char</td>
<td>vector signed char</td>
<td>signed int</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>unsigned char</td>
<td>vector bool</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>unsigned short</td>
<td>vector bool short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>signed int</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>unsigned int</td>
<td>vector bool</td>
<td></td>
</tr>
<tr>
<td>vector signed long long</td>
<td>signed long long</td>
<td>vector signed long long</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>unsigned long long</td>
<td>vector bool long long</td>
<td></td>
</tr>
<tr>
<td>vector signed long</td>
<td>signed long</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
<tr>
<td>vector double</td>
<td>double</td>
<td>vector double</td>
<td></td>
</tr>
</tbody>
</table>

**vec_insert_and_zero: Vector Insert and Zero**

\[ d = \text{vec\_insert\_and\_zero}\left(a\right) \]

Returns vector \( d \) with the rightmost sub-element or element of the leftmost doubleword element set to what is pointed to by \( a \). The bit positions of all other elements are set to zero.

Table 220. Vector Insert and Zero

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>const unsigned char *</td>
</tr>
<tr>
<td>vector signed char</td>
<td>const signed char *</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>const unsigned short *</td>
</tr>
<tr>
<td>vector signed short</td>
<td>const signed short *</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>const unsigned int *</td>
</tr>
<tr>
<td>vector signed int</td>
<td>const signed int *</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>const unsigned long long *</td>
</tr>
<tr>
<td>vector signed long</td>
<td>const signed long long *</td>
</tr>
<tr>
<td>vector double</td>
<td>const double *</td>
</tr>
</tbody>
</table>

**vec_perm: Vector Permute**

\[ d = \text{vec\_perm}\left(a, b, c\right) \]

Returns a vector that contains some elements of two vectors, in the order specified by a third vector.
Each byte of the result is selected by using the least significant 5 bits of the corresponding byte of c as an index into the concatenated bytes of a and b.

**Note:** The vector generate mask built-in functions could help generate the mask c.

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector signed long</td>
<td>vector signed long</td>
<td>vector signed long</td>
</tr>
<tr>
<td>vector bool long</td>
<td>vector bool long</td>
<td>vector bool long</td>
<td>vector bool long</td>
</tr>
<tr>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector signed double</td>
<td></td>
</tr>
</tbody>
</table>

**vec_permi: Vector Permute Immediate**

\[ d = \text{vec_permi}(a, b, c) \]

Returns a vector by permuting and combining the two eight-byte-long vector elements in a and b based on the value of c.
If you use \( a[0] \) and \( a[1] \) to represent the first and second eight-byte-long elements in \( a \), and likewise use \( b[0] \) and \( b[1] \) for elements in \( b \), this function determines the elements in the result vector based on the binary value of \( c \).

The value of \( c \) can be:
- \( 0 \) (b'00') - \( a[0] \), \( b[0] \)
- \( 1 \) (b'01') - \( a[0] \), \( b[1] \)
- \( 2 \) (b'10') - \( a[1] \), \( b[0] \)
- \( 3 \) (b'11') - \( a[1] \), \( b[1] \)

<table>
<thead>
<tr>
<th>( d )</th>
<th>( a )</th>
<th>( b )</th>
<th>( c )</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>0 - 3</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
<td></td>
</tr>
</tbody>
</table>

vec_promote: Vector Promote

\[
d = \text{vec_promote}(a, b)
\]

Returns a vector with \( a \) in element position \( b \). The result is a vector with \( a \) in element position \( b \). This function uses modulo arithmetic on \( b \) to determine the element number. For example, if \( b \) is out of range, the compiler uses \( b \) modulo the number of elements in the vector to determine the element position. The other elements of the vector are undefined.

<table>
<thead>
<tr>
<th>( d )</th>
<th>( a )</th>
<th>( b )</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>signed char</td>
<td>signed int</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>unsigned int</td>
<td></td>
</tr>
<tr>
<td>vector signed long long</td>
<td>signed long long</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>unsigned long long</td>
<td></td>
</tr>
<tr>
<td>vector double</td>
<td>double</td>
<td></td>
</tr>
</tbody>
</table>

vec_scatter_element: Vector Scatter Element

\[
\text{vec_scatter_element}(a, b, c, d)
\]

Store vector element \( a[d] \) to \( *(c+b[d]) \).
Table 224. Vector Scatter Element

<table>
<thead>
<tr>
<th>a</th>
<th>b</th>
<th>c</th>
<th>d</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed int</td>
<td>vector unsigned int</td>
<td>signed int *</td>
<td>0 - 3</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector unsigned int</td>
<td>unsigned int *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned long</td>
<td>signed long long *</td>
<td>0 - 1</td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector unsigned long</td>
<td>unsigned long long *</td>
<td></td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector unsigned long</td>
<td>unsigned long long *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
<td>double *</td>
<td>0 - 1</td>
</tr>
</tbody>
</table>

vec_sel: Vector Select

\[ d = \text{vec\_sel}(a, b, c) \]

Returns a vector containing the value of either \( a \) or \( b \) depending on the value of \( c \). Each bit of the result vector has the value of the corresponding bit of \( a \) if the corresponding bit of \( c \) is 0, or the value of the corresponding bit of \( b \) otherwise.

Table 225. Vector Select

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
</tbody>
</table>

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Table 225. Vector Select (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

Example:
vector signed int a = {1, 2, 3, 4};
vector signed int b = {5, 6, 7, 8};
vector unsigned int e = {9, 10, 11, 12};
vector unsigned int f = {9, 9, 11, 11};
vector bool int c = vec_cmpeq(e, f); // c = {0xFFFFFFFF, 0, 0xFFFFFFFF, 0};
vector signed int d = vec_sel (a, b, c); // d = {5, 2, 7, 4}

Generate Mask
This section describes vector built-in functions for generating mask.

vec_genmask: Vector Generate Byte Mask
d = vec_genmask(a)

Generates byte masks for elements in the return vector. For each bit in a, if the bit is one, all bit positions in the corresponding byte element of d are set to ones. Otherwise, if the bit is zero, the corresponding byte element is set to zero.

Table 226. Vector Generate Byte Mask

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>unsigned short literal</td>
</tr>
</tbody>
</table>

vec_genmasks_8: Vector Generate Mask (Byte)
d = vec_genmasks_8(a, b)

Generates bit masks for elements in the return vector. For each byte element in d, a bit mask is generated. The mask consists of bits set to one starting at the bit position specified by a and ending with the bit position specified by b. All other bit positions are set to zero.

Notes:
- If a or b is greater than 8, the operation is performed as if the value gets modulo by 8.
- If a is greater than b, the operation is perform as if b equals 7.
Table 227. Vector Generate Mask (Byte)

\[
\begin{array}{ccc}
  & a & b \\
vectext{vector unsigned char} & 0-255 & 0-255 \\
\end{array}
\]

vec_genmasks_16: Vector Generate Mask (Halfword)

\[
d = \text{vec_genmasks}\_16(a, b)
\]

Generates bit masks for elements in the return vector. For each halfword element in \(d\), a bit mask is generated. The mask consists of bits set to one starting at the bit position specified by \(a\) and ending with the bit position specified by \(b\). All other bit positions are set to zero.

**Notes:**
- If \(a\) or \(b\) is greater than 16, the operation is performed as if the value gets modulo by 16.
- If \(a\) is greater than \(b\), the operation is perform as if \(b\) equals 15.

Table 228. Vector Generate Mask (Halfword)

\[
\begin{array}{ccc}
  & a & b \\
vectext{vector unsigned short} & 0 - 255 & 0 - 255 \\
\end{array}
\]

vec_genmasks_32: Vector Generate Mask (Word)

\[
d = \text{vec_genmasks}\_32(a, b)
\]

Generates bit masks for elements in the return vector. For each element in \(d\), a bit mask is generated. The mask consists of bits set to one starting at the bit position specified by \(a\) and ending with the bit position specified by \(b\). All other bit positions are set to zero.

**Notes:**
- If \(a\) or \(b\) is greater than 32, the operation is performed as if the value gets modulo by 32.
- If \(a\) is greater than \(b\), the operation is perform as if \(b\) equals 31.

Table 229. Vector Generate Mask (Word)

\[
\begin{array}{ccc}
  & a & b \\
vectext{vector unsigned int} & 0-255 & 0-255 \\
\end{array}
\]

vec_genmasks_64: Vector Generate Mask (Doubleword)

\[
d = \text{vec_genmasks}\_64(a, b)
\]

Generates bit masks for elements in the return vector. For each doubleword element in \(d\), a bit mask is generated. The mask consists of bits set to one starting at the bit position specified by \(a\) and ending with the bit position specified by \(b\). All other bit positions are set to zero.

**Notes:**
- If \(a\) or \(b\) is greater than 64, the operation is performed as if the value gets modulo by 64.
- If \(a\) is greater than \(b\), the operation is perform as if \(b\) equals 63.
Copy until Zero

This section describes vector built-in functions for copying until a zero is encountered.

**vec_cp_until_zero: Vector Copy Until Zero**

\[
d = \text{vec\_cp\_until\_zero}(a)
\]

Copies the vector elements from \(a\) to \(d\), starting from vector element 0, until the vector element from \(a\) contains a value of 0, or the entire vector is copied. The remaining vector elements in \(d\) are set to 0.

**Table 231. Vector Copy Until Zero**

<table>
<thead>
<tr>
<th>(d)</th>
<th>(a)</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

**vec_cp_until_zero_cc: Vector Copy Until Zero**

\[
d = \text{vec\_cp\_until\_zero\_cc}(a, b)
\]

Copies the vector elements from \(a\) to \(d\), starting from vector element 0, until the vector element from \(a\) contains a value of 0, or the entire vector is copied. The remaining vector elements in \(d\) are set to 0.

\(c\) is set to 0, if the entire vector was not copied, due to an element from \(a\) contains a value of 0. Otherwise, if all elements of \(a\) are non-zero, \(c\) is set to 3.
Load and Store

This section describes vector built-in functions for loading and storing vectors.

**vec_ld2f: Vector Load 2 float**

d = vec_ld2f(a)

Loads 2 consecutive float (total 8-bytes) from the address specified in a, and extended them as a vector double.

*Note:* This function is emulated.

**Table 233. Vector Load 2 float**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>const float</td>
<td></td>
</tr>
</tbody>
</table>

**vec_load_bndry: Vector Load to Block Boundary**

d = vec_load_bndry(a, b)

Returns a vector with content loaded from *a*, filling the vector starting at byte 0, up to 16 bytes or the byte boundary specified by b. When a boundary condition is encountered, the rest of the bytes in the resulting vector are undefined.

**Table 234. Vector Load to Block Boundary**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>const signed char</td>
<td>64, 128, 256, 512, 1024, 2048, or 4096</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>const unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>const signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>const unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>const signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>const unsigned int</td>
<td></td>
</tr>
<tr>
<td>vector signed long long</td>
<td>const signed long long</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>const unsigned long long</td>
<td></td>
</tr>
<tr>
<td>vector double</td>
<td>const double</td>
<td></td>
</tr>
</tbody>
</table>
**vec_load_len: Vector Load with Length**

d = vec_load_len(a, b)

Returns a vector with content loaded from *a, filling the vector starting at byte 0, up to the number of bytes specified by b modulo 16. The remaining bytes of the returned vector are set to zero.

*Table 235. Vector Load with Length*

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>const signed char *</td>
<td>unsigned int</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>const unsigned char *</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>const signed short *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>const unsigned short *</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>const signed int *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>const unsigned int *</td>
<td></td>
</tr>
<tr>
<td>vector signed long long</td>
<td>const signed long long *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>const unsigned long long *</td>
<td></td>
</tr>
<tr>
<td>vector double</td>
<td>const double *</td>
<td></td>
</tr>
</tbody>
</table>

**vec_load_pair: Vector Load Pair**

d = vec_load_pair(a, b)

Returns a vector with a on the 0-indexed element, and b on the 1-indexed element.

*Note:* This function might be emulated.

*Table 236. Vector Load Pair*

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed long long</td>
<td>signed long long</td>
<td>signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>unsigned long long</td>
<td>unsigned long long</td>
</tr>
</tbody>
</table>

**vec_st2f: Vector Store 2 float**

vec_st2f(a, b)

Rounds the vector double a as 2 float, and stores them to 2 consecutive location (total 8-bytes) as specified by b.

*Note:* This function is emulated.

*Table 237. Vector Store 2 float*

<table>
<thead>
<tr>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>float *</td>
</tr>
</tbody>
</table>

**vec_store_len: Vector Store with Length**

vec_store_len(a, b, c)

Store c+1 number of bytes to *b from the vector a.

*Note:* If c is greater than 15, only 16 bytes will be stored.
Table 238. Vector Store with Length

<table>
<thead>
<tr>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>signed char *</td>
<td>unsigned int</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>unsigned char *</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>signed short *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>unsigned short *</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>signed int *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>unsigned int *</td>
<td></td>
</tr>
<tr>
<td>vector signed long long</td>
<td>signed long long *</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>unsigned long long *</td>
<td></td>
</tr>
<tr>
<td>vector double</td>
<td>double *</td>
<td></td>
</tr>
</tbody>
</table>

vec_xld2: Vector Load 2 Doubleword

d = vec_xld2(a, b)

Loads a 16-byte vector from two 8-byte elements at the memory address specified by the displacement a and the pointer b. This function adds the displacement and the pointer R-value to obtain the address for the load operation.

Table 239. Vector Load 2 Doubleword

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>long</td>
<td>signed char *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td></td>
<td>unsigned char *</td>
</tr>
<tr>
<td>vector signed short</td>
<td></td>
<td>signed short *</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td></td>
<td>unsigned short *</td>
</tr>
<tr>
<td>vector signed int</td>
<td></td>
<td>signed int *</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td></td>
<td>unsigned int *</td>
</tr>
<tr>
<td>vector signed long long</td>
<td></td>
<td>signed long long *</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td></td>
<td>unsigned long long *</td>
</tr>
<tr>
<td>vector double</td>
<td></td>
<td>double *</td>
</tr>
</tbody>
</table>

vec_xlw4: Vector Load 4 Word

d = vec_xlw4(a, b)

Loads a 16-byte vector from four 4-byte elements at the memory address specified by the displacement a and the pointer b. This function adds the displacement and the pointer R-value to obtain the address for the load operation.

Table 240. Vector Load 4 Word

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>long</td>
<td>signed char *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td></td>
<td>unsigned char *</td>
</tr>
<tr>
<td>vector signed short</td>
<td></td>
<td>signed short *</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td></td>
<td>unsigned short *</td>
</tr>
<tr>
<td>vector signed int</td>
<td></td>
<td>signed int *</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td></td>
<td>unsigned int *</td>
</tr>
<tr>
<td>vector signed long long</td>
<td></td>
<td>signed long long *</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td></td>
<td>unsigned int *</td>
</tr>
</tbody>
</table>
vec_xstd2: Vector Store 2 Doubleword

d = vec_xstd2(a, b, c)

Puts a 16-byte vector a as two 8-byte elements to the memory address specified by
the displacement b and the pointer c. This function adds the displacement and the
pointer R-value to obtain the address for the store operation.

Table 241. Vector Store 2 Doubleword

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>void</td>
<td>vector signed char</td>
<td>long</td>
<td>signed char *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td></td>
<td>unsigned char *</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td></td>
<td>signed short *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td></td>
<td>unsigned short *</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td></td>
<td>signed int *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td></td>
<td>unsigned int *</td>
</tr>
<tr>
<td></td>
<td>vector signed long</td>
<td></td>
<td>signed long long *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long</td>
<td></td>
<td>unsigned long long *</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td></td>
<td>double *</td>
</tr>
</tbody>
</table>

vec_xstw4: Vector Store 4 Word

d = vec_xstw4(a, b, c)

Puts a 16-byte vector a to four 4-byte elements at the memory address specified by
the displacement b and the pointer c. This function adds the displacement and the
pointer R-value to obtain the address for the store operation.

Table 242. Vector Store 4 Word

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>void</td>
<td>vector signed char</td>
<td>long</td>
<td>signed char *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td></td>
<td>unsigned char *</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td></td>
<td>signed short *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td></td>
<td>unsigned short *</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td></td>
<td>signed int *</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td></td>
<td>unsigned int *</td>
</tr>
</tbody>
</table>

Logical

This section describes vector built-in functions for logical calculation.

vec_cntlz: Vector Count Leading Zeros

d = vec_cntlz(a)

Computes the count of leading zero bits of each element of the input.

Each element of the result is set to the number of leading zeros of the
corresponding element of a.
Table 243. Vector Count Leading Zeros

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td>vector signed long long</td>
</tr>
</tbody>
</table>

vec_cnttz: Vector Count Trailing Zeros

d = vec_cnttz(a)

Computes the count of trailing zero bits of each element of the input.

Each element of the result is set to the number of tailing zeros of the corresponding element of a.

Table 244. Vector Count Trailing Zeros

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td>vector signed long long</td>
</tr>
</tbody>
</table>

vec_nor: Vector NOR

d = vec_nor(a, b)

Performs a bitwise NOR of the given vectors a and b.

Note: This function will not cause IEEE exception on vector double.

Table 245. Vector NOR

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector bool char</td>
</tr>
</tbody>
</table>

Table 246. Vector NOR
Table 245. Vector NOR (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector vector bool short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector bool long long</td>
<td>vector double</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td>vector bool long long</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_popcnt: Vector Population Count**

\[ d = \text{vec\_popcnt}(a) \]

Computes the population count (number of set bits) in each element of the input.

Each element of the result is set to the number of set bits in the corresponding element of the input.

**Note:** This function emulates the operation, except for vector signed char and vector unsigned char.

Table 246. Vector Population Count

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
</tr>
</tbody>
</table>
### Merge

This section describes vector built-in functions for merging vectors.

**vec_mergeh: Vector Merge High**

\[
d = \text{vec_mergeh}(a, b)
\]

Merges the most significant ("high") halves of two vectors.

**Figure 159. Merge 2 high-order elements (32-bit)**

Assume that the elements of each vector are numbered beginning with 0. The even-numbered elements of the result are taken, in order, from the elements in the most significant half of \(a\). The odd-numbered elements of the result are taken, in order, from the elements in the most significant half of \(b\).

**Table 247. Vector Merge High**

<table>
<thead>
<tr>
<th>(d)</th>
<th>(a)</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
</tbody>
</table>
vec_mergel: Vector Merge Low

d = vec_mergel(a, b)

Merges the least significant ("low") halves of two vectors.

Table 248. Vector Merge Low

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

Pack and Unpack

This section describes vector built-in functions for pack and unpack.
vec_pack: Vector Pack
\[ d = \text{vec\_pack}(a, b) \]

The value of each element of the result vector is taken from the low-order half of the corresponding element of the result of concatenating \( a \) and \( b \).

\[ a \begin{array}{cccc} 0 & 1 & 2 & 3 \end{array} \quad \begin{array}{cccc} 0 & 1 & 2 & 3 \end{array} \quad b \]

![Figure 161. Pack 8 integer elements (32-bit) to 8 integer elements (16-bit)]

Table 249. Vector Pack
<table>
<thead>
<tr>
<th>( d )</th>
<th>( a )</th>
<th>( b )</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool int</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

vec_packs: Vector Pack Saturate
\[ d = \text{vec\_packs}(a, b) \]

The value of each element of the result vector is the saturated value of the corresponding element of the result of concatenating \( a \) and \( b \).

\[ a \begin{array}{cccc} 0 & 1 & 2 & 3 \end{array} \quad \begin{array}{cccc} 0 & 1 & 2 & 3 \end{array} \quad b \]

![Figure 162. Pack 8 integer elements (32-bit) to 8 integer elements (16-bit)]
Table 250. Vector Pack Saturate

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

vec_packs_cc: Vector Pack Saturate Condition Code

\[ d = \text{vec_packs_cc}(a, b, c) \]

The value of each element of the result vector is the saturated value of the corresponding element of the result of concatenating \( a \) and \( b \). The resulting condition code is returned through parameter \( c \). For the signed types, the resulting condition code is from the VECTOR PACK SATURATE (VPKS) instruction. For the unsigned types, the resulting condition code is from the VECTOR PACK LOGICAL SATURATE (VPKLS) instruction.

Table 251. Vector Pack Saturate Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
</tbody>
</table>

vec_packsu: Vector Pack Saturated Unsigned

\[ d = \text{vec_packsu}(a, b) \]

The value of each element of the result vector is the saturated unsigned value of the corresponding element of the result of concatenating \( a \) and \( b \).

Table 252. Vector Pack Saturated Unsigned

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

vec_packsu_cc: Vector Pack Saturated Unsigned Condition Code

\[ d = \text{vec_packsu_cc}(a, b, c) \]
The value of each element of the result vector is the saturated unsigned value of the corresponding element of the result of concatenating a and b. The resulting condition code from the VECTOR PACK LOGICAL SATURATE (VPKLS) instruction is returned through parameter c.

Table 253. Vector Pack Saturated Unsigned Condition Code

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>int *</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned long int</td>
<td>vector unsigned long int</td>
<td></td>
</tr>
</tbody>
</table>

vec_unpackh: Vector Unpack High Element

d = vec_unpackh(a)

Unpacks the most significant ("high") half of a vector into a vector with larger elements. The value of each element of the result is the value of the corresponding element of the most significant half of a.

Figure 163. Unpack high-order integer elements (16-bit) to integer elements (32-bit)

Table 254. Vector Unpack High Element

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed short</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool short</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool int</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

vec_unpackl: Vector Unpack Low Element

d = vec_unpackl(a)

Unpacks the least significant ("low") half of a vector into a vector with larger elements. The value of each element of the result is the value of the corresponding
element of the least significant half of \( a \).

\[
\begin{array}{cccccccc}
0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 \\
\hline
\text{a} & & & & & & & \\
\downarrow & & & & & & & \\
\text{d} & S & S & S & S & S & S & S \\
\end{array}
\]

\textbf{Figure 164. Unpack low-order integer elements (16-bit) to integer elements (32-bit)}

\begin{table}[h]
\centering
\caption{Vector Unpack Low Element}
\begin{tabular}{|c|c|}
\hline
d & a \\
\hline
vector signed short & vector signed char \\
vctor bool short & vector bool char \\
vctor signed int & vector signed short \\
vctor bool int & vector bool short \\
vctor signed long long & vector signed int \\
vctor bool long long & vector bool int \\
vctor unsigned short & vector unsigned char \\
vctor unsigned int & vector unsigned short \\
vctor unsigned long long & vector unsigned int \\
\hline
\end{tabular}
\end{table}

\textbf{Replicate}

This section describes vector built-in functions for replicating vector elements.

\textbf{vec\_splat: Vector Splat}

\[ d = \text{vec\_splat}(a, b) \]

Returns a vector that has all of its elements set to a given value. The value of each element of the result is the value of the element of \( a \) specified by \( b \).

\begin{table}[h]
\centering
\caption{Vector Splat}
\begin{tabular}{|c|c|c|}
\hline
d & a & b \\
\hline
vector bool char & vector bool char & 0 - 15 \\
vctor signed char & vector signed char \\
vctor unsigned char & vector unsigned char \\
vctor bool short & vector bool short & 0 - 7 \\
vctor signed short & vector signed short \\
vctor unsigned short & vector unsigned short \\
vctor bool int & vector bool int & 0 - 3 \\
vctor signed int & vector signed int \\
vctor unsigned int & vector unsigned int \\
\hline
\end{tabular}
\end{table}
**Table 256. Vector Splat (continued)**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool long</td>
<td>vector bool long</td>
<td>0 - 1</td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector signed long</td>
<td></td>
</tr>
<tr>
<td>vector unsigned</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
<tr>
<td>double</td>
<td>vector double</td>
<td></td>
</tr>
</tbody>
</table>

**vec_splat_s8: Vector Splat Signed Byte**

d = vec_splat_s8(a)

Returns a vector with each of the 16 signed 8-bits element equal to the given value.

**Table 257. Vector Splat Signed Byte**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>-128 - 127</td>
</tr>
</tbody>
</table>

**vec_splat_s16: Vector Splat Signed Halfword**

d = vec_splat_s16(a)

Returns a vector with each of the 8 signed 16-bits element equal to the given value.

**Table 258. Vector Splat Signed Halfword**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed short</td>
<td>-2^{15} - 2^{15}.1</td>
</tr>
</tbody>
</table>

**vec_splat_s32: Vector Splat Signed Word**

d = vec_splat_s32(a)

Returns a vector with each of the 4 signed 32-bits element equal to the given value.

**Table 259. Vector Splat Signed Word**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed int</td>
<td>-2^{31} - 2^{31}.1</td>
</tr>
</tbody>
</table>

**vec_splat_s64: Vector Splat Signed Doubleword**

d = vec_splat_s64(a)

Returns a vector with each of the 2 signed 64-bits element equal to the given value.

**Table 260. Vector Splat Signed Doubleword**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed long</td>
<td>-2^{63} - 2^{63}.1</td>
</tr>
</tbody>
</table>

**vec_splat_u8: Vector Splat Unsigned Byte**

d = vec_splat_u8(a)

Returns a vector with each of the 16 unsigned 8-bits element equal to the given value.
Table 261. Vector Splat Unsigned Byte

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>0 - 255</td>
</tr>
</tbody>
</table>

vec_splat_u16: Vector Splat Unsigned Halfword

\[ d = \text{vec\_splat\_u16}(a) \]

Returns a vector with each of the 8 unsigned 16-bits element equal to the given value.

Table 262. Vector Splat Unsigned Halfword

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned short</td>
<td>0 - 2^{16-1}</td>
</tr>
</tbody>
</table>

vec_splat_u32: Vector Splat Unsigned Word

\[ d = \text{vec\_splat\_u32}(a) \]

Returns a vector with each of the 4 unsigned 32-bits element equal to the given value.

Table 263. Vector Splat Unsigned Word

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned int</td>
<td>(-2^{15} - 2^{15-1})</td>
</tr>
</tbody>
</table>

vec_splat_u64: Vector Splat Doubleword

\[ d = \text{vec\_splat\_u64}(a) \]

Returns a vector with each of the 2 unsigned 64-bits element equal to the given value.

Table 264. Vector Splat Doubleword

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned long long</td>
<td>(-2^{31} - 2^{31-1})</td>
</tr>
</tbody>
</table>

vec_splats: Vector Splats

\[ d = \text{vec\_splats}(a) \]

Returns a vector of which the value of each element is set to \( a \).

Table 265. Vector Splats

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed char</td>
<td>signed char</td>
</tr>
<tr>
<td>vector unsigned char</td>
<td>unsigned char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>signed short</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>signed long long</td>
</tr>
</tbody>
</table>
Rotate and Shift

This section describes vector built-in functions for rotate and shift.

**vec_rl: Vector Element Rotate Left**

\[ d = \text{vec_rl}(a, b) \]

Rotates each element of a vector left by a given number of bits. Each element of the result is obtained by rotating the corresponding element of \( a \) left by the number of bits specified by the corresponding element of \( b \), modulo the number of bits in the element.

**Table 266. Vector Element Rotate Left**

<table>
<thead>
<tr>
<th>( d )</th>
<th>( a )</th>
<th>( b )</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
</tr>
</tbody>
</table>

**vec_rl_mask: Vector Element Rotate and Insert Under Mask**

\[ d = \text{vec_rl}(a, b, c) \]

Rotates each element of vector \( a \) left by a given number of bits \( c \), modulo the number of bits in the element, and overlay with the original vector \( a \) depends on the mask \( b \). Each bit of the result is obtained where if the corresponding bit the mask \( b \) is 1, it will get the corresponding bit from the intermediate result. Otherwise, if the corresponding bit the mask \( b \) is 0, it will get the corresponding bit from \( a \), before the rotation.
### Table 267. Vector Element Rotate and Insert Under Mask

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>unsigned char literal</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
<td></td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector signed long</td>
<td>vector unsigned long</td>
<td></td>
</tr>
</tbody>
</table>

**vec_rli: Vector Element Rotate Left Immediate**

\[ d = \text{vec_rli}(a, b) \]

Rotates each element of a vector left by a given number of bits. Each element of the result is obtained by rotating the corresponding element of a left by the number of bits specified by \( b \), modulo the number of bits in the element.

### Table 268. Vector Element Rotate Left Immediate

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
<td>unsigned long</td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector signed long</td>
<td>unsigned long</td>
</tr>
</tbody>
</table>

**vec_slb: Vector Shift Left by Byte**

\[ d = \text{vec_slb}(a, b) \]

Performs a left shift for a vector by a given number of bytes. Each element of the result is obtained by shifting the corresponding element of a left by the number of bytes specified by bits 1-4 of byte element seven of \( b \). The bits that are shifted out are replaced by zeros.

### Table 269. Vector Shift Left by Byte

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
<td>vector unsigned long</td>
</tr>
<tr>
<td>vector signed long</td>
<td>vector signed long</td>
<td>vector unsigned long</td>
</tr>
</tbody>
</table>
Table 269. Vector Shift Left by Byte (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector signed long long</td>
</tr>
</tbody>
</table>

vec_sld: Vector Shift Left Double by Byte

\[ d = \text{vec\_sld}(a, b, c) \]

Performs a left shift for two concatenated vectors by a given number of bytes. The result is the most significant 16 bytes obtained by concatenating \(a\) and \(b\), and shifting left by the number of bytes specified by \(c\).

---

*Figure 165. Bit-wise conditional select of vector contents (128-bit)*
vec_sldw: Vector Shift Left Double by Word

\[ d = \text{vec\_sldw}(a, b, c) \]

Returns a vector by concatenating \(a\) and \(b\), and then left shifts the result vector by multiples of 4 bytes. \(c\) specifies the offset for the shifting operation. After left-shifting the concatenated \(a\) and \(b\) by multiples of 4 bytes specified by \(c\), the function takes the four leftmost 4-byte values and forms the result vector.

Table 271. Vector Shift Left Double by Word

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>0 - 15</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector signed char</td>
<td></td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td></td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector signed short</td>
<td></td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td></td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
<td></td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td></td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
<td></td>
</tr>
</tbody>
</table>

vec_sll: Vector Shift Left

\[ d = \text{vec\_sll}(a, b) \]

Performs a left shift for a vector by a given number of bits. Each element of the result is obtained by shifting the corresponding element of \(a\) left by the number of bits specified by the last 3 bits of every byte of \(b\). The bits that are shifted out are replaced by zeros.

Note: The low-order 3 bits of all byte elements in \(b\) must be the same, otherwise the result is undefined.
### Table 272. Vector Shift Left

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned char</td>
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<td></td>
<td></td>
<td>vector unsigned short</td>
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<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
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<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
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<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

**vec_srab: Vector Shift Right Arithmetic by Byte**

\[ d = \text{vec_srab}(a, b) \]
Performs an algebraic right shift for a vector by a given number of bytes. Each element of the result is obtained by shifting the corresponding element of a right by the number of bytes specified by bits 1-4 of byte element seven of b. The bits that are shifted out are replaced by copies of the most significant bit of the element of a.

Table 273. Vector Shift Right Arithmetic by Byte

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

vec_sral: Vector Shift Right Arithmetic

d = vec_sral(a, b)

Performs an algebraic right shift for a vector by a given number of bits. Each element of the result is obtained by shifting the corresponding element of a right by the number of bits specified by the last 3 bits of every byte of b. The bits that are shifted out are replaced by copies of the most significant bit of the element of a.

Note: The low-order 3 bits of all byte elements in b must be the same, otherwise the result is undefined.

Table 274. Vector Shift Right Arithmetic

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>
Table 274. Vector Shift Right Arithmetic (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

**vec_srb: Vector Shift Right by Byte**

\[ d = \text{vec} \text{sr}b(a, b) \]

Performs a right shift for a vector by a given number of bytes. Each element of the result is obtained by shifting the corresponding element of \( a \) right by the number of bytes specified by bits 1-4 of byte element seven of \( b \). The bits that are shifted out are replaced by zeros.
### Table 275. Vector Shift Right by Byte

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

### vec_srl: Vector Shift Right

\[ d = \text{vec}_srl(a, b) \]

Performs a right shift for a vector by a given number of bits. Each element of the result is obtained by shifting the corresponding element of a right by the number of bits specified by the last 3 bits of every byte of b. The bits that are shifted out are replaced by zeros.

**Note:** The low-order 3 bits of all byte elements in b must be the same, otherwise the result is undefined.

### Table 276. Vector Shift Right

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>
Table 276. Vector Shift Right (continued)

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector short unsigned</td>
<td>vector short unsigned</td>
<td>vector char</td>
</tr>
<tr>
<td>vector short unsigned int</td>
<td>vector short unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector char</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector char</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector char</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector unsigned int</td>
</tr>
</tbody>
</table>

Rounding and Conversion

This section describes vector built-in functions for rounding and conversion.

**vec_ceil: Vector Ceiling**

\[ d = \text{vec}_\text{ceil}(a) \]

Returns a vector containing the smallest representable floating-point integral values greater than or equal to the values of the corresponding elements of the given vector.

**Note:** `vec_ceil` provides the same functionality as `vec_roundp`, except that `vec_ceil` could trigger the IEEE-inexact exception.
### Table 277. Vector Ceiling

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

#### vec_ctd: Vector Convert to Double

\[ d = \text{vec	extunderscore ctd}(a, b) \]

Converts the type of each element in \( a \) from integer to floating-point double precision and divides the result by 2 to the power of \( b \).

**Note:** Current BFP rounding mode is used on the conversion.

### Table 278. Vector Convert to Double

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector signed long long</td>
<td>0 - 31</td>
</tr>
<tr>
<td>vector double</td>
<td>vector unsigned long long</td>
<td></td>
</tr>
</tbody>
</table>

#### vec_ctsl: Vector Convert to signed long long

\[ d = \text{vec	extunderscore ctsl}(a, b) \]

Multiplies each element in \( a \) by 2 to the power of \( b \) and rounds the result toward 0 into an integer.

### Table 279. Vector Convert to signed long long

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed long long</td>
<td>vector double</td>
<td>0 - 31</td>
</tr>
</tbody>
</table>

#### vec_ctul: Vector Convert to unsigned long long

\[ d = \text{vec	extunderscore ctul}(a, b) \]

Multiplies each element in \( a \) by 2 to the power of \( b \) and rounds the result toward 0 into an unsigned integer.

### Table 280. Vector Convert to unsigned long long

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed long long</td>
<td>vector double</td>
<td>0 - 31</td>
</tr>
</tbody>
</table>

#### vec_extend_s64: Vector Sign Extend to Doubleword

\[ d = \text{vec	extunderscore extend	extunderscore s64}(a) \]

Returns a vector with sign-extended on the rightmost element-sized sub-element of each doubleword.

### Table 281. Extend Sign to Doubleword

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector signed long long</td>
<td>vector signed char</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed short</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector signed int</td>
</tr>
</tbody>
</table>
**vec_floor: Vector Floor**

\[ d = \text{vec\_floor}(a) \]

Returns a vector containing the largest representable floating-point integral values less than or equal to the values of the corresponding elements of the given vector.

**Note:** \text{vec\_floor} provides the same functionality as \text{vec\_roundm}, except that \text{vec\_floor} could trigger the IEEE-inexact exception.

<table>
<thead>
<tr>
<th>Table 282. Vector Floor</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
</tr>
<tr>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_round: Vector Round to Nearest**

\[ d = \text{vec\_round}(a) \]

Returns a vector containing the rounded values to the nearest representable floating-point integer, using IEEE round-to-nearest rounding, of the corresponding elements of the given vector.

**Note:** IEEE-inexact exception is suppressed.

<table>
<thead>
<tr>
<th>Table 283. Vector Round to Nearest</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
</tr>
<tr>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_roundc: Vector Round to Current**

\[ d = \text{vec\_roundc}(a) \]

Returns a vector by using the current rounding mode to round every double-precision floating-point element in the given vector to integer.

**Note:** IEEE-inexact exception is suppressed.

<table>
<thead>
<tr>
<th>Table 284. Vector Round to Current</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
</tr>
<tr>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_roundm: Vector Round toward Negative Infinity**

\[ d = \text{vec\_roundm}(a) \]

Returns a vector containing the largest representable floating-point integral values less than or equal to the values of the corresponding elements of the given vector.

**Note:** \text{vec\_roundm} provides the same functionality as \text{vec\_floor}, except that \text{vec\_roundm} would not trigger the IEEE-inexact exception.

<table>
<thead>
<tr>
<th>Table 285. Vector Round toward Negative Infinity</th>
</tr>
</thead>
<tbody>
<tr>
<td>d</td>
</tr>
<tr>
<td>vector double</td>
</tr>
</tbody>
</table>
**vec_roundp: Vector Round toward Positive Infinity**

\[ d = \text{vec\_roundp}(a) \]

Returns a vector containing the smallest representable floating-point integral values greater than or equal to the values of the corresponding elements of the given vector.

**Note:** `vec_roundp` provides the same functionality as `vec_ceil`, except that `vec_roundp` would not trigger the IEEE-inexact exception.

*Table 286. Vector Round toward Positive Infinity*

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_roundz: Vector Round toward Zero**

\[ d = \text{vec\_roundz}(a) \]

Returns a vector containing the truncated values of the corresponding elements of the given vector. Each element of the result contains the value of the corresponding element of \( a \), truncated to an integral value.

**Note:** `vec_roundz` provides the same functionality as `vec_trunc`, except that `vec_roundz` would not trigger the IEEE-inexact exception.

*Table 287. Vector Round toward Zero*

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

**vec_trunc: Vector Truncate**

\[ d = \text{vec\_trunc}(a) \]

Returns a vector containing the truncated values of the corresponding elements of the given vector. Each element of the result contains the value of the corresponding element of \( a \), truncated to an integral value.

**Note:** `vec_trunc` provides the same functionality as `vec_roundz`, except that `vec_trunc` could trigger the IEEE-inexact exception.

*Table 288. Vector Truncate*

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

**Test**

This section describes vector built-in functions for testing.

**vec_fp_test_data_class: Vector Floating-Point Test Data Class**

\[ d = \text{vec\_fp\_test\_data\_class}(a, b, c) \]

Performs a test of the BFP element class on the vector element \( a \), based on the specified condition \( b \), using the VECTOR FP TEST DATA CLASS IMMEDIATE (VFTCIDB) instruction. The condition code set by the VFTCIDB instruction is returned through \( c \).
d represents the first operand in the instruction.

a represents the second operand in the instruction.

b represents the third operand in the instruction.

**Table 289. Vector Floating-Point Test Data Class**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
<th>c</th>
</tr>
</thead>
<tbody>
<tr>
<td>vector bool long</td>
<td>vector double</td>
<td>0 - 4095</td>
<td>int *</td>
</tr>
</tbody>
</table>

**vec_test_mask: Vector Test under Mask**

d = vec_test_mask(a, b)

Returns the condition code set by the Vector Test Under Mask (VTM) instruction. a is the first operand, and b is the second operand on the instruction.

**Table 290. Vector Test under Mask**

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

**All Predicates**

This section describes vector built-in functions for searching and comparing all elements.

**vec_all_eq: All Elements Equal**

d = vec_all_eq(a, b)

Tests whether all sets of corresponding elements of the given vectors are equal. The result is 1 if each element of a is equal to the corresponding element of b. Otherwise, the result is 0.
### vec_all_ge: All Elements Greater Than or Equal


d = vec_all_ge(a, b)

Tests whether all elements of the first argument are greater than or equal to the corresponding elements of the second argument. The result is 1 if all elements of a are greater than or equal to the corresponding elements of b. Otherwise, the result is 0.
**vec_all_gt: All Elements Greater Than**

\[ d = \text{vec_all_gt}(a, b) \]

Tests whether all elements of the first argument are greater than the corresponding elements of the second argument. The result is 1 if all elements of \( a \) are greater than the corresponding elements of \( b \). Otherwise, the result is 0.

<table>
<thead>
<tr>
<th>( d )</th>
<th>( a )</th>
<th>( b )</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td></td>
<td>vector bool short</td>
<td>vector bool short</td>
</tr>
<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector bool int</td>
<td>vector bool int</td>
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<tr>
<td></td>
<td>vector signed int</td>
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<td>vector unsigned int</td>
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<td>vector bool int</td>
<td>vector bool int</td>
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<td></td>
<td>vector signed long long</td>
<td>vector signed long long</td>
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<td>vector bool long long</td>
<td>vector bool long long</td>
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<td>vector signed long long</td>
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<td>vector unsigned long long</td>
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<td></td>
<td>vector bool long long</td>
<td>vector bool long long</td>
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<tr>
<td></td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>
Table 293. All Elements Greater Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td></td>
<td>vector bool char</td>
</tr>
<tr>
<td>vector bool char</td>
<td>vector bool char</td>
<td>vector signed char</td>
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<td></td>
<td></td>
<td>vector unsigned char</td>
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<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector bool char</td>
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<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector bool short</td>
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<td>vector bool short</td>
<td>vector bool short</td>
<td>vector signed short</td>
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<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector bool short</td>
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<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector bool int</td>
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<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector signed int</td>
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<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector bool int</td>
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<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector bool long long</td>
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<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
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<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td></td>
</tr>
</tbody>
</table>

**vec_all_le: All Elements Less Than or Equal**

\[d = \text{vec\_all\_le}(a, b)\]

Tests whether all elements of the first argument are less than or equal to the corresponding elements of the second argument. The result is 1 if all elements of \(a\) are less than or equal to the corresponding elements of \(b\). Otherwise, the result is 0.


Table 294. All Elements Less Than or Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector signed short</td>
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<td>vector signed short</td>
<td>vector signed char</td>
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<td>vector unsigned char</td>
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<td></td>
<td>vector unsigned short</td>
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<tr>
<td></td>
<td>vector signed int</td>
<td>vector signed int</td>
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<td></td>
<td>vector bool int</td>
<td>vector bool int</td>
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<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
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<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
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<td>vector bool long long</td>
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<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td></td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_all_lt: All Elements Less Than

d = vec_all_lt(a, b)

Tests whether all elements of the first argument are less than the corresponding elements of the second argument. The result is 1 if all elements of a are less than the corresponding elements of b. Otherwise, the result is 0.
Table 295. All Elements Less Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector bool char</td>
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<td>vector bool char</td>
<td>vector bool char</td>
<td>vector signed char</td>
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<td>vector signed char</td>
<td>vector unsigned char</td>
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<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector bool char</td>
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<td>vector signed short</td>
<td>vector signed short</td>
<td>vector bool short</td>
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<td>vector bool short</td>
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<td>vector signed short</td>
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<td>vector signed short</td>
<td>vector unsigned short</td>
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<tr>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector bool short</td>
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<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector bool int</td>
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<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector signed int</td>
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<td>vector unsigned int</td>
<td>vector unsigned int</td>
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<tr>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector bool int</td>
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<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector bool long long</td>
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<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
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<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td></td>
</tr>
</tbody>
</table>

vec_all_nan: All Elements Not a Number

d = vec_all_nan(a)

Tests whether each element of the given vector is a NaN. The result is 1 if each element of a is a NaN. Otherwise, the result is 0.

Table 296. All Elements Not a Number

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_all_ne: All Elements Not Equal

d = vec_all_ne(a, b)
Tests whether all sets of corresponding elements of the given vectors are not equal. The result is 1 if each element of a is not equal to the corresponding element of b. Otherwise, the result is 0.

Table 297. All Elements Not Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector bool char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector signed char</td>
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<tr>
<td>vector signed</td>
<td>vector bool char</td>
<td>vector signed char</td>
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<tr>
<td>vector unsigned</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
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<td>vector bool short</td>
<td>vector signed short</td>
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<td>vector signed short</td>
<td>vector bool short</td>
<td>vector signed short</td>
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<tr>
<td>vector unsigned short</td>
<td>vector bool short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector signed int</td>
<td>vector signed int</td>
</tr>
<tr>
<td>vector unsigned int</td>
<td>vector signed int</td>
<td>vector unsigned int</td>
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<tr>
<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector signed long long</td>
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<tr>
<td>vector signed long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
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<td>vector unsigned long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_all_nge: All Elements Not Greater Than or Equal

d = vec_all_nge(a, b)

Tests whether each element of the first argument is not greater than or equal to the corresponding element of the second argument. The result is 1 if each element of a is not greater than or equal to the corresponding element of b. Otherwise, the result is 0.
Table 298. All Elements Not Greater Than or Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_all_ngt: All Elements Not Greater Than

\[ d = \text{vec\_all\_ngt}(a, b) \]

Tests whether each element of the first argument is not greater than the corresponding element of the second argument. The result is 1 if each element of \( a \) is not greater than the corresponding element of \( b \). Otherwise, the result is 0.

Table 299. All Elements Not Greater Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_all_nle: All Elements Not Less Than or Equal

\[ d = \text{vec\_all\_nle}(a, b) \]

Tests whether each element of the first argument is not less than or equal to the corresponding element of the second argument. The result is 1 if each element of \( a \) is not less than or equal to the corresponding element of \( b \). Otherwise, the result is 0.

Table 300. All Elements Not Less Than or Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_all_nlt: All Elements Not Less Than

\[ d = \text{vec\_all\_nlt}(a, b) \]

Tests whether each element of the first argument is not less than the corresponding element of the second argument. The result is 1 if each element of \( a \) is not less than the corresponding element of \( b \). Otherwise, the result is 0.

Table 301. All Elements Not Less Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_all_numeric: All Elements Numeric

\[ d = \text{vec\_all\_numeric}(a) \]

Tests whether each element of the given vector is numeric (not a NaN). The result is 1 if each element of \( a \) is numeric (not a NaN). Otherwise, the result is 0.

Table 302. All Elements Numeric

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
</tr>
</tbody>
</table>
Any Predicates

This section describes vector built-in functions for searching and comparing any elements.

vec_any_eq: Any Element Equal

\[ d = \text{vec\_any\_eq}(a, b) \]

Tests whether any set of corresponding elements of the given vectors are equal. The result is 1 if any element of \( a \) is equal to the corresponding element of \( b \). Otherwise, the result is 0.

Table 303. Any Element Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector unsigned char</td>
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<tr>
<td>vector signed char</td>
<td>vector bool char</td>
<td>vector signed char</td>
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<td>vector unsigned char</td>
<td>vector bool char</td>
<td>vector unsigned char</td>
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<tr>
<td>vector bool short</td>
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<td>vector signed short</td>
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<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector signed int</td>
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<td>vector bool int</td>
<td>vector signed int</td>
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<tr>
<td>vector unsigned int</td>
<td>vector bool int</td>
<td>vector unsigned int</td>
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<tr>
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<td>vector bool long long</td>
<td>vector signed long long</td>
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<td></td>
<td>vector signed long long</td>
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<td>vector signed long long</td>
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<tr>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>
Tests whether any element of the first argument is greater than or equal to the corresponding element of the second argument. The result is 1 if any element of \( a \) is greater than or equal to the corresponding element of \( b \). Otherwise, the result is 0.

Table 304. Any Element Greater Than or Equal

<table>
<thead>
<tr>
<th>( d )</th>
<th>( a )</th>
<th>( b )</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector bool char</td>
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<tr>
<td>vector bool char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
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<tr>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector bool char</td>
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<td>vector signed short</td>
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<td>vector bool short</td>
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<td>vector unsigned short</td>
<td>vector unsigned short</td>
<td>vector bool short</td>
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<tr>
<td>vector signed int</td>
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<td>vector bool int</td>
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<td>vector bool int</td>
<td>vector signed int</td>
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<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector bool int</td>
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<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector bool long long</td>
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<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
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<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec\_any\_gt: Any Element Greater Than

\[ d = \text{vec\_any\_gt}(a, b) \]

Tests whether any element of the first argument is greater than the corresponding element of the second argument. The result is 1 if any element of \( a \) is greater than the corresponding element of \( b \). Otherwise, the result is 0.
### Table 305. Any Element Greater Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector signed char</td>
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<td></td>
<td>vector unsigned char</td>
<td>vector signed char</td>
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<tr>
<td></td>
<td>vector bool char</td>
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<td>vector signed short</td>
<td>vector signed short</td>
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<td>vector signed int</td>
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<td>vector bool int</td>
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<td>vector unsigned int</td>
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<td>vector signed long long</td>
<td>vector signed long long</td>
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<td>vector bool long long</td>
<td>vector signed long long</td>
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<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
</tbody>
</table>

#### vec_any_le: Any Element Less Than or Equal

\[ d = \text{vec\_any\_le}(a, b) \]

Tests whether any element of the first argument is less than or equal to the corresponding element of the second argument. The result is 1 if any element of a is less than or equal to the corresponding element of b. Otherwise, the result is 0.
Table 306. Any Element Less Than or Equal

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector bool char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
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<tr>
<td>char</td>
<td>vector unsigned char</td>
<td>vector bool char</td>
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<tr>
<td>vector signed short</td>
<td>vector signed short</td>
<td>vector bool short</td>
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<td>vector bool short</td>
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<td>vector unsigned short</td>
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<td>vector bool short</td>
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<td>vector signed int</td>
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<td>vector bool int</td>
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<td>vector signed long long</td>
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<td>vector bool long long</td>
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<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
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<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td></td>
</tr>
</tbody>
</table>

vec.any.lt: Any Element Less Than

d = vec.any.lt(a, b)

Tests whether any element of the first argument is less than the corresponding element of the second argument. The result is 1 if any element of a is less than the corresponding element of b. Otherwise, the result is 0.
Table 307. Any Element Less Than

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
<th>b</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector signed char</td>
<td>vector signed char</td>
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<tr>
<td></td>
<td>vector bool char</td>
<td>vector char</td>
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<td>vector bool char</td>
<td>vector signed char</td>
<td>vector unsigned char</td>
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<td>vector unsigned char</td>
<td>vector unsigned char</td>
<td>vector bool char</td>
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<td>vector signed short</td>
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<td>vector bool short</td>
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<td>vector unsigned short</td>
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<td>vector bool short</td>
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<tr>
<td>vector signed int</td>
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<td>vector bool int</td>
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<td>vector bool int</td>
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<td>vector unsigned int</td>
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<td>vector unsigned int</td>
<td>vector unsigned int</td>
<td>vector bool int</td>
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<tr>
<td>vector signed long long</td>
<td>vector signed long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
<td>vector bool long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_any_nan: Any Element Not a Number

\[ d = \text{vec\_any\_nan}(a) \]

Tests whether any element of the given vector is a NaN. The result is 1 if any element of a is a NaN. Otherwise, the result is 0.

Table 308. Any Element Not a Number

<table>
<thead>
<tr>
<th>d</th>
<th>a</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
</tr>
</tbody>
</table>

vec_any_ne: Any Element Not Equal

\[ d = \text{vec\_any\_ne}(a, b) \]

Tests whether any set of corresponding elements of the given vectors are not equal. The result is 1 if any element of a is not equal to the corresponding element of b. Otherwise, the result is 0.
### Table 309. Any Element Not Equal

<table>
<thead>
<tr>
<th>$d$</th>
<th>$a$</th>
<th>$b$</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector bool char</td>
<td>vector bool char</td>
</tr>
<tr>
<td></td>
<td>vector signed char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector signed char</td>
<td>vector bool char</td>
<td>vector signed char</td>
</tr>
<tr>
<td></td>
<td>vector unsigned char</td>
<td>vector unsigned char</td>
</tr>
<tr>
<td>vector bool short</td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector signed short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector signed short</td>
<td>vector bool short</td>
<td>vector signed short</td>
</tr>
<tr>
<td></td>
<td>vector unsigned short</td>
<td>vector unsigned short</td>
</tr>
<tr>
<td>vector bool int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector signed int</td>
<td>vector bool int</td>
<td>vector signed int</td>
</tr>
<tr>
<td></td>
<td>vector unsigned int</td>
<td>vector unsigned int</td>
</tr>
<tr>
<td>vector bool long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector signed long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector signed long long</td>
<td>vector bool long long</td>
<td>vector signed long long</td>
</tr>
<tr>
<td></td>
<td>vector unsigned long long</td>
<td>vector unsigned long long</td>
</tr>
<tr>
<td>vector double</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>

### vec_any_nge: Any Element Not Greater Than or Equal

$d = \text{vec}\_\text{any\_nge}(a, b)$

Tests whether any element of the first argument is not greater than or equal to the corresponding element of the second argument. The result is 1 if any element of $a$ is not greater than or equal to the corresponding element of $b$. Otherwise, the result is 0.

### Table 310. Any Element Not Greater Than or Equal

<table>
<thead>
<tr>
<th>$d$</th>
<th>$a$</th>
<th>$b$</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>vector double</td>
<td>vector double</td>
</tr>
</tbody>
</table>
vec\_any\_ngt: Any Element Not Greater Than
\[ d = \text{vec\_any\_ngt}(a, b) \]
Tests whether any element of the first argument is not greater than the corresponding element of the second argument. The result is 1 if any element of \( a \) is not greater than the corresponding element of \( b \). Otherwise, the result is 0.

\[ \text{Table 311. Any Element Not Greater Than} \]
\[
\begin{array}{ccc}
  d & a & b \\
  \text{int} & \text{vector double} & \text{vector double} \\
\end{array}
\]

vec\_any\_nle: Any Element Not Less Than or Equal
\[ d = \text{vec\_any\_nle}(a, b) \]
Tests whether any element of the first argument is not less than or equal to the corresponding element of the second argument. The result is 1 if any element of \( a \) is not less than or equal to the corresponding element of \( b \). Otherwise, the result is 0.

\[ \text{Table 312. Any Element Not Less Than or Equal} \]
\[
\begin{array}{ccc}
  d & a & b \\
  \text{int} & \text{vector double} & \text{vector double} \\
\end{array}
\]

vec\_any\_nlt: Any Element Not Less Than
\[ d = \text{vec\_any\_nlt}(a, b) \]
Tests whether any element of the first argument is not less than the corresponding element of the second argument. The result is 1 if any element of \( a \) is not less than the corresponding element of \( b \). Otherwise, the result is 0.

\[ \text{Table 313. Any Element Not Less Than} \]
\[
\begin{array}{ccc}
  d & a & b \\
  \text{int} & \text{vector double} & \text{vector double} \\
\end{array}
\]

vec\_any\_numeric: Any Element Numeric
\[ d = \text{vec\_any\_numeric}(a) \]
Tests whether any element of the given vector is numeric (not a NaN). The result is 1 if any element of \( a \) is numeric (not a NaN). Otherwise, the result is 0.

\[ \text{Table 314. Any Element Numeric} \]
\[
\begin{array}{c}
  d \\
  \text{int} \\
\end{array}
\begin{array}{c}
  a \\
  \text{vector double} \\
\end{array}
\]

**Defining vector built-in functions from the operators**

The following function-like macros can be used to define some vector built-in functions, available on the XL C/C++ compilers for some other platforms, from the operators:

```c
#define vec_neg(a) (-(a)) // Vector Negate
#define vec_add(a, b) ((a) + (b)) // Vector Add
#define vec_sub(a, b) ((a) - (b)) // Vector Subtract
```
#define vec_mul(a, b) ((a) * (b)) // Vector Multiply
#define vec_div(a, b) ((a) / (b)) // Vector Divide
#define vec_and(a, b) ((a) & (b)) // Vector AND
#define vec_or(a, b) ((a) | (b)) // Vector OR
#define vec_xor(a, b) ((a) ^ (b)) // Vector XOR
#define vec_sl(a, b) ((a) << (b)) // Vector Shift Left
#define vec_sra(a, b) ((a) >> (b)) // Vector Shift Right
#define vec_sr(a, b) ((a) >> (b)) // Vector Shift Right Algebraic
#define vec_slo(a, b) vec_slb(a, (b) << 64) // Vector Shift Left by Octet
#define vec_sro(a, b) vec_srb(a, (b) << 64) // Vector Shift Right by Octet

Note: The vec_sra macro definition must only be used with first parameter having a vector signed types. Similarly, the vec_sr macro definition must only be used for vector unsigned types, to have the correct bits inserted on the shifted out bits.
Chapter 36. ANSI C/C++ 98 applications and C99

The z/OS XL C Compiler and z/OS Language Environment C runtime library are designed to support the Programming languages - C (ISO/IEC 9899:1999) standard and its amendments. This standard is commonly referred to as C99. The z/OS XL C++ compiler is also designed to support the latest ISO C++ 2003 (Programming languages - C++ (ISO/IEC 14882:2003) ) standard and the latest technical corrigendum.

The compiler language additions for C99 do not apply to C++ applications because the C++ standard does not mandate support for C99.

Obtaining C99 behavior with XL C

Obtaining C99 behavior with XL C

You obtain compiler behavior defined by the C99 language standard when you do either of the following:

- Use the c89 command with LANGLVL(STDC99) option.
- Use the c99 command (supported by the xlc utility) with the default language level.

When you want to obtain C99 extended support, do either of the following:

- Use the c89 utility with the LANGLVL(EXTC99) option.
- Use the c99 command with the LANGLVL(EXTENDED) option.

Using C99 functions in XL C++ applications

Using C99 functions in XL C++ applications

IBM has made some C99 functions accessible to the XL C++ compiler. These C99 functions are enabled by the individual LANGLVL or KEYWORD suboptions.

You can also obtain C99 behavior with the XL C++ compiler by using the following KEYWORD and LANGLVL suboptions:

- KEYWORD(REstrict) or LANGLVL(EXTENDED), which enable the restrict qualifier for improved aliasing information.
- LANGLVL(UCS), which enables support for valid universal character name ranges.
- LANGLVL(C99__FUNC__) or LANGLVL(EXTENDED), which enable the __func__ identifier for debugging assistance.

C++ applications can also access C99 runtime library functions by using feature test macros. See “Feature test macros that control C99 interfaces in XL C++ applications.”

Feature test macros that control C99 interfaces in XL C++ applications

Feature test macros that control C99 interfaces in XL C++ applications

The following C99 headers are not available to C++ applications:

- `<tgmath.h>`
- `<complex.h>` — If `<complex.h>` is included, the USL Complex Class Library version of this header file will be used.
- `<stdbool.h>`

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To expose C99 interfaces, C++ applications can define the appropriate feature test macros before including the identified header:

__ISOC99_SOURCE
Used to control exposure to new C99 interfaces that do not require a C99-compliant compiler. The application programmer defines this feature test macro to inform the compile time library that new C99 interfaces are desired. This feature test macro must be defined prior to inclusion of the first header in order to expose the new C99 interfaces that do not require a C99-compliant compiler. This feature test macro requires a minimum of the z/OS V1R2 C/C++ compiler and TARGET(zOSV1R5) in order to expose the new C99 interfaces.

__STDC_LIMIT_MACROS
Required by C++ applications wishing to expose limits of fixed-width integer types and limits of other integer types as documented in <stdint.h>. The __ISOC99_SOURCE feature test macro must be defined before this feature test macro.

__STDC_CONSTANT_MACROS
Required by C++ applications wishing to expose macros for integer constants as documented in <stdint.h>. The __ISOC99_SOURCE feature test macro must be defined before this feature test macro.

__STDC_FORMAT_MACROS
Required by C++ applications wishing to expose macros for format specifiers as documented in <inttypes.h>. The __ISOC99_SOURCE feature test macro must be defined before this feature test macro.

__TR1_C99
Used to control exposure to the C++ TR1 C99 name space as described in Chapter 8 of ISO/IEC DTR 19768: Draft Technical Report on C++ Library Extensions.

Using C99 functions in C++ applications when ambiguous definitions exist

The C++ standard namespace does not include any C99 functions. Therefore, when ambiguous definitions exist, C++ applications must access these functions through the global namespace. The syntax of the global namespace is ::function().

XL C++ applications that need C99 interfaces must use the required feature macros or, when ambiguous definitions exist, global namespace syntax (when ambiguous definitions exist).

Figure 166 on page 679 is an example of code that requires the global namespace syntax. In this example, std:: is not allowed for C99 interfaces.
#include <cstdio>

namespace FRED {
  int snprintf(char *b, size_t x, const char *f, ...) { return(x); }
};

using namespace FRED;

main() { char buf[512]; int rc;
  /*rc = snprintf(buf,32,"hello\n"); AMBIGUOUS */
  rc = ::snprintf(buf,32,"hello\n");
  rc = FRED::snprintf(buf,32,"hello\n");
  /*rc = std::snprintf(buf,32,"hello\n"); NOT ALLOWED */
}

Figure 166. Example of code that requires the global namespace syntax
Chapter 37. Writing applications for Single UNIX Specification, Version 3

As of z/OS V1R9, the most current UNIX standard, Single UNIX Specification, Version 3 (SUSv3), is defined by IEEE Std 1003.1-2001, updated in 2004 with the integration of the two corrigenda issued subsequent to the 2001 release. The standard, also known as The Open Group Base Specifications Issue 6, is aligned with the ISO/IEC 9899:1999 Programming Languages - C standard. The new UNIX standard draws from the POSIX.1 and POSIX.2 specifications and their amendments, as well as The Open Group Base Specifications Issue 5 and The Open Group Technical Standard, January 2000, Networking Services, Issue 5.2.


In z/OS V1R9, the XL C/C++ Runtime Library provides a high degree of support for the Single UNIX Specification, Version 3. With the exception of the list of known non-compliances, library users may expect most conforming SUSv3 applications to compile and run on the z/OS platform in conformance with the standard.

Announcing your intentions

When compiling with system headers, there is a standard announcement mechanism for applications to notify the compiler that they are written for SUSv3. Notification is accomplished through the use of feature test macros _POSIX_C_SOURCE and _XOPEN_SOURCE. Applications insert either of the following definitions before any system header #include directives:

- #define _POSIX_C_SOURCE 200112L - Exposes the base POSIX namespace of SUSv3.
- #define _XOPEN_SOURCE 600 - Exposes the X/Open System Interface (XSI) extension of SUSv3.

Because XSI is a superset of the POSIX base, _POSIX_C_SOURCE 200112L is implicit in the definition of _XOPEN_SOURCE 600 and does not need to be defined when _XOPEN_SOURCE 600 is defined.

Several other implementation-specific feature test macros impact support of SUSv3. An application may request SUSv3 threads support by defining _UNIX03_THREADS or as part of XSI. Because the Threads Option is a required component of XSI, you do not need to to define _UNIX03_THREADS when _XOPEN_SOURCE 600 is defined. Another new macro, _UNIX03_WITHDRAWN, preserves symbols withdrawn from the UNIX standard, making them visible in the SUSv3 namespace.

Before z/OS V1R9, other feature test macros enabled subsets of SUSv3 functionality. The _UNIX03_SOURCE macro has been used to expose a number of SUSv3 functions and constants missing from the XL C/C++ Runtime Library, before the more general implementation of SUSv3 in z/OS V1R9. The macro is additive, in that for a given target release, the compiler exposes all symbols exposed by _UNIX03_SOURCE for the target and any prior release. Given that any
symbol it exposes is part of XSI, the _UNIX03_SOURCE macro is subsumed by _XOPEN_SOURCE 600, and is redundant when the latter is defined.

Like _UNIX03_SOURCE, the definition of _OPEN_THREADS 2 or _OPEN_THREADS 3 enables a specific subset of SUSv3 threads interfaces. Similarly, these interfaces are also exposed by defining _XOPEN_SOURCE 600 (or _UNIX03_THREADS). However, there are behavioral differences and some differences in the naming of constants. With _OPEN_THREADS, other than the new functions, which are SUSv3 compliant, the remainder of the thread-related functions behave according to the POSIX.4a, draft 6 specification, which differs from SUSv3.

Program developers have the option of writing SUSv3 applications that still use the old threads behavior. An application may override the implicit XSI threads behavior by defining both _OPEN_THREADS and _XOPEN_SOURCE 600, if there is a reason to maintain the previous POSIX.4a, draft 6 behavior. On the other hand, concurrent definition of the _UNIX03_THREADS and _OPEN_THREADS macros is not allowed and will generate a compile-time error message.

The intent of the XL C/C++ Runtime Library SUSv3 implementation is to maintain a great deal of flexibility and choice, supporting as many customer environments as possible. As in the case of _OPEN_THREADS, you can use most feature test macros that provide implementation-specific extensions with the SUSv3 macros, with the understanding that the resulting namespace does not conform to SUSv3. For more specific details about requirements or restrictions, see the individual feature test macros in Feature Test Macros in z/OS XL C/C++ Runtime Library Reference.

In addition to the feature test macros controlling that symbols are exposed in the system headers, two new environment variables determine behaviors at run time. In both cases, these variables impact error handling, enabling paths to provide errno information and fail a function for errors that were not previously detected. Default behavior for affected functions is unchanged. The new behavior must be explicitly enabled through a new setting of the environment variable.

• _EDC_SUSV3 - Default is unset. For parts of SUSV3 behavior, set to 1. For additional pole error related SUSV3 behavior, set to 2.
• _EDC_EOVERFLOW - Default is NO. For new behavior, set to YES.

When _EDC_SUSV3=1, SUSV3 error handling occurs in setenv(), readdir(), getnameinfo(), and tcgetsid(). When _EDC_SUSV3=2, in addition to behaviors introduced by _EDC_SUSV3=1, error handling compliant with SUSV3 occurs in log(), logf(), log1(), log10(), log10f(), log10l(), log1p(), log1pf(), log1pl(), log2(), log2f(), log2l(), pow(), and powl(). With _EDC_EOVERFLOW=YES, overflow detection takes place in ftell1(), fseek(), fstat(), lstat(), stat(), and mmap(). The EOVERFLOW error checking is for 31-bit applications only. For more specific information about behavior affected by these environment variables, see the individual function descriptions in z/OS XL C/C++ Runtime Library Reference.

Testing the environment

Many symbols have been added in <limits.h> and <unistd.h> to support SUSv3. Some of these symbols are tested at compile time by the preprocessor to allow differential compiles based on the values found, while others are intended for use by sysconf(), pathconf(), fpathconf(), and confstr() to test the version of the
Table 315. SUSv3 options and option groups

<table>
<thead>
<tr>
<th>Description</th>
<th>Symbol Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>File Synchronization</td>
<td>_POSIX_FSYNC</td>
</tr>
<tr>
<td>Memory Mapped Files</td>
<td>_POSIX_MAPPED_FILES</td>
</tr>
<tr>
<td>Memory Protection</td>
<td>_POSIX_MEMORY_PROTECTION</td>
</tr>
<tr>
<td>Realtime Signals Extension</td>
<td>_POSIX_REALTIME_SIGNALS</td>
</tr>
<tr>
<td>Thread Stack Address Attribute</td>
<td>_POSIX_THREAD_ATTR_STACKADDR</td>
</tr>
<tr>
<td>Thread Stack Size Attribute</td>
<td>_POSIX_THREAD_ATTR_STACKSIZE</td>
</tr>
<tr>
<td>Thread Process-Shared Synchronization</td>
<td>_POSIX_THREAD_PROCESS_SHARED</td>
</tr>
<tr>
<td>Thread-Safe Functions</td>
<td>_POSIX_THREAD_SAFE_FUNCTIONS</td>
</tr>
<tr>
<td>Threads</td>
<td>_POSIX_THREADS</td>
</tr>
<tr>
<td>Encryption Option Group</td>
<td>_XOPEN_CRYPT</td>
</tr>
<tr>
<td>Legacy Option Group</td>
<td>_XOPEN_LEGACY</td>
</tr>
<tr>
<td>XSI Streams Option Group</td>
<td>_XOPEN_STREAMS</td>
</tr>
<tr>
<td>XSI Extension</td>
<td>_XOPEN_UNIX</td>
</tr>
</tbody>
</table>

What is different in SUSv3

The SUSv3 implementation adds a number of new functions to the XL C/C++ Runtime Library, while applying modifications to the signatures of some existing functions in SUSv3 as result of the following behaviors:

- Addition or removal of arguments.
- Use of const declarator.
- Specialization of argument types.
- Use of restrict keyword.

The SUSv3 namespace excludes all withdrawn headers, functions, external variables, and constants. The specification further targets additional symbols for removal in a future version of the standard.

As noted earlier, Single UNIX Specification, Version 3 aligns with ISO/IEC 9899:1999, is commonly referred to as the C99 language standard. In some cases, SUSv3 extends the C99 definition, although in the case of a conflict, it always defers to the C99 standard. For this reason, applications compiled for SUSv3 are also implicitly C99, and you do not need to define feature test macro _ISOC99_SOURCE when _XOPEN_SOURCE 600 or _POSIX_C_SOURCE 200112L is defined.

Beyond these obvious differences in the library, there are other behavioral differences. One of the more notable differences is the change in the return value of most threads functions. The POSIX.4a, draft 6 threads behavior indicates a return of -1 on failure with the error code set in errno. In SUSv3, the majority of these functions now return the error code on failure rather than a value of -1. With the exception of pthread_getspecific(), the z/OS implementation will continue to set errno in addition to returning the error code.
For complete details about syntactical differences and special behavior of functions, see the individual function descriptions in *z/OS XL C/C++ Runtime Library Reference*.

**Symbols withdrawn in SUSv3**

Functions, headers, and external variables that comprised the Legacy Feature Group in Single UNIX Specification, Version 2 are removed and not part of SUSv3. Also, any symbols that were marked obsolescent in Version 2 have been removed.

For a complete list of the withdrawn symbols, see the description of `_UNIX03_WITHDRAWN in Feature Test Macros in z/OS XL C/C++ Runtime Library Reference`. In the case of headers that have been withdrawn, there is no special mechanism employed. An application simply includes them, like any other non-standard header. The withdrawn headers are `<re_comp.h>`, `<regexp.h>`, and `<varargs.h>`. Dependencies on symbols that are not part of the SUSv3 namespace affect portability and, if this is an issue, make such applications nonconforming.

**Candidates for removal in a future version**

In addition to symbols withdrawn from the SUSv3 namespace, a number of symbols have been marked obsolete in the POSIX base or added to the Legacy Option for XSI that may be removed from the Single UNIX Specification in a future version.

**Obsolescent**: `bsd_signal()`, `gethostbyaddr()`, `gethostbyname()`, `h_errno`, `pthread_attr_getstackaddr()`, `pthread_attr_setstackaddr()`, `scalb()`, `ualarm()`, `usleep()`, `vfork()`

**Legacy Option** `bcmp()`, `bcopy()`, `bzero()`, `ecvt()`, `fcvt()`, `ftime()`, `gcvt()`, `getwd()`, `index()`, `mktemp()`, `rindex()`, `utimes()`, `wcswcs()`

**Implementation compliance**

IBM makes no claim that the z/OS platform complies with Single UNIX Specification, Version 3 or that the z/OS XL C/C++ Runtime Library contains a complete implementation of the C programming interfaces and headers found in the Base Definitions of this standard. While the library implementation comes close, a number of known discrepancies remain in z/OS R9. The following summary lists those discrepancies from SUSv3 behavior that have been identified.

The z/OS XL C/C++ Runtime Library does not support:

- `accept()` – ECONNABORTED from accept() when a connection has been aborted.
- `alarm()` and `setitimer()` deliver SIGALRM to the thread that invoked the service rather than at the process level.
- `exec()` family of functions in a multi-threaded environment.
- `fgetc()`, `fgetwc()`, `read()` – EOVERFLOW in `fgetc()`, `fgetwc()`, or `read()` when reading at or beyond a file offset maximum.
- `getsockopt()`, `setsockopt()` – Options `SO_DONTROUTE`, `SO_RCVLOWAT`, `SO_RCVTIMEO`, `SO_SNDOLOWAT`, `SO_SNDTIMEO` in `getsockopt()` or `setsockopt()`.
- EDOM in `setsockopt()` when send/receive timeout values are too big to fit into the timeout fields in the socket structure.
EISCONN in setsockopt() when socket is already connected and a specified option cannot be set while the socket is connected.

- `fpathconf()` and `pathconf()` do not support the symbols shown in Table 316.

### Table 316. Symbols not supported

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>_PC_FILESIZEBITS</code></td>
<td>(FILESIZEBITS)</td>
</tr>
<tr>
<td><code>_PC_2_SYMLINKS</code></td>
<td>(POSIX2_SYMLINKS)</td>
</tr>
<tr>
<td><code>_PC_ALLOC_SIZE_MIN</code></td>
<td>(POSIX_ALLOC_SIZE_MIN)</td>
</tr>
<tr>
<td><code>_PC_REC_INCR_XFER_SIZE</code></td>
<td>(POSIX_REC_INCR_XFER_SIZE)</td>
</tr>
<tr>
<td><code>_PC_REC_MAX_XFER_SIZE</code></td>
<td>(POSIX_REC_MAX_XFER_SIZE)</td>
</tr>
<tr>
<td><code>_PC_REC_MIN_XFER_SIZE</code></td>
<td>(POSIX_REC_MIN_XFER_SIZE)</td>
</tr>
<tr>
<td><code>_PC_REC_XFER_ALIGN</code></td>
<td>(POSIX_REC_XFER_ALIGN)</td>
</tr>
<tr>
<td><code>_PC_SYMLINK_MAX</code></td>
<td>(SYMLINK_MAX)</td>
</tr>
<tr>
<td><code>_PC_ASYNC_IO</code></td>
<td>(POSIX_ASYNC_IO)</td>
</tr>
<tr>
<td><code>_PC_PRIO_IO</code></td>
<td>(POSIX_PRIO_IO)</td>
</tr>
<tr>
<td><code>_PC_SYNC_IO</code></td>
<td>(POSIX_SYNC_IO)</td>
</tr>
</tbody>
</table>

- `mmap()` – ENXIO in `mmap()` when MAP_FIXED is specified in flags and the combination of `addr`, `len`, and `off` is not valid for the file descriptor.
- `msync()` – EBUSY during `msync()` when some or all addresses in the range starting at `addr` and continuing for `len` bytes are locked, and MS_INVALIDATE is specified.
- `recvmsg()` – EMSGSIZE in `recvmsg()` when `msg_iovlen` in the `msghdr` pointed to by `msg` is less than or equal to 0, or is greater than `{IOV_MAX}`.
- `regexec()` - Use of the restrict keyword is not supported.
- `socket()`, `socketpair()` – SOCK_SEQPACKET type in `socket()` and `socketpair()`.
- `stderr` open for reading.
Chapter 38. Saved compile-time options information

Following a successful compilation, the application executable file will always include compile-time options information in a compact form. This information supports determination of runtime problems. Saved compile-time options information includes:

- Fixed subset of compilation options for each source file compiled.
- Source file name for each source file compiled.
  - The source file name of the compilation unit for which the options are saved is the first entry in the source file and component version information block.
  - For names longer than 252 characters, only the last 252 bytes of the source file name are provided.
  - The name does not include path information for UNIX files and only the member name is provided for partitioned data sets.
  - A dummy name “IPA Link” is provided for programs optimized with IPA.
- Version information for each compiler component that is active during the compilation.
  - You can use the version information to determine the compile-time maintenance level. If the maintenance level is not the most current, there might be an update available that solves the problem.
  - This version information will be the same as the information produced using the PHASEID compiler option. For further information about the PHASEID compiler option, see z/OS XL C/C++ User’s Guide.
  - Although information about the debug writer is not included because the debug writer runs after the code generation, that information is available inside the .dbg file.

A compilation flag in the Program Prolog Area-2 (PPA2) indicates the presence of saved options information. If the service string is specified, the saved option string follows it. Otherwise the saved options information follows the time stamp string. For more information about PPA2, see z/OS Language Environment Vendor Interfaces.
Saved options information layout

Figure 167 shows the layout of the saved options information.

```c
#define USHRT unsigned short
#define UINT unsigned int
typedef struct SOS_s {
    UINT sos_words : 8, /* 0xFF000000 sizeof(SOS)/4 */
    sos_version : 8, /* 0x00FF0000 version number */
        /* 1 - as of XL C/C++ 1.10 */
        /* 2 - as of XL C/C++ 1.11 */
        /* 3 - as of XL C/C++ 1.13 */
        /* 4 - as of XL C/C++ 2.1 */
        /* 5 - as of XL C/C++ 2.1 PTF */
        /* 6 - as of XL C/C++ 2.1.1 */
        /* 7 - as of XL C/C++ 2.2 */
    sos_arch : 8, /* 0x0000FF00 ARCHITECTURE */
    sos_tune : 8; /* 0x000000FF TUNE */
        /* offset: 4 */
    UINT sos_csect : 1, /* 0x80000000 0 - NOCSECT */
        /* 1 - CSECT */
    sos_version_info :15, /* 0x7FFF0000 version list (PHASEIDs location - */
        /* offset/4 from SOS start) */
    sos_locale_ccsid :16; /* 0x0000FFFF CCSID from the LOCALE */
        /* offset: 8 */
    USHRT sos_lit_ccsid; /* 0xFFFF0000 CONVLIT(xx) */
    USHRT sos_wlit_ccsid; /* 0x0000FFFF CONVLIT(WCHAR|UNICODE) */
        /* offset: 12 */
    UINT sos_target_rel; /* 0xFFFFFFFF TARGET(release value in HEX) */
        /* As given by __TARGET_LIB__ */
        /* offset: 16 */
    UINT sos_initauto_val; /* 0xFFFFFFFF INITAUTO value */
} SOS_s

Definition of saved options information layout (Part 1 of 5)

Figure 167. Definition of saved options information layout
/* offset: 20 */

UINT sos_enumsize : 3, /* 0xE0000000 0 - ENUMSIZE(SMALL) */
   /* 1 - ENUMSIZE(INT) */
   /* 2 - ENUMSIZE(INTLONG) */
   /* 3 - ENUMSIZE(1) */
   /* 4 - ENUMSIZE(2) */
   /* 5 - ENUMSIZE(4) */
   /* 6 - ENUMSIZE(8) */

sos_round : 3, /* 0x1C000000 0 - ROUND(N) */
   /* 1 - ROUND(Z) */
   /* 2 - ROUND(P) */
   /* 3 - ROUND(M) */

sos_round_dfp : 4, /* 0x03C00000 0 - NODFP */
   /* 1 - ROUND(DN) */
   /* 2 - ROUND(DM) */
   /* 3 - ROUND(DP) */
   /* 4 - ROUND(DZ) */
   /* 5 - ROUND(DNA) */
   /* 6 - ROUND(DM) */
   /* 7 - ROUND(DNZ) */

sos_flt_hex : 1, /* 0x00200000 0 - FLOAT(HEX) */
   /* 1 - FLOAT(IEEE) */

sos_flt_afp : 2, /* 0x00180000 0 - FLOAT(NOAFP) */
   /* 1 - FLOAT(AFP(NOVOLATILE)) */
   /* 2 - FLOAT(AFP(VOLATILE)) */

sos_flt_fold : 1, /* 0x00040000 FLOAT(FOLD) */

sos_flt_maf : 1, /* 0x00020000 FLOAT(MAF) */

sos_flt_rrm : 1, /* 0x00010000 FLOAT(RRM) */

sos_aggrcopy : 1, /* 0x00008000 0 - AGGRCOPY(NOOVERLAP) */
   /* 1 - AGGRCOPY(overlap) */
   /* 2 - AGGRCOPY(overlapping) */

sos_bitfield : 1, /* 0x00004000 0 - BITFIELD(UNSIGNED) */
   /* 1 - BITFIELD(SIGNED) */

sos_chars : 1, /* 0x00002000 0 - CHARS(UNSIGNED) */
   /* 1 - CHARS(SIGNED) */

sos_hgpr : 2, /* 0x00001800 0 - NOHGPR */
   /* 1 - HGPR(PRESERVE) */
   /* 2 - HGPR(NOPRESERVE) */

sos_initauto : 2, /* 0x00000600 0 - NOINITAUTO */
   /* 1 - INITAUTO (xx) */
   /* 2 - INITAUTO (xx, WORD) */

sos_inline : 2, /* 0x00000180 0 - NOINLINE */
   /* 1 - INLINE(AUTO) */
   /* 2 - INLINE(NOAUTO) */

sos_ipa : 2, /* 0x00000600 0 - NOIPA */
   /* 1 - IPA(OBJECT) */
   /* 2 - IPA(NOOBJECT) */

sos_unroll : 2, /* 0x00000018 0 - UNROLL(AUTO) */
   /* 1 - UNROLL(NO) */
   /* 2 - UNROLL(YES) */

sos_dll : 2, /* 0x00000006 0 - NODLL */
   /* 1 - DLL(NOCALLBACKANY) */
   /* 2 - DLL(CALLBACKANY) */

sos_exportall : 1; /* 0x00000001 EXPORTALL */

Definition of saved options information layout (Part 2 of 5)
/* offset: 24 */

UINT sos_ansialias : 1, /* 0x80000000 ANSIALIAS */
sos_argparse : 1, /* 0x40000000 ARGPARSE */
sos_compress : 1, /* 0x20000000 COMPRESS */
sos_compact : 1, /* 0x10000000 COMPACT */
sos_execops : 1, /* 0x08000000 EXECOPS */
sos_goff : 1, /* 0x04000000 GOFF */
sos_hot : 1, /* 0x02000000 HOT */
sos_ignerrno : 1, /* 0x01000000 IGNERRNO */
sos_libansi : 1, /* 0x00800000 LIBANSI */
sos_upconv : 1, /* 0x00400000 UPCONV */
sos_longname : 1, /* 0x00200000 LONGNAME */
sos_lp64 : 1, /* 0x00100000 LP64 */
sos_rent : 1, /* 0x00080000 0 - NORENT */
/* 1 - RENT */
sos_wsizeof : 1, /* 0x00040000 WSIZEOF */
sos_roconst : 1, /* 0x00020000 ROCONST */
sos_rostring : 1, /* 0x00010000 ROSTRING */
sos_start : 1, /* 0x00008000 START */
sos_strict : 1, /* 0x00004000 STRICT */
sos_strictind : 1, /* 0x00002000 STRICT_INDUCTION */
sos_xpl_bkchn : 1, /* 0x00001000 XPLINK(BACKCHAIN) */
sos_xpl_callbk : 1, /* 0x00000000 XPLINK(CALLBACK) */
sos_xpl_grd : 1, /* 0x00000400 XPLINK(GUARD) */
sos_xpl_oscall : 2, /* 0x00000300 0 - XPLINK(OSCALL(NOSTACK)) */
/* 1 - XPLINK(OSCALL(DOWNSTACK)) */
/* 2 - XPLINK(OSCALL(UPSTACK)) */
sos_hook_line : 1, /* 0x00000080 DEBUG(HOOK(LINE)) */
sos_hook_block : 1, /* 0x00000040 DEBUG(HOOK(BLOCK)) */
sos_hook_path : 1, /* 0x00000020 DEBUG(HOOK(PATH)) */
sos_hook_func : 1, /* 0x00000010 DEBUG(HOOK(FUNC)) */
sos_hook_call : 1, /* 0x00000008 DEBUG(HOOK(CALL)) */
sos_debug_sym : 1, /* 0x00000004 DEBUG(SYMBOL) */
sos_debug_fmt : 2; /* 0x00000003 0 - NODEBUG */
/* 1 - DEBUG(Format(ISD)) */
/* 2 - DEBUG(Format(DWARF)) */

Definition of saved options information layout (Part 3 of 5)
/* offset: 28 */

UINT sos_gonumber : 1, /* 0x80000000 GONUMBER */
sos_target : 2, /* 0x60000000 0 - TARGET(LE) */
/* 1 - TARGET(IMS) */
sos_plist : 1, /* 0x10000000 0 - PLIST(HOST) */
/* 1 - PLIST(OS) */
sos_optlevel : 4, /* 0x0F000000 OPTIMIZE */
sos_redir : 1, /* 0x00800000 REDIR */
sos_cvft : 1, /* 0x00400000 CVFT */
sos_objmodel : 2, /* 0x00300000 0 - OBJECTMODEL(CLASSIC) */
/* 1 - OBJECTMODEL(IBM) */
sos_exh : 1, /* 0x00300000 EXH */
sos_rtti : 1, /* 0x00040000 RTTI */
sos_namemangling : 6, /* 0x0003F000 0 - NAMEMANGLING(zOSV1R2) and */
/* NAMEMANGLING(zOSV1R5_DEFAULT) */
/* 1 - NAMEMANGLING(ANSI) */
/* 2 - NAMEMANGLING(COMPAT) and */
/* NAMEMANGLING(OSV2R10) */
/* 3 - NAMEMANGLING(zOSV1R5_ANSI) */
/* 4 - NAMEMANGLING(zOSV1R7_ANSI) */
/* 5 - NAMEMANGLING(zOSV1R8_ANSI) */
/* 6 - NAMEMANGLING(zOSV1R9_ANSI) */
/* 7 - NAMEMANGLING(zOSV1R10_ANSI) */
/* 8 - NAMEMANGLING(zOSV1R11_ANSI) */
/* 9 - NAMEMANGLING(zOSV1R12_ANSI) */
/* 10 - NAMEMANGLING(zOSV2R1_ANSI) */
/* 11 - NAMEMANGLING(zOSV2R1M1_ANSI) */
sos_ansisinit : 1, /* 0x00000800 LANGLVL(ANSISINIT) */
sos_newexcp : 1, /* 0x00000400 LANGLVL(NEWEXCP) */
sos_oldmath : 1, /* 0x00000200 LANGLVL(OLDMATH) */
sos_oldstr : 1, /* 0x00000100 LANGLVL(OLDMPLALIGN) */
sos_restrict : 1, /* 0x00000080 RTCHECK */
sos_restrict_param : 1; /* 0x00000001 RESTRICT */
sos_prefetch : 1, /* 0x00000020 PREFETCH */
/* Applicable to zOSV1R11 and later */
sos_rtc : 1, /* 0x00000010 RTCHECK */
/* Applicable to zOSV1R11 and later */
sos_rtc_bounds : 1, /* 0x00000008 RTCHECK(BOUNDS) */
/* Applicable to zOSV1R11 and later */
sos_rtc_divzero : 1, /* 0x00000004 RTCHECK(DIVZERO) */
/* Applicable to zOSV1R11 and later */
sos_rtc_nullptr : 1, /* 0x00000002 RTCHECK(NULLPTR) */
/* Applicable to zOSV1R11 and later */
sos_restrict_param : 1; /* 0x00000001 RESTRICT */
/* Applicable to zOSV1R12 and later */

Definition of saved options information layout (Part 4 of 5)
/* offset: 32 */

UNIT sos_rvaluerefs : 1, /* 0x80000000 LANGLVL(RVALUEREFERENCES) */
    /* Applicable to zOSV2R1 and later */
sos_refcollapsing : 1, /* 0x40000000 LANGLVL(REFERENCECOLLAPSING) */
    /* Applicable to zOSV2R1 and later */
sos_rightanglebkt : 1, /* 0x20000000 LANGLVL(RIGHTANGLEBRACKET) */
    /* Applicable to zOSV2R1 and later */
sos_scopedenum : 1, /* 0x10000000 LANGLVL(SCOPEDENUM) */
    /* Applicable to zOSV2R1 and later */
sos_debug_level : 4, /* 0x0F000000 DEBUG(LEVEL(0-9)) */
    /* Applicable to zOSV2R1 and later */
sos_subscript_wrap : 1, /* 0x00800000 STRICT(SUBSTRICTWRAP) */
    /* Applicable to zOSV2R1 and later */
sos_tempsaslocals : 1, /* 0x00400000 LANGLVL(TEMPSASLOCALS) */
    /* Applicable to zOSV1R13 and later */
sos_smp : 1, /* 0x00200000 SMP */
    /* Applicable to zOSV2R1 and later */
sos_smp_opt : 1, /* 0x00100000 SMP(OPT) */
    /* Applicable to zOSV2R1 and later */
sos_smp_explicit : 1, /* 0x00080000 SMP(EXPLICIT) */
    /* Applicable to zOSV2R1 and later */
sos_threaded : 1, /* 0x00040000 THREADED */
    /* Applicable to zOSV2R1 and later */
sos_funcevent : 1, /* 0x00020000 FUNCEVENT */
    /* Applicable to zOSV2R1M1 and later */
sos_vector : 1, /* 0x00010000 VECTOR */
    /* Applicable to zOSV2R1M1 and later */
sos_asm : 1, /* 0x00008000 ASM */
    /* Applicable to zOSV2R1M1 and later */
sos_unrolln : 8, /* 0x000007F00 UNROLL(N) where 0 <= N <= 255 */
    /* Applicable to zOSV2R1M1 and later */
sos_check_pl_new : 1, /* 0x00000040 LANGLVL(CHECKPLACEMENTNEW) */
    /* Applicable to zOSV2R1M1 and later */
sos_check_new : 1, /* 0x00000020 CHECKNEW */
    /* Applicable to zOSV2R1M1 and later */
sos_vector_is_type : 1, /* 0x00000010 VECTOR(TYPE) */
    /* Applicable to zOSV2R2 and later */
sos_vector_autosimd : 1, /* 0x00000008 VECTOR(AUTOSIMD) */
    /* Applicable to zOSV2R2 and later */
sos_padding : 3;

} SOS_t;

Definition of saved options information layout (Part 5 of 5)
Part 5. Performance optimization

This part describes guidelines for improving the performance of your XL C/C++ application. Performance improvement can be achieved through coding, compiling, and the runtime environment. The following chapters discuss guidelines for these three areas:

- Chapter 39, “Improving program performance,” on page 695
- Chapter 40, “Using built-in functions to improve performance,” on page 717
- Chapter 41, “I/O Performance considerations,” on page 719
- Chapter 42, “Improving performance with compiler options,” on page 723
- Chapter 45, “Optimizing the system and Language Environment,” on page 777
- Chapter 46, “Balancing compilation time and application performance,” on page 781
- Chapter 47, “Stepping through optimized code using the dbx debugger utility,” on page 785

You may also find useful information in the IBM Redbook Tuning Large C/C++ Applications on z/OS UNIX System Services. This Redbook is available on the web at http://www.redbooks.ibm.com/abstracts/sg245606.html.
Chapter 39. Improving program performance

This information discusses coding guidelines that improve the performance of a C or C++ application. While they are most effective when creating new code, these guidelines can also provide a gradual performance improvement when they are consistently used when porting or fixing areas of the code. The guidelines cover the following topics:

- “Writing code for performance”
- “Using C++ constructs in performance-critical code”
- “Using explicit instantiation declarations (C++11 only)” on page 697
- “ANSI aliasing rules” on page 697
- “Using ANSI aliasing rules” on page 699
- “Using variables” on page 701
- “Passing function arguments” on page 702
- “Coding expressions” on page 703
- “Coding conversions” on page 704
- “Arithmetical considerations” on page 704
- “Using loops and control constructs” on page 705
- “Choosing a data type” on page 705
- “Using built-in library functions and macros” on page 707
- “Using library extensions” on page 709
- “Using #pragmas” on page 710
- “Using rvalue references (C++11)” on page 712

Writing code for performance

When you write code, it is a good practice to write it so that you can understand it when you simply read it on a printed page or on a screen, without having to refer to anything else. If the code is simple and concise, both the programmer and the compiler can understand it easily. Code that is easy for the compiler to understand is also easy for it to optimize. If you follow this practice you might not only create code that performs well on execution, you might also create code that compiles more quickly.

If you follow the guidelines in this information, you will create code that performs well on execution and can be compiled efficiently.

Using C++ constructs in performance-critical code

Note: The discussion in this information applies to high-level language constructs that might seriously degrade the performance of C++ programs. All other coding discussions in this information apply to both C and C++ programs.

Be aware that in C++, more than in C, certain coding constructs can lead to n-to-1, m-to-1 or even z-to-1 code expansion. You can create well-performing code with these constructs, but you must use them carefully and appropriately, especially when you are writing critical-path or high-frequency code.
When writing performance-critical C++ programs, ensure that you understand why problems might occur and what you can do about them if you use any of the following high-level language constructs:

**Virtual**

The virtual construct is an important part of object-oriented coding and can be very useful in removing the if and switch logic from an application. Programmers often use virtual and neglect to remove the switch logic. Note the following:

- The use of a virtual construct (like the use of a pointer and unlike the use of if statements) prevents the compiler from knowing how that construct is defined, which would provide the compiler with an optimization opportunity. In other words, when you use a virtual construct instead of if or switch statements, you limit optimization opportunities.
- In a non-XPLINK module, because of function overhead, virtual functions are costlier to execute than straight-line code with if or switch statements.

**Exception handling**

When exception handling is available (that is, when you are using the EXH compiler option), opportunities for both normal optimizations and for inlining are limited. This is because the compiler must generate extra code to keep track of execution events and to ensure that all required objects are caught by the correct routines.

When you use the C++ try and catch blocks, the compiler creates obstacles to optimization. The compiler cannot pull common code out of a try block because it might trigger an exception that would need to be caught. Similarly, code cannot be pulled out of a catch block because:

- The code in a catch block is triggered far down the call chain, after the exception has occurred.
- After a catch has occurred, the compiler must ensure that all requested tasks have been executed.

You might improve compiler performance by:

- Removing dependencies on C++ exception handling from your code.
- Compiling with the NOEXH compiler option.

**Dynamic casts/Runtime type identification (RTTI)**

A dynamic cast (also known as RTTI) is a coding construct that delays, until run time, the determination of which code is to be executed. This limits the potential for optimization. In addition, the process of actually doing the dynamic cast involves multiple function calls and large amounts of code.

**Note:** We strongly recommend that RTTI/dynamic casts not be used in performance-critical code. You can often avoid the use of RTTI through careful application design.

**iostream**

As discussed in Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23 and in Chapter 9, “Using C and C++ standard streams and redirection,” on page 63, iostream is often built upon the standard C I/O library (fprintf, fopen, fclose, fread, fwrite). For I/O performance-critical portions of your application, it is often faster to use the C I/O functions explicitly instead of iostream.
**Note:** You must be careful if you are mixing the C++ stream classes with the C library. For more information, see Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23.

**Standard Template Library and other class libraries**

These libraries are very convenient and are often well coded, but you must remember that each use of a class can involve one or more function calls. If you keep this in mind when coding, you can design applications that use these libraries efficiently. For example, you would not initialize all local string variables to the NULL string and then redefine the string on first reference.

**new/delete**

New C++ applications on z/OS often depend heavily on `new` and `delete` operators because they are commonly one of the first things taught in a C++ introductory course, and many courses never explicitly teach that classes can also be automatic (default for local) or global variables.

You should be aware that the `new` and `delete` operators are costlier to use than variables. Also, before using `new`, you should carefully consider:

- The scope/usage pattern of the variable
- Whether an automatic (local) or global variable is more appropriate

**Note:** You can ensure that all memory and storage requests are properly optimized by following the instructions given in Chapter 42, “Improving performance with compiler options,” on page 723 and “Optimizing memory and storage” on page 777.

---

**Using explicit instantiation declarations (C++11 only)**

Use template explicit instantiation declarations to suppress implicit template instantiations. This helps reduce the collective size of the object files and shorten compiler time. This technique is described in “Using explicit instantiation declarations (C++11 only)” on page 462.

---

**ANSI aliasing rules**

You must indicate whether your source code conforms to the ANSI aliasing rules when you use the IPA or the OPT(2) (or above) z/OS XL C/C++ compiler options. If the code does not conform to the rules, it must be compiled with NOANSIALIAS. Incorrect use of these options might generate bad code.

**Note:** The compiler expects that the source code conforms to the ANSI aliasing rules when the ANSIALIAS option is used. This option is on by default.

The ANSI aliasing rules are part of the ISO C Standard, and state that a pointer can be dereferenced only to an object of the same type or compatible type. Because the z/OS XL C/C++ compiler follows these rules during optimization, the developer must create code that conforms to the rules.

**Note:** The common coding practice of casting a pointer to an incompatible type and then dereferencing it violates ANSI aliasing rules.

When you are using ANSI aliasing, you can cast an integer pointer only to the types described in Table 317 on page 698.
Table 317. Examples of acceptable alias types

<table>
<thead>
<tr>
<th>Type</th>
<th>Reason for acceptance</th>
</tr>
</thead>
<tbody>
<tr>
<td>int</td>
<td>This is the declared type of the object.</td>
</tr>
<tr>
<td>const int or volatile int</td>
<td>These types are the qualified version of the declared type of the object.</td>
</tr>
<tr>
<td>unsigned int</td>
<td>This is a signed or unsigned type corresponding to the declared type of the object.</td>
</tr>
<tr>
<td>const unsigned int or</td>
<td>These types are the signed or unsigned types corresponding to a qualified version of</td>
</tr>
<tr>
<td>volatile unsigned int</td>
<td>the declared type of the object.</td>
</tr>
<tr>
<td>struct foo {</td>
<td>This is an aggregate or union type that includes one of the aforementioned types</td>
</tr>
<tr>
<td>unsigned int bar;</td>
<td>among its members. This can include, recursively, a member of a subaggregator-contained</td>
</tr>
<tr>
<td>};</td>
<td>union.</td>
</tr>
<tr>
<td>char or unsigned char</td>
<td>The char pointers are an exception to the rules, as any pointer can be used to point to</td>
</tr>
<tr>
<td></td>
<td>a char variable.</td>
</tr>
</tbody>
</table>

Conversely, your code breaks the aliasing rules if it casts a float to an int and then assigns it to the int pointer.

For more information, see type-based aliasing in z/OS XL C/C++ Language Reference and ANSIALIAS in z/OS XL C/C++ User’s Guide.

You can cast and mix data types as long as you are careful how you intermix values and their pointers in your code. The compiler follows the ANSI aliasing rules to determine:

- Which variables must be stored into memory before you read a value through a pointer
- Which variables must be updated from memory after you have updated a value through a pointer

When you use the NOANSIALIAS option, the compiler generates code to accommodate worst-case assumptions (for example, that any variable could have been updated by the store through a pointer). This means that every variable (local and global) must be stored in memory to ensure that any value can be read through a pointer. This severely limits the potential for optimization.

```c
int ei1;
float ef1;
int *eip1;
float *efp1;

float exmpl ()
{
    ef1 = 3.0;
    ei1=5;
    *efp1 = ef1;
    *eip1 = ei1;
    return *efp1;
}
```

Table 318 on page 699 shows the difference between code generated with, and without, ANSI aliasing.
Table 318. Comparison of code generated with the ANSIALIAS and NOANSIALIAS options

<table>
<thead>
<tr>
<th>ANSIALIAS RENT and OPT(2)</th>
<th>NOANSIALIAS RENT and OPT(2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>* {</td>
<td>* {</td>
</tr>
<tr>
<td>* ef1 = 3.0;</td>
<td>* ef1 = 3.0;</td>
</tr>
<tr>
<td>L r4,=A(@CONSTANT_AREA)(,r3,94)</td>
<td>L r2,=A(@CONSTANT_AREA)(,r3,110)</td>
</tr>
<tr>
<td>L r2,=Q(EF1)(,r3,98)</td>
<td>L r14,CEECAA_(,r12,500)</td>
</tr>
<tr>
<td>LD f0,+CONSTANT_AREA(,r4,0)</td>
<td>L r4,=Q(EF1)(,r3,114)</td>
</tr>
<tr>
<td>L r14,CEECAA_(,r12,500)</td>
<td>L r15,=Q(EFP1)(,r3,118)</td>
</tr>
<tr>
<td>L r4,=Q(EFP1)(,r3,102)</td>
<td>LD f0,+CONSTANT_AREA(,r2,0)</td>
</tr>
<tr>
<td>L r1,#retvalptr_1(,r1,0)</td>
<td></td>
</tr>
<tr>
<td>STE f0,ef1(r2,r14,0)</td>
<td>* *efp1 = ef1;</td>
</tr>
<tr>
<td>L r15,efp1(r15,r14,0)</td>
<td>L r4,=Q(EF1)(,r3,122)</td>
</tr>
<tr>
<td>* ei1=5;</td>
<td>STE f0,ef1(r4,r14,0)</td>
</tr>
<tr>
<td>L r2,=Q(EI1)(,r3,110)</td>
<td>* *efp1 = ef1;</td>
</tr>
<tr>
<td>LA r0,</td>
<td>L r4,efp1(r15,r14,0)</td>
</tr>
<tr>
<td>L r4,ei1(r4,r14,0)</td>
<td>* *eip1 = eip1;</td>
</tr>
<tr>
<td>* *efp1 = ef1;</td>
<td></td>
</tr>
<tr>
<td>STE f0,(* )float(,r15,0)</td>
<td>L r0,eip1(r2,r14,0)</td>
</tr>
<tr>
<td>ST r0,eip1(r4,r14,0)</td>
<td></td>
</tr>
<tr>
<td>* *eip1 = eip1;</td>
<td>* *eip1 = eip1;</td>
</tr>
<tr>
<td>ST r0,( * )int(,r4,0)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>* return *efp1;</td>
</tr>
<tr>
<td></td>
<td>STD f0,#retval_1(,r1,0)</td>
</tr>
<tr>
<td></td>
<td>* }</td>
</tr>
</tbody>
</table>

- In the ANSIALIAS case:
  - f0, loaded with 3.0, is used whenever referring to ef1 or efp1
  - r0 is loaded with the value of 5, which is used for ei and eip
- In the NOANSIALIAS case, the loads and stores are always done. This removes opportunities for optimizations. For example, if \(a + b + c\) were used instead of 3.0 and ef1, saving through the pointer might have updated a, b, or c, and therefore you cannot commonly at all, and many more reloads.
- ANSIALIAS would not help if all the floats were also integers
- There is a group of problems that occurs when the ANSIALIAS option is used to compile code that does not conform to ANSI-aliasing rules (for example, when it casts a variable to a non-ANSI-aliasing type and then assigns the address of the value to a pointer for later use). If the ANSIALIAS option is in effect (it is the default) when a value is used through a pointer, the compiler might not reload the pointer value when the original value is updated, and the value might be stale when it is read.

### Using ANSI aliasing rules

Your programs are likely to perform better if you follow these guidelines:

- Use ANSI aliasing whenever possible.
- Declare constant variables with `const`. This is particularly helpful when using the C++ compiler because if something is qualified as `const`, the compiler will not be forced to perform unnecessary reloads to see if the value has changed.
This can generate significantly faster code.

```c
ggPoint3 operator*(const ggHAffineMatrix3 &m
, const ggPoint3 &p)
{
    return ggPoint3{
        m.e[0][0] * p.x() + m.e[0][1] * p.y() + m.e[0][2] * p.z() + m.e[0][3],
        m.e[1][0] * p.x() + m.e[1][1] * p.y() + m.e[1][2] * p.z() + m.e[1][3],
        m.e[2][0] * p.x() + m.e[2][1] * p.y() + m.e[2][2] * p.z() + m.e[2][3]
    );
}
```

- Whenever their values cannot change, qualify pointers and their targets as constants, ensuring that you mark the appropriate part as `const`.
  - If only the pointer is constant, you can use a statement that is similar to the following:
    ```c
    int * const i = p /* a constant pointer to an integer that may vary */
    ```
  - If only the target is constant, use a statement similar to either of the following:
    ```c
    int const * i = p /* a variable pointer to a constant integer */
    const int * i = p /* a variable pointer to a constant integer */
    ```
  - If both the target integer and the pointer are constants, use a statement similar to either of the following:
    ```c
    const int * const i = &p; /* a constant pointer to a constant integer */
    int const * const i = &p; /* a constant pointer to a constant integer */
    ```

- Use the ROCONST compiler option. The ROCONST option works with both C and C++. This option causes the compiler to treat variables that are defined as `const` as if they are read-only. In some cases, these variables will be stored in read-only memory. For more information, see "ROCONST" on page 727.
- For global variables initialized to large read-only arrays or strings: Use a `#pragma` variable to ensure that they are implemented as read-only csects. This prevents them from being initialized at load time.
  **Example:** For large initialized arrays
  ```c
  # pragma variable (arrayname, noent)
  ```
- In a read-only situation: If you are using the value through a pointer, use a temporary automatic variable. The difference in the source code is significant, as shown in the following table:
Table 319. Example of using temporaries to remove aliasing effects

<table>
<thead>
<tr>
<th>ANSIALIAS RENT and OPT(2)</th>
<th>NOANSIALIAS RENT and OPT(2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>...</td>
<td></td>
</tr>
<tr>
<td>while (hot_loop &lt; hot_loop_end) {</td>
<td></td>
</tr>
<tr>
<td>hot_loop = hot_loop + foo-&gt;increment;</td>
<td></td>
</tr>
<tr>
<td>fun[x] = hot_loop*foo-&gt;expansion;</td>
<td></td>
</tr>
<tr>
<td>}</td>
<td></td>
</tr>
<tr>
<td>{</td>
<td></td>
</tr>
<tr>
<td>...</td>
<td></td>
</tr>
<tr>
<td>increment = foo-&gt;increment;</td>
<td></td>
</tr>
<tr>
<td>expansion = foo-&gt;expansion;</td>
<td></td>
</tr>
<tr>
<td>while (hot_loop &lt; hot_loop_end) {</td>
<td></td>
</tr>
<tr>
<td>hot_loop = hot_loop + increment;</td>
<td></td>
</tr>
<tr>
<td>fun[x] = hot_loop*expansion;</td>
<td></td>
</tr>
<tr>
<td>}</td>
<td></td>
</tr>
</tbody>
</table>

Using variables

When choosing variables and data structures for your application, keep the following guidelines in mind:

- Use local variables, preferably automatic variables, as often as possible.

  The compiler can accurately analyze the use of local variables, while it has to make several worst-case assumptions about global variables, which hinders optimizations. For example, if you code a function that uses external variables, and calls several external functions, the compiler assumes that every call to an external function could change the value of every external variable.

- If none of the function calls affect the global variables being used and you have to read them frequently with function calls interspersed, copy the global variables to local variables and use these local variables to help the compiler perform optimizations that otherwise would not be done.

  Using IPA can improve the performance of code written using global variables, because it coalesces global variables. IPA puts global variables into one or more structures and accesses them using offsets from the beginning of the structures. For more information, see “Using the IPA option” on page 732.

- If you need to share variables only between functions within the same compilation unit, use static variables instead of external variables. Because static variables are visible only in the current source file, they might not have to be reloaded if a call is made to a function in another source file.

  Organize your source code so references to a given set of externally defined variables occur only in one source file, and then use static variables instead of external variables.

  In a file with several related functions and static variables, the compiler can group the variables and functions together to improve locality of reference.

  Use a local static variable instead of an external variable or a variable defined outside the scope of a function.

  The #pragma isolated_call preprocessor directive can improve the runtime performance of optimized code by allowing the compiler to make fewer assumptions about the references to external and static variables. For more information, see isolated_call in z/OS XL C/C++ Language Reference.

  Coalescing global variables causes variables that are frequently used together to be mapped close together in memory. This strategy improves performance in the same way that changing external variables to static variables does.

- Group external data into structures (all elements of an external structure use the same base address) or arrays wherever it makes sense to do so.
Before it can access an external variable, the compiler has to make an extra memory access to obtain the variable’s address. The compiler removes extraneous address loads, but this means that the compiler has to use a register to keep the address.

Using many external variables simultaneously requires many registers, thereby causing spilling of registers to storage. If you group variables into structures then it can use a single variable to keep the base address of the structure and use offsets to access individual items. This reduces register pressure and improves overall performance, especially in programs compiled with the RENT option.

The compiler treats register variables the same way it treats automatic variables that do not have their addresses taken.

- Minimize the use of pointers.
  Use of pointers inhibits most memory optimizations such as dead store elimination in C and C++.
  You can improve the runtime performance of optimized code by using the z/OS C #pragma disjoint directive to list identifiers that do not share the same physical storage. A similar mechanism that can be used to improve runtime performance of optimized code includes using the C99 restrict qualifier for pointers feature. The restrict type qualifier indicates for the lifetime of the pointer, and only it or a value directly derived from it will be used to access the object to which it points. For more information, see #pragma disjoint and restrict type qualifier in z/OS XL C/C++ Language Reference.

**Passing function arguments**

When writing code for optimization, it is usually better to pass a value as an argument to a function than to let the function take the value from a global variable. Global variables might have to be stored before a value is read from a pointer or before a function call is made. Global variables might have to be reloaded after function calls, or stored through a pointer. For more information, see “Using ANSI aliasing rules” on page 699 and “Using variables” on page 701.

The #pragma isolated_call preprocessor directive lists functions that do not modify global storage. You can use it to improve the runtime performance of optimized code. For more information, see isolated_call in z/OS XL C/C++ Language Reference.

Linkage convention or how arguments are passed is not specified in the C language, but is defined by the platform. Compilers in general follow the calling convention as described by the Application Binary Interface (ABI). An ABI can define more than one linkage due to performance considerations; for example, the XPLINK and non-XPLINK linkages on the z/OS platform. To correctly invoke a function, the arguments passed must match the parameters as defined in the function definition. For example, if you pass a pointer argument to a function expecting an integer, the code generated by the compiler for the call and for the function definition may not match (see the note at the end of this topic).

As the following example shows, you can declare a function without providing information about the number and types of its parameters.
Because the function declaration has no parameter information, the compiler is not required to diagnose parameter mismatch. You can call this function, passing it any number of arguments of any type, but the compilation will not be guaranteed to work if the function is not defined to receive the arguments as passed, due to differences in linkage conventions. In the worse case, when the z/OS XL C/C++ compiler attempts inlining of such ill-formed function calls, it may get into an unrecoverable condition and the compilation is halted.

To correct the situation, use the CHECKOUT(GEN) option to identify missing function declarations and non-prototype function declarators. Add or change the declarations to prototyped declarations, and proceed with compilation again. Should you receive diagnostic messages regarding incorrect function argument assignment, change the function call to pass the expected parameter type.

Note: Such a mismatch may sometimes turn out not to be an issue, depending on the ABI; for example, if the ABI happens to allow both pointers and integers passed using general purpose registers. Even in this case, there is no guarantee that the optimized code would work as expected due to ambiguous information received by the compiler.

Coding expressions

When coding expressions, consider the following recommendations:

- When components of an expression are duplicate expressions, code them either at the left end of the expression or within parentheses, as shown in the following example.

```c
int func();
...
int a;
func(a);
...
int func(p)
  void *p;
{
...
}
```

The compiler can recognize `x*y*z` and `x + y` as duplicate expressions when they are coded in parentheses or coded at the left end of the expression.

It is the best practice to avoid using pointers as much as possible within high-usage or other performance-critical code.

Note: The compiler might not be able to optimize duplicate expressions if either of the following are true:

- The address of any of the variables is already taken
- Pointers are involved in the computation
- When components of an expression in a loop are constant, code the constant expressions either at the left end of the expression or within parentheses.

The following example shows the difference in evaluation when c, d, and e are constant and v, w, and x are variable.

```c
v*w*x*(c*d*e);  /* Constant expressions recognized */
c + d + e + v + w + x;
v*w*x*c*d*e;  /* Constant expressions not recognized */
v + w + x + c + d + e;
```

**Coding conversions**

Avoid forcing the compiler to convert numbers between integer and floating-point internal representations. Conversions require several instructions, including some double-precision floating-point arithmetic. When you must use mixed-mode arithmetic, code the integral, floating-point, and decimal arithmetic in separate computations wherever possible. [Figure 168](#) shows an example.

```c
/* this example shows how numeric conversions are done */
int main(void)
{
  int i;
  float array[10]={1.0,2.0,3.0,4.0,5.0,6.0,7.0,8.0,9.0,10.0}
  float x = 1.0;
  for (i = 0; i < 10; i++)
  {
    array[i] = array[i]*x; /* No conversions needed */
    x = x + 1.0;
  }
  for (i = 1; i <= 9; i++)
    array[i] = array[i]+1; /* Conversions may be needed */
  return(0);
}
```

*Figure 168. Numeric conversions example*

**Arithmetical considerations**

Wherever possible, use multiplication rather than division. For example,

```c
x*(1.0/3.0);  /* 1.0/3.0 is evaluated at compile time */
```

produces faster code than:

```c
x/3.0;
```

If you divide many values by the same number in your code: Assign the divisor’s reciprocal to a temporary variable and then multiply by that variable.

**Using loops and control constructs**

For the for-loop index variable:
Use a `long` type variable whenever possible. Under ILP32, `long` and `int` are equivalent, but `long` is better for portability to an LP64 environment.

Use the `auto` or `register` storage class over the `extern` or `static` storage class.

If you use an `enum` variable, expand the variable to be a fullword by using the `ENUMSIZE` compiler option or by placing a large defined value at the end of your `enum` variable, as follows:

```c
enum animals {
    ant,
    cat,
    dog,
    robin,
    last_animal = INT_MAX;
};
```

Do not use the address operator (`&`) on the index.

The index should not be a member of a `union`.

For `if` statements:

- Order the `if` conditions efficiently; put the most decisive tests first and the most expensive tests last.

  By performing the most common tests first, you increase the efficiency of your code; fewer tests are required to meet the test conditions.

```c
if (command.is_classg &&
    command.len == 6 &&
    !strcmp(command.str, "LOGON")) /* call to strcmp() most expensive */
    logon();
```

### Choosing a data type

Use the `int` data type instead of `char` when performing arithmetic operations.

```c
char_var += '0';
int_var += '0';    /* better */
```

A `char` type variable is efficient when you are:

- Assigning a literal to a `char` variable
- Comparing the variable with a `char` literal

For example:

```c
char_var = 27;
if (char_var == 'D')
```

Table 320 on page 706 lists analogous data types and shows which data types are more expensive to reference.
<table>
<thead>
<tr>
<th>More Expensive</th>
<th>Less Expensive</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsigned short</td>
<td>signed short (Although unsigned short is less expensive on many systems, the z/OS implementation of signed short is less expensive.)</td>
</tr>
<tr>
<td>signed char</td>
<td>unsigned char</td>
</tr>
<tr>
<td>long double</td>
<td>double</td>
</tr>
<tr>
<td>Longer decimal</td>
<td>Shorter decimal</td>
</tr>
</tbody>
</table>

For storage efficiency, the compiler packs enumeration variables in 1, 2 or 4 bytes, depending on the largest value of a constant. When performance is critical, expand the size to a fullword either by adding an enumeration constant with a large value or by specifying the ENUMSIZE compiler option. For example:

```c
enum byte { land, sea, air, space };  
enum word { low, medium, high, expand_to_fullword = INT_MAX };  
```

Example that is equivalent to using the ENUMSIZE(INT) compiler option:

```c
enum word { low, medium, high };  
```

Fullword enumeration variables are preferred as function parameters.

For efficient use of extern variables:
- Place scalars ahead of arrays in extern struct.
- Copy heavily referenced scalars to auto or register variables (especially in a loop).

When using float:
- When passing variables of type float to a function, an implicit widening to double occurs (which takes time).
- On some machines divisions of type float are faster than those of type double.

When using bit fields, be aware that:
- Even though the compiler supports a bit field spanning more than 4 bytes, the cost of referencing it is higher.
- An unsigned bit field is preferred over a signed bit field.
- A bit field used to store integer values should have a length of 8, 16, or 24 bits and be on a byte boundary.
Using built-in library functions and macros

- You can use built-in functions (that is, compiler-generated expansions for the functions) by including the appropriate library header files. For a list of the built-in functions, see Chapter 33, “Using hardware built-in functions,” on page 505.

You can prevent parameter type mismatch and ensure optimal performance by including the appropriate library header files.

You can call a library function explicitly and avoid using the built-in functions by enclosing the function name in parentheses when you make the call, as follows: (memcpy)(buf1, buf2, len).

**Note:** At NOOPT the compiler might not expand all built-in functions.

- You can use the following macros (rather than their equivalent functions), if you include the ctype.h header file.

```
isalpha()  isalnum()  islower()  isprint()  isupper()  isxdigit()
isctl()   ispunct()   topper()  isdigit()  ispace()   tolower()  isgraph()
```

- If you are using the _cs1 or _cnds1 function with arguments other than the ones declared in the prototypes in stdlib.h, the compiler might not be able to generate correct code at OPT. In this case, use the NOANSIALIAS option.

**Note:** As of z/OS V1R2, the new forms for cs() and cnds() are _cs1 and _cnds1, respectively. For more information, see Chapter 33, “Using hardware built-in functions,” on page 505.

- Typically, arrays are compared element-by-element, using a loop. When you compare two arrays for equality, replace the loop with the memcmp() library function. This could result in the execution of many machine instructions being replaced by the execution of a only a few machine instructions.
More efficient comparison with `memcmp()` library function

<table>
<thead>
<tr>
<th>More efficient comparison with <code>memcmp()</code> library function</th>
<th>Less efficient comparison in a loop</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>if (!memcmp(a, b, sizeof(a)))</code></td>
<td><code>int a[1000], b[1000];</code></td>
</tr>
<tr>
<td>/* arrays are equal */</td>
<td><code>for (i = 0; i &lt; 1000; ++i)</code></td>
</tr>
<tr>
<td></td>
<td><code>if (a[i] != b[i])</code></td>
</tr>
<tr>
<td></td>
<td><code>break;</code></td>
</tr>
<tr>
<td></td>
<td><code>if (i == 1000)</code></td>
</tr>
<tr>
<td></td>
<td>/* arrays are equal */</td>
</tr>
</tbody>
</table>

- Neither the C nor the C++ language allows structure comparison, because structures might contain padding bytes with undefined values. In cases where you know that no padding bytes exist, use `memcmp()` to compare structures. The z/OS AGGREGATE compiler option for C is used to obtain a structure and union map.
- The `memset()` library function should be used to initialize a character buffer and to initialize an array to a repetitive byte pattern (such as zeros).
- Use `memset()` to clear structs, unions, arrays or character buffers as follows:

```c
char c[10];
for (i = 0; i < 10; i++) /* do not use */
c[i] = ' ';           /* do not use */
memset(c, ' ', sizeof(c)); /* better */
```

- Use the `alloca()` function to automatically allocate memory from the stack. This function frees memory at the end of a function call when z/OS XL C/C++ collapses the stack. For more information, see `alloca` in z/OS XL C/C++ Runtime Library Reference.
- When using `strlen()`, do not hide size information. Less code is needed for `strlen()` when the upper bound is known at compile time.

```c
char small_str_array[100];
char *small_str_ptr;    /* unknown upper bound */
x = strlen(small_str_ptr); /* unknown upper bound */
x = strlen(small_str_array); /* better */
```

- When concatenating strings, use `strcat()`.
- When performing character-to-integer conversions, use `atoi()` rather than `sscanf()`.
- Whenever possible, replace `strxxx()` functions with their corresponding `memxxx()` functions, because `memxxx()` functions are more efficient. You can minimize the execution cost of a `strxxx()` function by using fixed-length character buffers to save the length of incoming strings (including null terminators) for subsequent calls to `memcpy()` and `memcmp()`.
If you try to replace all `strcmp()` calls with a `memcmp()` call taking a `strlen()` value of one of the strings, the result might be an attempt to access protected storage which follows the shorter string. Such an attempt could cause an exception because `memcmp()` does not stop comparing strings when it encounters a null in one of the strings.

Whenever possible, replace `wcsxxx()` functions with their corresponding `wmemxxx()` functions, because `wmemxxx()` functions are more efficient. You can minimize the execution cost of a `wcsxxx()` function by using fixed-length wide character buffers to save the length of incoming wide character strings (including null terminators) for subsequent calls to `wmemcpy()` and `wmemcmp()`.

### Using library extensions

Effective use of DLLs could improve the performance of your application if either of the following is true:

- The application relies on a `fetch()` or `system()` function to call programs in other modules.
- The application is overly large and there are some low-use or special-purpose routines that you can move to a DLL.

If you are using C, consider calling other C modules with `fetch()` or DLLs instead of `system()`. A `system()` call does full environment initialization and termination, but a fetched module and a DLL share the environment of the calling routine. If you are using C++, consider using DLLs.

Use of DLLs requires more overhead than use of statically-bound function calls. You can test your code to determine whether you can afford this extra overhead. First, write the code so that it can be built to implement either a single module or a DLL. Next build your application both ways, and time both applications to see if you can handle the difference in execution time. For best DLL performance, structure the code so that once a function in the DLL is called, it does all it needs to do in the DLL before it returns control to the caller.

You can also choose how to implement DLLs. If you are using C, you can choose between:

- The XPLINK compiler option
- The DLL compiler option (which is used with the NOXPLINK option)

**Note:** In C++, DLL is not an option, but a default. When you use the XPLINK option, the compiler loads and accesses DLLs faster than it would if you used the DLL option.

The following suggestions could improve the performance of the application:

- If you are using a particular DLL frequently across multiple address spaces, you can install the DLL in either the LPA/ELPA or the DLPA to avoid load overhead. When the DLL resides in a PDSE, the DLPA services should be used.
• When you are binding your code, specify both the RENT and the REUSE options. Otherwise, each load of a DLL results in a separately loaded DLL with its own writable static area.
• Group external variables into one external structure.
• When you are using z/OS UNIX, avoid unnecessary load attempts.
  z/OS Language Environment supports loading a DLL that resides in the UNIX file system or in a data set. However, the location from which it first tries to load the DLL varies, depending whether your application runs with the runtime option POSIX(ON) or POSIX(OFF).
  – If your application runs with POSIX(ON), z/OS Language Environment tries to load the DLL from the UNIX file system first. If you are doing an explicit DLL load using the dllload() function, you can avoid searching the UNIX file system directories. You can direct a DLL search to a data set by prefixing the DLL name with two slashes (/ /), as follows:
    //MYDLL
  – If your application runs with POSIX(OFF), z/OS Language Environment tries to load your DLL from a data set. Similarly, if you are loading your DLL with the dllload() function and your DLL is loading in UNIX file system, you can avoid the search of the data set by directing a DLL search to the UNIX file system. You can do so by prefixing the DLL name with a period and slash (./), as follows:
    ./mydll

Note: DLL names are case sensitive in the UNIX file system.
• When you are using IPA, export only those subprograms (functions and C++ methods) or variables that you need for the interface to the final DLL.
  If you export subprograms or variables unnecessarily (for example, by using the EXPORTALL option), you severely limit IPA optimization. In this case, global variable coalescing and pruning of unreachable or 100% inlined code does not occur. Before it can be processed by IPA, DLLs must contain at least one subprogram. Any attempt to process a data-only DLL will result in a compilation error.
• The suboption NOCALLBACKANY of the compiler option DLL is more efficient than the CALLBACKANY suboption.
  The CALLBACKANY option calls a Language Environment routine at run time. This runtime service enables a C or C++ NOXPLINK DLL routine to call a C NOXPLINK NODLL routine, which use function pointers that point to actual function entry points rather than function descriptors.

Note: Compiling source with the DLL option will often cause a degradation in performance when compared against a statically bound application compiled without that option.

### Using #pragmas

Table 321 describes #pragmas that can affect performance. For information about using each pragma, see z/OS XL C/C++ Language Reference.

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>#pragma disjoint</td>
<td>Lists identifiers that do not share the same physical storage, which provides more opportunities for optimizations.</td>
</tr>
<tr>
<td>Name</td>
<td>Description</td>
</tr>
<tr>
<td>------</td>
<td>-------------</td>
</tr>
<tr>
<td>#pragma execution_frequency (C++ only)</td>
<td>Marks program source code that you expect will be either very frequently or very infrequently executed.</td>
</tr>
<tr>
<td>#pragma export</td>
<td>Selectively exports functions or variables from a DLL module. The EXPORTALL compiler option exports all functions or variables, which often results in larger modules and significantly increased WSA requirements.</td>
</tr>
<tr>
<td>#pragma inline (C only)</td>
<td>Together with the INLINE compiler option, ensures that frequently used functions are inlined. This directive is only supported in C; however, you can use the inline keyword in C++.</td>
</tr>
<tr>
<td>#pragma isolated_call</td>
<td>Lists functions that have no side effects (that do not modify global storage). This directive can improve the runtime performance of variables and storage by allowing the compiler to make fewer assumptions about whether external and static variables could be updated.</td>
</tr>
<tr>
<td>#pragma leaves</td>
<td>Specifies that a function never returns to the instruction following a call to that function. This directive provides information to the compiler that enables it to explore additional opportunities for optimization.</td>
</tr>
<tr>
<td>#pragma noinline</td>
<td>This directive can improve pipeline usage and allow more of the used routines to be inlined.</td>
</tr>
<tr>
<td>#pragma option_override</td>
<td>Allows you to specify optimization options on a per-routine basis rather than on only a per-compilation basis. It enables you to specify which functions you do not want to optimize while compiling the rest of the program optimized. This directive helps you to isolate which function is causing problems under optimization. The option_override pragma can be also used to change the spill size for a function. If the compiler requests that you to increase the spill size for a specific function, you should use the option_override pragma instead of the SPILL compiler option, which increases the spill size for all functions in the compile unit and can have a negative performance impact on the generated code. <strong>Note:</strong> The spill size should not be increased unless requested by a compiler message.</td>
</tr>
<tr>
<td>#pragma reachable</td>
<td>Declares that the point in the program after the specified function can be the target of a branch from some unknown location. That is, you can reach the instruction after the specified function from a point in your program other than the return statement in the named function. This directive provides information to the compiler that enables it to explore additional opportunities for optimization.</td>
</tr>
<tr>
<td>#pragma strings</td>
<td>Indicates if strings should be placed in read-only memory or read/write memory. You can reduce the memory requirements for DLLs by specifying #pragma strings(readonly), so that string literals are not placed in the writable static area. Alternatively, you can also use the ROSTRING compiler option (the default), which informs the compiler that string literals are read-only.</td>
</tr>
<tr>
<td>#pragma unroll</td>
<td>Informs the compiler how to perform loop unrolling on the loop body that immediately follows it. The directive works in conjunction with the UNROLL compiler option to provide you with some control over the application of this optimization technique. The pragma directive overrides the &quot;UNROLL&quot; on page 728 or NOUNROLL compiler option in effect for the designated loop.</td>
</tr>
</tbody>
</table>
### Using rvalue references (C++11)

**Note:** C++11 is a new version of the C++ programming language standard. IBM continues to develop and implement the features of the new standard. The implementation of the language level is based on IBM’s interpretation of the standard. Until IBM’s implementation of all the features of the C++11 standard is complete, including the support of a new C++ standard library, the implementation may change from release to release. IBM makes no attempt to maintain compatibility, in source, binary, or listings and other compiler interfaces, with earlier releases of IBM’s implementation of the new features of the C++11 standard and therefore they should not be relied on as a stable programming interface.

In C++11, you can overload functions based on the value categories of arguments and similarly have lvalueeness detected by template argument deduction. You can also have an rvalue bound to an rvalue reference and modify the rvalue through the reference. This enables a programming technique with which you can reuse the resources of expiring objects and therefore improve the performance of your libraries, especially if you use generic code with class types, for example, template data structures. Additionally, the value category can be considered when writing a forwarding function.

When you want to optimize the use of temporary values, you can use a move operation in what is known as destructive copying. Consider the following string concatenation and assignment:

```c++
std::string a, b, c;
c = a + b;
```

In this program, the compiler first stores the result of `a + b` in an internal temporary variable, that is, an rvalue.

The signature of a normal copy assignment operator is as follows:

```c++
string& operator = (const string&)
```

With this copy assignment operator, the assignment consists of the following steps:

1. Copy the temporary variable into `c` using a deep-copy operation.
2. Discard the temporary variable.

Deep copying the temporary variable into `c` is not efficient because the temporary variable is discarded at the next step.
To avoid the needless duplication of the temporary variable, you can implement an assignment operator that moves the variable instead of copying the variable. That is, the argument of the operator is modified by the operation. A move operation is faster because it is done through pointer manipulation, but it requires a reference through which the source variable can be manipulated. However, \(a + b\) is a temporary value, which is not easily differentiated from a const-qualified value in C++ before C++11 for the purposes of overload resolution.

With rvalue references, you can create a move assignment operator as follows:

```cpp
string& operator=(string&&)
```

With this move assignment operator, the memory allocated for the underlying C-style string in the result of \(a + b\) is assigned to \(C\). Therefore, it is not necessary to allocate new memory to hold the underlying string in \(C\) and to copy the contents to the new memory.

The following code can be an implementation of the string move assignment operator:

```cpp
string& string::operator=(string&& str)
{
    // The named rvalue reference str acts like an lvalue
    std::swap(_capacity, str._capacity);
    std::swap(_length, str._length);

    // char* _str points to a character array and is a
    // member variable of the string class
    std::swap(_str, str._str);
    return *this;
}
```

However, in this implementation, the memory originally held by the string being assigned to is not freed until \(str\) is destroyed. The following implementation that uses a local variable is more memory efficient:

```cpp
string& string::operator=(string&& parm_str)
{
    // The named rvalue reference parm_str acts like an lvalue
    string sink_str;
    std::swap(sink_str, parm_str);
    std::swap(*this, sink_str);
    return *this;
}
```

In a similar manner, the following program is a possible implementation of a string concatenation operator:

```cpp
string operator+(string&& a, const string& b)
{
    return std::move(a+=b);
}
```

**Note:** The `std::move` function only casts the result of \(a+b\) to an rvalue reference, without moving anything. The return value is constructed using a move constructor because the expression `std::move(a+b)` is an rvalue. The relationship between a move constructor and a copy constructor is analogous to the relationship between a move assignment operator and a copy assignment operator.

The `std::forward` function is a helper template, much like `std::move`. It returns a reference to its function argument, with the resulting value category determined by the template type argument. In an instantiation of a forwarding function template,
the value category of an argument is encoded as part of the deduced type for the related template type parameter. The deduced type is passed to the std::forward function.

The wrapper function in the following example is a forwarding function template that forwards to the do_work function. Use std::forward in forwarding functions on the calls to the target functions. The following example also uses the decltype and trailing return type features to produce a forwarding function that forwards to one of the do_work functions. Calling the wrapper function with any argument results in a call to a do_work function if a suitable overload function exists. Extra temporaries are not created and overload resolution on the forwarding call resolves to the same overload as it would if the do_work function were called directly.

```cpp
struct s1 *do_work(const int&); // #1
struct s2 *do_work(const double&); // #2
struct s3 *do_work(int&&); // #3
struct s4 *do_work(double&&); // #4

template <typename T> auto wrapper(T && a)->
    decltype(do_work(std::forward<T>(*static_cast<typename std::remove_reference<T>::type*>(0))))
{
    return do_work(std::forward<T>(a));
}

template <typename T> void tPtr(T *t);

int main()
{
    int x;
    double y;
    tPtr<s1>(wrapper(x)); // calls #1
    tPtr<s2>(wrapper(y)); // calls #2
    tPtr<s3>(wrapper(0)); // calls #3
    tPtr<s4>(wrapper(1.0)); // calls #4
}
```

**Note:**

1. The following sample implements functionality similar to std::move and std::forward:

```cpp
namespace MyStd {
    template <typename T> struct remove_reference {
        typedef T type;
    };
    template <typename T> struct remove_reference<T&> {
        typedef T type;
    };
    template <typename T> struct remove_reference<T&&> {
        typedef T type;
    };

    namespace Impl {
        template <typename T> struct NotAnLvalueReference {
            enum { value=1 };
        };
        template <typename T> struct NotAnLvalueReference<T&> {
            enum { value=0 };
        };
    }

    template <typename T> inline
    T &&forward(typename remove_reference<T>::type &t) {
        return static_cast<T &&>(t);
    }
    template <typename T> inline
    T &&forward(typename remove_reference<T>::type &&t) {
```
Using shared-memory parallelism (SMP)

You can compile your program with the SMP option to generate threaded code that exploits shared-memory parallelism. The SMP option implies the HOT option and an optimization level of OPTIMIZE(2).

The following table lists the suboptions of the SMP option. For descriptions and syntax of the suboptions, see the SMP option in z/OS XL C/C++ User’s Guide.

<table>
<thead>
<tr>
<th>suboption</th>
<th>Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>EXPLICIT</td>
<td>Enables directives that control explicit parallelization of loops.</td>
</tr>
<tr>
<td>NOEXPLICIT</td>
<td>Disables the directives that control explicit parallelization of loops.</td>
</tr>
<tr>
<td>OPT</td>
<td>Instructs the compiler to optimize as well as parallelize. The optimization is equivalent to OPTIMIZE(2) and HOT in the absence of other optimization options.</td>
</tr>
<tr>
<td>NOOPT</td>
<td>Instructs the compiler to do the smallest amount of optimization that is required to parallelize the code. During development, it can be useful to turn off optimization to facilitate debugging.</td>
</tr>
</tbody>
</table>

Tips for using the SMP option

Here are some suggestions for using the SMP option:
- Before using the SMP option, test your programs using OPTIMIZATION and HOT in a single-threaded manner.
- Use the thread-safe version of system library routines inside the parallel regions.
- By default, the runtime environment uses all available processors. Do not set the OMP_NUM_THREADS environment variable unless you want to use fewer than the number of available processors. You might want to set the number of executing threads to a small number or to 1 to ease debugging.
- When debugging an OpenMP program, try using SMP(NOOPT) (without OPTIMIZE) to make the debugging information produced by the compiler more precise.
Chapter 40. Using built-in functions to improve performance

A built-in function is inline code that is generated in place of an actual function call.

The built-in functions described in this chapter behave exactly the same as those in the C library. The compiler will generate inline code for these functions if the appropriate header file is included in the source. For more information, see built-in functions in z/OS XL C/C++ Runtime Library Reference.

If you have included the header files but you want to call either the library version of the function or your own version, enclose the function name in parentheses when you make the call. For example, if you wanted to call only memcpy from the header file and use the built-in functions for other memory-related functions, code the function call as follows:

\[(\text{memcpy})(\text{buf1, buf2, len})\]

<table>
<thead>
<tr>
<th>Table 323. C-library built-in functions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Built-In Function</strong></td>
</tr>
<tr>
<td>abs()</td>
</tr>
<tr>
<td>alloca()</td>
</tr>
<tr>
<td>ceil()</td>
</tr>
<tr>
<td>ceilf()</td>
</tr>
<tr>
<td>ceill()</td>
</tr>
<tr>
<td>Note: The compiler only attempts to generate inline code for ceil(), ceilf(), and ceill() when the OPTIMIZE(2) compiler option is used.</td>
</tr>
<tr>
<td>decabs()</td>
</tr>
<tr>
<td>decchk()</td>
</tr>
<tr>
<td>decfix()</td>
</tr>
<tr>
<td>Note: The compiler only attempts to generate inline code for decabs() when the OPTIMIZE(2) compiler option is used.</td>
</tr>
<tr>
<td>fabs()</td>
</tr>
<tr>
<td>Note: The compiler only attempts to generate inline code for fabs() when the OPTIMIZE(2) compiler option is used.</td>
</tr>
<tr>
<td>floor()</td>
</tr>
<tr>
<td>floorf()</td>
</tr>
<tr>
<td>floorl()</td>
</tr>
<tr>
<td>Note: The compiler only attempts to generate inline code for floor(), floorf(), and floorl() when the OPTIMIZE(2) compiler option is used.</td>
</tr>
<tr>
<td>fortrc()</td>
</tr>
<tr>
<td>memchr()</td>
</tr>
<tr>
<td>memcpy()</td>
</tr>
<tr>
<td>memcmp()</td>
</tr>
<tr>
<td>memset()</td>
</tr>
<tr>
<td>strcat()</td>
</tr>
<tr>
<td>strchr()</td>
</tr>
<tr>
<td>strcmp()</td>
</tr>
</tbody>
</table>

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Table 323. C-library built-in functions (continued)

<table>
<thead>
<tr>
<th>Built-In Function</th>
<th>Header File</th>
</tr>
</thead>
<tbody>
<tr>
<td>strcpy()</td>
<td>string.h</td>
</tr>
<tr>
<td>strlen()</td>
<td>string.h</td>
</tr>
<tr>
<td>strncat()</td>
<td>string.h</td>
</tr>
<tr>
<td>strncmp()</td>
<td>string.h</td>
</tr>
<tr>
<td>strncpy()</td>
<td>string.h</td>
</tr>
<tr>
<td>strrchr()</td>
<td>string.h</td>
</tr>
<tr>
<td>wmemchr()</td>
<td>wchar.h</td>
</tr>
<tr>
<td>wmemcmp()</td>
<td>wchar.h</td>
</tr>
<tr>
<td>wmemcpy()</td>
<td>wchar.h</td>
</tr>
<tr>
<td>wmemset()</td>
<td>wchar.h</td>
</tr>
</tbody>
</table>

**Note:** The compiler only attempts to generate inline code for wmemchr(), wmemcmp(), wmemcpy(), and wmemset() when the ARCH(7) compiler option is used. LP64 compiles will not generate inline code.

**Platform-specific functions**

The built-in functions in this section are related to C-library functions that are z/OS specific. The full description of each function can be found in z/OS XL C/C++ Runtime Library Reference.

Table 324. Platform-specific built-in functions

<table>
<thead>
<tr>
<th>Built-In Function</th>
<th>Header File</th>
</tr>
</thead>
<tbody>
<tr>
<td>cds()</td>
<td>stdlib.h</td>
</tr>
<tr>
<td>cs()</td>
<td>stdlib.h</td>
</tr>
</tbody>
</table>

**Note:** cds() and cs() are masking macros. The system header expands them to the _cds and _cs. It is advisable to use the hardware functions instead of the library functions whenever possible. For more information, see Table 89 on page 505.
Chapter 41. I/O Performance considerations

This chapter discusses the most efficient use of the available XL C/C++ input and output methods. This includes:

- "Accessing MVS data sets"
- "Accessing UNIX file system files" on page 721
- "Using memory files" on page 721
- "Using the C++ I/O stream libraries" on page 721

Accessing MVS data sets

- Consider the use of the file when choosing DCB parameters:
  - Specify largest possible BLKSIZE (blocked files).
  - Use recfm = FB5 or F over FB unless dealing with a PDS. The use of standard (S) blocks optimizes the sequential processing of a file on a direct-access device.
  - fseek() on sequential files is most efficient when using recfm = F or recfm = FB5.
  - If you are accessing an existing sequential file created as FB, and you know that there are no short blocks in the file, specify FB5 on the call to fopen() or freopen() to enable the library to perform faster repositions.

The proper choice of file attributes is important for efficient I/O.

- When you do not need to reposition within a file, take advantage of NOSEEK for more efficient reading and writing to a data set. You can also specify NCP or BUFSIZE on the DD statement for MVS DASD data sets, thereby reducing the clock time of the application. See "Multiple buffering" on page 102 for more information.
- If possible, read or write a block at a time to minimize the I/O overhead and elapsed time.
- Using text I/O for writing can be slower than using binary or record I/O. When you use binary or record I/O, the application must ensure that the data is written to the file in the correct format.
- If you are using FB or FB5 files, use binary I/O instead of record I/O. This way, you can read or write more than one record at a time.
- Use fread() instead of fgets(), and fwrite() in place of fputs(), wherever possible.
- Use putc() instead of fputc(), and getc() instead of fgetc(), if you must read or write a character.

The fputc() function, as defined by ANSI, puts a single character to the text stream. Special action occurs when writing a control character. On the other hand, the putc() macro buffers characters in storage and invokes fputc() only when encountering a control character. This reduces call overhead when you are writing one character at a time.

- If you are using hiperspace memory files, you can use setvbuf() to set the buffer size.

The default buffer size for memory files in hiperspace is 16K. You can override this by calling setvbuf() after fopen(), but before performing any I/O.
operations on the file. The minimum buffer size is 4K. If you specify a smaller
size, it is ignored, and the default is used instead.
If your file will be large, you can improve execution time by increasing the
buffer size. This will result in less frequent flushing of the buffer to the
hiperspace, but will cost you memory in the user address space for the larger
buffers. For example,

```c
rc = setvbuf(fp, NULL, _IOFBF, 32768);
```
Alternatively, if your memory is constrained, you can reduce requirements for
memory in the user address space by reducing the buffer size. This will result in
more frequent flushing of the buffer to the hiperspace. For example,

```c
rc = setvbuf(fp, NULL, _IOFBF, 4096);
```
For more information on hiperspace memory files, refer to Chapter 14,
“Performing memory file and hiperspace I/O operations,” on page 201.

- When writing to text files that do not use DBCS characters, ensure that
  MB_CUR_MAX is set to 1 for the current locale. This will prevent internal I/O
  checks for DBCS strings.
- Avoid using fscanf() or fprintf() if you can use other I/O routines instead.
  For example, use fwrite() rather than fprintf() to write out a format string
  with no substitution variables.
- When using fflush() beware of NULL file pointers; fflush(NULL) flushes all open
  streams.
- Specify DCB parameters on fopen() only when you are creating the file. When
  you are appending, updating or reading a file, these attributes are retrieved from
  the existing file.
  Many file attributes (DCB parameters) are possible when you open a file with
  z/OS XL C/C++. DCB parameters specified on fopen() must be compatible with
  those of the file or the ddname. This checking may cause unwanted overhead.
- Use fseekpos() and fsetpos() instead of ftell() and fseek() when you are
  saving a position you will return to later. fseekpos() saves more information
  about the position than ftell().
- Where possible, use striped data sets. These data sets improve overall I/O
  throughput.
- For temporary files, use memory files rather than files created with tmpfile().
  You can use MVS memory files from z/OS UNIX C++ application programs. However,
  use of the fork() function from the program clears a memory file and
  removes access from a hiperspace memory file for the child process. Use of an
  exec function from the program clears a memory file when the process address
  space is cleared.
- For large memory files (1MB or larger) in which you perform random seeking,
  use hiperspace memory files, if they are available.
- When your library is below the 16MB line, use hiperspace memory files.
  The non-hiperspace files use up your storage from below the line. Hiperspace
  memory files do not reside in user virtual storage. Changing a memory file to a
  hiperspace memory file saves user virtual storage only if the file is larger than
  one hiperspace memory file buffer.
- For VSAM I/O use VSAM buffers appropriately and use flocate() instead of
  ftell() and fseek().
Accessing UNIX file system files

When accessing UNIX file system files, you should review the following considerations:

- Use `fread()` instead of `fgets()`, and `fwrite()` in place of `fputs()`, wherever possible.
- Use `putc()` instead of `fputc()`, and `getc()` instead of `fgetc()`, if you must write or read a character.
- When using `fflush()`, beware of `NULL` file pointers; `fflush(NULL)` flushes all open streams.
- Changing the buffer size for access to UNIX file system may provide advantages. Rather than using the default of 4K, you may want to use the `setvbuf()` function to set the buffer size to be the length of the read or write operation that you normally do. For example, in applications that access files in a z/OS File System (zFS) file system, the recommended `setvbuf()` buffer size is 64K.

When you include the header file `stdio.h`, macros are defined for `getc()`, `putc()`, `getchar()`, and `putchar()`. To use the function calls instead of the macro calls, use `#undef` after the `stdio.h` header file is included. If you are working with a threaded application, these macros are automatically undefined forcing the application to use function calls, which are thread safe. The feature test macro `_ALL_SOURCE` causes these four macros to be undefined. However, if you require `_ALL_SOURCE`, and want these macros to be used in a non multi-threaded application, you can use feature test macro `_ALL_SOURCE_NOTHREADS`.

Using memory files

Use memory files as efficient temporary files by specifying the `type=memory` attribute in `fopen()` before creating the temporary file. Some applications use temporary files to pass data between program modules.

When using one of the z/OS UNIX shells, an MVS memory file may or may not make an efficient temporary file. This depends on whether your z/OS UNIX XL C/C++ application program uses `fork()` and `exec()` functions to call another program to run in a child process. The child process does not inherit MVS memory files after an `exec()` function. For more information, see “Accessing MVS data sets” on page 719.

Using the C++ I/O stream libraries

The following information applies to the USL I/O Stream Class Library and to the Standard C++ I/O stream classes.

- Unit-buffering incurs a significant performance penalty. Unit-buffering can be enabled by setting the `ios::unitbuf` flag. It is enabled for the `cerr` object by default.
- The `sync_with_stdio()` function enables unit-buffering of standard streams, to ensure their synchronization with C standard streams. However, a runtime performance penalty is incurred to ensure this synchronization. For more information about `sync_with_stdio()`, see Chapter 4, “Using the Standard C++ Library I/O Stream Classes,” on page 23.
- In most cases, calls to functions in the USL or ANSI C++ I/O stream libraries are mapped to calls to the I/O functions of the C standard library. For this reason, direct calls to the C I/O functions are recommended for applications that must
have the best possible performance. This does not mean that these types of applications cannot or should not contain any iostream.h calls. However, you might want to ensure that iostream.h I/O calls do not appear on the critical path; it is safe to keep them for unused debugging code.

**Note:** If you access the same file with both C and C++ I/O stream classes, undefined results will occur.
Chapter 42. Improving performance with compiler options

This information discusses and lists the z/OS XL C/C++ compiler options that you can use to improve application performance. The information includes the following topics:

- "Using the OPTIMIZE option"
- "Optimizations performed by the compiler"
- "Additional options that affect performance" on page 725
- "Inlining" on page 728
- "Using the XPLINK option" on page 731
- "Using the IPA option" on page 732

Using the OPTIMIZE option

During optimization, the compiler changes the unoptimized code sequences, derived from the source code, into equivalent code sequences that execute faster and usually require less memory space. It is also possible for an expression that would normally cause an exception to be removed by optimization, thus preventing the exception.

**Note:** You can optimize code by specifying either OPTIMIZE(2) or OPTIMIZE(3). Optimized code takes significantly more time to compile than unoptimized code, but will likely result in faster-running code. There is no guarantee that the compile time at OPTIMIZE(3) will remain similar from release to release.

Because the optimization is achieved by transforming the code using knowledge obtained from a larger program context, the direct correspondence between source and object code is often lost. Optimized code is also more sensitive to subtle coding errors.

One example of a subtle coding error is to type cast a pointer variable incorrectly. The compiler assumes ISO conformance when doing optimization. If your program does not conform, you may receive undefined results. For more information, see "ANSI aliasing rules" on page 697 and "Using ANSI aliasing rules" on page 699.

Optimizations performed by the compiler

The compiler performs several optimizations, including:

**Inlining**

Inlining replaces certain function calls with the actual code of the function being performed. For more information on inlining, see "Inlining" on page 728.

For z/OS XL C/C++, automatic inlining is performed by default when you specify OPTIMIZE. You can override this inlining by using the NOINLINE option. For more information, see [INLINE] in z/OS XL C/C++ User’s Guide.

**Value numbering**

Value numbering involves local constant propagation, local expression elimination, and folding several instructions into a single instruction.
Straightening

Straightening is rearranging the program code to minimize branching logic and to combine physically separate blocks of code.

Common expression elimination

Common expressions recalculate the same value in a subsequent expression. The duplicate expression can be eliminated by using the previous value. This is done even for intermediate expressions within expressions.

If your program contains the following statements, the common expression \( c + d \) is saved from its first evaluation and is used in the subsequent statement to determine the value of \( f \).

\[
\begin{align*}
  a &= c + d; \\
  \cdot \\
  \cdot \\
  f &= c + d + e;
\end{align*}
\]

Code motion

If variables used in a computation within a loop are not altered within the loop, it may be possible to perform the calculation outside of the loop and use the results within the loop.

Strength reduction

Less efficient instructions are replaced with more efficient ones. For example, in array addressing, an add instruction replaces a multiply.

Constant propagation

Constants used in an expression are combined and new ones generated. Some mode conversions are done, and compile-time evaluation of some intrinsic functions takes place.

Instruction scheduling

Instructions are reordered to minimize execution time.

Dead store elimination

The compiler eliminates stores when the value stored is never referred to again. For example, if two stores to the same location have no intervening load, the first store is unnecessary, and is therefore removed.

Dead code elimination

The compiler may eliminate code for calculations that are not required. Other optimization techniques may cause code to become dead.

Graph coloring register allocation

The compiler uses a global register allocation for the whole function, thereby allowing variables to be kept in registers rather than in memory.

These optimization techniques may be performed both locally and globally. Increases in storage and compile time requirements over NOOPT will occur. Higher levels of optimization may perform the same options more rigourously as well as adding additional options.

Aggressive optimizations with OPTIMIZE(3)

The compiler optimizes more aggressively with OPTIMIZE(3) than with OPTIMIZE(2). Code may be moved, and computations may be scheduled, even if this could potentially raise an exception.
OPTIMIZE(3) may place instructions onto execution paths where they will be executed when they may not have been according to the actual semantics of the program. For example, a loop-invariant floating-point computation that is found on some, but not all, paths through a loop will not be moved using OPTIMIZE(2) because the computation may cause an exception. For OPTIMIZE(3), the compiler will move the computation because it is not certain to cause an exception.

The same is true for moving loads. Although a load through a pointer is never moved, loads off the static or stack base register are considered movable using OPTIMIZE(3). Loads in general are not considered to be absolutely safe using OPTIMIZE(2) because a program can contain a declaration of a static array a of 10 elements and load a[60000000003], which could cause a segmentation violation.

The same concepts apply to scheduling. In Figure 169 using OPTIMIZE(2), the computation of \( b + c \) is not moved out of the loop for two reasons:

- It is considered dangerous because it is a floating-point operation
- It does not occur on every path through the loop

```c
int i;
float a[100], b, c;
for (i=0; i < 100; i++)
{
  if (a[i] < a[i+11])
    a[i] = b + c;
}
```

Additional options that affect performance

The following topics describe compiler options that affect performance. For more information, see compiler options in z/OS XL C/C++ User's Guide.

**ANSIALIAS**

The ANSIALIAS option specifies whether type-based aliasing is to be used during optimization. Type-based aliasing will improve optimization. For more information about ANSI aliasing, see “ANSI aliasing rules” on page 697 and “Using ANSI aliasing rules” on page 699.

**ARCHITECTURE and TUNE**

The ARCHITECTURE option specifies the architectural level for which the executable program's instructions will be generated. The TUNE option specifies for which architectural level the executable program will be optimized.

ARCHITECTURE allows the compiler to take advantage of specific hardware instruction sets. TUNE allows the compiler to take advantage of differences (such as scheduling of instructions) in architectural levels.
**ASSERT(RESTRICT)**

The ASSERT(RESTRICT) option enables optimizations for restrict qualified pointers.

**COMPRESS**

Use the COMPRESS option to suppress the generation of function names in the function control block to reduce the size of your application's load module. The amount of reduction depends on the average function size in the application, as compared to the length of the function name.

**COMPACT**

When the COMPACT option is active, the compiler favors optimizations that tend to limit the growth of the code. Depending on your specific program, the object size may increase or decrease and the execution time may increase or decrease. Any time you change your program, or change the release of the compiler, you should re-evaluate your use of the COMPACT option.

**CVFT (C++ only)**

Use the NOCVFT option to reduce the size of the writable static area for constructors that call virtual functions within the class hierarchy where virtual inheritance is used.

**EXH (C++ only)**

You might improve the run time of your C++ code by using NOEXH. The resultant code will run faster, but it will not be ISO-compliant if the program uses exception handling.

**EXPORTALL**

Use the EXPORTALL option only if you want to export all external functions and variables in the source file so that a DLL application can use them. If you only need to export some externally defined functions and variables, use the \#pragma export directive or the \_Export C++ keyword instead of EXPORTALL.

If you use EXPORTALL, you can severely limit IPA optimization, and can cause your modules and WSA to be larger than necessary.

**HGPR**

The HGPR option enables the compiler to exploit 64-bit General Purpose Registers (GPRs) in 32-bit programs targeting z/Architecture hardware.

**HOT**

The HOT compiler option enables the compiler to request high-order transformations on loops during optimization, which gives you the ability to generate more highly optimized code.

**IGNERRNO**

The IGNERRNO option informs the compiler that the program is not using errno. This allows the compiler more freedom to explore optimization opportunities for certain library functions (for example, sqrt). You need to include the system header files to get the full benefit of the IGNERRNO option.
IPA
The IPA option specifies that the compiler should use interprocedural analysis when optimizing this module. This can lead to significant performance improvements. For more information, see “Using the IPA option” on page 732.

LIBANSI
The LIBANSI option specifies whether or not all functions with the name of an ANSI C library function are in fact the ANSI functions. This allows the compiler to generate code based on existing knowledge concerning the behavior of the function. For example, the compiler will determine whether any side effects are associated with a particular library function. LIBANSI can provide additional benefits when used in conjunction with IGNERRNO.

OBJECTMODEL (C++ only)
You can compile your programs using two different object models. They differ in the following areas:

- Layout for the virtual function table
- Name mangling scheme

The OBJECTMODEL compiler option has the following suboptions to set the type of object model:

CLASSIC
uses the original object model that was available on all previous releases of C++ compiler.

IBM
uses the new object model and should be selected if you want improved performance. This is especially true for class hierarchies with many virtual base classes. The size of the derived class is considerably smaller and access to the virtual function table is faster.

All classes in the same inheritance hierarchy must have the same object model.

Use the `#pragma object_model` directive to specify an object model in your source. For more information, see `object_model` in z/OS XL C/C++ Language Reference.

PREFETCH
The PREFETCH option inserts prefetch instructions automatically where there are opportunities to improve code performance.

RESTRICT
The RESTRICT option indicates to the compiler that all pointer parameters in some or all functions are disjoint.

ROCONST
The ROCONST option specifies that the `const` qualifier is respected by the program. Variables that are defined with the `const` keyword are not overridden by a casting operation. When you use this option in C with the DLL option, you must ensure that no `const` global variables (static or external) are initialized with the address of an entity from another compile unit.
**ROSTRING**

The ROSTRING option specifies that strings are placed in read-only memory. It has the same effect as the `#pragma strings(readonly)` directive.

**RTTI**

If you are not using RTTI/dynamic casts in your program, compile with the NORTTI option.

**SPILL**

When you specify a very large spill size, you can force the compiler to generate less than optimal code. For this reason, you might not want to specify the large spill size for an entire application. For example, either you can specify the large spill size for only the specific compilation unit that needs it or you can use the `#pragma option_override` directive.

**STRICT**

The STRICT option prevents optimizations done by default at optimization levels OPT(3), and optionally at OPT(2), from re-ordering instructions that could introduce rounding errors.

**STRICT_INDUCTION**

With strict induction, induction (loop counter) variables are not optimized. This guards against problems that can occur if an optimized induction variable overflows.

If it is certain that the induction variables will not overflow, use the NOSTRICT_INDUCTION option. This option can improve the performance of induction variables that are smaller than the register size on the processor.

**THREADED**

The THREADED option indicates to the compiler whether it must generate threaded code.

**UNROLL**

The UNROLL option gives the user the ability to control the amount of loop unrolling done by the compiler. Loop unrolling exposes instruction level parallelism for instruction scheduling and software pipelining and thus can improve a program's performance. It should be used in conjunction with `#pragma unroll`.

---

**Inlining**

Inlining replaces certain function calls with the actual code of the function and is performed before all other optimizations. Not only does inlining eliminate the linkage overhead, it also exposes the entire called function to the caller, which enables the compiler to better optimize your code.

**Note:** See "Inlining under IPA" on page 731 for information on differences in inlining under IPA.

The following types of calls are not inlined:
- A call where the number of parameters on the call does not match that on the function definition. An example of this is a variable argument function call.
- A call that is directly recursive; the routine calls itself.
- K&R style \texttt{var\_arg} functions.

Consider the C examples CCNGOP1 and CCNGOP2, shown in Table 325. CCNGOP1 specifies the \texttt{#pragma inline} directive for the function \texttt{which\_group()}. If you use the OPTIMIZE option when you compile CCNGOP1, the compiler determines that CCNGOP1 is equivalent to CCNGOP2.

**Table 325. Examples of optimization**

<table>
<thead>
<tr>
<th>Sample program CCNGOP1</th>
<th>Sample program CCNGOP2</th>
</tr>
</thead>
<tbody>
<tr>
<td>/* this example demonstrates optimization */</td>
<td>/* this example also demonstrates optimization */</td>
</tr>
<tr>
<td>#include &lt;stdio.h&gt;</td>
<td>#include &lt;stdio.h&gt;</td>
</tr>
<tr>
<td>#pragma inline (which_group)</td>
<td></td>
</tr>
<tr>
<td>int which_group (int a) {</td>
<td>int main(void) {</td>
</tr>
<tr>
<td>if (a &lt; 0) {</td>
<td>printf(&quot;third group\n&quot;); /* a lot less code generation */</td>
</tr>
<tr>
<td>printf(&quot;first group\n&quot;);</td>
<td>return(77);</td>
</tr>
<tr>
<td>return(99);</td>
<td>}</td>
</tr>
<tr>
<td>}</td>
<td>}</td>
</tr>
<tr>
<td>else if (a == 0) {</td>
<td></td>
</tr>
<tr>
<td>printf(&quot;second group\n&quot;);</td>
<td>return(88);</td>
</tr>
<tr>
<td>return(88);</td>
<td>}</td>
</tr>
<tr>
<td>}</td>
<td>}</td>
</tr>
<tr>
<td>else</td>
<td></td>
</tr>
<tr>
<td>printf(&quot;third group\n&quot;);</td>
<td></td>
</tr>
<tr>
<td>return(77);</td>
<td>return(77);</td>
</tr>
<tr>
<td>}</td>
<td></td>
</tr>
<tr>
<td>}</td>
<td></td>
</tr>
<tr>
<td>int main (void) {</td>
<td></td>
</tr>
<tr>
<td>int j;</td>
<td></td>
</tr>
<tr>
<td>j = which_group (7);</td>
<td></td>
</tr>
<tr>
<td>return(j);</td>
<td>return(j);</td>
</tr>
</tbody>
</table>

**Selectively marking code to inline**

The z/OS XL C/C++ inliner supports two modes of running: selective and automatic.

Selective mode enables you to specify, in your source code, the functions that you do, and do not, want inlined.

If you know which functions are frequently invoked from within a compilation unit, you can mark them for inlining:
- For a C program, add the appropriate \texttt{#pragma inline} directives in your source and compile with \texttt{INLINE (NOAUTO,REPORT,\_\_)}.
- For a C++ program, add \texttt{inline} keywords to your source and compile with \texttt{INLINE (NOAUTO,REPORT,\_\_)}.
- You can also use the \texttt{always\_inline} function attribute to inline a function, regardless of whether optimization was specified at compile time.
If your code contains complex macros, the macros can be made into static routines that are marked to be inlined at no execution-time cost. All static routines that are interfaces to a data object can be placed in a header file.

**Automatically choosing functions to inline**

Automatic mode assists you with starting to optimize your code. It allows the compiler to choose potential functions to inline. The compiler will inline all routines that are less than the *threshold* in abstract code units (ACUs) until the function that the functions are inlined into is greater than *limit* abstract code units. The *threshold* and *limit* parameters are defined as follows:

*threshold*

Maximum relative size of a function to inline. The default value is 100 Abstract Code Units (ACUs), both for C and C++. ACUs are proportional in size to the executable code in the function; your code is translated into ACUs by the compiler. Specifying a threshold of 0 is equivalent to specifying NOAUTO. Note that the proportion of ACUs to executable code in a function is different under IPA.

*limit*

Maximum relative size a function can grow before auto-inlining stops. The default is 1000 ACUs for the specific function. Specifying a limit of 0 is equivalent to specifying NOAUTO.

**Note:** When functions become too large, runtime performance can degrade.

Under the z/OS UNIX shell, to provide assistance in choosing which routines to inline, use the `c89 -W` command to pass the INLRPT option to the z/OS XL C/C++ compiler. At NOOPT, you will also need to specify the INLINE option. The default at NOOPT is NOINLINE.

For example, at NOOPT, to get INLINE(AUTO,REPORT,100,1000) for a C program, use one of the following c89 commands:

```
c89 -W "0,inline(REPORT,,)" example.c
```

You can get the same value at OPT for a C program passing the INLRPT option to the z/OS XL C/C++ compiler as follows:

```
c89 -2 -W "0,inlrpt"
```

**Note:** Inlining debugging functions or functions that are rarely invoked can degrade performance. Use the *#pragma noinline* directive to instruct the automatic inliner to not inline these types of functions. The *#pragma inline* and the *#pragma noinline* directives and the inline keyword are honored by automatic inlining regardless of the *limit* and *threshold* you have specified. For more information, see *inline* in z/OS XL C/C++ Language Reference.

**Modifying automatic inlining choices**

While automatic inlining is the best choice the compiler can make for you, you can further improve your performance. Use *#pragma inline* and *#pragma noinline* to reduce the need to modify your inlining choices when you change your application. You may want to wait until you have a stable application before you do the following steps.

1. Compile with the OPTIMIZE option and ask for a report from the inliner by specifying the compiler options INLINE(REPORT,.) or INLRPT and OPTIMIZE.
2. Look at the report to see if anything was inlined that should not have been; for example, routines for debugging or handling exceptions. Add `#pragma noinline` to your source to insure that these functions do not get inlined.

3. Add the `inline` keyword (for C++) or the `#pragma inline` directive (for C) to any frequently used routines to ensure that it gets inlined.

4. Recompile with OPTIMIZE then, regenerate the inline report and reanalyze for functions that should and should not be inlined.

5. You should also vary the limit and threshold values.
   - The inline report tells you the abstract code units (ACUs) for each function. These should help you determine an appropriate threshold to start from. In general, your initial threshold should be as small as possible, and your initial limit should be in the 1000 to 2000 range.
   - Increase the threshold by an increment small enough to catch a few more routines each time.
   - Change the limit when you wish. Because performance will improve as a function of both the limit and the threshold values, it is not recommended that you change both limit and threshold at the same time.

6. Repeat the process until you feel that you have found the best performance parameters. You should run your application to determine if the tuning has found the best performance parameters.

7. When you are satisfied with the selection of inlined routines, add the appropriate `#pragma inline` directives or `inline` keywords to the source. That is, when the selected routines are forced with these directives, you can then compile the program in selective mode. This way, you do not need to be affected by changes made to the heuristics used in the automatic inliner.

**Overriding inlining defaults**

Automatic and selective inlining are performed when the OPTIMIZE compiler option is specified. You can override this by specifying the NOINLINE option when you specify your optimization level. You can also override this by specifying the `#pragma noinline` directive for a particular function. For more information, see `inline` in z/OS XL C/C++ Language Reference.

**Inlining under IPA**

The IPA Inliner functions differently from the regular inliner:

- It performs inlining across compilation units, rather than within a compilation unit.
- It handles inlining of functions with variable argument lists.
- It inlines calls from recursive cycles (for example, where function A calls function B calls function C calls function A). However, it avoids making the functions too large.

For more information about IPA, see "Using the IPA option" on page 732.

**Using the XPLINK option**

Applications that make many calls to small functions get the most benefit from using XPLINK. Many C++ applications are structured this way, because of the object oriented programming model. C applications that make many function calls may also be suitable for XPLINK.
When you should not use XPLINK

Functions compiled XPLINK and NOXPLINK cannot be combined in the same program object.

XPLINK provides a significant performance enhancement to some applications, but can degrade the performance of applications that are not suitable for XPLINK.

Another way to call an XPLINK function from a non-XPLINK program object is to use the DLL call mechanism. There is an overhead cost associated with calls made from non-XPLINK to XPLINK, and from XPLINK to non-XPLINK. This overhead includes the need to swap from one stack type to another and to convert the passed parameters to the style accepted by the callee. Applications that make a large number of these "cross-linkage" calls may lose any benefit obtained from the parts that have been compiled XPLINK. In fact, performance could degrade from the pure non-XPLINK case. If the number of pure XPLINK function calls is significantly greater than the number of "cross-linkage" calls, the cost saved on XPLINK calls will offset the costs associated with calls that involve stack swapping.

When you introduce an XPLINK program object into your application (for example, an XPLINK version of a vendor-DLL which your application uses), your application must run in an XPLINK environment (this is controlled by the XPLINK runtime option). In an XPLINK environment, an XPLINK version of the C/C++ Runtime Library (RTL) is used. You cannot have both the non-XPLINK and XPLINK versions of the C/C++ RTL active at the same time, so non-XPLINK callers of the C/C++ RTL will also incur this stack swapping overhead in an XPLINK environment.

The maximum performance improvement can be achieved by recompiling an entire application XPLINK. The further the application gets from pure XPLINK, the less the performance improvement. At some point, you may actually see a performance degradation.

The only compiler that currently supports the XPLINK compiler option is the z/OS C/C++ compiler. All COBOL and PL/I programs are non-XPLINK. Calls between COBOL or PL/I and XPLINK-compiled C/C++ are cross-linkage calls and will incur the stack swapping overhead.

For more information on making ILC calls with XPLINK, refer to z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications.

Applications that use Language Environment facilities that are not supported in an XPLINK environment, or that use products that are not supported in an XPLINK environment (for example, CICS), cannot be recompiled as XPLINK applications.

For more information about XPLINK, see z/OS Language Environment Programming Guide.

Using the IPA option

Interprocedural Analysis (IPA), through the IPA compiler option, can also improve the execution time of your z/OS XL C/C++ application. IPA is a mechanism for performing optimizations across compilation unit boundaries. It also performs optimizations not otherwise available with the z/OS XL C/C++ compiler, such as:
- Inlining across compilation units
IPA also supports Program-directed feedback (PDF). The PDF suboptions allow the compiler to use information from training runs when optimizing the code. The compiler can then focus its optimizations on the most executed parts of the code and move low-priority code out of the critical path.

This information provides an overview of the Interprocedural Analysis (IPA) processing that is available through the IPA compiler option. For more information, see:

- For the effects of IPA on compiling, compiler options, and compiler listings: IPA considerations in z/OS XL C/C++ User’s Guide
- For the effects of IPA on pragmas: IPA considerations in z/OS XL C/C++ Language Reference

### Types of procedural analysis

The z/OS XL C/C++ compiler performs both intraprocedural and interprocedural analysis.

Intraprocedural analysis is a mechanism for performing optimization for each function in a compilation unit, using only the information available for that function and compilation unit.

Interprocedural analysis is a mechanism for performing optimization across function and compilation unit boundaries. When inlining is in effect, the C/C++ compiler performs a limited form of interprocedural analysis, where it only applies within a compilation unit.

Interprocedural analysis through the IPA compiler option improves upon the limited interprocedural analysis described above. When you invoke interprocedural analysis through the IPA option, the compiler performs optimizations across the entire program. It also performs optimizations not otherwise available with the C/C++ compiler. The types of optimizations performed include:

- **Inlining across compilation units**
  - Inlining replaces certain function calls with the actual code of the function. Inlining not only eliminates the linkage overhead but also exposes the entire function to the caller and thus enables the compiler to better optimize your code.

- **Program partitioning**
  - Program partitioning improves performance by reordering functions to exploit locality of reference. Functions that call each other frequently will be closer together in memory.

- **Coalescing of global variables**
  - The compiler puts global variables into one or more structures and accesses the variables by calculating the offsets from the beginning of the structures. This lowers the cost of variable access and exploits data locality.

- **Code straightening**
  - Code straightening streamlines the flow of your program.
Unreachable code elimination
Unreachable code elimination removes unreachable code within a function.

Call graph pruning of unreachable functions
Call graph pruning of unreachable functions removes code that is 100% inlined or never referenced.

Intraprocedural constant and set propagation
IPA propagates floating point and integer constants to their uses and computes constant expressions at compile time. Also, variable uses that are known to be one of several constants can result in the folding of conditionals and switches.

Intraprocedural pointer alias analysis
IPA tracks pointer definitions to their uses, resulting in more refined information about memory locations that a pointer dereference may use or define. This enables other parts of the compiler to better optimize code around such dereferences. IPA tracks data and function pointer definitions. When a pointer dereference can only refer to a single memory location or function, the dereference is rewritten to be an explicit reference to the memory location or function.

Intraprocedural copy propagation
IPA propagates expressions defining some variables to the uses of the variable. This creates additional opportunities for constant expression folding. It also eliminates redundant variable copies.

Intraprocedural unreachable code and store elimination
IPA removes definitions of variables that cannot be reached, along with the computation feeding the definition.

Conversion of reference (address) arguments to value arguments
IPA converts reference (address) arguments to value arguments when the formal parameter is not written in the called procedure.

Conversion of static variables to automatic (stack) variables
IPA converts static variables to automatic (stack) variables when their use is limited to a single procedure invocation.

The execution time for code optimized using interprocedural analysis (IPA compile and link) is normally faster than for code optimized using intraprocedural analysis (IPA compile only) or the OPT compiler option. Please note that not all applications are suited for IPA optimization and the performance gains realized from using IPA will vary.

Note: For additional information about using the IPA(LINK) option, see “IPA(LINK) option and exploitation of 64-bit virtual memory” on page 332.

Program-directed feedback
IPA uses program-directed feedback (PDF) to organize the code and to focus optimization on the frequently-used portions of the code. This can result in significant performance gains. Using PDF is a two-step process, that first gathers training data, then optimizes code during compile time.

Training data is gathered by running an application that was built using the PDF suboptions. When the application is run it collects information about itself. This information is the training data. The application should be run in a normal manner with accurate and varied input in order to gather as much valid training data as possible.
The second IPA build uses the training data when optimizing. This training data gives IPA information on:

- The most common paths
- The critical paths
- The least-used parts of the code

As of z/OS V1R12 XL C/C++ compiler, stale profiling data can be used in the second stage of the PDF process, if minor changes are made to the source file in the first PDF stage. As a result of this change to the behavior of the PDF process, it will be possible to run both stages of PDF under different compilation options. The compiler will issue a list of warnings but will not terminate. During the link step, the compiler will print a message identifying any functions that have been detected to change from the first stage of PDF process.

**Compiler processing flow**

IPA changes the flow of compiler processing. The following sections explain the differences.

**Regular compiler execution**

If you specify the NOIPA compiler option (the default), the compiler processes source files, as shown in Figure 170. The output is an object module for each source file processed. You can then bind the object modules to produce an executable module.

![Figure 170. Flow of regular compiler processing](image)

**Compiler execution with IPA**

IPA processing consists of two steps: IPA Compile and IPA Link. You run the IPA Compile step once for each compilation unit, and run the IPA Link step once for the program as a whole. The final output is a single IPA-optimized object module which you must bind with the binder to produce an executable load module.

**Notes:**

- If you want to get the maximum benefit from IPA, run both the IPA Compile and IPA Link steps.
- In z/OS UNIX shell environments, the c89 utility is required during the IPA Link step.
You can invoke the IPA Compile step in the same environments that you use for a regular compilation. You can invoke the IPA Link step only in MVS batch mode or in one of the z/OS UNIX shell environments through the c89 utility.

This information describes the flow of IPA processing under MVS batch. The flow of processing with the c89 utility is the same, but there are differences in how you invoke IPA.

**IPA Compile step processing:** You invoke the IPA Compile step by specifying the IPA(NOLINK) compiler option, as shown in Figure 171 (NOLINK is the default suboption). During the IPA Compile step, the compiler creates optimized objects. These objects contain information that the IPA Link step can use for further optimization.

The following processing takes place for each compilation unit that you specify for the IPA Compile step:
1. The compiler determines the final suboptions for the IPA option, based upon the compiler options and IPA suboptions that you specified. This is necessary because the compiler does not support some combinations of compiler options and IPA suboptions. The compiler issues a warning message if it finds unsupported combinations.
2. The compiler promotes some IPA suboptions based upon the presence of related compiler options and issues informational messages if it does so. For more information, see [Interactions](#) in z/OS XL C/C++ User’s Guide.
3. The compiler generates an IPA object file. This object file contains control information for a compilation unit required for the IPA Link step.
The IPA object module produced by IPA (NOLINK,NOOBJECT) has the same structure as a regular object module. It should not be used as input to the prelinker, linker, or binder.

Each IPA object contains a CSECT that includes the ESD name @@IPAOBJ.

4. If you specify the OBJECT suboption of the IPA option, the compiler produces a combined IPA and conventional object file. While the conventional object file is not required by the IPA Link step, creating it permits you to bind this file to create an executable module, without doing the IPA Link step, because it is more difficult to debug code optimized by the interprocedural analysis.

During the IPA Compile step, the compiler generates information that allows you to create object libraries with the C370LIB utility or to create z/OS UNIX archives with the ar utility. The information consists of XSD and ESD records for the external symbols that were defined in the compilation units of your program. You can use the object libraries and z/OS UNIX archives for autocall searching in the IPA Link step. During autocall searching, the IPA Link step searches these libraries and archives for external references from your program.

IPA Link step processing: You invoke the IPA Link step by specifying the IPA(LINK) compiler option, as shown in Figure 172. During this step, the compiler links the IPA objects that were produced by the IPA Compile step (along with non-IPA object files and load modules, if specified), does partitioning, performs optimizations, and generates the final object code.

![Figure 172. IPA link step processing](image)

The following processing takes place:

1. The compiler determines the final suboptions for the IPA option, based upon the compiler options and IPA suboptions you specify. This is necessary because
some combinations of compiler options and IPA suboptions are unsupported. The compiler issues informational and warning messages for unsupported combinations.

2. The compiler links IPA object files, as well as non-IPA object files and load modules (if specified). The compiler also merges information from the IPA Compile step.

Input for the Link step comes from one of three sources:

- The primary input file (specified by the SYSIN ddname). This can be either:
  - A set of IPA Link control statements that you create
    These may be INCLUDE and LIBRARY IPA Link control statements that explicitly identify secondary input files. IPA uses the same control statement format (with some exceptions) used by the binder.
  - The IPA object file from the compilation unit that contains the main function or fetchable entry point. If you specify this file, the compiler searches for all other IPA files using the SYSLIB ddname.

- One or more secondary input files
  The secondary input file may contain:
  - IPA object files or PDS libraries
  - Conventional object files or PDS libraries
  - Load module libraries
  - z/OS UNIX archive libraries
  - IPA Link control statements
  These secondary input files are to be used for autocall searches. You can specify these files through the SYSLIB ddname or explicitly include them through INCLUDE or LIBRARY IPA Link control statements on the IPA Link step.

Load module libraries are used to support library interface routines (such as CICS and Language Environment) that are implemented as load module libraries. Since IPA must resolve all parts of your application program before beginning optimization, make all of these libraries as well as your application object modules available to the IPA Link step.

The IPA Link step resolves external references using explicit and autocall resolution. This allows IPA to identify the static and global data and the external references for the whole program.

Ensure that you do not accidentally specify FB, LRECL 80 source files as input to the IPA Link step. The IPA Link step will assume that records from these files contain valid object information, and will retain them in the object file. When the linkage editor processes the object file, it will determine the records to be invalid, and will issue diagnostic messages.

- The IPA Link step control file. This file contains additional IPA control directives. The CONTROL suboption of the IPA compiler option identifies this file. For more information, see IPA Link step control file in z/OS XL C/C++ User’s Guide.

3. As objects are processed, IPA Link Step builds the program call graph, merging the IPA object code according to its place in the call graph. If necessary, IPA Link Step stores non-IPA object code for inclusion in the final object file, and converts load module library members into object format for inclusion in the final object file.

4. The compiler performs optimizations across the call graph. You specify the type and extent of optimizations using the LEVEL suboption of the IPA compiler option.
5. IPA Link Step divides the program call graph into separate units called partitions. Partitioning of the call graph is controlled by:
   • The partition size limit that is specified in the IPA control file.
   • The connectivity of your program. IPA places code that is isolated from the rest of the program into a separate partition.
   • Resolution of conflicting effects between the compiler options and pragmas specified for compilation units processed during the IPA Compile step. These are the compiler options and pragmas that generate information during the analysis phase of the compiler for input to the code-generation phase.

IPA Link Step produces a final single object module for the program from these partitions.

You must bind the IPA single object module to produce the executable module.

**Note:** IPA Compile and IPA Link, as follows:

- An object file produced by an IPA Compile that contains IPA Object or combined IPA and conventional object information can be used as input to the z/OS XL C/C++ IPA Link of the same or later Version/Release.
- An object file produced by an IPA Compile that contains IPA Object or combined IPA and conventional object information cannot be used as input by the z/OS XL C/C++ IPA Link of an earlier Version/Release. If this is attempted, the IPA Link will issue an error diagnostic message.
- If the IPA object is recompiled by a later z/OS XL C/C++ IPA Compile, additional optimizations may be performed and the resulting application program may perform better.

An exception to this is the IPA object files produced by the OS/390 Release 2 C IPA Compile. These must be recompiled from the program source using a compiler that is version OS/390 Release 3 or later before attempting to process them with the current IPA Link.
Chapter 43. Using high performance libraries

IBM z/OS XL C/C++ is shipped with a set of libraries for high-performance mathematical computing:

- The Mathematical Acceleration Subsystem (MASS) is a set of libraries of tuned mathematical intrinsic functions that provide improved performance over the corresponding standard system math library functions. MASS is described in "Using the Mathematical Acceleration Subsystem (MASS) libraries."
- The Automatically Tuned Linear Algebra Software (ATLAS) is a set of high-performance, processor-tuned linear algebra libraries. ATLAS is described in "Using the Automatically Tuned Linear Algebra Software (ATLAS) libraries" on page 753.

Using the Mathematical Acceleration Subsystem (MASS) libraries

The XL C/C++ compiler is shipped with a set of Mathematical Acceleration Subsystem (MASS) libraries for high-performance mathematical computing.

The MASS libraries consist of a library of scalar C functions tuned for specific architectures described in "Using the MASS scalar library," a vector library tuned for specific architectures described in "Using the MASS vector library" on page 744, and a SIMD library tuned for specific architectures described in "Using the MASS SIMD library" on page 748. Note that accuracy and exception handling might not be identical between MASS functions and system library functions.

The MASS functions must run with the round-to-nearest rounding mode (ROUND(N)), ARCHITECTURE(10) or higher, FLOAT(IEEE), and exception trapping turned off (NOEXH, C++ only). If you want to use the MASS SIMD functions, ARCHITECTURE(11) and VECTOR options are required.

"Compiling and linking a program with MASS" on page 749 describes how to compile and link a program that uses the MASS libraries, and how to selectively use the MASS scalar library functions in conjunction with the regular system libraries.

Using the MASS scalar library

The MASS scalar library contains an accelerated set of frequently used math intrinsic functions. They are compatible with 31-bit C linkage, 31-bit XPLINK, and 64-bit. If you want to explicitly call the MASS scalar functions, you can take the following steps:

1. Provide the prototypes for the functions by including math.h and mass.h in your source files. See the table below for the location of header files.
2. Link the appropriate scalar library with your application. Names of libraries are described in the following table.

<table>
<thead>
<tr>
<th>System Environment</th>
<th>Header file location</th>
<th>Library name for zEC12/zBC12</th>
<th>Library name for z13</th>
</tr>
</thead>
<tbody>
<tr>
<td>USS</td>
<td>/usr/include/math.h</td>
<td>/usr/lpp/cbclib/lib/</td>
<td>/usr/lpp/cbclib/lib/</td>
</tr>
<tr>
<td></td>
<td>/usr/include/mass.h</td>
<td>libmass.arch10.a</td>
<td>libmass.arch11.a</td>
</tr>
</tbody>
</table>
Table 326. Header files and library names for the MASS scalar library (continued)

<table>
<thead>
<tr>
<th>System Environment</th>
<th>Header file location</th>
<th>Library name for zEC12/zBC12</th>
<th>Library name for z13</th>
</tr>
</thead>
<tbody>
<tr>
<td>MVS</td>
<td></td>
<td>• CBC.SCCNM10 (for functions that overlap with <code>&lt;math.h&gt;</code>)</td>
<td>• CBC.SCCNM11 (for functions that overlap with <code>&lt;math.h&gt;</code>)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• CBC.SCCNN10 (for functions which are only introduced in <code>&lt;mass.h&gt;</code>)</td>
<td>• CBC.SCCNN11 (for functions which are only introduced in <code>&lt;mass.h&gt;</code>)</td>
</tr>
</tbody>
</table>

**Note:** MASS scalar functions can only run on IBM zEC12/zBC12/z13 and newer machine models. A set of libraries tuned for each machine model group are provided.

The MASS scalar functions accept double-precision parameters and return a double-precision result, or accept single-precision parameters and return a single-precision result, except sincos which gives 2 double-precision results. They are summarized in Table 327.

Table 327. MASS scalar functions

<table>
<thead>
<tr>
<th>Double-precision function</th>
<th>Single-precision function</th>
<th>Description</th>
<th>Double-precision function prototype</th>
<th>Single-precision function prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>acos</td>
<td>acosf</td>
<td>Returns the arc cosine of x</td>
<td>double acos (double x);</td>
<td>float acosf (float x);</td>
</tr>
<tr>
<td>acosh</td>
<td>acoshf</td>
<td>Returns the arc hyperbolic cosine of x</td>
<td>double acosh (double x);</td>
<td>float acoshf (float x);</td>
</tr>
<tr>
<td>anintf</td>
<td></td>
<td>Returns the nearest integer to x (as a float)</td>
<td>float anint (float x);</td>
<td></td>
</tr>
<tr>
<td>asin</td>
<td>asinf</td>
<td>Returns the arc sine of x</td>
<td>double asin (double x);</td>
<td>float asinf (float x);</td>
</tr>
<tr>
<td>asinh</td>
<td>asinhf</td>
<td>Returns the arc hyperbolic sine of x</td>
<td>double asinh (double x);</td>
<td>float asinhf (float x);</td>
</tr>
<tr>
<td>atan2</td>
<td>atan2f</td>
<td>Returns the arc tangent of x/y</td>
<td>double atan2 (double x, double y);</td>
<td>float atan2f (float x, float y);</td>
</tr>
<tr>
<td>atan</td>
<td>atanf</td>
<td>Returns the arc tangent of x</td>
<td>double atan (double x);</td>
<td>float atanf (float x);</td>
</tr>
<tr>
<td>atanh</td>
<td>atanhf</td>
<td>Returns the arc hyperbolic tangent of x</td>
<td>double atanh (double x);</td>
<td>float atanhf (float x);</td>
</tr>
<tr>
<td>cbrt</td>
<td>cbrtf</td>
<td>Returns the cube root of x</td>
<td>double cbrt (double x);</td>
<td>float cbrtf (float x);</td>
</tr>
<tr>
<td>copysign</td>
<td>copysignf</td>
<td>Returns x with the sign of y</td>
<td>double copysign (double x, double y);</td>
<td>float copysignf (float x);</td>
</tr>
<tr>
<td>cos</td>
<td>cosf</td>
<td>Returns the cosine of x</td>
<td>double cos (double x);</td>
<td>float cosf (float x);</td>
</tr>
<tr>
<td>cosh</td>
<td>coshf</td>
<td>Returns the hyperbolic cosine of x</td>
<td>double cosh (double x);</td>
<td>float coshf (float x);</td>
</tr>
<tr>
<td>Double-precision function</td>
<td>Single-precision function</td>
<td>Description</td>
<td>Double-precision function prototype</td>
<td>Single-precision function prototype</td>
</tr>
<tr>
<td>---------------------------</td>
<td>---------------------------</td>
<td>-------------</td>
<td>-------------------------------------</td>
<td>-------------------------------------</td>
</tr>
<tr>
<td>cosisin</td>
<td></td>
<td>Returns a complex number with the real part cosine of ( x ) and the imaginary part sine of ( x ).</td>
<td><code>double_Complex cosisin(double);</code></td>
<td></td>
</tr>
<tr>
<td>dnint(^1)</td>
<td></td>
<td>Returns the nearest integer to ( x ) (as a double)</td>
<td><code>double dnint(double x);</code></td>
<td></td>
</tr>
<tr>
<td>erf</td>
<td>erff</td>
<td>Returns the error function of ( x )</td>
<td><code>double erf(double x);</code></td>
<td><code>float erff(float x);</code></td>
</tr>
<tr>
<td>erfc</td>
<td>erfcf</td>
<td>Returns the complementary error function of ( x )</td>
<td><code>double erfc(double x);</code></td>
<td><code>float erfcf(float x);</code></td>
</tr>
<tr>
<td>exp</td>
<td>expf</td>
<td>Returns the exponential function of ( x )</td>
<td><code>double exp(double x);</code></td>
<td><code>float expf(float x);</code></td>
</tr>
<tr>
<td>expm1</td>
<td>expm1f</td>
<td>Returns (the exponential function of ( x )) - 1</td>
<td><code>double expm1(double x);</code></td>
<td><code>float expm1f(float x);</code></td>
</tr>
<tr>
<td>hypot</td>
<td>hypotf</td>
<td>Returns the square root of ( x^2 + y^2 )</td>
<td><code>double hypot(double x, double y);</code></td>
<td><code>float hypotf(float x, float y);</code></td>
</tr>
<tr>
<td>lgamma</td>
<td>lgammaf</td>
<td>Returns the natural logarithm of the absolute value of the Gamma function of ( x )</td>
<td><code>double lgamma(double x);</code></td>
<td><code>float lgammaf(float x);</code></td>
</tr>
<tr>
<td>log</td>
<td>logf</td>
<td>Returns the natural logarithm of ( x )</td>
<td><code>double log(double x);</code></td>
<td><code>float logf(float x);</code></td>
</tr>
<tr>
<td>log10</td>
<td>log10f</td>
<td>Returns the base 10 logarithm of ( x )</td>
<td><code>double log10(double x);</code></td>
<td><code>float log10f(float x);</code></td>
</tr>
<tr>
<td>log1p</td>
<td>log1pf</td>
<td>Returns the natural logarithm of ((x + 1))</td>
<td><code>double log1p(double x);</code></td>
<td><code>float log1pf(float x);</code></td>
</tr>
<tr>
<td>pow</td>
<td>powf</td>
<td>Returns ( x ) raised to the power ( y )</td>
<td><code>double pow(double x, double y);</code></td>
<td><code>float powf(float x, float y);</code></td>
</tr>
<tr>
<td>rint</td>
<td>rintf</td>
<td>Returns the nearest integer to ( x ) (as a double)</td>
<td><code>double rint(double x);</code></td>
<td><code>float rintf(float x);</code></td>
</tr>
<tr>
<td>rsqrt(^1)</td>
<td></td>
<td>Returns the reciprocal of the square root of ( x )</td>
<td><code>double rsqrt(double x);</code></td>
<td></td>
</tr>
<tr>
<td>sin</td>
<td>sinf</td>
<td>Returns the sine of ( x )</td>
<td><code>double sin(double x);</code></td>
<td><code>float sinf(float x);</code></td>
</tr>
<tr>
<td>sincos(^1)</td>
<td></td>
<td>Sets ( *s ) to the sine of ( x ) and ( *c ) to the cosine of ( x )</td>
<td><code>void sincos(double x, double* s, double* c);</code></td>
<td></td>
</tr>
<tr>
<td>sinh</td>
<td>sinhf</td>
<td>Returns the hyperbolic sine of ( x )</td>
<td><code>double sinh(double x);</code></td>
<td><code>float sinhf(float x);</code></td>
</tr>
<tr>
<td>sqrt</td>
<td></td>
<td>Returns the square root of ( x )</td>
<td><code>double sqrt(double x);</code></td>
<td></td>
</tr>
<tr>
<td>tan</td>
<td>tanf</td>
<td>Returns the tangent of ( x )</td>
<td><code>double tan(double x);</code></td>
<td><code>float tanf(float x);</code></td>
</tr>
</tbody>
</table>
### Table 327. MASS scalar functions (continued)

<table>
<thead>
<tr>
<th>Double-precision function</th>
<th>Single-precision function</th>
<th>Description</th>
<th>Double-precision function prototype</th>
<th>Single-precision function prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>tanh</td>
<td>tanhf</td>
<td>Returns the hyperbolic tangent of x</td>
<td>double tanh (double x);</td>
<td>float tanhf (float x);</td>
</tr>
</tbody>
</table>

**Notes:**
- Functions denoted as `function-name` are declared in `<mass.h>`, and all other functions are declared in `<math.h>`.
- The trigonometric functions (`sin`, `cos`, `tan`) return NaN (Not-a-Number) for large arguments (where the absolute value is greater than $2^{50}\pi$).
- The `pow` function accepts negative `x` arguments with integer `y` arguments according to the C standard.
- In some cases, the MASS functions are not as precise as the system library, and they might handle edge cases differently (e.g., `sqrt(Inf)` for example).

### Using the MASS vector library

The MASS vector library provides a set of functions that compute the same mathematical function for vectors of operands. If you want to explicitly call the MASS vector functions, take the following steps:

1. Provide the prototypes for the functions by including `massv.h` in your source files. See the table below for the location of header files.
2. Link the appropriate library with your application. Names of libraries are described in the following table.

#### Table 328. Header files and library names for the MASS vector library

<table>
<thead>
<tr>
<th>System Environment</th>
<th>Header file location</th>
<th>Library name for zEC12/zBC12</th>
<th>Library name for z13</th>
</tr>
</thead>
<tbody>
<tr>
<td>USS</td>
<td>/usr/include/massv.h</td>
<td>/usr/lpp/cbclib/lib/libmassv.arch10.a</td>
<td>/usr/lpp/cbclib/lib/libmassv.arch11.a</td>
</tr>
<tr>
<td>MVS</td>
<td>CEE.SCEEH.H</td>
<td>CBC.SCCNNIO</td>
<td>CBC.SCCNN11</td>
</tr>
</tbody>
</table>

**Note:** MASS vector functions can only run on IBM zEC12/zBC12/z13 and newer hardware models. A set of libraries tuned for each machine model group are provided.

The single-precision and double-precision floating-point functions contained in the vector library are summarized in Table 329 on page 745. Note that in C and C++ applications, only call by reference is supported, even for scalar arguments. With the exception of a few functions (described in the following paragraph), all of the floating-point functions in the vector library accept three parameters:

- A double-precision (for double-precision functions) or single-precision (for single-precision functions) vector output parameter
- A double-precision (for double-precision functions) or single-precision (for single-precision functions) vector input parameter
- An integer vector-length parameter

Except for the special cases listed below, the functions are of the form:

```
function_name (y, x, n)
```
where $y$ is the target vector, $x$ is the source vector, and $n$ is the pointer to the vector length. The parameters $y$ and $x$ are assumed to be double-precision for functions with the prefix v, and single-precision for functions with the prefix vs.

For example, the following code:

```c
#include <massv.h>

double x[500], y[500];
int n;
n = 500;
...
vexp (y, x, &n);
```

outputs a vector $y$ of length 500 whose elements are $\exp(x[i])$, where $i=0,\ldots,499$.

The functions vdiv, vsin, vsin, and vatan2 (and their single-precision versions, vdiv, vsin, vpow, and vsatan2) take four arguments. The functions vdiv, vpow, and vatan2 take the arguments $(z, x, y, n)$. The function vdiv outputs a vector $z$ whose elements are $x[i]/y[i]$, where $i=0,\ldots,n-1$. The function vpow outputs a vector $z$ whose elements are $x[i]^y[i]$, where $i=0,\ldots,n-1$. The function vatan2 outputs a vector $z$ whose elements are $\tan(x[i]/y[i])$, where $i=0,\ldots,n-1$. The function vsin takes the arguments $(y, x, n)$, and outputs two vectors, $y$ and $z$, whose elements are $\sin(x[i])$ and $\cos(x[i])$, respectively.

Note that some of the MASS floating point vector functions are only available when compiled with ARCHITECTURE(11). These functions are denoted by having a superscript 't' after their name (for example, “functiont” in the following table.)

Table 329. MASS floating-point vector functions

<table>
<thead>
<tr>
<th>Double-precision function</th>
<th>Single-precision function</th>
<th>Description</th>
<th>Double-precision function prototype</th>
<th>Single-precision function prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>vacos</td>
<td>vsacos</td>
<td>Sets $y[i]$ to the arc cosine of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vacos (double y[], double x[], int *n);</td>
<td>void vsacos (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vacosh</td>
<td>vsacosh</td>
<td>Sets $y[i]$ to the hyperbolic arc cosine of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vacosh (double y[], double x[], int *n);</td>
<td>void vsacosh (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vasin</td>
<td>vsasin</td>
<td>Sets $y[i]$ to the arc sine of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vasin (double y[], double x[], int *n);</td>
<td>void vsasin (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vasin</td>
<td>vsasin</td>
<td>Sets $y[i]$ to the hyperbolic arc sine of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vasinh (double y[], double x[], int *n);</td>
<td>void vsasinh (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vatan2</td>
<td>vsatan2</td>
<td>Sets $z[i]$ to the arc tangent of $x[i]/y[i]$, for $i=0,\ldots,n-1$</td>
<td>void vatan2 (double z[], double x[], double y[], int *n);</td>
<td>void vsatan2 (float z[], float x[], float y[], int *n);</td>
</tr>
<tr>
<td>vatan'</td>
<td>vsatan'</td>
<td>Sets $y[i]$ to the arc tangent of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vatan (double y[], double x[], int *n);</td>
<td>void vsatan (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vatanh</td>
<td>vsatanh</td>
<td>Sets $y[i]$ to the hyperbolic arc tangent of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vatanh (double y[], double x[], int *n);</td>
<td>void vsatanh (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vcbrt</td>
<td>vscbrt</td>
<td>Sets $y[i]$ to the cube root of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vcbrt (double y[], double x[], int *n);</td>
<td>void vscbrt (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vcos</td>
<td>vscos</td>
<td>Sets $y[i]$ to the cosine of $x[i]$, for $i=0,\ldots,n-1$</td>
<td>void vcos (double y[], double x[], int *n);</td>
<td>void vsicos (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>Double-precision function</td>
<td>Single-precision function</td>
<td>Description</td>
<td>Double-precision function prototype</td>
<td>Single-precision function prototype</td>
</tr>
<tr>
<td>---------------------------</td>
<td>---------------------------</td>
<td>-------------</td>
<td>-------------------------------------</td>
<td>-------------------------------------</td>
</tr>
<tr>
<td>vcosh</td>
<td>vcosinh</td>
<td>Sets ( y[i] ) to the hyperbolic cosine of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vcosh (double y[], double x[], int *n);</td>
<td>void vcosinh (double y[], double x[], int *n);</td>
</tr>
<tr>
<td>vcosisin</td>
<td>vcosisin</td>
<td>Sets the real part of ( y[i] ) to the cosine of ( x[i] ) and the imaginary part of ( y[i] ) to the sine of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vcosisin (double _Complex y[], double x[], int *n);</td>
<td>void vcosisin (float _Complex y[], float x[], int *n);</td>
</tr>
<tr>
<td>vdint</td>
<td></td>
<td>Sets ( y[i] ) to the integer truncation of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vdint (double y[], double x[], int *n);</td>
<td></td>
</tr>
<tr>
<td>vdiv</td>
<td>vdsdiv</td>
<td>Sets ( z[i] ) to ( x[i] / y[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vdiv (double z[], double x[], double y[], int *n);</td>
<td>void vdsdiv (float z[], float x[], float y[], int *n);</td>
</tr>
<tr>
<td>vdnint</td>
<td></td>
<td>Sets ( y[i] ) to the nearest integer to ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vdnint (double y[], double x[], int *n);</td>
<td></td>
</tr>
<tr>
<td>verf</td>
<td>vserf</td>
<td>Sets ( y[i] ) to the error function of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void verf (double y[], double x[], int *n);</td>
<td>void vserf (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>verfc</td>
<td>vserfc</td>
<td>Sets ( y[i] ) to the complimentary error function of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void verfc (double y[], double x[], int *n);</td>
<td>void vserfc (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vexp</td>
<td>vsexp</td>
<td>Sets ( y[i] ) to the exponential function of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vexp (double y[], double x[], int *n);</td>
<td>void vsexp (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vexp2</td>
<td>vsexp2</td>
<td>Sets ( y[i] ) to ( 2 ) raised to the power of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vexp2 (double y[], double x[], int *n);</td>
<td>void vsexp2 (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vexpm1</td>
<td>vsexpm1</td>
<td>Sets ( y[i] ) to ( (\text{the exponential function of } x[i])^{-1} ), for ( i=0,\ldots,n-1 )</td>
<td>void vexpm1 (double y[], double x[], int *n);</td>
<td>void vsexpm1 (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vexp2m1</td>
<td>vsexp2m1</td>
<td>Sets ( y[i] ) to ( (2 \text{ raised to the power of } x[i]) - 1 ), for ( i=0,\ldots,n-1 )</td>
<td>void vexp2m1 (double y[], double x[], int *n);</td>
<td>void vsexp2m1 (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vhypot</td>
<td>vshypot</td>
<td>Sets ( z[i] ) to the square root of the sum of the squares of ( x[i] ) and ( y[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vhypot (double z[], double x[], double y[], int *n);</td>
<td>void vshypot (float z[], float x[], float y[], int *n);</td>
</tr>
<tr>
<td>vlog</td>
<td>vslog</td>
<td>Sets ( y[i] ) to the natural logarithm of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vlog (double y[], double x[], int *n);</td>
<td>void vslog (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vlog2</td>
<td>vslog2</td>
<td>Sets ( y[i] ) to the base-2 logarithm of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vlog2 (double y[], double x[], int *n);</td>
<td>void vslog2 (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vlog10</td>
<td>vslog10</td>
<td>Sets ( y[i] ) to the base-10 logarithm of ( x[i] ), for ( i=0,\ldots,n-1 )</td>
<td>void vlog10 (double y[], double x[], int *n);</td>
<td>void vslog10 (float y[], float x[], int *n);</td>
</tr>
</tbody>
</table>
### Table 329. MASS floating-point vector functions (continued)

<table>
<thead>
<tr>
<th>Double-precision function</th>
<th>Single-precision function</th>
<th>Description</th>
<th>Double-precision function prototype</th>
<th>Single-precision function prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>vlog1p</td>
<td>vslog1p</td>
<td>Sets y[i] to the natural logarithm of (x[i]+1), for i=0,..,*n-1</td>
<td>void vlog1p (double y[], double x[], int *n);</td>
<td>void vslog1p (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vlog21p</td>
<td>vslog21p</td>
<td>Sets y[i] to the base-2 logarithm of (x[i]+1), for i=1,..,*n-1</td>
<td>void vlog21p (double y[], double x[], int *n);</td>
<td>void vslog21p (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vpow</td>
<td>vspow</td>
<td>Sets z[i] to x[i] raised to the power y[i], for i=0,..,*n-1</td>
<td>void vpow (double z[], double x[], double y[], int *n);</td>
<td>void vspow (float z[], float x[], float y[], int *n);</td>
</tr>
<tr>
<td>vqdrt</td>
<td>vsqdrt</td>
<td>Sets y[i] to the fourth root of x[i], for i=0,..,*n-1</td>
<td>void vqdrt (double y[], double x[], int *n);</td>
<td>void vsqdrt (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vrcbrt</td>
<td>vsrcbrt</td>
<td>Sets y[i] to the reciprocal of the cube root of x[i], for i=0,..,*n-1</td>
<td>void vrcbrt (double y[], double x[], int *n);</td>
<td>void vsrcbrt (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vrec</td>
<td>vsrec</td>
<td>Sets y[i] to the reciprocal of x[i], for i=0,..,*n-1</td>
<td>void vrec (double y[], double x[], int *n);</td>
<td>void vsrec (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vrqdrt</td>
<td>vsrqdrt</td>
<td>Sets y[i] to the reciprocal of the fourth root of x[i], for i=0,..,*n-1</td>
<td>void vrqdrt (double y[], double x[], int *n);</td>
<td>void vsrqdrt (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vrqrt</td>
<td>vsrqrt</td>
<td>Sets y[i] to the reciprocal of the square root of x[i], for i=0,..,*n-1</td>
<td>void vrqrt (double y[], double x[], int *n);</td>
<td>void vsrqrt (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vsin</td>
<td>vssin</td>
<td>Sets y[i] to the sine of x[i], for i=0,..,*n-1</td>
<td>void vsin (double y[], double x[], int *n);</td>
<td>void vssin (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vsincos</td>
<td>vssincos</td>
<td>Sets y[i] to the sine of x[i] and z[i] to the cosine of y[i], for i=0,..,*n-1</td>
<td>void vsincos (double y[], double z[], double x[], int *n);</td>
<td>void vssincos (float y[], float z[], float x[], int *n);</td>
</tr>
<tr>
<td>vsinh</td>
<td>vssinh</td>
<td>Sets y[i] to the hyperbolic sine of x[i], for i=0,..,*n-1</td>
<td>void vsinh (double y[], double x[], int *n);</td>
<td>void vssinh (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vsqrt</td>
<td>vssqrt</td>
<td>Sets y[i] to the square root of x[i], for i=0,..,*n-1</td>
<td>void vsqrt (double y[], double x[], int *n);</td>
<td>void vssqrt (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vtan</td>
<td>vstan</td>
<td>Sets y[i] to the tangent of x[i], for i=0,..,*n-1</td>
<td>void vtan (double y[], double x[], int *n);</td>
<td>void vstan (float y[], float x[], int *n);</td>
</tr>
<tr>
<td>vtaninh</td>
<td>vstanh</td>
<td>Sets y[i] to the hyperbolic tangent of x[i], for i=0,..,*n-1</td>
<td>void vtaninh (double y[], double x[], int *n);</td>
<td>void vstanh (float y[], float x[], int *n);</td>
</tr>
</tbody>
</table>

Integer functions are of the form `function_name(x[]`, *n), where x[] is a vector of 4-byte (for vpopcnt4) or 8-byte (for vpopcnt8) numeric objects (integral or floating-point), and *n is the vector length.

### Table 330. MASS integer vector functions

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
<th>Prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>vpopcnt4</td>
<td>Returns the total number of 1 bits in the concatenation of the binary representation of x[i], for i=0,..,*n-1 , where x is a vector of 32-bit objects.</td>
<td>unsigned int vpopcnt4 (void *x, int *n)</td>
</tr>
</tbody>
</table>
Table 330. MASS integer vector functions (continued)

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
<th>Prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>vpopcnt8</td>
<td>Returns the total number of 1 bits in the concatenation of the binary representation of x[i], for i=0,..,n-1, where x is a vector of 64-bit objects.</td>
<td>unsigned int vpopcnt8 (void *x, int *n)</td>
</tr>
</tbody>
</table>

Using the MASS SIMD library

The MASS SIMD library contains a set of frequently used math intrinsic functions that provide improved performance over the corresponding standard scalar system library functions, and operate on and return vector data types. If you want to explicitly call the MASS SIMD functions, take the following steps:

1. Link the appropriate scalar library with your application using information in the following table.
2. Provide the prototypes for the functions by including mass_simd.h in your source files. The default installation location of these files is as follows:
   - In USS, mass_simd.h can be found in /usr/include.
   - Under MVS (batch mode), the headers are found in CEE.SCEEH.H.
3. Link the appropriate SIMD library with your application using information in the following table.

Table 331. Header files and library names for the MASS SIMD library

<table>
<thead>
<tr>
<th>System Environment</th>
<th>Header file location</th>
<th>Library name for z13</th>
</tr>
</thead>
<tbody>
<tr>
<td>USS</td>
<td>/usr/include/mass_simd.h</td>
<td>/usr/lpp/cbclib/lib/libmass_simd.arch11.a</td>
</tr>
<tr>
<td>MVS</td>
<td>CEE.SCEEH.H</td>
<td>CBC.SCCNN11</td>
</tr>
</tbody>
</table>

Note: MASS SIMD functions can only run on IBM z13 and newer hardware models.

The double-precision MASS SIMD functions have arguments and return values of type vector double. The available MASS SIMD functions are summarized in Table 332.

Table 332. MASS SIMD functions

<table>
<thead>
<tr>
<th>Double-precision function</th>
<th>Description</th>
<th>Double-precision function prototype</th>
</tr>
</thead>
<tbody>
<tr>
<td>cosd2</td>
<td>Computes the cosine of each element of vx.</td>
<td>vector double cosd2 (vector double vx);</td>
</tr>
<tr>
<td>divd2</td>
<td>Computes the quotient vx/vy.</td>
<td>vector double divd2 (vector double vx, vector double vy);</td>
</tr>
<tr>
<td>expd2</td>
<td>Computes the exponential function of each element of vx.</td>
<td>vector double expd2 (vector double vx);</td>
</tr>
<tr>
<td>logd2</td>
<td>Computes the natural logarithm of each element of vx.</td>
<td>vector double logd2 (vector double vx);</td>
</tr>
<tr>
<td>powd2</td>
<td>Computes each element of vx raised to the power of the corresponding element of vy.</td>
<td>vector double powd2 (vector double vx, vector double vy);</td>
</tr>
</tbody>
</table>
### Compiling and linking a program with MASS

This section deals with the specifics of compiling and linking your application with the MASS libraries.

**Required compiler options**

To compile a program that utilizes any MASS functions, the following compiler options must be used:

- FLOAT(IEEE)
- ARCHITECTURE(10) - the minimum required ARCH level
- ARCHITECTURE(11) - required if you use any MASS SIMD functions
- VECTOR - required if you use any MASS SIMD functions
- NOEXH - required for C++ applications only

While you might still be able to compile your MASS application without satisfying the above requirements, the program will likely not give correct results.

**Compilation step - MASS headers**

To use MASS functions in your application, you need to include the appropriate MASS header(s) for the type of MASS function being used (for a complete list of MASS functions available, see "Using the MASS scalar library" on page 741, "Using the MASS vector library" on page 744, and "Using the MASS SIMD library" on page 748).

The default installation of MASS places the MASS headers in your default header search path. If you cannot find the MASS headers in your default search path, contact your system programmer.

The following examples demonstrate the relationship among MASS functions, headers, and libraries, and show how to use MASS in your source program.

**Sample 1:**

```c
/* Using the MASS-only scalar function 'rsqrt'
  Compile command: xlc -qARCH=10 -qFLOAT=IEEE -c sample1.c */
#include <math.h>
#include <mass.h> /* The 'rsqrt' function is declared in <mass.h>, not <math.h> */
int main(void) {
  double input = 16;
  double output;
```
output = rsqrt(input);

/* ... Code to utilize the results in "output" goes here */
}

Sample 2:
/* Using the MASS scalar function 'pow'
   Compile command: xlc -qARCH=10 -qFLOAT=IEEE -c sample2.c
 */
#include <math.h> /* The 'pow' function is declared in <math.h>, not <mass.h> */
#include <mass.h>

int main(void) {
    double base = 3;
    double exponent = 2;
    double output;
    output = pow(base, exponent);
    /* ... Code to utilize the results in "output" goes here */
}

Sample 3:
/* Call the MASS vector function 'vlog2'
   Compile command: xlc -qARCH=11 -qFLOAT=IEEE -c sample3.c
 */
#include <massv.h>

int main(void) {
    int size = 1000;
    double input[size];
    double output[size];
    input[0] = 8;
    input[1] = 16;
    ... input[999] = 42;
    vlog2(output, input, &size);
    /* ... Code to utilize the results in "output[]" goes here */
}

Sample 4:
/* Call the MASS SIMD function 'powd2'
   Compile command: xlc -qARCH=11 -qFLOAT=IEEE -qVECTOR -c sample4.c
 */
#include <mass_simd.h>

int main(void) {
    vector double bases = {0, 1};
    vector double exponents = {2, 2};
    vector double output;
    output = powd2(bases, exponents);
    /* ... Code to utilize the results in "output" goes here */
}
Sample 5:
/* Call the MASS scalar functions 'pow' and 'rsqrt', and
the vector function 'vlog10'
Compile command: xlc -qARCH=10 -qFLOAT=IEEE -c sample5.c */

#include <math.h> /* This includes the prototype for 'pow' */
#include <mass.h> /* This includes the prototype for 'rsqrt' */
#include <massv.h> /* This includes the prototype for 'vlog10' */

int main(void) {
    int size = 1000;
    double input[size];
    double result[size];
    int i;

    for (i = 0; i < size; i++) {
        input[i] = i; /* Trivially initialize the input vector */
    }

    vlog10(result, input, &size);
    double output = pow(result[27], result[525]);
    output = rsqrt(output);

    /* ... Code to utilize the results in "output" goes here */
}

Link step - MASS libraries

IBM provides the MASS library in both USS and MVS. There is no performance difference based on where the library resides. This is simply to allow USS users to link with MASS in USS, and MVS users to link with MASS in MVS.

Although USS users can link with the copy of the MASS libraries which resides in PDS's (and vice-versa), IBM does not recommend this because it does not provide a performance gain, and it adds unnecessary complexity to your build process.

Linking in USS

To link your program with the MASS library, include the appropriate library name(s) with the -l linker option, depending on which type of MASS functions are used, as well as which ARCHITECTURE suboption is used, ARCH(10) or ARCH(11).

- -lmass.arch10 or -lmass.arch11 For MASS scalar functions
- -lmassv.arch10 or -lmassv.arch11 For MASS vector functions
- -lmass_simd.arch11 For MASS SIMD functions

Sample 1
# Link the MASS-only scalar function 'rsqrt'.
# Assume 'sample1.o' was compiled with ARCHITECTURE(10).
xlc sample1.o -lmass.arch10

Sample 2
# Link the MASS scalar function 'pow'.
# Assume 'sample2.o' was compiled with ARCHITECTURE(10).
xlc sample2.o -lmass.arch10

Sample 3
# Link the MASS vector function 'vlog2'.
# Assume 'sample3.o' was compiled with ARCHITECTURE(11).
xlc sample3.o -lmassv.arch11

Sample 4
# Link the MASS SIMD function 'powd2'.
# Assume 'sample4.o' was compiled with ARCHITECTURE(11).
xlc sample4.o -lmass_simd.arch11

Sample 5
# Link the MASS scalar functions 'pow' and 'rsqrt', and
# the vector function 'vlog10'.
# Assume 'sample5.o' was compiled with ARCHITECTURE(10).
xlc sample5.o -lmass.arch10 -lmassv.arch10

Linking in MVS

To link your program with the MASS library under MVS in batch mode, you must prepend the MASS library you want to use to your SYSLIB concatenation.

- CBC.SCCNM10 if you are using MASS scalar functions which are also available through <math.h>
- CBC.SCCNN10 for all other MASS functions

Note that this only applies to applications that are compiled with ARCHITECTURE(10) (for IBM zEC12/zBC12 and newer hardware).

The MVS library names for applications that are compiled with ARCHITECTURE(11) (for IBM z13 and newer hardware) are:

- CBC.SCCNM11 if you are using MASS scalar functions which are also available through <math.h>
- CBC.SCCNN11 for all other MASS functions

For example, if your current SYSLIB concatenation is:

```
//SYSLIB    DD DSN=CBC.SCCNN10,DISP=SHR
//           DD DSN=CBC.SCCNOBJ,DISP=SHR
//           DD DSN=CEE.SCEELKED,DISP=SHR
//           DD DSN=CEE.SCEELKEX,DISP=SHR
```

and you want to link each of the sample programs presented above (using NOXPLINK), here are the SYSLIB concatenations you would use:

Sample 1
```
//SYSLIB    DD DSN=CBC.SCCNN10,DISP=SHR
//           DD DSN=CBC.SCCNOBJ,DISP=SHR
//           DD DSN=CEE.SCEELKED,DISP=SHR
//           DD DSN=CEE.SCEELKEX,DISP=SHR
```

Sample 2
```
//SYSLIB    DD DSN=CBC.SCCNN10,DISP=SHR
//           DD DSN=CBC.SCCNOBJ,DISP=SHR
//           DD DSN=CEE.SCEELKED,DISP=SHR
//           DD DSN=CEE.SCEELKEX,DISP=SHR
```

Sample 3
```
//SYSLIB    DD DSN=CBC.SCCNN11,DISP=SHR
//           DD DSN=CBC.SCCNOBJ,DISP=SHR
//           DD DSN=CEE.SCEELKED,DISP=SHR
//           DD DSN=CEE.SCEELKEX,DISP=SHR
```

752  z/OS V2R2 XL C/C++ Programming Guide
Using the Automatically Tuned Linear Algebra Software (ATLAS) libraries

XL C/C++ compiler is shipped with a set of Automatically Tuned Linear Algebra Software (ATLAS) libraries for algebra high-performance computing.

This documentation is intended only as a high level description of ATLAS and the IBM specific extensions and naming convention. For more in depth information about ATLAS, consult the ATLAS documentation at http://math-atlas.sourceforge.net/

Description and functionality provided

The ATLAS libraries contain all the Basic Linear Algebra Subprograms (BLAS) and a subset of the Linear Algebra Package (LAPACK) routines with interfaces provided for both C and Fortran F77 versions of the routines across platforms and architectures. Versions are provided and tuned herein for both the single-threaded and multi-threaded execution on IBM zEC12/zBC12 and IBM z13 hardware models. C and C++ calling programs are supported, with 31-bit C linkage, 31-bit XPLINK linkage, or 64-bit linkage.

Note: ATLAS is only provided as a USS package.

If you want to call ATLAS functionality in your program, take the following steps:

- Provide the prototype for the functions by including the appropriate header file (see “Supplied ATLAS libraries and their corresponding header files” for header file names).
- Link with the appropriate ATLAS libraries (see “Supplied ATLAS libraries and their corresponding header files” for library names).
- Use the appropriate compiler and linker flags (see “Required compiler options” on page 755).

Supplied ATLAS libraries and their corresponding header files

Note: In the subsequent names, replace * with any specific name (specific header file name or library file name).
The following main libraries are provided with ATLAS.

**ATLAS main library**

ATLAS main library contains ATLAS specific variants of the BLAS, CBLAS, and LAPACK routines.

**Table 333. Sample interface routine provided: ATL_dgemm**

<table>
<thead>
<tr>
<th>Operation type</th>
<th>Library name for zEC12/zBC12</th>
<th>Library name for z13</th>
<th>Library location</th>
<th>Header files to be used with the library</th>
<th>Header file location</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single threaded</td>
<td>libatlas.arch10.a</td>
<td>libatlas.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>various atlas_* .h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
<tr>
<td>Multithreaded</td>
<td>libatlas.arch10.a</td>
<td>libatlas.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>various atlas_* .h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
</tbody>
</table>

**CBLAS library**

CBLAS library contains the implementation of the C routines of the BLAS algorithms - also known as the CBLAS interface.

**Table 334. Sample interface routine provided: cblas_dgemm**

<table>
<thead>
<tr>
<th>Operation type</th>
<th>Library name for zEC12/zBC12</th>
<th>Library name for z13</th>
<th>Library location</th>
<th>Header files to be used with the library</th>
<th>Header file location</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single threaded</td>
<td>libcblas.arch10.a</td>
<td>libcblas.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>cblas.h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
<tr>
<td>Multithreaded</td>
<td>libtcblas.arch10.a</td>
<td>libtcblas.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>cblas.h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
</tbody>
</table>

**LAPACK library**

LAPACK library contains the implementation of the C routines of the LAPACK algorithms - also known as the CLAPACK interface.

**Table 335. Sample interface routine provided: clapack_dgesv**

<table>
<thead>
<tr>
<th>Operation type</th>
<th>Library name for zEC12/zBC12</th>
<th>Library name for z13</th>
<th>Library location</th>
<th>Header files to be used with the library</th>
<th>Header file location</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single threaded</td>
<td>liblapack.arch10.a</td>
<td>liblapack.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>clapack.h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
<tr>
<td>Multithreaded</td>
<td>libtlapack.arch10.a</td>
<td>libtlapack.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>clapack.h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
</tbody>
</table>

**Fortran BLAS library**

Fortran BLAS library contains the implementation of the Fortran 77 routines of the BLAS algorithms - also known as the BLAS interface.
Table 336. Sample interface routine provided: dgemm_

<table>
<thead>
<tr>
<th>Operation type</th>
<th>Library name for zEC12/zBC12</th>
<th>Library name for z13</th>
<th>Library location</th>
<th>Header files to be used with the library</th>
<th>Header file location</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single threaded</td>
<td>lib77blas.arch10.a</td>
<td>lib77blas.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>various atlas_<em>f77</em>.h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
<tr>
<td>Multithreaded</td>
<td>libt77blas.arch10.a</td>
<td>libt77blas.arch11.a</td>
<td>/usr/lpp/cbclib/lib/atlas</td>
<td>various atlas_<em>f77</em>.h</td>
<td>/usr/lpp/cbclib/include/atlas</td>
</tr>
</tbody>
</table>

Notes:
1. For each of the above mentioned base libraries, the single-threaded and multi-threaded versions of the same base library contain the same list of functions.
2. Only static libraries are provided.
3. The libraries will archive 31-bit C linkage, 31-bit XPLink C linkage, and 64-bit C linkage objects. The linker, based on supplied options and/or environment variables will choose the appropriate archive members of specified libraries.

Required compiler options
The following C/C++ compiler options are required to compile and link a program that utilizes ATLAS functionality:
- FLOAT(IEEE) - only IEEE floating point format is supported. Hexadecimal floating-point format is not supported.
- ROUND(N) - this is enabled by default when FLOAT(IEEE) is enabled.
- ARCHITECTURE(10) - the minimum required ARCH level. Higher ARCHITECTURE levels in future releases will also support ATLAS functionality.
- ARCHITECTURE(11) - required if you want to enable ATLAS vector functionality in your program.
- VECTOR - required if you want to enable ATLAS vector functionality in your program.
- TARGET(zOSV2R1) - the minimum required TARGET level. Higher TARGET levels in future releases will also support ATLAS functionality.

You might still be able to compile and link your ATLAS application without satisfying the above requirements, but the program will likely not give the correct results.

Examples - Compiling, linking, and running a simple matrix multiplication ATLAS program
This simple sample achieves a multiplication of two matrices, A and B. A and B have elements randomly generated with values between 0 and 1. The multiplication is achieved in the following ways:
- by calling dgemm/cblas_dgemm BLAS functionality provided by ATLAS
- by a manual calculation of the same
The resulting matrices C and D will contain the same elements.

Sample output produced by all executables across all platforms and architectures should look like this:
Matrix A has 3 rows and 6 columns:
0.566 0.974 0.202 0.941 0.294 0.427
0.580 0.539 0.772 0.248 0.832 0.848
0.080 0.533 0.434 0.163 0.576 0.416

Matrix B has 6 rows and 4 columns:
0.309 0.316 0.569 0.182
0.725 0.389 0.472 0.649
0.448 0.368 0.354 0.665
0.994 0.740 0.649 0.616
0.133 0.906 0.447 0.590
0.773 0.774 0.893 0.913

Matrix C has 3 rows and 4 columns:
2.276 1.926 1.978 2.013
1.928 2.270 2.148 2.387
1.165 1.356 1.185 1.469

Matrix D has 3 rows and 4 columns:
2.276 1.926 1.978 2.013
1.928 2.270 2.148 2.387
1.165 1.356 1.185 1.469

Pay attention to the fact that matrices C and D are congruent.

Also note that matrix data is organized or ordered in the Fortran way, namely columns major.

**Sample 1**

This program contains a C invocation of the Fortran BLAS function `dgemm_` provided by the ATLAS framework.

**Observation:** In this sample, the invocation of `dgemm_` has no previously declared prototype, hence the compiler might issue a warning message. Prototypes may be declared by including the `atlas_f77` header files, but source files might not have these header files specified (i.e. old source code written prior to ATLAS).

Source code:
```c
#include <stdio.h>
#include <time.h>
#include <stdlib.h>

void init(double* matrix, int row, int column)
{
    for (int j = 0; j < column; j++){
        for (int i = 0; i < row; i++){
            matrix[j*row + i] = ((double)rand())/RAND_MAX;
        }
    }
}

void print(const char * name, const double* matrix, int row, int column)
{
    printf("Matrix %s has %d rows and %d columns:\n", name, row, column);
    for (int i = 0; i < row; i++){
        for (int j = 0; j < column; j++){
            printf("%.3f ", matrix[j*row + i]);
        }
        printf("\n");
    }
    printf("\n");
}

int main(int argc, char * argv[])
```
{
    int rowsA, colsB, common;
    int i,j,k;

    if (argc != 4){
        printf("Using defaults\n");
        rowsA = 2; colsB = 4; common = 6;
    } else{
        rowsA = atoi(argv[1]); colsB = atoi(argv[2]); common = atoi(argv[3]);
    }

double A[rowsA * common]; double B[common * colsB];
double C[rowsA * colsB]; double D[rowsA * colsB];

    char transA = 'N', transB = 'N';
    double one = 1.0, zero = 0.0;

    srand(time(NULL));

    init(A, rowsA, common); init(B, common, colsB);

dgemm_(&transA, &transB, &rowsA, &colsB, &common, &one, A, 
&rowsA, B, &common, &zero, C, &rowsA);

for(i=0;i<colsB;i++){
    for(j=0;j<rowsA;j++){
        D[i*rowsA+j]=0;
        for(k=0;k<common;k++){
            D[i*rowsA+j]+=A[k*rowsA+j]*B[k+common*i];
        }
    }
}

    print("A", A, rowsA, common); print("B", B, common, colsB);
    print("C", C, rowsA, colsB); print("D", D, rowsA, colsB);

    return 0;
}

To compile the program for ARCH(10):
  xlc -c -qfloat=ieee -qround=n -qarch=10 -qtarget=zosv2r1 -I 
    /usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.c

To compile the program for ARCH(11) and higher ARCHITECTURE levels:
  xlc -c -qfloat=ieee -qround=n -qarch=11 -qtarget=zosv2r1 -I 
    /usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.c

To link the program for ARCH(10):
  xlc sample.o -L /usr/lpp/cbclib/lib/atlas -lf77blas.arch10 
    -latlas.arch10 -lf2c.arch10 -qfloat=ieee -o sample

To link the program for ARCH(11) and higher ARCHITECTURE levels:
  xlc sample.o -L /usr/lpp/cbclib/lib/atlas -lf77blas.arch11 
    -latlas.arch11 -lf2c.arch11 -qfloat=ieee -o sample

Sample 2

This program contains a C++ invocation of the Fortran BLAS function dgemm_ 
provided by the ATLAS framework.
Observation: As opposed to sample 1, the compiler must be explicitly instructed that the function dgemm_ has C linkage and thus no mangling should be attempted. This can be achieved either as specified, or by including the appropriate header file with the extern "C" designation.

Source code:
```c
#include <stdio.h>
#include <time.h>
#include <stdlib.h>
extern "C"
{
    int dgemm_(char *, char *, int *, int *, int *, double *, double *, int *,
               double *, int *, double *, double *, int *);
}

void init(double* matrix, int row, int column)
{
    for (int j = 0; j < column; j++)
        for (int i = 0; i < row; i++)
            matrix[j*row + i] = ((double)rand())/RAND_MAX;
}

void print(const char * name, const double* matrix, int row, int column)
{
    printf("Matrix %s has %d rows and %d columns:\n", name, row, column);
    for (int i = 0; i < row; i++)
        for (int j = 0; j < column; j++)
            printf("%.3f ", matrix[j*row + i]);
    printf("\n");
    printf("\n");
}

int main(int argc, char * argv[])
{
    int rowsA, colsB, common;
    int i,j,k;

    if (argc != 4)
    {
        printf("Using defaults\n");
        rowsA = 2; colsB = 4; common = 6;
    }
    else{
        rowsA = atoi(argv[1]); colsB = atoi(argv[2]);common = atoi(argv[3]);
    }

double A[rowsA * common]; double B[common * colsB];
double C[rowsA * colsB]; double D[rowsA * colsB];

char transA = 'N', transB = 'N';
double one = 1.0, zero = 0.0;

    srand(time(NULL));
init(A, rowsA, common); init(B, common, colsB);
dgemm_(&transA, &transB, &rowsA, &colsB, &common, &one, A,
             &rowsA, B, &common, &zero, C, &rowsA);

    for(i=0;i<colsB;i++)
        for(j=0;j<rowsA;j++)
```


```c
D[i*rowsA+j]=0;
for(k=0;k<common;k++){
    D[i*rowsA+j]+=A[k*rowsA+j]*B[k+common*i];
}
}

print("A", A, rowsA, common); print("B", B, common, colsB);
print("C", C, rowsA, colsB); print("D", D, rowsA, colsB);
return 0;
}
```

To compile the program for ARCH(10):
```
xlC -c -qfloat=ieee -qround=n -qarch=10 -qtarget=zosv2r1 -I/usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.C
```

To compile the program for ARCH(11) and higher ARCHITECTURE levels:
```
xlC -c -qfloat=ieee -qround=n -qarch=11 -qtarget=zosv2r1 -I/usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.C
```

To link the program for ARCH(10):
```
xlC sample.o -L/usr/lpp/cbclib/lib/atlas -lf77blas.arch10 -latlas.arch10 -lf2c.arch10 -qfloat=ieee -o sample
```

To link the program for ARCH(11) and higher ARCHITECTURE levels:
```
xlC sample.o -L/usr/lpp/cbclib/lib/atlas -lf77blas.arch11 -latlas.arch11 -lf2c.arch11 -qfloat=ieee -o sample
```

**Sample 3**

This program contains a C invocation of the CBLAS function `cblas_dgemm_` provided by the ATLAS framework.

**Observation:** Same result and functionality as if `dgemm_` would be called, but this program uses the CBLAS version of the functions.

Source code:
```
#include <time.h>
#include <stdlib.h>
#include <cblas.h>

void init(double* matrix, int row, int column)
{
    for (int j = 0; j < column; j++){
        for (int i = 0; i < row; i++){
            matrix[j*row + i] = ((double)rand())/RAND_MAX;
        }
    }
}

void print(const char * name, const double* matrix, int row, int column)
{
    printf("Matrix %s has %d rows and %d columns:\n", name, row, column);
    for (int i = 0; i < row; i++){
        for (int j = 0; j < column; j++){
            printf("%.3f ", matrix[j*row + i]);
        }
        printf("\n");
    }
    printf("\n");
}
```
int main(int argc, char * argv[])
{
    int rowsA, colsB, common;
    int i,j,k;

    if (argc != 4){
        printf("Using defaults\n");
        rowsA = 2; colsB = 4; common = 6;
    }
    else{
        rowsA = atoi(argv[1]); colsB = atoi(argv[2]); common = atoi(argv[3]);
    }

    double A[rowsA * common]; double B[common * colsB];
    double C[rowsA * colsB]; double D[rowsA * colsB];

    enum CBLAS_ORDER order = CblasColMajor;
    enum CBLAS_TRANSPOSE transA = CblasNoTrans;
    enum CBLAS_TRANSPOSE transB = CblasNoTrans;

    double one = 1.0, zero = 0.0;

    srand(time(NULL));

    init(A, rowsA, common); init(B, common, colsB);
    cblas_dgemm(order,transA,transB, rowsA, colsB, common ,1.0,A,
       rowsA ,B, common ,0.0,C, rowsA);
    for(i=0;i<colsB;i++){
        for(j=0;j<rowsA;j++){
            D[i*rowsA+j]=0;
            for(k=0;k<common;k++){
                D[i*rowsA+j]+=A[k*rowsA+j]*B[k+common*i];
            }
        }
    }

    print("A", A, rowsA, common); print("B", B, common, colsB);
    print("C", C, rowsA, colsB); print("D", D, rowsA, colsB);

    return 0;
}

To compile the program for ARCH(10):

xlc -c -qfloat=ieee -qround=n -qarch=10 -qtarget=zosv2r1 -I/usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.c

To compile the program for ARCH(11) and higher ARCHITECTURE levels:

xlc -c -qfloat=ieee -qround=n -qarch=11 -qtarget=zosv2r1 -I/usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.c

To link the program for ARCH(10):

xlc sample.o -L /usr/lpp/cbclib/lib/atlas -lcblas.arch10
-latlas.arch10 -qfloat=ieee -o sample

To link the program for ARCH(11) and higher ARCHITECTURE levels:

xlc sample.o -L /usr/lpp/cbclib/lib/atlas -lcblas.arch11
-latlas.arch11 -qfloat=ieee -o sample
Sample 4

This program contains a C++ invocation of the CBLAS function cblas_dgemm_ provided by the ATLAS framework.

Observation: Same result and functionality as if dgemm_ would be called, but this program uses the CBLAS version of the functions.

Source code:

```c
#include <time.h>
#include <stdlib.h>
extern "C"
{
#include <cblas.h>
}

void init(double* matrix, int row, int column)
{
    for (int j = 0; j < column; j++){
        for (int i = 0; i < row; i++){
            matrix[j*row + i] = ((double)rand())/RAND_MAX;
        }
    }
}

void print(const char * name, const double* matrix, int row, int column)
{
    printf("Matrix %s has %d rows and %d columns:\n", name, row, column);
    for (int i = 0; i < row; i++){
        for (int j = 0; j < column; j++){
            printf("%.3f ", matrix[j*row + i]);
        }
        printf("\n");
    }
    printf("\n");
}

int main(int argc, char * argv[])
{
    int rowsA, colsB, common;
    int i,j,k;
    if (argc != 4){
        printf("Using defaults\n");
    rowsA = 2; colsB = 4; common = 6;
    } else{
    rowsA = atoi(argv[1]); colsB = atoi(argv[2]);common = atoi(argv[3]);
    }
    double A[rowsA * common]; double B[common * colsB];
    double C[rowsA * colsB]; double D[rowsA * colsB];
    enum CBLAS_ORDER order = CblasColMajor;
    enum CBLAS_TRANSPOSE transA = CblasNoTrans;
    enum CBLAS_TRANSPOSE transB = CblasNoTrans;
    double one = 1.0, zero = 0.0;
    srand(time(NULL));
    init(A, rowsA, common); init(B, common, colsB);
    cblas_dgemm(order,transA,transB, rowsA, colsB, common ,1.0,A,
```
rowsA, B, common, 0, 0, C, rowsA);

for (i = 0; i < colsB; i++) {
    for (j = 0; j < rowsA; j++) {
        D[i * rowsA + j] = 0;
        for (k = 0; k < common; k++) {
            D[i * rowsA + j] += A[k * rowsA + j] * B[k + common * i];
        }
    }
}

print("A", A, rowsA, common); print("B", B, common, colsB);
print("C", C, rowsA, colsB); print("D", D, rowsA, colsB);

return 0;
}

To compile the program for ARCH(10):
xlC -c -qfloat=ieee -qround=n -qarch=10 -qtarget=zosv2r1 -I
/usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.C

To compile the program for ARCH(11) and higher ARCHITECTURE levels:
xlC -c -qfloat=ieee -qround=n -qarch=11 -qtarget=zosv2r1 -I
/usr/lpp/cbclib/include/atlas -qfloat=ieee -o sample.o sample.C

To link the program for ARCH(10):
xIC sample.o -L /usr/lpp/cbclib/lib/atlas -lcblas.arch10 -latlas.arch10 -qfloat=ieee -o sample

To link the program for ARCH(11) and higher ARCHITECTURE levels:
xIC sample.o -L /usr/lpp/cbclib/lib/atlas -lcblas.arch11 -latlas.arch11 -qfloat=ieee -o sample

Examples - Compiling, linking, and running a complex ATLAS sample

This section assumes that a complex test sample, invtst.c, ships with the ATLAS source code. This program is a complex sample that combines ATLAS specific, CBLAS, and LAPACK functionality that has to be compiled using the C compiler.

Example of ATLAS specific functions being called in this sample: ATL_flushcache, ATL_assert, ATL_DivBySize, and ATL_MulBySize.

Example of CBLAS specific functions being called in this sample: cblas_asum, cblas_scasum, cblas_dzasum, cblas_copy, cblas_gemm, cblas_symm, and cblas_hemm.

ATLAS header files being used: atlas_misc.h, atlas_lapack.h, cblas.h, atlas_cblastypealias.h, atlas_tst.h, atlas_level3.h, and clapack.h.

To compile invtst.c for ARCH(10):
xIC -c -qfloat=ieee -qround=n -qarch=10 -qtarget=zosv2r1 -I
/usr/lpp/cbclib/include/atlas -qLANGLEVEL=EXTC99 -DL2SIZE=4194304
-DAdd_ -DF77_INTEGER=int -DStringSunStyle -DATL_NCPU=20 -DATLCINT
-DSREAL -DWALL -DATL_CPUMHZ=5564 -DATL_OS_s390 -o invtst.o invtst.c

To compile invtst.c for ARCH(11) and higher ARCHITECTURE levels:
where:

- L2SIZE represents the size of the L2 cache on the target machine, namely the machine on which the executable will be run.
- Add_, F77_INTEGER, and StringSunStyle are Fortran defines outlining the inter-language interaction between C and Fortran code on z/OS.
- ATL_NCPU represents the number of CPUs on the target hardware where the executable will be run.
- ATLCINT and SREAL are ATLAS specific defines.
- WALL instructs the ATLAS framework to issue all possible warnings.
- ATL_CPUMHZ represents the speed of the target architecture where the executable will be run.
- ATL_OS_s390 instructs ATLAS that a z/OS operating system is used for compile operations.

To link the program for ARCH(10):

```bash
xlc invtst.o -L /usr/lpp/cbclib/lib/atlas -ltstatlas.arch10
-llapack.arch10 -lcblas.arch10 -lf77blas.arch10 -latlas.arch10
-lf2c.arch10 -o invtst
```

To link the program for ARCH(11) and higher ARCHITECTURE levels:

```bash
xlc invtst.o -L /usr/lpp/cbclib/lib/atlas -ltstatlas.arch11
-llapack.arch11 -lcblas.arch11 -lf77blas.arch11 -latlas.arch10
-lf2c.arch11 -o invtst
```

When ran, the executable will produce the following output:

```
NREPS ORDER UPLO N LDA TIME MFLOP RESID
===== ===== ===== === ======== ======== ============
  0  Col  GE 100 100  0.027  73.97  8.918092e-03
  0  Col  GE 200 200  0.005 3024.80  6.950735e-03
  0  Col  GE 300 300  0.015 3535.71  8.034554e-03
  0  Col  GE 400 400  0.034 3783.16  9.250009e-03
  0  Col  GE 500 500  0.063 3937.21  7.678587e-03
  0  Col  GE 600 600  0.107 4046.78  9.520883e-03
  0  Col  GE 700 700  0.167 4097.17  8.519278e-03
  0  Col  GE 800 800  0.247 4148.75  8.575264e-03
  0  Col  GE 900 900  0.346 4217.16  1.272196e-02
  0  Col  GE 1000 1000 0.471 4247.66  8.753754e-03
10 cases: 10 passed, 0 skipped, 0 failed
```

**Related external information**

For details about the ATLAS libraries, such as lists of functions included in the various libraries, visit the Automatically Tuned Linear Algebra Software website at http://math-atlas.sourceforge.net.
Chapter 44. Parallelizing your programs

The z/OS XL C/C++ compiler offers you the following method of implementing shared memory program parallelization:

- Explicit parallelization of C and C++ program code using pragma directives compliant to the OpenMP Application Program Interface specification. An overview of the OpenMP directives is provided in “Using OpenMP directives.”

Program parallelization is enabled when the **SMP** compiler option is in effect. The thread-safe version of system library routines should be used inside the parallel regions.

Parallel regions of program code are executed by multiple threads, possibly running on multiple processors. The number of threads created is determined by environment variables and calls to library functions. Work is distributed among available threads according to scheduling algorithms specified by the environment variables. If you are using OpenMP constructs, you can use the OpenMP environment variables to control thread scheduling.

For information about OpenMP runtime functions, see “OpenMP runtime functions for parallel processing” on page 768.

For detailed description of the OpenMP directives, see Pragma directives for parallel processing in *z/OS XL C/C++ Language Reference*.

For information about OpenMP environment variables, see Environment variables for OpenMP in *z/OS XL C/C++ User’s Guide*.


Using OpenMP directives

OpenMP directives exploit shared memory parallelism by defining various types of parallel regions. Parallel regions can include both iterative and non-iterative segments of program code.

The **#pragma omp** pragmas fall into the following general categories:

1. The **#pragma omp** pragmas for defining parallel regions in which work is done by threads in parallel (**#pragma omp parallel**). Most of the OpenMP directives either statically or dynamically bind to an enclosing parallel region.
2. The **#pragma omp** pragmas for defining how work is distributed or shared across the threads in a parallel region (**#pragma omp sections, #pragma omp for, #pragma omp single, #pragma omp task**).
3. The **#pragma omp** pragmas for controlling synchronization among threads (**#pragma omp atomic, #pragma omp master, #pragma omp barrier, #pragma omp critical, #pragma omp flush, #pragma omp ordered**).
4. The **#pragma omp** pragmas for defining the scope of data visibility across parallel regions within the same thread (**#pragma omp threadprivate**).
5. The `#pragma omp` pragmas for synchronization (`#pragma omp taskwait`, `#pragma omp barrier`)

OpenMP directive syntax

```plaintext
#pragma omp pragma_name [clause] statement_block
```

Including clauses in the `#pragma omp` pragmas can fine tune the behavior of the parallel or work-sharing regions. For example, a `num_threads` clause can be used to control a parallel region pragma.

The `#pragma omp` pragmas generally appear immediately before the section of code to which they apply. The following code defines a parallel region in which iterations of a for loop can run in parallel:

```c
#pragma omp parallel
{
  #pragma omp for
  for (i=0; i<n; i++)
    ...
}
```

The following example defines a parallel region in which two or more non-iterative sections of program code can run in parallel:

```c
#pragma omp parallel
{
  #pragma omp sections
  {
    #pragma omp section
    structured_block_1
    ...
    #pragma omp section
    structured_block_2
    ...
  }
}
```

For detailed description of the OpenMP directives, see Pragma directives for parallel processing in z/OS XL C/C++ Language Reference.

---

Shared and private variables in a parallel environment

Variables can have either shared or private context in a parallel environment. Variables in shared context are visible to all threads running in associated parallel regions. Variables in private context are hidden from other threads. Each thread has its own private copy of the variable, and modifications made by a thread to its copy are not visible to other threads.

The default context of a variable is determined by the following rules:

- Variables with static storage duration are shared.
- Dynamically allocated objects are shared.
- Variables with automatic storage duration that are declared in a parallel region are private.
Variables in heap allocated memory are shared. There can be only one shared heap.

All variables defined outside a parallel construct become shared when the parallel region is encountered.

Loop iteration variables are private within their loops. The value of the iteration variable after the loop is the same as if the loop were run sequentially.

Memory allocated within a parallel loop by the `alloca` function persists only for the duration of one iteration of that loop, and is private for each thread.

The following code segments show examples of these default rules:

```c
int E1; /* shared static */
void main (argvc,...) { /* argvc is shared */
    int i; /* shared automatic */
void *p = malloc(...); /* memory allocated by malloc */
    /* is accessible by all threads */
    /* and cannot be privatized */
#pragma omp parallel firstprivate (p)
{
    int b; /* private automatic */
    static int s; /* shared static */
#pragma omp for
    for (i =0;...) {
        b = 1; /* b is still private here! */
        foo (i); /* i is private here because it */
        /* is an iteration variable */
    }
#pragma omp parallel
{
    b = 1; /* b is shared here because it */
    /* is another parallel region */
}
}
```

```c
int E2; /*shared static */
void foo (int x) { /* x is private for the parallel */
    /* region it was called from */
    int c; /* the same */
    ...
}
```

Some OpenMP clauses enable you to specify visibility context for selected data variables. A brief summary of data scope attribute clauses are listed below:

<table>
<thead>
<tr>
<th>Data scope attribute clause</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>private</td>
<td>The <code>private</code> clause declares the variables in the list to be private to each thread in a team.</td>
</tr>
<tr>
<td>firstprivate</td>
<td>The <code>firstprivate</code> clause provides a superset of the functionality provided by the <code>private</code> clause. The private variable is initialized by the original value of the variable when the parallel construct is encountered.</td>
</tr>
</tbody>
</table>
### Data scope attribute clause

<table>
<thead>
<tr>
<th>Attribute Clause</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>lastprivate</td>
<td>The <code>lastprivate</code> clause provides a superset of the functionality provided by the private clause. The private variable is updated after the end of the parallel construct.</td>
</tr>
<tr>
<td>shared</td>
<td>The <code>shared</code> clause declares the variables in the list to be shared among all the threads in a team. All threads within a team access the same storage area for shared variables.</td>
</tr>
<tr>
<td>reduction</td>
<td>The <code>reduction</code> clause performs a reduction on the scalar variables that appear in the list, with a specified operator.</td>
</tr>
<tr>
<td>default</td>
<td>The <code>default</code> clause allows the user to affect the data-sharing attribute of the variables appeared in the parallel construct.</td>
</tr>
</tbody>
</table>

For more information, you can also refer to the *OpenMP Application Program Interface Language Specification*, which is available at [http://www.openmp.org](http://www.openmp.org).

### OpenMP runtime functions for parallel processing

Function definitions for the `omp_` functions can be found in the `omp.h` header file.

For complete information about OpenMP runtime library functions, refer to the OpenMP Application Program Interface specification at [www.openmp.org](http://www.openmp.org).

**omp_destroy_lock, omp_destroy_nest_lock**

**Purpose**

Ensures that the specified lock variable `lock` is uninitialized.

**Prototype**

```c
void omp_destroy_lock (omp_lock_t *lock);
void omp_destroy_nest_lock (omp_nest_lock_t *lock);
```

**Parameter**

- `lock`
  
  Must be a variable of type `omp_lock_t` that is initialized with `omp_init_lock` or `omp_init_nest_lock`.

**omp_get_active_level**

**Purpose**

Returns the number of nested, active parallel regions enclosing the task that contains the call. The routine always returns a nonnegative integer, and returns 0 if it is called from the sequential part of the program.

**Prototype**

```c
int omp_get_active_level(void);
```
**omp_get_ancestor_thread_num**

**Purpose**

Returns the thread number of the ancestor of the current thread at a given nested level. Returns -1 if the nested level is not within the range of 0 and the current thread's nested level as returned by `omp_get_level`.

**Prototype**

```c
int omp_get_ancestor_thread_num(int level);
```

**Parameter**

- **level**
  
  Specifies a given nested level of the current thread.

**omp_get_dynamic**

**Purpose**

Returns non-zero if dynamic thread adjustment is enabled and returns 0 otherwise.

**Prototype**

```c
int omp_get_dynamic (void);
```

**omp_get_level**

**Purpose**

Returns the number of active and inactive nested parallel regions that the generating task is executing in. This does not include the implicit parallel region. Returns 0 if it is called from the sequential part of the program. Otherwise, returns a nonnegative integer.

**Prototype**

```c
int omp_get_level(void);
```

**omp_get_max_active_levels**

**Purpose**

Returns the value of the `max-active-levels-var` internal control variable that determines the maximum number of nested active parallel regions. `max-active-levels-var` can be set with the `OMP_MAX_ACTIVE_LEVELS` environment variable or the `omp_set_max_active_levels` runtime routine.

**Prototype**

```c
int omp_get_max_active_levels(void);
```

**omp_get_max_threads**

**Purpose**

Returns the first value of `num_list` for the `OMP_NUM_THREADS` environment variable. This value is the maximum number of threads that can be used to form a
new team if a parallel region without a `num_threads` clause is encountered.

**Prototype**

```c
int omp_get_max_threads (void);
```

**omp_get_nested**

**Purpose**

Returns non-zero if nested parallelism is enabled and 0 if it is disabled.

**Prototype**

```c
int omp_get_nested (void);
```

**omp_get_num_procs**

**Purpose**

Returns the maximum number of processors that could be assigned to the program.

**Prototype**

```c
int omp_get_num_procs (void);
```

**omp_get_num_threads**

**Purpose**

Returns the number of threads currently in the team executing the parallel region from which it is called.

**Prototype**

```c
int omp_get_num_threads (void);
```

**omp_get_schedule**

**Purpose**

Returns the `run-sched-var` internal control variable of the team that is processing the parallel region. The argument `kind` returns the type of schedule that will be used. `modifier` represents the chunk size that is set for applicable schedule types. `run-sched-var` can be set with the `OMP_SCHEDULE` environment variable or the `omp_set_schedule` function.

**Prototype**

```c
int omp_get_schedule(omp_sched_t * kind, int * modifier);
```

**Parameters**

- `kind`
  The value returned for `kind` is one of the schedule types affinity, auto, dynamic, guided, runtime, or static.
For the schedule type dynamic, guided, or static, modifier is the chunk size that is set. For the schedule type auto, modifier has no meaning.

**omp_get_team_size**

**Purpose**

Returns the thread team size that the ancestor or the current thread belongs to. `omp_get_team_size` returns -1 if the nested level is not within the range of 0 and the current thread's nested level as returned by `omp_get_level`.

**Prototype**

```c
int omp_get_team_size(int level);
```

**Parameter**

*level*

Specifies a given nested level of the current thread.

**omp_get_thread_limit**

**Purpose**

Returns the maximum number of OpenMP threads available to the program. The value is stored in the `thread-limit-var` internal control variable. `thread-limit-var` can be set with the `OMP_THREAD_LIMIT` environment variable.

**Prototype**

```c
int omp_get_thread_limit(void);
```

**omp_get_thread_num**

**Purpose**

Returns the thread number, within its team, of the thread executing the function.

**Prototype**

```c
int omp_get_thread_num (void);
```

**Return value**

The thread number lies between 0 and `omp_get_num_threads()-1`, inclusive. The master thread of the team is thread 0.

**omp_get_wtick**

**Purpose**

Returns the number of seconds between clock ticks.

**Prototype**

```c
double omp_get_wtick (void);
```
Usage

The value of the fixed starting time is determined at the start of the current program, and remains constant throughout program execution.

**omp_get_wtime**

**Purpose**

Returns the time elapsed from a fixed starting time.

**Prototype**

```c
double omp_get_wtime (void);
```

Usage

The value of the fixed starting time is determined at the start of the current program, and remains constant throughout program execution.

**omp_in_final**

**Purpose**

Returns a nonzero integer value if the function is called in a final task region; otherwise, it returns 0.

**Prototype**

```c
int omp_in_final(void);
```

**omp_in_parallel**

**Purpose**

Returns non-zero if it is called within the dynamic extent of a parallel region executing in parallel; otherwise, returns 0.

**Prototype**

```c
int omp_in_parallel (void);
```

**omp_init_lock, omp_init_nest_lock**

**Purpose**

Initializes the lock associated with the parameter lock for use in subsequent calls.

**Prototype**

```c
void omp_init_lock (omp_lock_t *lock);
void omp_init_nest_lock (omp_nest_lock_t *lock);
```

**Parameter**

`lock`

Must be a variable of type `omp_lock_t`. 
omp_set_dynamic

Purpose

Enables or disables dynamic adjustment of the number of threads available for execution of parallel regions.

Prototype

    void omp_set_dynamic (int dynamic_threads);

Parameter

dynamic_threads
    Indicates whether the number of threads available in subsequent parallel region can be adjusted by the runtime. If dynamic_threads is nonzero, the runtime can adjust the number of threads. If dynamic_threads is zero, the runtime cannot dynamically adjust the number of threads.

omp_set_lock, omp_set_nest_lock

Purpose

Blocks the thread executing the function until the specified lock is available and then sets the lock.

Prototype

    void omp_set_lock (omp_lock_t * lock);
    void omp_set_nest_lock (omp_nest_lock_t * lock);

Parameter

lock
    Must be a variable of type omp_lock_t that is initialized with omp_init_lock or omp_init_nest_lock.

Usage

A simple lock is available if it is unlocked. A nestable lock is available if it is unlocked or if it is already owned by the thread executing the function.

omp_set_max_active_levels

Purpose

Sets the value of the max-active-levels-var internal control variable to the value in the argument. If the number of parallel levels requested exceeds the number of the supported levels of parallelism, the value of max-active-levels-var is set to the number of parallel levels supported by the runtime. If the number of parallel levels requested is not a positive integer, this routine call is ignored.

When nested parallelism is turned off, this routine has no effect and the value of max-active-levels-var remains 1. max-active-levels-var can also be set with the OMP_MAX_ACTIVE_LEVELS environment variable. To retrieve the value for max-active-levels-var, use the omp_get_max_active_levels function.
Use `omp_set_max_active_levels` only in serial regions of a program. This routine has no effect in parallel regions of a program.

**Prototype**

```c
void omp_set_max_active_levels(int max_levels);
```

**Parameter**

`max_levels`

An integer that specifies the maximum number of nested, active parallel regions.

**omp_set_nested**

**Purpose**

Enables or disables nested parallelism.

**Prototype**

```c
void omp_set_nested (int nested);
```

**Usage**

If the argument to `omp_set_nested` evaluates to true, nested parallelism is enabled for the current task; otherwise, nested parallelism is disabled for the current task. The setting of `omp_set_nested` overrides the setting of the `OMP_NESTED` environment variable.

**Note:** If the number of threads from all regions exceeds the number of available processors, your program might suffer performance degradation.

**omp_set_num_threads**

**Purpose**

Overrides the setting of the `OMP_NUM_THREADS` environment variable, and specifies the number of threads to use for a subsequent parallel region by setting the first value of `num_list` for `OMP_NUM_THREADS`.

**Prototype**

```c
void omp_set_num_threads (int num_threads);
```

**Parameters**

`num_threads`

Must be a positive integer.

**Usage**

If the `num_threads` clause is present, then for the parallel region it is applied to, it supersedes the number of threads requested by this function or the `OMP_NUM_THREADS` environment variable. Subsequent parallel regions are not affected by it.
omp_set_schedule

Purpose

Sets the value of the run-sched-var internal control variable. Use omp_set_schedule if you want to set the schedule type separately from the OMP_SCHEDULE environment variable.

Prototype

    void omp_set_schedule (omp_sched_t kind, int modifier);

Parameters

kind
    Must be one of the schedule types affinity, auto, dynamic, guided, runtime, or static.

modifier
    For the schedule type dynamic, guided, or static, modifier is the chunk size that you want to set. Generally it is a positive integer. If the value is less than one, the default will be used. For the schedule type auto, modifier has no meaning.

Related reference:
    "omp_get_schedule" on page 770

omp_test_lock, omp_test_nest_lock

Purpose

Attempts to set a lock but does not block execution of the thread.

Prototype

    int omp_test_lock (omp_lock_t * lock);

    int omp_test_nest_lock (omp_nest_lock_t * lock);

Parameter

lock
    Must be a variable of type omp_lock_t that is initialized with omp_init_lock or omp_init_nest_lock.

omp_unset_lock, omp_unset_nest_lock

Purpose

Releases ownership of a lock.

Prototype

    void omp_unset_lock (omp_lock_t * lock);

    void omp_unset_nest_lock (omp_nest_lock_t * lock);
Parameter

lock

Must be a variable of type omp_lock_t that is initialized with omp_init_lock or omp_init_nest_lock.
Chapter 45. Optimizing the system and Language Environment

This chapter gives some basic tips for tuning Language Environment for optimal C/C++ performance, and some basic system setup tips for efficient program execution.

Improving the performance of the Language Environment

This section discusses how to increase the performance of an application by:

- “Storing libraries and modules in system memory”
- “Optimizing memory and storage”
- “Optimizing runtime options” on page 778

Storing libraries and modules in system memory

One way to boost performance is to load common or reusable modules into memory. For example, placing the Language Environment Library in a link pack area (LPA) can increase the performance of your entire system. This is recommended if your z/OS system contains many applications that use the Language Environment Library, or is a heavy user of z/OS UNIX. LPAs store reentrant routines from system libraries. This saves loading time when a reentrant routine is needed. Individual modules can also be loaded into a single LIBPACK, in order to reduce the time that would otherwise be needed to load the individual load modules. For instructions for placing Language Environment Modules in Link Pack and LIBPACK, see z/OS Language Environment Customization.

If LPAs or LIBPACKS do not have enough space for the Language Environment Library, then you can place it into a library lookaside (LLA). This reduces library I/O activity by keeping selected directory entries in storage.

Similarly, if your application uses C++ class libraries, then application performance may be increased by placing specific libraries in the LPA or the dynamic link pack area (DLPA). For example:

- If the application is a heavy user of the C++ ANSI Standard Libraries, then place the 31-bit CEE.SCEERUN2(C128) or 64-bit CEE.SCEERUN2(C64) Language Environment runtime library in the DLPA.
- If the application is using the non-XPLINK C++ standard library, then place the CEE.SCEERUN(C128N) Language Environment runtime library in an LPA.
- If the application is a heavy user of the USL IOSTREAM libraries, then place the CBC.SCLBDLL Language Environment runtime library in an LPA (for non-XPLINK applications) or the CBC.SCLBDLL2 Language Environment runtime library in a DLPA (for XPLINK applications).

Optimizing memory and storage

Memory allocations can significantly affect the performance of your application. You can optimize your runtime space requirements by using the following Language Environment runtime options:

ANYHEAP       BELOWHEAP       HEAP       HEAPPOOLS
Stack extensions can also cause significant performance hits. For this reason:

- The STACK/STACK64 specified should be large enough to ensure that a stack extension never occurs during the execution of the program.
- The HEAP/HEAP64 should be large enough for an average application execution run, and the increment size should be a reasonable portion of the difference between the typical heap used and the maximum amount of heap that may be used.
- Use the RPTSTG(ON) Language Environment runtime option or the _heaprpt() function to determine the storage usage and the option settings for the given run of your application. The generated report will show if the ANYHEAP, BELOWHEAP, LIBSTACK, and THREADSTACK/THREADSTACK64 are set to the recommended values. The STACK/STACK64 and HEAP/HEAP64 defaults should be as specified above.

The RPTSTG(ON) option should not be used in the final build or run because it is resource-intensive, which adversely affects the performance of the application. The _heaprpt() function, which does not require the RPTSTG(ON) option, obtains a summary heap storage report while your application is running. For more information, see _heaprpt() in z/OS XL C/C++ Runtime Library Reference.

You can also tune I/O storage by using the _EDC_STOR_INITIAL and _EDC_STOR_INCREMENT environment variables. The I/O storage usage is not in the storage report.

For more information about runtime storage, see Stack and heap storage in z/OS Language Environment Programming Guide

### Optimizing runtime options

In addition to the memory options, the ALL31 and HEAPPOOLS runtime options can improve the performance of your application. ALL31 indicates that a Language Environment application has a 31-bit addressing mode. The Language Environment default is ALL31(ON). If your application has some AMODE 24 components, you will need to run the application with ALL31(OFF), but will lose some performance.

The HEAPPOOLS runtime option might increase storage use, but will improve the performance of the application. This option is effective if:

- The application is multi-threaded
- The application often uses:
  - new()
  - delete()
  - new[]()
  - delete[]()
  - malloc()
  - __malloc31()
  - realloc()
  - calloc()
  - free()
Note: If you are not sure which settings of ALL31 and HEAPP00LS are in effect, use the Language Environment runtime option RPTOPTS. RPTOPTS(ON) generates a report of runtime options and their settings that are in use by the currently-running application. Because this option diminishes the performance of the application, it should be used for diagnosis purposes only.

**Tuning the system for efficient execution**

This section is a quick overview of ways to preload modules, DLLs, files, and directories into z/OS. In general, preloading reduces overhead and memory cost. For more detailed information, see the following documents:

- z/OS UNIX System Services Planning
- z/OS MVS Initialization and Tuning Guide

**Link pack areas**

It is recommended that you preload items that are either critical or frequently used into the link pack area (LPA). For batch and z/OS UNIX tasks, use LPA for modules or dynamic LPA for program objects. If LPA is not an option due to system requirements, then consider putting the module into LLA.

IMS and CICS both have similar methods to allow you to preload a frequently used module.

**Library lookasides**

The library lookaside facility (LLA) reduces the amount of I/O activity necessary to locate and fetch modules and program objects from storage. In addition, LLA can work with virtual lookasides to quickly fetch modules from virtual storage instead of from a direct access storage device (DASD).

**Virtual lookasides**

The virtual lookaside facility (VLF) is used to cache various items to reduce I/O, reduce CPU time, and increase response time. For example, you can cache the user IDs (UIDs) and group IDs (GIDs), which will reduce the DASD I/O overhead for Resource Access Control Facility (RACF) calls.
Chapter 46. Balancing compilation time and application performance

Compilation time increases as the level of optimization increases. An end user requires that an application run as fast as possible, and therefore will compile with the maximum optimization possible. Conversely, a developer rebuilds an application many times while debugging a problem, and therefore will compile with the minimum optimization possible. In addition, a developer might need to implement debugging tools, or activate extra debugging code, both of which would affect the performance of the application. This information discusses how to determine the proper balance between compilation time and application performance.

General tips

The following list contains suggestions to support your efforts to debug programs, and reduce compilation time, and improve application performance.

- All builds for testing or production should be compiled with the optimization level at which you intend to ship the final product.
- Even if you compile with opt(0) and debug on a regular basis, you should also do some testing at higher optimization levels to ensure that no aliasing rules or ANSI rules have been broken, which would cause the code to be optimized incorrectly.
- You can ensure the cleanest possible optimized compilations, as well as reduce the number of bugs that occur only at high optimization levels, by reviewing every warning issued by the compiler.

Note: Warnings are often a sign that the compiler is not sure how to interpret the code. If the compiler is not sure how to interpret code at opt(0), the code could cause an error at higher optimization levels or contribute to longer compilation times.

- The simpler the code is, the more easily the compiler can understand it and the faster it will compile. For more information, see Chapter 39, “Improving program performance,” on page 695.
- The CHECKOUT (for C) or INFO (for C++) option can be used to look for certain common problems (such as unprototyped functions and uninitialized variables) that can increase both compilation time and execution time.
- Generate production builds each week throughout the project cycle. This makes it easier to determine when problems entered the code base. Waiting until the end of a cycle to generate a build with high optimization can make it more difficult to find errors caused by coding that does not confirm to ANSI aliasing rules.
- Set up a build so that you can customize options for any source file, if necessary. For example, use a makefile for a UNIX System Services-based build with a default rule for compilation. You can then customize targets for source files that require different options. Similarly, use the OPTFILE compiler option for a JCL-based build. A build script can then use a project-level option file for all source files in a module or DLL. You can specify either of the following:
  - Both a project-level option file and additional specific options for a source file
- A source-specific option file in the option list that follows the options file name

- Set up build scripts so that they can be used for both development and production builds to:
  - Eliminate a common source of errors (because it is necessary to update only one build environment)
  - Make it easier to reproduce and debug problems that occur only in the development build
  - Minimize occurrences of bugs that are reproducible only in the development build

**Programmer tips**

- You can add code to the beginning and end of a header file to ensure that it is not processed unnecessarily during compilation.

  The following example contains code that is included in a header file called myheader.

  ```
  #ifndef __myheader
  #ifdef __COMPILER_VER__
  #pragma filetag ("IBM-1047")
  #endif
  #define __myheader 1
  ...
  /* header file contents */
  #endif
  ```

  You must ensure that the filetag statement, if used, appears before the first statement or directive (except for any conditional compilation directives). The ifndef statement is the first non-comment statement in the header file (the actual token used after the ifndef statement is your choice). The define statement must follow; it cannot appear before the filetag statement, but it must appear before any other preprocessor statement (other than comments).

  Note that the header can contain comment statements in any location. Using this format of header-file blocking will improve compilation time for programs where a header file is included more than once.

- Use the system header files from UNIX file system instead of partitioned data sets to improve compilation time. Specify the following compiler options to do this:

  For **C++**
  ```
  NOSEARCH SEARCH('/usr/include/', '/usr/lpp/cbclib/include/')
  ```

  For **C**
  ```
  NOSEARCH SEARCH('/usr/include/')
  ```

- With the MEMORY compiler option (the default), the compiler uses a hiperspace or memory file in place of a work file (if possible). This option increases compilation speed, but you might require additional memory to use it. If the compilation fails because of a storage error, either increase your storage size or recompile your program using the NOMEMORY option.

- If your file has many recursive template definitions and you want to use the TEMPINC option, the FASTTEMPINC compiler option might reduce the compilation time.
Note: This option defers generating object code until the final versions of all template definitions have been determined. Then, a single compilation pass generates the final object code. Time is not wasted generating object code that will be discarded and generated again.

If your application has very few recursive template definitions, NOFASTTEMPINC might be faster than FASTTEMPINC.

- If you want to achieve a good balance of compilation time and small modules that execute quickly, consider using the TEMPLATEREGISTRY option instead of TEMPINC or NOTEMPINC.
- If a source file does not have try/catch blocks or does not throw objects, then the NOEXH C++ compiler option may improve the compilation time. The resultant code will not be ANSI-compliant if the program uses exception handling.
- If you want to improve your OPT compilation time at the expense of runtime performance, you can specify:

  MAXMEM
  Limits the amount of memory used for local tables of specific memory intensive optimizations. If this amount of memory is insufficient for a particular optimization, the compiler performs somewhat poorer optimization and issues a warning message. Reducing the MAXMEM value from 2G to 10M may disable some optimizations, which may cause some decrease in execution performance.

  NOINLINE
  Disables inlining, which might decrease the compilation time. There might also be a corresponding increase in execution time.

System programmer tips

- If you do a lot of application development on your machine, put the compiler and runtime library in the LPA. Similarly, if you are working in z/OS UNIX System Services also put the c89/cc/cc utilities in the dynamic LPA, LPA or linklist.
- Use packs that are cached with DASD fast write.
  If you are working in z/OS UNIX System Services, give each user a separate mountable file system to avoid I/O contention.
  If the compiler is not in LPA, tune your jobs to avoid channel and pack contention when the headers and the compiler are on the same pack and multiple compile jobs are executing.
- If you use the makedepend utility to generate dependency information, use the LIST option to generate a listing from makedepend. The summary section of this listing shows a list of the most frequently called headers and the frequency of these calls. Use this information to determine which headers should be cached.
- You can define /tmp as a RAM disk by specifying:
  FILESSTYPE TYPE(TFS) ENTRYPOINT(BPXTFS)
  This is described in more detail in z/OS UNIX System Services Planning.
Chapter 47. Stepping through optimized code using the dbx debugger utility

Starting from z/OS V2R1, debug information can be generated for optimized code. The debugger can do normal debugging with code that is compiled with the OPTIMIZE(2) and DEBUG(LEVEL(8)) compiler options.

However, the debug information generated for code compiled with OPTIMIZE(3) and higher levels is limited. You can use the dbx debugger utility to help you determine problems. One method is to set the stop location at the point where your program detects an error situation, or detects a severe condition, which the code cannot handle. This method has the following limitations:

- The point at which you want to allow dbx to take control must be determined prior to compile time.
- You can use the dbx stepi subcommand to step through the code at the instruction level only.
- No source or symbolic debug information is available, which means that the debugger cannot execute any instructions that require debug information, such as relating the execution to the source file or examining the values of variables.

For more information on dbx, and the dbx stop and stepi subcommands, refer to z/OS UNIX System Services Command Reference. For information on the OPTIMIZE, NOOPTIMIZE, and DEBUG compiler options, see z/OS XL C/C++ User’s Guide.

Steps for setting up a stopping point for dbx in optimized code

Perform the following steps to set up a stopping point for dbx in optimized code:

1. Create a source file named a.c, with a function func() defined in it.
2. At any point in the application (in any file, in any function compiled with OPTIMIZE), insert func(); where you want to allow the debugger to take control.
3. Compile main.c with the OPTIMIZE compiler option.
4. Compile a.c with the DEBUG and NOOPTIMIZE compiler options.
5. Relink the application, together with the newly created a.o object file.

Steps for setting up a stopping point for dbx in optimized code

Perform the following steps to use dbx to step through optimized code:
1. Load the a.out file into the dbx utility (a.out is the default name of an executable file produced by the compiler.)
2. Use the dbx stop subcommand to stop in func().
3. Use the dbx run or continue subcommand to resume dbx so that it can hit the entry breakpoint for func().
4. Use the dbx stepi subcommand to return to the point in the original source where the call to func() was inserted.

For more information on dbx, and the dbx stop and stepi subcommands, see z/OS UNIX System Services Command Reference. For information on the OPTIMIZE, NOOPTIMIZE, and DEBUG compiler options, see z/OS XL C/C++ User’s Guide.
Part 6. z/OS XL C/C++ Environments

This part describes the different z/OS XL C/C++ environments. Note that the MultiTasking Facility and the System Programming C Facilities are not available for z/OS XL C++. If you attempt to run an SPC application under z/OS XL C++, it will abend.

- Chapter 48, “Using the system programming C facilities,” on page 789
- Chapter 49, “Library functions for system programming C,” on page 831
- Chapter 50, “Using runtime user exits,” on page 837
- Chapter 51, “Using the z/OS XL C MultiTasking Facility,” on page 855
Chapter 48. Using the system programming C facilities

This chapter explains how to use the system programming C (SPC) facilities with z/OS XL C.

Notes:
1. Using the system programming C facilities, by programs which have been compiled with z/OS XL C++ is not supported.
2. IPA is not supported in an SPC environment unless there is a main() function present.
3. XPLINK is not supported by the SPC facilities.
4. AMODE 64 applications are not supported by the SPC facilities.

When z/OS XL C applications are compiled, many routines are needed to support the z/OS XL C environment that are not included in your executable. These routines, which are in z/OS Language Environment, are dynamically loaded at run time. This reduces the size of the program to its practical minimum and provides for the sharing of z/OS XL C library code by allowing its placement in Extended Link Pack Areas.

z/OS Language Environment provides facilities to set up the environment, handle termination, provide storage management, error handling, interlanguage calls and debugging support. Also, the C library functions are provided with z/OS Language Environment. In situations where not all of these services are needed or available, or more control over the executive environment is required, the system programming C facilities can provide a reduced customizable environment for your application.

System programming facilities enable you to run applications without z/OS Language Environment or with just the z/OS XL C library functions available. You can:

• Use a subset of the C language to develop specialized applications that do not require z/OS Language Environment on the machines where the application will run.

You can write freestanding applications that:
– Do not use the dynamic runtime library.
– Use only the C-specific library functions without any z/OS Language Environment facilities to manage the execution environment.

For example, a system programming application could use the C-specific library function printf() but not have the common run time initialize the environment. The system programming facilities would handle initialization. For more information on this type of application, see “Creating freestanding applications” on page 792.

• Use z/OS XL C as an assembler language alternative, such as for writing exit routines for MVS, TSO, or JES.

For more information on this type of application, see “Creating system exit routines” on page 798.

• Develop applications featuring a persistent C environment, where a z/OS XL C environment is created once and used repeatedly for C function execution.
For more information on this type of application, see “Creating and using persistent C environments” on page 802.

- Develop co-routines using a two-stack model, as used in client-server style applications. In this style, the user application calls upon the applications server to perform services independently of the user and then returns to the user.
  
  For more information on this type of application, see “Developing services in the service routine environment” on page 807.

Note: Using the decimal data type and its related functions (decabs(), decchk(), and decfix()) without z/OS Language Environment is not supported.

### Using functions in the system programming C environment

If you do not want to use the z/OS Language Environment runtime library and the z/OS XL C runtime component within z/OS Language Environment the following functions are available in the SPC environment:

- The following library functions are available as built-in so that they can be used without the runtime library:

<table>
<thead>
<tr>
<th>Function Type</th>
<th>Function Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mathematical</td>
<td>abs(), fabs()</td>
</tr>
<tr>
<td>Memory manipulation</td>
<td>memchr(), memcmp(), memcpy(), memset(), cds(), cs()</td>
</tr>
<tr>
<td>String operations</td>
<td>strcat(), strchr(), strcmp(), strcpy(), strlen(), strrchr()</td>
</tr>
<tr>
<td>Wide character memory</td>
<td>wmemchr(), wmemcmp(), wmemcpy(), wmemset()</td>
</tr>
</tbody>
</table>

The built-in versions of these functions are available only if the appropriate header file (string.h, wchar.h, math.h, or stdlib.h) is included in the source file. The use of these functions is described in z/OS XL C/C++ Runtime Library Reference.

- The memory management functions, including complete support for:
  - The malloc() function
  - The calloc() function
  - The realloc() function
  - The free() function
  - The HEAP runtime option
- The exit() function
- The sprintf() function.

Note: The use of floating point conversion specifiers (e,E,f,g or G) is not supported without the Language Environment runtime.

Additional memory management functions are available in the system programming C environment, as follows:

- _4kmalloc() to allocate page-aligned storage
- _24kmalloc() to allocate storage below the 16MB line in ESA systems (where MB is 1048576 bytes) even when HEAP(ANYWHERE) is specified.
Storage allocated by these functions is not part of the heap, so freeing it is your responsibility. You can use the `free()` function to free the storage before the environment is terminated. Storage allocated using these functions is not automatically freed when the environment is terminated.

In this environment, low-level memory management functions and contents supervision (loading and deleting executable code) are supported by low-level routines that you can replace to support non-standard environments. This is described in "Tailoring the system programming C environment" on page 823.

---

### System programming C facility considerations and restrictions

When using any system programming C environment, consider the following:

- The long long data type is not supported for the function `sprintf()` under SPC. If you need to use the long long data type, you must use the C/C++ Runtime library version of the `sprintf()` function.
- The `fetch()` function is not supported when you are running in a system programming C environment. You can use the `E0CXL0A0` routine, as described in "Loading a module" on page 826, to simulate some of the functionality of the `fetch()` function.
- The IMS parameter list established by the `#pragma runopts(PLIST(IMS))` directive is not supported in any of the system programming environments. However, this does not preclude the use of IMS within these environments, because the registers upon entry are available using the `_xregs()` function and `ctdl()` is bound statically. For more information on `_xregs()`, refer to "_xregs() — Get Registers on Entry" on page 833.
- Interlanguage calls to COBOL and PL/I are not supported. However, an SPC program can use the `system()` function to call modules written in other languages.
- SPC is not supported under CICS or MTF.
- Library functions for use with UNIX file system I/O are not supported under SPC. Calling them causes unpredictable results.
- All runtime options are ignored except for:
  - `STACK`
  - `HEAP`
  - `TRAP`
- Redirection of standard streams is not supported.
- The default initial stack size is the minimum size required to start the C program. (This default is different from the non-systems programming C environments.) If a size is specified, that actual value is used, provided it is large enough. If the value specified is smaller than the requirements for the program, the required value is used.
- The default value for the `HEAP` runtime option is `HEAP(12K,4K,ANY,FREE)`.
- When you are running a service routine, you should with `#pragma runopts(TRAP(OFF))`.
- Exception handling is not supported in a persistent environment.
- Invoking the `system()` function from an `atexit()` function results in undefined behavior.
- When using the `atexit()` function from a persistent environment, the `atexit` list will not be run until the persistent environment has been terminated by the `_xhott()` library function. For more information about this function, see "_xhott() — Terminate a Persistent C Environment" on page 832.
Calls to math library functions can be made in a system programming C environment using the dynamic library. For the most efficient use of calls to math library functions, you should enclose the function name in parentheses (). For example, if you make a call to \( \sin() \), use:

\[
z = (\sin)(x);
\]

You cannot call \( \text{ctrace}() \), \( \text{csnap}() \), \( \text{cdump}() \), or \( \text{ctest}() \) because they rely on z/OS Language Environment callable services.

System programming C environments are disjointed from each other; that is, memory files cannot be passed and file control is not maintained across environments. Thus, memory files cannot be passed between a C program and a callee that is written as an assembler exit.

An exception is between environments where the target environment is built with \( \text{EDCXSTR} \text{L} \) or \( \text{EDCXSTRX} \) but does not represent a server. For example, if a C program invokes a freestanding SPC application that is not a server by using \( \text{system}() \), a memory file can be passed successfully between the programs.

When developing an application with an interface with assembler, you can use the DSECT Conversion Utility to build structures mapping to the data types of your DSECTs.

The POSIX locale features and coded character set conversion routines are supported only for system programming applications that use z/OS Language Environment. They are not available for freestanding applications.

IEEE decimal floating-point data types are not supported for the function \( \text{sprintf}() \) under SPC. If you need to use IEEE decimal floating-point data types, you must use the C/C++ Run Time Library version of the \( \text{sprintf}() \) function.

### Creating freestanding applications

Freestanding applications are C modules that run either:

- Without z/OS Language Environment and the z/OS XL C library (using \( \text{EDCXSTRT} \))
- Without z/OS Language Environment but with the z/OS XL C library functions (using \( \text{EDCXSTRL} \))

Three initialization routines are provided by SPC for building freestanding applications:

**EDCXSTRT**

For building completely freestanding applications. The applications can use no z/OS XL C runtime library functions and can have no z/OS Language Environment attachment.

**EDCXSTRL**

For building applications that use z/OS XL C runtime library functions but have no z/OS Language Environment attachment.

**EDCXSTRX**

This routine accepts a parameter to choose whether your application should behave as if it was initialized with either \( \text{EDCXSTRT} \) or \( \text{EDCXSTRL} \). This parameter is described further in "Setting up a C environment with preallocated stack and heap" on page 794.

Certain restrictions apply to freestanding applications initialized by the routines \( \text{EDCXSTRT} \), \( \text{EDCXSTRL} \), and \( \text{EDCXSTRX} \). These restrictions are as follows:
They cannot perform interlanguage calls, except with assembler language routines that preserve register 12 and use the IBM-supplied macros for entry and exit.

The parameters received by the main() function (normally argc and argv) are undefined. __xregs() (described in "__xregs() — Get Registers on Entry" on page 833) can be used to examine the parameters passed by the calling environment.

They cannot do arithmetic using long double variables on pre-XA machines (that is, on machines that do not support the DXR instruction).

Creating modules without CEESTART

In many environments, the initialization normally performed by z/OS Language Environment is replaced by special-purpose routines that are tailored to the specific requirements of the type of application. This requires replacing the initialization routine (CEESTART) normally used by z/OS XL C.

When you do not use the System Programming C Facilities, the compiler generates a CEESTART CSECT (control section) whenever a main() or fetchable function is encountered in the source file. With the NOSTART compiler option, described in the z/OS XL C/C++ User’s Guide, you can suppress the generation of CEESTART for source files that contain a main() function where this is required. In a system programming C environment, you must compile using the NOSTART option. The object modules created will then be suitable for inclusion in applications that use the alternative initialization routines described in this section.

Including an alternative initialization routine under z/OS

When NOSTART is used to suppress the generation of CEESTART, an alternative initialization routine must be explicitly included in the executable by the user at Link Edit. Use the Linkage Editor INCLUDE and ENTRY control statements. To include the alternative initialization routines described in this chapter, allocate CEE.SCEESPC to the SYSLIB DD. For example, you can use the linkage editor statements in Figure 173 to specify EDCXSTRT as an alternative initialization routine:

```sh
//SYSLIN DD *
  INCLUDE SYSLIB(EDCXSTRT)
  ENTRY EDCXSTRT
  INCLUDE OBJECT(main-function)
/*
Figure 173. Specifying alternative initialization at link edit

Another example of specifying alternative initialization under z/OS is shown in Figure 175 on page 796.

Initializing a freestanding application without Language Environment.

The EDCXSTRT routine is for C applications that do not use any z/OS Language Environment facilities or z/OS XL C facilities or library functions. It must be explicitly included in the program and specified as the program entry point if it is to be used. Under this environment, only the following library routines are supported:

- Built-in compiler functions. For a list of these functions, see "Using functions in the system programming C environment" on page 790.
• Memory management routines, including malloc(), calloc(), realloc(), and free().
• The exit() and sprintf() functions.

Note: The use of floating point conversion specifiers (e, E, f, g or G) is not supported without the Language Environment runtime. Since the use of EDCXSTART allows the application to execute without the use of the Language Environment runtime, the use of the above conversion specifiers with sprintf() in this environment is not supported.
• The __4kmalc() and __24malc() functions.

The value returned to the host system will be the return value from main().

The RENT compiler option is supported in this environment.

Initializing a freestanding application using C functions

The EDCXSTRL routine is the analog of CEESTART for C applications that use the z/OS XL C library functions only. EDCXSTRL supports the full library of C functions except for functions such as cdump(), csnap(), ctest(), or ctrace(). EDCXSTRL must be explicitly included in the program and specified as the program entry point if it is to be used.

The value returned to the host system will be the return value from main().

The RENT compiler option is supported in this environment.

Service routines (described in “Developing services in the service routine environment” on page 807) require this routine (or EDCXSTRT if they do not require z/OS Language Environment) for their initialization.

Applications initialized with this routine will run in any environment supported by z/OS Language Environment.

Setting up a C environment with preallocated stack and heap

The EDCXSTRX routine is the analog of CEESTART for an application where you want to have more control over contents supervision and storage management. Unlike EDCXSTRT, EDCXSTRL, and CEESTART, this routine cannot be entered directly from the operating system (that is, from JCL, REXX EXECs, CLISTs, or the TSO command line). It requires a structured parameter list (05 linkage) containing:

1. The parameter list to be passed to main().
   _xregs() can be used to examine the parameters passed by the calling environment. This list cannot be accessed by argc or argv.
2. The address of the initial storage area.
   This area must be doubleword aligned with its first word containing its total length. It must be large enough to accommodate the entire stack requirements of the application.
3. The address of the complete heap allocation (or NULL if no malloc() family storage is required by the called routines).
   This area must be doubleword aligned with its first word containing its total length. This area must include sufficient space for the control structures required to manage the heap (currently a minimum of 40 bytes). Applications that use the z/OS XL C library functions will always require heap space; the
amount required depends on the structure of the application and may vary from run to run if external characteristics (file block sizes, for example) change. Any heap increments that occur because the size of the initial heap is not large enough will not be freed at termination by the system programming environment. If no initial heap allocation is specified, and a heap is required (because the z/OS XL C library functions are required, for example), it will not be freed by the System Programming C Environment. If this behavior is detected, the program will run to completion, but will abend during EDCXSTRX termination with abend code 2108 and reason code 7207.

Heap increments will be freed if you explicitly free the memory (using the free() function) and the runtime option HEAP(FREE) has been specified. You should specify a heap value of at least 4K if you are running with the z/OS XL C library functions.

4. The address of the z/OS XL C runtime library or NULL. Use CEEV083 (or EDCZV, if you want to maintain compatibility with previous releases of OS/390 Language Environment).

The parameters (argc and argv) passed to the main() function are undefined. There is no argument parsing (argc and argv) or redirection of standard streams.

If the z/OS XL C library functions are required, the routine EDCXABRT must be explicitly included during the link edit. This routine enables exception handling for EDCXSTRX. If it is not explicitly included, abend code 2107 with reason code 7206 will terminate the program.

The RENT compiler option is supported in this environment only if the z/OS XL C library functions are used.

**Determining ISA requirements**

The EDCXISA entry point is available to the caller of EDCXSTRX to determine the stack space overhead for the environment being created. Add stack space required by the application to the value returned by this routine to determine the size of the area to be passed as the second parameter to EDCXSTRX. If the routine is called from assembler, the value should be expected in Register 15. The routine should be declared as:

```c
#pragma linkage(__xisa,OS)
int __xisa(void);
```

**Building freestanding applications to run under z/OS**

When you are building freestanding applications under z/OS, CEE.SCEESPC must be included in the binder SYSLIB concatenation before CEE.SCEELED. The routines to support this function (EDCXSTRT, EDCXSTRL, and EDCXSTRX) are CEESTART replacements (described in "Creating modules without CEESTART" on page 793) in your module. Therefore, the appropriate EDCXSTRTn routine must be explicitly included ahead of the module at link edit. Figure 174 on page 796 shows a simple freestanding routine that requires the library.
This routine is compiled normally and link edited using control statements shown in Figure 175. The CEE.SCEERUN load library must be available at run time because it contains the C library function puts().

Special considerations for reentrant modules

A simple freestanding routine that does not require the library is shown in Figure 177 on page 797. To develop a reentrant module, this routine must be compiled with both the RENT (because the module contains writable static at ) and NOSTART (because this is a system programming environment) compiler options. This routine uses the exit() function, which is normally part of the z/OS Language Environment library. Like sprintf(), it is available to freestanding routines without requiring the dynamic library.
/* this is an example of a reentrant freestanding routine */
#include <stdlib.h>
int main() {
    static int i[5]={0,1,2,3,4};  // 1
    exit(320+i[1]);  // 2
}

Figure 177. Sample reentrant freestanding z/OS routine

/* this is an example of a reentrant freestanding routine */
#include <stdlib.h>
int main() {
    static int i[5]={0,1,2,3,4};  // 1
    exit(320+i[1]);  // 2
}

Figure 178. Building and running a reentrant freestanding z/OS routine

The z/OS Language Environment prelinker must be used for modules compiled with the RENT compiler option.

This is the object module created by compiling the sample module with the RENT and NOSTART compiler options.

The output from the prelinker is made available to the linkage editor.

The alternative initialization routine (EDCXSTRT in this example) must be included explicitly in the module. If this is not the first CSECT in the module, it must be explicitly named as the module entry point.

The prelinked output is included in the load module.

EDCXEXIT must be explicitly included if the exit() function is used in the application.

The routine EDCRCINT must be explicitly included in the module if the RENT compiler option is used. No error will be detected at load time if this
routine is not explicitly included. At execution time, abend 2106, reason code 7205, will result if EDCRCINT is required but not included.

**Parts used for freestanding applications**

Table 337 lists the parts used for freestanding applications and their function and location. The SYSLIB specified is CEE.SCEESPC.

<table>
<thead>
<tr>
<th>Part Name</th>
<th>Function</th>
<th>Inclusion in Program</th>
<th>Location</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>EDCXSTRT</td>
<td>Mainline for applications that do not require the z/OS Language Environment or z/OS XL C runtime library.</td>
<td>1</td>
<td>Member of SCEESPC</td>
<td>CSECT must be the module entry point.</td>
</tr>
<tr>
<td>EDCXSTRL</td>
<td>Mainline for applications that require only the C-specific library functions.</td>
<td>1</td>
<td>Member of SCEESPC</td>
<td>CSECT must be the module entry point.</td>
</tr>
<tr>
<td>EDCXSTRX</td>
<td>Mainline for applications that receive a structured parameter list that includes preallocated storage management areas.</td>
<td>2</td>
<td>Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXISA</td>
<td>Get ISA requirements for EDCXSTRX.</td>
<td>2</td>
<td>Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXSPRT</td>
<td>System programming version of printf().</td>
<td>3</td>
<td>Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXEXIT</td>
<td>System programming version of exit().</td>
<td>3</td>
<td>Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXMEM</td>
<td>System programming version of malloc(), calloc(), realloc(), free(), __4kmalc() and __24malc().</td>
<td>3</td>
<td>Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCRCINT</td>
<td>Must be included if the compiler option RENT is to be used.</td>
<td>3</td>
<td>Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXABRT</td>
<td>System programming version of exception handling.</td>
<td>3</td>
<td>Member of SCEESPC</td>
<td></td>
</tr>
</tbody>
</table>

**Notes:**
1. This module must be explicitly included in the program using the binder INCLUDE control statement.
2. This module will normally be included by automatic call.
3. This module must be explicitly included if you want to use the system programming version of the function.
4. Including EDCXABRT requires the system programmer C environment to be library enabled.

**Creating system exit routines**

*z/OS XL C** allows the creation of routines that have no environmental requirements on entry except:

- Register 13 must point to a 72-byte save area
- Register 14 must contain the return address
- Register 15 must contain the entry address

There is no requirement on the name of the entry point (that is, it does not have to be main()), so several different entry points, with names specified by the calling environment, can be combined in the same program.

Routines that do not require the *z/OS XL C* environment should specify one of these two pragma forms:
• `#pragma environment(function-name), if the library is required, or
• `#pragma environment(function-name,nolib), if no library is required.

This pragma causes the compiler to generate a different prolog for the specified function. The prolog contains the instructions at the beginning of the routine that perform the housekeeping necessary for the function to run, including allocation of the function’s automatic storage. This prolog will set up a C environment sufficient for both the function in which it is specified and any function that may be called. Called functions should not specify this pragma, unless they are called elsewhere without a C environment present. This new prolog will load and initialize the module containing the C library functions if this choice is specified. For more information on the `#pragma environment, see z/OS XL C/C++ Runtime Library Reference.

The RENT compiler option is not supported in this environment; if you require reentrant system exit routines, the routine must be naturally reentrant. See z/OS Language Environment Programming Guide for more information about reentrancy.

System exit routines can be linked with their callers or dynamically loaded and invoked.

**Building system exit routines under z/OS**

The CEE.SCEESPC object library must be available at link-edit time. If the C library is required by the exit routines, CEE.SCEELKED must also be made available after CEE.SCEESPC. You should explicitly name the entry point with an ENTRY statement.

**An example of a system exit**

Table 338 on page 802 lists the parts used by exits. The C program (CCNGSP3) shown in Figure 179 on page 800 is a system exit that gains control from the system when an unknown CLIST subroutine is encountered. It checks if the name is recognized as a user-specific subroutine before returning control to the system. For more information on this system exit, see z/OS TSO/E Customization.
/* this is an example of a system exit */
#pragma environment(IKJCT44B,nolib)
/* */
/* IKJCT44B CLIST EXIT */
/* */
#include <stdio.h>
#include <stdlib.h>
#include <spc.h>
struct parmentry { int key;
    int len;
    char *pt; 
};
typedef struct parmentry P_ENT;
#define REVERSE 0
#define FLIPCHR 1
/* Valid commands */
static char *cmds[] = {
    "SYSXTREV", "SYSXTFLIP" 
};
void revstring( P_ENT *p11, P_ENT *p12 );
void flipstring( P_ENT *p11, P_ENT *p12 );
int IKJCT44B() {
    int **parme;
    struct parmentry *e7, *e10, *e11, *e12, *e13;
    /* Get registers on entry */
    parme = (void *)__xregs(1);
    /* Get the parameter entry values for those relevant for CLISTs */
    e7 = (struct parmentry *)parme[6]; /* exit return */
    e10 = (struct parmentry *)parme[9];  
    e11 = (struct parmentry *)parme[10];
    e12 = (struct parmentry *)parme[11];
    e13 = (struct parmentry *)parme[12];
    /* Is the command supported? */
    switch( cmdchk(e10) ) {
        case REVERSE: /* Reverse string */
            revstring( e11, e12 );
            break;
        case FLIPCHR: /* Exchange the first and last chars only */
            flipstring( e11, e12 );
            break;
        default: /* Unknown command type. Return with an error. */
            e12->pt[0] = 0x00;
            e12->len = 0;
            /* Set the return code */
            e7->key = 0x01;
            e7->len = 0x04;
            *(int *)&e7->pt = 0x06;
            return 12;
    }
}

System exit example (Part 1 of 2)

Figure 179. System exit example
/* Return to caller - CLIST is supported. */
e7->key = 0x01;
e7->len = 0x04;
*(int *)&e7->pt = 0x00;
return 0;
}

/* cmdchk( P_ENT *pt ) */
/* - is the command in the list of user-specific cmds? */
int cmdchk( P_ENT *pt ) {
    int i;
    for( i=0; i<sizeof(cmds)/sizeof(char *); i++ ) {
        if( memcmp( pt->pt, cmds[i], pt->len ) == 0 )
            return i;
    }
    /* Not found */
    return -1;
}

/* revstring().... */
/* - reverse the string */
void revstring( P_ENT *p11, P_ENT *p12 ) {
    int i;

    for( i=0; i<p11->len; i++ )
        p12->pt[i] = p11->pt[p11->len-i-1];
p12->len = p11->len;
}

/* flipstring() ... */
/* - flip the first and last characters in the string */
void flipstring( P_ENT *p11, P_ENT *p12 ) {
    char t;
    t = p11->pt[p11->len-1];
    memcpy( p12->pt, p11->pt, p11->len );
p12->pt[p11->len-1] = p11->pt[0];
p12->pt[0] = t;
p12->len = p11->len;
}

System exit example (Part 2 of 2)

1. The #pragma environment directive sets up an entry point IKJCT44B other than main().
2. This is the list of user-specific subroutines that are available in this system exit.
3. The function ___xregs() is used to retrieve the parameters available to the system exit in R1 from the operating system.
4. The parameters are parameter entries passed from TSO to this system exit and are used for the following reasons:
   e7 Exit reason code
   e10 Name of subroutine
   e11 Arguments
   e12 Result
5. The list of user-specific subroutines is checked and if the unknown CLIST subroutine is recognized, the subroutine is called. Otherwise, the function returns in error.

Table 338 on page 802 lists the parts used by the routines, and their function and location in MVS. The SYSLIB specified is CEE.SCEESPC.
### Table 338. Parts used by exit routines

<table>
<thead>
<tr>
<th>Part Name</th>
<th>Function</th>
<th>Inclusion in Program</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>EDCXENV</td>
<td>Extended prolog code for exits that do not require the library.</td>
<td>2 Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXENVL</td>
<td>Extended prolog code for exits that require the library.</td>
<td>2 Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXSPRT</td>
<td>System programming version of <code>sprintf()</code>.</td>
<td>3 Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXEXIT</td>
<td>System programming version of <code>exit()</code>.</td>
<td>3 Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXMEM</td>
<td>System programming version of <code>malloc()</code>, <code>calloc()</code>, <code>realloc()</code>, <code>free()</code>, <code>_4kmalloc()</code> and <code>_24malce()</code>.</td>
<td>3 Member of SCEESPC</td>
<td></td>
</tr>
<tr>
<td>EDCXABRT</td>
<td>System programming version of exception handling.</td>
<td>3 Member of SCEESPC</td>
<td></td>
</tr>
</tbody>
</table>

**Notes:**
1. This module must be explicitly included in the program using the binder INCLUDE control statement.
2. This module will normally be included by automatic call.
3. This module must be explicitly included if you want to use the system programming version of the function.

### Creating and using persistent C environments

Four routines are available to create and use a persistent C environment. These routines are used by an assembler language application that needs a C environment available to support the C functions that it calls. C main routines cannot be called in persistent C environments. The four routines are:

- **EDCXHOTC**
  - Sets up a persistent C environment (no library)

- **EDCXHOTL**
  - Sets up a persistent C environment (with library)

- **EDCXHOTU**
  - Runs a function in a persistent C environment

- **EDCXHOTT**
  - Terminates a persistent C environment

An initialization routine, EDCXHOTC or EDCXHOTL (depending upon whether the called C subroutines will need the z/OS XL C library functions), is called to create a C environment. This call returns a handle that can be used (through EDCXHOTU) to call C subroutines. The environment persists until it is explicitly terminated by calling EDCXHOTT.
The functions that act as entry points for these routines are __xhotc(), __xhotl(), __xhotu(), and __xhott(), respectively. For more information on these four functions, refer to Chapter 49, “Library functions for system programming C,” on page 831.

Restrictions:
1. C main routines are not supported in persistent C environments.
2. The RENT compiler option is not supported in the persistent environment described in this chapter.
3. Exception handling is not supported in persistent C environments.

As an alternative to the persistent environments, you can also create and retain a C environment using the preinitialized programming interface. This interface supports the RENT compiler option, but is less versatile in other respects. z/OS Language Environment provides a callable service for preinitialization called CEEPIPI. This is described in z/OS Language Environment Programming Guide. You may also find information in “Retaining the C environment using preinitialization” on page 258 helpful.

Building applications that use persistent C environments
There are no special restrictions for building applications that use persistent C environments. The automatic call facility will cause the correct routines from the SYSLIB to be included.

If any C library function is required by any routine called in this environment, the stub routines library CEE.SCEELKED should be made available at link time after CEE.SCEESPC.

An example of persistent C environments
The assembler routine shown in Figure 181 on page 805 illustrates the use of this feature to call a C function shown in the sample program (CCNGSP4) in Figure 180 on page 804.
This C function accepts two parameters: an integer and a printf()-style formatting string. The formatting string has a maximum length of 300 bytes; it is terminated by an @ if shorter. This routine must use OS linkage (1). The routine scans the formatting string for the terminator, copies it to a local work area, adds a trailing newline and NULL character, and prints the integer according to the formatting string.

The structure of the assembler caller (CCNGSP5) is shown in Figure 181 on page 805.
* this example demonstrates a persistent C environment
* part 2 of 2 - other file is CCNGSP4

ENVA CSECT
ENVA AMODE ANY
ENVA RMODE ANY

STM R14, R12, 12(R13) 1
LR R3, R15
USING ENVA, R3
GETMAIN R, LV=DSALEN
ST R13, 4(R1)
LR R13, R1
USING DSA, R13
LA R4, HANDLE 2
LA R5, STKSIZE
LA R6, STKLOC
STM R4, R6, PARMLIST
OI PARMLIST+8, X'80'
LA R1, PARMLIST
L R15, =V(EDCXXHOTL)
BALR R14, R15
LA R8, 10 3

LOOP DS OH
ST R8, LOOPCTR 4
LA R4, HANDLE
LA R5, USEFN
LA R6, LOOPCTR
LA R7, FMTSTR1
STM R4, R7, PARMLIST
OI PARMLIST+12, X'80'
LA R1, PARMLIST
L R15, =V(EDCXXHOTU)
BALR R14, R15
LA R7, FMTSTR2 5
STM R4, R7, PARMLIST
OI PARMLIST+12, X'80'
L R15, =V(EDCXXHOTU)
BALR R14, R15
BCT R8, LOOP
ST R4, PARMLIST 6
OI 0(R1), X'80'
LA R1, PARMLIST
L R15, =V(EDCXXHOTT)
BALR R14, R15
LR R1, R13 7
L R13, 4(0, R13)
FREEMAIN R, A=(1), LV=DSALEN
LM R14, R12, 12(R13)
SR R15, R15
BR R14

Using a persistent C environment (Part 1 of 2)

Figure 181. Using a persistent C environment
Using a persistent C environment (Part 2 of 2)

1. This routine is entered with standard linkage conventions. It saves the registers in the save area pointed to by register 13, acquires a dynamic storage area for its own use, and chains the save areas together.

2. A C environment that includes support for the z/OS XL C library is created by calling EDCXHOTL. The parameter list for this call is the address of the handle (for the persistent C environment created), the address of a word containing the initial stack size, and the address of a word containing the initial stack location (0 for below the 16MB line and 1 for above). This parameter list uses the normal OS linkage format.

3. The routine loops 10 times calling the C function crtn twice each time through the loop.

4. The parameter list for the first call is the address of the handle, the address of a word pointing to the function, and the parameters to be received by the function. EDCXHOTU is called. This causes the specified C function, crtn() to be given control with register 1 pointing to the remaining parameters, LOOPCTR and FMTSTR1.

5. The C function is called again, this time with FMTSTR2 as the second parameter.

6. When the loop ends, EDCXHOTT is called to terminate the environment created at 2.

7. The routine terminates by freeing its dynamic storage area and returning to its caller.

[Table 339 on page 807 lists the parts used by persistent environments and their function and location. The SYSLIB is CEE.SCEESPC.]
### Table 339. Parts used by persistent environments

<table>
<thead>
<tr>
<th>Part Name</th>
<th>Function</th>
<th>Inclusion in Program</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>EDCXHOTC</td>
<td>Called to set up a C environment without z/OS Language Environment.</td>
<td>2</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXHOTL</td>
<td>Called to set up a C environment with the z/OS XL C library functions available.</td>
<td>2</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXHOTT</td>
<td>Called to terminate a C environment set up by EDCXHOTC or EDCXHOTL.</td>
<td>2</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXHOTU</td>
<td>Called to use a C environment set up by EDCXHOTC or EDCXHOTL.</td>
<td>2</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXSPRT</td>
<td>System programming version of sprintf().</td>
<td>3</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXEXIT</td>
<td>System programming version of exit().</td>
<td>3</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXMEM</td>
<td>System programming version of malloc(), calloc(), realloc(), free(), __4kmalc() and __24malc().</td>
<td>3</td>
<td>Member of SCEESPC</td>
</tr>
</tbody>
</table>

**Notes:**
1. This module must be explicitly included in the program using the binder INCLUDE control statement.
2. This module will normally be included by automatic call.
3. This module must be explicitly included if you want to use the system programming version of the function.

### Developing services in the service routine environment

The purpose of an application service routine environment is to allow the development, using z/OS XL C, of services that can be developed, tested, and packaged independently of their intended users. You can:

- Isolate the service code from its user
- Specify and enforce a clearly defined Application Programming Interface (API) between the user (another application program) and the service routine
- Share server code among more than one (perhaps different) user applications simultaneously
- Enhance or maintain the service routine code with no disruption to its various user applications

In this environment, a service application is developed as a C `main()` function together with any functions it may call, and packaged as a complete program. This program, if it is reentrant, can be freely installed in the ELPA and shared by all of its users.
To provide the service to a user application, the developer of the service must offer small assembler language stub routines that are link-edited with the user code. These stub routines use services provided by the System Programming Facilities to load or locate the server code and pass messages to it for execution. Examples of these stub routines are shown in “Constructing user-server stub routines” on page 822.

Using application service routine control flow

In this section examples are based on a service routine that manages a storage queue. This server might be used by languages that do not support dynamic memory allocation, or by applications that do not want to concern themselves with the management of such data structures. The operations supported by this service routine are:

- Initialize
- Terminate
- Add an element to the head of the queue (last in, first out)
- Add an element to the tail of the queue (first in, first out)
- Get the element at the head of the queue

Service routine user perspective

A conversation is initiated when a user routine calls a startup routine supplied by the author of the service to establish a connection between the user and the server. This routine returns a handle to the user that represents the server environment. User routines may establish connections with many different services or many times with the same server as long as the needed resources, principally memory, are available in the system. Each connection has a different handle, and it is the user routine's responsibility to keep track of them.

Note: Memory files cannot be shared between the user routines and the server.

Once the user has initialized the server, it uses other server-supplied stub routines to send requests (messages) to the server for action. One of the parameters to this routine will be the handle returned by the initialize call. These request stubs would typically return a feedback code to indicate success or failure as well as any other information requested. The server defines the parameter list to be passed and the feedback codes to be given to the user.

When the user is finished with the server, it calls yet another stub routine to terminate the server. This structure is illustrated in a sample user routine (CCNGSP6) shown in Figure 182 on page 809.
The user routine sets up a variable that will be used to hold the handle returned by the server. The form taken by this handle is up to the supplier of the service, but a fullword (4 bytes) should be regarded as typical.

The user routine calls the initialize routine to set up the connection between the user routine and the server.

The user routine adds three strings to the queue. In this example, the first character of the string indicates the order in which the user expects to retrieve the strings.

The user enters a loop in which the strings are retrieved from the queue.

The user routine prints out the strings passed back by the call to the server. If there is no string remaining in the queue a null string (zero length) is returned.

Before ending, the user routine closes down the server.

This routine is linked normally with the server-supplied stub routines (described in "Constructing user-server stub routines" on page 822).

Service routine perspective
A service routine is a complete, stand alone module that runs in its own C environment. Its environment is created on demand by user application routines that call it using stub routines supplied by the server. When this happens, the server code enters at its main() entry point and, typically, goes into a loop that contains a function call to get the next to-do. One possible to-do is terminate; when
this command is received the server should exit() or return from its main() function. The environment created when the server was started terminates and all resources held by the server are freed (except storage acquired by __24malc() or __4kmalc(), as described in "__24malc() — Allocate Storage below 16MB Line" on page 835 and "__4kmalc() — Allocate Page-Aligned Storage" on page 836. This structure is illustrated in a sample user routine shown in Figure 183.

/* this is an example of an application service routine */

#include <spc.h>
#include <stdlib.h>
#include <string.h>
define LIFO 1
#define FIFO 2
#define GET 3
#define TERM -1

int main(void) {
    int retcode=0;
    /* data structures to manage the queue */
    struct queue_entry {
        struct queue_entry *next;
        int length;
        char val[1];
    };
    struct queue_entry *head;
    struct queue_entry *tail;
    struct {
        int code;
        union info *plist;
    } *req;
    union info {
        struct {
            int *length;
            char *string;
        } lifo;
        struct {
            int *length;
            char *string;
        } fifo;
        struct {
            int *length;
            char *string;
        } get;
    };
    /* initialize the queue pointers */
    head = NULL;
    tail = NULL;

Example of application service routine (Part 1 of 2)

Figure 183. Example of application service routine (Part 1 of 2)
/* the main processing loop goes on until a termination signal is sent */

for(;;) {  3
  union info *info;
  int length;
  char *string;
  struct queue_entry *ent;

  /* get a message from the user routine */
  req__xsrvc(retcode);  9  18
  info = req->plist; 10

  switch(req->code) { 11
  case LIFO: { 12
    length=(*info).lifo.length;
    string=(*info).lifo.string;
    ent = malloc(sizeof *ent - 1 + length);  13
    memcpy((ent).val,string,length);
    __xsacc(0); 14
    (ent).length=length;
    (ent).next=head;
    head=ent;
    if (NULL==tail) tail=ent;
    break; 16
  }
  case FIFO: { 15
    length=(*info).fifo.length;
    string=(*info).fifo.string;
    ent = malloc(sizeof *ent - 1 + length);
    memcpy((ent).val,string,length);
    __xsacc(0);
    (ent).length=length;
    (ent).next=NULL;
    if (NULL==head) head=ent;
    else (*tail).next=ent;
    tail=ent;
    break; 16
  }
  case GET: { 15
    if (NULL==head) {
      *(info).get.length=0;
      break;
    }
    length = (*head).length;
    string = (*head).get.string;
    memcpy(string,(head).val,length);
    *(info).get.length=length;
    __xsacc(0);
    ent=start;
    head=(*ent).next;
    free(ent);
    if (NULL==head) tail=NULL;
    break;
  }
  case TERM: 16
    return 0;
  default:  17
  }
  __xsacc(666); 17
}

Example of application service routine (Part 2 of 2)
The server routine should include the appropriate header files. `spc.h` contains the function prototypes for the routines that are used to maintain the conversation between the server routine and the user routine. `string.h` is required if string or memory functions are used in the code and z/OS Language Environment will not be available at run time; this header file contains the directives necessary to use these built-in functions.

These are the command codes of the requests that can be sent to this server.

The server begins with a `main()` function. This function gets control when the user calls `QMGINIT`.

This server manages an in-storage queue of unstructured elements. It does this by maintaining a linked list of elements. The structure `queue_entry` contains an individual entry; `head` and `tail` point to the first and last entries in the queue.

Requests come to the server in the form of a pointer to a structure containing a command code (in this case, one of `LIFO`, `FIFO`, `GET`, or `TERM`) and a pointer to a parameter list associated with the command code. The parameter list is what follows `HANDLE` and `FEEDBACK` in the calls to `QMGLIFO`, `QMGFIFO`, and `QMGGET`. Like the command codes, the structure of this parameter list is established in concert with the stub routines.

In this example, all the commands have exactly the same format. This may not generally be the case, so a union of the various parameter list formats is appropriate. Then the interface can be expanded without disrupting existing code.

Before accepting commands, required initialization is performed.

This server is structured as an endless loop. This loop terminates when a terminate message sends control to a `return` statement at 17.

At this point, the server is ready for work. The call to `__xsrvc()` causes the user routine to resume execution at the place it left off when it last called the server. The value passed as the parameter is made available to the stub routines for use as a feedback code. This function will not return until the user application sends a request (using one of the stub routines, in this example `QMGLIFO`, `QMGFIFO`, `QMGGET`, or `QMGTERM`).

This function should be used to indicate that the server has completed its use of any data structures (parameters and data areas pointed to by the parameters) belonging to the user application. The value passed to this function or the value passed by the next call to `__xsrvc()` (which ever is greater in magnitude) will be passed to the stub routine for use as a feedback code.
The handling of FIFO and GET is similar.

When a terminate request is received, the server returns. This terminates the loop (at 8) and the environment set up when the server was first called.

If the command code is not recognized the server acknowledges the request and sets a return code that can be analyzed by the stub routine or the user application.

The server returns to the request for another to-do. The value passed as a parameter here or the last value passed to __xsacc(), whichever has the greater magnitude, is passed to the stub routine for use as a feedback code.

The server is built as a freestanding C application, as described in “Creating freestanding applications” on page 792.

You must specify EDCXSTRT, QMGSERV, EDCXMEM and EDCXEXIT when you link edit.

Understanding the stub perspective

The stub routines provide the link between the user application and the application service module. They are responsible for:

- Locating or loading the server code
- Providing the Application Programming Interface (API) seen by the user.

Many choices are available in the design of the API and how single calls in the user are mapped. For example, the initialize call could accept parameters governing the behavior of the session being established and pass them to the server as commands once the server has been initialized. In the example the interactions are straightforward, the initialize only starts up the server, and the message calls send single messages, untouched and unexamined, to the server.

There are two kinds of stubs: the initialization stub and the message stubs. Termination is a special case of a message stub. These stubs are most appropriately written in assembler so that they can run in any language environment with minimal performance cost.

The initialization stub is responsible for loading and calling the server. It can use the low-level storage management and contents supervision routines supplied in SCEESPC. These routines are described in “Tailoring the system programming C environment” on page 823. The structure of an initialization stub is shown in Figure 184 on page 814.
Stub routines are presumed to have a save area available at the location pointed to by register 13.

The parameter list passed to stub routines is OS linkage; that is, register 1 points to a list of addresses. In this example, the initialization stub receives only one parameter, the handle, that gets the address of a control block representing the environment.

For efficiency, this routine gets a work area that will be used by all the stub routines. The low level storage management routine EDCXGET, (described in “Getting storage” on page 824) is available for this purpose. This area will be the DSA for this and all other stub routines. It begins with an 18-word save area for use by routines called by this stub. It will be freed by the “terminate” stub.

When a save area is available, EDCXLOAD (described in “Loading a module” on page 826) is called to load the server.

EDCXSRVI is called to initialize the server. When control is returned from this call, the server has built a complete environment and has asked for something to do.
The value returned by EDCXSRVI is the address of a control block that is used to manage the interface between the user application and the service application module. The first 3 words (12 bytes) of this control block are reserved for the exclusive use of the stub routines. The fields following the first 3 words may not be used by either the stub routines or the user, nor may their values be altered. In this example, an *eye-catcher* (often useful for debugging) is moved into the first word.

The address of the work area acquired for dynamic storage requirements is moved into the second word. The address of this control block is stored in the user's handle.

The address of the control block from EDCXSRVI is placed in the user routine's handle. The user routine has no knowledge of the contents or format of this field; it is simply a *token* that is passed to other stub routines to manage the conversation between the user and the service routine.

Having initialized the server, the stub returns to the user at ② in Figure 182 on page 809.

Message stubs are responsible for passing requests from the user application to the service application. Like the initialization stub, they are free to use the low-level storage management and contents supervision routines supplied with the system programming facilities. Example message stubs are shown in Figure 185 on page 816, Figure 186 on page 817, Figure 187 on page 819, and Figure 188 on page 820.
Like the initialize stub, the QMGLIFO message stub expects a standard save area pointed to by register 13. The parameters are passed with standard OS linkage (register 1 pointing to a list of addresses).

The handle contains the value that was placed there by the initialization stub at in Figure 184 on page 814. This is the address of the control block that is used to manage the interface between the user application and the server.

Recover the address of the stub work area for use as a Dynamic Storage Area (DSA). This value was saved here by the initialization stub at The save area back chain field is set according to usual conventions.

A parameter list consisting of the handle (as returned by EDCXSRVI at in Figure 184 on page 814) in the initialization stub), code for LIFO, and the address of the remaining parameters.

Call EDCXSRVN to re-awaken the server. This causes the server to resume control at in Figure 183 on page 810 in the server. The server has control until it asks for the next todo, in this example at .

The value passed to __xsrvc() appears as the return code from EDCXSRVN.
This value is passed back to the user application in the second parameter. 
*This is part of the API defined by this particular server, not something inherent in 
the user-server relationship.*

Control is returned to the user in the usual way.

The routine in Figure 186 uses functions supplied in SCEESPC to load or locate the 
server code and initialize its environment.

```
* this is an example of a server message stub
QMGFIFO TITLE 'SERVER supplied stub for feeding strings FIFO'
QMGFIFO CSECT
QMGFIFO AMODE ANY
QMGFIFO RMODE ANY
STM R14,R12,12(R13) 1
LR R3,R15
LR R5,R1
USING INPARMS,R5
LR R6,HANDLE@
L R6,0,(R6) Point to the handle 2
L R1,4,(R6) Point to work area got by QMGINIT 3
USING WA,R1
LR R3,SA+4 Keep savearea passed into us
LR R13,R1 WA is new savearea
USING WA,R13
LA R7,FIFO 4
LA R8,INPARMS+8 User parms start at 3rd
STM R6,8,PLIST handle, FIFO, Other parms
LA R1,PLIST
L R15,=V(EDCXSRVN) 5
BALR R14,R15
L R1,FEEDBK@ 6
ST R15,0,(R1)
L R13,4,(R13) 7
L R14,12(R13)
LM R0,R12,20(R13)
BR R14
INPARMS DSECT
HANDLE@ DS F
FEEDBK@ DS F
LENGTH@ DS F
STRING@ DS F
WA DSECT
SA DS 1BF
PLIST DS 4F
WALEN EQU *-WA
LIFO EQU 1
FIFO EQU 2
GET EQU 3
TERM EQU -1
YREGS
END
```

Figure 186. Example of server message stub-FIFO

1. Like the initialize stub, the QMGFIFO message stub expects a standard 
save area pointed to by register 13. The parameters are passed with 
standard OS linkage (register 1 pointing to a list of addresses).

2. The `handle` contains the value that was placed there by the initialization 
stub at 8 in Figure 184 on page 814. This is the address of the control 
block that is used to manage the interface between the user application 
and the server.

3. Recover the address of the stub work area for use as a Dynamic Storage
Area (DSA). This value was saved here by the initialization stub at 7 in Figure 184 on page 814. The save area back chain field is set according to usual conventions.

4 A parameter list consisting of the handle (as returned by EDCXSRVI at 5 in Figure 184 on page 814), code for FIFO, and the address of the remaining parameters.

5 Call EDCXSRVN to re-awaken the server. This causes the server to resume control at 9 in Figure 183 on page 810 in the server. The server has control until it asks for the next to-do, in this example at 9 in Figure 183 on page 810 again.

6 The value passed to __xsvc() appears as the return code from EDCXSRVN. This value is passed back to the user application in the second parameter. This is part of the API defined by this particular server, not something inherent in the user-server relationship.

7 Control is returned to the user in the usual way.

The routine in Figure 187 on page 819 uses functions supplied in SCEESPC to load or locate the server code and initialize its environment.
Like the initialize stub, the QMGGET message stub expects a standard save area pointed to by register 13. The parameters are passed with standard OS linkage (register 1 pointing to a list of addresses).

The handle contains the value that was placed there by the initialization stub at Figure 184 on page 814. This is the address of the control block that is used to manage the interface between the user application and the server.

Recover the address of the stub work area for use as a Dynamic Storage Area (DSA). This value was saved here by the initialization stub at Figure 184 on page 814. The save area back chain field is set according to usual conventions.

A parameter list consisting of the handle (as returned by EDCXSRSI at Figure 184 on page 814 in the initialization stub), code for GET, and the address of the remaining parameters.

Call EDCXSRSN to re-awaken the server. This causes the server to resume.
The value passed to __xsrvc() appears as the return code from EDCXSrvn. This value is passed back to the user application in the second parameter. 
This is part of the API defined by this particular server, not something inherent in the user-server relationship.

Control is returned to the user in the usual way.

The routine in Figure 188 uses functions supplied in SCEESPC to load or locate the server code and initialize its environment.

* this is an example of a server message stub
QMGTERM TITLE 'SERVER supplied stub for feeding strings TERM'
QMGTERM CSECT
QMGTERM AMODE ANY
QMGTERM RMODE ANY
STM R14,R12,12(R13) 1
LR R3,R15
USING QMGTERM,R3
LR R5,R1
USING INPARM,R5
L R6,HANDLEB
L R6,0(R6) 2
L R1,4(R6) Point to the handle
L R6,0(R6) 3
L R6,HANDLEB
L R13,5A+4 Keep savearea passed into us
LR R13,R1
USING WA,R13
ST R13,5A+4 WA is new savearea
L R13,5A+4
USING WA,R13
ST R6,PLIST Store handle as first parameter 4
MVC PLIST+4,=A(TERM) Code for termination
LA R1,PLIST
L R15,=V(EDCXSRVN) 5
BALR R14,R15
L R13,4(R13)
L R14,12(R13)
LM R0,R12,20(R13)
BR R14

INPARM DSECT
HANDLE@ DS F
FEEDBK@ DS F
LENGTH@ DS F
STRING@ DS F
WA DSECT
SA DS 18F
PLIST DS 4F
WALEN EQU ++WA
LIFO EQU 1
FIFO EQU 2
GET EQU 3
TERM EQU -1
YREGS END

Figure 188. Example of server message stub-TERM

1 Like the initialize stub, the QMGTERM message stub expects a standard save area pointed to by register 13. The parameters are passed with standard OS linkage (register 1 pointing to a list of addresses).

2 The handle contains the value that was placed there by the initialization stub at 6 in Figure 184 on page 814. This is the address of the control block that is used to manage the interface between the user application and the server.
Recover the address of the stub work area for use as a Dynamic Storage Area (DSA). This value was saved here by the initialization stub at /SF580007/SF590000 in Figure 184 on page 814. The save area back chain field is set according to usual conventions.

A parameter list consisting of the handle (as returned by EDCXSRVI at /SF580005/SF590000 in Figure 184 on page 814), code for TERM, and the address of the remaining parameters.

Call EDCXSRVN to re-awaken the server. This causes the server to resume control at /SF580009/SF590000 in Figure 183 on page 810 in the server. The server has control until it asks for the next to-do, in this example at /SF580009/SF590000 in Figure 183 on page 810 again.

Control is returned to the user in the usual way.

The routines in the following section are used to create and use a persistent C environment for a server co-routine, written using z/OS XL C and EDCXSTRT, or EDCXSTRL and callable by a user application written in any language.

An initialization routine, EDCXSRVI, is called to start up a server. Control returns from the initialization call with the server code started and waiting for work.

As with the persistent C environment, the initialization call returns a handle that is used by EDCXSRVN for further communication with the created environment. EDCXSRVN suspends the execution of the calling routine and sends a message to the waiting server. When the server completes the function called for by the message its execution is suspended and the caller of EDCXSRVN resumes.

The server environment is terminated when a Terminate message is sent to the server.

**Establishing a server environment**

The EDCXSRVI routine creates a z/OS XL C environment for the server part of user-server application. It is intended that this routine be called by a stub routine supplied by the server and statically bound with the user application. The stub routine is responsible for loading the server application code. EDCXSRVI has the following parameters:

1. The address of the entry point of the server code. This must be the address of the EDCXSTRT or EDCXSTRL entry point.
2. The value to be in R1 when the server entry point is called. This can be used for communication between the initialization stub and the server mainline; its value can be retrieved in the server code. __xregs(1) will return a pointer to this list of parameters.
3. The address of a low-level get-storage routine (meeting the same interface as EDCXGET, but not necessarily EDCXGET).
4. The address of a low-level free-storage routine (meeting the same interface as EDCXFREE, but not necessarily EDCXFREE).

When this routine returns, the server environment is fully established and waiting for a message from the user. R15 points to a handle that is used in subsequent calls to EDCXSRVN to send messages to the server.
**Initiating a server request**

The EDCXSRVN routine is used by the stub routines that are linked with user application routines to send a message to an active server in a user-server application. EDCXSRVN has the following parameters:

1. The address of the handle returned by EDCXSRVI.
2. The function code for the function to be performed. The value -1 is used to indicate that the server should terminate. This value should not be used for any other purpose.
3. Other parameters, which are passed to the server code.

Upon return, R15 will contain the return code supplied by the server (as the parameter to EDCXSACC) for this service.

**Accepting a request for service**

The EDCXSACC routine operates in the server part of a user-server application. It is used to indicate acceptance or rejection of the last-requested service. EDCXSACC has the following parameter:

1. The return code of the last-requested service 0 indicating that the request was accepted and will be processed.

For more information on EDCXSACC, see "_xsacc() — Accept Request for Service" on page 834.

**Returning control from service**

The EDCXSRVC routine operates in the server part of a user-server application. It is used to indicate completion of the last-requested service and to get information required for the next service to be performed. For more information on EDCXSRVC, see "_xsrvc() — Return Control from Service" on page 835. EDCXSRVC has the following parameter:

1. The return code for the last-requested service.

**Constructing user-server stub routines**

Part of building a server for use in a user-server environment is the construction of stub routines that load and initialize the server, pass messages to the server, and terminate the server. These stub routines are typically written in assembler language to allow them to be freely called from other environments without regard to the characteristics of the calling environment.

**Building user-server environments**

To build your server application, follow the rules for building a freestanding application as described in "Building freestanding applications to run under z/OS" on page 795.

There are no special considerations for building user applications. The automatic call facility will cause the correct routines from CEE.SCEESPC to be included.
Table 340. Parts used by or with application server routines

<table>
<thead>
<tr>
<th>Part Name</th>
<th>Function</th>
<th>Inclusion in Program</th>
<th>Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>EDCXSRSVI</td>
<td>Used by a server-supplied stub routine to start up a server.</td>
<td>2</td>
<td>in the user module</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXSRSVN</td>
<td>Used by a server-supplied stub routine to send a service-request message to a server.</td>
<td>2</td>
<td>in the user module</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXSRSVC</td>
<td>Used by a server to wait for the next message to process.</td>
<td>2</td>
<td>in the user module</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXSACC</td>
<td>Used by a server to accept the last message received.</td>
<td>2</td>
<td>in the user module</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXSPRT</td>
<td>System programming version of sprintf().</td>
<td>3</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXEXIT</td>
<td>System programming version of exit().</td>
<td>3</td>
<td>Member of SCEESPC</td>
</tr>
<tr>
<td>EDCXMEM</td>
<td>System programming version of malloc(), calloc(), realloc(), free(), __4kmalc() and __24malc().</td>
<td>3</td>
<td>Member of SCEESPC</td>
</tr>
</tbody>
</table>

Notes:
1. This module must be explicitly included in the program using the binder INCLUDE control statement.
2. This module will normally be included by automatic call.
3. This module must be explicitly included if you want to use the system programming version of the function.

Tailoring the system programming C environment

Depending on the environment under which you want to run your z/OS XL C routines, you might want to replace some of the following routines for system-specific routines. To work correctly, your routines should match the interface as documented in this section. The routines as supplied by IBM with z/OS XL C meet the interface as documented.

Generating abends

The EDCXABND routine is called to generate an abend if there is an internal error during initialization or termination of a system programming C environment. This module must have the entry point name of @@@XABND. It uses the following parameter:

R1 The address of the abend code and reason code

This routine is not provided with a save area. In addition to the linkage registers, this routine may freely alter registers 2 and 4. Figure 189 on page 824 shows an example.
Getting storage

The EDCXGET routine is called to get storage from the operating system. The entry point name for this routine must be @@@XGET; see Figure 190 on page 825 for an example. It uses the following parameter:

- **R0**  The requested length, in bytes. If the high-order bit is zero or if the request was made in 24-bit addressing mode, the storage will be allocated below the 16M line. If the high-order bit is on and the request is made in 31-bit addressing mode, storage will be allocated anywhere with a preference for storage above the 16M line if available.

Upon return, the following values are set:

- **R0**  The length of the storage block acquired, in bytes.
- **R1**  The address of the acquired area or NULL.
- **R15**  A system dependent return code, which must be zero on success and non-zero otherwise.

This routine is not provided with a save area. In addition to the linkage registers, this routine may freely alter registers 2 and 4.

If you provide your own EDCXGET routine, it will be used when C library functions explicitly get storage. Whenever the library functions invoke operating system services, there may be implicit requests for storage that cannot be tailored.

---

* Figure 189. Example of routine to generate abend

```c
* this is an example of a routine to generate an abend
@@XABEND TITLE 'Generate an Abend'
EDCXABND CSECT
EDCXABND AMODE ANY
EDCXABND RMODE ANY
00XABND DS OH
ENTRY 00XABND
BALR R2,0
USING *,R2
SPACE 1
*
USING PARMS,R1
L R4,REAS_RC get reason code
L R2,ERROR_RC get error code
DROP R1,R2
ABEND ABEND(R2),REASON=(R4)
*
LTORG
EJECT
PARMS DSECT
ERROR_RC DS F
REAS_RC DS F
*
R1 EQU 1
R2 EQU 2
R3 EQU 3
R4 EQU 4
END
```

---

* Figure 189. Example of routine to generate abend
Getting page-aligned storage

The EDCX4KGT routine is called to get page-aligned storage from the operating system. Its entry point must be @@X4KGET. It has the following parameter:

**R0**  The requested length, in bytes. If the high-order bit of this register is zero or if the request was made in 24-bit addressing mode, the storage is allocated below the 16M line. If the high-order bit is on and the request is made in 31-bit addressing mode, storage is allocated above the 16M line. If this space is not available, storage is allocated elsewhere.

Upon return, the following values are set:

**R0**  The length of the storage block acquired, in bytes. This length may be greater than the size requested.

**R1**  The address of the acquired area or NULL.

**R15**  A system-dependent return code, which must be zero on success and nonzero otherwise.

This routine is *not* provided with a save area. In addition to the linkage registers, this routine may freely alter registers 2 and 4.

---

* Figure 190. Example of routine to get storage
Freeing storage
The EDCXFREE routine is called to return storage to the operating system. Its entry point must be @@XFREE. It uses the following parameters:

R0  The length of storage to be freed, in bytes
R1  The address of the area to be freed

Upon return, the following value is set.

R15  A system-dependent return code, which must be zero on success and nonzero otherwise

This routine is not provided with a save area. In addition to the linkage registers, this routine may freely alter registers 2 and 4.

If you provide your own EDCXFREE routine, it will be used when C library functions explicitly free storage. Whenever the library functions invoke operating-system services, there may be implicit requests to free storage that cannot be tailored.

Figure 191 shows an example of a routine that is used to free storage.

* this is an example of a routine to free storage
EDCXFREE CSECT
EDCXFREE AMODE ANY
EDCXFREE PMODE ANY
00XFREE DS OH
ENTRY 00XFREE
BALR R2,0
USING *,R2
*
FREEMAIN RC,SP=0,LV=(0),A=(1)
BR R14 return
*
R2 EQU 2
R14 EQU 14
END

Figure 191. Example of routine to free storage

Loading a module
The EDCXLOAD routine is called to load a named module into storage. Its entry point must be @@XLOAD. It has the following parameter:

R1  Points to the name of the routine to be loaded

On return, the following values are set.

R1  the address and amode of the routine or 0
R15  A system-dependent return code, which must be zero on success and nonzero otherwise

This routine is provided with a save area. Apart from the linkage registers, it must save and restore all registers used.

Deleting a module
The EDCXUNLD routine is called to delete a named module from storage. Its entry point must be @@XUNLD. It has the following parameter:
R1     Points to the name of the routine to be deleted

Upon return, the following values is set.

R15    A system-dependent return code, which must be zero on success and
       nonzero otherwise

This routine is provided with a save area. Apart from the linkage registers, it must
save and restore all registers used.

Including a runtime message file

When you are running a freestanding environment and runtime messages are
required, you must explicitly include a message file at link-edit time. One of the
three following modules can be included to produce these messages:

EDCXLANE
    Creates runtime error messages in uppercase and lowercase English

EDCXLANU
    Creates runtime error messages in uppercase English

EDCXLANK
    Creates runtime error messages in Kanji

If one of these message routines is not included and an exception occurs, the
program could terminate without displaying a message. These error messages are
directed to stderr. Refer to z/OS Language Environment Debugging Guide for more
information.

Table 341 contains the abend codes and reason codes specific to the system
programming facilities.

Table 341. Abend and reason codes specific to system programming environments

<table>
<thead>
<tr>
<th>Code Type</th>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abend</td>
<td>2100</td>
<td>No storage abend code</td>
</tr>
<tr>
<td></td>
<td>2101</td>
<td>Error freeing storage</td>
</tr>
<tr>
<td></td>
<td>2102</td>
<td>Error finding stack seg home</td>
</tr>
<tr>
<td></td>
<td>2103</td>
<td>Error loading library</td>
</tr>
<tr>
<td></td>
<td>2104</td>
<td>Error with heap allocation</td>
</tr>
<tr>
<td></td>
<td>2105</td>
<td>Error with system level command</td>
</tr>
<tr>
<td></td>
<td>2106</td>
<td>Error initializing statics</td>
</tr>
<tr>
<td></td>
<td>2107</td>
<td>Error establishing error handler for EDCXSTRX</td>
</tr>
<tr>
<td></td>
<td>2108</td>
<td>Error cleaning up heap for EDCXSTRX</td>
</tr>
<tr>
<td></td>
<td>4000</td>
<td>Error when handling abend</td>
</tr>
</tbody>
</table>
Table 341. Abend and reason codes specific to system programming environments (continued)

<table>
<thead>
<tr>
<th>Code Type</th>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reason</td>
<td>7201</td>
<td>Error in initialization.</td>
</tr>
<tr>
<td></td>
<td>7202</td>
<td>Error in termination.</td>
</tr>
<tr>
<td></td>
<td>7203</td>
<td>Error when extending stack.</td>
</tr>
<tr>
<td></td>
<td>7204</td>
<td>Error during longjmp/setjmp.</td>
</tr>
<tr>
<td></td>
<td>7205</td>
<td>Can not locate static init. The routine EDCRCINT must be included in your module if you use the RENT compiler option.</td>
</tr>
<tr>
<td></td>
<td>7206</td>
<td>Module EDCXABRT was not explicitly included at link edit time.</td>
</tr>
<tr>
<td></td>
<td>7207</td>
<td>No initial heap allocation is specified and a heap is required.</td>
</tr>
</tbody>
</table>

Additional library routines

The following routines provide additional support that is unique to applications running in a system programming C environment. These routines are packaged as part of the link library. For more information on these routines refer to "Library functions for system programming C," on page 831.

- __xregs()  
  Get registers on entry
- __xusr()  
  Get address of User Word
- __xusr2()  
  Get address of User Word
- __4kmalc()  
  Allocate page-aligned storage
- __24malc()  
  Allocate storage below 16mb line

Summary of application types

Table 342 shows the summary of application types, how they are called, and the module entry points.

Table 342. Summary of types

<table>
<thead>
<tr>
<th>Type of Application</th>
<th>How It Is Called</th>
<th>Module Entry Point</th>
<th>Data Sets Required at Execution Time</th>
<th>Runtime Options (1) and Other Considerations</th>
</tr>
</thead>
<tbody>
<tr>
<td>A mainline function that requires no dynamic library facilities</td>
<td>From the command line, JCL, or an EXEC or CLIST.</td>
<td>EDCXSTRT, which must be explicitly included at bind time</td>
<td>None.</td>
<td>Runtime options are specified by #pragma runopts in compilation unit for the main() function. The heap and stack options are honored. The stack defaults to be above the line.</td>
</tr>
<tr>
<td>Type of Application</td>
<td>How It Is Called</td>
<td>Module Entry Point</td>
<td>Data Sets Required at Execution Time</td>
<td>Runtime Options (1) and Other Considerations</td>
</tr>
<tr>
<td>---------------------</td>
<td>------------------</td>
<td>--------------------</td>
<td>-------------------------------------</td>
<td>---------------------------------------------</td>
</tr>
<tr>
<td>A mainline function that requires the z/OS XL C library functions</td>
<td>From the command line, JCL, or an EXEC or CLIST.</td>
<td>EDCXSTRL, which must be explicitly included at bind time</td>
<td>CEE.SCEERUN is required</td>
<td>Runtime options are specified by #pragma runopts in the compile unit for the entry point. The heap and stack options are honored, except that the stack will default to be above the line. The SPIE option is honored if a library is called for.</td>
</tr>
<tr>
<td>A C subroutine called from assembler language using a pre-established persistent environment</td>
<td>A handle, the address of the subroutine and a parameter list are passed to EDCXHOTU.</td>
<td></td>
<td>CEE.SCEERUN is optional, depending upon the way the handle was set up.</td>
<td>Runtime options are specified by #pragma runopts in any compile unit. The heap and stack options are honored, except that the stack will default to be above the line. The SPIE option is honored if a library is called for. The runopts in the first object module in the link edit that contains runopts will prevail, even if this compilation unit is part of the calling application. The environment is established by calling EDCXHOTC (or EDCXHOTL if library facilities are required). These functions return a value (the handle) which is used to call functions that use the environment.</td>
</tr>
<tr>
<td>A Server</td>
<td>User code includes a stub routine that calls EDCXSRVI. This causes the server to be loaded and control to be passed to its entry point.</td>
<td>EDCXSTRT, or EDCXSTRL, depending upon whether the server needs the C runtime library or not</td>
<td>CEE.SCEERUN if required by the server code.</td>
<td>Runtime options are the same as for EDCXSTRT or EDCXSTRTL. The author of the server must supply stub routines which call EDCXSRVI and EDCXSRVNI to initialize and communicate with the server. These are bound with the user application.</td>
</tr>
<tr>
<td>A User of an Application Server</td>
<td></td>
<td></td>
<td>CEE.SCEERUN if required by the server.</td>
<td>The author of the server must supply stub routines which call EDCXSRVI and EDCXSRVNI to initialize and communicate with the server.</td>
</tr>
</tbody>
</table>
Chapter 49. Library functions for system programming C

This chapter describes the library functions specific to the System Programming C environment:
- __xhotc()
- __xhotl()
- __xhott()
- __xhotu()
- __xregs()
- __xsacc()
- __xsrvc()
- __xusr()
- __xusr2()
- __24malc()
- __4kmalc()

__xhotc() — Set Up a Persistent C Environment (No Library)

Purpose

The function creates a persistent C environment that does not require the dynamic library facilities of z/OS Language Environment at run time.

For an extensive example of the use of __xhotc(), see "Creating and using persistent C environments" on page 802.

Format

```c
#include <spc.h>
void *__xhotc(void *handle, int stack, int location);
```

The parameters are fullwords (four bytes).

- **handle**
  - the field for the token (or handle) which is returned

- **stack**
  - initial stack allocation required for the environment

- **location**
  - location of the stack:
    - 0  Below the line
    - 1  Above the line

Returned value

__xhotc() returns a token (or handle) which is used in subsequent calls to __xhotu() and __xhott() to use or terminate a persistent C environment. This handle is found in both the first parameter passed and R15.
The RENT compiler option is not supported for routines called using this environment.

__xhotl() — Set Up a Persistent C Environment (With Library)

**Purpose**

The function creates a persistent C environment that will use the dynamic z/OS XL C/C++ library functions. All library facilities are available in this environment except:

- The RENT compiler option is not supported in the persistent environment described in this chapter.
- Exception handling is not supported in persistent C environments.

For an extensive example of the use of __xhotl(), see "Creating and using persistent C environments" on page 802.

**Format**

```
#include <spc.h>
void *__xhotl(void *handle, int stack, int location);
```

The following parameters are fullwords (four bytes):

- **handle**
  - the field for the token (or handle) which is returned
- **stack**
  - the initial stack allocation required for the environment
- **location**
  - location of the stack:
  - 0  Below the line
  - 1  Anywhere

**Returned value**

This routine returns a token (or handle) which is used in subsequent calls to __xhotu() and __xhott() to use or terminate a persistent C environment. This handle is found in both the first parameter passed and R15.

__xhott() — Terminate a Persistent C Environment

**Purpose**

This function terminates a persistent C environment created by __xhotc() or __xhotl(). __xhott() is specific to SP C. It is part of the group serving the persistent C environment. (The function is also available under the name EDCXHOTT.)

For an extensive example of the use of __xhott(), see "Creating and using persistent C environments" on page 802.
**Format**

```c
#include <spc.h>
void __xhott(void *handle);
```

The parameter of __xhott() is a handle returned by __xhotc() or __xhotl().

---

**__xhotu()**

**Purpose**

This function is used to run a function in a persistent C environment. The function is also available under the name EDCXHOTU.

This routine, and the C function being called, must use OS linkage. As a result, you cannot make direct use of z/OS XL C/C++ Library functions with this function. C functions being invoked using __xhotu() must be compiled with #pragma linkage(func_name,OS).

__xhotu() is specific to SP C. It is part of the group serving the persistent C environment.

For an extensive example of the use of __xhotu(), see "Creating and using persistent C environments" on page 802.

**Format**

```c
#include <spc.h>
void *__xhotu(void *handle, void *function, ...);
```

The parameters are fullwords (four bytes):

- **handle**
  a handle—returned by __xhotc() or __xhotl()

- **function**
  a function pointer, which points to the desired C function
  - First parameter to pass to the function
  - Second parameter to pass to the function

**Returned value**

The returned value from __xhotu() is the returned value from the function run in the persistent C environment.

---

**__xregs() — Get Registers on Entry**

**Purpose**

This routine finds the value a specified register had on entry to EDCXSTRT, EDCXSTRL, EDCXSTRX, or the main routine of an exit routine compiled with #pragma environment(...).
_xregs() is available in these environments only. For more information about EDCXSTRT, EDXSTRL, or EDCXSTRX, see “Creating freestanding applications” on page 792.

_xregs() is specific to SP C. It is part of the client-server group of functions.

The function is also available under the name EDCXREGS.

Format

```c
#include <spc.h>
int _xregs(int register);
```

Returned value

_xregs() returns the value found.

## _xsacc() — Accept Request for Service

### Purpose

This routine operates in the server part of a user-server application. It is used to indicate acceptance or rejection of the last-requested service. The function is also available under the name EDCXSACC.

Calls to _xsacc are optional but, if made, should be when the request is validated and all server references to user-owned storage are complete. _xsacc does not cause a return of control to the user; its sole purpose is to indicate that user-owned storage is no longer required by the application server.

In the case of a request that cannot be processed, possibly because the user's command is not recognized by the server or the parameter format is invalid, the call to _xsacc should be omitted.

_xsacc() is specific to SP C. It is part of the client-server group of functions.

Format

```c
#include <spc.h>
void _xsacc( int message);
```

Returned value

The return code for the last-requested service, zero indicating that the request was accepted and will be processed.
__xsrvc() — Return Control from Service

Purpose

This routine operates in the server part of a user-server application. It is used to indicate completion of the last-requested service and to get the information required for the next service to be performed. The function is also available under the name EDCXSRVIC.

__xsrvc() is specific to SP C. It is part of the client-server group of functions.

Format

```c
#include <spc.h>
void *__xsrvc(int message);
```

The message is the return code for the last-requested service.

__xusr() - __xusr2() — Get Address of User Word

Purpose

The __xusr() and __xusr2() functions are also available under the names EDCXUSR and EDCXUSR2, respectively. Two words in an internal control block are available for customer use. These words have an initial value of zero (that is, all bits are 0), but are otherwise ignored by compiled code, and by the z/OS XL C/C++-specific Library. The values in these words may be freely queried or set by application code using the pointers returned by these functions.

__xusr() and __xusr2() are specific to SP C.

Format

```c
#include <spc.h>
void *__xusr(void);
void *__xusr2(void);
```

Returned value

__xusr() and __xusr2() return the addresses of these user words. The words, and __xusr() and __xusr2() themselves, are available in any environment, not only the system programming environments.

__24malc() — Allocate Storage below 16MB Line

Purpose

This function performs in the same manner as malloc except that it allocates storage below the 16MB line in XA or ESA systems, even when the runtime option HEAP(ANYWHERE) is specified. Storage allocated by this function is not part of the heap, so you must free this storage explicitly using the free() function before this
environment is terminated. Storage allocated using __24malc() is not automatically freed when the environment is terminated.

The function is available under the System Programming Environment.

**Format**

```c
#include <spc.h>
void *__24malc(size_t size);
```

---

__4kmalc() — Allocate Page-Aligned Storage

**Purpose**

This function performs in the same manner as malloc(), except that it allocates page-aligned storage. Storage allocated by this function is not part of the heap, so you must free this storage explicitly using the free() function before this environment is terminated. Storage allocated using __4kmalc() is not automatically freed when the environment is terminated.

The function is available under the System Programming Environment.

**Format**

```c
#include <spc.h>
void *__4kmalc(size_t size);
```
Chapter 50. Using runtime user exits

This chapter shows how to use runtime user exits with the z/OS Language Environment runtime library. This is general-use programming interface information and associated guidance information for using the library.

This section is provided here for your convenience. For further information on using runtime user exits in the z/OS Language Environment environment, refer to z/OS Language Environment Programming Guide.

Note: Runtime user exits are not supported in AMODE 64 applications.

Using runtime user exits in z/OS Language Environment

z/OS Language Environment provides user exits that you can use for functions at your installation. You can use the assembler user exit (CEEBXITA) or the HLL user exit (CEEBINT). This section provides information about using these runtime user exits.

Note: You cannot code either the CEEBXITA user exit or the CEEBINT user exit as an XPLINK application.

Understanding the basics

User exits are invoked under z/OS Language Environment to perform enclave initialization functions and both normal and abnormal termination functions. User exits offer you a chance to perform certain functions at a point where you would not otherwise have a chance to do so. In an assembler initialization user exit, for example, you can specify a list of runtime options that establish characteristics of the environment. This is done before the actual execution of any of your application code. Another example is using an assembler termination user exit to request a dump after your application has terminated with an abend.

In most cases, you do not need to modify any user exit to run your application. Instead, you can accept the IBM-supplied default versions of the exits, or the defaults as defined by your installation. To do so, run your application normally and the default versions of the exits are invoked. You may also want to read the sections "User exits supported under z/OS Language Environment" on page 838 and "Order of processing of user exits" on page 838, which provide an overview of the user exits and describe when they are invoked.

If you plan to modify either of the user exits to perform some specific function, you must link the modified exit to your application before running, as described in "Using installation-wide or application-specific user exits" on page 839. In addition, the sections "Using the Assembler user exit" on page 840 and "High level language user exit interface" on page 852 describe the respective user exit interfaces to which you must adhere to change an assembler or HLL user exit.

PL/I and C/370 compatibility

For more information on compatibility support for the IBMBXITA and IBMFXITA assembler user exits, see "PL/I and C/370 compatibility” on page 851. Refer to
User exits supported under z/OS Language Environment

z/OS Language Environment provides two user exit routines, one written in assembler and the other in an HLL. You can find sample jobs containing these user exits in the SCEESAMP sample library. The user exits supported by z/OS Language Environment are shown in Table 343.

Table 343. User exits supported under z/OS Language Environment

<table>
<thead>
<tr>
<th>Name</th>
<th>Type of User Exit</th>
<th>When Invoked</th>
</tr>
</thead>
<tbody>
<tr>
<td>CEEBXITA</td>
<td>Assembler user exit</td>
<td>Enclave initialization</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Enclave termination</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Process termination</td>
</tr>
<tr>
<td>CEEBINT</td>
<td>HLL user exit. CEEBINT can be written in z/OS XL C, PL/I, z/OS Language Environment-conforming assembler, or in C++ (see restrictions in “Order of processing of user exits”).</td>
<td>Enclave initialization</td>
</tr>
</tbody>
</table>

Order of processing of user exits

The location and order in which user exits are driven for your application are summarized in Figure 192.

In Figure 192, runtime user exits are invoked in the following sequence:

1. Assembler user exit is invoked for enclave initialization.
The assembler user exit (CEEBXITA) is invoked very early during the initialization process, before the enclave initialization is complete. Early invocation of the assembler exit allows the enclave initialization code to benefit from any changes that might be contained in the exit. If runtime options are provided in the assembler exit, the enclave initialization code is aware of the new options.

2. Environment is established.

3. HLL user exit is invoked.

The HLL initialization exit (CEEBINT) is invoked just before the invocation of the application code. In z/OS Language Environment, this exit can be written in z/OS XL C, PL/I, z/OS Language Environment-conforming assembler, or z/OS XL C++. However, you can only write CEEBINT in z/OS XL C++ if the following conditions are met:

- CEEBINT must be declared with C linkage. That is, it must be declared with extern "C". If you are using C, you must compile your application code with the RENT compile-time option.
- You must bind your application code with the z/OS binder.
- CEEBINT must be used as an application-specific user exit, rather than as an installation-wide user exit (See “Using installation-wide or application-specific user exits” for more information).
- The following information must be coded so that SMP/E can maintain the CSECT and properly link the intended user exit:
  
  ```c
  #pragma map(CEEBINT,"CEEBINT")
  ```

The HLL initialization exit cannot be written in COBOL, although COBOL applications can use this HLL user exit. At the time when CEEBINT is invoked, the runtime environment is fully operational and all z/OS Language Environment-conforming HLLs are supported.

4. Main routine is invoked.

5. Main routine returns control to caller.

6. Environment is terminated.

7. Assembler user exit is invoked for termination of the enclave.

   CEEBXITA is invoked for enclave termination processing after all application code in the enclave has completed, but before any enclave termination activity.

8. Assembler user exit is invoked for termination of the process.

   CEEBXITA is invoked again when the z/OS Language Environment process terminates.

Although both the assembler and HLL exits are invoked for initialization, they do not perform exactly the same functions. See “CEEBXITA behavior during enclave initialization” on page 840 and “High level language user exit interface” on page 852 for a detailed description of each exit.

z/OS Language Environment provides the CEEBXITA assembler user exit for termination but does not provide a corresponding HLL termination user exit.

### Using installation-wide or application-specific user exits

IBM offers default versions of CEEBXITA and CEEBINT. You can use the IBM-supplied default version of either exit, or you can customize CEEBXITA or CEEBINT for use on an installation-wide basis. When CEEBXITA or CEEBINT is linked with the z/OS Language Environment initialization/termination library routines during installation, it functions as an installation-wide user exit.
Finally, you can customize CEEBXITA or CEEBINT yourself for use on your application. When CEEBXITA or CEEBINT is linked in your program, it functions as an application-specific user exit. The application-specific exit is used only when you run that application. The installation-wide assembler user exit is not executed.

To obtain an application-specific user exit, you must explicitly include it at bind time in the application using a binder INCLUDE control statement. Any time that the application-specific exit is modified, it must be relinked with the application.

The assembler user exit interface is described in "Assembler user exit interface" on page 842. The HLL user exit interface is described in "High level language user exit interface" on page 852.

Using the Assembler user exit

The assembler user exit CEEBXITA tailors the characteristics of the enclave before it is established. CEEBXITA must be written in assembler language because an HLL environment may not yet be established when the exit is invoked. CEEBXITA is driven for enclave initialization and enclave termination regardless of whether the enclave is the first enclave in the process or a nested enclave. CEEBXITA can differentiate easily between first and nested enclaves. For more information about nested enclaves, see z/OS Language Environment Programming Guide.

CEEBXITA behaves differently depending on when it is invoked, as described in the following sections.

Using sample Assembler user exits

Sample assembler user exit programs are distributed with z/OS Language Environment. You can use them and modify the code for the requirements of your own application. Choose a sample program appropriate for your application. Table 344 lists the assembler exit user programs that are delivered with z/OS Language Environment.

<table>
<thead>
<tr>
<th>Example User Exit</th>
<th>Operating System</th>
<th>Language (if Language Specific)</th>
</tr>
</thead>
<tbody>
<tr>
<td>CEEBXITA</td>
<td>MVS (default)</td>
<td></td>
</tr>
<tr>
<td>CEEBXITC</td>
<td>TSO</td>
<td></td>
</tr>
<tr>
<td>CEECXITA</td>
<td>CICS (default)</td>
<td></td>
</tr>
<tr>
<td>CEEBX05A</td>
<td>MVS</td>
<td>COBOL</td>
</tr>
</tbody>
</table>

Notes:
1. CEEBXITA and CEECXITA are the defaults on your system for MVS and CICS, if z/OS Language Environment is installed at your site without modification.
2. The source code for CEEBXITA, CEEBXITC, CEECXITA, and CEEBX05A can be found on MVS in the sample library SCEESAMP.
3. CEEBX05A is an example user exit program for COBOL applications on z/OS.

CEEBXITA behavior during enclave initialization

The CEEBXITA assembler user exit is invoked before enclave initialization is performed. You can use it to help guide the establishment of the environment in which your application runs. For example, you can allocate data sets in the assembler user exit. The user exit can interrogate program parameters supplied in the JCL and change them if desired. In addition, you can specify runtime options
in the user exit using the CEEAUE_OPTIONS field of the assembler interface (see "Assembler user exit interface" on page 842 for information about how to do this).

CEEBXITA performs no special tasks other than to return control to z/OS Language Environment initialization.

**CEEBXITA behavior during enclave termination**

The CEEBXITA assembler exit is invoked after the user code for the enclave has completed, but before the occurrence of any enclave termination activity. For example, CEEBXITA is invoked before the storage report is produced (if one was requested), before data sets are closed, and before HLLs are invoked for enclave termination. In other words, the assembler user exit for termination is invoked when the environment is still active.

The assembler user exits allow you to request an abend. Under z/OS (as well as TSO and CICS), you can also request a dump to assist in problem diagnosis. Note that termination activities have not yet begun when the user exit is invoked. Thus, the majority of storage has not been modified when the dump is produced.

It is possible to request an abend and dump in the enclave termination user exit for all enclave-terminating events.

Example code that shows how to request an abend and dump when there is an unhandled condition of severity 2 or greater can be found in the member CEEBX05A in the sample library.

**CEEBXITA behavior during process termination**

The CEEBXITA assembler exit is invoked after:

- All enclaves have terminated.
- The enclave resources have been relinquished.
- Any z/OS Language Environment-managed files have been closed.
- Debug Tool has terminated.

This allows you to free files at this time, and it presents another opportunity to request an abend.

During termination, CEEBXITA can interrogate the z/OS Language Environment reason and return codes and, if necessary, request an abend with or without a dump. This can be done at either enclave or process termination.

The IBM-supplied CEEBXITA performs no special tasks other than to return control to z/OS Language Environment termination.

**Specifying abend codes to be percolated by z/OS Language Environment**

The assembler user exit, when invoked for initialization, can return a list of abend codes that are to be percolated by z/OS Language Environment. On non-CICS systems, this list is contained in the CEEAUE_A_AB_CODES field of the assembler user exit interface. (See "Assembler user exit interface" on page 842.) Both system abends and user abends can be specified in this list.

When TRAP(ON) is in effect, and the abend code is in the CEEAUE_A_AB_CODES list, z/OS Language Environment percolates the abend. Normal z/OS Language Environment condition handling is never invoked to handle these abends. This
feature is useful when you do not want z/OS Language Environment condition handling to intervene for some abends, for example, when IMS issues abend code 777.

When TRAP(OFF) is specified, the condition handler is not invoked for any abends or program interrupts. The use of TRAP(OFF) is not recommended; refer to z/OS Language Environment Programming Reference for more information.

**Actions taken for errors that occur within the Assembler user exit**

If any errors occur during the enclave initialization user exit, the standard system action occurs because z/OS Language Environment condition handling has not yet been established.

Any errors occurring during the enclave termination user exit lead to abnormal termination (through an abend) of the z/OS Language Environment environment.

If a program check occurs during the enclave termination user exit and TRAP(ON) is in effect, the application ends abnormally with ABEND code 4044 and reason code 2. If a program check occurs during the enclave termination exit and "TRAP(OFF)" has been specified, the application ends abnormally without additional error checking support. z/OS Language Environment provides no condition handling; error handling is performed by the operating system. The use of TRAP(OFF) is not recommended; refer to z/OS Language Environment Programming Guide for more information.

z/OS Language Environment takes the same actions as described above for program checks during the process termination user exit.

**Assembler user exit interface**

You can modify CEEBXITA to perform any function desired, although the exit must have the following attributes after you modify it:

- The user-supplied exit must be named CEEBXITA.
- The exit must be reentrant.
- The exit must be capable of executing in AMODE(ANY) and RMODE(ANY).
- The exit must be relinked with the application after modification (if you want an application-specific user exit), or relinked with z/OS Language Environment initialization/termination routines after modification (if you want an installation-wide user exit).

If a user exit is modified, you are responsible for conforming to the interface shown in [Figure 193 on page 843](#). This user exit must be written in assembler.
When the user exit is called, register 1 (R1) points to a word that contains the address of the CXIT control block. The high order bit is on. The CXIT control block contains the following fullwords:

**CEEAUE_LEN (input parameter)**

A fullword integer that specifies the total length of this control block. For z/OS Language Environment, the length is 48 bytes.

**CEEAUE_FUNC (input parameter)**

A fullword integer that specifies the function code. In z/OS Language Environment, the following function codes are supported:

1. initialization of the first enclave within a process
2. termination of the first enclave within a process
3. nested enclave initialization
4. nested enclave termination
5. process termination

The user exit should ignore function codes other than those numbered from 1 through 5.

**CEEAUE_RETC (input/output parameter)**

A fullword integer that specifies the return or abend code. CEEAUE_RETC has different meanings depending on the flag CEEAUE_ABND:

- As an input parameter, this fullword is the enclave return code.
- As an output parameter, if the flag CEEAUE_ABND is on, this fullword is interpreted as an abend code that is used when an abend is issued. (This could be either an EXEC CICS ABEND or an SVC 13.)
- If the flag CEEAUE_ABND is off, this fullword is interpreted as the enclave return code that might have been modified by the exit.

See z/OS Language Environment Programming Guide for more information about how z/OS Language Environment computes return and reason codes.

**CEEAUE_RSNC (input/output parameter)**
A fullword integer that specifies the reason code for CEEAUE_RETC.
- As an input parameter, this fullword is the z/OS Language Environment return code modifier.
- As an output parameter, if the flag CEEAUE_ABND is on, CEEAUE_RETC is interpreted as an abend reason code that is used when an abend is issued. (This field is ignored when an EXEC CICS ABEND is issued.)
- If the flag CEEAUE_ABND is off, this fullword is the z/OS Language Environment return code modifier that might have been modified by the exit.

See z/OS Language Environment Programming Guide for more information about how z/OS Language Environment computes return and reason codes.

**CEEAUE_FLAGS (input/output parameter)**
Contains four flag bytes. CEEBXITA uses only the first byte but reserves the remaining bytes. All unspecified bits and bytes must be zero. The layout of these flags is shown in Figure 194.

<table>
<thead>
<tr>
<th>Byte 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>x.....</td>
</tr>
<tr>
<td>0.....</td>
</tr>
<tr>
<td>1.....</td>
</tr>
<tr>
<td>x.....</td>
</tr>
<tr>
<td>.0.....</td>
</tr>
<tr>
<td>.1.....</td>
</tr>
<tr>
<td>.x.....</td>
</tr>
<tr>
<td>..0</td>
</tr>
</tbody>
</table>

**Figure 194. CEEAUE_FLAGS format**

Byte 0 (CEEAUE_FLAG1) has the following meaning:

**CEEAUE_ABTERM (input parameter)**
When 0FF, the enclave terminates normally (severity 0 or 1 condition).
When ON, the enclave terminates with the z/OS Language Environment return code modifier of 2 or greater. This could, for example, indicate that a condition of severity 2 or greater was raised that was unhandled.

**CEEAU\_ABND (output parameter)**
When OFF, the enclave terminates without an abend. CEEAU\_RETC and CEEAU\_RSNC are placed in register 15 and register 0 and returned to the enclave creator.

When ON, the enclave terminates with an abend. Thus, CEEAU\_RETC and CEEAU\_RSNC are used by z/OS Language Environment in the invocation of the abend. While executing in CICS, an EXEC CICS ABEND command is issued.

CEEAU\_RSNC is ignored under CICS. The TRAP option does not affect the setting of CEEAU\_ABND.

**CEEAU\_DUMP (output parameter)**
When OFF and you request an abend, an abend is issued without requesting a system dump. When ON and you request an abend, an abend is issued requesting a system dump.

**CEEAU\_STEPS (output parameter)**
When OFF and you request an abend, one is issued to abend the entire task. When ON and you request an abend, one is issued to abend the step.

**Note:** This fullword is ignored under CICS.

**CEEAU\_A-CC-PLIST (input/output parameter)**
A fullword pointer to the parameter address list of the application program.

As an input parameter, this fullword contains the register 1 value passed to the main routine. The exit can modify this value, and the value is then passed to the main routine. If runtime options are present in the invocation command string, they are stripped off before the exit is called.

If the parameter inbound to the main routine is a character string, CEEAU\_A-CC-PLIST contains the address of a fullword address that points to a halfword prefixed string. If this string is altered by the user exit, the string must not be extended in place.

**CEEAU\_WORK (input parameter)**
Contains a fullword pointer to a 256-byte work area that the exit can use. On entry, it contains binary zeros and is doubleword-aligned. This area does not persist across exits.

**CEEAU\_OPTIONS (output parameter)**
On return, this field contains a fullword pointer to the address of a halfword length prefixed character string that contains runtime options. These options are only processed for enclave initialization. When invoked for enclave termination, this field is ignored.

These runtime options override all other sources of runtime options except those that are specified as non-overrideable.

Under CICS, the STACK runtime option cannot be modified using the assembler user exit.

**CEEAU\_USERWD (input/output parameter)**
Contains a fullword whose value is maintained without alteration and passed
to every user exit. On entry to the enclave initialization user exit, it is zero. Thereafter, the value of the user word is not altered by z/OS Language Environment or any member libraries. The user exit can change the value of this field and z/OS Language Environment maintains this value. This allows a user exit to initialize the fullword and pass it to subsequent user exits.

**CEE_A_AB_CODES (output parameter)**
During the initialization exit, this field contains the fullword address of a table of abend codes that the z/OS Language Environment condition handler percolates while in the (E)STAE exit. Therefore, the application is not given the opportunity to field the abend. The table consists of:
- A fullword count of the number of abend codes that are to be percolated
- A fullword for each of the particular abend codes that are to be percolated

The abend codes can be user abend codes or system abend codes. User abend codes are specified by F'uuu'. For example, if you wanted user abend 777 to be percolated, an F'777' would be coded. System abend codes are specified by X'00sss000'. Avoid specifying the values 0C0 through 0CF as 'sss'. Language Environment ignores values between OCO and OCF. No abend is percolated, and z/OS Language Environment condition handling semantics are in effect.

This function is not enabled under CICS.

**CEE_FBCODE (input parameter)**
Contains the fullword address of the condition token with which the enclave terminated. If the enclave terminates normally (that is, not because of a condition), the condition token is zero.

**CEE_PAGE (input/output parameter)**
Usage of this field is related to PL/I BASED variables that are allocated storage outside of AREAs. You can indicate whether storage should be allocated on a 4K-page boundary. You can specify the minimum number of bytes of storage that you want allocated. Your allocation request must be an exact multiple of 4K. The IBM-supplied default setting for CEE_PAGE is 32768 (32K).

If CEE_PAGE is set to zero, PL/I BASED variables can be placed on other than 4K-page boundaries.

CEE_PAGE is honored only during enclave initialization (that is, when CEE FUNC is 1 or 3).

The offset of CEE_PAGE under z/OS Language Environment is different from the offset of 1BMXITA under OS PL/I Version 2 Release 3.

**Parameter values in the Assembler user exit**
The parameters described in the following sections contain different values depending on how the user exit is used. Possible values are shown for the parameters based on how the assembler user exit is invoked.

**First enclave within process initialization—entry**

**CEE_LEN**
48

**CEE_FUNC**
1 (first enclave within process initialization function code).

**CEE_RETC**
0
The register 1 value from the operating system.

Address of a 256-byte work area of binary zeros.

0

0

The register 1 value from the operating system.

Address of a 256-byte work area of binary zeros.

0

0

Minimum number of storage bytes to be allocated for PL/I BASED variables (default = 32768).

First enclave within process initialization—return

CEEAE_RETC

0, or if CEEAE_ABND = 1, the abend code.

CEEAE_RSNC

0, or if CEEAE_ABND = 1, the reason code for CEEAE_RETC.

CEEAE_FLAGS

CEEAE_ABND = 1 if an abend is requested, or 0 if the enclave should continue with termination processing.

CEEAE_DUMP = 1 if the abend should request a dump.

CEEAE_STEPS = 1 if the abend should abend the step, or 0 if the abend should abend the task.

CEEAE_A-CC-PLIST

Register 1, used as the new parameter list.

CEEAE_OPTIONS

Pointer to the address of a halfword prefixed character string containing runtime options, or 0.

CEEAE_USERWD

Value of CEEAE_USERWD for all subsequent exits.

CEEAE_A_AB_CODES

Pointer to the abend code table, or 0.

CEEAE_PAGE

User-specified PAGE value. Minimum number of storage bytes to be allocated for PL/I BASED variables (default = 32768).

First enclave within process termination—entry

CEEAE_LEN

48

CEEAE_FUNC

2 (first enclave within process termination function code).

CEEAE_RETC

Return code issued by the application that is terminating.
CEEAUER_SNC
Reason code that accompanies CEEAUER_RETC.

CEEAUER_FLAGS
CEEAUER_ABTERM = 1 if the application is terminating with the z/OS Language Environment return code modifier of 2 or greater, or 0 otherwise.
CEEAUER_ABND = 0
CEEAUER_DUMP = 0
CEEAUER_STEPS = 0

CEEAUER_WORK
Address of a 256-byte work area of binary zeros.

CEEAUER_USERWD
Return value from the previous exit.

CEEAUER_FBCODE
Feedback code causing termination.

First enclave within process termination—return
CEEAUER_RETC
If CEEAUER_ABND = 0, the return code placed in register 15 when the enclave terminates.
If CEEAUER_ABND = 1, the abend code.

CEEAUER_RSNC
If CEEAUER_ABND = 0, the enclave reason code.
If CEEAUER_ABND = 1, the abend reason code.

CEEAUER_FLAGS
CEEAUER_ABND = 1 if an abend is requested, or 0 if the enclave should continue with termination processing.
CEEAUER_DUMP = 1 if the abend should request a dump.
CEEAUER_STEPS = 1 if the abend should abend the step, or 0 if the abend should abend the task.

CEEAUER_USERWD
The value of CEEAUER_USERWD for all subsequent exits.

Nested enclave initialization—entry
CEEAUER_LEN
48
CEEAUER_FUNC
3 (nested enclave initialization function).
CEEAUER_RETC
0
CEEAUER_RSNC
0
CEEAUER_FLAGS
0
CEEAUER-A-CC-PLIST
The register 1 value discovered in a nested enclave creation.
CEEAUER_WORK
Address of a 256-byte work area of binary zeros.
CEEAEU_USERWD
    The return value from previous exit.

CEEAEU_FBCODE
    0

CEEAEU_PAGE
    Minimum number of storage bytes to be allocated for PL/I BASED variables (default = 32768).

Nested enclave initialization—return
CEEAEU_RETC
    0, or if CEEAEU_ABND = 1, the abend code.

CEEAEU_RSNC
    0, or if CEEAEU_ABND = 1, the reason code for CEEAEU_RETC.

CEEAEU_FLAGS
    CEEAEU_ABND = 1 if an abend is requested, or 0 if the enclave should continue with termination processing.
    CEEAEU_DUMP = 1 if the abend should request a dump.
    CEEAEU_STEPS = 1 if the abend should abend the step, or 0 if the abend should abend the task.

CEEAEU-A-CC-PLIST
    Register 1 used as the new parameter list.

CEEAEU_OPTIONS
    Pointer to a fullword address that points to a halfword prefixed string containing runtime options, or 0.

CEEAEU_USERWD
    The value of CEEAEU_USERWD for all subsequent exits.

CEEAEU_A_AB_CODES
    Pointer to the abend code table, or 0.

CEEAEU_PAGE
    User-specified PAGE value. Minimum number of storage bytes to be allocated for PL/I BASED variables (default = 32768).

Nested enclave termination—entry
CEEAEU_LEN
    48

CEEAEU_FUNC
    4 (termination function).

CEEAEU_RETC
    Return code issued by the enclave that is terminating.

CEEAEU_RSNC
    Reason code that accompanies CEEAEU_RETC.

CEEAEU_FLAGS
    CEEAEU_ABTERM = 1 if the application is terminating with the z/OS Language Environment return code modifier of 2 or greater, or 0 otherwise.
    CEEAEU_ABND = 0
    CEEAEU_DUMP = 0
    CEEAEU_STEPS = 0
**CEEAU_WORK**  
Address of a 256-byte work area of binary zeros.

**CEEAU_USERWD**  
Return value from previous exit.

**CEEAU_FBCODE**  
Feedback code causing termination.

**Nested enclave termination—return**

**CEEAU_RETC**  
If CEEAU_ABND = 0, the return code from the enclave.  
If CEEAU_ABND = 1, the abend code.

**CEEAU_RSNC**  
If CEEAU_ABND = 0, the enclave reason code.  
If CEEAU_ABND = 1, the enclave reason code.

**CEEAU_FLAGS**  
CEEAU_ABND = 1 if an abend is requested, or 0 if the enclave should continue with termination processing.  
CEEAU_DUMP = 1 if the abend should request a dump.  
CEEAU_STEPS = 1 if the abend should abend the step, or 0 if the abend should abend the task.

**CEEAU_USERWD**  
Value of CEEAU_USERWD for all subsequent exits.

**Process termination—entry**

**CEEAU_LEN**  
48

**CEEAU_FUNC**  
5 (process termination function).

**CEEAU_RETC**  
Return code presented to the invoking system in register 15 that reflects the value returned from the first enclave within process termination.

**CEEAU_RSNC**  
Reason code accompanying CEEAU_RETC that is presented to the invoking system in register 0 and reflects the value returned from the first enclave within process termination.

**CEEAU_FLAGS**  
CEEAU_ABTERM = 1 if the last enclave is terminating abnormally (that is, the z/OS Language Environment return code modifier is 2 or greater). This reflects the value returned from the first enclave within process termination (function code 2).  
CEEAU_ABND = 1 if an abend is requested, or 0 if the enclave should continue with termination processing first enclave within process termination (function code 2).  
CEEAU_DUMP = 0  
CEEAU_STEPS = 0

**CEEAU_WORK**  
Address of a 256-byte work area of binary zeros.
**CEEAU_USERWD**
The return value from previous exit.

**CEEAU_FBCODE**
The feedback code causing termination.

**Process termination—return**

**CEEAU_RETC**
If CEEAU_ABND = 0, the return code from the process.
If CEEAU_ABND = 1, the abend code.

**CEEAU_RSNC**
If CEEAU_ABND = 0, the reason code for CEEAU_RETC from the process.
If CEEAU_ABND = 1, reason code for the CEEAU_RETC abend reason code.

**CEEAU_FLAGS**
CEEAU_ABND = 1 if an abend is requested, or 0 if the enclave should continue with termination processing.
CEEAU_DUMP = 1 if the abend should request a dump.
CEEAU_STEPS = 1 if the abend should abend the step, or 0 if the abend should abend the task.

**CEEAU_USERWD**
The value of CEEAU_USERWD for all subsequent exits.

**PL/I and C/370 compatibility**
The following OS PL/I Version 2 Release 3 assembler user exits are supported for compatibility under z/OS Language Environment:

- IBMBXITA (MVS Batch version)
- IBMFXITA (CICS version)

For more information about IBMBXITA see *PL/I for MVS & VM Compiler and Run-Time Migration Guide*. These user exits are available only under C, not C++.

Default versions of the above exits are not supplied under z/OS Language Environment; instead, z/OS Language Environment supplies a default version of CEEBXITA. Table 345 describes the order of precedence if the IBMBXITA and IBMFXITA user exits are found in the same root program with CEEBXITA.

<table>
<thead>
<tr>
<th>CEEBXITA Present</th>
<th>IBMBXITA Present under MVS Batch, IBMFXITA Present under CICS</th>
<th>Exit Driven</th>
</tr>
</thead>
<tbody>
<tr>
<td>No</td>
<td>No</td>
<td>Default version of CEEBXITA</td>
</tr>
<tr>
<td>Yes</td>
<td>No</td>
<td>CEEBXITA</td>
</tr>
<tr>
<td>No</td>
<td>Yes</td>
<td>IBMBXITA under MVS Batch; IBMFXITA under CICS</td>
</tr>
<tr>
<td>Yes</td>
<td>Yes</td>
<td>CEEBXITA</td>
</tr>
</tbody>
</table>

CXIT_FUNC in IBMBXITA will map to CEEBXITA as follows:
- CXIT_FUNC = 1 when IBMBXITA is invoked for initial enclave initialization or nested enclave initialization
• CXIT_FUNC = 2 when IBMBXITA is invoked for initial enclave termination or
  nested enclave termination

CXIT_USERWD in IBMBXITA will persist across enclaves (for example, in system() calls).

**High level language user exit interface**

z/OS Language Environment provides CEEBINT, an HLL user exit, for enclave
initialization. You can code CEEBINT in z/OS XL C, PL/I, or z/OS XL C++ (subject
to the restrictions in [Order of processing of user exits” on page 838], or z/OS
Language Environment-conforming assembler. The HLL user exit cannot be written
in COBOL. COBOL programmers can use an HLL exit written in z/OS XL C, PL/I,
z/OS Language Environment-conforming assembler, z/OS XL C++ (again, subject
to the restrictions in [Order of processing of user exits” on page 838], or default to
the IBM-supplied default HLL user exit.

The HLL enclave initialization exit is invoked after the enclave has been
established, after the Debug Tool initial command string has been processed, and
prior to the invocation of compiled code. When invoked, it is passed a parameter
list that conforms to the z/OS Language Environment definition. The parameters
are all fullwords and are defined as follows:

**Number of arguments in parameter list (input)**
  A fullword binary integer.
  • On entry: Contains 7.
  • On exit: Not applicable.

**Return code (output)**
  A fullword binary integer.
  • On entry: 0.
  • On exit: Able to be set by the exit, but not interrogated by z/OS Language
    Environment.

**Reason code (output)**
  A fullword binary integer.
  • On entry: 0
  • On exit: Able to be set by the exit, but not interrogated by z/OS Language
    Environment.

**Function code (input)**
  A fullword binary integer.
  • On entry: 1, indicating the exit is being driven for initialization.
  • On exit: Not applicable.

**Address of the main program entry point (input)**
  A fullword binary address.
  • On entry: The address of the routine that gains control first.
  • On exit: Not applicable.

**User word (input/output)**
  A fullword binary integer.
  • On entry: Value of the user word (CEEAUE_USERWD) as set by the assembler
    user exit.
  • On exit: The value set by the user exit, maintained by z/OS Language
    Environment and passed to subsequent user exits.
Exit List Address (output)
A fullword binary integer reserved for future use. This allows the establishment of one or more user exits when the enclave user exit sets this field to a list of user exits. Currently, only one user exit is supported in z/OS Language Environment.

A_Exits
The address of the exit list control block, Exit_list.
- On entry: 0.
- On exit: 0, unless you establish a hook exit, in which case you would set this pointer and fill in relevant control blocks. The control blocks for Exit_list and Hook_exit are shown in the following figure.

As supplied, CEEBINT has only one exit defined that you can establish: the hook exit described by the Hook_exit control block. This exit gains control when hooks generated by the PL/I compile-time TEST option are executed. You can establish this exit by setting appropriate pointers (A_Exits to Exit_list to Hook_exit). Figure 195 illustrates the Exit_list and Hook_exit control blocks.

![Figure 195. Exit_list and hook_exit control blocks](image)

The control block Exit_list exit contains the following fields:

Exit_list_len
The length of the control block. It must be 1.

Exit_list_hooks
The address of the Hook_exit control block.
The control block for the hook exit must contain the following fields:

**Hook_exit_len**
- The length of the control block.

**Hook_exit_rtn**
- The address of a routine you want invoked for the exit. When the routine is invoked, it is passed the address of this control block. Because this routine is invoked only if the address you specify is nonzero, you can turn the exit on and off.

**Hook_exit_fnccode**
- The function code with which the exit is invoked. This is always 1.

**Hook_exit_retcode**
- The return code set by the exit. You must ensure it conforms to the following specifications:
  - 0  Requests that Debug Tool be invoked next
  - 4  Requests that the program resume immediately
  - 16 Requests that the program be terminated

**Hook_exit_rsnrncode**
- The reason code set by the exit. This is always zero.

**Hook_exit_userwd**
- The user word passed to the user exits.

**Hook_exit_ptr**
- An exit-specific user word.

**Hook_exit_reserved**
- Reserved.

**Hook_exit_dsa**
- The contents of register 13 when the hook was executed.

**Hook_exit_addr**
- The address of the hook instruction executed.

**Usage requirements**
1. The user exit must not be a main-designated routine. For example, it cannot be a z/OS XL C or a z/OS XL C++ main() function.
2. The HLL exit routines must be linked with compiled code. If you do not provide an initialization user exit, an IBM-supplied default, which returns control to your application, is linked with the compiled code.
3. The exit cannot be written in COBOL/370.
4. The exit should be coded so that it returns for all unknown function codes.
5. z/OS XL C constructs such as the exit(), abort(), raise(SIGTERM), and raise(SIGABRT) functions terminate the enclave.
6. A PL/I EXIT or STOP statement terminates the enclave.
7. Use the callable service IBMHKS to turn hooks on and off. For more information about IBMHKS, see PL/I for MVS & VM Compiler and Run-Time Migration Guide.
8. When CEEBINT is written in C/C++, the following information must be coded so that SMP/E can maintain the CSECT and properly link the intended user exit:
   
   #pragma map(CEEBINT,"CEEBINT")
Chapter 51. Using the z/OS XL C MultiTasking Facility

This chapter describes how to use the MultiTasking Facility (MTF) with z/OS XL C. It explains how to organize, code, compile, link, and run a program using MTF. It also lists restrictions while using MTF.

MTF is a facility available under z/OS that can be used by application programs to improve turnaround time on multiprocessor and attached-processor configurations. When a program uses MTF on such a system, the elapsed time required to run the program can be reduced. You can run tasks, which can run independently of each other, simultaneously.

MTF is easy to use and requires very little knowledge of the multitasking capabilities upon which it depends. From the programmer's perspective, multitasking facilities are available through the library functions of z/OS XL C. Because of this simplicity, it is easy to introduce MTF to existing applications and code new MTF applications to gain the benefits of multitasking.

Notes:

1. Except for a few differences, the MTF support for z/OS XL C is the same as for the equivalent FORTRAN multitasking facilities. MTF is not supported under CICS, IMS, DB2, C++, or z/OS UNIX. In addition, IPA is not supported in an MTF environment.
2. XPLINK is not supported in an MTF environment.
3. AMODE 64 applications are not supported in an MTF environment.

Organizing a program with MTF

MTF takes advantage of the multitasking capabilities of the operating system to enable a single z/OS XL C application program to use more than one processor of a multiprocessing configuration simultaneously. The z/OS operating system organizes all work into units called tasks. These tasks are used by the operating system to assign work to the processors of the multiprocessor configuration.

MTF's facilities allow a single z/OS XL C application to be organized so it can be run in a main task and in one or more subtasks. As a result of this organization, the system can schedule these individual tasks to run simultaneously. This can significantly reduce the elapsed time needed to run the program.

When a program is organized in this manner, the main task runs the part of the program that controls the overall processing. This part is referred to as the main task program throughout this manual.

The subtasks run the portions of the program that can run independently of the main task program and of each other. These portions of the program are referred to as parallel functions. The library functions provided by MTF allow the main task program to schedule parallel functions and allow them to run independently. Parallel functions are queued for execution on the next available subtask. Scheduling a parallel function does not require that there be a free subtask at the time of the scheduling. MTF allows the main task program to schedule more parallel functions than there are actual MVS subtasks.
The parallel functions are coded the same way as normal C functions, with the exception of a few rules discussed in “Designing and coding applications for MTF” on page 863. In particular, parallel functions cannot issue MTF calls.

MTF applications are link-edited as two separate load modules: a main task load module (containing the main task program) and a parallel load module (containing all parallel functions).

z/OS XL C provides the following MTF functions (for details, refer to z/OS XL C/C++ Runtime Library Reference):

- \texttt{vinit()} to initialize the MTF environment
- \texttt{vtsched()} to schedule parallel functions to run
- \texttt{vtsyncro()} to synchronize the completion of parallel functions
- \texttt{vtterm()} to terminate all executing parallel functions.

z/OS XL C also provides the header file \texttt{mtf.h}, which must be included in your main task program if you are going to use the MTF facilities. The \texttt{mtf.h} header file contains the macros \texttt{MTF\_ANY} and \texttt{MTF\_ALL}, as well as the error-return codes and prototypes for library functions.

**Ensuring computational independence**

To use multitasking successfully, the parallel functions must have \textit{computational independence}. This means that no data modified by either the main task program or a parallel function is examined or modified by a parallel function that might be running simultaneously.

[Figure 196] is a graphic example of hypothetical data in an array subscripted by I, J, and K. Each of the three divisions of the box represents a section of the array that can be operated on independently of the other sections. The same parallel function could be scheduled three times, with each instance of the function processing one of the three sections of the array.

![Figure 196. Computational independence](image)

Your application may not have computational independence along the same subscript axis of K, as in this picture. The divisions might have been along one of the other subscript axes, I or J. Also, the computational independence in your application may not fall into neat, box-like divisions.
It is also possible to have computational independence that is not based on sections of the same array, but rather on separate arrays (perhaps with completely different types of data), the values of which do not depend on each other. In this case, separate parallel functions could be scheduled, with each function processing its own unique data.

Computational independence also applies to input/output files. One parallel function should not use a file while another is updating it. However, different functions can successfully read the same file. No single file pointer should be used concurrently by multiple parallel functions, because the behavior is undefined in such a case.

**Running a C program without MTF**

The following diagrams illustrate the way a z/OS XL C program runs without multitasking. The program and its functions must run in a strictly sequential manner, function following function, using one processor at a time. Consequently, your program takes more elapsed time to complete than it would if it could use several processors at the same time.

For example, as Figure 197 shows, without multitasking, the z/OS XL C program and all its functions can only use one processor. While running, your program may be switched back and forth between the processors, but it can only run on one processor at a time.

![Diagram of a C program running without MTF](image)

*Figure 197. Example of a C program running without MTF*
Running a C program with MTF

To illustrate the concept of multitasking, this section shows three examples of running a z/OS XL C program with MTF. These examples show programs using:

- One parallel function
- Two different functions
- Two or more instances of the same function

Each example provides an illustration of how the processors are used and how the program is organized to accomplish the particular use of the processors.

Running a C program with one parallel function

If your C program uses MTF, the main task program and a computationally-independent parallel function can run concurrently.

**Processor use**

In Figure 199 on page 859, only the function suba has computations that can be done independently of the main task program, which includes the C main program plus its functions. Note that the arrows to Processor 1 and Processor 2 are for illustration only. The main task program could have run on Processor 2 and the parallel function, suba, on Processor 1; in fact, while they run, they may be switched between the processors.
Sample program
With the appropriate MTF request, the parallel function, suba, is scheduled to run in a subtask. As Figure 200 on page 860 shows, the MTF functions perform the following tasks:

1. `tinit()` names the parallel load module `plmod` and specifies one subtask.
2. `tsched()` schedules the parallel function `suba` to run. `suba` is computationally-independent of the main task.
3. At this point, `tsyncro()` makes the main task program wait until `suba` is finished before the main task program continues.

Figure 198. Processor usage with one parallel function
Running a C program with two different parallel functions

If your C program uses MTF, the main task program and several different computationally-independent parallel functions can run concurrently.

**Processor use**

In Figure 201, functions suba and subc are independent of each other and of the main task program. The arrows to Processors 1, 2, and 3 are for illustration only. The main task program and the parallel functions could run on any of the processors.
Sample program

Figure 201 on page 860 shows a sample program. The logic is similar to that for only one parallel function and can be extended to as many parallel functions as necessary to complete the logic of the program.

```
#include <mtf.h>
... 
tinit("plmod",2);
... 
tsched(MTF_ANY, "suba", arglist1);
... 
tsched(MTF_ANY, "subc", arglist2);
... 
subb();
... 
tsyncro(MTF_ALL);
... 
Function subb()
... 
```

1. \texttt{tinit()} names the parallel load module \texttt{plmod} and specifies two subtasks.
2. Each call to \texttt{tsched()} schedules one of the parallel functions, passing different data to each for processing. \texttt{suba} and \texttt{subc} are computationally-independent parallel functions.
3. At this point, \texttt{tsyncro()} makes the main task program wait until both \texttt{suba} and \texttt{subc} are finished before the main task program continues its processing.

\textbf{z/OS XL C with multiple instances of the same parallel function}

If your C program uses MTF, the main task program and multiple instances of the same parallel function can run concurrently.

\textbf{Processor use}

In Figure 203 on page 862, parallel function \texttt{suba} has data you can divide, so two instances of \texttt{suba} run independently of the main task program and of each other.
Sample program

As Figure 204 on page 863 shows, the MTF functions perform the following tasks:

1. `tinit()` names the parallel load module `plmod` and specifies two subtasks.

2. Each call to `tsched()` schedules one instance of the parallel function to run and supplies separate data to be processed by that instance of `suba`. The data to be processed by each instance of the parallel function could be two different sections of the same array. Both instances of `suba` are computationally-independent of the main task program and each other, because each instance of `suba` processes different data.

3. At this point, `tsyncro()` makes the main task program wait until all instances of `suba` finish before the main task program continues.
Designing and coding applications for MTF

You can use the following steps when preparing a z/OS XL C application to work with MTF:

1. Identify computationally-independent code
2. Create parallel functions
3. Insert calls to parallel functions in main task program

New programs can be designed to use MTF, and existing programs can be reconstructed.

**Step 1: Identifying computationally-independent code**

The first step in adapting an application program for MTF is to identify groups of computations that can be performed in parallel. To produce correct results, the computations that are done in parallel must be computationally-independent. This is further explained under "Ensuring computational independence" on page 856.

**Step 2: Creating parallel functions**

After the segments of code that are computationally-independent are identified, they are separated from the main task program and placed in parallel functions. A parallel function is coded as a normal C function that follows several rules required for correct operation with MTF. Besides to data independence, there are rules for:

- Parallel functions
- Calling other functions
- Separate storage for separate modules
- Passing data

Figure 204. Sample program using multiple instances of the same parallel function
• Input and output
• Exception/signal handling
• Function termination

Parallel functions
• A parallel function must be written only in C.
• The return value of a parallel function must be void. If a parallel function attempts to return a value, the behavior will be undefined.
• External parallel function names must be 8 characters or shorter in length and will be uppercased.

Calling other functions
• A parallel function may actually be coded as a series of functions that call one another. All of these functions operate in the parallel function’s subtask environment and must follow the rules of a parallel function except that they can be written in assembler as well as C, and they can have return values.
• A parallel function cannot call the MTF library functions tinit(), tsched(), tsyncro(), or tterm(). Such calls can only be used in the main task.

Separate storage for separate modules
• Every MTF application consists of two modules: the main task module which runs on the main task, and the parallel module that runs on the subtask(s). Each task (main or sub) has its own unique runtime storage structure consisting of ISA, heap, and residual storage. Each task has:
  – Separate writable static (whether reentrant or not)
  – Separate library-internal storage (for example, file and storage management control blocks)
  – Separate exception and signal-handling environment (for example, errno, __amrc)
• Usually, functions must abide by the restrictions inherent in this arrangement. The remaining rules in this section mostly arise from this arrangement.
Passing data

A parallel function is always invoked in its last-used state. If, for example, a parallel function has defined a static variable with an initializer, then the variable has that value the first time the parallel function executes on a given task. Should the value be modified, the modification is available the next time that parallel function is run only if the function is scheduled to the same task. If

---

**Notes:**

1. Each task has private and separate storage structure that leads to most of the parallel function idiosyncrasies:
   - All file operations from same task.
   - Storage must be `malloc()` or `free()`d from same task.
   - Independent signal handling environments.
2. MTF library functions are only operational in the main task.
3. `call/return` used for invocation within a task.
4. MTF only supports parallel load modules in a PDS. Parallel load modules in a PDSE are NOT supported.

*Figure 205. Basic MTF layout*
you don't schedule the parallel function to the same task, you cannot depend upon residual values from previous invocations of the function.

- Data can be passed between the main task program and parallel functions, and between parallel functions by passing a pointer to the storage area as a parameter. Care must be taken to ensure that the data remains valid and available until completion of the particular parallel function instance being scheduled.

- If heap storage is obtained on a given task, it must be freed on that task and no other. Other tasks may be given access to that storage by passing pointers but no other task can use that pointer to free the storage.

**Input/Output**

- File pointers must not be shared across subtasks. A given file pointer must only be used (for file access and closing) on the same task on that it was created (using fopen()). File pointers must be utilized as a serial resource. z/OS XL C does not protect against misuse, and a program will have unpredictable behavior if this rule is not enforced.

- Each parallel function updates (writes or changes) a file as if it had complete control over the file; therefore, there should be no simultaneous read or update of a given file while any function on any task is updating that file (even if separate file pointers are used).

- Memory files cannot be shared across subtasks.

**Exception/Signal handling**

- The parallel functions on the subtasks run with TRAP(ON) runtime option, and each has a signal handling environment entirely independent from that of each other task. All signals are initialized to default handling on each task, and can be modified for a given task only through a signal statement from a parallel function on that task.

- All signal interrupts are eligible to be raised from the operating system or by the raise() function during execution of parallel functions. All signals, however, require special handling in the case of parallel functions because of the requirement that parallel functions always return normally. Signals must either be ignored or a handler must be established that does not terminate the program. If these signals are left to default handling or a handler is established that terminates the program, MTF will treat this as an abnormal termination of the parallel function.

**Function termination**

- Parallel functions run as called functions (from EDCMTFS, the z/OS XL C library supplied main function for parallel modules) and must terminate by simple return (to EDCMTFS). For more information on EDCMTFS, see "Creating the parallel functions load module" on page 873.

- Termination with exit() and abort() calls is invalid because these functions interfere with EDCMTFS operation and they are treated by MTF as abnormal terminations.

- On the first valid call to MTF (tsched(), tsyncro(), tterm()) from the main task program after a parallel function has abnormally terminated (via exit()/abort() or otherwise) MTF will:
  - Abort all parallel functions scheduled or in progress
  - Remove the MTF environment
  - Return ETASKABND on that MTF call
A subsequent tterm() call is unnecessary and will simply return EINACTIVE. A tinit() can be reissued, but depending on the severity of the condition that caused the ETASKABND, the tinit() may or may not be successful.

Step 3: Inserting calls to parallel functions

In the main task, insert a call to tinit() to initialize the MTF environment before any other MTF function call, or after tterm() is invoked. Replace each segment of code that was identified for parallel computation with a call to tsched() which schedules the corresponding parallel function. If more parallel function instances are scheduled than tasks are currently available, the additional instances are queued for subsequent execution in the order in which they were scheduled. They are queued for any task or to a particular task according to the task_id parameter supplied on the tsched() call. If parallel operation is to be achieved by scheduling the same function multiple times with different data, the function call may be placed within a loop.

The arguments passed to the parallel function may be:

- A variable
- An array element
- An array name
- A constant
- A structure

The following items must not be used as the arguments supplied to the parallel function using tsched():

- Function pointers
- A pointer to data or storage that will be modified or released before a tsync().

After inserting calls to the parallel functions, insert a call to tsync() wherever the program requires that any subtask, one particular subtask, or all of the subtasks have finished executing the parallel functions previously scheduled to them. As the last MTF call, insert a call to tterm() before to exit/return from the main task program to remove the MTF environment.

To properly use MTF from the main task program it is necessary to include the mtf.h header file before to the first MTF call in your program. MTF calls themselves can be issued from non-main as well as main functions within the main task program, subject only to the restrictions already described above. MTF calls, however, can only be issued from C functions and not from functions written in any other language.

The next sections show examples of how to change existing C programs to use MTF following the steps just outlined.

Changing an application to use MTF

The following examples show how to change an application to use MTF by creating parallel functions and inserting calls to these functions.

Example 1

Figure 206 on page 868 shows a computation of the dot product on two long one-dimensional arrays of data. The processing within the loop structure may be separated so that the dot product is not a result of serial calculations but a result of parallel calculations. This is because the first part of the array is not dependent on
the results computed in any other section of the array. Thus the calculations are therefore computationally independent of each other, and can be performed at the same time.

---

double dotprod(double *a, double *b, int len)
{
    int i;
    double res = 0;
    for (i=0; i < len; ++i)
        res += *a++ * *b++;
    return(res);
}

---

Figure 206. Identifying Computationally-Independent Code

Create parallel functions
The segments of the program that have been identified to run as parallel functions are then recoded as new z/OS XL C functions. In this case, there will be one parallel function, multiple instances of which will be scheduled. The parallel function corresponding to the code in Figure 206 now looks like Figure 207.

---

void pdotprod(double *a, double *b, int len, int m, int n, double *pres)
/* m = the section of the array */
/* n = the number of subtasks. n must be a factor of len */
{
    int i, from, to;
    *pres = 0;
    /* Determine which section of the array to operate on */
    from = (m-1) * len / n;
    to = (m * len) / n;
    /* Calculate the partial result on part of the array */
    for (a+= from, b+=from, i=from; i < to; ++i)
        *pres += *a++ * *b++;

---

Figure 207. Sample code as a parallel function

The variables to and from are used to determine on which part of the array the parallel function is to perform.

Insert calls to parallel functions
The segments of the program that have been removed to form parallel functions are replaced by calls to these new parallel functions. For the sample code in Figure 206, sub:exph. is scheduled for each subtask that will be used at run time. In order to do this, the computations controlled by the k index must be divided so that each instance of the function sub operates on a different part of the original range of the k variable. See Figure 208 on page 869 for an example of how two instances of a parallel function can be scheduled.
Also, within the main task program, the subtasks must be initialized and eventually terminated as shown in Figure 209.

```
#include <mtf.h>

double dotprod(double *a, double *b, int len)
{
    int i;
    double res = 0;
    double pres[MAXTASK];

    /* Schedule the parallel functions according to */
    /* how many subtasks exist */
    for (i=1; i < n ; ++i)
        tsched(MTF_ANY,"pdotprod",a,b,len,i,n,&pres[i-1]);

    /* Perform the calculations on the last part of the array */
    pdotprod(a,b,len,n,n,&pres[n-1]);

    /* Wait until all of the partial results are determined */
    tsyncro(MTF_ALL);

    /* Add all the partial results to determine the final dot product*/
    for (i=0; i < n; ++i)
        res += pres[i];

    return(res);
}
```

**Figure 208. Scheduling instances of a parallel function**

Also, within the main task program, the subtasks must be initialized and eventually terminated as shown in Figure 209.

```
#include <mtf.h>

int main(void)
{
    /* other code */
    /* Attach and initialize a subtask */
    tinit(load_sub_name, n);

    result = dotprod(vector1,vector2,len);

    /* Terminate subtasks */
    tterm();
    /* more code */
}
```

**Figure 209. Main task program to call dot product function**

**Example 2**

Not all application programs contain parallelism within the iterations of a loop structure. The following example illustrates parallel computations that appear as different segments of code in the original program. Also illustrated is the use of pointer arguments for passing data, and I/O operations to files in parallel functions.

**Figure 210 on page 870** (program CCNGMT1) shows two calls to the same function that performs the dot product on the values in two files of data. The values are
read from each file and the function performs the dot product upon these values. The loop ends when the end of either file is reached. The two computations are independent of each other and thus can be performed simultaneously in two different parallel functions.

/* MTF example 2 */
#include <stdio.h>

void fdotprod(char *fn1, char *fn2)
{
    int i, res1;
    double result=0, val1, val2;
    FILE *file1, *file2;
    file1 = fopen(fn1, "r");
    file2 = fopen(fn2, "r");
    while (1)
    {
        res1 = fscanf(file1, "%lf", &val1);
        res1 += fscanf(file2, "%lf", &val2);
        if (res1 != 2)
            break;
        result += val1 * val2;
    }
    if (res1 == 1)
        printf("Error: Files of unequal lengthn");
    else
        printf("Result: %lfn", result);
}

int main(void)
{
    fdotprod("a.input", "b.input");
    fdotprod("c.input", "d.input");
    return(0);
}

Figure 210. Sample code to be changed to use MTF

Create parallel functions
The fdotprod routine is identified as a parallel function so it is recoded as a new C function in a separate file. Data is passed from the main function to the parallel functions by means of pointer arguments. The main task program (CCNGMT2) is shown in Figure 211 on page 871. The parallel functions are shown in Figure 212 on page 872 (sample program CCNGMT3).
/* MTF example 2 */
/* part 2 of 2-other file is CCNGMT1 */
#include <stdio.h>
#include <mtf.h>

int main(void)
{
  tinit("plmod", 2);
  tsched(MTF_ANY, "fdotprod", "a.input", "b.input");
  tsched(MTF_ANY, "fdotprod", "c.input", "d.input");
  tsyncro(MTF_ALL);
  tterm();
  return(0);
}

void fdotprod(char *fn1, char *fn2)
{
  int i, res1;
  double result=0, val1, val2;
  FILE *file1, *file2;
  file1 = fopen(fn1, "r");
  file2 = fopen(fn2, "r");
  while(1)
  {
    res1 = fscanf(file1, "%lf", &val1);
    res1 += fscanf(file2, "%lf", &val2);
    if (res1 != 2)
      break;
    result += val1 * val2;
  }
  if (res1 == 1)
    printf("Error: Files of unequal length\n");
  else
    printf("Result: %lf\n", result);
}

Figure 211. Sample code (main routine)
Compiling and linking programs that use MTF

Programs that use MTF run using two MVS load modules: a load module that contains the main task program, and a load module that contains the parallel functions. You compile and link-edit the main task program in the same procedure as non-MTF C programs. The parallel function is compiled in the same procedure as non-MTF C programs and is linked with EDCMTFS.

Creating the main task program load module

The main task program load module is the load module that first receives control when MVS starts running your program. It is the load module named in the PGM keyword of the EXEC statement. This load module contains your application’s C main() function plus all other functions that are to run as part of the main task. The MTF functions can be invoked from any of the C functions contained in the main task load module and do not necessarily have to be invoked from the C function called main().

The procedures that you usually use to compile and link-edit a z/OS XL C program can be used to create the main task program load module. For example, the following JCL sequence (see Figure 213 on page 873) uses the standard z/OS XL C cataloged procedure EDCCL to compile and link-edit the C source for the main task program (stored in data set USERPGM.C(MTASKPGM)) and create a main task program load module named MTASKPGM in data set USERPGM.LOAD.

Figure 212. Sample code (routine to create parallel functions)
Creating the parallel functions load module

The parallel functions load module is the load module named in the call to the MTF library function \texttt{tinit()}. This single load module contains all of your main task program’s parallel functions. It must not contain any user’s \texttt{main()} programs. \texttt{z/OS} XL C itself provides the \texttt{EDCMTFS} module to act as the \texttt{main()} function in the parallel module. \texttt{EDCMTFS} controls processing of the parallel functions as they are scheduled (by way of \texttt{tsched()} calls) to the subtasks. The source code for the \texttt{EDCMTFS} module is included in Figure 215 on page 874.

Note: The executable module for parallel function program must be a load module (in a PDS data set), created using the linkage editor (and prelinker if required due to the presence of C++ code or C code compiled with the RENT option). The MTF library functions used to access the parallel functions are not compatible with a program object executable module (in a PDSE data set).

The procedures that you usually use to compile and link-edit a \texttt{z/OS} XL C program must be modified such that the library module \texttt{CEESTART} will be the entry point of the parallel functions load module.

When you link-edit this load module, include the following linkage editor control statements:

\begin{verbatim}
INCLUDE SYSLIB(EDCMTFS)
ENTRY CEESTART
\end{verbatim}

For example, the JCL sequence in Figure 214 uses the standard \texttt{z/OS} XL C cataloged procedure \texttt{EDCCL} to compile and link-edit the C source for the parallel functions and create a parallel functions load module named \texttt{PLMOD} in data set \texttt{USERPGM.LOAD}. This load module contains the module \texttt{EDCMTFS}, and has \texttt{EDCMTFS} as the load module’s entry point.

\begin{verbatim}
//MTASKPGM EXEC EDCCL,
// INFILE='CBC.SCCNSAM(CCNGMT2)',
// OUTFILE='USERPGM.LOAD(CCNGMT2),DISP=SHR'
/*
//PFUNC EXEC EDCCL,
// INFILE='CBC.SCCNSAM(CCNGMT3)',
// OUTFILE='USERPGM.LOAD(PLMOD),DISP=SHR'
//LKED.SYSLIN DD
   INCLUDE SYSLIB(EDCMTFS)
   ENTRY CEESTART
/*
\end{verbatim}

*Figure 214. Sample JCL to compile and link parallel functions*

Note: First, we have a step that compiles and link-edits the main task program.

The addressing mode is subject to normal consideration as described in the \texttt{z/OS Language Environment Programming Guide}. 
Specifying the linkage-editor option
Do not specify the NE linkage-editor option when link-editing the parallel functions load module. MTF cannot schedule parallel functions that are contained in a load module link-edited with the NE option.

Modifying runtime options
You can alter the #pragma runopts options STACK and HEAP within the EDCMTFS module for each subtask, but you must recompile the module under the same name. The source code for EDCMTFS is shown in Figure 215.

```c
//********** Modify the isa/isainc/heap subparameters in the following line */
// as required to meet your needs. Ensure that your version (compiled+/
// and linked) is then accessed in your link-edit of the parallel */
// module in place of the prebuilt EDCMTFS found in SCEELKED. */
//******************************************************************************
#pragma runopts(STACK(8K,4K,ANY,FREE),HEAP(4K,4K,ANY,FREE))
//******************************************************************************
/* The following lines must remain unmodified to ensure proper */
/* operation of MTF. */
//******************************************************************************
#pragma runopts(TRAP(ON),RPTSTG(OFF),
 (STAE,SPIE,NOREPORT,NOTEST,\
 ARGPARSE,REDIR,NOEXECOPS)
 int main(int argc, char **argv) { return tsetsubt(argc,argv); }
```

Figure 215. Source code for EDCMTFS

You can also add a #pragma runopts statement with the LIBRARY and VERSION options to EDCMTFS, if required.

Running programs that use MTF
To run your program, use the usual MVS JCL for z/OS XL C programs, plus a few additional JCL statements that are required to run MTF.

STEPLIB DD statement
You must ensure that the library containing the load modules is specified on the STEPLIB DD statement in your JCL, as well as the other libraries usually specified, as follows:

```c
//STEPLIB DD DSN=user.dsn,DISP=SHR
```

user.dsn
name of the load module library that contains the parallel functions load module. The parallel functions load module (parallel_loadmod_name), specified on the call to tinit(), must be in this data set. You must allocate the ddname EDCMTF to the user.dsn data set as well as adding user.dsn to the STEPLIB concatenation list.

DD statements for standard streams
For standard streams, MTF assigns a unique runtime output file to each parallel function. These output files contain diagnostic messages that the library can issue while the parallel functions are running. They also contain output directed to the standard streams (stderr and stdout) by parallel functions and input from the standard stream stdin.
Because these files are automatically allocated while the program is running, you need not supply DD statements for them unless you wish to override the default device type or other file characteristics. The default device type is a terminal in TSO or SYSOUT=* in batch.

If you do supply DD statements, use the following ddnames:
- stdinstn for files containing input for operations such as getc()
- stderrstn for files containing diagnostic messages
- stdoutstn for files containing output from operations such as printf()

Where stn is the 2-digit subtask number; that is, 01, 02, 03, and so on. Thus, for example, if you had four subtasks and the first two used printf() functions, you would use the ddnames stdout01, stdout02, stderr01, stderr02, stderr03, and stderr04.

Example of JCL
An example of the runtime JCL to run a program that uses MTF is shown in Figure 216. This figure shows the JCL that is unique to running MTF, as well as the other JCL the program would typically require. (Some programs might require additional DD statements.)

```
//GO  EXEC  PGM=MTASKPGM
//STEPLIB DD DSN=USERPGM.LOAD,DISP=SHR
//STDIN01 DD DSN=USERPGM.INPUT,DISP=SHR
//STDOUT02 DD SYSOUT=S,DCB=(RECFM=F)
```

Figure 216. Example runtime JCL

MTASKPGM is the name of the main task program load module, and is the load module that gets control when MVS first starts running the program. In this example, this load module is contained in data set USERPGM.LOAD, which is referred to by the STEPLIB DD statement. USERPGM.LOAD also contains the parallel functions.

The STDIN01 DD statement specifies the data set that contains the program’s input data for the first task. The STDOUT02 DD statement specifies that printed output aside from runtime error messages from the second subtask is to be written to SYSOUT class S and that the record format is to be fixed-length. These DD statements are necessary only if you do not want to accept the defaults.

Debugging programs that use MTF
Debug Tool can be used to interactively debug your main task program. It cannot, however, be used to debug your parallel functions.

Avoiding undesirable results when using MTF
To prevent undesirable results, be aware of the following concerns and restrictions:
- MTF only supports parallel load modules in a PDS. Parallel load modules in a PDSE are NOT supported.
- Do not update a file with one task if the other tasks read the same file. Files can be destroyed if this is attempted.
- The following products should not be used from the main task or any subtasks while MTF is active:
  - Information Management System (IMS)
The CICS command level interface

The following products should not be used from subtasks while MTF is active but can be used from the main task:

- Data Window Services (DWS)
- Interactive System Productivity Facility (ISPF)
- Graphical Data Display Manager (GDDM)

All library functions can be issued from the main task program.

The following library functions should not be issued from parallel functions (see "Function termination" on page 866):

- exit()
- abort()
- atexit()

The following library functions can be used with some restrictions from parallel functions:

- setjmp()/longjmp() can be used from within any task/subtask but must not be used across tasks. That is, the stack environment saved via setjmp() on a given task may be restored by a longjmp() from that task but from no other task.
- setlocale()/localeconv() are only effective within a task. Each task has its own distinct locale information. Thus setlocale()/localeconv() issued from one task have no effect on such functions issued from other tasks.
- tmpnam() may produce identical file names across tasks and should be restricted to being invoked from a single task (subtask or main task).
- rand()/srand() produce entirely independent series of pseudorandom integers on each task.

All file manipulation functions (such as fopen()/fread()/...) - were identified earlier under the rules for parallel functions in "Designing and coding applications for MTF" on page 863. These functions can only be used on the same task.

Note: When opening files under MTF, you incur additional overhead when fopen() and freopen() are called. This overhead would normally be performed at the first read or write to the stream and will not affect the performance of a program that does indeed perform at least one read or write to the stream.

- fetch()/release() must only be issued from the same task.
- free() must be issued on the same task as the malloc()/calloc()/realloc() functions were issued. Note also that a realloc() must be issued in the same task as the malloc().
- signal()/raise() also identified earlier under the rules for parallel functions in "Designing and coding applications for MTF" on page 863. Basically, each task has its own distinct interrupt environment. Thus signal()/raise() issued from one task have no effect on the operation of any other task.
- PL/I and COBOL interlanguage calls must not be made from parallel functions.
- Busy waits (loops that iterate until a flag is changed by a cooperating task) violate the requirement for computational independence. In particular, they can result in deadlock because of the scheduling algorithm used by MVS. They must be avoided.
Part 7. Programming with Other Products

This part contains the following programming product information:

- Chapter 52, “Using the CICS Transaction Server (CICS TS),” on page 879
- Chapter 53, “Using Cross System Product (CSP),” on page 905
- Chapter 54, “Using Data Window Services (DWS),” on page 919
- Chapter 55, “Using DB2 Universal Database,” on page 921
- Chapter 56, “Using Graphical Data Display Manager (GDDM),” on page 929
- Chapter 57, “Using the Information Management System (IMS),” on page 935
- Chapter 58, “Using the Query Management Facility (QMF),” on page 943
Chapter 52. Using the CICS Transaction Server (CICS TS)

This chapter describes how to develop XL C/C++ programs for the CICS Transaction Server for z/OS (CICS TS). You can find more information about the general features of z/OS Language Environment and CICS in z/OS Language Environment Programming Guide.

For information on using CSP/AD or CSP/AE under CICS, see Chapter 53, “Using Cross System Product (CSP),” on page 905.

Notes:
1. AMODE 64 applications are not supported in a CICS TS environment.
2. As of this publication, the standalone CICS translator does not recognize the C compiler’s support for alternative locales and coded character sets. Therefore, you should write all your CICS C code in coded character set IBM-1047 (APL 293).
3. XPLINK applications are not supported under CICS prior to CICS TS 3.1.
4. As of V1R2, a non-XPLINK Standard C++ Library DLL allows support for the Standard C++ Library in the CICS subsystem. For further information, see “Binding z/OS C/C++ Programs” in z/OS XL C/C++ User’s Guide.

Developing XL C/C++ programs for the CICS environment

When developing a program to run under CICS TS you must complete all of the following actions:
1. Prepare CICS for use with z/OS Language Environment
2. Design and code the CICS program
3. Translate and compile the translated source for reentrancy
4. Prelink and link all object modules with the CICS stub
5. Define the program to CICS

Preparing CICS for use with z/OS Language Environment

This section gives general instructions on enabling z/OS Language Environment to use a new CICS TS environment or to add z/OS Language Environment to an existing CICS TS environment. For more detailed information on CICS TS, refer to the CICS documentation, which is available at:

After CICS TS has been installed on your system, you must perform the following tasks:

- Create a CICS TS environment if one does not already exist. This involves creating a CICS System Definition (CSD), journals, and a Global Catalog Set (GCD).
- Copy CEECCICS from SCEERUN to an Authorized Program Facility (APF) data set. The data set should be concatenated in the STEPLIB when CICS is cold started.
- Create the CESO and CESE Transient Data Queues. Sample Destination Control Table (DCT) definitions are supplied in SCEESAMP(CEECSDT).
• Add required definitions to the CSD. Sample CSD definitions are provided in SCEESAMP(CEECCSD). These sample definitions create a group called CEE, which must be added to the installation LIST.

• Add SCEERUN and SCEECICS to the DFHRPL concatenation.

The C runtime event handler module CEEEV003 is required for CICS TS support (in addition to the z/OS Language Environment interface modules). CEEEV003 must be link-edited as AMODE=31, RMODE=ANY, and loaded above the 16M line.

If you will be using the I/O stream library, complex mathematics, collection, or Application Support Class DLLs provided with the z/OS XL C++ compiler, you must define these DLLs in the CSD, and the CBC.SCLBDLL library must be added to the DFHRPL concatenation. Sample CICS CSD definitions can be found in CBC.SCLB3JCL(CLB3YCSDD).

Designing and coding for CICS
This section describes what you must do differently when designing and coding a z/OS XL C/C++ program for CICS TS, such as using EXEC CICS commands in your code, using input and output, using z/OS XL C/C++ functions, managing storage, using interlanguage calls, and exception handling.

Using the CICS command-level interface
CICS TS provides a set of commands to access the CICS transaction server. The format of a CICS command is:

EXEC CICS function [option[[arg]]]...;

In the following CICS command, the function is SEND TEXT. This function has 4 options: FROM, LENGTH, RESP and RESP2. In this case, each of the options takes one argument.

EXEC CICS SEND TEXT FROM(mymsg)
   LENGTH(mymsglen)
   RESP(myresp)
   RESP2(myresp2);

For further information on the EXEC CICS interface and a list of available CICS TS functions, refer to CICS documentation, which is available at:

When you are designing and coding your CICS TS application, remember the following:
• The EXEC CICS command and options should be in uppercase. The arguments follow general C or C++ conventions.
• Before any EXEC CICS command is issued, the EXEC Interface Block (EIB) must be addressed by the EXEC CICS ADDRESS EIB command.
• z/OS XL C/C++ does not support the use of EXEC CICS commands in macros.

The example program in Figure 217 on page 882 (CCNGCI1) shows the use of several EXEC CICS commands to perform various tasks.

1 Initialize the CICS interface
Access the storage passed from the caller
Handle unexpected abends
and
I/O to RRDS files
and
Requesting and formatting time
Example illustrating how to use EXEC CICS commands (Part 1 of 3)

Figure 217. Example illustrating how to use EXEC CICS commands
void check_4_down_status( char *status_record )
{
    unsigned char uptime[9];
    unsigned char update[9];
    char curabs[8];
    unsigned char curtime[9];
    unsigned char curdate[9];

    long int vsmrrn;
    signed short int vsmlen;
    signed long int dnresp;
    signed long int dnresp2;

    strncpy((status_record+8),update,8);
    strncpy((status_record+16),uptime,8);
    update[8] = '\0';
    uptime[8] = '\0';

    /* get the current time/date */
    EXEC CICS ASKTIME ABSTIME(curabs)
            RESP(dnresp)
            RESP2(dnresp2);

    if (dnresp != DFHRESP(NORMAL))
        unexpected_prob("Unexpected prob with ASKTIME",dnresp);

    /* format current date to YYMMDD */
    EXEC CICS FORMATTIME ABSTIME(curabs)
            YYMMDD(curdate)
            TIME(curtime)
            TIMESEP
            DATESEP;

    if (dnresp != DFHRESP(NORMAL))
        unexpected_prob("Unexpected prob with FORMATTIME",dnresp);

    curdate[8] = '\0';
    curtime[8] = '\0';

    if ((atoi(curdate) > atoi(update))
        ||
        (atoi(curdate) == atoi(update) && atoi(curtime) >= atoi(uptime)))
    {
        strcpy(status_record,"OK ");
        vsmrrn = 1;
        vsmlen = FILE_LEN;

        /* update the first record to OK */
        EXEC CICS REWRITE FILE("STATFILE")
                FROM(status_record)
                LENGTH(vsmlen)
                RESP(dnresp)
                RESP2(dnresp2);

        if (dnresp != DFHRESP(NORMAL))
            {
                printf("The dnresp from REWRITE = %d\n", dnresp);
                printf("The dnresp2 from REWRITE = %d\n", dnresp2);
                unexpected_prob("Unexpected prob with WRITE",dnresp);
            }
}

Example illustrating how to use EXEC CICS commands (Part 2 of 3)
printf("%s %s Changed status from DOWNTME to OK\n",curdate,
curt ime);
}
}

void sendmsg( char* status_record )
{
    long int msgresp, msgresp2;
    char outmsg[80];
    int outlen;

    if (memcmp(status_record,"OK\n",3)==0)
        strcpy(outmsg,"The system is available.");
    else if (memcmp(status_record,"DOWNTME\n",8)==0)
        strcpy(outmsg,"The system is down for regular backups.");
    else
        strcpy(outmsg,"SYSTEM PROBLEM -- call help line for details.");

    printf("%s\n",outmsg);
    outlen=strlen(outmsg);

    EXEC CICS SEND TEXT FROM(outmsg)
       LENGTH(outlen)
       RESP(msgresp)
       RESP2(msgresp2);

    if (msgresp != DFHRESP(NORMAL))
        unexpected_prob("Message output failed from sendmsg",71);
}

void unexpected_prob( char* desc, int rc)
{
    long int msgresp, msgresp2;
    int msglen;

    msglen = strlen(desc);

    EXEC CICS SEND TEXT FROM(desc)
        LENGTH(msglen)
        RESP(msgresp)
        RESP2(msgresp2);

    fprintf(stderr,"%s\n",desc);
    if (msgresp != DFHRESP(NORMAL))
        exit(99);
    else
        exit(rc);
}

Example illustrating how to use EXEC CICS commands (Part 3 of 3)

Using input and output

This section describes how to use z/OS XL C/C++ I/O with CICS TS. It describes the file and device support and the type of I/O used with CICS TS.

**Note:** You can set up a SIGIOERR handler to catch read or write system errors. See Chapter 18, “Debugging I/O programs,” on page 223 for more information.

**Standard stream support**

Under CICS, if you are using the z/OS XL C++ standard streams, note the following:

- cin is not supported under CICS.
cout maps to the Standard C I/O stream stdout.
cerr and clog both map to the C standard stream stderr.

stdout and stderr are assigned to transient data destinations (queues). The type of queue, intrapartition or extrapartition, is determined during CICS initialization. Intrapartition queues are used for queueing messages and data within a CICS region. Extrapartition queues are used to send data outside the CICS region or to receive data from outside the CICS region.

The transient data queues associated with stdout and stderr are CES0 and CESE respectively. z/OS XL C/C++ supports VA and VBA queues with an lrecl of at least 137 bytes.

Records sent to the transient data queues associated with stdout and stderr take the form of a message. The entire message record can be preceded by an ASA Standard control character. Figure 218 illustrates the recommended message format.

Figure 218. Format of data written to a CICS data queue

ASA is the carriage-control character.
terminal id is a 4-character terminal identifier.
transaction id 4-character transaction identifier
sp a space
Time Stamp date and time displayed in the format YYYYMMDDHHMMSS
data data that is output to the standard streams stdout and stderr

The following are sample messages of data written to a CICS data queue:

<table>
<thead>
<tr>
<th>ASA</th>
<th>terminal id</th>
<th>transaction id</th>
<th>sp</th>
<th>Time Stamp</th>
<th>sp</th>
<th>data</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>4</td>
<td>4</td>
<td>1</td>
<td>14</td>
<td>1</td>
<td>108</td>
</tr>
</tbody>
</table>

SAMATST1 19940401080523 Hello World - from transaction TST1!
BOBATST3 19940401112348 Hello World - from transaction TST3!
TEDATST2 19940401112348 Hello World - from transaction TST2!

Standard streams can only be redirected to, or from, memory files. Because only one transient data queue can be associated with each of stdout and stderr, these queues can contain output written in chronological order from many C and C++ programs. This output must be sorted as necessary into the desired sequence.

Full memory file support
The full set of C I/O library functions is supported under CICS TS for memory files. Memory files are created with the parameter type set to memory on the fopen() call. If you are using C++, you can also use the I/O stream library to create and access memory files. Hiperspace memory files are not supported.
Support for disk files and other devices
There is no support by the C I/O library or the I/O stream library for using disk files and other devices with CICS TS. I/O to access methods supported by CICS TS must use the CICS TS Application Programming Interface.

Using z/OS XL C/C++ library support
This section discusses restrictions and support for the z/OS XL C/C++ library with CICS.

Arguments to C or main()
When a z/OS XL C/C++ program is running under CICS TS, you cannot pass command line arguments to it. The values for argc and argv have the following settings:

```
argc  1
argv[0]  4-character CICS transaction ID
```

Runtime options
Command line runtime options cannot be passed in CICS. To specify runtime options in XL C/C++, you must include the #pragma runopts directive in the code. Figure 217 on page 882 shows how to do this. See z/OS Language Environment Programming Guide for information on other ways to supply runtime options when you are running under CICS TS.

Using packed decimal with CICS
The packed decimal data type is supported under CICS TS. However, the standalone CICS translator does not support packed decimal. CICS expects packed decimal streams to be passed to it as arrays of characters. If you want to manipulate these arrays as a packed decimal number, you should define the array of characters in union with the appropriate packed decimal definition. For information about how to define the data fields for the EXEC CICS commands you are using, refer to CICS documentation, which is available at:

```
```

Note: The z/OS XL C++ compiler does not support packed decimal data. Any program using the C or C++ character data type to handle packed decimal data must have its own functions for the manipulation of this data.

Locales
All locale functions are supported for locales that have been defined in the CSD. CSD definitions for the IBM-supplied locales are provided in SCEESAMP(CEECCSD). setlocale() returns NULL if the locales are not defined.

Code set conversion tables
The code set conversion tables that are used by the iconv() functions must be defined in the CSD.

POSIX
There is no support for POSIX functions that are not already defined as part of ANSI/ISO. z/OS UNIX is not supported under CICS.

Multitasking facility
MTF functions are not supported under CICS TS.

System programming C facilities
There is no support for the System Programming C facilities (SP C) under CICS TS.
SVC99 and dynamic allocation functions
svc99() and the dynamic allocation functions dynalloc(), dynfree(), and dyninit() are not supported under CICS TS. The svc99() function returns 0 if the input is NULL, otherwise the return value is undefined.

IMS
There is no support for the ctdli() function under CICS TS. If you call ctdli() under CICS TS, the return value is -1. For information about the CICS TS method to access IMS, refer the CICS documentation at:

Dump functions
The dump functions csnap(), cdump(), and ctrace() are supported under CICS TS. The output is sent to the CESE transient data queue. The dump can not be written if the queue does not have a sufficient LRECL. An LRECL of at least 161 is recommended.

Dynamic Linked Libraries (DLL)
All DLLs must be defined in the CSD.

fetch()
The fetch() function is supported under CICS TS. Modules to be fetched must be defined to the CSD and installed in the PPT.

release()
The release() function is supported under CICS TS.

system()
The system() function is not supported under CICS TS. However, there are two EXEC CICS commands that give you similar functionality:

EXEC CICS LINK
   This command enables you to transfer control to another program and return to the calling program later. See Figure 219 on page 891

EXEC CICS XCTL
   This command enables you to transfer control to another program. Control does not return to the caller after completion of the called program.

Time functions
All time functions are supported except the clock() function, which returns the value (time_t)(-1) if it is used under CICS TS.

iscics()
The iscics() function is an extension to the C library. It returns a non-zero value if your program is currently running under CICS. If your program is not running under CICS, iscics() returns the value 0. The following example shows how to use iscics() in your C or C++ program to specify non-CICS or CICS specific behavior.

```c
if (iscics() == 0)
   <non-CICS behavior>
else
   <CICS-specific behavior>
```

Floating point arithmetic
The simulation of extended precision floating point is not supported in CICS TS.
Program termination

A C or C++ program running under CICS will terminate when:

- An exit() function call or a return statement is issued in the C or C++ program. The atexit() list of functions is run when the C or C++ program terminates.

  Note: On return from a C or C++ application, the return statement or values passed by C or C++ through the exit() function are saved in the EIBRESP2 field of the EIB.

- An abend occurs and is not handled.

- An EXEC CICS RETURN is issued in your C or C++ program. The atexit() list of functions runs after these calls.

- The abort() function is started.

Storage management

A z/OS XL C/C++ program can acquire storage from and release storage to CICS TS either implicitly or explicitly.

Storage is acquired and released implicitly by the runtime environment. This storage is used for automatic, external, and static variables. External variables are valid until program completion.

Storage is acquired and released explicitly by the user with the C library functions malloc(), calloc(), realloc(), or free(), with z/OS Language Environment Callable Services (refer to z/OS Language Environment Programming Guide), with the C++ new and delete operators, or with the EXEC CICS commands EXEC CICS GETMAIN, or EXEC CICS FREEMAIN.

- If you request the storage by using the C functions malloc(), realloc(), or calloc() you must deallocate it by using C functions as well.

- If you request the storage by using z/OS Language Environment Callable Services, you must deallocate it by using z/OS Language Environment Callable Services.

- If you request the storage by using EXEC CICS GETMAIN, you must deallocate it by using EXEC CICS FREEMAIN.

- If you request storage using the C++ new operator, you must deallocate it by using the C++ delete operator.

All other combinations of methods of requesting and deallocating storage are unsupported and lead to unpredictable behavior.

Partial deallocations are not supported. All storage allocated at a given time must be deallocated at the same time.

Under the z/OS Language Environment library, z/OS XL C/C++ uses the z/OS Language Environment Callable Services to allocate and free storage. Refer to z/OS Language Environment Programming Guide for specific information on memory and storage manipulation in CICS.

The z/OS XL C/C++ library functions acquire all storage from the Extended Dynamic Storage Area (EDSA) unless you specify otherwise using the ANYHEAP, BELOWHEAP, HEAP, STACK, or LIBSTACK runtime options.
Storage that is acquired with the EXEC CICS GETMAIN command exists for the duration of the CICS task.

If your application is multi-threaded or often uses malloc(), realloc(), calloc(), and free(), you should consider using the HEAPPOOLS runtime option. Although storage requirements may increase, you can expect better performance.

Using ILC support

The z/OS Language Environment library supports a variety of different types of interlanguage calls (ILC) with CICS TS. For information on supported configurations, please refer to z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications.

Exception handling

You can use three different kinds of exception handlers when running C programs in a CICS TS environment: CICS exception handlers, z/OS Language Environment abend handlers, and C exception handlers. If you are using C++, you can use any of these three, or the C++ exception handling approach using try, throw, and catch. When a CICS condition is not handled under C++, the behavior of constructors and destructors for objects is undefined.

If the CICS command EXEC CICS HANDLE ABEND PROGRAM(name) was specified in the application, it will be called for any program exception that occurs (such as an operation exception or a protection exception) as well as for any EXEC CICS ABEND ABCODE(...) command that is run.

z/OS Language Environment provides facilities to set up a user handler. These facilities are discussed in detail in z/OS Language Environment Programming Guide.

In CICS TS, the C error handling facilities have almost the same behavior as discussed in Chapter 28, “Handling error conditions, exceptions, and signals,” on page 403. A signal raised with the raise() function is handled by its corresponding signal handler or the default actions if no handler is installed. If a program exception such as a protection exception occurs, it is handled by the appropriate C handler if no CICS or z/OS Language Environment handler is present.

When a C or C++ application is invoked by an EXEC CICS LINK PROGRAM(...), the invoked program inherits any handlers registered by EXEC CICS HANDLE ABEND PROGRAM(...) in the parent program. Any handlers registered in the child override the inherited handlers. C signal handlers are not inherited.

The following chart shows the process for handling abends in CICS TS.

Error handling in CICS

Procedure

1. Is this the result of a call to raise()?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 2</td>
</tr>
<tr>
<td>No</td>
<td>See 9 on page 890</td>
</tr>
</tbody>
</table>

2. Is SIG_IGN set for the signal?
<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 3</td>
</tr>
<tr>
<td>No</td>
<td>See 4</td>
</tr>
</tbody>
</table>

3. a. Resume at the next instruction.

4. Is z/OS Language Environment handler registered?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 5</td>
</tr>
<tr>
<td>No</td>
<td>See 6</td>
</tr>
</tbody>
</table>


6. Is a C or C++ handler established?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 7</td>
</tr>
<tr>
<td>No</td>
<td>See 8</td>
</tr>
</tbody>
</table>

7. a. Run C or C++ handler.

8. a. Default handling the program check and percolate to next stack frame.

9. Has EXEC CICS HANDLE ABEND been issued?

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Yes</td>
<td>See 10</td>
</tr>
<tr>
<td>No</td>
<td>See 11</td>
</tr>
</tbody>
</table>

10. a. Call z/OS XL C/C++-CICS interface for termination of program. CICS turns off signal and runs program in handler.

11. a. Continue at Step 005.

**Example of error handling in CICS**

The example program in Figure 219 on page 891 (CCNGCI2) shows how to handle errors when using z/OS XL C/C++ with CICS.
/* program : CHKSTAT */
/* transaction : called stand alone from transaction CHST */
/* is also used by other transactions to determine */
/* system status */

#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <signal.h>
#define FILE_LEN 40

void status_not_ok(int sig);
void unexpected_prob(char* desc, int rc);
volatile unsigned char status_record [41];

struct com_struct {
    int quiet;
} com_reg;

main (int argc, char *argv [])
{
    long int vsamrrn;
    signed short int vsamlen;
    signed long int myresp;
    signed long int myresp2;
    unsigned char status_downtime [41];

    if (strcmp(argv[0],"CHST") !=0) {
        printf("argv[0] = %s\n", argv[0]);
        com_reg.quiet = 1;
    } else
        com_reg.quiet = 0;

    Example illustrating error handling under CICS (Part 1 of 3)

    Figure 219. Example illustrating error handling under CICS
/* get addressability to the EIB first */
EXEC CICS ADDRESS EIB(dfheiptr);

EXEC CICS HANDLE ABEND PROGRAM("CATCHIT ");  
  signal(SIGUSR1, status_not_ok);   ①

EXEC CICS LINK PROGRAM("GETSTAT ")  ③
               RESP(myresp)
               RESP2(myresp2)
               COMMAREA(&com_reg)
               LENGTH(4);

/* check for failure in linked-to program */
if (myresp != DFHRESP(NORMAL)) {
    printf("The RESP of LINK = %d\n", myresp);
    printf("The RESP2 of LINK = %d\n", myresp2);
    unexpected_prob("CICS failure on EXEC CICS LINK\n",51);
}

if (myresp2 != 11)
    unexpected_prob("Unexpected rc from GETSTAT\n",myresp2);

vsamrrn = 1;
vsamrlen = FILE_LEN;

/* following READ for UPDATE is for test purpose only. */
EXEC CICS READ FILE("STATFILE")
         UPDATE
         INTO(status_record)
         RIDFLD(vsamrrn)
         RRN
         LENGTH(vsamrlen)
         RESP(myresp)
         RESP2(myresp2);

/* check for cics response - non-0 implies problem */
if (myresp != DFHRESP(NORMAL))
    unexpected_prob("Unable to read from file",52);

Example illustrating error handling under CICS (Part 2 of 3)
/* write DOWNTME back to file - for test purpose only */
strcpy(status_downtme,"DOWNTME");
EXEC CICS REWRITE FILE("STATFILE")
   FROM(status_downtme)
   LENGTH(vsamlen)
   RESP(myresp)
   RESP2(myresp2); 
if (myresp != DFHRESP(NORMAL)) { 
   printf("The dnresp from REWRITE = %d
", myresp);
   printf("The dnresp2 from REWRITE = %d
", myresp2);
   unexpected_prob("Unexpected prob with WRITE",myresp);
}
if (memcmp(status_record,"OK ",3) != 0)
   raise(SIGUSR1);
exit(11);
}
void unexpected_prob( char* desc, int rc)
{
    long int msgresp, msgresp2;
    int msglen;

    msglen = strlen(desc);
    EXEC CICS SEND TEXT FROM(desc)
       LENGTH(msglen)
       RESP(msgresp)
       RESP2(msgresp2);

    fprintf(stderr,"%s
",desc);
    if (msgresp != DFHRESP(NORMAL))
       exit(99);
    else
       exit(rc);
}
void status_not_ok( int sig ) 4
{
    if (memcmp(status_record,"DOWNSTR ",8) != 0)
       exit(22);
    else
       exit(33);
}

Example illustrating error handling under CICS (Part 3 of 3)

1. The program CATCHIT has been installed as the CICS abend handler. Because this CICS abend handler is installed, C exception handlers will only catch signals raised with the raise() function.

2. Install a C signal handler to catch the user defined signal SIGUSR1. This handler will only be called if raise(SIGUSR1) is run.

3. This command causes the flow of control to shift to a child program called GETSTAT. GETSTAT will inherit CHKSTAT’s CICS abend handler.

4. The C signal handler status_not_OK that was will be invoked if this line is run. The raise() function will not trigger the CICS abend handler.
ABEND codes and error messages under z/OS XL C/C++

For information on ABEND Codes and error messages used by the z/OS Language Environment library, refer to z/OS Language Environment Programming Guide and z/OS Language Environment Debugging Guide.

Coding hints and tips

- Do not use EXEC CICS commands in macros.
- Do not use EXEC CICS commands in header files. This makes the translation process much simpler.
- Do not set atexit() routines before an EXEC CICS XCTL. You will get unpredictable results.
- If you call fclose() or freopen() for a standard stream, you cannot redirect or reopen the link to the transient data queue. z/OS XL C/C++ does not provide a method of opening or reopening the transient data queues.
- The actual transient data queue is not closed when you call fclose() or freopen() for a standard stream; however, the transaction will lose access to the stream.
- You should not use the stdin stream unless you are redirecting it from a memory file.
- Closing the cout, cerr, or clog standard streams in a C++ application has the same effect as closing stdout or stderr.
- When CICS handlers (using EXEC CICS HANDLE ABEND PROG) are activated along with C or C++ signal handlers, the CICS handler is invoked when an abend occurs. The C or C++ signal handler that corresponds to that class of abends is ignored.

Note: The handler mentioned here is not a catch clause. It is a C signal handler exception registered by a C++ routine.

- If you do an EXEC CICS RETURN out of an atexit() routine, the resulting return code (RESP2) is undefined.

Translating and compiling for reentrancy

This section discusses translation of embedded CICS statements and provides examples. It also discusses reentrancy issues with respect to CICS.

Options for translating CICS statements

There are two options for translating CICS statements into C or C++ code: The z/OS XL C/C++ integrated CICS translator and the standalone CICS translator, a CICS TS utility.

z/OS XL C/C++ integrated CICS translator

If you are using CICS Transaction Server 3.1 or later, you can compile XL C/C++ source code with embedded CICS commands and keywords without using the CICS TS language translation utility if you use the CICS compiler option. You can embed comments and macros within the embedded CICS commands.

When you use the z/OS XL C/C++ integrated CICS translator, you might experience the following benefits:
- More seamless operation of C/C++ applications that run in the CICS environment, especially under UNIX System Services
- Improved program readability
• Easier application maintenance
• Tighter coupling between the translation and compilation phases
• A more unified development approach across z/OS XL C, z/OS XL C++, COBOL, and PL/I

For more information, refer to the CICS compiler option in z/OS XL C/C++ User’s Guide.

In general, source code that can be processed successfully by the standalone CICS translator will be compatible with the integrated CICS translator.

**Exception:** The standalone CICS translator does not recognize C/C++ macros. For this reason, a CICS command that is processed with the integrated CICS translator can either fail to translate or change semantically if it (coincidentally) contains an identifier that is identical to a macro that is active within the scope of the CICS command.

**Standalone CICS translator**
The CICS TS utility called the CICS language translator is still supported. This program translates the EXEC CICS statements into C or C++ code. In this document, the CICS language translator is referred to as the *standalone CICS translator*.

**Note:** If you are using C++, you must use the CPP translator option to indicate to the compiler that you are using the C++ language, rather than the C language. The use of the CPP parameter specifies that the translator is to translate z/OS XL C++ programs. Code translated without the CPP option or with a translator released before version 4.1 of CICS is not supported by the z/OS XL C++ compiler and will not compile.

The standalone CICS translator supplies a control block (DFHEIBLK) for passing information between CICS TS and the application program. C or C++ function references for the EXEC CICS commands are generated. The translation step is not required if you do not use EXEC CICS statements.

The standalone CICS translator does not evaluate preprocessor directives such as #include or #define. You should ensure that all EXEC CICS statements are translated.

**Translating example**
The samples in this section are valid for both the integrated CICS translator and the standalone CICS translator. [Figure 220 on page 896](CCNGCI3) shows pieces of C and C++ code before they are translated with the standalone CICS translator. [Figure 221 on page 897](CCNGCI3) shows the corresponding programs after translation.
These programs each contain two EXEC CICS commands to be translated by the standalone CICS translator. A single instance of the EXEC CICS ADDRESS EIB command is required before any other call to the EXEC CICS interface. In this case, the main program (see Figure 217 on page 882) issues the ADDRESS EIB command. Since the two pieces of code make up one program there is no need to ADDRESS the EIB again.

Figure 221 on page 897 shows how the programs appear after they are translated.
```c
#define __dfheitab 1
char *dfhlver = "LD TABLE DFHEITAB 320.";
unsigned short int dfheib0 = 0;
char *dfheid0 = "\x00\x00\x00\x0c"
char *dfheicb = " ";

typedef struct {
    unsigned char eibtime [4];
    unsigned char eibdate [4];
    unsigned char eibtrnid [4];
    unsigned char eibtaskn [4];
    unsigned char eibtrmid [4];
    signed short int eibfil01;
    signed short int eibcposn;
    signed short int eibcalen;
    unsigned char eibaid;
    unsigned char eibfn [2];
    unsigned char eibrcode [6];
    unsigned char eibds [8];
    unsigned char eibreqid [8];
    unsigned char eibrsrc [8];
    unsigned char eibsync;
    unsigned char eibfree;
    unsigned char eibrecv;
    unsigned char eibfil02;
    unsigned char eibatt;
    unsigned char eibeoc;
    unsigned char eibfmh;
    unsigned char eibcompl;
    unsigned char eibsig;
    unsigned char eibconf;
    unsigned char eiberr;
    unsigned char eiberrcd [4];
    unsigned char eibsynrb;
    unsigned char eibnodat;
    signed long int eibresp;
    signed long int eibresp2;
    unsigned char eibrldbk;
} DFHEIBLK;

DFHEIBLK *dfheiptr;
#endif

#ifndef __dfhtemps
#pragma linkage(dfhexec,OS) /* force OS linkage */
void dfhexec(); /* Function to call CICS */
#endif
```

*Child C program after translation (Part 1 of 3)*

*Figure 221. Child C program after translation*
/* this is an example of a CICS program for C */
/* program : GETSTAT ( part 2 - infrequent use routines ) */

#include <stdio.h>
#include <string.h>
#include <stdlib.h>

void unexpected_prob( char* desc, int rc);

void sendmsg( char* status_record )
{
  long int msgresp, msgresp2;
  char outmsg[80];
  int outlen;
  if (memcmp(status_record,"OK ",3)==0)
    strcpy(outmsg,"The system is available.");
  else if (memcmp(status_record,"DOWNTME ",8)==0)
    strcpy(outmsg,"The system is down for regular backups.");
  else
    strcpy(outmsg,"SYSTEM PROBLEM -- call help line for details.");
  outlen=strlen(outmsg);

  /* EXEC CICS SEND TEXT FROM(outmsg)
     LENGTH(outlen)
     RESP(msgresp)
     RESP2(msgresp2) */
  dfhb0020 = outlen;
  dfhexec("\x18\x06\x60\x00\x2F\x00\x00\x00\x00\x20\xF0\xF0\xF2\xF2\xF0\xF0",dfhdummy,outmsg,dfhb020 );
  msgresp = dfheiptr->eibresp;
  msgresp2 = dfheiptr->eibresp2;
}

if (msgresp != 0 )
  unexpected_prob("Message output failed from sendmsg",71);

void unexpected_prob( char* desc, int rc)
{
  long int msgresp, msgresp2;
  int msglen;
  msglen = strlen(desc);

  /* EXEC CICS SEND TEXT FROM(desc)
     LENGTH(msglen)
     RESP(msgresp)
     RESP2(msgresp2) */

Child C program after translation (Part 2 of 3)
Child C program after translation (Part 3 of 3)

This structure, DFHEIBLK, is used for passing information between CICS and the application program.

This is the CICS command that was interpreted by the translator. The translator comments out the EXEC CICS commands.

The translator inserts this call to the function dfhexec and comments out the EXEC CICS commands for further processing by the z/OS XL C/C++ compiler. The values msgresp and msgresp2 are set from the values in the DFHEIBLK structure.

This EXEC CICS command is similar in format to the one discussed in 4. However, you should note that the generated call to dfhexec is different. For this reason it is important that EXEC CICS commands are not imbedded in macros.

Compiling XL C/C++ programs that were preprocessed by the standalone CICS translator

CICS requires that programs be reentrant at CICS entry points. If you are using C, this means:

- If your program is not naturally reentrant, you must compile with the RENT compiler option.
- If you are compiling code that was translated by the standalone CICS translator, you must compile with the RENT compiler option. The standalone CICS translator puts external writable static in the program.

For both C and C++, this means that if your program is naturally reentrant and has not been translated, you can compile and link it just as you would a non-CICS program.

Sample JCL to translate and compile

The sample JCL in Figure 222 on page 900 shows to translate and compile C modules.
Figure 223 shows an example of JCL to translate and compile a C++ program.

```plaintext
//TRANSTEP EXEC PGM=DFHEDP1$,
// REGION=2048K,
// PARM='MAR(1,80,0),OM(1,80,0),NOS,CPP'
//STEPLIB DD DSN=CICS.SDFHLOAD,DISP=SHR
//SYSPRINT DD SYSOUT=*
//SYSPUNCH DD DSN=&&SYSCIN,DISP=(,PASS),UNIT=VIO,
// DCB=BLKSIZE=400,SPACE=(400,(400,100))
//SYSIN DD DSN=MYID.CHKSTAT.C,DISP=SHR
//---
// Compile the translated C++ source.
//---
//C0010308 EXEC CBCC,
// INFILE='MYID.CHKSTAT.C",
// OUTFILE='MYID.OBJECT(CHKSTAT),DISP=SHR",
// CPARM='NOSEQ NOMAR RENT ',
// SYSOUT6='*
//SYSPUNCH DD DSN=*.TRANSTEP.SYSPUNCH,DISP=(OLD,DELETE)
//USERLIB DD DSN=MYID.MYHDR.FILES,DISP=SHR
```

Figure 223. JCL to translate and compile a C++ program

**Prelinking and linking all object modules**

If you are using C++, or if you have compiled your C source with the RENT compile-time option, you must prelink all of the object modules together. The prelinker accepts one or more object modules, combines them, and generates a single output object module which can then be linked. For more information, see *z/OS XL C/C++ User’s Guide*.  

---

*Figure 222. JCL to translate and compile a C program*

---

*Figure 223*
When prelinking for CICS, you should expect some unresolved external references and a return code of 4. These unresolved references should be resolved at link time.

CICS provides a stub called DFHELII, which must be link-edited with the load module. For your convenience, the linkage editor commands required for CICS are provided with CICS in the DFHEILID member of the SDFHC370 data set. The DFHEILID member must be reblocked before it is passed to the linkage editor. A name card should also be passed to the linkage editor. All applications must run AMODE=31. It is recommended that the object module is linked with AMODE(31) and RMODE(ANY). CICS does not require any other linkage editor options.

If you are using C, and your program will reside in one of the DFHRPL libraries, you do not need to link-edit the module with the RENT option. However, if the program is to be installed in one of the link pack areas, STEPLIBs, or data sets in the system link list, you should link-edit the module with the RENT option.

Figure 224 shows an example of how to prelink and link C and C++ modules.

```c
/* Figure 224 shows an example of how to prelink and link C and C++ modules. */
```

```c
#include "prelink_cics_support_link_module.c"
```

When prelinking for CICS, you should expect some unresolved external references and a return code of 4. These unresolved references should be resolved at link time.

CICS provides a stub called DFHELII, which must be link-edited with the load module. For your convenience, the linkage editor commands required for CICS are provided with CICS in the DFHEILID member of the SDFHC370 data set. The DFHEILID member must be reblocked before it is passed to the linkage editor. A name card should also be passed to the linkage editor. All applications must run AMODE=31. It is recommended that the object module is linked with AMODE(31) and RMODE(ANY). CICS does not require any other linkage editor options.

If you are using C, and your program will reside in one of the DFHRPL libraries, you do not need to link-edit the module with the RENT option. However, if the program is to be installed in one of the link pack areas, STEPLIBs, or data sets in the system link list, you should link-edit the module with the RENT option.

Figure 224 shows an example of how to prelink and link C and C++ modules.

```c
/* Figure 224 shows an example of how to prelink and link C and C++ modules. */
```

```c
#include "prelink_cics_support_link_module.c"
```
Defining and running the CICS program

This section discusses the implications of program processing, link considerations for C programs, and CSD considerations. Sample JCL to install z/OS XL C/C++ application programs is provided.

Program processing

In a CICS environment, a single copy of a program is used by several transactions concurrently. One section of a program can process a transaction and then be suspended (usually as a result of an EXEC CICS command). Another transaction can then start or resume processing the same or any other section of the same application program. This behavior requires that the program be reentrant.

Link considerations for C programs

If your C program will reside in one of the DFHRPL libraries, following the translate, compile, and link steps detailed earlier in this chapter is sufficient; there is no requirement to link-edit the module with the RENT linkage editor option.

However, if the program is to be installed in one of the link pack areas, STEPLIBs, or data sets in the system link list, the module should be link-edited with the RENT option.

CSD considerations

Before you can run a program, you must define it in the CICS CSD. When defining a program to CICS, you should use LANGUAGE(LE). However, if the program is in C and does not use ILC support, you can use LANGUAGE(C).

If you use a copy of a reentrant C or C++ application program that was installed in the link pack area, you must specify USELPACOPY(YES) in the resource definition when you define the program in the CSD. You can use the CICS-supplied procedure DFFEITDL to translate, compile, prelink, and link-edit C or C++ programs. For C programs, you may have to change the compile step of this procedure. You will have to change the compile step to use it with the C++ compiler.

Sample JCL to install z/OS XL C/C++ application programs

Figure 225 shows sample JCL to install a C or C++ application program. Your application is anyname; x can resolve to I or X.

```
//jobname  JOB  accounting info,name,MSGLEVEL=1
  // EXEC PROC=DFHEXTEL
  # //TRN.SYSIN DD  *
  #pragma XOPTS(Translator options . .)
  :
  z/OS XL C/C++ source statements
  :
  /*
  //LKED.SYSIN DD  *
  NAME  anyname(R)
  */
  //
```

Figure 225. JCL to install z/OS XL C/C++ application programs
Chapter 53. Using Cross System Product (CSP)

This chapter briefly describes the interface between z/OS XL C and applications generated through the Cross System Product/Application Development (CSP/AD) and the Cross System Product/Application Execution (CSP/AE) Version 3 Release 2 Modification 2 or later. CSP refers to both CSP/AD and CSP/AE.

CSP/AD is an interactive application generator that provides methods for interactively defining, testing, and generating application programs. It can aid in improving productivity in application development.

CSP/AE takes the generated program and executes it in a production environment.

Notes:
1. XPLINK is not supported in a CSP environment.
2. AMODE 64 applications are not supported in a CSP environment.

Common data types

Table 346 lists the data types common to both CSP and z/OS XL C. You must use the function __csplist to receive the parameter list from a CSP application. See z/OS XL C/C++ Runtime Library Reference for more information on this function.

<table>
<thead>
<tr>
<th>z/OS XL C</th>
<th>CSP</th>
</tr>
</thead>
<tbody>
<tr>
<td>signed short</td>
<td>BIN - 2 bytes</td>
</tr>
<tr>
<td>signed int/long</td>
<td>BIN - 4 bytes</td>
</tr>
<tr>
<td>struct</td>
<td>RECORD</td>
</tr>
<tr>
<td>char array(size)</td>
<td>Characters</td>
</tr>
</tbody>
</table>

Passing control

You can pass control between CSP and z/OS XL C as follows:

**CALL**  Calls another application or subroutine to be run. When execution is completed, control is returned to the statement following the CALL statement in the original application.

**XFER** | **DXFR**  Transfers control and initiates execution of a CSP application or non-CSP program or transaction. The current application is terminated when the transfer statement is executed.

Under CICS, XFER is used to transfer control to another CICS transaction, while DXFR is used to transfer control to an application or program. If the target name is an application, control remains in CSP and the application is initiated immediately. If the target name is a program, CSP issues CICS XCTL to the program name.

**Note:** From a z/OS XL C program, you can pass control to a CSP application but you cannot pass control to another z/OS Language Environment-enabled language
(COBOL, PL/I) from that CSP application. Only one z/OS Language Environment-enabled language can be in the chain of calls.

Running CSP under MVS

The following sections cover calling CSP applications from z/OS XL C and calling z/OS XL C from CSP.

Calling CSP applications from z/OS XL C

To call a CSP application from z/OS XL C, you must:

1. Define the CSP program to be called one of the following:
   - DCGCALL - calling under MVS/TSO
   - DCGXFER - transferring control under MVS/TSO with OS pragma linkage

2. Fetch the program dynamically.

3. Transfer control to the program. You must pass at least one parameter when calling CSP from z/OS XL C. This is the pointer to the ALF name and application name.

Example programs

The following example program (CCNGCP1 in Figure 226) CALLs a CSP application in the z/OS environment. You must receive a structure.

Note: CSP cannot pass the DXFR statement to z/OS XL C under TSO.

```c
/* this example shows how to CALL CSP from C under TSO */
/* CALL */
/* CCNGCP1 ===> R924A6 */
/* R924A6 is a CSP application */

#include <stdlib.h>
#include <math.h>
#pragma linkage(DCGCALL,OS)

void main(int argc , char * argv[])
{
  int ctr,base, power ;

  typedef void ASM_VOID();
  #pragma linkage (ASM_VOID,OS)
  ASM_VOID * fetch_ptr;

  int rc = 0;
  char module [ 8] = "DCGCALL ";
  struct tag_a6progc {
    char alfx [ 8];
    char applx [ 8];
  };

  C/370 CALLing CSP under TSO (Part 1 of 2)

  Figure 226. C/370 CALLing CSP under TSO
```
struct tag_a6rec {
    char a6ct [ 4];
    char a6lan [ 4];
    char fil1 [ 8]; /* packed fields for PLI */
    char fil2 [ 8]; /* packed fields for PLI */
    char fil3 [ 8]; /* packed fields for PLI */
    int a6xbc;
    int a6ybc;
    int a6zbc;
};

struct {char s_parm [ 240];}
s_parms = {"ALF=C "};

struct tag_a6progc a6_progc = {"FZERSAM.","R924A6 "};

_Packed struct tag_a6rec a6_rec = {"CALL",
    "C ",
    "0000110C",
    "0000220C",
    "0000330C",
    12, 2, 0
};

base = atoi(argv[1]);
power= atoi(argv[2]);

a6_rec.a6xbc = base;
a6_rec.a6ybc = power;
a6_rec.a6zbc = (int) pow((double) a6_rec.a6xbc,
    (double) a6_rec.a6ybc);

if ((fetch_ptr = (ASM VOID *) fetch(module)) == NULL ) {
    printf(" failed on fetch of CSP %s module \n", module);
}
else {
    fetch_ptr (&a6_progc, &a6_rec);
    rc = release((void (*)()) fetch_ptr) ;
    if ( rc != 0 ) {
        printf("CCNGCP1: rc from release =%d\n", rc );
    }
}

C/370 CALLing CSP under TSO (Part 2 of 2)

Figure 227 on page 908 shows example program CCNGCP2, which uses an XFER command to transfer control to a CSP application. You must pass a structure.
/* this example shows how to transfer control to CSP from C under */
/* TSO, using XFER */
/* XFER */
/* CCNGCP2 ===> R924A5 */
/* R924A5 is a CSP application */

#include <stdlib.h>
#include <math.h>
#pragma linkage(DCGXFER,OS)

void main(int argc , char * argv[]) {
    int ctr,base, power ;
    int rc = 0;
    char module [ 8] = {"DCGXFER " } ;

    typedef void ASM_VOID();
    #pragma linkage (ASM_VOID,OS)
    ASM_VOID * fetch_ptr;

    struct tag_a5ws {
        short length ;
        char filler [ 8];
        char a5ct [ 4];
        char a5lan [ 4];
        char fill1 [ 8]; /* packed fields for PLI */
        char fill2 [ 8]; /* packed fields for PLI */
        char fill3 [ 8]; /* packed fields for PLI */
        int a5xbc;
        int a5ybc;
        int a5zbc;
    };
    struct tag_a5progx {
        char alfx [ 8];
        char applx [ 8];
    };
    struct {
        char s_parm [ 240];
    } s_parms = {"ALF=C ";}
    struct tag_a5progx a5_progx = {"FZERSAM. ","R924A5 "} ;
    Packed struct tag_a5ws a5_ws = { 54,
        "CCNGCP2",
        "XFER",
        "C",
        "0000110C",
        "0000220C",
        "0000330C",
        12, 2, 0
    };

    base = atoi(argv[1]) ;
power= atoi(argv[2]) ;
a5_ws.a5xbc = base;
a5_ws.a5ybc = power;
a5_ws.a5zbc = (int) pow((double) a5_ws.a5xbc,
        (double) a5_ws.a5ybc);
if ((fetch_ptr = (ASM_VOID *) fetch(module)) == NULL ) {
    printf(" failed on fetch of CSP %8s module \n", module);
}

z/OS XL C transferring control to CSP under TSO using the XFER/DXFR statement (Part 1 of 2)

Figure 227. z/OS XL C transferring control to CSP under TSO using the XFER/DXFR statement

908  z/OS V2R2 XL C/C++ Programming Guide
else {
    fetch_ptr (&a5_ws , &a5_progx);
    rc = release((void (*) ())fetch_ptr) ;
    if ( rc != 0 ) {
        printf("CCNGCP2: rc from release =%d"\n", rc);
    }
}

z/OS XL C transferring control to CSP under TSO using the XFER/DXFR statement (Part 2 of 2)

Calling z/OS XL C from CSP

To call a z/OS XL C program from CSP:

- PLIST(OS) must be specified in the z/OS XL C program so that input parameters will not be processed by the runtime environment.
- When CSP passes a parameter list to a z/OS XL C function, the list is in a different format from what z/OS XL C expects in a normal z/OS environment. To receive the parameters, use the macro __csplist, found in the csp.h header file and described in z/OS XL C/C++ Runtime Library Reference.

Notes:
1. PLIST(OS) must be specified in the z/OS XL C program so that input parameters will not be processed by the runtime environment.
2. When CSP passes a parameter list to a z/OS XL C function, the list is in a different format from what z/OS XL C expects in a normal z/OS environment. To receive the parameters, use the macro __csplist, found in the csp.h header file and described in z/OS XL C/C++ Runtime Library Reference.

Example programs
Figure 228 on page 910 shows example program CCNGCP3, which shows how parameters are received from a CSP application that uses a CALL statement to transfer control. You must pass three parameters:
- An int
- A string
- A struct
Figure 229 on page 911 shows example program CCNGCP4, which shows how parameters are received from a CSP application that uses an XFER/DXFR statement to transfer control. You must pass a structure.

Notes:
1. Under TSO, CSP/AD cannot use the XFER statement to transfer control to z/OS XL C.
2. Under TSO, you cannot use the DXFR statement to transfer control to CSP.

/* this example shows how to CALL C from CSP under TSO */

#pragma runopts (plist(os))
#include <csp.h>
#include <math.h>
#include <stdlib.h>

void main()
{
  struct date {
    char yy[2];
    char mm[2];
    char dd[2];
  };
  int *parm1_ptr ;
  char *parm2_ptr ;
  struct date * parm3_ptr ;
  parm1_ptr = (int *) __csplist[0]; /* get 1st parm */
  parm2_ptr = (char *) __csplist[1]; /* get 2nd parm */
  parm3_ptr = (struct date *) __csplist[2]; /* get 3rd parm */
}
/* this example shows how to transfer control from CSP to C */
/* This program will be called from CSP through */
/* "XFER" or DXFR call. */
/* Parameters are passed as a working storage record */
/* plus 10 bytes of filler information */
/* 2 bytes length */
/* 8 bytes filler */
/* n bytes working storage record. */

#pragma runopts (plist(os))
#include <stdlib.h>
#include <csp.h>
#include <math.h>
#include <string.h>
#pragma linkage(DCGXFER,OS)
#pragma linkage(DCGCALL,OS)

void xfer_rtn();
void call_rtn();

struct tag_a3ws {
    short length;
    char filler[8];
    char a3ct[4];
    char a3lan[4];
    char fil1[8]; /* packed fields for PLI */
    char fil2[8]; /* packed fields for PLI */
    char fil3[8]; /* packed fields for PLI */
    int a3xbc;
    int a3ybc;
    int a3zbc;
};

struct tag_a3progx {
    char aflx[8];
    char applx[8];
};

void main() {
    _Packed struct tag_a3ws *parm1;
    _Packed struct tag_a3ws a3_ws;

    parm1 = (_Packed struct tag_a3ws *)__csplist[0];
    parm1->a3zbc = (int) pow((double) parm1->a3xbc,
        (double) parm1->a3ybc);

    if (parm1->a3zbc > 255)
        xfer_rtn(parm1); /* xfer to csp */
    else
        call_rtn(parm1); /* call to csp */
}

CSP transferring control to z/OS XL C under TSO using the XFER statement (Part 1 of 3)

Figure 229. CSP transferring control to z/OS XL C under TSO using the XFER statement
void xfer_rtn(_Packed struct tag_a3ws * parm1 )
{
    #pragma linkage (ASM_VOID,OS)
    typedef void ASM_VOID();
    ASM_VOID * fetch_ptr;

    struct tag_a3progx a3_progx = {"FZERSAM.","R924A5 "} ;
    int rc = 0;
    char pgm_xfer [ 8 ] = {"DCGXFER " } ;

    if ((fetch_ptr = (ASM_VOID *) fetch(pgm_xfer)) == NULL ) {
        printf("%s failed on fetch of CSP %s module \n", pgm_xfer);
    } else {
        fetch_ptr (parm1, &a3_progx);
        rc = release((void (*)()) fetch_ptr) ;
        if ( rc != 0 ) {
            printf("xfer_rtn: rc from release =%d\n", rc);
        }
    }
}

void call_rtn(_Packed struct tag_a3ws * parm1 )
{
    typedef void ASM_VOID();
    ASM_VOID * fetch_ptr;
    char pgm_call [ 8 ] = {"DCGCALL " } ;
    int rc = 0;
    struct tag_a3progx a3_progx = {"FZERSAM.","R924A6 "} ;
    struct tag_a6rec {
        char a6ct [ 4 ];
        char a6lan [ 4 ];
        char fill[ 8 ]; /* packed fields for PLI */
        char fill2[ 8 ]; /* packed fields for PLI */
        char fill3[ 8 ]; /* packed fields for PLI */
        int a6xbc;
        int a6ybc;
        int a6zbc;
    };
    struct tag_a6rec a6_rec ;
    memcpy(a6_rec.a6ct ,parm1->a3ct ,4);
    memcpy(a6_rec.a6lan ,parm1->a3lan ,4);
    memcpy(a6_rec.fill ,parm1->fill ,8);
    memcpy(a6_rec.fill2 ,parm1->fill2 ,8);
    memcpy(a6_rec.fill3 ,parm1->fill3 ,8);
    a6_rec.a6xbc = parm1->a3xbc;
    a6_rec.a6ybc = parm1->a3ybc;
    a6_rec.a6zbc = parm1->a3zbc;

    CSP transferring control to z/OS XL C under TSO using the XFER statement (Part 2 of 3)
if ((fetch_ptr = (ASM_VOID *) fetch(pgm_call)) == NULL ) { 
    printf(" failed on fetch of CSP %s module \n", pgm_call);
} 
else { 
    fetch_ptr (&a3_progx, &a6_rec);
    rc = release( (void (*)()) fetch_ptr);
    if ( rc != 0 ) {
        printf("CCNGCP4: rc from release =%d\n", rc);
    }
}

CSP transferring control to z/OS XL C under TSO using the XFER statement (Part 3 of 3)

Running under CICS control

For CSP-CICS, note that because all z/OS XL C applications running under CICS must run with AMODE=31, when passing parameters to CSP, you must either
- Pass parameters below the line, or
- Relink the CSP load library with AMODE=31

Example programs

Figure 230 shows example program CCNGCP5, which shows how parameters are received from a CSP application that uses a CALL statement to transfer control. The z/OS XL C program is expecting to receive an int as a parameter. 

```c
/* this example shows how to call C from CSP under CICS, and how */
/* parameters are passed */
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <math.h>
main()
{
    struct tag_commarea { /* commarea passed to z/OS C from R024A1 */
        int *ptr1 ;
        int *ptr2 ;
        int *ptr3 ;
    } * ca_ptr ; /* commarea ptr */
    int *parm1_ptr ;
    int *parm2_ptr ;
    int *parm3_ptr ; /* addressability to EIB control block */
    EXEC CICS ADDRESS EIB(dfheiptr) COMMAREA(ca_ptr) ;
    parm1_ptr = ca_ptr->ptr1 ;
    parm2_ptr = ca_ptr->ptr2 ;
    parm3_ptr = ca_ptr->ptr3 ;
    *parm3_ptr = (int) pow((double) *parm1_ptr,
                          (double) *parm2_ptr); 
    EXEC CICS RETURN;
}
```

Figure 230. CSP CALLing z/OS XL C under CICS
Figure 231 (example program CCNGCP6) shows how parameters are received from a CSP application that uses an XFER statement to transfer control.

```c
/* this example shows how to XFER control to C from CSP under CICS */
/* XFER CALL */
/* R924A3 ===> CCNGCP6 ===> R924A6 */
/* R924A3 and R924A6 are CSP applications */

#include <math.h>
#include <string.h>

/* structure passed to R924A6*/

/* structure received R924A3*/

void main()
{
    struct {
        char *appl_ptr:
        _Packed struct tag_a3rec *rec3_ptr;
    } parm_ptr;

    struct tag_a3rec {
        char a3ct [ 4];
        char a3lan [ 4];
        char fil1 [ 8];    /* packed fields for PLI */
        char fil2 [ 8];    /* packed fields for PLI */
        char fil3 [ 8];    /* packed fields for PLI */
        int a3xbc;        /* int field 1 for z/OS C */
        int a3ybc;        /* int field 2 for z/OS C */
        int a3zbc;        /* int field 3 for z/OS C */
    }
}
```

CSP transferring control to z/OS XL C under CICS using the XFER statement (Part 1 of 2)

**Figure 231. CSP transferring control to z/OS XL C under CICS using the XFER statement**
Packed struct tag_a3rec a3rec;
char 1k_appl[16] = "USR5ALF.R924A6 " ;

struct tag_a3progx {
    char alfx [ 8];
    char applx [ 8];
};
_Packed struct tag_a3progx a3progx = {"USR5ALF.","R924A6 "} ;
short length_a3rec = sizeof(a3rec) ;
char * pa3rec ;
short i ;

/*----- start of CSP XFER-ing to C under CICS ----------------------*/
EXEC CICS ADDRESS EIB(dfheiptr);
/* retrieve data from CSP */
EXEC CICS RETRIEVE INTO(&a3rec) LENGTH(length_a3rec) ;
a3rec.a3zbc = (int) pow((double) a3rec.a3xbc,
(double) a3rec.a3ybc);

/*----- end of CSP XFER-ing to C under CICS ----------------------*/

/* call CSP to display results*/
parm_ptr.appl_ptr = lk_appl ; /* alf.application */
parm_ptr.rec3_ptr = &a3rec ; /* LINK to CSP application */
EXEC CICS LINK PROGRAM("DCBINIT ")
COMMAREA(parm_ptr)
LENGTH(8) ;

if (dfheiptr->eibresp2 != 0) {
    printf("CCNGCP6: EXEC CICS LINK returned non zero 
return code. eibresp2 =%d
",
dfheiptr->eibresp2);
}
/*----- end of C calling CSP under CICS ----------------------*/
EXEC CICS RETURN ;
}

CSP transferring control to z/OS XL C under CICS using the XFER statement (Part 2 of 2)

Figure 232 on page 916 (example program CCNGCP7) The following example program shows how parameters are received from a CSP application that uses a DXFR statement to transfer control. You must receive a structure.
/* this example shows how to transfer control to C from CSP under CICS, using the DXFR statement */

/* DXFR XCTL( equivalent to dxfr) */
/* R924A3 ===> CCNGCP7 ===> DCBINIT ( appl R924A5) */
/* R924A3 is a CSP application */

#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include <math.h>

main () {
    struct tag_a3rec {
        char a3ct [4];
        char a3lan [4];
        char fil1 [8]; /* packed fields for PLI */
        char fil2 [8]; /* packed fields for PLI */
        char fil3 [8]; /* packed fields for PLI */
        int a3xbc;
        int a3ybc;
        int a3zbc;
    };
}

CSP Transferring Control to z/OS XL C under CICS Using the DXFR Statement (Part 1 of 2)

Figure 232. CSP Transferring Control to z/OS XL C under CICS Using the DXFR Statement
CSP Transferring Control to z/OS XL C under CICS Using the DXFR Statement (Part 2 of 2)
Chapter 54. Using Data Window Services (DWS)

Data Window Services (DWS) is part of the CSL (Callable Services Library). DWS gives your C or C++ program the ability to manipulate data objects (temporary data objects known as TEMPSPACE, and VSAM linear data sets).

Notes:
1. XPLINK is not supported with DWS.
2. AMODE 64 applications are not supported with DWS.

To use DWS functions with C code, you do not have to specify a linkage pragma or add any specialized code. Code the DWS function call directly inside your z/OS XL C program just as you would a call to a C or C++ library function and then link-edit the DWS module containing the function you want (such as CSRIDAC, CSRVIEW, CSRSOT, CSRSAVE or CSREFR) with your C or C++ program.

To use DWS functions with C++ code, you must specify C linkage for any DWS function that you use. For example, if you wished to use CSRIDAC, you would use a code fragment as shown in Figure 233.

```c
/* this example shows how DWS may be used with C++ */
#include <stdlib.h>
extern "C" {  
  void csridac( char*, char*, char*, char*, char*,  
  char*, long int*, char*, long int*,  
  long int*, long int*);  
}

int main(void)  
{  
  /* Set up the parameters that will be used by CSRIDAC. */  

  char op_type[6] = "BEGIN";
  char object_type[10] = "TEMPSPACE";
  char object_name[45] = "DWS.FILE";
  char scroll_area[4] = "YES";
  char object_state[4] = "NEW";
  char access_mode[7] = "UPDATE";
  long int object_size = 8;
  char object_id[9];
  long int high_offset, return_code, reason_code;

  /* Access a DWS TEMPSPACE data object. */  

  csridac(op_type, object_type, object_name, scroll_area, object_state,  
           access_mode, OBJECT_SIZE, object_id, &high_offset,  
           &return_code, &reason_code);  

  /* INSERT ADDITIONAL CODE HERE */  
}  
```

Figure 233. Example using DWS and C++

At link-edit time, you should link-edit the DWS module containing the function you want, just as you would for a C program.

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In DWS, the data types of the parameters are specified differently from z/OS XL C/C++ data types. When invoking DWS functions from your C or C++ program, you must specify:

- A `long int` data type for DWS parameters of integer (I*4) type.
- Character strings (of the required length) for DWS parameters of character type.

For example, if the DWS function requires a 9-character object name (in this example we will set the object name to `TEMPSPACE`) you can declare the parameter in your C or C++ function as follows:

```c
char object_type[9] = "TEMPSPACE";
```

For more information on DWS, see z/OS MVS Programming: Callable Services for High-Level Languages.

As another example, Figure 234 is an excerpt from a C program (CCNGDW1) that shows parameter declarations for the DWS `CSRIDAC` function and the function call.

```c
/* this example shows how DWS may be used with C */

int main(void)
{
    /* Set up the parameters that will be used by CSRIDAC. */
    char op_type[5] = "BEGIN";
    char object_type[9] = "TEMPSPACE";
    char object_name[45] = "DWS.FILE ";
    char scroll_area[3] = "YES";
    char object_state[3] = "NEW";
    char access_mode[6] = "UPDATE";
    long int object_size = 8;
    char object_id[8];
    long int high_offset, return_code, reason_code;

    /* Access a DWS TEMPSPACE data object. */
    csridac(op_type, object_type, object_name, scroll_area, object_state,
            access_mode,OBJECT_size,OBJECT_id,&high_offset,
            &return_code,&reason_code);
    /* INSERT ADDITIONAL CODE HERE */

    return 0;
}
```

---

*Figure 234. z/OS XL C/C++ Using Data Window Services*
Chapter 55. Using DB2 Universal Database

Both z/OS Language Environment and z/OS XL C/C++ provide an interface to the IBM DB2 Universal Database™ Licensed Program. For a list of books describing DB2, refer to “DB2” on page 1176.

An XL C/C++ program requests DB2 services by using SQL statements embedded in the program. This source code is translated into host language statements that perform assignments and call a database language interface module. After DB2 processes each request, it returns processing control to the XL C/C++ program.

Any errors that occur during database processing are handled by the database product. If a program is terminated during DB2 processing, DB2 takes appropriate action, depending on the nature of termination.

Preparing an XL C/C++ application to request DB2 services

Before a C/C++ program can request DB2 services, the code with embedded SQL statements must be converted into compilable code. There two ways to do this:

- Use the XL C/C++ DB2 coprocessor (provided by the z/OS XL C compiler).
- Use the DB2 C/C++ precompiler (provided by DB2).

To ensure that you are using compatible releases of z/OS XL C/C++ and DB2, see z/OS Program Directory.

Refer to the SQL compiler option in z/OS XL C/C++ User’s Guide whenever your application performs the following operations:

- Declares global host variables.
- Declares host variables inside functions.
- Includes a header found in SYSLIB or in the LSEARCH path.
- Puts comments at the end of selected lines in the middle of a multiline SQL statement.
- Inserts, updates, or retrieves data using a host variable.
- Embeds SQL statements in template functions or classes.

Using the XL C/C++ DB2 coprocessor

If all the SQL statements are embedded in XL C programs, you can use the XL C DB2 coprocessor to prepare the program to request DB2 services. You can either run the program through the DB2 C/C++ precompiler before you compile, or you can specify the SQL compiler option when you compile the program. For detailed information about using the SQL option, refer to SQL in z/OS XL C/C++ User’s Guide. If you are compiling code with SQL in effect, refer to z/OS Program Directory for a complete list of SQL suboptions.

When the XL C/C++ SQL(NOSTD) option is in effect, code should be written in codepage IBM-1047 (APL).293.

The following are advantages of using the XL C/C++ DB2 coprocessor instead of the DB2 C/C++ precompiler:

- Host variable names follow the same lexical scoping rules as C/C++ variables.
• Preprocessor directives (such as \texttt{#include} and \texttt{#define}) are supported.
• Variable-length source input is supported.

Notes:
1. Typically, NOSQL is the default compiler option. If your environment is customized to make SQL the default, be aware that the compiler will attempt to call the API that contains DBRMLIB DD even if the source code does not contain SQL statements. When that happens, DB2 generates a message that you can ignore.

2. "SQLCODE", "SQLSTATE", and "sqlca" are not valid user host variable names, because they are reserved by the compiler and DB2 coprocessor as embedded SQL keywords. Previous to the compiler embedding the DB2 coprocessor, the DB2 precompiler did not recognize these three identifiers as keywords, but the new DB2 coprocessor correctly recognizes them and will not successfully compile any source file that attempts to use them as user host variable names. If you are already using any of these reserved keywords as table column names in your program (and referencing them through identically named user host variable names), and you are migrating from a compiler release that uses the DB2 precompiler to one that uses the DB2 coprocessor, you must restructure your queries in order to avoid any conflicts with these reserved keywords. For detailed information, see the documentation available at the following URL:

\url{http://www.ibm.com/software/data/db2/zos/library.html}

Using the DB2 C/C++ precompiler

The DB2 C/C++ precompiler scans source code for potentially SQL-related keywords, such as the following:

• Host variables that can be used in SQL statements in the same source.
• SQL statements that start with the token pair EXEC SQL.

While the DB2 C/C++ precompiler can fully parse the SQL syntax, it has limited capacity for parsing compiler-language-related syntax. If you are compiling code with SQL in effect, all DB2 z/OS XL C/C++ code should be written in codepage IBM-1047 (APL293).

An advantage of using the DB2 C/C++ precompiler instead of the XL C/C++ DB2 coprocessor is that you can obtain a more useful message listing by preprocessing, precompiling, and then compiling source code with embedded SQL statements. Compiler diagnostics refer to line numbers of the translated output from the DB2 C/C++ precompiler, not to the line numbers of your source code. This means that you need both the DB2 C/C++ precompiler listing and the compiler listing to work through the compilation errors. Runtime troubleshooting tools also refer to coordinates of the DB2 C/C++ precompiler output.

Using DB2 services and stored procedures with XPLINK

XL C/C++ applications that are compiled with the XPLINK option can invoke DB2 services that are called through stubs defined as \texttt{#pragma linkage(..., OS)}.

When you embed DB2 stored procedures in a program that will be compiled with XPLINK, each CREATE PROCEDURE statement must include a RUN OPTIONS clause that specifies XPLINK(ON).
Examples of how to use XL C/C++ programs to request DB2 services

The examples in this section demonstrate how to code C and C++ programs with embedded SQL statements. You can use them with either the XL C/C++ DB2 coprocessor or the DB2 C/C++ precompiler.

Example CCNGB4 demonstrates how to code a C program with embedded SQL statements. In Figure 235 on page 924 a program CCNGB4 creates a table called CTAB1, inserts literal values into the table, and drops the table. You can use this example either by compiling the program with the SQL option in effect or by running the program through the DB2 C/C++ precompiler, and then compiling the generated code with the NOSQL option in effect.
/* this example demonstrates how to use SQL with C */

#include <string.h>
#include <stdio.h>

EXEC SQL INCLUDE SQLCA;

int main(void)
{
    if (CreaTab() == -1)
    {
        printf("Test Failed in table-creation.\n");
        exit(-1);
    }
    if (DropTab() == -1)
    {
        printf("Test Failed in table-dropping.\n");
        exit(-1);
    }
    printf("Test Successful.\n");
    return(0);
}

/*
 * This routine creates the table CTAB1 and inserts some values
 * into it
 */

int CreaTab(void)
{
    EXEC SQL CREATE TABLE CTAB1
    ( EMPNO CHAR(6) NOT NULL,
      FIRSTNME VARCHAR(12) NOT NULL,
      LASTNME VARCHAR(15) NOT NULL,
      WORKDEPT CHAR(3) NOT NULL,
      PHONENO CHAR(7),
      EDUC_LVL SMALLINT,
      SALARY FLOAT(21) );

    if (sqlca.sqlcode != 0)
    {
        printf("ERROR - SQL code returned non-zero for "
               "creation of CTAB1, received %d\n",sqlca.sqlcode);
        return(-1);
    }

Using DB2 with C (Part 1 of 2)

Figure 235. Using DB2 with C
Now insert some values into the table:

EXEC SQL INSERT INTO CTAB1 VALUES
    ( '097892','John','Adams','003','8883945',3,29500.00 );
EXEC SQL INSERT INTO CTAB1 VALUES
    ( '000002','Joe','Smith','004','8883791',NULL,25500.00 );
EXEC SQL INSERT INTO CTAB1 VALUES
    ( '043929','Ralph','Holland','001','8888734',1,NULL);
EXEC SQL INSERT INTO CTAB1 VALUES
    ( '000010','Holly','Waters','001','8884590',3,29550.00 );

if (sqlca.sqlcode != 0)
{
    printf("ERROR - SQL code returned non-zero for ",sqlca.sqlcode);
    return(-1);
}
return(0);

This routine will drop the table.

int DropTab(void)
{
    EXEC SQL DROP TABLE CTAB1;
    if (sqlca.sqlcode != 0)
    {
        printf("ERROR - SQL code returned non-zero for ",sqlca.sqlcode);
        return(-1);
    }
    EXEC SQL COMMIT WORK;
    return(0);
}

Using DB2 with C (Part 2 of 2)

Figure 236 on page 926 is a C++ code example with embedded SQL statements. The sample code creates, populates, updates, and drops a table called CTAB1V.
You can use this example either by compiling the program with the SQL option in effect or by running the program through the DB2 C/C++ precompiler, and then compiling the generated code with the NOSQL option in effect.
#include <iostream>

// The test case information
typedef char TestType;

#define NUM_ROWS 3
#define IN_VALUE {'A', 'B', 'C'}
#define OUT_VALUE {'D', 'E', 'F'}

EXEC SQL INCLUDE SQLCA;

class SqlTestTable {
public:
  // The constructor and destructor create and drop the test table
  SqlTestTable() {
    EXEC SQL CREATE TABLE CTAB1V (
      ID INTEGER NOT NULL,
      TESTVAR CHAR(1) NOT NULL
    ) IN DATABASE DSNUCOMP;
    if (sqlca.sqlcode != 0) {
      std::cout << "ERROR - SQL code returned " << sqlca.sqlcode
                << " for creation of CTAB1V.\n";
    }
  }

  ~SqlTestTable() {
    EXEC SQL DROP TABLE CTAB1V; // Clean up the database
    if (sqlca.sqlcode != 0) {
      std::cout << "ERROR - SQL code returned " << sqlca.sqlcode
                << " for drop of CTAB1V.\n";
    }
    EXEC SQL COMMIT WORK;
  }

  int insertRow(int idToAdd, TestType inputData) {
    int returnValue = 55;
    EXEC SQL BEGIN DECLARE SECTION;
    int idForRow = idToAdd;
    TestType inputValue = inputData;
    EXEC SQL END DECLARE SECTION;
    EXEC SQL INSERT INTO CTAB1V
    VALUES ( :idForRow, :inputValue );
    if (sqlca.sqlcode != 0) {
      std::cout << "ERROR - SQL code returned " << sqlca.sqlcode
                << " for insert into tables.\n";
      returnValue = 66; // Not returned immediately in case cleanup is needed
    }
    return returnValue;
  }
}

Using DB2 with C/C++ (Part 1 of 3)

Figure 236. Using DB2 with C/C++
int updateTable(int idToChange, TestType inputData) {
    int returnValue = 55;

    EXEC SQL BEGIN DECLARE SECTION;
    int idForRow = idToChange;
    TestType inputValue = inputData;
    EXEC SQL END DECLARE SECTION;

    EXEC SQL UPDATE CTAB1V
    SET TESTVAR = :inputValue
    WHERE ID = :idForRow;

    if (sqlca.sqlcode != 0) {
        std::cout << "ERROR - SQL code returned " << sqlca.sqlcode << " for update in tables.\n";
        returnValue = 66; // Not returned immediately in case cleanup is needed
    }

    return returnValue;
}

int checkTable(int idToCheck, TestType value) {
    int returnValue = 55;

    // Try other format variable names
    EXEC SQL BEGIN DECLARE SECTION;
    int idForRow = idToCheck;
    TestType check_var;
    EXEC SQL END DECLARE SECTION;

    EXEC SQL SELECT TESTVAR INTO :check_var
    FROM CTAB1V
    WHERE ID = :idForRow;

    if (sqlca.sqlcode != 0) {
        std::cout << "ERROR - SQL code returned " << sqlca.sqlcode << " for SELECT of the data.\n";
        return 66; // Return immediately since no cleanup; nothing else to be done
    }

    if (check_var != value) {
        std::cout << "ERROR - Value in table " << check_var << " is not the expected value " << value << "\n";
        returnValue = 66; // Not returned immediately in case cleanup is needed
    }

    return returnValue;
};
int main(void) {
    SqlTestTable testTable; // Creates the tables
    int i = 0;
    int returnValue = 55;

    TestType aLongVariableName[NUM_ROWS] = IN_VALUE;
    TestType expectedResults[NUM_ROWS] = OUT_VALUE;

    // SQL Declare's Not needed. Added to see what happens if not used as SQL vars.
    EXEC SQL BEGIN DECLARE SECTION;
    TestType inValue;
    TestType outValue;
    EXEC SQL END DECLARE SECTION;

    // Populate the table using non-host variables as function parameters
    for (i = 0; i < NUM_ROWS; i++) {
        returnValue = testTable.insertRow(i, aLongVariableName[i]);

        if (returnValue != 55) {
            return returnValue;
        }
    }

    // Check to see if the insert went OK using host variables as function parms
    for (i = 0; i < NUM_ROWS; i++) {
        inValue = aLongVariableName[i];
        returnValue = testTable.checkTable(i, inValue);

        if (returnValue != 55) {
            return returnValue;
        }
    }

    // Update the values using host variables as function parameters
    for (i = 0; i < NUM_ROWS; i++) {
        outValue = expectedResults[i];
        returnValue = testTable.updateTable(i, outValue);

        if (returnValue != 55) {
            return returnValue;
        }
    }

    // Check to see if the update went OK using non-host variables as function parms
    for (i = 0; i < NUM_ROWS; i++) {
        returnValue = testTable.checkTable(i, expectedResults[i]);

        if (returnValue != 55) {
            return returnValue;
        }
    }

    return returnValue;  // Deletes the table through the destructor
}

Using DB2 with C/C++ (Part 3 of 3)
Chapter 56. Using Graphical Data Display Manager (GDDM)

The Graphical Data Display Manager (GDDM) provides programmers with a comprehensive set of functions for displaying or printing information in the most effective manner. The major functions provided are:

- A windowing system that the user can tailor to display selected information
- Support for presentation and interaction through the keyboard
- Comprehensive graphics support
- Fonts, including support for double-byte character sets (DBCS)
- Business image support
- Saving and restoring graphics pictures
- Support for many types of display terminals, printers, and plotters.

Because GDDM uses OS-style linkage, calls from C to GDDM require the #pragma linkage pragma, as in the following example:

```
#pragma linkage(identifier, OS)
```

In C++ code, calls to and from GDDM require that any GDDM functions you use be prototyped as extern "OS", as shown in the following example:

```
extern "OS" {
    ASREAD(int *type, int *num, int *count);
    CHATT(int num, int *attrib);
    CHHATT(int num, int *attrib);
}
```

Because C++ does not support #pragma linkage, any existing C code that you are moving to C++ should use the extern "OS" specification instead.

When linking a GDDM application, you must add the GDDM library to your SYSLIB concatenation.

Notes:
1. XPLINK is not supported by GDDM.
2. AMODE 64 applications are not supported by GDDM.
Examples

The following examples demonstrate the interface between C and GDDM by drawing a polar chart to compare the characteristics of two cars.

**Figure 237** shows a sample program (CCNGGD1) using GDDM and C.

```c
/* this example demonstrates the use of C and GDDM */
#include <string.h>
#pragma linkage(asread,OS)
#pragma linkage(chaatt,OS)
#pragma linkage(chhatt,OS)
#pragma linkage(chhead,OS)
#pragma linkage(chkatt,OS)
#pragma linkage(chkey,OS)
#pragma linkage(chnatt,OS)
#pragma linkage(chnoff,OS)
#pragma linkage(chnote,OS)
#pragma linkage(chpolr,OS)
#pragma linkage(chset,OS)
#pragma linkage(chxlab,OS)
#pragma linkage(chxlat,OS)
#pragma linkage(chxtic,OS)
#pragma linkage(chyrng,OS)
#pragma linkage(chyset,OS)
#pragma linkage(fsinit,OS)
#pragma linkage(fsterm,OS)

/* Arrays are expected for int * and float * */
/* char * can be an array or a string */
extern int asread (int *type, int *num, int *count);
extern int chaatt (int num, int *attrib);
extern int chhatt (int num, int *attrib);
extern int chkatt (int num, int *attrib);
extern int chkey (int, int, char *);
extern int chnatt (int num, int *attrib);
extern int chnoff (double, double);
extern int chnote (char *string, int num, char *title);
extern int chpolr (int, int, float *xdata, float *ydata);
extern int chset (char *charactr);
extern int chxlab (int num, int, char *);
extern int chxlat (int num, int *attrib);
extern int chctic (double x, double y);
extern int chyrng (double from, double to);
extern int chyset (char *charactr);
extern int fsinit (void);
extern int fsterm (void);

/** Attribute arrays used for the chart. **
   *********************************************/
int i;
int h_attrs[4] = {3, 3, 0, 175}; /* Head text attribute */
int n_attrs[4] = {7, 3, 0, 200}; /* Note text attribute */
int a_attrs[2] = {7, 1}; /* X-axis color and line */
int x1_attrs[1] = {5}; /* X-label color */
int k_attrs[1] = {5}; /* Key text color */
int type, num, count;

Example using GDDM and C (Part 1 of 2)

**Figure 237. Example using GDDM and C**
Example using GDDM and C (Part 2 of 2)

Figure 238 on page 932 is a similar example program (CCNGGD2) in C++.
/* this example demonstrates the use of C++ and GDDM */
#include <stdlib.h>
#include <string.h>
/* Arrays are expected for int * and float * */
/* char * can be an array or a string */
extern "OS" {
  int asread (int *type, int *num, int *count);
  int chaatt (int num, int *attrib);
  int chhattr (int num, int *attrib);
  int chkatt (int num, int *attrib);
  int chkey (int, int, char *);
  int chhead( int, char *);
  int chnatt (int num, int *attrib);
  int chnoff (double, double);
  int chnote (char *string, int num, char *title);
  int chpolr (int, int, float *xdata, float *ydata);
  int chset (char *character);
  int chxlab (int num, int, char *);
  int chxlat (int num, int *attrib);
  int chxtic (double x, double y);
  int chyrng (double from, double to);
  int chyset (char *character);
  int fsinit (void);
  int fsterm (void);
}

Example using GDDM and C++ (Part 1 of 2)

Figure 238. Example using GDDM and C++
Example using GDDM and C++ (Part 2 of 2)
Chapter 57. Using the Information Management System (IMS)

This chapter explains how the Information Management System (IMS) and z/OS XL C/C++ coordinate error handling, and describes the limitations to using IMS with z/OS XL C/C++.

z/OS XL C/C++ provides the ctdli() C library function to invoke IMS facilities (see z/OS XL C/C++ Runtime Library Reference for more information).

You can also invoke IMS facilities with the callable service CEETDLI which is provided by the z/OS Language Environment. The CEETDLI interface performs essentially the same functions as ctdli(), but it offers some advantages, particularly if you plan to run an ILC application in IMS. If you use the CEETDLI interface instead of ctdli(), condition handling is improved because of the coordination between z/OS Language Environment and IMS condition handling facilities. For complete information on the CEETDLI interface, see z/OS Language Environment Programming Guide.

For a description of writing IMS batch and online programs in C or C++, see the appropriate book listed in "IMS/ESA” on page 1176.

To use IMS from z/OS XL C/C++, you must keep the following in mind:

- The file <ims.h> must be included in the program.
- PLIST(OS) and TARGET(IMS) must be used to compile IMS z/OS XL C/C++ application programs. PLIST(OS) establishes the correct parameter list format when invoked under IMS, and TARGET(IMS) establishes the correct operating environment. The descriptions that follow use the compile-time options. The compile-time option PLIST(OS) can alternatively be specified using #pragma runopts(PLIST(OS)).
- TARGET(IMS) is mandatory, as it establishes the correct operating environment. PLIST(OS) must also be used if the program is the initial main() program called under IMS. Programs in nested enclaves do not need to be compiled with PLIST(OS).
- The argument count (argc) will be set to one (1), and the first element in the argument vector (argv[0]) will contain a NULL string when compiled with z/OS XL C compiler and the deprecated #pragma runopts(PLIST(IMS)) is specified in the source. Otherwise, the argument vector will contain the name of the program.
- IMS provides a language interface module (DFSLI000) that gives a common interface to IMS and DL/I. This module must be link-edited with the application program.

The rest of this chapter is based on the assumption that you are using the ctdli() interface.

Notes:
1. AMODE 64 applications are not supported in an IMS environment.
2. As of V1R2, a non-XPLINK Standard C++ Library DLL allows support for the Standard C++ Library in the IMS subsystem. For further information, see [binding programs in z/OS XL C/C++ User’s Guide](#).
3. XPLINK applications are supported under the IMS environment.
Handling errors

The IMS environments are sensitive to errors and error-handling issues. A failing IMS transaction or program can potentially corrupt an IMS database. IMS must know about the failure of a transaction or program that has been updating a database so that it can back out any updates made by that failing program.

z/OS XL C/C++ provides extensive error-handling facilities for the programmer, but special steps are required to coordinate IMS and C or C++ error handling so that IMS can do its database rollbacks when a program fails.

When you are using IMS from C or C++:

- Run your C or C++ program with the \texttt{TRAP(ON)} option, and use IMS interfaces by calling the \texttt{ctdli()} library function. If your application programs also use SQL facilities provided by DB2, you must modify the user exit \texttt{CEEBXITA} to add the user abend codes 777 and 778 to prevent the error handler from trapping these abends. This will allow deadlocks to be successfully resolved by IMS. See \textit{z/OS Language Environment Programming Guide} for more information on \texttt{CEEBXITA}.
- The \texttt{ctdli()} library function will keep track of calls to and returns from IMS. If an abend or program check occurs and the C or C++ error handler gets control, it can determine if the problem arose on the IMS side of the interface or on the C or C++ side.
- If a program check or abend occurs in IMS, when the C or C++ exception handler gets control, it immediately issues an \texttt{ABEND}. The IMS Region Controller gets control next and ensures that the integrity of the database is preserved.
- If a program check occurs in the C or C++ program rather than in IMS, all the facilities of C or C++ error handling apply, provided that you meet certain conditions when you code your program. For any error condition that arises, you must do one of the following:
  1. Resolve the error completely so that the application can continue.
  2. Have IMS back out the program's updates by issuing a rollback call to IMS, and then terminate the program.
  3. Make sure that the program terminates abnormally and provide an installation-modified runtime user exit that turns all abnormal terminations into operating system \texttt{ABEND}s to effect IMS rollbacks. See \textit{z/OS Language Environment Programming Guide} for more information.

The errors you most likely can fix in your program are arithmetic exception (SIGFPE) conditions. It is unlikely that you can resolve other types of program checks or system abends in your program.

Any program that invokes IMS by way of some other IMS interface should be executed with \texttt{TRAP(OFF)}. You should be sure that the program contains code to issue a rollback call to IMS before terminating after an error. Refer to \textit{z/OS Language Environment Programming Reference} for more information about the limitations of using \texttt{TRAP(OFF)}.

Other considerations

A program communication block (PCB) is a control block used by IMS to describe results of a DL/I call (DB PCB) or the results of a message retrieval or insertion (I/O PCB) made by your program. A valid PCB is one that has been correctly initialized by IMS and passed to you through your C or C++ program. For details on PCBs, refer to "IMS/ESA" on page 1176. See also the sample C-IMS and C++-IMS programs in \textit{z/OS XL C/C++ Runtime Library Reference}. 
If you are running a C program under TSO or IMS, be aware of the effects of PLIST(OS), ENV(IMS), and their combinations when specified using the
#pragma runopts preprocessor directive. Table 347 shows the combinations of
PLIST(OS) and ENV(IMS) and the resulting PCB generated under each of the
environments.

Table 347. PCB generated for C program under TSO and IMS

<table>
<thead>
<tr>
<th>Combination</th>
<th>Running under TSO</th>
<th>Running under IMS</th>
</tr>
</thead>
<tbody>
<tr>
<td>ENV(IMS) only</td>
<td>Invalid PCB</td>
<td>Valid PCB</td>
</tr>
<tr>
<td>PLIST(OS) only</td>
<td>Null PCB</td>
<td>Null PCB</td>
</tr>
<tr>
<td>ENV(IMS) and PLIST(OS)</td>
<td>Invalid PCB</td>
<td>Valid PCB</td>
</tr>
</tbody>
</table>

For more information on the runtime options ENV and PLIST, see z/OS Language
Environment Programming Reference.

If you are running a C or C++ program under TSO or IMS, be aware of the effects
of specifying compiler options PLIST(OS), TARGET(IMS), and their combinations.
Table 348 shows the combinations of PLIST(OS) and TARGET(IMS) and the resulting
PCB generated under each of the environments.

Table 348. PCB generated for C or C++ program under TSO and IMS

<table>
<thead>
<tr>
<th>Combination</th>
<th>Running under TSO</th>
<th>Running under IMS</th>
</tr>
</thead>
<tbody>
<tr>
<td>TARGET(IMS) only</td>
<td>Invalid PCB</td>
<td>Valid PCB</td>
</tr>
<tr>
<td>PLIST(OS) only</td>
<td>Null PCB</td>
<td>Null PCB</td>
</tr>
<tr>
<td>TARGET(IMS) and PLIST(OS)</td>
<td>Invalid PCB</td>
<td>Valid PCB</td>
</tr>
</tbody>
</table>

For both C and C++, specifying PLIST(OS) under either TSO or IMS results in an
argc value of 1 (one), and argv[0] = NULL. For more information on the compiler
options TARGET(IMS) and PLIST(OS), see z/OS XL C/C++ User’s Guide.

Examples

The sample C++ program CCNGIM1 (Figure 239) makes an IMS call and checks
the return code status of the call in IMS batch. Header file CCNGIM3 (Figure 241
on page 940) is included by this program.

/* this is an example of how to use IMS with C++ */

#pragma runopts(env(ims),plist(os))
#include <ims.h>
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include "ccngim3.h"

int main(void) {
    PCB_STRUCT_8_TYPE *locdb_ptr,*orddb_ptr;

    C++ Program using IMS (Part 1 of 2)

Figure 239. C++ Program using IMS
/**
 * IO areas used for DL/I calls
 */

auto IOA2 aio_area, a2io_area;
static IOA2 sio_area;

/**
 * SSAs for DL/I calls
 */

static char qual0[] = "ORDER (ORDKEY =333333)";
static char qual1[] = "ORDITEM ";
static char qual2[] = "DELIVERY ";
static int six = 6;
static int four = 4;
static char gu[5] = "GU ";
static char isrt[5] = "ISRT";

int rc;
int failed = 0;  /* Indicate if any part of test case failed. */

/**
 * Get the pointers to the databases from the parameter list
 */

locdb_ptr = (__pcblist[1]);
orddb_ptr = (__pcblist[2]);

/**
 * Make some calls to the database and change its contents
 */

printf("IMS Test starting\n");
io_area = (IOA2 *)malloc(sizeof(IOA2));

/**
 * Issue a DL/I call with arguments below the line (using CTDLI) */

rc = ctdli(six,gu,orddb_ptr,&aio_area,qual0,qual1,qual2);
if ((orddb_ptr->stat_code[0] == ' ' & & orddb_ptr->stat_code[1]== ' ' & & rc == 0))
    printf("Call to CTDLI returned successfully\n");
else {
    printf("Call to CTDLI returned status of %c%c\n", 
           orddb_ptr->stat_code[0],orddb_ptr->stat_code[1]);
    failed = 1;
}
if (failed == 0)
    printf("Test Successful\n");
else printf("Test Failed");

return(0);

C++ Program using IMS (Part 2 of 2)
Figure 240 shows a sample C program (CCNGIM2) that makes an IMS call and checks the return code status of the call in IMS batch. Header file CCNGIM3 (Figure 241 on page 940) is included by this program.

/* This is an example of how to use IMS with C */

#pragma runopts(env(ims),plist(os))
#include <ims.h>
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include "ccngim3.h"

int main(void) {
    PCB_STRUCT_8_TYPE *locdb_ptr,*orddb_ptr;

    locdb_ptr = (__pcblist[1]);
    orddb_ptr = (__pcblist[2]);

    printf("IMS Test starting\n");
    io_area = malloc(sizeof(IOA2));

    C Program using IMS (Part 1 of 2)

    Figure 240. C Program using IMS
C Program using IMS (Part 2 of 2)

Figure 241 shows the header file (CCNGIM3) that is used by both the C and the C++ examples in Figure 239 on page 937 and Figure 240 on page 939 respectively.

/* this header file is used with the IMS example */

/* ------------------
/* DB PCB           */
/* ------------------*/
typedef struct {
    char db_name[8];
    char seg_level[2];
    char stat_code[2];
    char proc_opt[4];
    int dli;
    char seg_name[8];
    int len_kfb;
    int no_senseg;
    char key_fb[2];
} DB_PCB;
/* ------------------*/
/* IO PCB            */
/* ------------------*/
typedef struct {
    char term[8];
    char ims_res[2];
    char stat_code[2];
    char date[4];
    char time[4];
    int input_seq;
    char output_mess[8];
    char mod_nme[8];
    char user_id[8];
} IO AREA;

Header file for IMS example (Part 1 of 2)

Figure 241. Header file for IMS example
/*------------------*/
/* SPA DATA */
/*------------------*/
typedef struct {
    short int uosploit;
    char uospres1[4];
    char uosptran[8];
    char uospuser;
    char fill[85];
} SPA_DATA;
/*------------------*/
/* INPUT MESSAGE */
/*------------------*/
typedef struct {
    short int ll;
    char zz[2];
    char fill[2];
    char numb[4];
    char nme[6];
} IN_MSG;
/*------------------*/
/* OUTPUT MESSAGE */
/*------------------*/
typedef struct {
    short int ll;
    char z1;
    char z2;
    char fill[2];
    char sca[2];
} OUT_MSG;
/*------------------*/
/* IO AREA */
/*------------------*/
typedef struct {
    char key[20];
} IOA1;

typedef struct {
    char item[40];
} IOA2;

Header file for IMS example (Part 2 of 2)
Chapter 58. Using the Query Management Facility (QMF)

The z/OS XL C/C++ compiler’s support of the Query Management Facility (QMF) interface, a query and report writing facility, enables you to write applications through the SAA callable interface. You can create applications to perform a variety of tasks such as data entry, query building, administration aids, and report analysis.

The z/OS XL C++ compiler itself does not support QMF. However, QMF can be accessed through C code that is statically or dynamically called from C++.

You must include the header file DSQCOMMHC.H (provided with the QMF application), which contains the function and structure definitions necessary to use the QMF interface.

For information on how to write your z/OS XL C/C++ applications with the QMF interface, see the appropriate QMF manual listed in "QMF" on page 1176.

Notes:
1. AMODE 64 applications are not supported by QMF.
2. XPLINK is not supported by QMF.

Example programs

Figure 242 is a sample program (CCNGQM1) that demonstrates the interface between the QMF facility and the z/OS XL C/C++ compiler.

/* this example shows how to use the interface between QMF and C */
#include <string.h>
#include <stdlib.h>
#include <DSQCOMMHC.H> /* QMF header file */

int main(void)
{
  struct dsqcomm communication_area; /* found in DSQCOMM */
  /**********************************************************/
  /* Query interface command length and commands */
  /**********************************************************/
  signed long command_length;
  static char start_query_interface [] = "START";
  static char set_global_variables [] = "SET GLOBAL";
  static char run_query [] = "RUN QUERY Q1";
  static char print_report [] = "PRINT REPORT (FORM=F1)";
  static char end_query_interface [] = "EXIT";
  /**********************************************************/
  /* Query command extension, number of parameters and lengths */
  /**********************************************************/
  signed long number_of_parameters;
  signed long keyword_lengths[10];
  signed long data_lengths[10];

QMF interface example (Part 1 of 3)

Figure 242. QMF interface example
QMF interface example (Part 2 of 3)
Figure 243 is a sample program (CCNGQM2) that demonstrates how a C++ program may call a C program (see Figure 244 on page 946) that accesses QMF.
Sample program CCNGQM3 (Figure 244) is called from the C program shown in Figure 243 on page 945.

/*
this example shows how C++ can access QMF by way of a C program */
/* part 2 of 2-this file is called from C */
/* other file is CCNGQM2 */

#include <string.h>
#include <stdlib.h>
#include <DSQCOMMC.H> /* QMF header file */

int Gen_Report(void)
{
    struct dsqcomm communication_area; /* found in DSQCOMM */

    signed long command_length;
    static char start_query_interface [] = "START";
    static char set_global_variables [] = "SET GLOBAL";
    static char run_query [] = "RUN QUERY Q1";
    static char print_report [] = "PRINT REPORT (FORM=F1)";
    static char end_query_interface [] = "EXIT";

    signed long number_of_parameters;
    signed long keyword_lengths[10];
    signed long data_lengths[10];

    static char char_data_type[] = DSQ_VARIABLE_CHAR;
    static char int_data_type[] = DSQ_VARIABLE_FINT;

    static char start_keywords[] = "DSQSCMD";
    static char start_keyword_values[] = "USERCMD1";

    #define SIZE_VAL 8
    char set_keywords[3][SIZE_VAL];
    signed long set_values[3];

C program that accesses QMF (Part 1 of 3)

Figure 244. C program that accesses QMF
C program that accesses QMF (Part 2 of 3)
C program that accesses QMF (Part 3 of 3)
Part 8. Internationalization: Locales and Character Sets

This part includes the following topics related to Locales and Character Sets:

- Chapter 59, “Introduction to locale,” on page 951
- Chapter 60, “Building a locale,” on page 955
- Chapter 61, “Customizing a locale,” on page 1005
- Chapter 62, “Customizing a time zone,” on page 1013
- Chapter 63, “Definition of S370 C, SAA C, and POSIX C locales,” on page 1015
- Chapter 64, “Code set conversion utilities,” on page 1023
- Chapter 65, “Coded character set considerations with locale functions,” on page 1047
- Chapter 66, “Bidirectional language support,” on page 1065
Chapter 59. Introduction to locale

This topic introduces locales and how they relate to the internationalization of programs.

Internationalization in programming languages

Internationalization in programming languages is a concept that comprises externally stored cultural data, a set of programming tools to create such cultural data, a set of programming interfaces to access this data, and a set of programming methods that enable you to use provided interfaces to write programs that do not make any assumptions about the cultural environments they run in. Such programs modify their behavior according to the user's cultural environment, specified during the program's execution.

Elements of internationalization

The typical elements of cultural environment are as follows:

Native language
The text that the executing program uses to communicate with a user or environment, that is, the natural language of the end user.

Character sets and coded character sets
Map an alphabet, the characters used in a particular language, onto the set of hexadecimal values (code points) that uniquely identify each character. This mapping creates the coded character set, which is uniquely identified by the character set it encodes, the set of code point values, and the mapping between these two.

For example IBM-273, also known as the German Code Page, and IBM-297, also known as the French Code Page, are two coded character sets which assign different EBCDIC encodings in the hexadecimal range 40 to FE to the same Latin Alphabet Number 1. IBM S/390 systems in Germany and France both use this Latin 1 alphabet, which is specified by International Standard ISO/IEC 8859-1. However, systems in Germany are configured for encodings of this alphabet given by IBM-273; whereas, systems in France are configured for encodings of this alphabet given by IBM-297.

IBM-1027, Japanese Latin Code Page, is another example of a coded character set. It assigns EBCDIC encodings in the hexadecimal range 40 to FE to characters specified by Japanese Industrial Standard JIS X 201-1978 plus encodings for a few more Latin characters selected by IBM. The resulting alphabet defined by IBM-1027 consists of some characters found in Latin Alphabet Number 1 and some Katakana characters. IBM S/390 systems in Japan are configured for encodings of this alphabet assigned by IBM-1027.

Collating and ordering
The relative ordering of characters used for sorting.

Character classification
Determines the type of character (alphabetic, numeric, and so forth) represented by a code point.
Character case conversion
Defines the mapping between uppercase and lowercase characters within a single character set.

Date and time format
Defines the way date and time data are formatted (names of weekdays and months; order of month, day, and year, and so forth).

Format of numeric and non-numeric numbers
Define the way numbers and monetary units are formatted with commas, decimal points, and so forth.

z/OS XL C/C++ Support for internationalization
The z/OS XL C/C++ compiler and library support of internationalization is based on the IEEE POSIX P1003.2 and X/Open Portability Guide standards for global locales and coded character set conversion. See Chapter 60, “Building a locale,” on page 955 for more information about locales.

Locales and localization
A locale is a collection of data that encodes information about the cultural environment. Localization is an action that establishes the cultural environment for an application by selecting the active locale. Only one locale can be active at one time, but a program can change the active locale at any time during its execution. The active locale affects the behavior of the locale-sensitive interfaces for the entire program. This is called the global locale model.

Locale-sensitive interfaces
The z/OS XL C/C++ runtime library provides many interfaces to manipulate and access locales. You can use these interfaces to write internationalized C programs. The following list summarizes all the z/OS XL C/C++ library functions which affect or are affected by the current locale.

Selecting locale
Changing the characteristics of the user’s cultural environment by changing the current locale: setlocale()

Querying locale
Retrieving the locale information that characterizes the user’s cultural environment:

Monetary and numeric formatting conventions:
localeconv()

Date and time formatting conventions:
localtconv()

User-specified information:
nl_langinfo()

Encoding of the variant part of the portable character set:
getsyntx()

Character set identifier:
csid(), wcsid()

Classification of characters:
Single-byte characters:
  isalnum(), isalpha(), isblank(), iscntrl(), isdigit(), isgraph(),
  islower(), isprint(), ispunct(), isspace(), isupper(), isxdigit()

Wide characters:
  iswalnum(), iswalpha(), iswblank(), iswcntrl(), iswdigit(),
  iswgraph(), iswlower(), iswprint(), iswpunct(), iswspace(),
  iswupper(), iswxdigit(), wctype(), iswctype()

Character case mapping:

Single-byte characters:
  tolower(), toupper()

Wide characters:
  towlower(), towupper()

Multibyte character and multibyte string conversion:
  mbstrlen(), mbstrlen(), mbtowc(), mbrtowc(), wcrtomb(), mbstowcs(),
  mwstowcs(), wcstombs(), mbsinit(), wctob(), mbtowc16(),
  mbtowc32(), cl6rtomb(), c32rtomb()

String conversions to arithmetic:
  strtod(), wcstod(), strtol(), wcstol(), strtoul(), wcstoul(), atof(),
  atoi(), atol()

String collating:
  strcoll(), strxfrm(), wcscoll(), wcsxfrm()

Character display width:
  wcswidth(), wcwidth()

Date, time, and monetary formatting:
  strftime(), strptime(), wcsftime(), mktime(), ctime(), gmtime(),
  localtime(), strftime()

Formatted input/output:
  printf() (and family of functions), scanf() (and family of functions),
  vswprintf(), swprintf(), swscanf(), snprintf(), vsnprintf()

Processing regular expressions:
  regcomp(), regexec()

Wide character unformatted input/output:
  fgetwc(), fgetws(), fputwc(), fputws(), getwc(), getwchar(), putwc(),
  putwchar(), ungetwc()

Response matching:
  rpmatch()

Collating elements:
  ismccollel(), strtostr(), colltostr(), collequiv(), collrange(),
  collorder(), cclass(), maxcoll(), getmccoll(), getwmccoll()
Chapter 60. Building a locale

Cultural information is encoded in the locale source file using the locale definition language. One locale source file characterizes one cultural environment. See Appendix D, “Locales supplied with z/OS XL C/C++,” on page 1091 for a list of the locale source and object files supplied with the z/OS XL C/C++ compiler.

The locale source file is processed by the locale compilation tool, called the localedef tool.

To enhance portability of the locale source files, certain information related to the character sets can be encoded using the symbolic names of characters. The mapping between the symbolic names and the characters they represent and its associated hexadecimal value is defined in the character set description file or charmap file. See Appendix E, “Charmap files supplied with z/OS XL C/C++,” on page 1117 for a list of the charmap files shipped with your product.

Figure 245 shows the conceptual model of the locale build process.

Limitations of enhanced ASCII

This section explains under what conditions you can use Enhanced ASCII.

- A subset of C headers and functions is provided in ASCII. For more information, see z/OS XL C/C++ Runtime Library Reference.
- The only way to get to the ASCII version of functions and the external variables environ and tzname is to use the appropriate IBM header files.
- ASCII applications may read, but not update, environment variables using the environ external variable. Updates to the environment variables using environ in an ASCII application causes unpredictable results and may result in an abend. Language Environment maintains two equivalent arrays of environment variables when running an ASCII application, one with EBCDIC encodings and the other with ASCII encodings. All ASCII compile units that use the environ external variable must include <stdlib.h> so that environ can be mapped to...
access the ASCII encoded environment strings. If <stdlib.h> is not included, `environ` will refer to the EBCDIC representation of the environment variable strings.

Enhanced ASCII provides limited conversion of ASCII to EBCDIC, and EBCDIC to ASCII. The character set or alphabet that is associated with any locale consists of the following:

- A common, XPG4-defined subset of characters such as POSIX portable characters
- A unique, locale-specific subset of characters such as NLS characters

The conversion only applies to the portable subset of characters that are associated with a locale. Only the EBCDIC IBM-1047 encoding of portable characters is supported.

You might encounter unexpected results in the following situations:

- If Enhanced ASCII applications run in locales that contain non-Latin Alphabet Number 1 NLS characters, C-RTL functions might copy some of the locale’s non-Latin 1 NLS characters into buffers that the application is writing to stdout or another files in the z/OS UNIX file system. The non-Latin Alphabet Number 1 NLS characters would then cause problems during automatic conversion.
- Language Environment applications select non-English message files. If your NATLANG runtime option is not UEN or ENU, messages directed to the Language Environment message file are not converted to ASCII.

### Using the charmap file

The charmap file defines a mapping between the symbolic names of characters and the hexadecimal values associated with the character in a given coded character set. Optionally, it can provide the alternate symbolic names for characters. Characters in the locale source file can be referred to by their symbolic names or alternate symbolic names, thereby allowing for writing generic locale source files independent of the encoding of the character set they represent.

Each charmap file must contain at least the definition of the portable character set and the character symbolic names associated with each character. The characters in the portable character set and the corresponding symbolic names, and optional alternate symbolic names, are defined in Table 349.

<table>
<thead>
<tr>
<th>Symbolic Name</th>
<th>Alternate Name</th>
<th>Character</th>
<th>Hex Value (EBCDIC)</th>
<th>Hex Value (ASCII)</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;NUL&gt;</code></td>
<td></td>
<td>00</td>
<td>00</td>
<td></td>
</tr>
<tr>
<td><code>&lt;tab&gt;</code></td>
<td><code>&lt;SE10&gt;</code></td>
<td>05</td>
<td>09</td>
<td></td>
</tr>
<tr>
<td><code>&lt;vertical-tab&gt;</code></td>
<td><code>&lt;SE12&gt;</code></td>
<td>0b</td>
<td>0b</td>
<td></td>
</tr>
<tr>
<td><code>&lt;form-feed&gt;</code></td>
<td><code>&lt;SE13&gt;</code></td>
<td>0c</td>
<td>0c</td>
<td></td>
</tr>
<tr>
<td><code>&lt;carriage-return&gt;</code></td>
<td><code>&lt;SE14&gt;</code></td>
<td>0d</td>
<td>0d</td>
<td></td>
</tr>
<tr>
<td><code>&lt;newline&gt;</code></td>
<td><code>&lt;SE11&gt;</code></td>
<td>15</td>
<td>0a</td>
<td></td>
</tr>
<tr>
<td><code>&lt;backspace&gt;</code></td>
<td><code>&lt;SE09&gt;</code></td>
<td>16</td>
<td>08</td>
<td></td>
</tr>
<tr>
<td><code>&lt;alert&gt;</code></td>
<td><code>&lt;SE08&gt;</code></td>
<td>2f</td>
<td>07</td>
<td></td>
</tr>
<tr>
<td><code>&lt;space&gt;</code></td>
<td><code>&lt;SP01&gt;</code></td>
<td>40</td>
<td>20</td>
<td></td>
</tr>
<tr>
<td><code>&lt;period&gt;</code></td>
<td><code>&lt;SP11&gt;</code></td>
<td>.</td>
<td>4b</td>
<td>2e</td>
</tr>
</tbody>
</table>
Table 349. Characters in portable character set and corresponding symbolic names (continued)

<table>
<thead>
<tr>
<th>Symbolic Name</th>
<th>Alternate Name</th>
<th>Character</th>
<th>Hex Value (EBCDIC)</th>
<th>Hex Value (ASCII)</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;less-than-sign&gt;</td>
<td>&lt;SA03&gt;</td>
<td>&lt;</td>
<td>4c</td>
<td>3c</td>
</tr>
<tr>
<td>&lt;left-parenthesis&gt;</td>
<td>&lt;SP06&gt;</td>
<td>(</td>
<td>4d</td>
<td>28</td>
</tr>
<tr>
<td>&lt;plus-sign&gt;</td>
<td>&lt;SA01&gt;</td>
<td>+</td>
<td>4e</td>
<td>2b</td>
</tr>
<tr>
<td>&lt;ampersand&gt;</td>
<td>&lt;SM03&gt;</td>
<td>&amp;</td>
<td>50</td>
<td>26</td>
</tr>
<tr>
<td>&lt;right-parenthesis&gt;</td>
<td>&lt;SP07&gt;</td>
<td>)</td>
<td>5d</td>
<td>29</td>
</tr>
<tr>
<td>&lt;semicolon&gt;</td>
<td>&lt;SP14&gt;</td>
<td>;</td>
<td>5e</td>
<td>3b</td>
</tr>
<tr>
<td>&lt;hyphen&gt;</td>
<td>&lt;SP10&gt;</td>
<td>-</td>
<td>60</td>
<td>2d</td>
</tr>
<tr>
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<td>&lt;SP10&gt;</td>
<td>-</td>
<td>60</td>
<td>2d</td>
</tr>
<tr>
<td>&lt;slash&gt;</td>
<td>&lt;SP12&gt;</td>
<td>/</td>
<td>61</td>
<td>2f</td>
</tr>
<tr>
<td>&lt;solidus&gt;</td>
<td>&lt;SP12&gt;</td>
<td>/</td>
<td>61</td>
<td>2f</td>
</tr>
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<td>&lt;SP08&gt;</td>
<td>,</td>
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<td>2c</td>
</tr>
<tr>
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<td>&lt;SM02&gt;</td>
<td>%</td>
<td>6c</td>
<td>25</td>
</tr>
<tr>
<td>&lt;underscore&gt;</td>
<td>&lt;SP09&gt;</td>
<td>_</td>
<td>6d</td>
<td>5f</td>
</tr>
<tr>
<td>&lt;low-line&gt;</td>
<td>&lt;SP09&gt;</td>
<td>_</td>
<td>6d</td>
<td>5f</td>
</tr>
<tr>
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<td>&lt;SA05&gt;</td>
<td>&gt;</td>
<td>6e</td>
<td>3e</td>
</tr>
<tr>
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<td>&lt;SP15&gt;</td>
<td>?</td>
<td>6f</td>
<td>3f</td>
</tr>
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<td>&lt;SP13&gt;</td>
<td>:</td>
<td>7a</td>
<td>3a</td>
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<tr>
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<td>&lt;SP05&gt;</td>
<td>'</td>
<td>7d</td>
<td>27</td>
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<td>&lt;SA04&gt;</td>
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</tr>
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<td>&lt;SP04&gt;</td>
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<tr>
<td>&lt;a&gt;</td>
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</tr>
<tr>
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<td>&lt;LB01&gt;</td>
<td>b</td>
<td>82</td>
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</tr>
<tr>
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<td>63</td>
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</tr>
<tr>
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<td>85</td>
<td>65</td>
</tr>
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<td>g</td>
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<td>&lt;LI01&gt;</td>
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<td>89</td>
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<td>l</td>
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</tr>
<tr>
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<tr>
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<td>o</td>
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<td>6f</td>
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<td>98</td>
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</tr>
<tr>
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<td>Alternate Name</td>
<td>Character</td>
<td>Hex Value (EBCDIC)</td>
<td>Hex Value (ASCII)</td>
</tr>
<tr>
<td>---------------</td>
<td>----------------</td>
<td>-----------</td>
<td>--------------------</td>
<td>-------------------</td>
</tr>
<tr>
<td>&lt;s&gt;</td>
<td>&lt;LS01&gt;</td>
<td>s</td>
<td>a2 73</td>
<td></td>
</tr>
<tr>
<td>&lt;t&gt;</td>
<td>&lt;LT01&gt;</td>
<td>t</td>
<td>a3 74</td>
<td></td>
</tr>
<tr>
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<td>&lt;LU01&gt;</td>
<td>u</td>
<td>a4 75</td>
<td></td>
</tr>
<tr>
<td>&lt;v&gt;</td>
<td>&lt;LU01&gt;</td>
<td>v</td>
<td>a5 76</td>
<td></td>
</tr>
<tr>
<td>&lt;w&gt;</td>
<td>&lt;LW01&gt;</td>
<td>w</td>
<td>a6 77</td>
<td></td>
</tr>
<tr>
<td>&lt;x&gt;</td>
<td>&lt;LX01&gt;</td>
<td>x</td>
<td>a7 78</td>
<td></td>
</tr>
<tr>
<td>&lt;y&gt;</td>
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<td>y</td>
<td>a8 79</td>
<td></td>
</tr>
<tr>
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<td>z</td>
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<td></td>
</tr>
<tr>
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<td>&lt;LA02&gt;</td>
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<td>c1 41</td>
<td></td>
</tr>
<tr>
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<td>&lt;LB02&gt;</td>
<td>B</td>
<td>c2 42</td>
<td></td>
</tr>
<tr>
<td>&lt;C&gt;</td>
<td>&lt;LC02&gt;</td>
<td>C</td>
<td>c3 43</td>
<td></td>
</tr>
<tr>
<td>&lt;D&gt;</td>
<td>&lt;LD02&gt;</td>
<td>D</td>
<td>c4 44</td>
<td></td>
</tr>
<tr>
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<td>&lt;LE02&gt;</td>
<td>E</td>
<td>c5 45</td>
<td></td>
</tr>
<tr>
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<td>&lt;LF02&gt;</td>
<td>F</td>
<td>c6 46</td>
<td></td>
</tr>
<tr>
<td>&lt;G&gt;</td>
<td>&lt;LG02&gt;</td>
<td>G</td>
<td>c7 47</td>
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</tr>
<tr>
<td>&lt;H&gt;</td>
<td>&lt;LH02&gt;</td>
<td>H</td>
<td>c8 48</td>
<td></td>
</tr>
<tr>
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<td>&lt;LI02&gt;</td>
<td>I</td>
<td>c9 49</td>
<td></td>
</tr>
<tr>
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<td>&lt;LJ02&gt;</td>
<td>J</td>
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<td></td>
</tr>
<tr>
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<td>K</td>
<td>d2 4b</td>
<td></td>
</tr>
<tr>
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</tr>
<tr>
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<td>M</td>
<td>d4 4d</td>
<td></td>
</tr>
<tr>
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<td>&lt;LN02&gt;</td>
<td>N</td>
<td>d5 4e</td>
<td></td>
</tr>
<tr>
<td>&lt;O&gt;</td>
<td>&lt;LO02&gt;</td>
<td>O</td>
<td>d6 4f</td>
<td></td>
</tr>
<tr>
<td>&lt;P&gt;</td>
<td>&lt;LP02&gt;</td>
<td>P</td>
<td>d7 50</td>
<td></td>
</tr>
<tr>
<td>&lt;Q&gt;</td>
<td>&lt;LQ02&gt;</td>
<td>Q</td>
<td>d8 51</td>
<td></td>
</tr>
<tr>
<td>&lt;R&gt;</td>
<td>&lt;LR02&gt;</td>
<td>R</td>
<td>d9 52</td>
<td></td>
</tr>
<tr>
<td>&lt;S&gt;</td>
<td>&lt;LS02&gt;</td>
<td>S</td>
<td>e2 53</td>
<td></td>
</tr>
<tr>
<td>&lt;T&gt;</td>
<td>&lt;LT02&gt;</td>
<td>T</td>
<td>e3 54</td>
<td></td>
</tr>
<tr>
<td>&lt;U&gt;</td>
<td>&lt;LU02&gt;</td>
<td>U</td>
<td>e4 55</td>
<td></td>
</tr>
<tr>
<td>&lt;V&gt;</td>
<td>&lt;LV02&gt;</td>
<td>V</td>
<td>e5 56</td>
<td></td>
</tr>
<tr>
<td>&lt;W&gt;</td>
<td>&lt;LW02&gt;</td>
<td>W</td>
<td>e6 57</td>
<td></td>
</tr>
<tr>
<td>&lt;X&gt;</td>
<td>&lt;LX02&gt;</td>
<td>X</td>
<td>e7 58</td>
<td></td>
</tr>
<tr>
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<td>&lt;LY02&gt;</td>
<td>Y</td>
<td>e8 59</td>
<td></td>
</tr>
<tr>
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<td>&lt;LZ02&gt;</td>
<td>Z</td>
<td>e9 5a</td>
<td></td>
</tr>
<tr>
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<td>&lt;ND10&gt;</td>
<td>0</td>
<td>f0 30</td>
<td></td>
</tr>
<tr>
<td>&lt;one&gt;</td>
<td>&lt;ND01&gt;</td>
<td>1</td>
<td>f1 31</td>
<td></td>
</tr>
<tr>
<td>&lt;two&gt;</td>
<td>&lt;ND02&gt;</td>
<td>2</td>
<td>f2 32</td>
<td></td>
</tr>
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<td>&lt;three&gt;</td>
<td>&lt;ND03&gt;</td>
<td>3</td>
<td>f3 33</td>
<td></td>
</tr>
</tbody>
</table>
The portable character set is the basis for the syntactic and semantic processing of the localedef tool, and for most of the utilities and functions that access the locale object files. Therefore the portable character set must always be defined. It is conceptually divided into two parts:

**Invariant**

Characters for which encoding must be constant among all charmap files. The required encoded values are specified in Table 349 on page 956. If any of these values change, the behavior of any utilities and functions on z/OS XL C/C++ is unpredictable. For example, if you are using charmaps such as Turkish IBM-1026 or Japanese IBM-290, where the characters encoded vary from the encoding in Table 349 on page 956, you may get unpredictable results with the utilities and functions.

**Variant**

Characters for which encoding may vary from one EBCDIC charmap file to another. Only the following characters are allowed in this group:
The default EBCDIC encoding of each variant character is shown by a hexadecimal value in parentheses in Table 349 on page 956. It is equivalent to the encoding in code page 1047.

The charmap file is divided into two main sections:
1. the charmap section, or CHARMAP
2. the character set identifier section, or CHARSETID

The following definitions can precede the two sections listed above. Each consists of the symbol shown in the following list, starting in column 1, including the surrounding brackets, followed by one or more `<blank>`s, followed by the value to be assigned to the symbol.

```
<code_set_name>
The string literal containing the name of the coded character set name (IBM-1047, IBM-273, etc.)

<mb_cur_max>
the maximum number of bytes in a multibyte character which can be set to a value between 1 and 4. EBCDIC locales have mb_cur_max settings of either 1 or 4. ASCII locales have mb_cur_max settings of 1, 2 or 3.

If it is 1, each character in the character set defined in this charmap is encoded by a one-byte value. If it is 4, each character in the character set defined in this charmap is encoded by a one-, two-, three-, or four-byte value. If it is not specified, the default value of 1 is assumed. If a value of other than 1 or 4 is specified for an EBCDIC locale, a warning message is issued and the default value of 1 is assumed.

For ASCII locales mb_cur_max is defined as 1, 2 or 3. The value 1 means the same as for EBCDIC locales, while the values 2 and 3 mean 2 and 3 bytes per character respectively.

<mb_cur_min>
The minimum number of bytes in a multibyte character. Can be set to 1 only. If a value of other than 1 is specified, a warning message is issued and the default value of 1 is assumed.

<escape_char>
Specifies the escape character that is used to specify hexadecimal or octal notation for numeric values. It defaults to the hexadecimal value 0xe0, which represents the \ character in the coded character set IBM-1047. For portability among the EBCDIC based systems, the escape character has been redefined to the / or `<slash>` character in all IBM-supplied charmap files, with the following statement:

<escape_char> /
### The CHARMAP section

The CHARMAP section defines the values for the symbolic names representing characters in the coded character set. Each charmap file must define at least the portable character set. The character symbolic names or alternate symbolic names (or both) must be used to define the portable character set. These are shown in Table 349 on page 956.

Additional characters can be defined by the user with symbolic character names.

The CHARMAP section starts with the line containing the keyword CHARMAP, and ends with the line containing the keywords END CHARMAP. CHARMAP and END CHARMAP must both start in column one.

The character set mapping definitions are all the lines between the first and last lines of the CHARMAP section. The formats of the character set mappings for this section are as follows:

```
"%s %s %s\n", <symbolic-name>, <encoding>, <comments>
"%s...%s %s %s\n", <symbolic-name>, <symbolic-name>, <encoding>, <comments>
```

The first format defines a single symbolic name and a corresponding encoding. A symbolic name is one or more characters with visible glyphs, enclosed between angle brackets.

For reasons of portability, a symbolic name should include only the characters from the invariant part of the portable character set. If you use variant characters or decimal or hexadecimal notation in a symbolic name, the symbolic name will not be portable. A character following an escape character is interpreted as itself; for example, the sequence `<\\>` represents the symbolic name `\` enclosed within angle brackets, where the backslash `\` is the escape character. If `/` is the escape character, the sequence `<//>` represents the symbolic name `/`. In the supplied charmap files, the escape character has been redefined to the forward slash `/`.  

---

<comment_char>

Denotes the character chosen to indicate a comment within a charmap file. It defaults to the hexadecimal value 0x7b, which represents the `#` character in the coded character set IBM-1047. For portability among the EBCDIC based systems, the comment character has been redefined to the `%` or `<percent-sign>` character in all IBM-supplied charmap files, with the following statement:

```
<comment_char> %
```

<shift_out>

Specifies the value of the shift-out control character that indicates the start of a string of double-byte characters. If specified, it must be the value of the EBCDIC shift-out (SO) character (hexadecimal value 0x0e). It is ignored if the `<mb_cur_max>` value is 1.

<shift_in>

Specifies the value of the shift-in control character that indicates the end of a string of double-byte characters. If specified, it must be the value of the EBCDIC shift-in (SI) character (hexadecimal value 0x0f). It is ignored if the `<mb_cur_max>` value is 1.
The second format defines a group of symbolic names associated with a range of values. The two symbolic names are comprised of two parts, a prefix and suffix. The prefix consists of zero or more non-numeric invariant visible glyph characters and is the same for both symbolic names. The suffix consists of a positive decimal integer. The suffix of the first symbolic name must be less than or equal to the suffix of the second symbolic name. As an example, \texttt{j0101...j0104} is interpreted as the symbolic names \texttt{j0101}, \texttt{j0102}, \texttt{j0103}, \texttt{j0104}. The common prefix is \texttt{j} and the suffixes are \texttt{0101} and \texttt{0104}.

The encoding part can be written in one of two forms:

- \texttt{<escape-char><number>} (single byte value)
- \texttt{<escape-char><number><escape-char><number>} (double byte value)

The number can be written using octal, decimal, or hexadecimal notation. Decimal numbers are written as a \texttt{d} followed by 2 or 3 decimal digits. Hexadecimal numbers are written as an \texttt{x} followed by 2 hexadecimal digits. An octal number is written with 2 or 3 octal digits. As an example, the single byte value \texttt{x1F} could be written as \texttt{\37}, \texttt{\x1F}, or \texttt{\d31}.

The double byte value of \texttt{0x1A1F} could be written as \texttt{\32\37}, \texttt{\x1A\x1F}, or \texttt{\d26\d31}.

In lines defining ranges of symbolic names, the encoded value is the value for the first symbolic name in the range (the symbolic name preceding the ellipsis). Subsequent names defined by the range have encoding values in increasing order.

When constants are concatenated for multibyte character values, they must be of the same type, and are interpreted in byte order from first to last with the least significant byte of the multibyte character specified by the last constant. Each value is then prepended by the byte value of <shift_out> and appended with the byte value of <shift_in>. Such a string represents one EBCDIC multibyte character, as the following example shows:

```
<escape_char> %
<comment_char> %
<mb_cur_max> 4
<mb_cur_min> 1
<shift-out> /x0e
<shift-in> /x0f

CHARMAP
% many definition lines
<j0101>...<j0104> /d129/d254
%many definition lines
END CHARMAP
```

is interpreted as:

\begin{verbatim}
j0101 /d129/d254
j0102 /d129/d255
j0103 /d130/d0
j0104 /d130/d1
\end{verbatim}

It produces four 4-byte long multibyte EBCDIC characters:

\begin{verbatim}
j0101 x0Ex81xFEx0F
j0102 x0Ex81xFFx0F
j0103 x0Ex82x00x0F
j0104 x0Ex82x01x0F
\end{verbatim}
The CHARSETID section

The character set identifier section of the charmap file maps the symbolic names defined in the CHARMAP section to a character set identifier.

Note: The two functions csid() and wcsid() query the locales and return the character set identifier for a given character. This information is not currently used by any other library function.

The CHARSETID section starts with a line containing the keyword CHARSETID, and ends with the line containing the keywords END CHARSETID. Both CHARSETID and END CHARSETID must begin in column 1. The lines between the first and last lines of the CHARSETID section define the character set identifier for the defined coded character set.

The character set identifier mappings are defined as follows:

```
"%s %c", <symbolic-name>, <value>
"%c %c", <value>, <value>
"%s...%s %c", <symbolic-name>, <symbolic-name>, <value>
"%c...%c %c", <value>, <value>
"%s...%c %c", <symbolic-name>, <value>, <value>
"%c...%s %c", <value>, <symbolic-name>, <value>
```

The individual characters are specified by the symbolic name or the value. The group of characters are specified by two symbolic names or by two numeric values (or combination) separated by an ellipsis (...). The interpretation of ranges of values is the same as specified in the CHARMAP section. The character set identifier is specified by a numeric value.
Locale source files

Locales are defined through the specification of a locale definition file. The locale definition contains one or more distinct locale category source definitions and not more than one definition of any category. Each category controls specific aspects of the cultural environment. A category source definition is either the explicit definition of a category or the copy directive, which indicates that the category definition should be copied from another locale definition file.

ASCII locales must be specified using only the characters from the portable character set, and all character references must be symbolic names, not explicit code point values.

The definition file is composed of an optional definition section for the escape and comment characters to be used, followed by the category source definitions. Comment lines and blank lines can appear anywhere in the locale definition file. If the escape and comment characters are not defined, default code points are used (x00 for the escape character and x00 for the comment character, respectively). The definition section consists of the following optional lines, where <character> in both cases is a single-byte character to be used:

```
escape_char <character>
comment_char <character>
```

For example, the following statement defines the escape character in this file to be '/\' (the <slash> character).
```
escape_char /
```

Locale definition files passed to the localedef utility are assumed to be in coded character set IBM-1047.

To ensure portability among EBCDIC systems, you should redefine these characters to characters from the invariant part of the portable character set. The suggested redefinition is:
```
escape_char /
comment_char %
```

This suggested redefinition is used in all locale definition files supplied by IBM. For reasons of portability, you should use the suggested redefinition in all your customized locale definition files. See Chapter 61, “Customizing a locale,” on page 1005 for information about customizing locales. These two redefinitions should be placed in the first lines of the locale definition source file, before any of the redefined characters are used.

Each category source definition consists of a category header, a category body, and a category trailer, in that order.

category header

consists of the keyword naming the category. Each category name starts with the characters LC. The following category names are supported: LC_CTYPE, LC_COLLATE, LC_NUMERIC, LC_MONETARY, LC_TIME, LC_MESSAGES, LC_TOD, and LC_SYNTAX.

The LC_TOD and LC_SYNTAX categories, if present, must be the last two categories in the locale definition file.
category body
consists of one or more lines describing the components of the category. Each component line has the following format:

\(<\text{identifier}> \ <\text{operand1}>\)
\(<\text{identifier}> \ <\text{operand1};;\text{operand2};;\ldots;;\text{operandN}>\)

\(<\text{identifier}>\) is a keyword that identifies a locale element, or a symbolic name that identifies a collating element. \(<\text{operand}>\) is a character, collating element, or string literal. Escape sequences can be specified in a string literal using the \(<\text{escape_character}>\). If multiple operands are specified, they must be separated by semicolons. White space can be before and after the semicolons.

category trailer
consists of the keyword \text{END} followed by one or more \text{blank}s and the category name of the corresponding category header.

\text{Figure 246} is an example of locale source containing the header, body, and trailer.

\begin{verbatim}
escape_char /
comment_char %
%
% Here is a simple locale definition file consisting of one
% category source definition, LC_CTYPE.
%
LC_CTYPE
upper <A>;;<Z>
END LC_CTYPE
\end{verbatim}

\text{Figure 246. Example locale source containing header, body, and trailer}

You do not have to define each category. Where category definitions are absent from the locale source, default definitions are used.

In each category, the keyword \text{copy} followed by a string specifies the name of an existing locale to be used as the source for the definition of this category.

If the locale is not found, an error is reported and no locale output is created.

For the batch (EDC(X)LDEF proc) and TSO (LOCALDEF) commands, the name must be the member name of a partitioned data set allocated to the EDCLOCL DD statement. For the UNIX System Services localedef command, the \text{copy} keyword specifies the path name of the source file.

You can continue a line in a locale definition file by placing an escape character as the last character on the line. This continuation character is discarded from the input. Even though there is no limitation on the length of each line, for portability reasons it is suggested that each line be no longer than 2048 characters (bytes). There is no limit on the accumulated length of a continued line. You cannot continue comment lines on a subsequent line by using an escaped \text{newline}.

Individual characters, characters in strings, and collating elements are represented using symbolic names, as defined below. Characters can also be represented as the characters themselves, or as octal, hexadecimal, or decimal constants. If you use non-symbolic notation, the resultant locale definition file may not be portable.
among systems and environments. The left angle bracket (<) is a reserved symbol, denoting the start of a symbolic name; if you use it to represent itself, you must precede it with the escape character.

The following rules apply to the character representation:

1. A character can be represented by a symbolic name, enclosed within angle brackets. The symbolic name, including the angle brackets, must exactly match a symbolic name defined in the charmap file. The symbolic name is replaced by the character value determined from the value associated with the symbolic name in the charmap file.
   The use of a symbolic name not found in the charmap file constitutes an error, unless the name is in the category LC_CTYPE or LC_COLLATE, in which case it constitutes a warning. Use of the escape character or right angle bracket within a symbolic name is invalid unless the character is preceded by the escape character. For example:

   `<c><c-cedilla>`
   specifies two characters whose symbolic names are "c" and "c-cedilla"

   `<M><a><y>`
   specifies a 3-character string composed of letters represented by symbolic names "M", "a", and "y"

   `<a><\>`
   specifies a 2-character string composed of letters represented by symbolic names "a" and ">" (assuming the escape character is ")

   If the character represented by the symbolic name is a multibyte character defined by 2 byte values in the charmap file, and the shift-out and shift-in characters are defined, the value is enclosed within shift-out and shift-in characters before the localedef utility processes it any further.

2. A character can represent itself. Within a string, the double quotation mark, the escape character, and the left angle bracket must be escaped (preceded by the escape character) to be interpreted as the characters themselves. For example:

   `c`               'c' character represented by itself

   "may"             represents a 3-character string, each character within the string represented by itself

   "\%\%\%\%>"     represents the three character long string "\%\%\%\%>", where the escape character is defined as %

3. A character can be represented as an octal constant. An octal constant is specified as the escape character followed by two or more octal digits. Each constant represents a byte value.
   For example: \131 "\212\129\168" \16\66\193\17

4. A character can be represented as a hexadecimal constant. A hexadecimal constant is specified as the escape character, followed by an x, followed by two or more hexadecimal digits. Each constant represents a byte value.
   For example: \x83 "\xD4\xB1\xA8"

5. A character can be represented as a decimal constant. A decimal constant is specified as the escape character followed by a d followed by two or more decimal digits. Each constant represents a byte value.
   For example: \d131 "\d212\d129\d168" \d14\d66\d193\d15
For multibyte characters, the entire encoding sequence, including the shift-out and shift-in characters, must be present. Otherwise, the sequence of bytes not enclosed between the shift-out and shift-in characters are interpreted as a sequence of single byte characters.

Multibyte characters can be represented by concatenating constants specified in byte order with the last constant specifying the least significant byte of the character. If the sequence of octal, hexadecimal, or decimal constants is to represent a multibyte character, it must be enclosed in shift-out and shift-in constants. For example: \x0e\x42\xC1\x0f

**LC_CTYPE category**

This category defines character classification, case conversion, and other character attributes. In this category, you can represent a series of characters by using three adjacent periods as an ellipsis symbol (...). An ellipsis is interpreted as including all characters with an encoded value higher than the encoded value of the character preceding the ellipsis and lower than the encoded value following the ellipsis.

An ellipsis is valid within a single encoded character set. For example, \x30;...;\x39; includes in the character class all characters with encoded values from X'30' to X'39'.

The keywords recognized in the LC_CTYPE category are listed below. In the descriptions, the term “automatically included” means that it is not an error either to include or omit any of the referenced characters; they are assumed by default even if the entire keyword is missing and accepted if present. If a keyword is specified without any arguments, the default characters are assumed.

When a character is automatically included, it has an encoded value dependent on the charmap file in effect. If no charmap file is specified, the encoding of the encoded character set IBM-1047 is assumed.

**copy** Specifies the name of an existing locale to be used as the source for the definition of this category. If this keyword is specified, no other keywords are present in this category. If the locale is not found, an error is reported and no locale output is created. The copy keyword cannot specify a locale that also specifies the copy keyword for the same category.

**charclass** Defines one or more locale-specific character class names as strings separated by semicolons. Each named character class can then be defined subsequently in the LC_CTYPE definition. A character class name consists of at least one and at most (CHARCLASS_NAME_MAX) bytes of alphanumeric characters from the portable filename character set. The first character of a character class name cannot be a digit. The name cannot match any of the LC_CTYPE keywords defined in this document.

**upper** Defines characters to be classified as uppercase letters. No character defined for the keywords cntrl, digit, punct, or space can be specified. The uppercase letters A through Z are automatically included in this class. The isupper() and iswupper() functions test for any character and wide character, respectively, included in this class.

**lower** Defines characters to be classified as lowercase letters. No character defined for the keywords cntrl, digit, punct, or space can be specified. The lowercase letters a through z are automatically included in this class.
The *islower()* and *iswlower()* functions test for any character and wide character, respectively, included in this class.

**alpha** Defines characters to be classified as letters. No character defined for the keywords *cntrl*, *digit*, *punct*, or *space* can be specified. Characters classified as either *upper* or *lower* are automatically included in this class. The *isalpha()* and *iswalpha()* functions test for any character or wide character, respectively, included in this class.

**digit** Defines characters to be classified as numeric digits. Only the digits 0, 1, 2, 3, 4, 5, 6, 7, 8, 9 can be specified. If they are, they must be in contiguous ascending sequence by numerical value. The digits 0 through 9 are automatically included in this class. The *isdigit()* and *iswdigit()* functions test for any character or wide character, respectively, included in this class.

**space** Defines characters to be classified as whitespace characters. No character defined for the keywords *upper*, *lower*, *alpha*, *digit*, or *xdigit* can be specified for *space*. The characters `<space>`, `<form-feed>`, `<newline>`, `<carriage-return>`, `<horizontal-tab>`, and `<vertical-tab>`, and any characters defined in the class *blank* are automatically included in this class. The functions *isspace()* and *iswspace()* test for any character or wide character, respectively, included in this class.

**cntrl** Defines characters to be classified as control characters. No character defined for the keywords *upper*, *lower*, *alpha*, *digit*, *punct*, *graph*, *print*, or *xdigit* can be specified for *cntrl*. The functions *iscntrl()* and *iswcntrl()* test for any character or wide character, respectively, included in this class.

**punct** Defines characters to be classified as punctuation characters. No character defined for the keywords *upper*, *lower*, *alpha*, *digit*, *cntrl*, or *xdigit*, or as the `<space>` character, can be specified. The functions *ispunct()* and *iswpunct()* test for any character or wide character, respectively, included in this class.

**graph** Defines characters to be classified as printing characters, not including the `<space>` character. Characters specified for the keywords *upper*, *lower*, *alpha*, *digit*, *xdigit*, and *punct* are automatically included. No character specified in the keyword *cntrl* can be specified for *graph*. The functions *isgraph()* and *iswgraph()* test for any character or wide character, respectively, included in this class.

**print** Defines characters to be classified as printing characters, including the `<space>` character. Characters specified for the keywords *upper*, *lower*, *alpha*, *digit*, *xdigit*, *punct*, and the `<space>` character are automatically included. No character specified in the keyword *cntrl* can be specified for *print*. The functions *isprint()* and *iswprint()* test for any character or wide character, respectively, included in this class.

**xdigit** Defines characters to be classified as hexadecimal digits. Only the characters defined for the class *digit* can be specified, in contiguous ascending sequence by numerical value, followed by one or more sets of six characters representing the hexadecimal digits 10 through 15, with each set in ascending order (for example, A, B, C, D, E, F, a, b, c, d, e, f). The digits 0 through 9, the uppercase letters A through F, and the lowercase letters a through f are automatically included in this class. The functions *isxdigit()* and *iswxdigit()* test for any character or wide character, respectively, included in this class.
**blank**  Defines characters to be classified as blank characters. The characters <space> and <tab> are automatically included in this class. The functions isblank() and iswblank() test for any character or wide character, respectively, included in this class.

**toupper**  Defines the mapping of lowercase letters to uppercase letters. The operand consists of character pairs, separated by semicolons. The characters in each character pair are separated by a comma; the pair is enclosed in parentheses. The first character in each pair is the lowercase letter, and the second is the corresponding uppercase letter. Only characters specified for the keywords lower and upper can be specified for toupper. The lowercase letters a through z, their corresponding uppercase letters A through Z, are automatically in this mapping, but only when the toupper keyword is omitted from the locale definition. It affects the behavior of the toupper() and towupper() functions for mapping characters and wide characters, respectively.

**tolower**  Defines the mapping of uppercase letters to lowercase letters. The operand consists of character pairs, separated by semicolons. The characters in each character pair are separated by a comma; the pair is enclosed by parentheses. The first character in each pair is the uppercase letter, and the second is its corresponding lowercase letter. Only characters specified for the keywords lower and upper can be specified. If the tolower keyword is omitted from the locale definition, the mapping is the reverse mapping of the one specified for the toupper. The tolower keyword affects the behavior of the tolower() and towlower() functions for mapping characters and wide characters, respectively.

You may define additional character classes using your own keywords. A maximum of 31 classes are supported in total: the 12 standard classes, and up to 19 user-defined classes. The defined classes affect the behavior of wctype() and iswctype() functions.

[Figure 247 on page 970](#) is an example of the definition of the LC_CTYPE category.
**LC_COLLATE category**

A collation sequence definition defines the relative order between collating elements (characters and multicharacter collating elements) in the locale. This order is expressed in terms of collation values. It assigns each element one or more collation values (also known as collation weights). The collation sequence definition is used by regular expressions, pattern matching, and sorting and collating functions. The following capabilities are provided:

1. **Multicharacter collating elements.** Specification of multicharacter collating elements (sequences of two or more characters to be collated as an entity).

2. **User-defined ordering of collating elements.** Each collating element is assigned a collation value defining its order in the character (or basic) collation sequence. This ordering is used by regular expressions and pattern matching, and unless collation weights are explicitly specified, also as the collation weight to be used in sorting.

3. **Multiple weights and equivalence classes.** Collating elements can be assigned 1 to 6 collating weights for use in sorting. The first weight is referred to as the primary weight.

4. **One-to-many mapping.** A single character is mapped into a string of collating elements.

5. **Many-to-many substitution.** A string of one or more characters are mapped to another string (or an empty string). The character or characters are ignored for collation purposes.

**Note:** This is an IBM extension; therefore, locales that use it may not be portable to localedef tools developed by other vendors.

---

```c
escpec_char       /
comment_char      \%

% LC_COLLATE
% LC_CTYPE
%
% upper letters are A-Z by default plus the three defined below
upper  <A-acute>;<A-grave>;<C-acute>
%
% lower case letters are a-z by default plus the three defined below
lower  <a-acute>;<a_grave>;<c-acute>
%
% space characters are default 6 characters plus the one defined below
space  <hyphen-minus>
%
% default graph, print, punct, digit, xdigit, blank classes
%
% toupper mapping defined only for the following three pairs
toupper  (<a-acute>,<A-acute>);/
       (<a-grave>,<A-grave>);/
       (<c-acute>,<C-acute>);
%
% default upper to lower case mapping
%
% user defined class
myclass  <e-ogonek>;<E-ogonek>
%
END LC_CTYPE
```

*Figure 247. Example LC_CTYPE definition*
6. **Equivalence class definition.** Two or more collating elements have the same collation value (primary weight).

7. **Ordering by weights.** When two strings are compared to determine their relative order, the two strings are first broken up into a series of collating elements. Each successive pair of elements is compared according to the relative primary weights for the elements. If they are equal, and more than one weight is assigned, then the pairs of collating elements are compared again according to the relative subsequent weights, until either two collating elements are not equal or the weights are exhausted.

**Collating rules**

Collation rules consist of an ordered list of collating order statements, ordered from lowest to highest. The `<NULL>` character is considered lower than any other character. The ellipsis symbol ("...") is a special collation order statement. It specifies that a sequence of characters collate according to their encoded character values. It causes all characters with values higher than the value of the `<collating-identifier>` in the preceding line, and lower than the value for the `<collating-identifier>` on the following line, to be placed in the character collation order between the previous and the following collation order statements in ascending order according to their encoded character values.

The use of the ellipsis symbol ties the definition to a specific coded character set and may preclude the definition from being portable among implementations.

The ellipsis symbol can precede or succeed the ellipsis symbol and may also have weights on the same line.

A collating order statement describes how a collating identifier is weighted.

Each `<collating-identifier>` consists of a character, `<collating-element>`, `<collating-symbol>`, or the special symbol UNDEFINED. The order in which collating elements are specified determines the character order sequence, such that each collating element is considered lower than the elements following it. The `<NULL>` character is considered lower than any other character. Weights are expressed as characters, `<collating-symbol>`, `<collating-element>`, or the special symbol IGNORE. A single character, a `<collating-symbol>`, or a `<collating-element>` represents the relative position in the character collating sequence of the character or symbol, rather than the character or characters themselves. Thus rather than assigning absolute values to weights, a particular weight is expressed using the relative "order value" assigned to a collating element based on its order in the character collation sequence.

A `<collating-element>` specifies multicharacter collating elements, and indicates that the character sequence specified by the `<collating-element>` is to be collated as a unit and in the relative order specified by its place.

A `<collating-symbol>` can define a position in the relative order for use in weights.

The `<collating-symbol>` UNDEFINED is interpreted as including all characters not specified explicitly. Such characters are inserted in the character collation order at the point indicated by the symbol, and in ascending order according to their encoded character values. If no UNDEFINED symbol is specified, and the current coded character set contains characters not specified in this clause, the localedef utility issues a warning and places such characters at the end of the character collation order.
The syntax for a collation order statement is:
<collating-identifier> <weight1>;<weight2>;...;<weightn>

Collation of two collating identifiers is done by comparing their relative primary weights. This process is repeated for successive weight levels until the two identifiers are different, or the weight levels are exhausted. The operands for each collating identifier define the primary, secondary, and subsequent relative weights for the collating identifier. Two or more collating elements can be assigned the same weight. If two collating identifiers have the same primary weight, they belong to the same equivalence class.

The special symbol IGNORE as a weight indicates that when strings are compared using the weights at the level where IGNORE is specified, the collating element should be ignored, as if the string did not contain the collating element. In regular expressions and pattern matching, all characters that are IGNOREd in their primary weight form an equivalence class.

All characters specified by an ellipsis are assigned unique weights, equal to the relative order of the characters. Characters specified by an explicit or implicit UNDEFINED special symbol are assigned the same primary weight (they belong to the same equivalence class).

One-to-many mapping is indicated by specifying two or more concatenated characters or symbolic names. For example, if the character "<ezset>" is given the string "<s><s>" as a weight, comparisons are performed as if all occurrences of the character <ezset> are replaced by <s><s> (assuming <s> has the collating weight <s>). If it is desirable to define <ezset> and <s><s> as an equivalence class, then a collating element must be defined for the string "ss".

If no weight is specified, the collating identifier is interpreted as itself. For example, the order statement

\(<a>\ <a>\)

is equivalent to

\(<a>\)

**Collating keywords**

The following keywords are recognized in a collation sequence definition.

- **copy** Specifies the name of an existing locale to be used as the source for the definition of this category. If this keyword is specified, no other keyword shall be present in this category. If the locale is not found, an error is reported and no locale output is created. The copy keyword cannot specify a locale that also specifies the copy keyword for the same category.

- **collating-element** Defines a collating-element symbol representing a multicharacter collating element. This keyword is optional. In addition to the collating elements in the character set, the collating-element keyword can be used to define multicharacter collating elements. The syntax is:

  "collating-element %s from %s\", <collating-element>, <string>

  The <collating-element> should be a symbolic name enclosed between angle brackets (< and >), and should not duplicate any symbolic name in the current charmap file (if any), or any other symbolic name defined in this collation definition. The string operand is a string of two or more characters.
characters that collate as an entity. A `<collating-element>` defined with 
this keyword is only recognized within the LC_COLLATE category. For 
example:
collating-element <ch> from "<c><h>
collating-element <e-acute> from "<acute><e>
collating-element <ll> from "ll"

**collating-symbol**

Defines a collating symbol for use in collation order statements.

The `collating-symbol` keyword defines a symbolic name that can be 
associated with a relative position in the character order sequence. While 
such a symbolic name does not represent any collating element, it can be 
used as a weight. This keyword is optional.

This construct can define symbols for use in collation sequence statements, 
between the `order_start` and `order_end` keywords. The syntax is:
"collating-symbol %s", <collating-symbol>

The `<collating-symbol>` must be a symbolic name, enclosed between 
angle brackets (< and >), and should not duplicate any symbolic name in 
the current charmap file (if any), or any other symbolic name defined in 
this collation definition. A `<collating-symbol>` defined with this keyword 
is only recognized within the LC_COLLATE category.

For example:
collating-symbol <UPPER_CASE>
collating-symbol <HIGH>

**substitute**

The `substitute` keyword defines a substring substitution in a string to be 
collated. This keyword is optional. The following operands are supported 
with the `substitute` keyword:
"substitute %s with %s", <regular-exp>, <replacement>

The first operand is treated as a basic regular expression. The replacement 
operand consists of zero or more characters and regular expression 
back-references (for example, \1 through \9). The back-references consist of 
the backslash followed by a digit from 1 to 9. If the backslash is followed 
by two or three digits, it is interpreted as an octal constant.

When strings are collated according to a collation definition containing 
substitute statements, the collation behaves as if occurrences of substrings 
matching the basic regular expression are replaced by the replacement 
string, before the strings are compared based on the specified collation 
sequence. Ranges in the regular expression are interpreted according to the 
current character collation sequence and character classes according to the 
character classification specified by the LC_CTYPE environment variable at 
collation time. If more than one substitute statement is present in the 
collation definition, the collation process behaves as if the substitute 
statements are applied to the strings in the order they occur in the source 
definition. The substitution for the substitute statements are processed 
before any substitutions for one-to-many mappings. The support of the 
"substitute" keyword is an IBM z/OS XL C/C++ extension to the POSIX 
standard.

**Note:** This is an IBM extension; therefore, locales that use it may not be 
portable to localedef tools developed by other vendors.
order_start

Define collating rules. This statement is followed by one or more collation
order statements, assigning character collation values and collation weights
to collating elements.

The order_start keyword must precede collation order entries. It defines
the number of weights for this collation sequence definition and other
collation rules. The syntax of the order_start keyword is:

order_start <sort-rule1>; <sort-rule2>; ...; <sort-ruleN>

The operands of the order_start keyword are optional. If present, the
operands define rules to be applied when strings are compared. The
number of operands define how many weights each element is assigned; if
no operands are present, one forward operand is assumed. If any is
present, the first operand defines rules to be applied when comparing
strings using the first (primary) weight; the second when comparing
strings using the second weight, and so on. Operands are separated by
semicolons (;). Each operand consists of one or more collation directives
separated by commas (,). If the number of operands exceeds the limit of 6,
the localedef utility issues a warning message.

The following directives are supported:

forward
    specifies that comparison operations for the weight level proceed
    from the start of the string towards its end.

backward
    specifies that comparison operations for the weight level proceed
    from the end of the string toward its beginning.

no-substitute
    no substitution is performed, such that the comparison is based on
    collation values for collating elements before any substitution
    operations are performed.

Notes:
1. This is an IBM extension; therefore, locales that use it may not
   be portable to localedef tools developed by other vendors.
2. When the no-substitute keyword is specified, one-to-many
   mappings are ignored.

position
    specifies that comparison operations for the weight level must
    consider the relative position of non-IGNOREd elements in the
    strings. The string containing a non-IGNOREd element after the
    fewest IGNOREd collating elements from the start of the comparison
collates first. If both strings contain a non-IGNOREd character in the
    same relative position, the collating values assigned to the elements
determine the order. If the strings are equal, subsequent
    non-IGNOREd characters are considered in the same manner.

order_end

The collating order entries are terminated with an order_end keyword.

Figure 248 on page 975 is an example of an LC_COLLATE category.
The example is interpreted as follows:

1. collating elements
   - Character `<c>` followed by `<h>` collate as one entity named `<ch>`
   - Character `<C>` followed by `<h>` collate as one entity named `<Ch>`
   - Character `<s>` followed by `<z>` collate as one entity named `<eszet>`

2. collating symbols `<LOW>`, `<UPPER-CASE>`, `<LOWER-CASE>` and `<NONE>` are defined to be used in relative order definition

3. up to 3 string comparisons are defined:
   - First pass starts from the beginning of the strings
   - Second pass starts from the end of the strings, and
   - Third pass starts from the beginning of the strings

4. the collating weights are defined such that
   - `<LOW>` collates before `<UPPER-CASE>`,
   - `<UPPER-CASE>` collates before `<LOWER-CASE>`,
   - `<LOWER-CASE>` collates before `<NONE>`;

5. all characters for which collation is not specified here are ordered after `<NONE>`, and before `<space>` in ascending order according to their encoded values

6. all characters with an encoded value larger than the encoded value of `<space>` and lower than the encoded value of `<quotation-mark>` in the current encoded character set, collate in ascending order according to their values;
7. `<a>` has a:
   • primary weight of `<a>`,
   • secondary weight `<NONE>`,
   • tertiary weight of `<LOWER-CASE>`,

8. `<A>` has a:
   • primary weight of `<a>`,
   • secondary weight of `<NONE>`,
   • tertiary weight of `<UPPER-CASE>`,

9. the weights of `<s>` and `<z>` are determined in a similar fashion to `<a>` and `<A>`.

10. `<a-acute>` has a:
    • primary weight of `<a>`,
    • secondary weight of `<a-acute>` itself,
    • tertiary weight of `<LOWER-CASE>`,

11. the weights of `<a-grave>`, `<A-acute>`, `<A-grave>`, `<ch>` and `<Ch>` are determined in a similar fashion to `<a-acute>`.

12. `<eszet>` has a:
    • primary weight determined by replacing each occurrence of `<eszet>` with the sequence of two `<s>`'s and using the weight of `<s>`,
    • secondary weight determined by replacing each occurrence of `<eszet>` with the sequence of `<eszet>` and `<s>` and using their weights,
    • tertiary weight is the relative position of `<LOWER-CASE>`.

**Comparison of strings**

Compare the strings `s1=“aAch”` and `s2=“AaCh”` using the above `LC_COLLATE` definition:

1. `s1=> "aA<ch>"`, and `s2=> "Aa<Ch>"`

2. first pass:
   a. substitute the elements of the strings with their primary weights: `s1=> "<a><a><ch>"`, `s2=> "<a><a><ch>"`
   b. compare the two strings starting with the first element — they are equal.

3. second pass:
   a. substitute the elements of the strings with their secondary weights: `s1=> "<NONE><NONE><NONE>"`, `s2=> "<NONE><NONE><NONE>"`
   b. compare the two strings from the last element to the first — they are equal.

4. third pass:
   a. substitute the elements of the strings with their tertiary weights:
      `s1=> "<LOWER-CASE><UPPER-CASE><LOWER-CASE>"`,
      `s2=> "<UPPER-CASE><LOWER-CASE><UPPER-CASE>"`,
   b. compare the two strings starting from the beginning of the strings: `s2` compares lower than `s1`, because `<UPPER-CASE>` is before `<LOWER-CASE>`.

Compare the strings `s1=“áß”` and `s2=“àss”`:

1. `s1=> "á<eszet>"` and `s2= "àss"`;

2. first pass:
   a. substitute the elements of the strings with their primary weights: `s1=> "<a><s><s>"`, `s2=> "<a><s><s>"`
   b. compare the two strings starting with the first element — they are equal.

3. second pass:
a. substitute the elements of the strings with their secondary weights: s1=>"<a-acute><eszet><s>" , s2=>"<a-grave><s><s>

b. compare the two strings from the last element to the first — <<s> is before <ezset>.

**LC_MONETARY category**

This category defines the rules and symbols used to format monetary quantities. The operands are strings or integers. The following keywords are supported:

- **copy** 
  Specifies the name of an existing locale to be used as the source for the definition of this category. If this keyword is specified, no other keyword should be present in this category. If the locale is not found, an error is reported and no locale output is created. The copy keyword cannot specify a locale that also specifies the copy keyword for the same category.

- **int_curr_symbol**
  Specifies the international currency symbol. The operand is a four-character string, with the first three characters containing the alphabetic international currency symbol in accordance with those specified in ISO4217 Codes for the Representation of Currency and Funds. The fourth character is the character used to separate the international currency symbol from the monetary quantity.

    The following value may also be specified, though it is not If not defined, it defaults to the empty string (""").

- **currency_symbol**
  Specifies the string used as the local currency symbol. If not defined, it defaults to the empty string (""").

- **mon_decimal_point**
  The string used as a decimal delimiter to format monetary quantities. If not defined it defaults to the empty string (""").

- **mon_thousands_sep**
  Specifies the string used as a separator for groups of digits to the left of the decimal delimiter in formatted monetary quantities. If not defined, it defaults to the empty string (""").

- **mon_grouping**
  Defines the size of each group of digits in formatted monetary quantities. The operand is a sequence of integers separated by semicolons. Also, for compatibility, it may be a string of integers separated by semicolons. Each integer specifies the number of digits in each group, with the initial integer defining the size of the group immediately preceding the decimal delimiter, and the following integers defining the preceding groups. If the last integer is not -1, then the size of the previous group (if any) is used repeatedly for the rest of the digits. If the last integer is -1, then no further grouping is performed. If not defined, mon_grouping defaults to -1 which indicates that no grouping. An empty string is interpreted as -1.

- **positive_sign**
  A string used to indicate a formatted monetary quantity with a non-negative value. If not defined, it defaults to the empty string (""").

- **negative_sign**
  Specifies a string used to indicate a formatted monetary quantity with a negative value. If not defined, it defaults to the empty string (""").
int_frac_digits
Specifies an integer representing the number of fractional digits (those to the right of the decimal delimiter) to be displayed in a formatted monetary quantity using int_curr_symbol. If not defined, it defaults to -1.

frac_digits
Specifies an integer representing the number of fractional digits (those to the right of the decimal delimiter) to be displayed in a formatted monetary quantity using currency_symbol. If not defined, it defaults to -1.

p_cs_precedes
Specifies an integer set to 1 if the currency_symbol or int_curr_symbol precedes the value for a non-negative formatted monetary quantity, and set to 0 if the symbol succeeds the value. If not defined, it defaults to -1.

p_sep_by_space
Specifies an integer set to 0 if no space separates the currency_symbol or int_curr_symbol from the value for a non-negative formatted monetary quantity, set to 1 if a space separates the symbol from the value, and set to 2 if a space separates the symbol and the string sign, if adjacent. If not defined, it defaults to -1.

n_cs_precedes
An integer set to 1 if the currency_symbol or int_curr_symbol precedes the value for a negative formatted monetary quantity, and set to 0 if the symbol succeeds the value. If not defined, it defaults to -1.

n_sep_by_space
An integer set to 0 if no space separates the currency_symbol or int_curr_symbol from the value for a negative formatted monetary quantity, set to 1 if a space separates the symbol from the value, and set to 2 if a space separates the symbol and the string sign, if adjacent. If not defined, it defaults to -1.

p_sign_posn
An integer set to a value indicating the positioning of the positive_sign for a non-negative formatted monetary quantity. The following integer values are recognized; if not defined, it defaults to -1.

0 Parentheses surround the quantity and the currency_symbol or int_curr_symbol.
1 The sign string precedes the quantity and the currency_symbol or int_curr_symbol.
2 The sign string succeeds the quantity and the currency_symbol or int_curr_symbol.
3 The sign string immediately precedes the currency_symbol or int_curr_symbol.
4 The sign string immediately succeeds the currency_symbol or int_curr_symbol.

part of the POSIX standard.
5 Use debit-sign or credit-sign for p_sign_posn or n_sign_posn.

n_sign_posn
An integer set to a value indicating the positioning of the negative_sign for a negative formatted monetary quantity. The recognized values are the same as for p_sign_posn. If not defined, it defaults to -1.
left_parenthesis
The symbol of the locale's equivalent of ( to form a negative-valued formatted monetary quantity together with right_parenthesis. If not defined, it defaults to the empty string ("").

Note: This is an IBM-specific extension.

right_parenthesis
The symbol of the locale's equivalent of ) to form a negative-valued formatted monetary quantity together with left_parenthesis. If not defined, it defaults to the empty string ("");

Note: This is an IBM-specific extension.

debit_sign
The symbol of locale's equivalent of $ to indicate a non-negative-valued formatted monetary quantity. If not defined, it defaults to the empty string ("");

Note: This is an IBM-specific extension.

credit_sign
The symbol of locale's equivalent of € to indicate a negative-valued formatted monetary quantity. If not defined, it defaults to the empty string ("");

Note: This is an IBM-specific extension.

int_p_cs_precedes
Specifies an integer set to 1 if the int_curr_symbol precedes the value for a non-negative formatted monetary quantity, and set to 0 if the symbol succeeds the value. If not defined, it defaults to -1.

int_n_cs_precedes
An integer set to 1 if the int_curr_symbol precedes the value for a negative formatted monetary quantity, and set to 0 if the symbol succeeds the value. If not defined, it defaults to -1.

int_p_sep_by_space
Specifies an integer set to 0 if no space separates the int_curr_symbol from the value for a non-negative formatted monetary quantity, set to 1 if a space separates the symbol from the value, and set to 2 if a space separates the symbol and the string sign, if adjacent. If not defined, it defaults to -1.

int_n_sep_by_space
An integer set to 0 if no space separates the int_curr_symbol from the value for a negative formatted monetary quantity, set to 1 if a space separates the symbol from the value, and set to 2 if a space separates the symbol and the string sign, if adjacent. If not defined, it defaults to -1.

int_p_sign_posn
For a non-negative monetary quantity, the following integer values are recognized:
0 Parentheses surround the quantity and the int_curr_symbol.
1 The sign string precedes the quantity and the int_curr_symbol.
2 The sign string succeeds the quantity and int_curr_symbol.
3 The sign string immediately precedes the int_curr_symbol.
The sign string immediately succeeds the currency_symbol or int_curr_symbol.

**int_n_sign_posn**

For a negative monetary quantity, the following integer values are recognized:

0  Parentheses surround the quantity and the int_curr_symbol.
1  The sign string precedes the quantity and the int_curr_symbol.
2  The sign string succeeds the quantity and int_curr_symbol.
3  The sign string immediately precedes the int_curr_symbol.
4  The sign string immediately succeeds the currency_symbol or int_curr_symbol.

Figure 249 is an example of the definition of the LC_MONETARY category.

```
escape_char    /
comment_char   %

%%%%%%%%%%%%%%%%%
LC_MONETARY
%%%%%%%%%%%%%%%%%

int_curr_symbol  "<J><P><Y><space>"
currency_symbol   "<yen>"
mon_decimal_point "<period>"
mon_thousands_sep  "<comma>"
mon_grouping      3
positive_sign     ""
negative_sign     "<hyphen-minus>"
int_frac_digits   0
frac_digits       0
p_cs_precedes     1
p_sep_by_space    0
n_cs_precedes     1
n_sep_by_space    0
p_sign_posn       1
n_sign_posn       1
debit_sign        "<D><B>"
credit_sign       "<C><R>"
left_parenthesis  "<left-parenthesis>"
right_parenthesis "<right-parenthesis>"
int_p_cs_precedes -1
int_n_cs_precedes -1
int_p_sep_by_space -1
int_n_sep_by_space -1
int_p_sign_posn   -1
int_n_sign_posn   -1

END LC_MONETARY
```

*Figure 249. Example LC_MONETARY definition*

**LC_NUMERIC category**

This category defines the rules and symbols used to format non-monetary numeric information. The operands are strings. The following keywords are recognized:

**copy** Specifies the name of an existing locale to be used as the source for the definition of this category. If this keyword is specified, no other keyword should be present in this category. If the locale is not found, an error is reported and no locale output is created. The *copy* keyword cannot specify a locale that also specifies the *copy* keyword for the same category.
**decimal_point**

Specifies a string used as the decimal delimiter in numeric, non-monetary formatted quantities. This keyword cannot be omitted and cannot be set to the empty string.

**thousands_sep**

Specifies a string containing the symbol that is used as a separator for groups of digits to the left of the decimal delimiter in numeric, non-monetary, formatted quantities.

**grouping**

Defines the size of each group of digits in formatted non-monetary quantities. The operand is a sequence of integers separated by semicolons. Also, for compatibility, it may be a string of integers separated by semicolons. Each integer specifies the number of digits in each group, with the initial integer defining the size of the group immediately preceding the decimal delimiter, and the following integers defining the preceding groups. If the last integer is not -1, then the size of the previous group (if any) is used repeatedly for the rest of the digits. If the last integer is -1, then no further grouping is performed. An empty string is interpreted as -1.

**Figure 250** is an example of how to specify the LC_NUMERIC category.

```plaintext
escape_char /
comment_char %

LC_NUMERIC

decimal_point "<comma>
thousands_sep "<space>
grouping 3

END LC_NUMERIC
```

**Figure 250. Example LC_NUMERIC definition**

**LC_TIME category**

The LC_TIME category defines the interpretation of the field descriptors used for parsing, then formatting, the date and time. The descriptors identify the replacement portion of the string, while the rest of a string is constant. The definition of descriptors is included in z/OS XL C/C++ Runtime Library Reference. All these descriptors can be used in the format specifier in the time formatting functions strftime().

The following keywords are supported:

**copy**

Specifies the name of an existing locale to be used as the source for the definition of this category. If this keyword is specified, no other keyword should be present in this category. If the locale is not found, an error is reported and no locale output is created. The copy keyword cannot specify a locale that also specifies the copy keyword for the same category.

**abday**

 Defines the abbreviated weekday names, corresponding to the %a field descriptor. The operand consists of seven semicolon-separated strings. The first string is the abbreviated name corresponding to Sunday, the second string corresponds to Monday, and so forth.
**day**
Defines the full weekday names, corresponding to the %A field descriptor. The operand consists of seven semicolon-separated strings. The first string is the full name corresponding to Sunday, the second string to Monday, and so forth.

**abmon**
Defines the abbreviated month names, corresponding to the %b field descriptor. The operand consists of twelve strings separated by semicolons. The first string is an abbreviated name that corresponds to January, the second corresponds to February, and so forth.

**mon**
Defines the full month names, corresponding to the %B field descriptor. The operand consists of twelve strings separated by semicolons. The first string is an abbreviated name that corresponds to January, the second corresponds to February, and so forth.

**d_t_fmt**
Defines the appropriate date and time representation, corresponding to the %c field descriptor. The operand consists of a string, which may contain any combination of characters and field descriptors.

**d_fmt**
Defines the appropriate date representation, corresponding to the %x field descriptor. The operand consists of a string, and may contain any combination of characters and field descriptors.

**t_fmt**
Defines the appropriate time representation, corresponding to the %X field descriptor. The operand consists of a string, which may contain any combination of characters and field descriptors.

**am_pm**
Defines the appropriate representation of the ante meridian and post meridian strings, corresponding to the %p field descriptor. The operand consists of two strings, separated by a semicolon. The first string represents the ante meridian designation, the last string the post meridian designation.

**t_fmt_ampm**
Defines the appropriate time representation in the 12-hour clock format with am_pm, corresponding to the %r field descriptor. The operand consists of a string and can contain any combination of characters and field descriptors.

**era**
Defines how the years are counted and displayed for each era (or emperor's reign) in a locale. No era is needed if the %E field descriptor modifier is not used for the locale. See the description of the strftime() function in z/OS XL C/C++ Runtime Library Reference for information about this field descriptor.

For each era, there must be one string in the following format:

direction:offset:start_date:end_date:name:format

direction
Either a + or - character. The + character indicates the time axis should be such that the years count in the positive direction when moving from the starting date towards the ending date. The - character indicates the time axis should be such that the years count in the negative direction when moving from the starting date towards the ending date.

offset
A number of the first year of the era.

start_date
A date in the form yyyy/mm/dd where yyyy, mm and dd are the year, month and day numbers, respectively, of the start of the era.
Years prior to the year AD 0 are represented as negative numbers. For example, an era beginning March 5th in the year 100 BC would be represented as -100/3/5.

**end_date**
The ending date of the era in the same form as the start_date above or one of the two special values -* or +*. A value of -* indicates the ending date of the era extends to the beginning of time while +* indicates it extends to the end of time. The ending date may be either before or after the starting date of an era. For example, the strings for the Christian eras AD and BC would be:

+0:0000/01/01:+*:AD:%EC %Ey
+1:0000/01/01:-*:BC:%EC %Ey

**name**
A string representing the name of the era which is substituted for the %EC field descriptor.

**format**
A string for formatting the %Ey field descriptor. This string is usually a function of the %EC and %Ey field descriptors.

The operand consists of one string for each era. If there is more than one era, strings are separated by semicolons.

**era_year**
Defines the format of the year in alternate era format, corresponding to the %Ey field descriptor.

**era_d_fmt**
Defines the format of the date in alternate era notation, corresponding to the %Ex field descriptor.

**era_t_fmt**
Defines the locale’s appropriate alternative time format, corresponding to the %Ex field descriptor.

**era_d_t_fmt**
Defines the locale’s appropriate alternative date and time format, corresponding to the %Ec field descriptor.

**alt_digits**
Defines alternate symbols for digits, corresponding to the %0 field descriptor modifier. The operand consists of semicolon-separated strings. The first string is the alternate symbol corresponding to zero, the second string the symbol corresponding to one, and so forth. A maximum of 100 alternate strings may be specified. The %0 modifier indicates that the string corresponding to the value specified by the field descriptor is used instead of the value.

For the definitions of the time formatting descriptors, see the description of the strftime() function in z/OS XL C/C++ Runtime Library Reference.

**LC_MESSAGES category**
The LC_MESSAGES category defines the format and values for positive and negative responses. The following keywords are recognized:

**copy**
Specifies the name of an existing locale to be used as the source for the definition of this category. If you specify this keyword, no other keyword should be present in this category. If the locale is not found, an error is reported and no locale output is created. The copy keyword cannot specify a locale that also specifies the copy keyword for the same category.
**yesexpr**

The operand consists of an extended regular expression that describes the acceptable affirmative response to a question that expects an affirmative or negative response.

**noexpr**

The operand consists of an extended regular expression that describes the acceptable negative response to a question that expects an affirmative or negative response.

**yestr**

The operand consists of a fixed string (not a regular expression) that can be used by an application for composition of a message that lists an acceptable affirmative response, such as in a prompt.

**nostr**

The operand consists of a fixed string that can be used by an application for composition of a message that lists an acceptable negative response.

Figure 251 shows an example of how to define the **LC_MESSAGES** category.

```plaintext
%%%%%% LC_MESSAGES
%%%%%%
% yes expression is a string that starts with
% "$", "$i", "$I", "$1", "$s", "$S", "$", "$".
% yesexpr "<circumflex><left-parenthesis><left-square-bracket><s><S>/
% <right-square-bracket><left-square-bracket><i><I><right-square-bracket>/
% <vertical-line><left-square-bracket><s><S><right-square-bracket>/
% <right-parenthesis>"
%
% no expression is a string that starts with
% "$", "$n", "$0", "$0", "$N", "$n".
% noexpr "<circumflex><left-parenthesis><left-square-bracket><n><N>/
% <right-square-bracket><left-square-bracket><o><O><right-square-bracket>/
% <vertical-line><left-square-bracket><n><N><right-square-bracket>/
% <right-parenthesis>"

END LC_MESSAGES
```

**Figure 251. Example LC_MESSAGES definition**

**LC_TOD category**

The **LC_TOD** category defines the rules used to define the beginning, end, and duration of daylight savings time, and the difference between local time and Greenwich Mean time. This is an IBM extension.

**Note:** **LC_TOD** and **LC_SYNTAX** are not supported for ASCII locales (a locale specification can not contain a definition for these categories). However, for consistency with EBCDIC locales, localedef generates default values for these categories in ASCII locale objects (the values generated for the C locale but with ASCII code points).

The following keywords are recognized:

**copy**

Specifies the name of an existing locale to be used as the source for the definition of this category. If this keyword is specified, no other keyword should be present in this category. If the locale is not found, an error is reported and no locale output is created. The copy keyword cannot specify a locale that also specifies the copy keyword for the same category.

**Note:** If you specify this keyword, no other keyword should be present in this category.
timezone_difference
An integer specifying the time zone difference expressed in minutes. If the local time zone is west of the Greenwich Meridian, this value must be positive. If the local time zone is east of the Greenwich Meridian, this value must be negative. An absolute value greater than 1440 (the number of minutes in a day) for this keyword indicates that z/OS Language Environment is to get the time zone difference from the system.

timezone_name
A string specifying the time zone name such as "PST" (Pacific Standard Time) specified within quotation marks. The default for this field is a NULL string.

daylight_name
A string specifying the Daylight Saving Time zone name, such as "PDT" (Pacific Daylight Time), if there is one available. The string must be specified within quotation marks. If DST information is not available, this is set to NULL, which is also the default. This field must be filled in if DST information as provided by the other fields is to be taken into account by the mktime() and localtime() functions. These functions ignore DST if this field is NULL.

start_month
An integer specifying the month of the year when Daylight Saving Time comes into effect. This value ranges from 1 through 12 inclusive, with 1 corresponding to January and 12 corresponding to December. If DST is not applicable to a locale, start_month is set to 0, which is also the default.
end_month
An integer specifying the month of the year when Daylight Saving Time ceases to be in effect. The specifications are similar to those for start_month.

start_week
An integer specifying the week of the month when DST comes into effect. Acceptable values range from -4 to +4. A value of 4 means the fourth week of the month, while a value of -4 means fourth week of the month, counting from the end of the month. Sunday is considered to be the start of the week. If DST is not applicable to a locale, start_week is set to 0, which is also the default.

daylight_name
An integer specifying the week of the month when DST ceases to be in effect. The specifications are similar to those for start_week.

Note: The start_week and end_week need not be used. The start_day and end_day fields can specify either the day of the week or the day of the month. If day of month is specified, start_week and end_week become redundant.

start_day
An integer specifying the day of the week or the day of the month when DST comes into effect. The value depends on the value of start_week. If start_week is not equal to 0, this is the day of the week when DST comes into effect. It ranges from 0 through 6 inclusive, with 0 corresponding to Sunday and 6 corresponding to Saturday. If start_week equals 0, start_day is the day of the month (for the current year) when DST comes into effect. It ranges from 1 through to the last day of the month inclusive. The last day of the month is 31 for January, March, May, July, August, October, and
December. It is 30 for April, June, September, and November. For February, it is 28 on non-leap years and 29 on leap years. If DST is not applicable to a locale, start_day is set to 0, which is also the default.

**end_day**

An integer specifying the day of the week or the day of the month when DST ceases to be in effect. The specifications are similar to those for start_day.

**start_time**

An integer specifying the number of seconds after 12:00 midnight, local standard time, when DST comes into effect. For example, if DST is to start at 2:00 am, start_time is assigned the value 7200; for 12:00 am (midnight), start_time is 0; for 1:00 am, it is 3600.

**end_time**

An integer specifying the number of seconds after 12 midnight, local standard time, when DST ceases to be in effect. The specifications are similar to those for start_time.

**shift**

An integer specifying the DST time shift, expressed in seconds. The default is 3600, for 1 hour.

**uctname**

A string specifying the name to be used for Coordinated Universal Time. If this keyword is not specified, the uctname will default to "UTC".

**Figure 252** is an example of how to define the LC_TOD category.

```
escape_char  /
comment-char \

% the time zone difference is 8hrs; the name of the daylight saving
% time is PDT, and it starts on the first Sunday of April at 2&00AM
% and ends on the second Sunday of October at 2&00AM
timezone_difference +480
timezone_name "<P><S><T>"* 
daylight_name "<P><D><T>"* 
start_month 4
daytime_end 10
start_week 1
daytime_end 2
start_day 1
daytime_end 30
start_time 7200
daytime_end 3600
shift 3600
END LC_TOD
```

**Figure 252. Example LC_TOD definition**

**LC_SYNTAX category**

The LC_SYNTAX category defines the variant characters from the portable character set. LC_SYNTAX is an IBM-specific extension. This category can be queried by the C library function getsyntax() to determine the encoding of a variant character if needed.

**Attention:** Customizing the LC_SYNTAX category is not recommended. You should use the LC_SYNTAX values obtained from the charmap file when you use the localedef utility.
The operands for the characters in the LC_SYNTAX category accept the single byte character specification in the form of a symbolic name, the character itself, or the decimal, octal, or hexadecimal constant. The characters must be specified in the LC_CTYPE category as a punct character. The values for the LC_SYNTAX characters must be unique. If symbolic names are used to define the encoding, only the symbolic names listed for each character should be used.

The code points for the LC_SYNTAX characters are set to the code points specified. Otherwise, they default to the code points for the respective characters from the charmap file, if the file is present, or to the code points of the respective characters in the IBM-1047 code page.

**Note:** LC_TOD and LC_SYNTAX are not supported for ASCII locales (a locale specification can not contain a definition for these categories). However, for consistency with EBCDIC locales, localedef generates default values for these categories in ASCII locale objects (the values generated for the C locale but with ASCII code points).

The following keywords are recognized:

```
copy
```

Specifies the name of an existing locale to be used as the source for the definition of this category. If you specify this keyword, no other keyword should be present. If the locale is not found, an error is reported and no locale output is created. The copy keyword cannot specify a locale that also specifies the copy keyword for the same category.

```
backslash
```

Specifies a string that defines the value used to represent the backslash character. If this keyword is not specified, the value from the charmap file for the character `<backslash>`, `<reverse-solidus>`, or `<SM07>` is used, if it is present.

```
right_brace
```

Specifies a string that defines the value used to represent the right brace character. If this keyword is not specified, the value from the charmap file for the character `<right-brace>`, `<right-curly-bracket>`, or `<SM14>` is used, if it is present.

```
left_brace
```

Specifies a string that defines the value used to represent the left brace character. If this keyword is not specified, the value from the charmap file for the character `<left-brace>`, `<left-curly-bracket>`, or `<SM11>` is used, if it is present.

```
right_bracket
```

Specifies a string that defines the value used to represent the right bracket character. If this keyword is not specified, the value from the charmap file for the character `<right-square-bracket>`, or `<SM08>` is used, if it is present.

```
left_bracket
```

Specifies a string that defines the value used to represent the left bracket character. If this keyword is not specified, the value from the charmap file for the character `<left-square-bracket>`, or `<SM06>` is used, if it is present.

```
circumflex
```

Specifies a string that defines the value used to represent the circumflex character. If this keyword is not specified, the value from the charmap file for the character `<circumflex>`, `<circumflex-accent>`, or `<SD15>` is used, if it is present.
tilde  Specifies a string that defines the value used to represent the tilde character. If this keyword is not specified, the value from the charmap file for the character <tilde>, or <SD19> is used, if it is present.

exclamation_mark  Specifies a string that defines the value used to represent the exclamation mark character. If this keyword is not specified, the value from the charmap file for the character <exclamation-mark>, or <SP02> is used, if it is present.

number_sign  Specifies a string that defines the value used to represent the number sign character. If this keyword is not specified, the value from the charmap file for the character <number-sign>, or <SM01> is used, if it is present.

vertical_line  Specifies a string that defines the value used to represent the vertical line character. If this keyword is not specified, the value from the charmap file for the character <vertical-line>, or <SM13> is used, if it is present.

dollar_sign  Specifies a string that defines the value used to represent the dollar sign character. If this keyword is not specified, the value from the charmap file for the character <dollar-sign>, or <SC03> is used, if it is present.

commercial_at  Specifies a string that defines the value used to represent the commercial at character. If this keyword is not specified, the value from the charmap file for the character <commercial-at>, or <SM05> is used, if it is present.

grave_accent  Specifies a string that defines the value used to represent the grave accent character. If this keyword is not specified, the value from the charmap file for the character <grave-accent>, or <SD13> is used, if it is present.

Figure 253 is an example of how the LC_SYNTAX category is defined.

```
escape_char  /
comment-char  %

%%%%%%%%%%%%%%%
LC_SYNTAX
%%%%%%%%%%%%%%%

backslash    "<backslash>"
right_brace  "<right-brace>"
left_brace   "<left-brace>"
right_bracket "<right-square-bracket>"
left_bracket "<left-square-bracket>"
circumflex   "<circumflex>"
tilde        "<tilde>"
exclamation_mark "<exclamation-mark>"
number_sign  "<number-sign>"
vertical_line "<vertical-line>"
dollar_sign  "<dollar-sign>"
commercial_at "<commercial-at>"
grave_accent "<grave-accent>"

END LC_SYNTAX
```

Figure 253. Example definition of LC_SYNTAX
Method files

Method files can be used when creating ASCII locales. They specify the method functions used by the C runtime’s locale-sensitive interfaces when the ASCII locale is activated.

IBM ships the method files used to build its ASCII locales in the /
/usr/lib/nls/method directory. These method files support various ASCII Latin 1 and non-Latin 1 single byte encodings, ASCII SJIS and EUC multibyte encodings and UTF-8 multibyte encodings.

By replacing the CHARMAP related method functions in a method file, users can create a locale which supports a user-defined code page. For each replaced method, the method file supplies the user-written method function name, and optionally indicates where the method function code is to be found (.o file, archive library or DLL). The method source file maps method names to the National Language Support (NLS) subroutines that implement those methods. The method file also specifies the object libraries or DLL side decks where the implementing subroutines are stored. The methods correspond to those subroutines that require direct access to the data structures representing locale data.

Each user provided method must follow the standard interface defined for the API it implements and add an argument of type _LC_charmap_objhdl_t as the first argument. The _LC_charmap_objhdl_t is defined in the localdef.h header file.

Users can provide these CHARMAP methods via a DLL side deck, an archive library or an object file. The user-written method functions are used both by the locale-sensitive APIs they represent, and also by the localedef utility itself while generating the method-file based ASCII locale object. This second use by localedef itself causes a temporary DLL to be created while processing the CHARMAP file supplied on the -f parameter. The name of the file containing method objects or side deck information is passed by the localedef utility as a parameter on the c89 command line, so the standard archive/object/side deck suffix naming conventions apply (for example, .a, .o, .x).

[Figure 254 on page 990] shows the expected grammar for a method file.
method_def :
   "METHODS"
   method_assign_list "END METHODS"
   ;
   method_assign_list :
   method_assign_list method_assign
   method_assign_list
   method_assign
   ;
   method_assign :
   "csid" meth_name meth_lib_path
   "fnmatch" meth_name meth_lib_path
   "is_wctype" meth_name meth_lib_path
   "mblen" meth_name meth_lib_path
   "mbstowcs" meth_name meth_lib_path
   "mbtowc" meth_name meth_lib_path
   "regcomp" meth_name meth_lib_path
   "regerror" meth_name meth_lib_path
   "regexec" meth_name meth_lib_path
   "regfree" meth_name meth_lib_path
   "rpmatch" meth_name meth_lib_path
   "strcoll" meth_name meth_lib_path
   "strftime" meth_name meth_lib_path
   "strptime" meth_name meth_lib_path
   "strxfrm" meth_name meth_lib_path
   "towlower" meth_name meth_lib_path
   "towupper" meth_name meth_lib_path
   "wcsColl" meth_name meth_lib_path
   "wcsftime" meth_name meth_lib_path
   "wcsid" meth_name meth_lib_path
   "wcsstol" meth_name meth_lib_path
   "wcstombs" meth_name meth_lib_path
   "wcstowcs" meth_name meth_lib_path
   "wcsxfrm" meth_name meth_lib_path
   "wctomb" meth_name meth_lib_path
   "wcwidth" meth_name meth_lib_path
   ;
   meth_name :
   global_name
   cfunc_name
   ;

Expected grammar for method files (Part 1 of 2)

Figure 254. Expected grammar for method files
global_name:
    CSID_STD
    FNMATCH_C
    FNMATCH_STD
    GET_WCTYPE_STD
    IS_WCTYPE_SB
    IS_WCTYPE_STD
    LOCALECONV_STD
    MBLEN_932
    MBLEN_EUCJP
    MBLEN_SB
    MBSTOWCS_932
    MBSTOWCS_EUCJP
    MBSTOWCS_SB
    MBTOWC_932
    MBTOWC_EUCJP
    MBTOWC_SB
    REGCOMP_STD
    REGERROR_STD
    REGEXEC_STD
    REGFREE_STD
    RPMATCH_C
    RPMATCH_STD
    STRCOLL_C
    STRCOLL_SB
    STRCOLL_STD
    STRFMON_STD
    STRFTIME_STD
    STRFTIME(STD)
    STRXFRM_C
    STRXFRM_SB
    STRXFRM_STD
    TOWLOWER_STD
    TOWUPPER_STD
    WCSCOLL_C
    WCSCOLL_STD
    WCSTIME_STD
    WCSTIME(STD)
    WCSTOMBS_932
    WCSTOMBS_EUCJP
    WCSTOMBS_SB
    WCSTWIDTH_932
    WCSTWIDTH_EUCJP
    WCSTWIDTH_LATIN
    WCSTWIDTH_LATIN
    WCSTWIDTH_LATIN
    WCTOBM_C
    WCTOMB_STD
    WCTOMB_932
    WCTOMB_EUCJP
    WCTOMB_SB
    WCWIDTH_932
    WCWIDTH_EUCJP
    WCWIDTH_LATIN
    WCWIDTH_LATIN
    WCWIDTH_LATIN

Expected grammar for method files (Part 2 of 2)

Where cfunc_name is the name of a user supplied subroutine, and meth_lib_path
is an optional path name for the file containing the compiled subroutine or a
side-deck for the DLL containing the subroutine.

The localedef command parses this information to determine the methods to be
used for this locale. The following subroutines must be specified in the method
file:
The following additional subroutines are mandatory in AIX method files, but are not supported on z/OS and if specified are ignored:

Any other method not specified in the method file retains the default. Mixing of user-written method function names (represented as cfunc_name in the grammar) and IBM-provided method function names (represented by global_name in the grammar) is not allowed. A method file should not include both. If the localedef command encounters both cfunc_name values and global_name values in a method file, an error is generated and the locale is not created.

It is not mandatory that the METHODS section specify the meth_lib_path name for all methods. The following is an example of how to specify the meth_lib_path and what the localedef passes on the c89 command invoking the binder when linking the method-based ASCII locale object:

In the example, libmyuni.a contains functions __mbstowcs_myuni and __mbtowc_myuni. Similarly, libgenuni.a contains functions __wcstombs_myuni, __wcswidth_myuni and __wctomb_myuni. The function __wcwidth_myuni is contained in the file wcwidth.o. If the function __mblen_myuni is not defined in either of the three files indicated, a locale object will not be created. For this example the localedef utility would invoke the binder using the following c89 command line:

It is also possible to use the -L localedef option to specify the c89 -L library flags and only reference the library names in the method file following the liblibname.a convention.

If an individual method does not specify a meth_lib_path name, the method inherits the most recently specified meth_lib_path name. If no meth_lib_path name is specified in the METHODS section, the default runtime library side-deck is assumed. The files indicated by meth_lib_path names of all methods in the method
file are used when linking the locale object. A concatenated list of all meth_lib_path names is specified on the link step. If multiple object libraries or side decks are specified, the same routine should not be defined in more than one of them. Unexpected results may occur if the method functions appear in more than one file, particularly if the duplicate copies are not identical. The binder could resolve a method function from a file different from the one given in the method file itself.

The method for the mbtowc and wcwidth subroutines should avoid calling other methods where possible.

Using the localedef utility

The locale objects or locales are generated using the localedef utility. The localedef utility:
1. Reads the locale definition file
2. Resolves all the character symbolic names to the values of characters defined in the specified character set definition file, (CHARMAP)
3. Produces a z/OS XL C source file.
4. Compiles the source file using the z/OS XL C compiler and link-edits the produced text module to produce a locale object. localedef produces ASCII locale objects as XPLINK DLL's exclusively, while EBCDIC locales can be non-XPLINK objects or XPLINK DLL's.

Note: AMODE 64 locales are always XPLINK locales, while 31-bit locales may be XPLINK or non-XPLINK.

The locale DLL object can be loaded by the setlocale() function and then accessed by the z/OS XL C/C++ functions that are sensitive to the cultural information, or that can query the locales. For a list of all the library functions sensitive to locale, see "Locale-sensitive interfaces" on page 952. For detailed information on how to invoke localedef, see "localedef Utility" in the z/OS XL C/C++ User's Guide.

The locale DLL object created by localedef must adhere to certain naming conventions so that the locale can be used by the system. These conventions are outlined in "Locale naming conventions" on page 994.

XPLINK applications require XPLINK locale objects, and non-XPLINK applications require non-XPLINK locale objects. Likewise, AMODE 64 applications require AMODE 64 locale objects. localedef creates non-XPLINK locales by default. The option XPLINK causes the TSO localedef command (LOCALDEF) to produce an XPLINK locale object. The batch XPLINK localedef command (EDCXLDEF proc) produces an XPLINK locale object (while the batch localedef command (EDCLDEFF) produces a non-XPLINK locale object). The -X parameter causes the UNIX System Services localedef command to generate an XPLINK locale object.

The TSO localedef (LOCALDEF) command and the batch XPLINK localedef command (EDCXLDEF proc) cannot be used to generate ASCII locales or AMODE 64 locales. Only the UNIX System Services localedef command may be used. ASCII locales are generated by specifying the -A localedef option on the command line of the UNIX System Services localedef command. AMODE 64 locales are generated by specifying the -6 option on the command line of the UNIX System Services localedef command. Specify both -A and -6 to produce locale objects which are both ASCII and AMODE 64. AMODE 64 locales are always XPLINK locales. The -X option is implicitly specified whenever the -6 option is
specified. Users can supply functions for the methods referenced in the locale charmap category by indicating the \-m method_file option on the command line.

The POSIX shell (/bin/sh) UNIX System Services shell, /bin/sh, is an example of a non-XPLINK application that uses locales. It needs non-XPLINK locales. If the shell invokes an XPLINK application that uses locales, the application will need an XPLINK version of the same locale. Usually, both XPLINK and non-XPLINK versions of a locale are needed whenever an XPLINK application is invoked from the shell, or when an XPLINK application invokes the shell or any other non-XPLINK application. Likewise, usually both AMODE 64 and non-XPLINK versions of a locale are needed whenever a AMODE 64 application is invoked from the shell, or when a AMODE 64 application invokes the shell or any other non-XPLINK application. The locale object naming conventions ensure that the runtime library loads the appropriate version of the locale.

**Locale naming conventions**

The `setlocale()` library function that selects the active locale maps the descriptive locale name into the name of the locale object before loading the locale and making it accessible.

In z/OS XL C/C++ programs, the locale modules are referred to by descriptive locale names. The locale names themselves are not case sensitive. They follow these conventions:

\<Language>-\<Territory>-<Codeset>

**Language**

is a two-letter uppercase abbreviation for the language name. The abbreviations come from the ISO 639 standard.

**Territory**

is a two-letter uppercase abbreviation for the territory name. The abbreviation comes from the ISO 3166 standard.

**Codeset**

is the name registered by the MIT X Consortium that identifies the registration authority that owns the specific encoding. A modifier may be added to the registered name but is not required. The modifier is of the form `@codeset modifier` and identifies the coded character set as defined by that registration authority.

The Codeset parts are optional. If they are not specified, Codeset defaults to IBM-nnn, where nnn is the default code page, which for EBCDIC locales is shown in Table 351 on page 996 and for ASCII locales in Table 352 on page 998. (The modifier portion defaults to nothing.)

For PDS resident locales, the mapping between the descriptive locale name and the eight-character name of the locale object is performed as follows:

1. The Language-Territory part is mapped into a two-letter LT code.
2. The Codeset part is mapped into a two-letter CC code.
3. The object name is built from a prefix, the two-letter LT code, and the two-letter CC code. The prefix is one of the following show in Table 350 on page 995. (Note that the @-sign in the PDS and z/OS UNIX locale names always has Latin-1/Open Systems encoding; see IBM-1047 CHARMAP.)
Table 350. Locale object prefix

<table>
<thead>
<tr>
<th>Application</th>
<th>No modifier</th>
<th>@euro modifier</th>
<th>@preeuro modifier</th>
</tr>
</thead>
<tbody>
<tr>
<td>non-XPLINK</td>
<td>EDC$</td>
<td>EDC@</td>
<td>EDC3</td>
</tr>
<tr>
<td>XPLINK</td>
<td>CEH$</td>
<td>CEH@</td>
<td>CEH3</td>
</tr>
<tr>
<td>XPLINK ASCII</td>
<td>CEJ$</td>
<td>NA</td>
<td>NA</td>
</tr>
<tr>
<td>AMODE 64</td>
<td>CEQ$</td>
<td>CEQ@</td>
<td>CEQ3</td>
</tr>
<tr>
<td>AMODE 64 ASCII</td>
<td>CEZ$</td>
<td>NA</td>
<td>NA</td>
</tr>
</tbody>
</table>

Type Mapping

Non-XPLINK

Fr_BE.IBM-1148 maps to EDC$FBHO
Fr_BE.IBM-1148@euro maps to EDC@FBHO
Fr_BE.IBM-1148@preeuro maps to EDC3FBHO

XPLINK

Fr_BE.IBM-1148 maps to CEH$FBHO
Fr_BE.IBM-1148@euro maps to CEH@FBHO
Fr_BE.IBM-1148@preeuro maps to CEH3FBHO

ASCII

Fr_BE.ISO8859-1 maps to CEJ$FBI1
Fr_BE.UTF-8 maps to CEJ$FBU8

AMODE 64

Fr_BE.IBM-1148 maps to CEQ$FBHO
Fr_BE.IBM-1148@euro maps to CEQ@FBHO
Fr_BE.IBM-1148@preeuro maps to CEQ3FBHO

AMODE 64 ASCII

Fr_BE.ISO8859-1 maps to CEZ$FBI1
Fr_BE.UTF-8 maps to CEZ$FBU8

For resident locales in the z/OS UNIX file system, the mapping between the descriptive locale name and the z/OS UNIX file name is performed as follows:
1. The locale object file name starts out the same as the descriptive name.
2. If the locale object is XPLINK, add a suffix of ".xplink" to the end of the object file name.
3. If the locale object is AMODE 64, add a suffix of ".lp64" to the end of the object file name.

Type Mapping

Non-XPLINK

Fr_BE.IBM-1148 maps to Fr_BE.IBM-1148
Fr_BE.IBM-1148@euro maps to Fr_BE.IBM-1148@euro
Fr_BE.IBM-1148@preeuro maps to Fr_BE.IBM-1148@preeuro

XPLINK

Fr_BE.IBM-1148 maps to Fr_BE.IBM-1148.xplink
Fr_BE.IBM-1148@euro maps to Fr_BE.IBM-1148@euro.xplink
Fr_BE.IBM-1148@preeuro maps to Fr_BE.IBM-1148@preeuro.xplink

ASCII

Fr_BE.ISO8859-1 maps to Fr_BE.ISO8859-1.xplink
Fr_BE.UTF-8 maps to Fr_BE.UTF-8.xplink

AMODE 64

Fr_BE.IBM-1148 maps to Fr_BE.IBM-1148.lp64
Fr_BE.IBM-1148@euro maps to Fr_BE.IBM-1148@euro.lp64
Fr_BE.IBM-1148@preeuro maps to Fr_BE.IBM-1148@preeuro.lp64

AMODE 64 ASCII

Fr_BE.ISO8859-1 maps to Fr_BE.ISO8859-1.lp64
Fr_BE.UTF-8 maps to Fr_BE.UTF-8.lp64

The mapping between Language-Territory and the two-letter LT code is defined in the LT conversion table EDC$LCNM, built with assembler macros as follows:
**Locale** specifies the name of Language-Territory, while **CODE** specifies the respective LT code.

You can customize this table by adding new **Locale** name mappings. z/OS XL C/C++ reserves alphabetic LT codes, but you can use codes containing numeric values for your own customized names.

The **Language-Territory** names and their mappings into LT codes that are provided are shown in **Table 351**.

<table>
<thead>
<tr>
<th>Locale Name</th>
<th>Language</th>
<th>Country/Territory</th>
<th>EBCDIC Codeset</th>
<th>2-Byte LT Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ar_AA</td>
<td>Arabic</td>
<td>Algeria, Bahrain, Egypt, Iraq, Jordan, Kuwait, Lebanon, Libya, Morocco, Oman, Qatar, Saudi Arabia, Syria, Tunisia, U.A.E., Yemen</td>
<td>IBM-425</td>
<td>AR</td>
</tr>
<tr>
<td>Be_BY</td>
<td>Byelorussian</td>
<td>Belarus</td>
<td>IBM-1025</td>
<td>BB</td>
</tr>
<tr>
<td>Bg_BG</td>
<td>Bulgarian</td>
<td>Bulgaria</td>
<td>IBM-1025</td>
<td>BG</td>
</tr>
<tr>
<td>C</td>
<td></td>
<td></td>
<td>IBM-1047</td>
<td>CC</td>
</tr>
<tr>
<td>Ca_ES</td>
<td>Catalan</td>
<td>Spain</td>
<td>IBM-924</td>
<td>CS</td>
</tr>
<tr>
<td>Cs_CZ</td>
<td>Czech</td>
<td>Czech Republic</td>
<td>IBM-870</td>
<td>CZ</td>
</tr>
<tr>
<td>Da_DK</td>
<td>Danish</td>
<td>Denmark</td>
<td>IBM-1047</td>
<td>DA</td>
</tr>
<tr>
<td>De_AT</td>
<td>German</td>
<td>Austria</td>
<td>IBM-924</td>
<td>DT</td>
</tr>
<tr>
<td>De_CH</td>
<td>German</td>
<td>Switzerland</td>
<td>IBM-1047</td>
<td>DC</td>
</tr>
<tr>
<td>De_DE</td>
<td>German</td>
<td>Germany</td>
<td>IBM-1047</td>
<td>DD</td>
</tr>
<tr>
<td>De_LU</td>
<td>German</td>
<td>Luxembourg</td>
<td>IBM-924</td>
<td>DL</td>
</tr>
<tr>
<td>El_GR</td>
<td>Greek</td>
<td>Greece</td>
<td>IBM-875</td>
<td>EL</td>
</tr>
<tr>
<td>En_AU</td>
<td>English</td>
<td>Australia</td>
<td>IBM-1047</td>
<td>NA</td>
</tr>
<tr>
<td>En_BE</td>
<td>English</td>
<td>Belgium</td>
<td>IBM-924</td>
<td>EB</td>
</tr>
<tr>
<td>En_CA</td>
<td>English</td>
<td>Canada</td>
<td>IBM-1047</td>
<td>EC</td>
</tr>
<tr>
<td>En_GB</td>
<td>English</td>
<td>United Kingdom</td>
<td>IBM-1047</td>
<td>EK</td>
</tr>
<tr>
<td>En_HK</td>
<td>English</td>
<td>China (Hong Kong S.A.R. of China)</td>
<td>IBM-1047</td>
<td>NH</td>
</tr>
<tr>
<td>En_IE</td>
<td>English</td>
<td>Ireland</td>
<td>IBM-924</td>
<td>EI</td>
</tr>
<tr>
<td>En_IN</td>
<td>English</td>
<td>India</td>
<td>IBM-1047</td>
<td>NI</td>
</tr>
<tr>
<td>En_JP</td>
<td>English</td>
<td>Japan</td>
<td>IBM-1027</td>
<td>EJ</td>
</tr>
<tr>
<td>En_NZ</td>
<td>English</td>
<td>New Zealand</td>
<td>IBM-1047</td>
<td>NZ</td>
</tr>
<tr>
<td>Locale Name</td>
<td>Language</td>
<td>Country/Territory</td>
<td>EBCDIC Codeset</td>
<td>2-Byte LT Code</td>
</tr>
<tr>
<td>-------------</td>
<td>----------</td>
<td>-------------------</td>
<td>----------------</td>
<td>---------------</td>
</tr>
<tr>
<td>En_PH</td>
<td>English</td>
<td>Philippines</td>
<td>IBM-1047</td>
<td>NP</td>
</tr>
<tr>
<td>En_SG</td>
<td>English</td>
<td>Singapore</td>
<td>IBM-1047</td>
<td>NS</td>
</tr>
<tr>
<td>En_US</td>
<td>English</td>
<td>United States</td>
<td>IBM-1047</td>
<td>EU</td>
</tr>
<tr>
<td>En_ZA</td>
<td>English</td>
<td>South Africa</td>
<td>IBM-1047</td>
<td>EZ</td>
</tr>
<tr>
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Table 351. Supported language-territory names and LT codes for EBCDIC locales (continued)

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Table 352 shows the supported language-territory names and LT codes for ASCII locales. Note that ASCII locale names can also be coded <uppercase><lowercase>_<uppercase><uppercase>. For example, both en_US and En_US are valid ASCII locale names.

Table 352. Supported language-territory names and LT codes for ASCII locales

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Table 352. Supported language-territory names and LT codes for ASCII locales (continued)

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<td>Slovakia</td>
<td>ISO8859-2</td>
<td>SK</td>
</tr>
<tr>
<td>sl_SI</td>
<td>Slovene</td>
<td>Slovenia</td>
<td>ISO8859-2</td>
<td>SI</td>
</tr>
<tr>
<td>sv_SE</td>
<td>Swedish</td>
<td>Sweden</td>
<td>ISO8859-1</td>
<td>SV</td>
</tr>
<tr>
<td>ta_IN</td>
<td>Tamil</td>
<td>India</td>
<td>UTF-8</td>
<td>AN</td>
</tr>
<tr>
<td>te_IN</td>
<td>Telugu</td>
<td>India</td>
<td>UTF-8</td>
<td>EN</td>
</tr>
<tr>
<td>th_TH</td>
<td>Thai</td>
<td>Thailand</td>
<td>TIS-620</td>
<td>TH</td>
</tr>
<tr>
<td>tr_TR</td>
<td>Turkish</td>
<td>Turkey</td>
<td>ISO8859-9</td>
<td>TR</td>
</tr>
<tr>
<td>zh_CN</td>
<td>Simplified Chinese</td>
<td>China (PRC)</td>
<td>IBM-eucCN</td>
<td>ZC</td>
</tr>
<tr>
<td>zh_HKS</td>
<td>Simplified Chinese</td>
<td>China (Hong Kong S.A.R. of China)</td>
<td>UTF-8</td>
<td>ZG</td>
</tr>
<tr>
<td>zh_HKT</td>
<td>Traditional Chinese</td>
<td>China (Hong Kong S.A.R. of China)</td>
<td>UTF-8</td>
<td>ZU</td>
</tr>
<tr>
<td>zh_SGS</td>
<td>Simplified Chinese</td>
<td>Singapore</td>
<td>UTF-8</td>
<td>ZS</td>
</tr>
<tr>
<td>zh_TW</td>
<td>Simplified Chinese</td>
<td>Taiwan</td>
<td>BIG5</td>
<td>ZT</td>
</tr>
</tbody>
</table>
The mapping between Codeset and the two-letter CC code is defined in the CC conversion table EDCUCSNM. This table is built with assembler macros, as follows:

```assembly
EDCUCSNM TITLE 'CODE SET NAME CONVERSION TABLE'
EDCUCSNM CSECT
EDCCSNAM TYPE=ENTRY, CODESET='IBM-037', CODE='EA'
EDCCSNAM TYPE=ENTRY, CODESET='IBM-273', CODE='EB'
EDCCSNAM TYPE=ENTRY, CODESET='IBM-274', CODE='EC'
EDCCSNAM TYPE=ENTRY, CODESET='IBM-277', CODE='ED'
EDCCSNAM TYPE=ENTRY, CODESET='IBM-278', CODE='EE'
:
EDCCSNAM TYPE=END
END EDCUCSNM
```

CODESET specifies the name Codeset; CODE specifies the respective CC code.

You can customize this table by adding new CODESET names. The alphabetic codes in the first byte of each CC name are reserved by IBM for future use, but you can use codes starting with numeric values for your own customized names.

Table 353 lists the Codeset names and their mappings into CC codes that are provided.

**Table 353. Supported codeset names and CC codes**

<table>
<thead>
<tr>
<th>Codesets</th>
<th>Primary Country or Territory</th>
<th>2-Byte CC code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Big5</td>
<td>Taiwan</td>
<td>BT</td>
</tr>
<tr>
<td>IBM-037</td>
<td>USA, Canada, Brazil</td>
<td>EA</td>
</tr>
<tr>
<td>IBM-273</td>
<td>Germany, Austria</td>
<td>EB</td>
</tr>
<tr>
<td>IBM-274</td>
<td>Belgium</td>
<td>EC</td>
</tr>
<tr>
<td>IBM-277</td>
<td>Denmark, Norway</td>
<td>EE</td>
</tr>
<tr>
<td>IBM-278</td>
<td>Finland, Sweden</td>
<td>EF</td>
</tr>
<tr>
<td>IBM-280</td>
<td>Italy</td>
<td>EG</td>
</tr>
<tr>
<td>IBM-282</td>
<td>Portugal</td>
<td>EI</td>
</tr>
<tr>
<td>IBM-284</td>
<td>Spain, Latin America</td>
<td>EJ</td>
</tr>
<tr>
<td>IBM-285</td>
<td>United Kingdom</td>
<td>EK</td>
</tr>
<tr>
<td>IBM-290</td>
<td>Japan (Katakana)</td>
<td>EL</td>
</tr>
<tr>
<td>IBM-297</td>
<td>France</td>
<td>EM</td>
</tr>
<tr>
<td>IBM-300</td>
<td>Japanese DBCS</td>
<td>EN</td>
</tr>
<tr>
<td>IBM-420</td>
<td>Algeria, Bahrain, Egypt, Iraq, Jordan, Kuwait, Lebanon, Libya, Morroco, Oman, Qatar, Saudi Arabia, Syria, Tunisia, U.A.E., Yemen</td>
<td>FF</td>
</tr>
<tr>
<td>IBM-424</td>
<td>Israel</td>
<td>FB</td>
</tr>
<tr>
<td>IBM-425</td>
<td>Algeria, Bahrain, Egypt, Iraq, Jordan, Kuwait, Lebanon, Libya, Morroco, Oman, Qatar, Saudi Arabia, Syria, Tunisia, U.A.E., Yemen</td>
<td>AR</td>
</tr>
<tr>
<td>IBM-500</td>
<td>International</td>
<td>EO</td>
</tr>
<tr>
<td>IBM-838</td>
<td>Thailand</td>
<td>EP</td>
</tr>
<tr>
<td>IBM-848</td>
<td>Ukraine with Euro (Cyrillic)</td>
<td>AS</td>
</tr>
<tr>
<td>Codesets</td>
<td>Primary Country or Territory</td>
<td>2-Byte CC code</td>
</tr>
<tr>
<td>-----------</td>
<td>-----------------------------------------------------------------------</td>
<td>----------------</td>
</tr>
<tr>
<td>IBM-870</td>
<td>Croatia, Czech Republic, Hungary, Poland, Romania, Serbia(Latin), Slovakia, Slovenia</td>
<td>EQ</td>
</tr>
<tr>
<td>IBM-871</td>
<td>Iceland</td>
<td>ER</td>
</tr>
<tr>
<td>IBM-875</td>
<td>Greece</td>
<td>ES</td>
</tr>
<tr>
<td>IBM-880</td>
<td>Cyrillic</td>
<td>ET</td>
</tr>
<tr>
<td>IBM-924</td>
<td>Latin 9/Open Systems</td>
<td>DL</td>
</tr>
<tr>
<td>IBM-930</td>
<td>Japan Katakana Extended (combined with DBCS)</td>
<td>EU</td>
</tr>
<tr>
<td>IBM-933</td>
<td>Korea</td>
<td>GZ</td>
</tr>
<tr>
<td>IBM-935</td>
<td>China(PRC)</td>
<td>GY</td>
</tr>
<tr>
<td>IBM-937</td>
<td>Taiwan</td>
<td>GW</td>
</tr>
<tr>
<td>IBM-943</td>
<td>Japan</td>
<td>JA</td>
</tr>
<tr>
<td>IBM-943</td>
<td>China (PRC)</td>
<td>No</td>
</tr>
<tr>
<td>IBM-943G</td>
<td>Japan</td>
<td>AN</td>
</tr>
<tr>
<td>IBM-1025</td>
<td>Bulgaria, Macedonia, Russia, Serbia (Cyrillic)</td>
<td>FE</td>
</tr>
<tr>
<td>IBM-1026</td>
<td>Turkey</td>
<td>EW</td>
</tr>
<tr>
<td>IBM-1027</td>
<td>Japan (Latin) Extended</td>
<td>EX</td>
</tr>
<tr>
<td>IBM-1047</td>
<td>Latin 1/Open Systems</td>
<td>EY</td>
</tr>
<tr>
<td>IBM-1112</td>
<td>Lithuania</td>
<td>GD</td>
</tr>
<tr>
<td>IBM-1122</td>
<td>Estonia</td>
<td>FD</td>
</tr>
<tr>
<td>IBM-1123</td>
<td>Ukraine (Cyrillic)</td>
<td>FH</td>
</tr>
<tr>
<td>IBM-1125</td>
<td>Ukraine (Cyrillic)</td>
<td>AT</td>
</tr>
<tr>
<td>IBM-1140</td>
<td>USA, Canada, Brazil</td>
<td>HA</td>
</tr>
<tr>
<td>IBM-1141</td>
<td>Austria, Germany</td>
<td>HB</td>
</tr>
<tr>
<td>IBM-1142</td>
<td>Denmark, Norway</td>
<td>HE</td>
</tr>
<tr>
<td>IBM-1143</td>
<td>Finland, Sweden</td>
<td>HF</td>
</tr>
<tr>
<td>IBM-1144</td>
<td>Italy</td>
<td>HG</td>
</tr>
<tr>
<td>IBM-1145</td>
<td>Spain, Latin America</td>
<td>HJ</td>
</tr>
<tr>
<td>IBM-1146</td>
<td>United Kingdom</td>
<td>HK</td>
</tr>
<tr>
<td>IBM-1147</td>
<td>France</td>
<td>HM</td>
</tr>
<tr>
<td>IBM-1148</td>
<td>International</td>
<td>HO</td>
</tr>
<tr>
<td>IBM-1149</td>
<td>Iceland</td>
<td>HR</td>
</tr>
<tr>
<td>IBM-1153</td>
<td>Czech Republic, Hungary, Poland, Slovakia, Slovenia</td>
<td>MB</td>
</tr>
<tr>
<td>IBM-1156</td>
<td>Latvia, Lithuania</td>
<td>HZ</td>
</tr>
<tr>
<td>IBM-1157</td>
<td>Estonia</td>
<td>HD</td>
</tr>
<tr>
<td>IBM-1158</td>
<td>Ukraine with Euro (Cyrillic)</td>
<td>FI</td>
</tr>
<tr>
<td>IBM-1165</td>
<td>Latin 2/Open Systems</td>
<td>FG</td>
</tr>
<tr>
<td>IBM-1364</td>
<td>Korea</td>
<td>KZ</td>
</tr>
<tr>
<td>IBM-1371</td>
<td>Taiwan</td>
<td>ZT</td>
</tr>
<tr>
<td>IBM-1388</td>
<td>China (PRC)</td>
<td>GV</td>
</tr>
</tbody>
</table>
Table 353. Supported codeset names and CC codes (continued)

<table>
<thead>
<tr>
<th>Codesets</th>
<th>Primary Country or Territory</th>
<th>2-Byte CC code</th>
</tr>
</thead>
<tbody>
<tr>
<td>IBM-1390</td>
<td>Japan</td>
<td>HU</td>
</tr>
<tr>
<td>IBM-1399</td>
<td>Japan</td>
<td>HV</td>
</tr>
<tr>
<td>IBM-4933</td>
<td>China (PRC)</td>
<td>FJ</td>
</tr>
<tr>
<td>IBM-4971</td>
<td>Greece</td>
<td>HS</td>
</tr>
<tr>
<td>IBM-13124</td>
<td>China (PRC)</td>
<td>FK</td>
</tr>
<tr>
<td>IBM-53668</td>
<td>Algeria, Behrain, Egypt, Iraq, Jordan, Kuwait, Lebanon, Libya,</td>
<td>FV</td>
</tr>
<tr>
<td></td>
<td>Morocco, Oman, Qatar, Saudia Arabia, Syria, Tunisia, U.A.E.,</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Yemen</td>
<td></td>
</tr>
<tr>
<td>IBMEUCCN</td>
<td>China (PRC)</td>
<td>BY</td>
</tr>
<tr>
<td>IBMEUCKR</td>
<td>Korea</td>
<td>BZ</td>
</tr>
<tr>
<td>ISO8859-1</td>
<td>All Latin 1 Countries</td>
<td>I1</td>
</tr>
<tr>
<td>ISO8859-2</td>
<td>Croatia, Czech Republic, Hungary, Poland, Romania, Serbia (Latin), Slovakia, Slovenia</td>
<td>I2</td>
</tr>
<tr>
<td>ISO8859-5</td>
<td>Bulgaria, Macedonia, Russia, Serbia (Cyrillic)</td>
<td>I5</td>
</tr>
<tr>
<td>ISO8859-7</td>
<td>Greece</td>
<td>I7</td>
</tr>
<tr>
<td>ISO8859-8</td>
<td>Israel</td>
<td>I8</td>
</tr>
<tr>
<td>ISO8859-9</td>
<td>Turkey</td>
<td>I9</td>
</tr>
<tr>
<td>TIS–620</td>
<td>Thailand</td>
<td>BU</td>
</tr>
<tr>
<td>UTF-8</td>
<td>All Countries</td>
<td>F8</td>
</tr>
</tbody>
</table>

The exceptions to the rule above are the following special locale names, which are already recognized:

- C (EBCDIC and ASCII)
- POSIX (EBCDIC and ASCII)
- SAA (EBCDIC only)
- S370 (EBCDIC only)

The special names C, POSIX, SAA, and S370 always refer to the built-in locales, which cannot be modified. The S370 locale and the following names are for locales in an old format, created with the EDCLOC assembler macro, rather than with the localedef utility:

- GERM (EBCDIC only)
- FRAN (EBCDIC only)
- UK (EBCDIC only)
- ITAL (EBCDIC only)
- SPAI (EBCDIC only)
- USA (EBCDIC only)

The EDCLOC generated locales are not supported in AMODE 64 applications.

You can use the C macros in Table 354 on page 1004, which are defined in the locale.h header file, as synonyms for these special locale names. These macros can only be used for EBCDIC locales. The <prefix> in the Compiled locale column is
EBC for non-XPLINK locales and CEH for XPLINK locales. The C macros for the locales which list a prefix in the Compiled locales column, are not defined for AMODE 64 compilations.

Table 354. C macros used as synonyms for special locale names

<table>
<thead>
<tr>
<th>Macro</th>
<th>Locale</th>
<th>Compiled locale</th>
</tr>
</thead>
<tbody>
<tr>
<td>LC_C</td>
<td>C</td>
<td>Not applicable</td>
</tr>
<tr>
<td>LC_POSIX</td>
<td>POSIX</td>
<td>Not applicable</td>
</tr>
<tr>
<td>LC_C_GERMANY</td>
<td>&quot;GERM&quot;</td>
<td>&lt;prefix&gt;$GERM</td>
</tr>
<tr>
<td>LC_C_FRANCE</td>
<td>&quot;FRAN&quot;</td>
<td>&lt;prefix&gt;$FRAN</td>
</tr>
<tr>
<td>LC_C_UK</td>
<td>&quot;UK&quot;</td>
<td>&lt;prefix&gt;$UK</td>
</tr>
<tr>
<td>LC_C_ITALY</td>
<td>&quot;ITAL&quot;</td>
<td>&lt;prefix&gt;$ITAL</td>
</tr>
<tr>
<td>LC_C_SPAIN</td>
<td>&quot;SPAI&quot;</td>
<td>&lt;prefix&gt;$SPAI</td>
</tr>
<tr>
<td>LC_C_USA</td>
<td>&quot;USA&quot;</td>
<td>&lt;prefix&gt;$USA</td>
</tr>
</tbody>
</table>

The predefined name for the built-in locale in the old format is S370.

The rest of the special names refer to the EBCDIC locale objects whose names are built by prepending the letters EDC$ for non-XPLINK locales or CEH$ for XPLINK locales to the special name, as for EDC$FRAN.
Chapter 61. Customizing a locale

This chapter describes how you can create your own locales, based on the locale definition files supplied by IBM. See Appendix D, “Locales supplied with z/OS XL C/C++,” on page 1091 for more information on the compiled locales and locale source files. The information in this chapter applies to the format of locales based on the localedef utility.

The following example assumes that the target of the generated locale will be a data set, but locales may also reside in a z/OS UNIX file system (see “Locale naming conventions” on page 994 for differences in object names). In this example you will build a locale named TEXAN using the charmap file representing the IBM-1047 encoded character set. The locale is derived from the locale representing the English language and the cultural conventions of the United States. We will assume that non-XPLINK, XPLINK, and AMODE 64 applications will use the TEXAN locale. All three versions of the TEXAN locale will be generated.

1. See “Locale source files” on page 1111 to determine the source of the locale you are going to use. In this case, it is the English language in the United States locale, the source for which is the member EDC$EUEY of the PDS CEE.SCEELOCX.

2. Copy the member EDC$EUEY from PDS CEE.SCEELOCX to the data set hlq.LOCALE.SOURCE which has been pre-allocated with the same attributes as CEE.SCEELOCX.

3. In your new file, change the locale variables to the desired values. For example, change

   d_t_fmt "%a %b %e %H:%M:%S %Z %Y"

   to

   d_t_fmt "Howdy Pardner %a %b %e %H:%M:%S %Z %Y"

4. This locale's Language-Territory value is TEXAN. The Codeset value is IBM-1047. TEXAN is not a valid PDS resident locale name in the runtime library, because it does not appear in the runtime Locale Name Table. You must modify the table to include the TEXAN locale. Here are the steps to follow.

   a. Copy the member EDC$LCNM from PDS CEE.SCEESAMP to the data set hlq.LOCALE.TABLE which has been pre-allocated with the same attributes as CEE.SCEESAMP. The z/OS XL C/C++ Library uses this table to map locale code registry prefixes into two-character codes.

   b. For this example, insert a new line into the assembler table before the last EDC$LCNM TYPE=END entry:

      EDC$LCNM TYPE=ENTRY,LOCALE='TEXAN',CODESET='IBM-1047',CODE='1T'

5. Now that your locale name table has been modified, you must make it available to the system. Assemble the EDC$LCNM member and link-edit it into the hlq.LOCALE.LOADLIB load library with the member name EDC$LCNM. For our example, this is done as follows:
6. Generate the non-XPLINK, XPLINK and 64-bit locale objects into a load library.
   Note that both the XPLINK and 64-bit locale objects must be placed in a PDSE, while non-XPLINK locale objects may be in either a PDS or PDSE load library.
   a. Determine the correct locale object names, using the locale naming conventions outlined in "Locale naming conventions" on page 994. PDS resident locale object names are of the form prefixLTCC.
      For this non-XPLINK locale the prefix is EDC$, the LT code for TEXAN is 1T and the CC code for IBM-1047 is EY. The non-XPLINK object name is therefore EDC$1TEY.
      For this XPLINK locale the prefix is CEH$. The LT and CC codes remain the same. The XPLINK object name is therefore CEH$1TEY.
      For this 64-bit locale the prefix is CEQ$. The LT and CC codes remain the same. The 64-bit locale object name is, therefore, CEQ$1TEY.
   b. Use localedef to generate the locale objects.
      • For non-XPLINK:

```
//GENLOCNX EXEC PROC=EDCXLDEF,
// INFILE='hlq.LOCALE.SOURCE(TEXAN)',
// OUTFILE='hlq.LOCALE.LOADLIB(EDC$1TEY),DISP=SHR',
// LOPT='CHARMAP(IBM-1047)'
```

• For XPLINK:

```
//GENLOCX EXEC PROC=EDCXLDEF,
// INFILE='hlq.LOCALE.SOURCE(TEXAN)',
// OUTFILE='hlq.LOCALE.PDSE.LOADLIB(CEH$1TEY),DISP=SHR',
// LOPT='CHARMAP(IBM-1047)'
```

• For 64–bit

The batch and TSO versions of the localedef utility cannot be used to generate 64–bit locales. The UNIX Systems Services utility must be used. To do this from TSO or batch the BPXBATCH utility can be used. See z/OS UNIX System Services Command Reference for more information about BPXBATCH. Here, we will assume we are in a UNIX System Services shell session:
See z/OS XL C/C++ User’s Guide for detailed information about the batch and TSO versions of localedef utility. The UNIX System Services version of the localedef utility is also described in z/OS UNIX System Services Command Reference.

**Note:** The TEXAN locale uses one of the IBM supplied CHARMAPs. If you need to customize a CHARMAP, then you must define its two-letter CC code in the Codeset Name table EDCUCSNM. This is similar to defining the locale TEXAN in EDCUCON. The two-letter CHARMAP codes beginning with a number are reserved for customer use. This is the same as the convention for customer-supplied Locale Name LT codes in the Locale Name table. The CC portion of your locale object names would then change to be the new CC value you added to the Codeset Name table.

### Using the customized locale

Your locale objects must be made available to your program before they can be used. For PDS and PDSE resident locales, your load library must be included in your program search order. For resident locales in the z/OS UNIX file system, do one of the following:

- Copy your locales into the system default locale object directory /usr/lib/nls/locale.
- Update your LOCPATH environment variable to include the directory containing your locales.

For example, assume that the CCNGCL1 program has been compiled with LP64 into a UNIX file system executable called getlocname. Further assume that you have generated non-XPLINK, XPLINK and AMODE 64 UNIX file system resident versions of the TEXAN locale into your current directory. The following commands make TEXAN available to non-XPLINK, XPLINK and AMODE 64 applications:

```bash
$ ls
TEXAN.IBM-1047 TEXAN.IBM-1047.xplink TEXAN.IBM-1047.lp64 getlocname
$ export LOCPATH=$PWD
$ export LC_ALL=TEXAN.IBM-1047
$ getlocname
Default NULL Locale = C
Default "" locale = /u/marcw/TEXAN.IBM-1047.lp64

$ getlocname
Default NULL Locale = C
Default "" locale = /u/marcw/TEXAN.IBM-1047

$ getlocname
Default NULL Locale = C
Default "" locale = /u/marcw/TEXAN.IBM-1047
```

If getlocname was compiled non-XPLINK then the output would look like the following:

```bash
$ getlocname
Default NULL Locale = C
Default "" locale = /u/marcw/TEXAN.IBM-1047

$ getlocname
Default NULL Locale = C
Default "" locale = /u/marcw/TEXAN.IBM-1047
```
If getlocname was compiled XPLINK then the output would look like the following:

```
$ getlocname
Default NULL locale = C
Default "" locale = /u/marcw/TEXAN.IBM-1047.xplink
$
```

The customized locale is now ready to be used in these ways:

- Explicitly referenced by name in z/OS XL C/C++ application code that uses setlocale() calls referring to the locale descriptive name (recommended) such as:

  ```c
  setlocale(LC_ALL, "TEXAN.IBM-1047");
  ```

  or by a short internal name (not recommended) such as:

  ```c
  setlocale(LC_ALL, "ITEY");
  ```

- Explicitly referenced in the z/OS XL C/C++ initialization exit, using customized setup code in CEEBINT.

- Implicitly specified in each user environment with environment variables.

**Note:** You cannot customize the built-in locales, C, POSIX, SAA, or S370. The locale source files EDC$POSX and EDC$SAAC are provided for reference only.

### Referring explicitly to a customized locale

**Figure 255** shows a non-XPLINK program (CCNGCL1) with an explicit reference to the TEXAN locale.

```c
/* this example shows how to get the local time formatted by the */
/* current locale */

#include <stdio.h>
#include <time.h>
#include <locale.h>

int main(void){
    char dest[80];
    int ch;
    time_t temp;
    struct tm *timeptr;
    temp = time(NULL);
    timeptr = localtime(&temp);
    /* Fetch default locale name */
    printf("Default empty_str locale is %s\n",setlocale(LC_ALL,""));
    ch = strftime(dest,sizeof(dest)-1,"Local C datetime is %c", timeptr);
    printf("%s\n", dest);
    /* Set new Texan locale name */
    printf("New locale is %s\n", setlocale(LC_ALL,"Texan.IBM-1047");
    ch = strftime(dest,sizeof(dest)-1,"Texan datetime is %c", timeptr);
    printf("%s\n", dest);
    return(0);
}
```

**Figure 255. Referring explicitly to a customized locale**
Compile the program. Before you execute it, ensure the load library containing the non-XPLINK version of the TEXAN locale and updated table is available. If you compile your program XPLINK, ensure the load library containing the XPLINK version of the TEXAN locale and updated Locale Name table is available. If you compile your program LP64, ensure the load library containing the 64–bit version of the TEXAN locale and updated Locale Name table is available. The output should be similar to:

Default empty_str locale is S370
Local C datetime is Fri Aug 20 14:58:12 1993
New locale is TEXAN
Texan datetime is Howdy Pardner Fri Aug 20 14:58:12 1993

For programs which are run POSIX(OFF), and which are not 64–bit programs, if the second operand to setlocale() had been NULL, rather than "", the default locale name returned would have been C.

setlocale(LC_ALL,"") returns "S370"
setlocale(LC_ALL,NULL) returns "C"

**Note:** For setlocale(LC_ALL,""), the result depends on the locale-related environment variables, the POSIX runtime option, and whether the program is AMODE 64 or not. See Chapter 63, “Definition of S370 C, SAA C, and POSIX C locales,” on page 1015 for more information about the definition of the S370 locale.

### Referring implicitly to a customized locale

An installation may require that a global mechanism should be used for all C programs. The exit CEEBINT may be used for this purpose. Users can insert a setlocale() call inside the routines referencing the locale required. Figure 256 shows an example program (CCNGCL2).

```c
/* this example refers implicitly to a customized locale */
#else ifdef _cplusplus
   extern "C"{
#else
   #pragma linkage(CEEBINT,OS)
#endif

void CEEBINT(int number, int retcode, int rsncode, int fnccode,
              void **a_main, int userwd, void **a_exits)
{ /* user code goes here */
   printf("CEEBINT entry. number = %i\n", number);
   printf("Locale = %s\n", setlocale(LC_ALL,"Texan.IBM-1047"));
}

Figure 256. Referring implicitly to a customized locale
```
If the above example is compiled and executed with the TEXAN locale, the results are as follows:

```plaintext
CEEBINT entry. number = 7
Locale = TEXAN.IBM-1047
Default NULL locale = TEXAN.IBM-1047
Default "" locale = S370
```

The exit CEEBINT may provide a uniform way of restricting the use of customized locales across an installation. To do this, a system programmer can compile CEEBINT separately, and link it with the application program that will use it. The disadvantage to this approach is that CEEBINT must be link-edited into each user module explicitly. See Chapter 50, “Using runtime user exits,” on page 837 for more information about user exits.

Figure 257 shows a sample program (CCNGCL3) that uses environment variables to select a locale. (For more information about setting environment variables, see Chapter 32, “Using environment variables,” on page 467.)

```c
/* this example can be used with setenv() to specify the name of a */
/* locale */

#include <locale.h>
#include <stdio.h>

int main(void)
{
    printf("Default NULL locale = %s\n", setlocale(LC_ALL,NULL));
    printf("Default "" locale = %s\n", setlocale(LC_ALL,""));

    return(0);
}
```

Figure 257. Using environment variables to select a locale

If you run this program in Figure 257 as is, without calling setenv(), you can expect the following result (for a 31-bit, POSIX(OFF), program):

Default NULL locale = C
Default "" locale = S370

On the other hand, if you issue the above setenv() call after main() but before the first printf() statement, the LC_ALL variable will be set to "TEXAN.IBM-1047" and you can expect this result instead:

Default NULL locale = C
Default "" locale = TEXAN.IBM-1047

In the example above, the default NULL locale returns C because the value of LC_ALL does not affect the current locale until the next setlocale(LC_ALL, "") is done. When this call is made, the LC_ALL environment variable will be used and the locale will be set to TEXAN.IBM-1047.

The names of the environment variables match the names of the locale categories:
- LC_ALL
- LC_COLLATE
- LC_CTYPE
- LC_MONETARY
- LC_NUMERIC
Customizing your installation

When z/OS XL C/C++ initializes its environment, it uses the C locale as its default locale. The only values that may be customized when z/OS Language Environment is installed are those defined in the TZ or _TZ environment variable, which can override LC_TOD category values in the default locale. Details on this customization are provided in Chapter 62, “Customizing a time zone,” on page 1013.
Chapter 62. Customizing a time zone

For applications that work with local time, you can customize time zone information in the following two ways:

- TZ or _TZ environment variable
  In a distributed environment, you may have users in several time zones. Use the TZ or _TZ environment variable to set each time zone. The user of your application can use the ENVAR runtime option with the TZ or _TZ environment variable to select the appropriate time zone.

For POSIX(ON) programs the TZ environment variable is used. For POSIX(OFF) programs the _TZ environment variable is used.

When neither TZ nor _TZ is defined, the current locale is interrogated for time zone information. If neither TZ nor _TZ is defined and LC_TOD time zone information is not present in the current locale, a default value is applied to local time. POSIX programs simply default to Coordinated Universal Time (UTC), while non-POSIX programs establish an offset from UTC based on the setting of the system clock.

The following functions are time zone sensitive: ctime(), ctime64(), getdate(), localtime(), localtime64(), mktime(), mktime64(), strftime(), and tzset(). The external variables daylight, timezone, and tzname and the thread specific functions __dtlight() and __tzone() are also time zone sensitive. LC_TOD category of a locale

You can customize the LC_TOD category in a locale to a particular time zone. The LC_TOD category binds each C/C++ locale to one time zone. For more information about customizing the LC_TOD category, see “LC_TOD category” on page 984 and Chapter 61, “Customizing a locale,” on page 1005.

Using the TZ or _TZ environment variable to specify time zone

The C/C++ runtime library assumes times returned by the operating system are stored using Greenwich Mean Time (GMT) or Coordinated Universal Time (UTC). This time is referred to as the universal reference time. You can use the TZ or _TZ environment variable to specify information at run time. The C/C++ runtime library uses this information to map universal reference times to local times.

The TZ or _TZ environment variable has the following format.

TZ=standardHH[:MM[:SS]]
[daylight[HH[:MM[:SS:]]]]
[,[startdate[/starttime],enddate[/endtime]]]

The value of the TZ or _TZ environment variable has the following five fields (two required and three optional):

- **standard**
  An alphabetic abbreviation for the local standard time zone (for example, GMT, EST, MSEZ).

- **HH[:MM[:SS]]**
  The time offset westward from the universal reference time. A leading minus sign (-) means that the local time zone is east of the universal reference time.
An offset of this form must follow standard and can also optionally follow daylight. An optional colon (:) separates hours from optional minutes and seconds.

If daylight is specified without a daylight offset, daylight savings time is assumed to be one hour ahead of the standard time.

[daylight]
The abbreviation for your local daylight savings time zone. If the first and third fields are identical, or if the third field is missing, daylight savings time conversion is disabled. The number of hours, minutes, and seconds your local daylight savings time is offset from UTC when daylight savings time is in effect. If the daylight savings time abbreviation is specified and the offset omitted, the offset of one hour is assumed.

[.startdate[/starttime],enddate[/endtime]]
A rule that identifies the start and end of daylight savings time, specifying when daylight savings time should be in effect. Both the startdate and enddate must be present and must either take the form Jn, n, or Mm.n.d where:

- Jn is the Julian day n (1 <= n <=365) and does not account for leap days.
- n is the zero-based Julian day (0 <= n <= 365). Leap days are counted; therefore, you can refer to February 29th.
- For Mm.n.d, the d’th day of week n of month m of the year. Day is (0<=d<=6), with day 0 = Sunday, day 1 = Monday, and so on. Week is (1<=n<=5) where week 1 is the first week in which day d occurs and week 5 is the last occurrence of day d in the month (may actually be in week 4 or 5). Month is (1<=m<=12).

Neither starttime nor endtime are required, and when omitted, their values default to 02:00:00. If this daylight savings time rule is omitted altogether, the values in the rule default to the standard American daylight savings time rules starting at 02:00:00 the second Sunday in March and ending at 02:00:00 the first Sunday in November.

### Relationship between TZ or _TZ and LC_TOD

The C/C++ runtime library uses time zone information specified by the TZ or _TZ environment variable to convert universal reference times to local times. When neither the TZ nor _TZ variable is defined, the C/C++ runtime library uses time zone information specified by the LC_TOD category of the current locale to map universal reference times to local times. If LC_TOD in the current locale has not been customized, the C/C++ runtime library uses Coordinated Universal Time (UTC) for POSIX programs or, for non-POSIX programs, the time zone of the system on which C/C++ is installed.

Note: The time zone external variables, tzname, timezone, and daylight, declarations remain feature test protected in time.h. Definition of these external variables are only known to the C/C++ runtime library if the z/OS UNIX System Services C/C++ signature CSECT is link edited with your C/C++ application.
Chapter 63. Definition of S370 C, SAA C, and POSIX C locales

The POSIX, SAA, and S370 locales are pre-built locales used as defaults by the C runtime library. The POSIX locale complies with the standard UNIX definition and supports the z/OS UNIX environment. The SAA locale, which provides compatibility with previous releases of C/370, is consistent with the POSIX model, but varies slightly with respect to several values. The S370 locale, which is not supported for AMODE 64 applications, is compatible with an older format generated by the EDCLOC assembler macro rather than through the use of the localedef utility.

The POSIX definition of the C locale is described below, with the IBM extensions LC_SYNTAX and LC_TOD showing their default values.

The SAA and S370 definitions of the C locale are different from the POSIX definition; consistency with previous releases of z/OS XL C/C++ is provided for migration compatibility. The differences are described in "Differences between SAA C and POSIX C locales" on page 1021.

The relationship between the POSIX C and SAA C locales is as follows. If you are running with the runtime option POSIX(OFF):

1. The SAA C locale definition is the default. "C", "SAA", and "S370" are treated as synonyms for the SAA C locale definition, which is prebuilt into the library.
   The source file EDCLC$SAAC LOCALE is provided for reference, but cannot be used to alter the definition of this prebuilt locale.

2. Issuing setlocale(category, "") has the following effect:
   - First, locale-related environment variables are checked for the locale name to use in setting the category specified. Querying the locale with setlocale(category, NULL) returns the name of the locales specified by the appropriate environment variables.
   - If no non-null environment variable is present, then it is the equivalent of having issued setlocale(category, "S370"). That is, the locale chosen is the SAA C locale definition, and querying the locale with setlocale(category, NULL) returns "S370" as the locale name.

3. If no setlocale() function is issued, or setlocale(LC_ALL, "C"), then the locale chosen is the pre-built SAA C locale, and querying the locale with setlocale(category, NULL) returns "C" as the locale name.

4. For setlocale(LC_ALL,"SAA"), the locale chosen is the pre-built SAA C locale, and querying the locale with setlocale(category, NULL) returns "SAA" as the locale name.

5. For setlocale(LC_ALL,"S370"), the locale chosen is the pre-built SAA C locale, and querying the locale with setlocale(category, NULL) returns "S370" as the locale name. AMODE 64 applications do not support the "S370" locale, and setlocale will fail requests for that name.

6. For setlocale(LC_ALL,"POSIX"), the locale chosen is the pre-built POSIX C locale, and querying the locale with setlocale(category, NULL) returns "POSIX" as the locale name.

If you are running with the runtime option POSIX(ON):
1. The POSIX C locale definition is the default. "C" and "POSIX" are synonyms for the POSIX C locale definition, which is pre-built into the library.
   The source file EDC$POSX LOCALE is provided for reference, but cannot be used to alter the definition of this pre-built locale.
2. Issuing `setlocale(category, "")` has the following effect:
   - Locale-related environment variables are checked to find the name of locales that can set the category specified. Querying the locale with `setlocale(category, NULL)` returns the name of the locale specified by the appropriate environment variables.
   - If no non-null environment variable is present, then the result is equivalent to having issued `setlocale(category, "C")`. That is, the locale chosen is the POSIX C locale definition, and querying the locale with `setlocale(category, NULL)` returns "C" as the locale name.
3. If no `setlocale()` function is issued, or if `setlocale(LC_ALL, "C")` is used, then the locale chosen is the pre-built POSIX C locale. Querying the locale with `setlocale(category, NULL)` returns "C" as the locale name.
4. For `setlocale(LC_ALL, "POSIX")`, the locale chosen is the pre-built POSIX C locale, and querying the locale with `setlocale(category, NULL)` returns "POSIX" as the locale name.
5. For `setlocale(LC_ALL, "SAA")`, the locale chosen is the pre-built SAA C locale. Querying the locale with `setlocale(category, NULL)` returns "SAA" as the locale name.
6. For `setlocale(LC_ALL, "S370")`, the locale chosen is the pre-built SAA C locale. Querying the locale with `setlocale(category, NULL)` returns "S370" as the locale name. As with POSIX(OFF), AMODE 64 applications do not support the "S370" locale and `setlocale` will fail requests for that name.

The `setlocale()` function supports locales built using the localedef utility, as well as locales built using the assembler source and produced by the EDCLOC macro. However, locales built using EDCLOC are not supported when running AMODE 64 applications.

The LC_TOD category for the SAA C and POSIX C locales can be customized during installation of the library by your system programmer. See "Customizing your installation" on page 1011 for more information. The supplied default will obtain the time zone difference from the operating system. However, it will not define the daylight savings time.

The LC_SYNTAX category for the SAA C and POSIX C locales is set to the IBM-1047 definition of the variant characters. Figure 258 lists other locale categories for the POSIX C locale.

```c
escape_char /
comment_char %

LC_CTYPE
% "alpha" is by default "upper" and "lower"
% "alnum" is by definition "alpha" and "digit"

Additional locale categories for POSIX C (Part 1 of 6)

Figure 258. Additional locale categories for POSIX C
```
%% "print" is by default "alnum", "punct" and <space> character
%% "punct" is by default "alnum" and "punct"


digit <zero>:<one>:<two>:<three>:<four>:<five>:<six>:<seven>:<eight>:<nine>

xdigit <zero>:<one>:<two>:<three>:<four>:<five>:<six>:<seven>:<eight>:<nine>
<zero>:<one>:<two>:<three>:<four>:<five>:<six>:<seven>:<eight>:<nine>
<zero>:<one>:<two>:<three>:<four>:<five>:<six>:<seven>:<eight>:<nine>
<zero>:<one>:<two>:<three>:<four>:<five>:<six>:<seven>:<eight>:<nine>
nl

toupper (<a>;<A>;<b>;<B>;<c>;<C>;<d>;<D>;<e>;<E>;<f>;<F>;<g>;<G>;<h>;<H>;<i>;<I>;<j>;<J>;<k>;<K>;<l>;<L>;<m>;<M>;<n>;<N>;<o>;<O>;<p>;<P>;<q>;<Q>;<r>;<R>;<s>;<S>;<t>;<T>;<u>;<U>;<v>;<V>;<w>;<W>;<x>;<X>;<y>;<Y>;<z>;<Z>

tolower (<a>;<A>;<b>;<B>;<c>;<C>;<d>;<D>;<e>;<E>;<f>;<F>;<g>;<G>;<h>;<H>;<i>;<I>;<j>;<J>;<k>;<K>;<l>;<L>;<m>;<M>;<n>;<N>;<o>;<O>;<p>;<P>;<q>;<Q>;<r>;<R>;<s>;<S>;<t>;<T>;<u>;<U>;<v>;<V>;<w>;<W>;<x>;<X>;<y>;<Y>;<z>;<Z>

END LC_CTYPE

%%% LC_COLLATE

order_start

%% ASCII Control characters
<NUL>
<SOH>
<STX>
<ETX>
<EOT>

Additional locale categories for POSIX C (Part 2 of 6)
Additional locale categories for POSIX C (Part 3 of 6)
END LC_COLLATE

Additional locale categories for POSIX C (Part 4 of 6)
positive_sign "="
negative_sign "="
int_frac_digits -1
frac_digits -1
p_cs_precedes -1
p_sep_by_space -1
n_cs_precedes -1
n_sep_by_space -1
p_sign_posn -1
n_sign_posn -1

END LC_MONETARY

%%%%%%%%%%%%%%%%
LC_NUMERIC
%%%%%%%%%%%%%%%%
decimal_point "<period>"
thousands_sep ""
grouping ""

END LC_NUMERIC

%%%%%%%%%%%%%%%%
LC_TIME
%%%%%%%%%%%%%%%%
abday "<S><u><n><n>;/<n>N><o><n><n>;/<t>T><u><e><s><d><a><y>;/<w>W><e><d><n><e><s><d><a><y>;/<t>T><h><u><r><s><d><a><y>;/<f>F><r><i><d><a><y>;/<s>S><a><t><u><r><d><a><y>

day "<S><u><n><d><a><y>;/<n>N><o><n><d><a><y>;/<t>T><u><e><s><d><a><y>;/<w>W><e><d><n><e><s><d><a><y>;/<t>T><h><u><r><s><d><a><y>;/<f>F><r><i><d><a><y>;/<s>S><a><t><u><r><d><a><y>

abmon "<J><a><n><n>;/<f>F><e><b><r><u><a><r><y>;/<m>M><a><r><c><h>;/<a>A><p><r><i><l>;/<m>M><a><y>;/<j>J><u><n><e>;/<j>J><u><l>;/<a>A><u><g>;/<s>S><e><p>;/<o>O><c><t>;/<n>N><o><v>;/<d>D><e><c>

mon "<l>L><a><n><n><u><a><r><y>;/<f>F><e><b><r><u><a><r><y>;/<m>M><a><r><c><h>;/<a>A><p><r><i><l>;/<m>M><a><y>;/<j>J><u><n><e>;/<j>J><u><l>;/<a>A><u><g>;/<s>S><e><p>;/<o>O><c><t>;/<n>N><o><v>;/<d>D><e><c>

Additional locale categories for POSIX C (Part 5 of 6)
Additional locale categories for POSIX C (Part 6 of 6)

Differences between SAA C and POSIX C locales

In fact, there are three built-in locales, S370 C, SAA C, and POSIX C. The default locale at your site depends on the system that is running the application. Issuing `setlocale(LC_ALL,"")` sets the default, based on the current environment. Issuing `setlocale(LC_ALL,"SAA")` sets the SAA C locale, even when you are running with the POSIX(ON) runtime option. Likewise, `setlocale(LC_ALL,"POSIX")` sets the POSIX locale.

If you are running in a C locale, one way you can determine if the SAA C or the POSIX locale is in effect is to check if the cent sign (¢ at X'4A') is defined as a punctuation character. Under the default POSIX support, the cent sign is not part of the POSIX portable character set. Figure 259 on page 1022 (sample CCNGDL1) shows how to perform this test.
Under the SAA or System/370 default locales, the lowercase letters collate before the uppercase letters; under the POSIX definition, the lowercase letters collate after the uppercase letters. The locale "" is the same locale as the one obtained from setlocale(LC_ALL,""). For more detail on these special environment variables, see Chapter 32, “Using environment variables,” on page 467.

Other differences between the SAA C locale and the POSIX C locale are as follows:

\(<\texttt{mb\_cur\_max}>\)

The POSIX C locale is built using coded character set IBM-1047, with \(<\texttt{mb\_cur\_max}>\) as 1. The SAA C locale is built using coded character set IBM-1047, with \(<\texttt{mb\_cur\_max}>\) as 4.

The cent sign

In the default POSIX support, the cent sign (¢) is not part of the POSIX portable character set; in the SAA locale, it is defined as a punctuation character.

Collation weight by case

In the POSIX definition, the lowercase letters collate after the uppercase letters; in the SAA or System/370 default locales, the lowercase letters collate before the uppercase letters.

\(\text{LC\_CTYPE} \text{ category}\)

The SAA C locale has all the EBCDIC control characters defined in the "\texttt{cntrl}" class. The POSIX C locale has only the ASCII control characters in the "\texttt{cntrl}" class. The SAA C locale includes "\texttt{c}" (the cent character) and "\texttt{;}" (the broken vertical line) as "\texttt{punct}" characters. The POSIX C locale does not group these characters as "\texttt{punct}" characters.

\(\text{LC\_COLLATE} \text{ category}\)

The default collation for the SAA C locale is the EBCDIC sequence. The POSIX C locale uses the ASCII collation sequence; the first 128 ASCII characters are defined in the collation sequence, and the remaining EBCDIC characters are at the end of the collating sequence.

\(\text{LC\_TIME} \text{ category}\)

The SAA C locale uses the date and time format (d_t_fmt) as "\%Y/%M/%D %X"; the POSIX C locale uses "%a %b %d %H/%M/%S %Y". The SAA C locale uses the strings "am" and "pm"; the POSIX C locale uses "AM" and "PM".

/* this example shows how to determine whether the SAA C or POSIX */
/* locale is in effect */
#include <stdio.h>
#include <ctype.h>
int main(void)
{
  if (ispunct(0x4A)) {
    printf(" cent sign is punct\n");
    printf(" current locale is SAA- or S370-like\n");
  } else {
    printf(" cent sign is not punct\n");
    printf(" default locale is POSIX-like\n");
  }
  return(0);
}

Figure 259. Determining which locale is in effect

Under the SAA or System/370 default locales, the lowercase letters collate before the uppercase letters; under the POSIX definition, the lowercase letters collate after the uppercase letters. The locale "" is the same locale as the one obtained from setlocale(LC_ALL,""). For more detail on these special environment variables, see Chapter 32, “Using environment variables,” on page 467.
Chapter 64. Code set conversion utilities

This chapter describes the code set conversion utilities supported by the z/OS XL C/C++ compiler. These utilities are as follows:

**genxlt utility**
Generates a translation table for use by the iconv utility and `iconv()` functions.

**iconv utility**
Converts a file from one code set encoding to another.  

**iconv() functions**
Perform code set translation. These functions are `iconv_open()`, `iconv()`, and `iconv_close()`. They are used by the iconv utility and may be called from any z/OS XL C/C++ program requiring code set translation.

**uconvdef utility**
Handles Universal-coded character sets. Creates binary conversion tables that define mapping between UCS-2 and multibyte code sets.


---

**The genxlt utility**

The genxlt utility reads a source translation file from `InputFile`, writes the compiled version to `OutputFile`, and then generates the translation load module. The source translation file provides the conversion specification from `fromCodeSet` to `toCodeSet`. The source translation file contains directives that are acted upon by the genxlt utility to produce the compiled version of the translation table.

The name of the conversion programs have the following naming conventions:

- The name starts with a four letter prefix. The prefix is `EDCU` for non-XPLINK converters, `CEHU` for XPLINK converters, and `CEQU` for AMODE 64 converters.
- The prefix is followed by the two-letter `CC` code that corresponds to the `CodesetRegistry.CodesetEncoding` name of the `fromCodeSet` defined in the Table 353 on page 1001.
- The first `CC` code is followed by the two-letter `CC` code that corresponds to the `CodesetRegistry.CodesetEncoding` name of the `toCodeSet` defined in the Table 353 on page 1001.

To generate your own conversions, you must modify the codeset name table `EDCUCSNM` with the macros described in “Locale naming conventions” on page 994. For descriptions of the genxlt and iconv utilities, refer to z/OS XL C/C++ User’s Guide. There is also a UNIX System Services iconv utility, which is described in z/OS UNIX System Services Command Reference.

---

**The iconv utility**

The iconv utility reads characters from the input file, converts them from `fromCodeSet` encoding to `toCodeSet` encoding, and writes them to the output file.
The conversion is performed by the code conversion functions of the runtime library. They are described in "Code conversion functions." The tables used are determined by the CC codes of the fromCodeSet and toCodeSet appended to the four-character prefix. The prefix is EDCU for non-XPLINK converters, CEHU for XPLINK converters, and CEQU for AMODE 64 converters. See z/OS XL C/C++ User’s Guide for descriptions of the genxlt and iconv utilities. There is also a UNIX System Services iconv utility, which is described in z/OS UNIX System Services Command Reference.

The iconv utility can also perform bidirectional layout transformation (such as shaping and reordering) while converting from fromCodeSet to toCodeSet according to the value of an environment variable called _BIDION. The value of this variable is either set to TRUE to activate the BiDi layout transformation or FALSE to prevent the bidirectional layout transformation. If this variable is not defined in the environment it defaults to FALSE. The _BIDIATTR environment variable can be used to contain the bidirectional attributes (for information on bidirectional layout transformation see Chapter 66, "Bidirectional language support," on page 1065) which will determine the way the bidirectional transformation takes place. These two environment variables are described in Chapter 32, "Using environment variables," on page 467.

**Code conversion functions**

The iconv_open(), iconv(), and iconv_close() library functions can be called from C or C++ source to initialize and perform the characters conversions from one character set encoding to another.

The iconv() family of functions has been modified to utilize character conversion services provided by Unicode Services. The iconv_open(), iconv(), and iconv_close() function interfaces remain unchanged except for the addition of the following:

- Four new errno values - ECUNNOENV, ECUNNOCONV, ECUNNOTALIGNED, and ECUNERR
- Two new environment variables - _ICONV_MODE and _ICONV_TECHNIQUE

For more information about these errno values and environment variables, see the iconv_open() function description in z/OS XL C/C++ Runtime Library Reference.

There are differences in externals between the iconv() family of functions and Unicode Services. However, the differences in externals are managed by the iconv() family of functions except where noted in the C/C++ Migration Guide for Application Developers. All conversions listed in Table 356 on page 1027 and Table 357 on page 1037 will continue to work as they do today. However, Unicode Services supports conversions between thousands of additional character sets not listed in Table 356 on page 1027 and Table 357 on page 1037. A complete list of conversions supported by Unicode Services can be found in EBCDIC Conversion Table, ASCII Conversion Table, and Unicode Conversion Table in z/OS Unicode Services User’s Guide and Reference. To set up a conversion using iconv_open() for any of the character sets listed in EBCDIC Conversion Table, ASCII Conversion Table, and Unicode Conversion Table, use a character string representing the CCSID’s for fromcode/tocode. For example, to set up a conversion from CCSID 00256 to CCSID 00870 using conversion technique R, you need to set the _ICONV_TECHNIQUE environment variable to R and call iconv_open() as follows:

```c
cd = iconv_open("00870", "00256");
```

and continue to use iconv() and iconv_close() as in previous releases.
**_ICONV_MODE environmental variable**

The _ICONV_MODE environmental variable selects the behavior mode for the iconv_open(), iconv(), and iconv_close() family of functions. The _ICONV_MODE value can be set to:

- **C** Users have created their own iconv() converter(s). Search for user created converters first. If the user-created converter is not located, try using Unicode Conversion Services to perform the conversion.

  **Note:** _ICONV_UCS2 and _ICONV_PREFIX environment variables will be honored while searching for user-created converters, but they will not be honored while using Unicode Conversion Services.

- **U** Use Unicode Conversion Services to perform all conversions not listed in the Table 356 on page 1027. This is the default value for _ICONV_MODE. The values of the _ICONV_UCS2 and _ICONV_PREFIX will not be honored.

**_ICONV_TECHNIQUE environmental variable**

The _ICONV_TECHNIQUE environmental variable is the technique value used by Unicode Conversion Services. For more information regarding the Unicode conversion Services value, see z/OS Unicode Services User’s Guide and Reference. _ICONV_TECHNIQUE can be set to one of the following values:

- **R** Roundtrip conversion; roundtrip conversions between two CCSIDs assure that all characters making the roundtrip arrive as they were originally.

- **E** Enforced subset conversion; enforced subset conversions map only those characters from one CCSID to another that have a corresponding character in the second CCSID. All other characters are replaced by a substitution character.

- **C** Customized conversion; customized conversions use conversion tables that have been created to address some special requirements. Note that these customized conversion tables refer to Unicode Conversion Services customized tables, not user-supplied iconv() style conversion tables.

- **L** Language Environment-Behavior conversion; Language Environment-Behavior conversions use tables that map characters like the iconv() function of the Language Environment runtime Library does. These conversions differ from others primarily in their mapping of the EBCDIC newline (NL) character to ASCII and Unicode linefeed (LF).

- **M** Modified Language Environment-Behavior conversion; Modified Language Environment-Behavior conversions use tables that map characters like the iconv() function of the Language Environment runtime library does for converters ending with C; for example IBM-932C.


  This refers to user defined tables for Unicode Conversion Services and should not be confused with user-defined converters for the Language Environment's iconv() function.

**Notes:**

1. You can specify more than one value for _ICONV_TECHNIQUE; the values will be tried in the order specified. For example, if a value of CE were specified as the _ICONV_TECHNIQUE, a converter using the Unicode Conversion
Services technique of C will be searched for first. If it does not exist, a converter using the Unicode Conversion Services technique of E will be searched for.

2. If a value is not specified for the _ICONV_TECHNIQUE environment variable, a default value of LMREC will be used.

## Code set converters supplied

A set of code set converters is provided in the National Language Resources component of z/OS Language Environment. Consult your system programmer to see if this component has been installed on your system. Figure 260 shows the converters.

### Round Trip Conversions(RTC) or Customized

Round Trip Conversions(C-RTC), which means round trip with exceptions.

**Conversions:**
- Latin-1 EBCDIC to/from Latin-1 EBCDIC: RTC
- Non-Latin-1 EBCDIC to/from Latin-1 EBCDIC: RTC
- Latin-1 ASCII to/from Latin-1 EBCDIC: C-RTC
- Non_Latin-1 ASCII to/from Latin-1 EBCDIC: C-RTC

**Example of Customized Round Trip Conversions(C-RTC) is IBM-850 to/from IBM-1047 conversion.**

**Customized Round Trip Conversion**

<table>
<thead>
<tr>
<th>Code Point</th>
<th>Code Point</th>
</tr>
</thead>
<tbody>
<tr>
<td>0A</td>
<td>15</td>
</tr>
<tr>
<td>DA</td>
<td>3F</td>
</tr>
<tr>
<td>0A</td>
<td>25</td>
</tr>
</tbody>
</table>

**Figure 260. Supplied code set converters**

The code set converters that are provided as programs are shown in Table 356 on page 1027. The GENXLIT source for the code set converters are shipped in the CEE/SC/EGXLT data set.

**Notes:**

1. Table 355 shows the <prefix> values that appear in the Program Name column of Table 356 on page 1027.

**Table 355. Referencing data types**

<table>
<thead>
<tr>
<th>Converter</th>
<th>Prefix</th>
</tr>
</thead>
<tbody>
<tr>
<td>31-bit</td>
<td>EDCU</td>
</tr>
<tr>
<td>31-bit XPLINK</td>
<td>CEHU</td>
</tr>
<tr>
<td>AMODE 64</td>
<td>CEQU</td>
</tr>
</tbody>
</table>

2. Specify IBM-932C or IBM-eucJC as the iconv_open() source or target code set name to set up for conversion of POSIX data encoded by IBM-932 or IBM-eucJP to or from a host code set encoding of the data such as IBM-930 or IBM-939.

Examples of POSIX data are C/C++ source and shell scripts. The data includes characters from the POSIX character set. The names IBM-932C and IBM-eucJC indicate that the <yen> and <overline> characters in POSIX data encoded by IBM-932 or IBM-eucJP map to the <backslash> and <tilde> characters, respectively, when the data is converted to or from host encodings.
CAUTION:
The naming conventions provided for building genxlt conversion tables allow
the iconv interfaces to recognize the converters. All genxlt conversion tables,
whether customized or shipped in z/OS Language Environment, are intended for
use with the C/C++ iconv interfaces or the iconv utility. Direct programming to
these tables is not supported and will produce unpredictable results.

IBM makes no guarantee that converter binaries or source shipped with z/OS
Language Environment will continue to be shipped in future releases. For a
complete list of names and aliases removed in z/OS V1R9, go to the following
URL: http://www-03.ibm.com/systems/z/os/zos/features/lang_environment/
assist/support/pk65279.html

UCS-2 converters, still shipped with z/OS Language Environment in z/OS V1R9,
are removed in z/OS V1R11. See "Universal coded character set converters" on
page 1035 for more information.

Starting in z/OS V1R12, the C/C++ Runtime Library will not ship the genxlt
source for character conversions performed by Unicode Services. However, if
you require the affected genxlt converters and plan to build them by creating
your own source or by migrating source from a prior release, you must continue
to name them as shown in Table 356. For more details, refer to “The genxlt
utility” on page 1023.

Table 356. Coded character set conversion tables

<table>
<thead>
<tr>
<th>FromCode</th>
<th>ToCode</th>
<th>GENXLT source shipped</th>
<th>Program Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>IBM-858</td>
<td>IBM-1047</td>
<td>Yes</td>
<td>&lt;prefix&gt;AIEY</td>
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### Table 356. Coded character set conversion tables (continued)

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<th>FromCode</th>
<th>ToCode</th>
<th>GENXLT source shipped</th>
<th>Program Name</th>
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### Table 356. Coded character set conversion tables (continued)

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### Universal coded character set converters

You can use the name UCS-2 to request setup for conversion to and from the Universal Two-Octet Coded Character Set, UCS-2, specified in ISO/IEC International Standard 10646–1. For example, `iconv_open("UCS-2", "IBM-1047")` requests setup for conversion from IBM-1047 character encoding to UCS-2 character encoding.
You can also use the name UTF-8 to request setup for conversion to and from Transform Format 8, UTF-8, specified in Unicode Standard, Version 2.1, Appendices A-7 and A-8. For example, iconv_open("UTF-8", "IBM-1047") requests setup for conversion from IBM-1047 character encoding to UTF-8 character encoding.

Before z/OS V1R12, source for UCS-2 converters was in a data set named installation-prefix.SCEEUMAP, where the installation prefix for z/OS XL C/C++ data sets defaults to CEE. UCS-2 source was also installed in the z/OS UNIX file system directory /usr/lib/nls/locale/ucmap. Starting in z/OS V1R12, IBM will no longer ship UCS-2 source with the C/C++ Runtime Library.

The uconvdef command, which is documented in z/OS UNIX System Services Command Reference, produces uconvTable binary files required by iconv_open() from UCS-2 source files.

The following notes apply only when you create your own converters:

- The iconv() family of functions uses Unicode Services to perform character conversion to or from UCS-2. Therefore, IBM no longer ships uconvTable binaries in either the installation-prefix.SCEEUTBL data set or the z/OS UNIX file system directory /usr/lib/nls/locale/uconvTable. Both the installation-prefix.SCEEUTBL data set and the /usr/lib/nls/locale/uconvTable directory have been removed. Users who create their own uconvTable converters need to create the installation-prefix.SCEEUTBL data set, the /usr/lib/nls/locale/uconvTable directory, or both to hold the converters. The installation-prefix.SCEEUTBL data set needs to be created with a fixed block record format and lrecl of 80.

- If your installation uses an installation-prefix different from CEE for z/OS XL C/C++ data sets, you must use the environment variable _ICONV_UCS2_PREFIX to specify the value of your installation-prefix before using iconv_open() to set up UCS-2 converters. Otherwise, iconv_open() cannot find your z/OS XL C/C++ uconvTable binary data set. One way to do this is to use the ENVAR runtime option when you start your application. For example, ENVAR(...,_ICONV_UCS2_PREFIX=YOUR.PREFIX, ...) has iconv_open() search for uconvTable binaries it requires in the data set YOUR.PREFIX.SCEEUTBL.

- If uconvTable binaries are installed in both the z/OS UNIX file system directory named /usr/lib/nls/locale/uconvTable and installation-prefix.SCEEUTBL data set, the iconv_open() function searches for uconvTable binaries in the z/OS UNIX file system before searching in the z/OS XL C/C++ UCS-2 data set.

- You can use the LOCPATH environment variable to give iconv_open() a colon-separated list of pathname prefixes to use instead of /usr/lib/nls/locale/ to find uconvTable directories in your z/OS UNIX file system.

- If you have created your own conversion tables and want the iconv() family of functions to use them, you need to set the _ICONV_MODE environment variable to C.

- If you want to create customized conversion tables with any of the CCSIDs related to the conversion table source that is no longer shipped, create customized Unicode Services conversion tables instead of customized LE conversion tables. For information about how to generate and use customized Unicode Services conversion tables, see z/OS Unicode Services User’s Guide and Reference.

You must set the _ICONV_TECHNIQUE environment variable to the same technique search order value used for the customized Unicode Services table in order for the iconv() family of functions to use the customized Unicode Services.
table. For example, if you want the `iconv()` family of functions to use a user defined Unicode Services table with a technique search order of 2, you need to set the `_ICONV_TECHNIQUE` environment variable to 2LMREC.

- The uconvdef and genxlt utilities continue to be shipped and maintained in z/OS V1R12. If you do not want to use Unicode Services to create customized conversion tables, you can continue to use the uconvdef and genxlt utilities. However, you must obtain the ucmap or genxlt source in one of the following ways:
  - Migrate the ucmap or genxlt source forward from a previous z/OS release.
  - Create the ucmap or genxlt source on your own.
  - Get the ucmap or genxlt source from the IBM Character Data Representation Architecture Conversion resources:
    

The UCS-2 and genxlt conversion table binaries produced by the uconvdef and genxlt utilities continue to be supported by the `iconv()` family of functions if you set the `_ICONV_MODE` environment variable to C. You must obtain the conversion table binaries in one of the following ways:

  - Migrate the conversion table binaries from a previous z/OS release.
  - Create the conversion table binaries by your own.
  - Create the conversion table binaries by the uconvdef or genxlt utilities.

**Note:** IBM makes no guarantee that the uconvdef or genxlt utilities will continue to be supported in future releases.

Members in the UCS-2 source data sets have names of the form `EDCUUccU`, where `cc` is the CC-id associated with a particular coded character set name. [Table 357](#) shows the CC-id and member name associated with each coded character set name for which UCS-2 source is provided. The UCS-2 source is in a data set named `installation-prefix.SCEEUMAP`. The default value of the installation-prefix is CEE.

**CAUTION:**
UCS-2 converter binaries added to the SCEEUTBL data set or the uconvTable directory must follow the `EDCUUccU` naming convention that allows `iconv` interfaces to recognize a UCS-2 converter.

All UCS-2 tables are intended for the use with the C/C++ `iconv` interfaces or the `iconv` utility. Direct programming to these tables is not supported and will produce unpredictable results.

Starting in z/OS V1R12, IBM will not ship conversion table source in either the `installation-prefix.SCEEUMAP` data set or the `/usr/lib/nls/locale/ucmap` directory. However, if you choose to migrate the conversion tables to your own `installation-prefix.SCEEUTBL` data set, you need to continue to name them as listed in [Table 357](#).

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Table 357. UCS-2 converter names (continued)

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### Codeset conversion using UCS-2

*z/OS XL C/C++* `iconv` supports use of UCS-2 as an intermediate code set for conversion of characters encoded in one code set to another. The `_ICONV_UCS2` environment variable instructs `iconv_open("Y", "X")` whether or not to set up indirect conversion from code set X to code set Y using UCS-2 as an intermediate code set. Values `iconv_open()` recognizes for `_ICONV_UCS2` are:

1. Set up indirect conversion using UCS-2 first. The indirect conversions will use direct unicode converters if available, if not, `iconv_open()` will fopen/fread uconvTable binaries. If set up of indirect conversion fails, `iconv_open()` will try to set up direct conversion.

2. Set up direct conversion first. If this fails, try to set up indirect conversion.
using UCS-2. The indirect conversions will use direct unicode converters if available, if not, `iconv_open()` will fopen/fread uconvTable binaries. This is the default.

3 Set up direct conversion first. If this fails, try to set up indirect conversion using UCS-2. The indirect conversions will use direct unicode converters, if direct unicode converters are unavailable, the `iconv_open()` request fails.

N Never set up indirect conversion using UCS-2. If a direct converter cannot be found, the `iconv_open()` request fails.

D Never set up indirect conversion using UCS-2. If a direct converter cannot be found, the `iconv_open()` request fails.

O Only set up indirect conversion using UCS-2. `iconv_open()` will fopen/fread uconvTable binaries. Direct unicode converters will not be used. If required unconvTable binaries cannot be found, the `iconv_open()` request fails.

U Only set up indirect conversion using UCS-2. The indirect conversions will use direct unicode converters if available, if not, `iconv_open()` will fopen/fread uconvTable binaries.

Notes:
1. `_ICONV_UCS2` environment variable only has effect when ICONV_MODE is set to C.
2. If the value of the `_ICONV_UCS2` environment variable allows `iconv_open("Y", "X")` to use UCS-2 as an intermediate code set when it cannot find a direct converter from X to Y, `iconv_open()` will attempt to do so even if X and Y are not compatible code sets. That is, even if character sets encoded by X and Y are not the same, `iconv_open()` will set up conversion from X to UCS-2 to Y.
3. The application must specify compatible source and target code set names on various `iconv_open()` requests. For detailed information about code set characteristics, refer to the specific coded character set identifier in the CCSID repository. For more information, refer to the following URL:

```
```

UCMAP source format

A UCMAP source file defines UCS-2 (Unicode) conversion mappings for input to the uconvdef command. Conversion mapping values are defined using UCS-2 symbolic character names followed by character encoding (code point) values for the multibyte code set. For example:

```xml
<U0020>
\x20 represents the mapping between the <U0020> UCS-2 symbolic character name for the space character and the \x20 hexadecimal code point for the space character in ASCII.
```

In addition to the code set mappings, directives are interpreted by the uconvdef command to produce the compiled table. These directives must precede the code set mapping section. They consist of the following keywords surrounded by < (angle brackets), starting in column 1, followed by white space and the value to be assigned to the symbol:

```
<comment_char>
Character used to denote start of escape sequence. Default escape character is <number_sign> (#). In ucmmap, source shipped by C/370 <percent_sign> (%) is specified for <comment_char>.
```
<escape_char>
  Character used to denote start of escape sequence. Default escape character
  is <backslash> (\). In ucmap source shipped by C/370 <slash> (/) is
  specified for <escape_char>.

<code_set_name>
  The name of the coded character set, enclosed in quotation marks("), for
  which the character set description file is defined.

<mb_cur_max>
  The maximum number of bytes in a multibyte character. The default value
  is 1.

<mb_cur_min>
  An unsigned positive integer value that defines the minimum number of
  bytes in a character for the encoded character set. The value is less than or
  equal to <mb_cur_max>. If not specified, the minimum number is equal to
  <mb_cur_max>.

<char_name_mask>
  A quoted string consisting of format specifiers for the UCS-2 symbolic
  names. This must be a value of AXXXX, indicating an alphabetic character
  followed by 4 hexadecimal digits. Also, the alphabetic character must be a
  U, and the hexadecimal digits must represent the UCS-2 code point for the
  character. An example of a symbolic character name based on this mask is
  <U0020> Unicode space character.

<uconv_class>
  Specifies the type of the code set. It must be one of the following:
  SBCS  Single-byte encoding
  DBCS  Stateless double-byte, single-byte, or mixed encodings
  EBCDIC_STATEFUL  Stateful double-byte, single-byte, or mixed encodings
  MBCS  Stateless multibyte encoding

  This type is used to direct uconvdef on the type of table to build. It is also stored
  in the table to indicate the type of processing algorithm in the UCS conversion
  methods.

<locale>
  Specifies the default locale name to be used if locale information is needed.

<subchar>
  Specifies the encoding of the default substitute character in the multibyte
  code set.

The mapping definition section consists of a sequence of mapping definition lines
preceded by a CHARMAP declaration and terminated by an END CHARMAP
declaration. Empty lines and lines containing <comment_char> in the first column
are ignored.

Symbolic character names in mapping lines must follow the pattern specified in
the <char_name_mask>, except for the reserved symbolic name, <unassigned>,
that indicates the associated code points are unassigned.

Each noncomment line of the character set mapping definition must be in one of
the following formats:
1. This format defines a single symbolic character name and a corresponding encoding.

"%s%s/n", <symbolic_name>, <encoding>, <comments>
For example: <U3004> \x81\x57
The encoding part is expressed as one or more concatenated decimal, hexadecimal, or octal constants in the following formats:
- "%c%d",<escape_char>, <decimal byte value>
- "%cx%x",<escape_char>,<hexadecimal byte value>
- "%c%o",<escape_char>,<octal byte value>
Decimal constants are represented by two or more decimal digits preceded by the escape character and the lowercase letter d, as in \d97 or \d143.
Hexadecimal constants are represented by two or more hexadecimal digits preceded by an escape character and the lowercase letter x, as in \x61 or \x8f.
Octal constants are represented by two or more octal digits preceded by an escape character.
Each constant represents a single-byte value. When constants are concatenated for multibyte character values, the last value specifies the least significant octet and preceding constants specify successively more significant octets.

2. This format defines a range of symbolic character names and corresponding encodings. The range is interpreted as a series of symbolic names formed from the alphabetic prefix and all the values in the range defined by the numeric suffixes.

"%s...%s %s %s/n",<symbolic-name>,<symbolic_name>,<encoding><comments>
For example: <U3003><U3006> \x81\x56
The listed encoding value is assigned to the first symbolic name, and subsequent symbolic names in the range are assigned corresponding incremental values. For example, the line:
/U3003>...<U3006> \x81\x56
is interpreted as:
/U3003> \x81\x56
/U3004> \x81\x57
/U3005> \x81\x58
/U3006> \x81\x59

3. This format defines a range of one or more unassigned encodings.

"<unassigned>"%s...%s %s/n",<encoding>,<comments>
For example, the line
/unassigned> \x9b...\x9c
is interpreted as:
/unassigned> \x9b <unassigned> \x9c
Chapter 65. Coded character set considerations with locale functions

Each EBCDIC *coded character set* consists of a mapping of all the available glyphs to their respective hex encodings and unique Graphic Character Global Identifiers (GCGIDs). GCGIDs are unique identifiers assigned to each character in the Unicode standard. A *glyph* is the printed appearance of a character. Each coded character set serves one linguistic environment.

There is wide variation among coded character sets; many glyphs do not appear in all coded character sets, and hexadecimal encodings for some glyphs differ from one coded character set to another. You may encounter problems when exporting a file from a system running in one coded character set, to a system running in another. For example, a left bracket (¡) entered under the APL-293 or Open Systems IBM-1047 coded character set will appear as the capitalized Y-acute (Ý). This occurs in such common coded character sets as International 500, France 297, Germany 273, and US or Canada 037.

*z/OS XL C/C++* contains the following extensions to prevent such problems:

- The `#pragma filetag` directive allows you to specify the coded character set that was used when entering the source files. See “The `pragma filetag` directive” on page 1053 for details on this pragma.
- The `LOCALE` compiler option enables you to tell the compiler what locale to use at compile time. See “Converting coded character sets at compile time” on page 1056 for details on this compiler option.
- The `CONVLIT` compiler option enables you to change the assumed code page for string literals. See “`CONVLIT` compiler option” on page 1056 for details on this compiler option.
- The `#pragma convert` directive allows you to change the assumed code page for string literals. It has the advantage of allowing more than one character encoding to be used for string literals in a single compilation unit. For more information, see `convert` in z/OS XL C/C++ Language Reference.

These facilities cause the compiler to respect your code page. Thus, you can enter source code with what appears to you to be the correct characters, and the compiler will recognize those characters.

The rest of this chapter discusses other ways to work efficiently in different locales.

### Variant character detail

The POSIX Portable Character Set (PPCS) identifies the core set of 128 characters that are needed to write code and to run applications. Of these, 13 characters are variant among the EBCDIC coded character sets.

Table 358 on page 1048 lists these 13 characters. It also displays their appearance when the Open Systems coded character set IBM-1047 hexadecimal values are entered on systems where different Country Extended Coded Character Sets are installed. These hex values are the ones expected by z/OS XL C/C++, and are consistent with the use of the APL-293 coded character set.
Table 358. Mappings of 13 PPCS variant characters

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>left bracket</td>
<td>AD</td>
<td>[</td>
<td>]</td>
<td>Ÿ</td>
<td>Ÿ</td>
<td>Ÿ</td>
<td>Ÿ</td>
</tr>
<tr>
<td>right bracket</td>
<td>BD</td>
<td>]</td>
<td>]</td>
<td>ü</td>
<td>~</td>
<td>ü</td>
<td>&quot;</td>
</tr>
<tr>
<td>left brace</td>
<td>C0</td>
<td>{</td>
<td>[</td>
<td>{</td>
<td>é</td>
<td>ä</td>
<td>{</td>
</tr>
<tr>
<td>right brace</td>
<td>D0</td>
<td>}</td>
<td>]</td>
<td>{</td>
<td>ü</td>
<td>}</td>
<td>)</td>
</tr>
<tr>
<td>backslash</td>
<td>E0</td>
<td>\</td>
<td>\</td>
<td>\</td>
<td>ã</td>
<td>\</td>
<td></td>
</tr>
<tr>
<td>circumflex</td>
<td>5F</td>
<td>^</td>
<td>^</td>
<td>^</td>
<td>^</td>
<td>^</td>
<td>^</td>
</tr>
<tr>
<td>tilda</td>
<td>A1</td>
<td>~</td>
<td>~</td>
<td>ü .</td>
<td>ª</td>
<td>β</td>
<td>~</td>
</tr>
<tr>
<td>exclamation mark</td>
<td>5A</td>
<td>!</td>
<td>!</td>
<td>]</td>
<td>§</td>
<td>Ü</td>
<td>!</td>
</tr>
<tr>
<td>pound (number) sign</td>
<td>7B</td>
<td>#</td>
<td>#</td>
<td>#</td>
<td>£</td>
<td>#</td>
<td>#</td>
</tr>
<tr>
<td>vertical bar</td>
<td>4F</td>
<td>!</td>
<td>!</td>
<td>!</td>
<td>!</td>
<td>!</td>
<td>!</td>
</tr>
<tr>
<td>accent grave</td>
<td>79</td>
<td>&quot;</td>
<td>&quot;</td>
<td>&quot;</td>
<td>µ</td>
<td>&quot;</td>
<td>&quot;</td>
</tr>
<tr>
<td>dollar sign</td>
<td>5B</td>
<td>$</td>
<td>$</td>
<td>$</td>
<td>$</td>
<td>$</td>
<td>$</td>
</tr>
<tr>
<td>commercial &quot;at&quot;</td>
<td>7C</td>
<td>@</td>
<td>@</td>
<td>@</td>
<td>á</td>
<td>§</td>
<td>@</td>
</tr>
</tbody>
</table>

Table 359 lists the hexadecimal values assigned across some of the EBCDIC coded character sets for the 13 variant characters from the PPCS. Appendix C, “z/OS XL C/C++ code point mappings,” on page 1089 gives more information about the mapping of glyphs and Appendix A, “POSIX character set,” on page 1079 lists the full PPCS.

Table 359. Mappings of Hex encoding of 13 PPCS variant characters

<table>
<thead>
<tr>
<th>Character Name</th>
<th>Glyph</th>
<th>GCGID</th>
<th>Open Systems IBM-1047 view</th>
<th>APL IBM-293 view</th>
<th>International 500 view</th>
<th>France 297 view</th>
<th>Germany 273 view</th>
<th>US/Can 037 view</th>
</tr>
</thead>
<tbody>
<tr>
<td>left bracket</td>
<td>[</td>
<td>SM060000</td>
<td>AD</td>
<td>AD</td>
<td>4A</td>
<td>90</td>
<td>63</td>
<td>BA</td>
</tr>
<tr>
<td>right bracket</td>
<td>]</td>
<td>SM080000</td>
<td>BD</td>
<td>BD</td>
<td>5A</td>
<td>B5</td>
<td>FC</td>
<td>BB</td>
</tr>
<tr>
<td>left brace</td>
<td>{</td>
<td>SM110000</td>
<td>C0</td>
<td>C0</td>
<td>C0</td>
<td>51</td>
<td>43</td>
<td>C0</td>
</tr>
<tr>
<td>right brace</td>
<td>}</td>
<td>SM140000</td>
<td>D0</td>
<td>D0</td>
<td>D0</td>
<td>54</td>
<td>DC</td>
<td>D0</td>
</tr>
<tr>
<td>backslash</td>
<td>\</td>
<td>SM070000</td>
<td>E0</td>
<td>E0</td>
<td>E0</td>
<td>48</td>
<td>EC</td>
<td>E0</td>
</tr>
<tr>
<td>circumflex</td>
<td>^</td>
<td>SD150000</td>
<td>5F</td>
<td>5F</td>
<td>5F</td>
<td>5F</td>
<td>5F</td>
<td>B0</td>
</tr>
<tr>
<td>tilda</td>
<td>~</td>
<td>SD190000</td>
<td>A1</td>
<td>A1</td>
<td>A1</td>
<td>BD</td>
<td>59</td>
<td>A1</td>
</tr>
<tr>
<td>exclamation mark</td>
<td>!</td>
<td>SP020000</td>
<td>5A</td>
<td>5A</td>
<td>4F</td>
<td>4F</td>
<td>4F</td>
<td>5A</td>
</tr>
<tr>
<td>pound (number) sign</td>
<td>#</td>
<td>SM010000</td>
<td>7B</td>
<td>7B</td>
<td>7B</td>
<td>B1</td>
<td>7B</td>
<td>7B</td>
</tr>
<tr>
<td>vertical bar</td>
<td>!</td>
<td>SM130000</td>
<td>4F</td>
<td>4F</td>
<td>BB</td>
<td>BB</td>
<td>BB</td>
<td>4F</td>
</tr>
<tr>
<td>accent grave</td>
<td>`</td>
<td>SD130000</td>
<td>79</td>
<td>79</td>
<td>79</td>
<td>A0</td>
<td>79</td>
<td>79</td>
</tr>
<tr>
<td>dollar sign</td>
<td>$</td>
<td>SC030000</td>
<td>5B</td>
<td>5B</td>
<td>5B</td>
<td>5B</td>
<td>5B</td>
<td>5B</td>
</tr>
<tr>
<td>commercial &quot;at&quot;</td>
<td>@</td>
<td>SM050000</td>
<td>7C</td>
<td>7C</td>
<td>7C</td>
<td>44</td>
<td>B5</td>
<td>7C</td>
</tr>
</tbody>
</table>
Two tables are available to show the full code—point mappings for Open Systems coded character set IBM-1047 (Figure 274 on page 1089) and for the APL coded character set IBM-293 (Figure 275 on page 1090). Upon examination of these coded character sets, you will notice that coded character set 1047 is a “Latinized” coded character set IBM-293. All the APL code points have been replaced by Latin 1 code points, allowing a one-to-one mapping among coded character set IBM-1047 and all other coded character sets in the Latin 1 group.

Although the official current coded character set for z/OS XL C/C++ is now coded character set IBM-1047 (Open Systems), the coded character set IBM-293 syntax points are still valid. Those points are the ones with syntactic relevance to the z/OS XL C/C++ compiler. Refer to Table 358 on page 1048 and Table 359 on page 1048 for more information.

**Alternate code points**

All syntactic code points that were supported in previous versions of z/OS XL C/C++ will continue to be supported if you are compiling with the NOLOCALE option.

To be compatible, the vertical bar character is represented by the following two encodings, provided you are not using the LOCALE compiler option or the NOLOCALE option:

- X'4F'
- X'6A'

If you do specify the LOCALE compiler option, each of these characters is represented by a unique value specified in the LC_SYNTAX category of the selected locale.

**Coding without locale support by using a hybrid coded character set**

If you want to avoid using the locale of the compiler, use a hybrid coded character set. A hybrid piece of code is in the local coded character set but the syntax is written as if it were in coded character set IBM-1047.

You can continue coding in the local coded character set, writing the syntax as if it were in coded character set IBM-1047. This solution uses the existing behavior of the compiler, but this method is not ideal for the following reasons; Figure 261 on page 1050 illustrates these difficulties.

- The code can be difficult to read and may not even look like C code anymore.
- There may be ambiguities in the code.
- Exporting code to another site can be difficult because the mapping between the hybrid characters used and the target coded character set may not be exact.
The code points in Figure 261, which have different glyphs in character code set IBM-273 and APL-293, are described below:

1. code point for the { character. In coded character set 273, this is the character ä.
2. code point for the [ character. In coded character set 273, this is the character Ŷ.
3. code point for the ] character. In coded character set 273, this is the character ü.
4. code point for the } character. In coded character set 273, this is the character û.

Figure 261. Example of hybrid coded character set

The code points in Figure 261, which have different glyphs in character code set IBM-273 and APL-293, are described below:

1. code point for the { character. In coded character set 273, this is the character ä.
2. code point for the [ character. In coded character set 273, this is the character Ŷ.
3. code point for the ] character. In coded character set 273, this is the character ü.
4. code point for the } character. In coded character set 273, this is the character û.
code point for the \ character. In coded character set 273, this is the character Ö.

6 code point for the ! character. In coded character set 273, this is the character Ü.

7 code point for the | character. In coded character set 273, this is the character !. This particular code point mapping is unfortunate because the | character and the ! character are both valid C syntax characters. Note that the ! character used in the `printf()` call at 4 will appear as ! on a terminal displaying in coded character set 273.

Writing code using a hybrid coded character set

Figure 261 on page 1050 illustrates some of the problems with hybrid files. The following steps were done when writing this code:

1. Look up each variant character in coded character set IBM-1047 to find out what the compiler expects. For example, z/OS XL C/C++ expects the character [ to have a byte value of X'AD'.

2. Determine which glyph is at X'AD' in the local coded character set, then use this in the code.

3. Always use the appropriate substitution. For example, to obtain a needed [ in Germany, one would look up X'AD' in the German IBM-273 coded character set, and find the character Ÿ.

Converting hybrid code

Existing code that was written in a hybrid coded character set will continue to be supported. Appendix G, “Converting hybrid code to a specific character set,” on page 1133 shows you a program you can use to convert the hybrid code to another coded character set.

Coded character set independence in developing applications

You can ensure that you are working effectively with the locale functionality if you use the appropriate functions, macros, and tools. Figure 262 on page 1052 is a summary of the compile-edit work flow and shows which functions to use and where you can use them.
Setup. The `localedef` information (see overview in Chapter 61, “Customizing a locale,” on page 1005 and details in “Locale source files” on page 964).

1. **Coded character set of source code, header files, and data.** The compiler must support the coded character set used to create a source file so that it will recognize the variant C syntax characters correctly.

   - The `#pragma filetag` directive identifies the coded character set of the source file as well as the library or user's include files (for an overview see “The pragma filetag directive” on page 1053).
   - Predefined macros `__LOCALE__`, `__FILETAG__`, and `__CODESET__` (for an overview see “Using predefined macros” on page 1054).
   - The function `setlocale()`.
   - The pragma `convlit` directive.
   - The pragma `convert` directive.

2. **Coded character set conversion utilities and functions.** The coded character set of a file, or a stream of data, can be converted to another coded character set using the utilities `genxlt` and `iconv` (for an overview see Chapter 64, “Code set conversion utilities,” on page 1025 for the details of the utilities and functions see z/OS XL C/C++ User's Guide), as well as the functions in the runtime library.

3. **Coded character set conversion at compile time** is determined by the compile-time locale and supported by the compiler options, `LOCASE` and `NOLOCASE` (for an overview, see “Converting coded character sets at compile time” on page 1056 for details, see `LOCASE` in z/OS XL C/C++ User's Guide).
Runtime environment. During run time, the setlocale() function has an effect on runtime functions, such as printf(), scanf(), and regcomp(), which use variant characters.

Listings and output files. The coded character set used to create or to convert source files may affect listings, preprocessed source code, object modules, and SYSEVENT files (for an overview see "Object modules and output listings" on page 1058). Your application can, however, include logic using the following to minimize the impact:

• __LOCALE__, __FILETAG__, and __CODESET__ macros
• Locale functions such as setlocale()

Coded character set in source code and header files

There are five types of locale-related changes that you can make in your source code:

• You can tag your source code and other associated files with the #pragma filetag directive to specify the coded character set that was used while entering the file. You can then compile these to ensure that all variant characters in your files are correct.

• You can use the three macros: __LOCALE__, __FILETAG__, and __CODESET__. These z/OS XL C/C++ macros expand to provide information about the #pragma filetag directive of the current source, and the locale and target coded character set used by the compiler at compile time. For more information, see predefined macros for [ISO Standard and z/OS XL C/C++ in z/OS XL C/C++ Language Reference.]

• You can use the setlocale() function to set the runtime locale to be the same as the locale used to compile the application. This can be used when your application contains dependencies on the coded character set, as it would when comparing constants with external data. Using the macros forces the runtime locale to be the same as the one used to compile your code.

• You can use the #pragma convlit suspend and resume to exclude portions of your code from string literal conversion. See CONVLIT in z/OS XL C/C++ User’s Guide for more details on the compiler option and convlit in z/OS XL C/C++ Language Reference for more information on the pragma.

• You can use the #pragma convert directive to specify the coded character set to use for converting string literals. See convert in z/OS XL C/C++ Language Reference for more information on this pragma.

The pragma filetag directive

By using the #pragma filetag directive, you may write your programs in any convenient supported coded character set (see Appendix D, “Locales supplied with z/OS XL C/C++,” on page 1091 for a list of coded character set names). The #pragma filetag directive instructs the z/OS XL C/C++ compiler how to “read” the source. Tagging the source files, the header files, and all data files (including messages) with the #pragma filetag directive enables you to keep the information about the coded character set used to create each source file, within the source file itself. This information can be helpful when moving source files to systems with different coded character sets. For more information, see filetag in z/OS XL C/C++ Language Reference.

The following example tag uses the German coded character set IBM-273:

??=pragma filetag("IBM-273")
Because the # character is variant in different coded character sets, you must use the trigraph ??= for the #pragma filetag directive.

The #pragma filetag directive specifies the coded character set in which the source or data was entered. The coded character set specified in the #pragma filetag directive is in effect for the entire source file, but not for any other source file. This also applies to header files and data files.

The #pragma filetag directive can only appear once in each file, and it must appear before the first statement in a program. If encountered elsewhere, a warning appears and the directive does not change. If a comment contains variant characters and appears before the directive, the comment does not translate.

Attention: If you wish to use the iconv utility on a file that is tagged with the ??= #pragma filetag directive, you must update the file manually to change the filetag to the correct converted coded character set. iconv does not update the pragma in source files.

Using predefined macros
There are three macros for z/OS XL C/C++ that relate to locale.

__LOCALE__
This macro expands to a string literal representing the locale of the LOCALE compiler option. This macro can be used to set the runtime locale to be the same as the compiled locale:

```c
main() {
    setlocale(LC_ALL, __LOCALE__);
    ...
}
```

The value of this macro is defined per compilation. If NOLOCALE compiler option is supplied, the macro is undefined.

__FILETAG__
This macro expands to a string literal representing the character coded character set of the #pragma filetag directive associated with the current file. For example, to convert to the coded character set specified by the LOCALE option from the coded character set specified by the #pragma filetag directive, you would use the iconv_open() function:

```c
iconv_open(__FILETAG__, variable);
```

The value of this macro is defined per source file. If no #pragma filetag directive is present, the macro is undefined.

__CODESET__
This macro expands to a string literal representing the character coded character set of the LOCALE compiler option. The value of this macro is defined per compilation. If a value is not supplied, the macro is undefined.

Figure 263 on page 1055 shows an example program (CCNGCC2) that uses the __CODESET__ macro.
Figure 264 on page 1056 shows the values that these macros will take on, emphasizing that for __FILETAG__, a value is assigned for each source file, but for __LOCALE__ and __CODESET__, a value is assigned for a compilation.
Using setlocale()

You can change the runtime locale to any one of the other predefined locales listed in [Table 362 on page 1092]. To use a defined locale, refer to it by its setlocale() parameter. To define a new locale, copy the source file provided, edit it, then assemble it (see Chapter 61, “Customizing a locale,” on page 1005).

Converting coded character sets at compile time

The following section describe compiler options you can use to covert coded character sets.

CONVLIT compiler option

You can control the conversion of string literals in your code by using the CONVLIT compiler option. CONVLIT provides a means for changing the assumed code page for character string literals by supplying a codepage value. For more information, see [CONVLIT] in z/OS XL C/C++ User’s Guide.

For example, if you used an ASCII client machine to write code that uses string literals, and then upload this to an EBCDIC server such as MVS, your string literals would be converted to EBCDIC. However, if you specified "CONVLIT(1508859-1)" when you compiled your code, your string literals would have been converted to an ASCII code page.
For example, consider the program in Figure 265. When this program is compiled with the CONVLIT(ISO8859-1) option, the string "Hi There!" will be converted to an ASCII string, but the string "Hello World" will not be converted.

```
/* header.h */
char *text="Hello World";

/* test.c */
#pragma convlit(suspend)
#pragma comment (user, "A user comment")
#include <stdio.h>
#include "header.h"
#pragma convlit(resume)
main (){char *text2 ="Hi There!";
}
```

Figure 265. Using the CONVLIT compiler option

**LOCALE compiler option**

The LOCALE compiler option enables you to instruct the compiler to use a specific locale at compile time, which then generates the output in the same coded character set.

The input files that are affected are:
- The primary source file
- Library header files
- User header files

The output files that are affected are:
- Object Modules
- Preprocessed source code
- Listings

To use the LOCALE option, you must supply a locale name value. The locale name is a string that represents the locale you want to compile source with; this will determine the characteristics of output, including the coded character set used for variant characters in the source. Usually, a locale name is of the format *territory name.coded character set*. For example, the German locale for coded character set 273 is *De_DE.IBM-273*. The *territory name* is *De_DE* and the *coded character set* is IBM-273. To determine the coded character set of the current locale, use the function `nl_langinfo(CODESET)`.

The special locale name "" gives you the default locale, which can be set using environment variables. The locale name "C" specifies the C default locale. Full details about the C locale are found in Chapter 63, "Definition of S370 C, SAA C, and POSIX C locales," on page 1015.

The default option setting is NOLOCALE. It instructs the compiler to do no conversion of text for input or for output.

You can create your own locales by using the *localedef* utility. See "Locale source files" on page 964 for details.
**Examples:** To compile a sample file, userid.SORTNAME.C, enter:

```
CC 'userid.SORTNAME.C' (LOCALE("De_DE.IBM-273")
```

The compiler recognizes "De_DE.IBM-273" as a valid locale and automatically converts the source code to coded character set IBM-273, for its own use. The compiler would then generate listings in the German coded character set 273.

To generate a preprocessed file that can be sent to other sites, that use different coded character sets, enter:

```
CC 'userid.SORTNAME.C' (LOCALE("De_DE.IBM-273") PPONLY
```

The compiler will insert the #pragma filetag directive at the start of the preprocessed file, using the coded character set specified in the LOCALE option. In this example, ??=pragma filetag("IBM-273") is inserted.

Since the preprocessed file has been tagged, it can be compiled using the z/OS XL C/C++ compiler at any site, regardless of the locale used.

**Summary of usage for LOCALE, NOLOCALE, and pragma filetag directive:** The following list shows the results from different combinations of the #pragma filetag directive and the LOCALE compiler option.

**Using LOCALE compiler option**

In this case, the compiler does the following:

- Converts the source code from the coded character set specified with the #pragma filetag directive to the code set specified by the LOCALE compiler option.
- If no #pragma filetag directive is specified, the compiler assumes the source is in the same coded character set as specified by the locale, and does not perform any conversion.
- Converts compiler error messages from coded character set IBM-1047 to the coded character set specified in the LOCALE compiler option.
- Generates compiler output in the same coded character set as that of the locale specified in the LOCALE compiler option.
- If PPONLY was specified, the compiler inserts the #pragma filetag directive at the beginning of the preprocessor file, using the coded character set specified in the locale option.

**Using NOLOCALE compiler option**

In this case, the compiler does the following:

- Does not convert text in the input or output file, and uses the default coded character set IBM-1047 to interpret syntactic characters.
- If a #pragma filetag directive is specified, the compiler suppresses the #pragma filetag directive in the preprocessor file. The compiler issues warnings if the #pragma filetag directive specifies a coded character set other than IBM-1047, and uses IBM-1047 anyway.

**Object modules and output listings:** The compiler respects the locale specified by the LOCALE compiler option when it generates the listing.

If the locale option is specified, the object module is generated in the coded character set of your current locale. Otherwise, the object module is generated in the coded character set IBM-1047.
Code will run correctly if the runtime locale is the same as the locale of the object module.

If the object was generated with a different locale from the one you run under, you must ensure that your code can run under different locales. Refer to Chapter 61, “Customizing a locale,” on page 1005 for more information.

For information about exporting code to other sites, see “Exporting source code to other sites” on page 1062.

You can use the LOCALE compiler option to ensure that listings are sensitive to a specified locale.

Figure 266 on page 1060 shows the result from compiling source file hello273.c with:

```
xlc -F:c89 -o hello273 -qso -qlocale="De_DE.IBM-273" -qxplink -qgoff hello273.c
```

In Figure 266 on page 1060 notice the locale-specific information:

1. The date at the top right. The format of the date in the listing is that specified by the locale.
2. The name of the locale and the code set.
3. Code points for the }, /, and \ characters.
Example of output when locale option is used (Part 1 of 2)

Figure 266. Example of output when locale option is used
Example of output when locale option is used (Part 2 of 2)

The **pragma convert directive**

You can control the conversion of string literals in your code by using the `#pragma convert` directive. It allows you to change the assumed code page for character string literals by supplying a codepage value. For more information, see `convert` in *z/OS XL C/C++ Language Reference*.

For example, if you use an ASCII client machine to write code with string literals and upload it to an EBCDIC server, then your string literals will be converted to EBCDIC. However, if you add the `pragma convert("ISO8859-1")` directive to your source code, then your string literals will be converted to an ASCII code page.

For example, consider the program in Figure 267 on page 1062. When this program is compiled, the string "Hello World" will be converted to an ASCII string, but the string "Hi There!" will not be converted.
There are two reasons why you would want to write source in coded character set IBM-1047.

First, even though z/OS XL C/C++ provides support for multiple coded character sets, other tools may not do so. Tools such as CICS and DB2 may not support source code in any coded character set other than the default coded character set, IBM-1047. If you are using these tools, and you write your code in a code page other than IBM-1047, you will need to use the z/OS XL C/C++ iconv utility to convert your code to coded character set IBM-1047 before you can use the tool.

Second, older versions of the C/370 product do not support source in coded character sets other than IBM-1047. This makes it difficult to share code with a site using an older compiler.

Exporting source code to other sites

This section deals with the exporting of code from one Latin-1 coded character set to another; that is, writing code that can be run in a locale that uses a different coded character set than the one used to write the source.

To export code, use the iconv() utility to convert each source file, header file, and data file to the target coded character set. You can then send all files to the target location for compilation.

Note: You must ensure that your code runs in the same locale that it was compiled under before running it with any other locales.

1. Use the #pragma filetag directive to tag each source file, header file, and data file.
2. Use message files for all external strings, such as prompts, help screens, and error messages. To write truly portable code, convert these strings to the runtime coded character set in your application code.
3. Use the setlocale() function so that the library functions are sensitive to the runtime coded character set.

Ensure that locale-sensitive information, such as decimal points, are displayed appropriately. Use either nl_langinfo() or localeconv() to obtain this information.

/* header.h */
#pragma convert("ISO8859-1")
char *text="Hello World";
#pragma convert(pop)

/* test.c */
#pragma comment (user, "A user comment")
#include "header.h"

main () {
    char *text2 ="Hi There!";
}

Figure 267. Using the pragma convert directive
The `setlocale()` function does not change the CEE callable services under the z/OS Language Environment in such areas as date, time, currency, and time zones. Internationalization is specific to z/OS XL C/C++ applications. Also, the z/OS Language Environment CEE callable services do not change the z/OS XL C/C++ locales. For a list of these callable services, see the z/OS Language Environment Programming Guide.

4. Compile with the locale specifying coded character set IBM-1047.

If you specify `locale("locale-name")`, your code will run correctly with libraries running in the same coded character set. However, if you compile with a different locale than you run under, you have to ensure that your code has no internal data, and also that all libraries you use are runtime locale sensitive.

For example, consider the following code fragment. If you compile with `locale("De_DE.IBM-273")`, the square brackets are converted to the hex values X'63' and X'FC'. If the default locale you then run under is not "De_DE.IBM-273", but instead "En_US.IBM-1047", and you have not used `setlocale()`, the square brackets will be interpreted as Ä and Ü, and the call to `scanf()` will not do what you intended.

```c
int main() {
    setlocale(LC_ALL, "");
    ...
    rc = scanf("%[1234567890abcdefABCDEF]", hexNum);
    ...
}
```

If you only need to run your code locally or export it to a site that has your locale environment, you can solve this problem by using the following coding. This ensures that your code runs with the same locale it was compiled under. Library functions such as `printf()`, `scanf()`, `strfmon()`, and `regcomp()` are sensitive to the current coded character set. The `__LOCALE__` macro is described in “Using predefined macros” on page 1054.

```c
int main() {
    setlocale(LC_ALL, __LOCALE__);
    ...
    rc = scanf("%[1234567890abcdefABCDEF]", hexNum);
    ...
}
```

If you are generating code to export to a site that may not have your locale environment, you should write your code in IBM-1047.

**Converting existing work**

This section describes some conversion issues and presents some conversion scenarios. It is assumed that existing source code and libraries cannot be quickly converted from mixed coded character sets into a common coded character set; thus a staged approach is recommended.
• Code your new source in one coded character set, preferably IBM-1047. Tag all new source files to make them more portable by putting the `#pragma filetag` directive at the top of each one.

• If you need to interact with existing code, compile your new code using the locale in which the existing code was written.

• If you want to write code in a coded character set that does not have a one-to-one mapping to coded character set IBM-1047 (that is, a coded character set that is not Latin-1), create your own conversion table and compile it with the `genxlt` utility. Use your own conversion table with the `iconv` utility to convert your source code to coded character set IBM-1047.

### Considerations with other products and tools

**Note:** Any software tool that scans source code or compiler listings is affected by the introduction of the locale functionality. Tools that read or generate source code now need to recognize the `#pragma filetag` directive. Tools that read listings need to recognize the coded character set in the title header.

Since the following tools scan source code, they may be affected:

• The Debug Tool does not support code written in any coded character set other than IBM-1047.

• Translators such as CICS and DB2 read source files and generate new source files. If they do not, then follow these steps:
  1. Convert the source file to coded character set IBM-1047 using the `iconv` utility.
  2. Remove the `#pragma filetag` directive from the source file, or change it to `??=pragma filetag("IBM-1047")`. Run the source that is in the IBM-1047 coded character set through the appropriate translator, if needed.
Chapter 66. Bidirectional language support

This chapter describes the characteristics of bidirectional languages, and provides an overview of the layout functions for bidirectional languages. For more information on the layout functions see z/OS XL C/C++ Runtime Library Reference, and X/Open Portable Layout Services: Context-dependent and Directional Text.

Bidirectional languages

Bidirectional languages are languages such as Arabic and Hebrew, that are written and read mainly from right to left, but some portions of the text, such as numbers and embedded Latin languages (e.g. English) are written and read left to right. Additional characteristics of bidirectional languages include:

- visual order versus logical order
- symmetric swapping
- number formats
- cursive (shaping) versus non-cursive

In bidirectional text, it is important to note the difference between the logical order in which the text is processed or read, and the visual order in which the text is displayed. Bidirectional text is usually stored in logical order. For example, assume that the following text is Arabic, then the logical storage would contain:

maple street 25 entrance b

and the visual display would be (if read from right to left):

b ecmartne 25 teerts elpam

Some characters, such as the greater-than sign, have an implied directional meaning and have a complementary symmetric character with an opposite directional meaning (the less-than sign.) When used within a segment that is presented right-to-left but is inverted (left-to-right) when stored for processing, such a character might have to be replaced by its symmetric sibling to ensure that the correct meaning of the text is preserved. The replacement of such a character by its complement during the transformation of BiDi text is called "symmetrical swapping". Other graphic characters that need symmetrical swapping include the parentheses, square brackets, braces, and so on. Although symmetrical swapping is a characteristic of BiDi languages, it is not always mandatory for the software functions that transform different BiDi language text layouts. Sometimes this function is performed automatically by the workstation hardware or micro code.

Arabic numerals (Latin digits) are those numerals used with Latin text, while Hindi numerals are used within Arabic text, in some of the Arabian countries, like Egypt. However, the Implicit algorithm states the number storage should use Arabic numerals (Latin digit), and be displayed according to the user's settings.

Note that even though the text in the example is displayed right to left, the number "25" is still written left to right. That is because Arabic/Hebrew numbers are written and read left to right.

Arabic is a cursive language. Arabic characters are connected together, and each character has different shapes depending on its location within the word: initial,
middle, final or isolated. Cursive languages are suited to handwriting rather than printing. Arabic is always cursive, whether in books, newspapers, signs or workstation displays. English can be handwritten in a cursive style, and it is often used that way in personal communications, but English is seldom published or displayed in a cursive style. Thus, English is not considered a cursive language.

To simplify processing, characters are usually stored in an unshaped form. (The unshaped form is also referred to as the abstract or basic form.) Shaping takes into account the character being shaped and the characters in its vicinity, and replaces the unshaped, abstract form with the proper shape. For example, in Arabic, the unshaped character would be replaced with the initial, middle, final or isolated shaped character, depending on the context.

Note that Hebrew letters do not use shaping, and numbers used with Hebrew text are always displayed with the same digits as used for English.

Legacy operating systems like MVS used to store Arabic and Hebrew data in their visual format. Sometimes for specific needs, data might be stored in a specific shape, for example initial shape. Currently, most applications store text in its unshaped form in logical order. Reordering and shaping are done at display time. Storing text in its unshaped form in logical order makes it easier to process the data (sorting, comparison).

**Overview of the layout functions**

The layout functions are used to handle bidirectional languages correctly, to transform text from a format readable for the user to a format suitable for processing, and vice-versa. The layout functions include the following:

- **m_create_layout()**
  - called at the beginning of the application to create the layout object that will be used by the other layout functions.

- **m_setvalues_layout()**
  - sets the values that will be used inside the transform. **m_setvalues_layout()** must be called before calling **m_transform_layout** or **m_wtransform_layout**.
  - This function is optional. Use this function if you need to change the values for the bidirectional attributes. You can eliminate it from the application, and use a modifier instead.

- **m_getvalues_layout()**
  - queries the current layout values within a layout object.

- **m_transform_layout()**
  - does the actual processing to convert the text format between different bidirectional layouts, according to the settings of the **LayoutObject**. Nothing will change if this function (or its wide character equivalent) is not called inside the application.

- **m_wtransform_layout()**
  - works the same as **m_transform_layout()**, except that it handles Unicode wide characters (wchar_t).

- **m_destroy_layout()**
  - called at the end of the application to destroy the layout object, and free up the allocated memory used by the layout object.
Those functions can be used to convert text from logical (implicit) unshaped forms to visual (display) shaped forms and vice versa. The layout functions also handle conversion of numerals.

Table 360 lists supported layout attributes and their corresponding values. These are the attributes most commonly used to provide Bidi support. Each attribute has input and output values that can be specified for the layout transformation process. The default value for each attribute is indicated in the table.

A full list of attributes and values is available in X/Open Portable Layout Services: Context-dependent and Directional Text. Some attributes listed in Table 360 are specific to the z/OS implementation and are noted with an asterisk (*) symbol.

You can set Bidi Layout Values in two ways:

- The m_setvalues_layout() function requires the Layout Attribute Names and Values to be specified by using keywords presented in columns 1 and 2.
- The m_create_layout() function allows a string to be passed to set the values. This string is preceded with the "@ls" characters and requires the names and values to be used as displayed in column 3. Multiple attribute and value pairs can be separated by commas in the following form:

  @ls <attribute_name1>=<input1>:<output1>,
  <attribute_name2>=<input2>:<output2>...

  Example:
  @ls orientation=ltr:ltr,typeoftext=implicit:visual,
  numerals=nominal:national, swapping=no:yes,
  bidiroundtrip=true

### Table 360. Layout attribute and values

<table>
<thead>
<tr>
<th>Attribute Name</th>
<th>Attribute values</th>
<th>Modifier layout string names and values (@ls)</th>
<th>Description</th>
</tr>
</thead>
</table>
| Orientation    | ORIENTATION_CONTEXTUAL
                | ORIENTATION_LTR (Default)
                | ORIENTATION_RTL | Name: orientation=                           | The direction of the text. |
|                | Values:          | contextual
                | ltr
                | rtl              |                                              |
| Context        | CONTEXT_LTR (Default)
                | CONTEXT_RTL     | Name: context=                                | Contextual orientation when the orientation attribute is set to ORIENTATION_CONTEXTUAL |
|                | Values:          | ltr
                | rtl              |                                              |
| TypeofText     | TEXT_EXPLICIT
                | TEXT_IMPLICIT (Input default)
                | TEXT_VISUAL (Output default) | Name: typeoftext=                           | Type of the text. |
|                | Values:          | explicit
                | implicit
                | visual           |                                              |
| Swapping       | SWAPPING_NO (Input default)
                | SWAPPING_YES (Output default) | Name: swapping=                              | Specifies if symmetric swapping is enabled. |
|                | Values:          | no
                | yes              |                                              |
| Numerals       | NUMERALS_CONTEXTUAL (Output default in Arabic locale)
                | NUMERALS_NATIONAL
                | NUMERALS NOMINAL (Input default,
                | Output default in Hebrew locale) | Name: numerals=                            | How numerals are shaped. (Only valid for Arabic.) |
|                | Values:          | contextual
                | national
                | nominal           |                                              |
### Table 360. Layout attribute and values (continued)

<table>
<thead>
<tr>
<th>Attribute Name</th>
<th>Attribute values</th>
<th>Modifier layout string names and values (@ls)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TextShaping</td>
<td></td>
<td>Name: shaping=</td>
<td>Specifies if text is to be shaped. (Only valid for Arabic.)</td>
</tr>
<tr>
<td></td>
<td>TEXT_NOMINAL (Input default, Output default in Hebrew locale) TEXT_SHAPE (Output default in Arabic locale)</td>
<td>Values: nominal shaped</td>
<td></td>
</tr>
<tr>
<td>ShapeCharset</td>
<td></td>
<td>Name: shapcharset=</td>
<td>Code set of the output buffer to result from layout transformation.</td>
</tr>
<tr>
<td>InputCharset*</td>
<td></td>
<td>N/A</td>
<td>Code set of the input buffer to use in layout transformation. The default value is the code set of the loaded locale.</td>
</tr>
<tr>
<td></td>
<td>IBM-1046 IBM-1089 IBM-1256 IBM-420 IBM-424 IBM-425 IBM-53668 IBM-864 ISO8859-6 UCS-2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>BidiRoundTrip*</td>
<td></td>
<td>Name: bidiroundtrip=</td>
<td>Specifies if the Bidi roundtrip algorithm is enabled. To take proper effect, BidiRoundTrip must be enabled in both legs of the layout transformations that complete the roundtrip.</td>
</tr>
<tr>
<td></td>
<td>BIDIROUNDTRIP_OFF (Default) BIDIROUNDTRIP_ON</td>
<td>Values false true</td>
<td></td>
</tr>
</tbody>
</table>

### m_create_layout()

This function creates a LayoutObject associated with the locale identified by attrobj. The LayoutObject is an opaque object containing all the data and methods necessary to perform the layout operations on context-dependent or directional characters of the locale identified by the attrobj. The memory for the LayoutObject is allocated by m_create_layout(). The LayoutObject created has default layout values. (If the modifier argument is not NULL, the layout values specified by the modifier overwrite the default layout values associated with the locale).

```c
#include <sys/layout.h>
LayoutObject m_create_layout(const AttrObject attrobj, const char* modifier);
```

**attrobj argument**

Is or may be an amalgam of many opaque objects. A locale object is just one example of the type of object that can be attached to an attribute object. The attrobj argument specifies a name that is usually associated with a locale category.
**modifier argument**

Can be used to announce a set of layout values when the LayoutObject is created.

**m_setvalues_layout( )**

This function is used to change the layout values of a LayoutObject.

```c
#include <sys/layout.h>
int m_setvalues_layout(LayoutObject layout_object, const LayoutValues values,
int *index_returned);
```

**layout_object argument**

Specifies a LayoutObject returned by the m_create_layout() function.

**values argument**

Specifies the list of layout values that are to be changed. The values are written into the LayoutObject and may affect the behavior of subsequent layout functions.

**m_getvalues_layout( )**

This function is used to query the current settings of the layout values within a Layout Object.

```c
#include <sys/layout.h>
int m_getvalues_layout(const LayoutObject layout_object, LayoutValues values,
int *index_returned);
```

**layout_object argument**

Specifies a Layout Object returned by the m_create_layout( ) function.

**values argument**

Specifies the list of layout values that are to be queried. Each value element of a LayoutValueRec must point to a location where the layout value is stored. That is, if the layout value is of type T, the argument must be of type *T. The values are queried from the Layout Object and represent its current setting. It is the user’s responsibility to manage the memory allocation for the layout values queried. If the layout value name has QueryValueSize ORed to it, instead of the setting of the layout value, only its size is returned. This option can be used by the caller to determine the amount of memory needed to be allocated for the layout values queried.

**m_transform_layout ( )**

This function performs layout transformations (reordering and shaping), or it may provide additional information needed for layout transformation (such as the expected size of the transformed layout, the nesting level of different segments in the text and cross references between the locations of the corresponding elements before and after the layout transformation). Both the input text and output text are character strings. The m_transform_layout( ) function transforms the input text in InpBuf according to the current layout values in layout_object. Any layout value whose value type is LayoutTextDescriptor describes the attributes of the InpBuf and OutBuf arguments. If the attributes are the same for both InpBuf and OutBuf, a null transformation is performed with respect to that specific layout value. The InpBuf argument specifies the source text to be processed. The InpSize argument is the number of bytes within InpBuf to be processed by the transformation. Its value will not change after return from the transformation.
#include <sys/layout.h>

int m_transform_layout(LayoutObject layout_object,
    const char *InpBuf,
    const size_t InpSize,
    void *OutBuf,
    size_t *Outsize,
    size_t *InpToOut,
    size_t *OutToInp,
    unsigned char *Property,
    size_t *InpBufIndex);

**LayoutObject argument**
Specifies the Layout Object returned by m_create_layout().

**InpBuf argument**
Corresponds to the input string that the layout functions will process.

**InpSize argument**
Gives the input size of the input string specified by the InpBuf argument.

**Note:** If you need to pass –1 as a value for InpSize, you must cast it using (size_t)-1.

**OutBuf argument**
Any transformed data is stored here. This buffer will contain the data after converting it to the specified layout values and output code page.

**Outsize argument**
Gives the number of bytes in the Output Buffer.

**InpToOut mapping argument**
A cross-reference from each InpBuf code element to the transformed data. The cross-reference relates to the data in InpBuf starting with the first element that InpBufIndex points to (and not necessarily starting from the beginning of the InpBuf).

**OutToInp mapping argument**
A cross-reference to each InpBuf code element from the transformed data. The cross-reference relates to the data in InpBuf starting with the first element that InpBufIndex points to (and not necessarily starting from the beginning of the InpBuf).

**Property argument**
A weighted value that represents peculiar input string transformation properties with different connotations. If this argument is not a NULL pointer, it represents an array of values with the same number of elements as the source sub string text before the transformation. Each byte will contain relevant "property" information of the corresponding element in InpBuf starting from the element pointed by InpBufIndex.

**InpBufIndex argument**
InpBufIndex is an offset value to the location of the transformed text. When m_transform_layout() is called, InpBufIndex contains the offset to the element in InpBuf that will be transformed first. (Note that this is not necessarily the first element in InpBuf). At the return from the transformation, InpBufIndex contains the offset to the first element in the InpBuf that has not been transformed. If the entire sub string has been transformed successfully, InpBufIndex will be incremented by the amount defined by InpSize.
m_wtransform_layout( )
The m_wtransform_layout is the same as m_transform_layout, except that it takes Unicode (wchar_t *) as an input buffer.

```c
#include <sys/layout.h>
int m_wtransform_layout(LayoutObject layout_object,
    const wchar_t *InpBuf,
    const size_t InpSize, void *OutBuf,
    size_t *Outsize,
    size_t *InpToOut, size_t *OutToInp,
    unsigned char *Property,
    size_t *InpBufIndex );
```

m_destroy_layout( )
This function destroys the layout object and frees up the allocated memory used by the layout object.

```c
#include <sys/layout.h>
int m_destroy_layout(const LayoutObject layout_object);
```

Using the layout functions
This section contains examples to illustrate how to call the BIDI layout engine. Note that to use the Bidi roundtrip algorithm, the option must be enabled in both legs of a layout transformation.

The example in Figure 268 sets the option using a layout string modifier.

```
Layout Transformation #1:
------------------------
"@ls orientation=ltr:ltr, typeoftext=visual:implicit,
   bidiroundtrip=true"
```

```
Layout Transformation #2:
------------------------
"@ls orientation=ltr:ltr, typeoftext=implicit:visual,
   bidiroundtrip=true"
```

Figure 268. Example of using a layout string modifier

Figure 269 demonstrates how to use the m_setvalues_layout() function to set the option.

```
LayoutValues layout = (LayoutValues)
calloc(2,sizeof(LayoutValueRec));
layout[0].name = BidiRoundTrip;
layout[0].value = (void *) BIDIROUNDTRIP_ON;
layout[1].name = 0;
```

Figure 269. Example of using the m_setvalues_layout() function

To use the layout functions, perform the following steps.
1. Include the sys/layout.h header file to define the values and function prototypes.
2. Declare the program variables.

```c
#include <sys/layout.h>

LayoutObject plh;
int error = 0, index;
sizet insize = 9, outsize;
LayoutValues layout;
LayoutTextDescriptor set_desc;

char *inbuffer;
char *outbuffer;
char *inShape;
char *outShape;
char *myModifier = 
   "@lstypeoftext=implicit:visual,shaping=nominal:shaped,orientation=ltr:rtl";
```

In the first line, declare a `LayoutObject` called "plh". This is the layout object that `m_create_layout()` creates later when invoked. `index` is the index of the returned error. `insize` is the size of the input buffer, and `outsize` is the size of the output buffer. The four integer variables in the second and third lines will be used later in the call of `m_setvalues_layout()` and `m_transform_layout()`. In the fourth line, declare a `LayoutValues` variable called "layout" and in the fifth line declare a `LayoutTextDescriptor` called "set_desc". These two variables are very important. They will be used with `m_setvalues_layout()` in the form of input/output pairs to specify new input and output values for each one of the specified attributes. The next two lines add four strings (char *), that will be used as the input buffer, output buffer, input code page and, finally, the output code page. The last line adds a string that specifies the modifier to be used as specified earlier in the `m_create_layout()` function to create the layout object.

3. Allocate memory to the declared strings, layout values, layout text descriptor, and write the contents of the input buffer.

```c
inbuffer = (char *)malloc(insize*sizeof(char));
outbuffer= (char *)malloc(outsize*sizeof(char));
layout = (LayoutValues)malloc(6*sizeof(LayoutValueRec));
set_desc = (LayoutTextDescriptor)malloc(3*sizeof(LayoutTextDescriptorRec));
inShape = (char*) malloc(20 * sizeof(char));
outShape = (char*) malloc(20 * sizeof(char));
inbuffer[0] = 0xB0;
inbuffer[1] = 0xB1;
inbuffer[2] = 0xB2;
inbuffer[3] = 0xBF;
inbuffer[4] = 0x40;
inbuffer[5] = 0x9A;
inbuffer[6] = 0x75;
inbuffer[7] = 0x58;
inbuffer[8] = 0xDC;
```

The values of the input buffer are added one by one as an array of characters, but several alternatives could be used. For example, you can read the input buffer as a string from a file, or get it from another application.

4. Call the `m_create_layout()` function to create a layout object "plh".
In the preceding example, the layout object "plh" is created with the locale Ar_AA with the modifier myModifier.

5. At this point of the program, there are two options: call m_setvalues_layout() or call the m_transform_layout() (or m_wtransform_layout()) directly.
   Specify the input/output layout values. The first two lines below specify the two strings used as the input and output code pages. These two strings will be used by the other functions to specify the input code page for the input buffer and the output code page for the output buffer.

   strcpy(outShape,"ibm-420");
   strcpy(inShape,"ibm-425");
   set_desc[0].inp = ORIENTATION_LTR;
   set_desc[0].out = ORIENTATION_LTR;
   set_desc[1].inp = TEXT_IMPLICIT;
   set_desc[1].out = TEXT_VISUAL;
   set_desc[2].inp = TEXT_NOMINAL;
   set_desc[2].out = TEXT_SHAPED;

Add the input/output layout text descriptor pairs. These pairs are in the form of input descriptor and output descriptor; for example, the first statement specifies that the input orientation will be "orientation-left-to-right" and the second statement specifies that the output orientation will be also "orientation-left-to-right". All the above pairs follow the same rule to define the input/output pairs.

   layout[0].name = ShapeCharset;
   layout[0].value = (char *)outShape;
   layout[1].name = InputCharset;
   layout[1].value = (char *)inShape;
   layout[2].name = Orientation;
   layout[2].value = (LayoutTextDescriptor)&set_desc[0];
   layout[3].name = TypeOfText;
   layout[3].value = (LayoutTextDescriptor)&set_desc[1];
   layout[4].name = TextShaping;
   layout[4].value = (LayoutTextDescriptor)&set_desc[2];
   layout[5].name = 0;

In the preceding lines, "set_desc" pairs create the new layout values attributes. Each one of these statements will be in the form of attribute_name/attribute_value pairs, for example in the fifth and sixth statements "Orientation" is the attribute name and set_desc[0] (as defined above) is the attribute value. The first two statements are used to declare the output code page and the following two lines are used to specify the input code page.
   Call the m_setvalues_layout() function.
Invoke `m_setvalues_layout()` using the layout object "plh", the layout values "layout" and an integer "index". If `m_setvalues_layout()` could not set any one of the layout values attributes, it will return -1 in the integer variable called "error", and also return the index of the layout value that caused the problem.

6. Call the `m_transform_layout()` function. The `m_transform_layout()` and `m_wtransform_layout()` functions are the same, except that `m_wtransform_layout()` is used for wide character (wchar_t). Both functions will do the actual reordering and shaping of the input buffer using the layout object (plh) created in step 4.

```c
if((error = m_setvalues_layout(plh,layout,&index)))
    printf("An error %d occurred in setting the value number %d\n",error,index);

m_transform_layout(plh,inbuffer,insize,outbuffer,&outsize,NULL,
    NULL,NULL,NULL);
```

- **plh** The Layout Object returned by `m_create_layout()`.
- **inbuffer** Corresponds to the input string to the function that the layout functions will process.
- **insize** Gives the input size of the input string specified by the Input Buffer argument.
- **outbuffer** Any transformed data is stored here. This buffer will contain the data after converting it to the specified output code page.
- **outsize** Gives the number of bytes in the Output Buffer.

The last four parameters are given here as NULL and they represent Input To Output Mapping, Output To Input Mapping, Property and Input Buffer Index as described above in the Overview of the Layout Functions. Each of these output arguments may be NULL to specify that no output is desired for the specific argument.

7. Call the `m_destroy_layout()` function. This function must be called at the end of the program to destroy the layout object or to free up the allocated memory used by the layout object.

```c
m_destroy_layout(plh);
```

Finally, **Figure 270 on page 1075** is sample program (CCNGBID1) that shows how the bidirectional layout API are used.
/* This is a simple program that explains how the layout API's are used */
/* This program will convert a simple implicit unshaped Arabic string */
/* to a visual shaped Arabic string. */
#include <sys/layout.h>
#include <stdio.h>

void main(int argc,char** argv)
{
    LayoutObject plh;
    int error = 0;
    int index;
    LayoutValues layout;
    LayoutTextDescriptor set_desc;
    size_t insize = 9,outsize = 9;

    char *inbuffer=NULL;
    char *outbuffer=NULL;
    char *inShape=NULL;
    char *outShape=NULL;
    char

    *myModifier="@lstypeoftext=implicit:visual,shaping=nominal:shaped,orientation=ltr:rtl";

    inbuffer =(char *)malloc((insize+1)*sizeof(char) ) ;
    outbuffer=(char *)malloc((outsize+1)*sizeof(char)) ;
    layout = (LayoutValues)malloc(6*sizeof(LayoutValueRec));
    set_desc = (LayoutTextDescriptor)malloc(3*sizeof(LayoutTextDescriptorRec));
    inShape = (char*) malloc(8 * sizeof(char));
    outShape = (char*) malloc(8 * sizeof(char));

    inbuffer[0] = 0xB0;  /* These are the HEX code for Arabic characters in the IBM-425 codepage */
    inbuffer[1] = 0xB1;
    inbuffer[2] = 0xB2;
    inbuffer[3] = 0xBF;
    inbuffer[4] = 0x40;
    inbuffer[5] = 0x9A;
    inbuffer[6] = 0x75;
    inbuffer[7] = 0x58;
    inbuffer[8] = 0xDC;

Example of bidirectional layout API's (Part 1 of 2)

Figure 270. Example of bidirectional layout API's
plh = m_create_layout("Ar_AA",myModifier);

strcpy(outShape,"ibm-420");
strcpy(inShape,"ibm-425");

set_desc[0].inp = ORIENTATION_LTR;
set_desc[0].out = ORIENTATION_LTR;
set_desc[1].inp = TEXT_IMPLICIT;
set_desc[1].out = TEXT_VISUAL;
set_desc[2].inp = TEXT_NOMINAL;
set_desc[2].out = TEXT_SHAPED;
layout[0].name = ShapeCharset;
layout[0].value = (char *)outShape;
layout[1].name = InputCharset;
layout[1].value = (char *)inShape;
layout[2].name = Orientation;
layout[2].value = (LayoutTextDescriptor)&set_desc[0];
layout[3].name = TypeOfText;
layout[3].value = (LayoutTextDescriptor)&set_desc[1];
layout[4].name = TextShaping;
layout[4].value = (LayoutTextDescriptor)&set_desc[2];
layout[5].name = 0;

if(error=m_setvalues_layout(plh,layout,&index))
  printf("An error %d occurred in setting the value number %d\n",error,index);

m_transform_layout(plh,inbuffer,insize,outbuffer,&outsize,NULL,NULL,NULL,NULL);

m_destroy_layout(plh);
if(inbuffer)
  free(inbuffer);
if(outbuffer)
  free(outbuffer);
if(set_desc)
  free(set_desc);
if(layout)
  free(layout);
if(inShape)
  free(inShape);
if(outShape)
  free(outShape);
}

Example of bidirectional layout API's (Part 2 of 2)
Part 9. Appendixes
Appendix A. POSIX character set

POSIX 1003.2, section 2.4, specifies the characters that are in the portable character set. The following table lists the characters in the portable character set with their symbolic name, the GCGID, and the graphic symbol for the character. Some of the characters (the hyphen, for example) also have alternate symbolic names. The input files for the localedef utility, the charmap file and the locale definition file, are coded using the characters in the portable character set.

<table>
<thead>
<tr>
<th>Symbolic Name</th>
<th>Alternate Name</th>
<th>Character</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;NUL&gt;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>&lt;alert&gt;</td>
<td>&lt;SE08&gt;</td>
<td>!</td>
</tr>
<tr>
<td>&lt;backspace&gt;</td>
<td>&lt;SE09&gt;</td>
<td></td>
</tr>
<tr>
<td>&lt;tab&gt;</td>
<td>&lt;SE10&gt;</td>
<td></td>
</tr>
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<td>&lt;SE11&gt;</td>
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</tr>
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<td>&lt;SP05&gt;</td>
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</tr>
<tr>
<td>&lt;right-parenthesis&gt;</td>
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</tr>
<tr>
<td>&lt;left-brace&gt;</td>
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<td>{</td>
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</tr>
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</tr>
<tr>
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</tr>
<tr>
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<td>&lt;SM14&gt;</td>
<td>}</td>
</tr>
<tr>
<td>&lt;tilde&gt;</td>
<td>&lt;SD19&gt;</td>
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</table>

With z/OS XL C/C++, the localedef utility uses code page IBM-1047 as the definition of the code points for the characters in the Portable Character Set. Therefore, the default values for the escape-char and comment-char are the code points from the IBM-1047 code page.
There are some coded character sets, such as the Japanese Katakana coded character set 290, that have code points for the lowercase characters different from the code points for the lowercase characters in the set IBM-1047. A charmap file or locale definition file cannot be coded using these coded character sets.
Appendix B. Mapping variant characters for z/OS XL C/C++

If you are running a programmable workstation using host emulation software, you must:

1. Remap the hexadecimal values for the variant characters. Remapping will send the values that are correct for the installed z/OS XL C/C++ compiler to the host system. For instructions, see “Specifying the appropriate code page for the compiler.”

2. Ensure that your current keyboard input generates the hexadecimal values that are expected by the z/OS XL C/C++ compiler and its library. For instructions, see “Testing the display of variant characters.”

3. Enable your ISPF editor to support local use of variant characters. For instructions, see “Inserting and viewing square brackets during an ISPF edit session” on page 1086.

Note: See `LOCAL|NOLOCALE` and other appropriate sections in z/OS XL C/C++ User’s Guide for information on the option and the list of IBM-supported locales available for use at compile time or run time. The default C locale is supported by code page IBM-1047; therefore the default encoding of variant characters is as shown in Figure 274 on page 1089. Consult your system programmer for the coded character set that your installation uses.

Specifying the appropriate code page for the compiler

To specify the code page based on the compiler version, use the `#pragma filetag` directive conditionally in the source and header file. The syntax is shown below, where `codepage` is the codepage in which the source code is written.

```c
#ifndef __COMPILER_VER__
#define __COMPILER_VER__
#pragma filetag ("codepage")
#endif
```

Note: If you are running standard 3270 emulation in the U.S., your workstation software most likely uses code page 37. You can then use this alternative by specifying IBM-037 as `codepage`.

Testing the display of variant characters

If you use a programmable workstation or a 3270 terminal, you can follow Figure 271 on page 1084 to ensure that the host system uses the correct hexadecimal values to display the variant characters. See `iconv` in z/OS XL C/C++ User’s Guide for more information on this utility. See “Inserting and viewing square brackets during an ISPF edit session” on page 1086 for instructions to insert square brackets into a C/C++ source file.
Displaying hexadecimal values

To ensure that your current keys generate the hexadecimal values that are expected by the z/OS XL C/C++ compiler and its library:

1. Create the input file MYFILE.DAT, typed in the following order on a single line, without spaces between them:
   - backslash \n
2. Run the program Figure 272 on page 1085 to display the following information:
   - Selected hexadecimal values for the variant characters that your current setup uses:
     - The values that the compiler and library expect for mapping the keyboard.

3. Perform the following steps until the hexadecimal values for the variant characters that your current setup matches the values that the compiler and library expect for mapping the keyboard.
   a. Use the values that the compiler and library expect for mapping the keyboard to edit the input file MYFILE.DAT.
   b. Run the program CCNGMV1 again.

Note: These ten variant characters are selected because they are syntactically important to the z/OS XL C/C++ compiler.
Sample program

CCNGMV1 in Figure 272 performs the following actions:

- Reads the ten characters from MYFILE.DAT.
- Queries the current compile time locale for the character values that compiler would expect.
- Generates the codes as shown in the column EXPECTED BY COMPILER.

```c
/* this example will display hexadecimal values for the variant */
/* characters */

#include <stdio.h>
#include <locale.h>
#include <variant.h>
#include <stdlib.h>

void read_user_data(char *, int);
void main() {
    char *user_char, *compiler_char;
    struct variant *compiler_var_char;
    int num_var_char, index;
    char *code_set;
    char *char_names[] = {"backslash", 
                          "right bracket", 
                          "left bracket", 
                          "right brace", 
                          "left brace", 
                          "circumflex", 
                          "tilde", 
                          "exclamation mark", 
                          "number sign", 
                          "vertical line"};

    num_var_char = sizeof(char_names) / sizeof(char *);
    if ((user_char = (char*)calloc(num_var_char, 1)) == NULL)
        {
        printf("Error: Unable to allocate the storage\n");
        exit(99);
        }

    read_user_data(user_char, num_var_char);
    /* managed to read the users' characters from the file */

    code_set = "default IBM-1047";
    compiler_char = "\xe0\xbd\xad\xd0\xc0\x5f\x81\x5a\x7b\x4f";
    /* standard compiler code page */

    printf("Compiler and library code page is : %s\n", code_set);
    printf(" Variate character values:\n");
    printf("  %16s expected by compiler your current\n", "");
    for (index = 0; index < num_var_char; index++)
        printf("  %16s : %X %X\n", 
                char_names[index], compiler_char[index], user_char[index]);
    exit(0);
}
```

CCNGMV1: Displaying hexadecimal values (Part 1 of 2)

Figure 272. CCNGMV1: Displaying hexadecimal values
void read_user_data(char* char_array, int num_var_char)
{
    FILE *stream;
    int num;

    if (stream = fopen("myfile.dat", "rb"))
        if(!(num = fread(char_array, 1, num_var_char, stream)))
            { printf("Error: Unable to read from the file\n");
                exit(99);
            }
        else { ;}
    else { printf("Error: Unable to open the file\n");
                exit(99);
        }
    fclose(stream);
    return;
}

CCNGMV1: Displaying hexadecimal values (Part 2 of 2)

Inserting and viewing square brackets during an ISPF edit session

When your workstation is sending correct hexadecimal values for the square brackets to the host system, you might find that they are still not correctly displayed during by ISPF. If you are using a programmable workstation or a 3270 terminal, you should include the sample ISPF macro CCNGMV2 in a regular CLIST library that is concatenated to the ddname SYSPROC. CCNGMV2 supports ISPF display of the "[" and "]" characters in text, trigraph, or hex form. You can toggle through the three settings.

Note: If you are using 3279-S3G-1 with ISPF, z/OS batch, or TSO, see “Displaying square brackets when using ISPF on 3279 emulation” on page 1087.

After you reset the environment by specifying the appropriate code page for the compiler, follow these steps:
1. Start ISPF and open a C or C++ source file with square brackets.
2. Run CCNGMV2 before editing to convert the compiler recognizable hexadecimal values of the square brackets to trigraphs.
3. Run CCNGMV2 again to convert the trigraphs to displayable characters.
4. Edit your C or C++ source code.
5. Run the CCNGMV2 macro again to convert the displayable characters back to the original hexadecimal values.
6. Save and file the C source file.

ISPF macro CCNGMV2

CCNGMV2 in Figure 272 on page 1085 is sample ISPF macro for displaying square brackets.
If you are using a 3279-S3G-1 with ISPF, z/OS batch, or TSO, you should have the APL keys on your keyboards.

1. Go to ISPF 0.1 and set the terminal type to 3278A.
2. Open the file that has the square brackets in the ISPF editor.
3. Whenever you want to enter square brackets:
   a. Press ALT APLon.

/* this ISPF macro can be used to display square brackets in different formats

PROC 0
ISREDIT MACRO

SET RP = &STR(})

/* Symbolic values for 6 C language symbols.
/* 1. left bracket, EBCDIC hex value
/* 2. right bracket, EBCDIC hex value
/* 3. left bracket, trigraph
/* 4. right bracket, trigraph
/* 5. left bracket, square
/* 6. right bracket, square
SET LBRACKET_HEX = X'AD'
SET RBRACKET_HEX = X'BD'
SET LBRACKET_TRI = &STR(??(
SET RBRACKET_TRI = &STR(??&RP)
SET LBRACKET_SQR = X'BA' /* LBRACKET_SQR = HEX BA */
SET RBRACKET_SQR = X'BB' /* RBRACKET_SQR = HEX BB */

ISREDIT FIND &LBRACKET_HEX ALL NX
ISREDIT (N1) = FIND_COUNTS
ISREDIT FIND &RBRACKET_HEX ALL NX
ISREDIT (N2) = FIND_COUNTS
IF (&N1 ¬= &N2) THEN WRITE ........UNBALANCED HEX BRACKETS
IF (&N1 > 0) THEN DO
   ISREDIT CHANGE &LBRACKET_HEX &LBRACKET_TRI ALL NX
   ISREDIT CHANGE &RBRACKET_HEX &RBRACKET_TRI ALL NX
   EXIT
END

ISREDIT FIND &LBRACKET_TRI ALL NX
ISREDIT (N1) = FIND_COUNTS
ISREDIT FIND &RBRACKET_TRI ALL NX
ISREDIT (N2) = FIND_COUNTS
IF (&N1 ¬= &N2) THEN WRITE ........UNBALANCED TRIGRAPH
IF (&N1 > 0) THEN DO
   ISREDIT CHANGE &LBRACKET_TRI &LBRACKET_SQR ALL NX
   ISREDIT CHANGE &RBRACKET_TRI &RBRACKET_SQR ALL NX
   EXIT
END

ISREDIT FIND &LBRACKET_SQR ALL NX
ISREDIT (N1) = FIND_COUNTS
ISREDIT FIND &RBRACKET_SQR ALL NX
ISREDIT (N2) = FIND_COUNTS
IF (&N1 ¬= &N2) THEN WRITE ........UNBALANCED SQUARE BRACKETS
IF (&N1 > 0) THEN DO
   ISREDIT CHANGE &LBRACKET_SQR &LBRACKET_HEX ALL NX
   ISREDIT CHANGE &RBRACKET_SQR &RBRACKET_HEX ALL NX
   EXIT
END

Figure 273. Sample ISPF macro for displaying square brackets

Displaying square brackets when using ISPF on 3279 emulation

If you are using a 3279-S3G-1 with ISPF, z/OS batch, or TSO, you should have the APL keys on your keyboards.
1. Go to ISPF 0.1 and set the terminal type to 3278A.
2. Open the file that has the square brackets in the ISPF editor.
3. Whenever you want to enter square brackets:
   a. Press ALT APLon.
b. Enter a bracket "[" or "]".
   - "]" is mapped to = X'AD'.
   - "][" is mapped to = X'BD'.

   c. Press ALT APLoff.
Appendix C. z/OS XL C/C++ code point mappings

This information provides figures that show the first and second nybbles of the hexadecimal digits that comprise the code point mappings for code page IBM-1047 and the APL code page 293.

Figure 274 shows the Latin-1/Open Systems code point mappings for code page IBM-1047.

Figure 275 on page 1090 shows the code point mappings for APL code page 293.
Figure 275. Coded character set for APL
Appendix D. Locales supplied with z/OS XL C/C++

The following tables list the compiled locales and locale source files supported by default with the z/OS XL C/C++ product. All of these locale files are provided with the National Language Resources feature of z/OS Language Environment.

Notes:
1. Prior to z/OS V1R6, the default currency for the European Economic Community was set to local currency in the LC_MONETARY category of the base locale. If customers wanted to set the Euro as currency, they needed to use setlocale() to set the @euro locales. Starting with z/OS V1R6, the LC_MONETARY category in the base locale is now set to use the Euro. Customers who set the base locale, now have the Euro as the default currency. If customers want to use the old (local) currency, they need to issue setlocale() to set the @preeuro locales.
2. Starting with OS/390 V1R3, the compiled locales are built using the locale source files stored in the CEE.SCEELOCX partitioned data set. The CEE.SCEELOCX locale source files were created in support of the XPG4 standard. The previous locale source files (pre-XPG4) are in the CEE.SCEELOCL partitioned data set. We include the pre-XPG4 source for customers who want to run in a non-POSIX locale environment.
3. In the z/OS UNIX file system, the locale source files are in /usr/lib/nls/localedef and the binaries are in /usr/lib/nls/locale (we do not ship the pre-XPG4 source or binaries in the z/OS UNIX file system).

Compiled locales

The following table lists each setlocale() parameter and its corresponding language, country/territory, codeset, and actual program name. The S370 C, POSIX C and SAA C locales do not have locale modules associated with them. They are built-in locales that cannot be modified, and are always present. Their names cannot be changed. These locales are based on the coded character set IBM-1047. The new versions of the POSIX C and SAA C locales can be provided, but to refer to them, you must specify the full name of the requested locale, including the CodesetRegistry-CodesetEncoding names. For example, the following refers to the SAA C locale built from the coded character set IBM-037:

"SAA.IBM-037"

Note: Not all locales listed in Table 362 on page 1092 are fully enabled. The compiler cannot compile source that is coded in Ja_JP:IBM-290, Ja_JP:IBM-930, Ja_JP:IBM-1390, or Tr.TR:IBM-1026.

The <prefix> in the Load module name column for EBCDIC locales is shown in the following table:

<table>
<thead>
<tr>
<th>EBCDIC locale</th>
<th>Prefix</th>
</tr>
</thead>
<tbody>
<tr>
<td>31-bit</td>
<td>EDC</td>
</tr>
<tr>
<td>31-bit XPLINK</td>
<td>CEH</td>
</tr>
<tr>
<td>AMODE 64</td>
<td>CEQ</td>
</tr>
</tbody>
</table>
### Table 362. Compiled EBCDIC locales supplied with z/OS XL C/C++

<table>
<thead>
<tr>
<th>Locale name as in setlocale() argument</th>
<th>Language</th>
<th>Country / Territory</th>
<th>Codeset</th>
<th>Load module name</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ar_AA.IBM-425</td>
<td>Arabic</td>
<td>Algeria, Bahrain, Egypt, Iraq, Jordan, Kuwait, Lebanon, Libya, Morocco, Oman, Qatar, Saudi Arabia, Syria, Tunisia, U.A.E., Yemen</td>
<td>IBM-425</td>
<td>&lt;prefix&gt;$AAAR</td>
</tr>
<tr>
<td>Be_BY.IBM-1025</td>
<td>Byelorussian</td>
<td>Belarus</td>
<td>IBM-1025</td>
<td>&lt;prefix&gt;$BBFE</td>
</tr>
<tr>
<td>Be_BY.IBM-1154</td>
<td>Byelorussian</td>
<td>Belarus</td>
<td>IBM-1154</td>
<td>&lt;prefix&gt;$BBHT</td>
</tr>
<tr>
<td>Bg_BG.IBM-1025</td>
<td>Bulgarian</td>
<td>Bulgaria</td>
<td>IBM-1025</td>
<td>&lt;prefix&gt;$BGFE</td>
</tr>
<tr>
<td>Bg_BG.IBM-1153@preeuro</td>
<td>Romanian</td>
<td>Romanian</td>
<td>IBM-1165</td>
<td>&lt;prefix&gt;3ROMBM</td>
</tr>
<tr>
<td>Bg_BG.IBM-1154</td>
<td>Bulgarian</td>
<td>Bulgaria</td>
<td>IBM-1154</td>
<td>&lt;prefix&gt;$BGHT</td>
</tr>
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<td>Bg_BG.IBM-1154@euro</td>
<td>Bulgarian</td>
<td>Bulgaria</td>
<td>IBM-1154</td>
<td>&lt;prefix&gt;@BGHT</td>
</tr>
<tr>
<td>Bg_BG.IBM-1154@preeuro</td>
<td>Bulgarian</td>
<td>Bulgaria</td>
<td>IBM-1154</td>
<td>&lt;prefix&gt;3BGHT</td>
</tr>
<tr>
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<td>Romanian</td>
<td>IBM-1165</td>
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</tr>
<tr>
<td>Ca_ES.IBM-924</td>
<td>Catalan</td>
<td>Spain</td>
<td>IBM-924</td>
<td>&lt;prefix&gt;$CSEZ</td>
</tr>
<tr>
<td>Ca_ES.IBM-924@euro</td>
<td>Catalan</td>
<td>Spain</td>
<td>IBM-924</td>
<td>&lt;prefix&gt;@CSEZ</td>
</tr>
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<td>Cs_CZ.IBM-870</td>
<td>Czech</td>
<td>Czech Republic</td>
<td>IBM-870</td>
<td>&lt;prefix&gt;$CZEQ</td>
</tr>
<tr>
<td>Cs_CZ.IBM-1153</td>
<td>Czech</td>
<td>Czech Republic</td>
<td>IBM-1153</td>
<td>&lt;prefix&gt;$CZMB</td>
</tr>
<tr>
<td>Cs_CZ.IBM-1153@euro</td>
<td>Czech</td>
<td>Czech Republic</td>
<td>IBM-1153</td>
<td>&lt;prefix&gt;@CZMB</td>
</tr>
<tr>
<td>Cs_CZ.IBM-1153@preeuro</td>
<td>Czech</td>
<td>Czech Republic</td>
<td>IBM-1153</td>
<td>&lt;prefix&gt;3CZMB</td>
</tr>
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<td>Czech Republic</td>
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<td>IBM-285</td>
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</tr>
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<td>Great Britain</td>
<td>IBM-924</td>
<td>$&lt;prefix&gt;EKEZ</td>
</tr>
<tr>
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<td>United Kingdom</td>
<td>IBM-1047</td>
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### Table 362. Compiled EBCDIC locales supplied with z/OS XL C/C++ (continued)

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Table 362. Compiled EBCDIC locales supplied with z/OS XL C/C++ (continued)

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<th>Load module name</th>
</tr>
</thead>
<tbody>
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<td>NL_NL.IBM-1047</td>
<td>Dutch</td>
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<td>IBM-1047</td>
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</tr>
<tr>
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<td>IBM-1140</td>
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</tr>
<tr>
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<td>Netherlands</td>
<td>IBM-1140</td>
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</tr>
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<td>IBM-1047</td>
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<td>IBM-1142</td>
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<td>Norway</td>
<td>IBM-1142</td>
<td>&lt;prefix&gt;@NOHE</td>
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<td>Brazil</td>
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<td>IBM-1047</td>
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<td>IBM-1140</td>
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<td>IBM-924</td>
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<td>IBM-1140</td>
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<td>IBM-1140</td>
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<td>IBM-870</td>
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<td>IBM-870</td>
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</tr>
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<td>IBM-870</td>
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<td>IBM-1153</td>
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<td>IBM-1165</td>
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<td>IBM-1165</td>
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<td>IBM-870</td>
<td>&lt;prefix&gt;$SIEQ</td>
</tr>
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<td>IBM-1153</td>
<td>&lt;prefix&gt;$SIMB</td>
</tr>
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<td>Slovenia</td>
<td>IBM-1153</td>
<td>&lt;prefix&gt;@SIMB</td>
</tr>
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<td>IBM-1153</td>
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<td>&lt;prefix&gt;$SIMB</td>
</tr>
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<td>Slovenia</td>
<td>IBM-1153</td>
<td>&lt;prefix&gt;@SIMB</td>
</tr>
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<td>Slovenia</td>
<td>IBM-1153</td>
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<td>IBM-1148</td>
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<td>IBM-1025</td>
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<td>IBM-924</td>
<td>&lt;prefix&gt;$SVEZ</td>
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<td>IBM-924</td>
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<td>Sweden</td>
<td>IBM-924</td>
<td>&lt;prefix&gt;$SVEZ</td>
</tr>
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<td>Sweden</td>
<td>IBM-1047</td>
<td>&lt;prefix&gt;$SVEY</td>
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<td>Sweden</td>
<td>IBM-1143</td>
<td>&lt;prefix&gt;@SVHF</td>
</tr>
<tr>
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<td>Sweden</td>
<td>IBM-1143</td>
<td>&lt;prefix&gt;$SVHF</td>
</tr>
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<td>Thai</td>
<td>Thailand</td>
<td>IBM-838</td>
<td>&lt;prefix&gt;$THEP</td>
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<td>Thai</td>
<td>Thailand</td>
<td>IBM-1160</td>
<td>&lt;prefix&gt;$THHP</td>
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<td>Turkey</td>
<td>IBM-1026</td>
<td>&lt;prefix&gt;$STREW</td>
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<tr>
<td>Tr_TR.IBM-1155</td>
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<td>Turkey</td>
<td>IBM-1155</td>
<td>&lt;prefix&gt;$TRHW</td>
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<td>Ukraine</td>
<td>IBM-1123</td>
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<tr>
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<td>Ukraine</td>
<td>IBM-1158</td>
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</tr>
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<td>IBM-1388</td>
<td>&lt;prefix&gt;$ZCGV</td>
</tr>
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<td>China (Hong Kong S.A.R. of China)</td>
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</table>
### Table 362. Compiled EBCDIC locales supplied with z/OS XL C/C++ (continued)

<table>
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<th>Locale name as in setlocale() argument</th>
<th>Language</th>
<th>Country / Territory</th>
<th>Codeset</th>
<th>Load module name</th>
</tr>
</thead>
<tbody>
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<td>China (Hong Kong S.A.R. of China)</td>
<td>IBM-1388</td>
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</tr>
<tr>
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<td>Simplified Chinese</td>
<td>Singapore</td>
<td>IBM-935</td>
<td>$ZSGY</td>
</tr>
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<td>Zh_SGS.IBM-1388</td>
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<td>Singapore</td>
<td>IBM-1388</td>
<td>$ZSGV</td>
</tr>
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<td>Zh_TW.IBM-937</td>
<td>Traditional Chinese</td>
<td>Taiwan</td>
<td>IBM-937</td>
<td>$ZTGW</td>
</tr>
<tr>
<td>Zh_TW.IBM-1371</td>
<td>Traditional Chinese</td>
<td>Taiwan</td>
<td>IBM-1371</td>
<td>$ZTKA</td>
</tr>
</tbody>
</table>

### Table 363. Compiled ASCII locales supplied with z/OS XL C/C++

<table>
<thead>
<tr>
<th>Locale name as in setlocale() argument</th>
<th>Language</th>
<th>Country / Territory</th>
<th>Codeset</th>
<th>Load module name</th>
</tr>
</thead>
<tbody>
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<td>af_ZA.UTF-8</td>
<td>South African Afrikaans</td>
<td>South Africa</td>
<td>UTF-8</td>
<td>CEJ$AFF8</td>
</tr>
<tr>
<td>az_AZ.UTF-8</td>
<td>Azerbaijani-Latin</td>
<td>Azerbaijan</td>
<td>UTF-8</td>
<td>CEJ$AZF8</td>
</tr>
<tr>
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<td>Belarus</td>
<td>ISO8859-5</td>
<td>CEJ$BBI5</td>
</tr>
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<td>UTF-8</td>
<td>CEJ$BGF8</td>
</tr>
<tr>
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<td>Bengali</td>
<td>India</td>
<td>UTF-8</td>
<td>CEJ$BNF8</td>
</tr>
<tr>
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<td>Catalan</td>
<td>Spain</td>
<td>UTF-8</td>
<td>CEJ$CSF8</td>
</tr>
<tr>
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<td>Catalan</td>
<td>Spain (euro)</td>
<td>UTF-8</td>
<td>CEJ@CSF8</td>
</tr>
<tr>
<td>ca_ES.UTF-8@preeuro</td>
<td>Catalan</td>
<td>Spain (preeuro)</td>
<td>UTF-8</td>
<td>CEJ3CSF8</td>
</tr>
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<td>ISO8859-2</td>
<td>CEJ$CZI2</td>
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<td>Czech Republic</td>
<td>UTF-8</td>
<td>CEJ$CZF8</td>
</tr>
<tr>
<td>cs_CZ.UTF-8@euro</td>
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<td>CEJ@CZF8</td>
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<td>UTF-8</td>
<td>CEJ3CZF8</td>
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<td>Great Britain</td>
<td>UTF-8</td>
<td>CEJ$CYF8</td>
</tr>
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<td>Great Britain (euro)</td>
<td>UTF-8</td>
<td>CEJ@CYF8</td>
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<td>UTF-8</td>
<td>CEJ$DAF8</td>
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<td>Denmark (euro)</td>
<td>UTF-8</td>
<td>CEJ@DAF8</td>
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<td>Austria</td>
<td>UTF-8</td>
<td>CEJ$DTF8</td>
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<td>UTF-8</td>
<td>CEJ@DTF8</td>
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<td>Austria (preeuro)</td>
<td>UTF-8</td>
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<td>ISO8859-1</td>
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<td>UTF-8</td>
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Appendix D. Locales supplied with z/OS XL C/C++ 1101
Table 363. Compiled ASCII locales supplied with z/OS XL C/C++ (continued)

<table>
<thead>
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<th>Locale name as in setlocale() argument</th>
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<th>Country / Territory</th>
<th>Codeset</th>
<th>Load module name</th>
</tr>
</thead>
<tbody>
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<td>CEJ3MTF8</td>
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<td>Country / Territory</td>
<td>Codeset</td>
<td>Load module name</td>
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<tr>
<td>pt_PT.UTF-8@euro</td>
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<td>UTF-8</td>
<td>CEJ@PTF8</td>
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<td>Serbia and Montenegro</td>
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<td>CEJ@SKF8</td>
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<td>Slovakia (preeuro)</td>
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Table 363. Compiled ASCII locales supplied with z/OS XL C/C++ (continued)

<table>
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<tr>
<th>Locale name as in setlocale() argument</th>
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<th>Country / Territory</th>
<th>Codeset</th>
<th>Load module name</th>
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<td>Kenya</td>
<td>UTF-8</td>
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<td>UTF-8</td>
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Table 364. ASCII locale object names and method files in the z/OS UNIX file system

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<td>sbmeth.m</td>
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<td>cy GB.UTF-8</td>
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<td>cy GB.UTF-8@euro</td>
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<td>iso1meth.m</td>
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<td>da DK.UTF-8.xplink</td>
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<td>UNIX file system Locale Object Name</td>
<td>Method File</td>
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<td>el_GR.UTF-8@preeuro</td>
<td>utfmeth.m</td>
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<td>utfmeth.m</td>
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<tr>
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<td>utfmeth.m</td>
</tr>
<tr>
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<td>iso1meth.m</td>
</tr>
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<tr>
<td>en_IE.UTF-8</td>
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<tr>
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<td>es_ES.UTF-8@preeuro</td>
<td>utfmeth.m</td>
</tr>
<tr>
<td>et_EE.UTF-8</td>
<td>utfmeth.m</td>
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<tr>
<td>et_EE.UTF-8@euro</td>
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Table 364. ASCII locale object names and method files in the z/OS UNIX file system (continued)

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<th>Method File</th>
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<tr>
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<td>utfmeth.m</td>
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<tr>
<td>fi_FL.UTF-8@preeuro</td>
<td>utfmeth.m</td>
</tr>
<tr>
<td>fr_BE.ISO8859-1.xplink</td>
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<tr>
<td>fr_BE.UTF-8.xplink</td>
<td>utfmeth.m</td>
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<tr>
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<td>utfmeth.m</td>
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<tr>
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<td>utfmeth.m</td>
</tr>
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<td>fr_CA.UTF-8.xplink</td>
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<tr>
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<td>utfmeth.m</td>
</tr>
<tr>
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<td>utfmeth.m</td>
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<tr>
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<td>utfmeth.m</td>
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<tr>
<td>hr_HR.ISO8859-2.xplink</td>
<td>sbmth.m</td>
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<td>UNIX file system Locale Object Name</td>
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<tr>
<td>lt_LT.UTF-8@preeuro</td>
<td>utfmeth.m</td>
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<tr>
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<td>iso1meth.m</td>
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<tr>
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<tr>
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<td>utfmeth.m</td>
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<td>mt_MT.UTF-8@preeuro</td>
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<td>utfmeth.m</td>
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<tr>
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<td>iso1meth.m</td>
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<td>no_NO.UTF-8.xplink</td>
<td>utfmeth.m</td>
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<tr>
<td>pl_PL.UTF-8@preeuro</td>
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<td>pt_PT.UTF-8@preeuro</td>
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<td>sh_CS.UTF-8</td>
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<tr>
<td>sk_SK.ISO8859-2.xplink</td>
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<td>sk_SK.UTF-8.xplink</td>
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</table>
Table 364. ASCII locale object names and method files in the z/OS UNIX file system (continued)

<table>
<thead>
<tr>
<th>UNIX file system Locale Object Name</th>
<th>Method File</th>
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<tbody>
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<td>sk_SK.UTF-8@euro</td>
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<tr>
<td>sk_SK.UTF-8@preeuro</td>
<td>utfmeth.m</td>
</tr>
<tr>
<td>sl_SI.ISO8859-2.xplink</td>
<td>sbmeth.m</td>
</tr>
<tr>
<td>sl_SI.UTF-8.xplink</td>
<td>utfmeth.m</td>
</tr>
<tr>
<td>sl_SI.UTF-8@euro</td>
<td>utfmeth.m</td>
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<tr>
<td>sl_SI.UTF-8@preeuro</td>
<td>utfmeth.m</td>
</tr>
<tr>
<td>sq_AL.UTF-8</td>
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<tr>
<td>sr_CS.UTF-8</td>
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<td>utfmeth.m</td>
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<tr>
<td>sv_SE.UTF-8@euro</td>
<td>utfmeth.m</td>
</tr>
<tr>
<td>sv_SE.UTF-8@preeuro</td>
<td>utfmeth.m</td>
</tr>
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<tr>
<td>th_TH.TIS-620.xplink</td>
<td>sbmeth.m</td>
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<tr>
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<td>uk-UA.IBM-1124.xplink</td>
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<tr>
<td>vi_VN_UTF-8</td>
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<td>zh_CN.IBM-eucCN.xplink</td>
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<tr>
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<td>utfmeth.m</td>
</tr>
<tr>
<td>zh_TW.BIG5.xplink</td>
<td>stdmeth.m</td>
</tr>
<tr>
<td>zh_TW.UTF-8.xplink</td>
<td>utfmeth.m</td>
</tr>
</tbody>
</table>

Locale source files

The locale source files are supplied to enable you to build locales in coded character sets other than those supplied. The locale sources supplied are listed in the following table in sequence by source file name.

The “Applicable Codesets” column indicates which charmap files can be used with the source files to build the locales. The values in this column indicate the following:

**All** The locale source contains only the portable character set and can be used to build a locale with any of the supplied charmap files.

**Latin-1** The locale source contains characters from the Latin-1 character set, and can be used to build a locale from any of the supplied Latin-1 charmap files. See Appendix E, “Charmap files supplied with z/OS XL C/C++,” on page 1117 for a list of Latin-1 charmap files.
Other  The locale source is specific to the specified coded character set, and can only be used to build a locale with the specified charmap file.

### Table 365. Locale source files supplied with z/OS XL C/C++

<table>
<thead>
<tr>
<th>Language</th>
<th>Country / Territory</th>
<th>Source name</th>
<th>Applicable Codesets</th>
</tr>
</thead>
<tbody>
<tr>
<td>POSIX (built-in)</td>
<td></td>
<td>EDC$POSX</td>
<td>All</td>
</tr>
<tr>
<td>SAA (built-in)</td>
<td></td>
<td>EDC$SAAC</td>
<td>Latin-1</td>
</tr>
<tr>
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<td>Algeria, Bahrain, Egypt, Iraq, Jordan, Kuwait, Lebanon, Libya, Morocco, Oman, Qatar, Saudi Arabia, Syria, Tunisia, U.A.E., Yemen</td>
<td>EDC$AAAR</td>
<td>IBM-425</td>
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<td>Bulgaria</td>
<td>EDC$BGFE</td>
<td>IBM-1025</td>
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<td>Bulgaria</td>
<td>EDC$BGHT</td>
<td>IBM-1154</td>
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<td>Brazil</td>
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<td>Latin-1</td>
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<td>Brazil</td>
<td>EDC$BRHA</td>
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<td>EDC@BRHA</td>
<td>IBM-1140</td>
</tr>
<tr>
<td>Catalan</td>
<td>Spain</td>
<td>EDC$CSEZ</td>
<td>IBM-924</td>
</tr>
<tr>
<td>Catalan</td>
<td>Spain</td>
<td>EDC@CSEZ</td>
<td>IBM-924</td>
</tr>
<tr>
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<td>IBM-870</td>
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<td>EDC$CZMB</td>
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<td>EDC$DAEY</td>
<td>Latin-1</td>
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<td>Denmark</td>
<td>EDC$DAEZ</td>
<td>IBM-924</td>
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<td>Denmark</td>
<td>EDC@DAEZ</td>
<td>IBM-924</td>
</tr>
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<td>Denmark</td>
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<td>EDC@DAHE</td>
<td>IBM-1142</td>
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<td>German</td>
<td>Switzerland</td>
<td>EDC$DCEY</td>
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<td>Switzerland</td>
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Table 365. Locale source files supplied with z/OS XL C/C++ (continued)

<table>
<thead>
<tr>
<th>Language</th>
<th>Country / Territory</th>
<th>Source name</th>
<th>Applicable Codesets</th>
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Appendix E. Charmap files supplied with z/OS XL C/C++

All the locales supplied were built using the appropriate charmap file that represents the coded character sets described by the CodesetRegistry-CodesetEncoding element of the locale name.

All of these charmap files are provided with the National Language Resources feature of z/OS Language Environment. Consult your system programmer to determine whether they have been installed.

Under MVS, the charmap files are provided in a separate partitioned data set, CEE.SCEECCMAP. The - sign is converted to the @ character.

Table 366 lists the coded character set name, which is the same as the name of the corresponding charmap file, and the national language each code set represents. The column marked Latin-1 indicates if the charmap file is for a coded character set that contains the Latin-1 character set.

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<td>IBM-1122</td>
<td>Estonia</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1123</td>
<td>Ukraine</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1124</td>
<td>Ukraine</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1140</td>
<td>USA, Canada, Brazil</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1141</td>
<td>Germany, Austria</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1142</td>
<td>Denmark, Norway</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1143</td>
<td>Finland, Sweden</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1144</td>
<td>Italy</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1145</td>
<td>Spain, Latin America</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1146</td>
<td>United Kingdom</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1147</td>
<td>France</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1148</td>
<td>International</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1149</td>
<td>Iceland</td>
<td>Yes</td>
</tr>
<tr>
<td>IBM-1153</td>
<td>Croatia, Czech Republic, Hungary, Poland, Romania, Serbia (Latin), Slovakia, Slovenia</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1154</td>
<td>Bulgaria, Macedonia, Russia, Serbia (Cyrillic)</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1155</td>
<td>Turkey</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1156</td>
<td>Lithuania</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1157</td>
<td>Estonia</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1158</td>
<td>Ukraine</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1160</td>
<td>Thailand</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1165</td>
<td>Multinational</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1364</td>
<td>Korea</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1371</td>
<td>Taiwan</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1388</td>
<td>China (PRC)</td>
<td>No</td>
</tr>
<tr>
<td>IBM-1390</td>
<td>Japan</td>
<td>No</td>
</tr>
</tbody>
</table>
Table 366. Coded character set names and corresponding primary country/territory (continued)

<table>
<thead>
<tr>
<th>Codeset</th>
<th>Primary Country/Territory</th>
<th>Latin-1</th>
</tr>
</thead>
<tbody>
<tr>
<td>IBM-1399</td>
<td>Japan</td>
<td>No</td>
</tr>
<tr>
<td>IBM-4971</td>
<td>Greece</td>
<td>No</td>
</tr>
<tr>
<td>IBM-5123</td>
<td>Japan</td>
<td>No</td>
</tr>
<tr>
<td>IBM-8482</td>
<td>Japan</td>
<td>No</td>
</tr>
<tr>
<td>IBM12712</td>
<td>Israel</td>
<td>No</td>
</tr>
<tr>
<td>IBMEUCCN</td>
<td>China (PRC)</td>
<td>No</td>
</tr>
<tr>
<td>IBMEUCKR</td>
<td>Korea</td>
<td>No</td>
</tr>
<tr>
<td>ISO8859-1</td>
<td>All Latin 1 Countries</td>
<td>Yes</td>
</tr>
<tr>
<td>ISO8859-2</td>
<td>Croatia, Czech Republic, Hungary, Poland, Romania, Serbia (Latin), Slovakia, Slovenia</td>
<td>No</td>
</tr>
<tr>
<td>ISO8859-5</td>
<td>Bulgaria, Macedonia, Russia, Serbia (Cyrillic)</td>
<td>No</td>
</tr>
<tr>
<td>ISO8859-7</td>
<td>Greece</td>
<td>No</td>
</tr>
<tr>
<td>ISO8859-8</td>
<td>Israel</td>
<td>No</td>
</tr>
<tr>
<td>ISO8859-9</td>
<td>Turkey</td>
<td>No</td>
</tr>
<tr>
<td>TIS–620</td>
<td>Thailand</td>
<td>No</td>
</tr>
<tr>
<td>UTF-8</td>
<td>All Countries</td>
<td>Yes</td>
</tr>
</tbody>
</table>

Only the charmap files for IBM-930, IBM-933, IBM-935, IBM-937, IBM-939 and IBM-1388 specify `<mb_cur_max>` as 4 and include the definition of the double-byte characters.

**Note:** The SAA C locale is built with the charmap IBM-1047, but has `<mb_cur_max>` set to 4 to maintain compatibility with old releases of C/370.

Any of these charmaps that represent the same character set, even though they represent different encoding of the same character sets, can be used with any locale source that uses the same character set, to build a new locale and charmap combination. See [Chapter 60, “Building a locale,” on page 955](#) for information about building your own locales.
Appendix F. Examples of charmap and locale definition source

The following sections show examples of the charmap source and locale definition source files.

Charmap file

Figure 276 shows the charmap file for the encoded character set IBM-1047.

```
<code_set_name> "IBM-1047"
<mb_cur_max> 1
<mb_cur_min> 1
<escape_char> /
<comment_char> %

CHARMAP
<NUL> /x00
<SOH> /x01
<STX> /x02
<ETX> /x03
<ESC> /x04
<BS> /x05
<HT> /x06
<CYR> /x07
<DEL> /x08
<SP> /x09
<VT> /x0a
<GFX> /x0b
<FF> /x0c
<CAR> /x0d
<DEL> /x0e
<BEL> /x0f
<BS2> /x10
<BS1> /x11
<BS0> /x12
<DEL> /x13
<DEL> /x14
<VBEL> /x15
<BEL> /x16
<BS> /x17
<BS> /x18
<BS> /x19
<BS> /x1a
<BS> /x1b
<BS> /x1c
<BS> /x1d
<BS> /x1e
<BS> /x1f

Charmap file (Part 1 of 6)

Figure 276. Charmap file
<table>
<thead>
<tr>
<th>Code</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>US</td>
<td>/x1f</td>
<td></td>
</tr>
<tr>
<td>TB</td>
<td>/x1f</td>
<td></td>
</tr>
<tr>
<td>BS</td>
<td>/x20</td>
<td></td>
</tr>
<tr>
<td>FS</td>
<td>/x21</td>
<td></td>
</tr>
<tr>
<td>ACS</td>
<td>/x22</td>
<td>Field separator</td>
</tr>
<tr>
<td>BYP</td>
<td>/x23</td>
<td></td>
</tr>
<tr>
<td>LF</td>
<td>/x24</td>
<td></td>
</tr>
<tr>
<td>ETB</td>
<td>/x25</td>
<td></td>
</tr>
<tr>
<td>ERE</td>
<td>/x26</td>
<td></td>
</tr>
<tr>
<td>ESC</td>
<td>/x27</td>
<td></td>
</tr>
<tr>
<td>SA</td>
<td>/x28</td>
<td></td>
</tr>
<tr>
<td>SE</td>
<td>/x29</td>
<td></td>
</tr>
<tr>
<td>CR</td>
<td>/x2a</td>
<td></td>
</tr>
<tr>
<td>DS</td>
<td>/x2b</td>
<td></td>
</tr>
<tr>
<td>HEA</td>
<td>/x2c</td>
<td></td>
</tr>
<tr>
<td>ENQ</td>
<td>/x2d</td>
<td></td>
</tr>
<tr>
<td>ACK</td>
<td>/x2e</td>
<td></td>
</tr>
<tr>
<td>alert</td>
<td>/x2f</td>
<td></td>
</tr>
<tr>
<td>BEL</td>
<td>/x30</td>
<td></td>
</tr>
<tr>
<td>SYN</td>
<td>/x32</td>
<td></td>
</tr>
<tr>
<td>IN</td>
<td>/x33</td>
<td></td>
</tr>
<tr>
<td>FF</td>
<td>/x34</td>
<td></td>
</tr>
<tr>
<td>TM</td>
<td>/x35</td>
<td></td>
</tr>
<tr>
<td>NBS</td>
<td>/x36</td>
<td></td>
</tr>
<tr>
<td>SO</td>
<td>/x37</td>
<td></td>
</tr>
<tr>
<td>SBS</td>
<td>/x38</td>
<td></td>
</tr>
<tr>
<td>IT</td>
<td>/x39</td>
<td></td>
</tr>
<tr>
<td>BT</td>
<td>/x3a</td>
<td></td>
</tr>
<tr>
<td>CUE</td>
<td>/x3b</td>
<td></td>
</tr>
<tr>
<td>DC1</td>
<td>/x3c</td>
<td></td>
</tr>
<tr>
<td>BK1</td>
<td>/x3d</td>
<td></td>
</tr>
<tr>
<td>BS1</td>
<td>/x3f</td>
<td></td>
</tr>
<tr>
<td>space</td>
<td>/x40</td>
<td></td>
</tr>
<tr>
<td>SP01</td>
<td>/x40</td>
<td></td>
</tr>
<tr>
<td>SP1</td>
<td>/x41</td>
<td></td>
</tr>
<tr>
<td>SP2</td>
<td>/x41</td>
<td></td>
</tr>
<tr>
<td>A-C</td>
<td>/x42</td>
<td></td>
</tr>
<tr>
<td>A-XS</td>
<td>/x42</td>
<td></td>
</tr>
<tr>
<td>A-D</td>
<td>/x43</td>
<td></td>
</tr>
<tr>
<td>A-L+</td>
<td>/x43</td>
<td></td>
</tr>
<tr>
<td>A-G</td>
<td>/x44</td>
<td></td>
</tr>
<tr>
<td>A-L1</td>
<td>/x44</td>
<td></td>
</tr>
<tr>
<td>A-T</td>
<td>/x45</td>
<td></td>
</tr>
<tr>
<td>A-L19</td>
<td>/x45</td>
<td></td>
</tr>
<tr>
<td>A-R</td>
<td>/x46</td>
<td></td>
</tr>
<tr>
<td>A-T27</td>
<td>/x47</td>
<td></td>
</tr>
<tr>
<td>A-Ci</td>
<td>/x48</td>
<td></td>
</tr>
<tr>
<td>A-C1</td>
<td>/x48</td>
<td></td>
</tr>
<tr>
<td>A-T1</td>
<td>/x49</td>
<td></td>
</tr>
<tr>
<td>A-N19</td>
<td>/x49</td>
<td></td>
</tr>
<tr>
<td>A-Cm</td>
<td>/x4a</td>
<td></td>
</tr>
<tr>
<td>A-C14</td>
<td>/x4a</td>
<td></td>
</tr>
<tr>
<td>period</td>
<td>/x4b</td>
<td></td>
</tr>
<tr>
<td>SP11</td>
<td>/x4b</td>
<td></td>
</tr>
<tr>
<td>less-thanh-sgn</td>
<td>/x4c</td>
<td>&lt;less-than-sgn&gt;</td>
</tr>
<tr>
<td>A-93</td>
<td>/x4c</td>
<td></td>
</tr>
<tr>
<td>&lt;left-paranthesis</td>
<td>/x4d</td>
<td>&lt;left-paranthesis&gt;</td>
</tr>
<tr>
<td>SP66</td>
<td>/x4d</td>
<td></td>
</tr>
<tr>
<td>plus-sgn</td>
<td>/x4e</td>
<td>&lt;plus-sgn&gt;</td>
</tr>
<tr>
<td>A-81</td>
<td>/x4e</td>
<td></td>
</tr>
<tr>
<td>&lt;vertical-line&gt;</td>
<td>/x4f</td>
<td>&lt;vertical-line&gt;</td>
</tr>
<tr>
<td>A-13</td>
<td>/x4f</td>
<td></td>
</tr>
<tr>
<td>ampersand</td>
<td>/x50</td>
<td>&lt;ampersand&gt;</td>
</tr>
<tr>
<td>A-93</td>
<td>/x50</td>
<td></td>
</tr>
<tr>
<td>A-acute</td>
<td>/x51</td>
<td>&lt;A-acute&gt;</td>
</tr>
<tr>
<td>LE11</td>
<td>/x51</td>
<td></td>
</tr>
<tr>
<td>e-circumflex</td>
<td>/x52</td>
<td>e-circumflex</td>
</tr>
<tr>
<td>LE15</td>
<td>/x52</td>
<td></td>
</tr>
<tr>
<td>e-diareisis</td>
<td>/x53</td>
<td>e-diareisis</td>
</tr>
<tr>
<td>LE17</td>
<td>/x53</td>
<td></td>
</tr>
<tr>
<td>e-grave</td>
<td>/x54</td>
<td>e-grave</td>
</tr>
</tbody>
</table>

Charmap file (Part 2 of 6)
Appendix F. Examples of charmap and locale definition source 1123
Charmap file (Part 5 of 6)

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Unicode</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt;currency&gt;</td>
<td>x9f</td>
</tr>
<tr>
<td>&lt;SC01&gt;</td>
<td>x9f</td>
</tr>
<tr>
<td>&lt;mu&gt;</td>
<td>xa0</td>
</tr>
<tr>
<td>&lt;SM17&gt;</td>
<td>xa0</td>
</tr>
<tr>
<td>&lt;tilde&gt;</td>
<td>xa1</td>
</tr>
<tr>
<td>&lt;SM19&gt;</td>
<td>xa1</td>
</tr>
<tr>
<td>&lt;s&gt;</td>
<td>xa2</td>
</tr>
<tr>
<td>&lt;L501&gt;</td>
<td>xa2</td>
</tr>
<tr>
<td>&lt;m&gt;</td>
<td>xa3</td>
</tr>
<tr>
<td>&lt;L701&gt;</td>
<td>xa3</td>
</tr>
<tr>
<td>&lt;u&gt;</td>
<td>xa4</td>
</tr>
<tr>
<td>&lt;L1001&gt;</td>
<td>xa4</td>
</tr>
<tr>
<td>&lt;ve&gt;</td>
<td>xa5</td>
</tr>
<tr>
<td>&lt;LV01&gt;</td>
<td>xa5</td>
</tr>
<tr>
<td>&lt;w&gt;</td>
<td>xa6</td>
</tr>
<tr>
<td>&lt;LW01&gt;</td>
<td>xa6</td>
</tr>
<tr>
<td>&lt;x&gt;</td>
<td>xa7</td>
</tr>
<tr>
<td>&lt;LX01&gt;</td>
<td>xa7</td>
</tr>
<tr>
<td>&lt;y&gt;</td>
<td>xa8</td>
</tr>
<tr>
<td>&lt;LY01&gt;</td>
<td>xa8</td>
</tr>
<tr>
<td>&lt;z&gt;</td>
<td>xa9</td>
</tr>
<tr>
<td>&lt;LZ01&gt;</td>
<td>xa9</td>
</tr>
<tr>
<td>&lt;exclamation-down&gt;</td>
<td>xaa</td>
</tr>
<tr>
<td>&lt;SP03&gt;</td>
<td>xab</td>
</tr>
<tr>
<td>&lt;question-down&gt;</td>
<td>xab</td>
</tr>
<tr>
<td>&lt;SP16&gt;</td>
<td>xac</td>
</tr>
<tr>
<td>&lt;Eth&gt;</td>
<td>xad</td>
</tr>
<tr>
<td>&lt;left-square-bracket&gt;</td>
<td>xad</td>
</tr>
<tr>
<td>&lt;SM06&gt;</td>
<td>xad</td>
</tr>
<tr>
<td>&lt;Thorn&gt;</td>
<td>xae</td>
</tr>
<tr>
<td>&lt;LT64&gt;</td>
<td>xae</td>
</tr>
<tr>
<td>&lt;registered&gt;</td>
<td>xaaf</td>
</tr>
<tr>
<td>&lt;SM53&gt;</td>
<td>xaaf</td>
</tr>
<tr>
<td>&lt;not&gt;</td>
<td>xbo</td>
</tr>
<tr>
<td>&lt;SM66&gt;</td>
<td>xbo</td>
</tr>
<tr>
<td>&lt;sterling&gt;</td>
<td>xbo1</td>
</tr>
<tr>
<td>&lt;SC02&gt;</td>
<td>xbo1</td>
</tr>
<tr>
<td>&lt;yen&gt;</td>
<td>xbo2</td>
</tr>
<tr>
<td>&lt;S05&gt;</td>
<td>xbo2</td>
</tr>
<tr>
<td>&lt;not&gt;</td>
<td>xbo3</td>
</tr>
<tr>
<td>&lt;S06&gt;</td>
<td>xbo3</td>
</tr>
<tr>
<td>&lt;copyright&gt;</td>
<td>xbo4</td>
</tr>
<tr>
<td>&lt;SM52&gt;</td>
<td>xbo4</td>
</tr>
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<td>&lt;section&gt;</td>
<td>xbo5</td>
</tr>
<tr>
<td>&lt;SM04&gt;</td>
<td>xbo5</td>
</tr>
<tr>
<td>&lt;paragraph&gt;</td>
<td>xbo6</td>
</tr>
<tr>
<td>&lt;SM05&gt;</td>
<td>xbo6</td>
</tr>
<tr>
<td>&lt;one-quarter&gt;</td>
<td>xbo7</td>
</tr>
<tr>
<td>&lt;NF04&gt;</td>
<td>xbo7</td>
</tr>
<tr>
<td>&lt;one-half&gt;</td>
<td>xbo8</td>
</tr>
<tr>
<td>&lt;NF01&gt;</td>
<td>xbo8</td>
</tr>
<tr>
<td>&lt;three-quarters&gt;</td>
<td>xbo9</td>
</tr>
<tr>
<td>&lt;NF09&gt;</td>
<td>xbo9</td>
</tr>
<tr>
<td>&lt;Y-acute&gt;</td>
<td>xba</td>
</tr>
<tr>
<td>&lt;LT12&gt;</td>
<td>xba</td>
</tr>
<tr>
<td>&lt;diaeresis&gt;</td>
<td>xbb</td>
</tr>
<tr>
<td>&lt;SD17&gt;</td>
<td>xbb</td>
</tr>
<tr>
<td>&lt;macron&gt;</td>
<td>xcb</td>
</tr>
<tr>
<td>&lt;SM15&gt;</td>
<td>xcb</td>
</tr>
<tr>
<td>&lt;right-square-bracket&gt;</td>
<td>xcd</td>
</tr>
<tr>
<td>&lt;SM08&gt;</td>
<td>xcd</td>
</tr>
<tr>
<td>&lt;acute&gt;</td>
<td>xde</td>
</tr>
<tr>
<td>&lt;SD11&gt;</td>
<td>xde</td>
</tr>
<tr>
<td>&lt;multiply&gt;</td>
<td>xdf</td>
</tr>
<tr>
<td>&lt;SD07&gt;</td>
<td>xdf</td>
</tr>
<tr>
<td>&lt;left-brace&gt;</td>
<td>xco</td>
</tr>
<tr>
<td>&lt;left-curly-bracket&gt;</td>
<td>xco</td>
</tr>
<tr>
<td>&lt;SM1&gt;</td>
<td>xco</td>
</tr>
</tbody>
</table>
Figure 277 on page 1127 shows the typical locale definition file that represents the cultural and language conventions in the United States of America. For this example (LC_COLLATE), note the following:

- The digits (0...9) sort before the letters.
- Upper case and lowercase letters have the same primary sorting weight.
• For each letter, the uppercase letter sorts before the equivalent lowercase letter.

```xml
escape_char /
comment-char %

LC_CTYPE

upper <A>;<B>;<C>;<D>;<E>;<F>;<G>;<H>;<I>;<J>;<K>;<L>;<M>;/<N>;<O>;<P>;<Q>;<R>;<S>;<T>;<U>;<V>;<W>;<X>;<Y>;<Z>
lower <a>;<b>;<c>;<d>;<e>;<f>;<g>;<h>;<i>;<j>;<k>;<l>;<m>;/<n>;<o>;<p>;<q>;<r>;<s>;<t>;<u>;<v>;<w>;<x>;<y>;<z>
space <tab>;<newline>;<vertical-tab>;<form-feed>;<carriage-return>;<space>
cntrl <alert>;<backspace>;<newline>;<vertical-tab>;<form-feed>;<carriage-return>;<NUL>;<SOH>;<STX>;<ETX>;<EOT>;<SBS>;<EOL>;<SUB>;<SUP>;
<punct><exclamation-mark>;<quotation-mark>;<number-sign>;<dollar-sign>;<percent-sign>;<ampersand>;<apostrophe>;<left-parenthesis>;<right-parenthesis>;<asterisk>;<plus-sign>;<comma>;<hyphen-minus>;<period>;<slash>;<colon>;<semicolon>;<less-than-sign>;<equals-sign>;<greater-than-sign>;<question-mark>;<commercial-at>;<left-square-bracket>;<backslash>;<right-square-bracket>;<circumflex>;<underscore>;<grave-accent>;<left-curly-bracket>;<vertical-line>;<right-curly-bracket>;<tilde>
digit <zero>;<one>;<two>;<three>;<four>;<five>;<six>;<seven>;<eight>;<nine>
xdigit <zero>;<one>;<two>;<three>;<four>;<five>;<six>;<seven>;<eight>;<nine>
<space>;<tab>
END LC_CTYPE

LC_COLLATE

order_start forward;forward
<NUL>
...<SUB>
<space>
<exclamation-mark>
<quotation-mark>
<number-sign>
<dollar-sign>
<percent-sign>

Example locale definition source file (Part 1 of 5)

Figure 277. Example locale definition source file
Example locale definition source file (Part 2 of 5)
Example locale definition source file (Part 3 of 5)
Example locale definition source file (Part 4 of 5)
Locale method source file

The method source file maps method names to the National Language Support (NLS) subroutines that implement those methods. The method file also specifies the object libraries or DLL side-decks where the implementing subroutines are stored. The methods correspond to those subroutines that require direct access to the data structures representing locale data. Figure 278 on page 1132 shows a typical locale method source file.
escape_char /
comment_char %

METHODS

mblen "__mblen_sb_a"
mbtowc "__mbtowc_isol"
mbstowcs "__mbstowcs_std_a"
wctomb "__wctomb_isol"
wctombs "__wctombs_std_a"
wctowc "__wcwidth_std_a"
wcswidth "__wcswidth_std_a"
csid "__csid_std_a"
towupper "__towupper_std_a"
towlower "__towlower_std_a"
get_wctype "__get_wctype_std_a"
is_wctype "__is_wctype_std_a"
strcoll "__strcoll_std_a"
strxfrm "__strxfrm_std_a"
wcscoll "__wcscoll_std_a"
wcsxfrm "__wcsxfrm_std_a"
regcomp "__regcomp_std_a"
regexec "__regexec_std_a"
regfree "__regfree_std_a"
regerror "__regerror_std_a"
strfmon "__strfmon_std_a"
strftime "__strftime_std_a"
strptime "__strptime_std_a"
wcsftime "__wcsftime_std_a"
wcsid "__wcsid_std_a"

END METHODS

Figure 278. Example locale method source file
Appendix G. Converting hybrid code to a specific character set

If you are responsible for maintaining all code, including legacy code, for a system that includes hybrid code, you will need to convert the hybrid code to the code page that your compiler expects. For example, you system might expect the APL code page 293. Hybrid code is code in which the data is in the local coded character set, but the program syntax uses IBM-1047 code.

Sample program

Figure 279 shows the contents of sample program CCNGHCl. The sample program CCNGHCl converts all C syntax from code page IBM-1047 to the coded character set that you specify. Comments, string literals and character constants are left alone.

Note: Appendix C, “z/OS XL C/C++ code point mappings,” on page 1089 provides figures that show the first and second nybbles of the hexadecimal digits that comprise the code point mappings for code page IBM-1047 and the APL code page 293.

/*
 * CCNGHCl: Sample code to convert all C syntax from code page 1047
 * to the coded character set the user specifies.
 * Comments, string literals and character constants are
 * left alone. The escape character in an escape sequence
 * is changed, since it is variant.
 * Usage: CCNGHCl <coded character set>
 * The input file is read from stdin and the output is written
 * to stdout.
 * Example: If you want to convert all C syntax, written in coded character set
 * 1047, in a file (test1047 c a) to coded character set 500, you can
 * use CCNGHCl by issuing the following command.
 * ccngcl <test1047.c.a >test1047.gen.a IBM-500
 * The result will store in "test500 gen a" file.
 */
#include <stdio.h>
#include <stdlib.h>
#include <iconv.h>
#include <errno.h>

enum boolean { false=0, FALSE=0, FALSE=0, true=1, True=1, TRUE=1 }

enum CharState { CodeState, SQuoteState, DQuoteState, CommentState,
                DBCSState, EscState, EOFState }

Converting hybrid C syntax from code page IBM-1047 (Part 1 of 8)

Figure 279. Converting hybrid C syntax from code page IBM-1047
int main(int argc, char *argv[]) {
    char *codeset = Initialize(argc, argv);
    if (codeset == NULL) {
        return(8);
    }
    return(Convert(codeset));
}

char *Initialize(int argc, char *argv[]) {
    if (argc != 2) {
        fprintf(stderr, "Expected %d argument but got %d
", 1, argc-1);
        return(NULL);
    }
    Converting hybrid C syntax from code page IBM-1047 (Part 2 of 8)
stdin = freopen("", "rb", stdin);
stdout = freopen("", "wb", stdout);
if (stdin == NULL || stdout == NULL) {
    fprintf(stderr, "Could not re-open standard streams\n");
    return(NULL);
}
return(argv[1]);

/*
* Return the last position in a record
*/
static int LAST.Pos(int recSize) {
    return(recSize-1);
}

/*
* Return the next to last position in a record
*/
static int NEXT_TO_LAST_POS(int recSize) {
    return(recSize-2);
}

/*
* Convert the stdin file using codeset and write to stdout.
* Set up the translation table.
* Read the first record and copy it into the output buffer.
* Go through the FSM, starting in the Code State and leaving
* when EOFState is reached (End Of File).
* Close the translation table.
*/
static int Convert(char *codeset) {
    enum CharVal c;
    int recSize;
    enum CharState prvState;
    int rc;
    int codeStartPos = 0;
    int curPos = 0;
    enum boolean high = FALSE;
    enum CharState state = CodeState;
    char * inBuff;
    char * outBuff;
    int maxRecSize;
    XlateTable xlateTable;
    rc = InitConv(&inBuff, &outBuff, &maxRecSize, codeset, &xlateTable);
    if (rc) {
        if (inBuff) free(inBuff);
        if (outBuff) free(outBuff);
        return(rc);
    }

Converting hybrid C syntax from code page IBM-1047 (Part 3 of 8)
recSize = ReadAndCopy(inBuff, outBuff, maxRecSize);

while (state != EOFState) {
    c = GetNextChar(inBuff, outBuff, &recSize, maxRecSize,
        &curPos, &codeStartPos, state, xlateTable);
    if (c == EOFChar) {
        state = EOFState;
    }
    switch(state) {
        case CodeState:
            switch (c) {
                case BSlashChar:
                    curPos = LAST_POS(recSize);
                    break;
                case SlashChar:
                    if (LookAhead(inBuff, outBuff, &recSize,
                        &curPos, maxRecSize, &codeStartPos, state, xlateTable) == StarChar) {
                        state = CommentState;
                    }
                    break;
                case SQuoteChar:
                    state = SQuoteState;
                    break;
                case DQuoteChar:
                    state = DQuoteState;
                    break;
            }
            if (state != CodeState || curPos == NEXT_TO_LAST_POS(recSize)) {
                if (curPos == NEXT_TO_LAST_POS(recSize)) {
                    ++curPos;
                } else {
                    ConvBuff(codeStartPos, curPos, outBuff, xlateTable);
                }
            }
            break;
        case CommentState:
            switch(c) {
                case BSlashChar:
                    curPos = LAST_POS(recSize);
                    break;
                case StarChar:
                    if (LookAhead(inBuff, outBuff, &recSize,
                        &curPos, maxRecSize, &codeStartPos, state, xlateTable) == SlashChar) {
                        state = CodeState;
                        codeStartPos = curPos;
                    }
                    break;
                break;
            }
            break;
    }
}

Converting hybrid C syntax from code page IBM-1047 (Part 4 of 8)
case DQuoteState:
    switch(c) {
    case DQuoteChar:
        state = CodeState;
        codeStartPos = curPos;
        break;
    case SOChar:
        prvState = state;
        state = DBCSState;
        break;
    case BSlashChar:
        ConvBuff(curPos, curPos, outBuff, xlateTable);
        if (curPos != LAST_POS(recSize)) {
            prvState = state;
            state = EscState;
        } else {
            break;
        } else {
            break;
    }
    case SQuoteState:
        switch(c) {
        case SQuoteChar:
            state = CodeState;
            codeStartPos = curPos;
            break;
        case SOChar:
            prvState = state;
            state = DBCSState;
            break;
        case BSlashChar:
            ConvBuff(curPos, curPos, outBuff, xlateTable);
            if (curPos != LAST_POS(recSize)) {
                prvState = state;
                state = EscState;
            } else {
                break;
            } else {
                break;
        }
    case DBCSState:
        high ¬= 1; /* TRUE -> FALSE or FALSE -> TRUE */
        if (high && (c == SIChar)) {
            state = prvState;
            high = FALSE;
        } else {
            break;
        }
    case EscState:
        state = prvState; /* really, this is ok */
        break;
    case EOFState:
        break;
    default:
        fprintf(stderr, "Internal error - ended up in state %d\n",
                state);
        return(16);
    } /* end of switch statement */
    ++curPos;
}

Converting hybrid C syntax from code page IBM-1047 (Part 5 of 8)
```c
rc = TermConv(inBuff, outBuff, xlateTable);
return(0);
}
/*
 * Initialize the translation table and allocate the input and
 * output buffers to use.
 * Return 0 if successful.
 */
static int InitConv(char **inBuff, char **outBuff, int *maxRecSize,
char *codeset, XlateTable* xlateTable) {

static char fileNameBuff[FILENAME_MAX+1];
fldata_t info;
int rc;
*outBuff = *inBuff = NULL;
rc = fldata(stdin, fileNameBuff, &info);
if (rc) {
    return(rc);
}

*maxRecSize = info.__maxreclen;
inBuff = malloc(*maxRecSize);
outBuff = malloc(*maxRecSize);
if ((xlateTable = iconv_open("IBM-1047",codeset)) == (iconv_t)(-1)) {
    fprintf(stderr,"Cannot open convertor from %s to IBM-1047",codeset);
    return (8);
}
return(!inBuff || !outBuff);
}
/*
 * Convert the buffer from start to end using the translation table
 */
static void ConvBuff(int start, int end,
char *buff, XlateTable xlateTable) {
    int rc;
    size_t inleft, outleft, org;
    char *inptr, *outptr;
    inleft = outleft = end-start+1;
    inptr = outptr = &buff[start];
    while (1) {
        rc = iconv(xlateTable,&inptr,&inleft,&outptr,&outleft);
        if (rc == -1) {
            switch (errno) {
            /* Skip the invalid character */
                case EINVAL: if (--inleft == 0) return;
                ++inptr;
                ++outptr;
                --outleft;
                break;
            default: fprintf(stderr,"iconv() fails with errno = %d\n",errno);
                exit(8);
            }
        } else
            return;
    }
}

Converting hybrid C syntax from code page IBM-1047 (Part 6 of 8)
```
/*/  
* Look ahead to the next character. If the current position  
* is the last character of the input record, write the current  
* output record and read in the next record.  
* Return the 'character' read, which may be EOF if the end of  
* the file was reached.  
*/
static enum CharVal LookAhead(char *inBuff, char *outBuff,
   int *recSize, int *curPos,
   int maxRecSize, int *codeStartPos,
   enum CharState state,
   XlateTable xlateTable) {

   if (*curPos == LAST_POS(*recSize)) {
      if (UpdateAndRead(inBuff, outBuff, recSize, maxRecSize,
                    *codeStartPos, state, xlateTable)) {
         return(EOFChar);
      }
      *curPos = 0;
      *codeStartPos = 0;
   } else {
      (*curPos)++;
   }
   return(inBuff[*curPos]);
}

/*/  
* Similar to LookAhead(), but return the current character  
*/
static enum CharVal GetNextChar(char *inBuff, char *outBuff,
   int *recSize, int maxRecSize,
   int *curPos, int *codeStartPos,
   enum CharState state,
   XlateTable xlateTable) {

   if (*curPos > LAST_POS(*recSize)) {
      if (UpdateAndRead(inBuff, outBuff, recSize, maxRecSize,
                    *codeStartPos, state, xlateTable)) {
         return(EOFChar);
      }
      *curPos = 0;
      *codeStartPos = 0;
   }
   return(inBuff[*curPos]);
}

Converting hybrid C syntax from code page IBM-1047 (Part 7 of 8)
static int UpdateAndRead(char *inBuff, char *outBuff,
        int *recSize, int maxRecSize,
        int codeStartPos, enum CharState state,
        XlateTable xlateTable) {

    if (state == CodeState) {
        ConvBuff(codeStartPos, LAST_POS(*recSize), outBuff, xlateTable);
        fwrite(outBuff, 1, *recSize, stdout);
        *recSize = ReadAndCopy(inBuff, outBuff, maxRecSize);
        return((*recSize == 0) ? 1 : 0);
    }

    /*
     * Read in a record from stdin and copy it to the output buffer.
     * Return the number of bytes read.
     */
    static int ReadAndCopy(char *inBuff, char *outBuff,
                          int maxRecSize) {
        int recSize;
        recSize = fread(inBuff, 1, maxRecSize, stdin);
        if (feof(stdin) & recSize == 0) {
            return(0);
        } else {
            memcpy(outBuff, inBuff, recSize);
            return(recSize);
        }
    }

    /*
     * Free allocated storage and close the translation table.
     */
    static int TermConv(char *inBuff,
                       char *outBuff, XlateTable xlateTable) {
        iconv_close(xlateTable);
        free(inBuff);
        free(outBuff);
        return(0);
    }

    /* If the current state is the code state, translate the remaining
     * part of the record.
     * Write out the record to stdout
     * Read in the next record and copy it to the output buffer.
     */
    Convert hybrid C syntax from code page IBM-1047 (Part 8 of 8)
Appendix H. Additional Examples

This chapter contains additional examples that you might find useful when you are writing a C or C++ program.

Memory Management

If you have ever received an error from overwriting storage created with the malloc() function, the following code may be of interest. It shows how to use debuggable versions of malloc()/calloc()/realloc() and free(). You can tailor the following macros.

Figure 280 shows an example program (CCNGMI1) that uses debuggable versions of malloc()/calloc()/realloc() and free() macros.

```c
/* debuggable malloc()/calloc()/realloc()/free() example */
/* part 1 of 2-other file is CCNGMI2 */
#ifndef __STORAGE__
#define __STORAGE__
#define PADDING_SIZE 4 /* amount of padding around */
#define PADDING_BYTE 0xFE /* special value to initialize*/
#define HEAP_INIT_SIZE 4096 /* get 4K to start with */
#define HEAP_INCR_SIZE 4096 /* get 4K increments */
#define HEAP_OPTS 72 /* HEAP(,,ANYWHERE,FREE) */
extern int heapVerbose; /* If 0, heap allocation and */
/* free messages will be */
/* suppressed, otherwise, they*/
/* will be displayed */
#endif

Figure 280. Debuggable malloc()/calloc()/realloc()/free() example
```

Figure 281 on page 1142 shows the main routine (CCNGMI2) that calls the preceding macros.
/*debuggable malloc()/calloc()/realloc()/free() example*/
/* part 2 of 2-other file is CCNGMI1*/
/*
* STORAGE:
* 
* EXTERNALS:
*
* This file contains code for the following functions:
* -debug_malloc......allocate storage from a Language Environment heap
* -debug_calloc........allocate storage from a Language Environment heap
* and initialize it to 0.
* -debug_realloc.......re-allocate storage previously allocated
* by debug_malloc in this file. If a NULL pointer is passed
* instead of a previously allocated pointer,
* debug_malloc will be called directly.
* -debug_free........free storage previously allocated by debug_malloc
* in this file.
* The prefix 'debug_' make sure these functions don't affect the calls
* to original functions within the libraries a user has no control over.
*
* USAGE:
* 
* To use this code, compile with no special options (although the
* DEBUG option is useful so that the trace back will give
* additional information - line number information and the type and
* values of variables will be dumped in a trace back for all
* files compiled with DEBUG).
* Prelink (or link) this text deck with your text decks (make sure
* you explicitly link this text deck - avoid using autocall since
* you might get the C/370 version of malloc/free/realloc).
*
* INTERNALS:
* 
* General Algorithm:
* 
* When storage is allocated, extra 'padding' is allocated at the
* start and end of the actual storage allocated for the user.
* This padding is then initialized to a special pad value. If the
* user's code is functioning correctly, the padding should not
* have been changed when it comes time to free the storage. If the
* debug_free() routine finds that the padding does not have the correct
* value, the storage about to be freed is dumped and a trace back
* is issued, and then the storage is dumped, as usual.
* The padding size and padding byte value can be modified to suit
* your needs. Update the include file "ccngmi1.h" if you want
* to modify these values.
* Here is a diagram of how storage is allocated (assume that the
* pad value is xFE, the padding size is 4 bytes and 8 bytes of
* storage were requested):
* 
* Length of  Padding   Allocated storage   Padding
* storage    |   | returned to user   |   |
* | [-------|---|-----------------|---|-------|
* +----------[-----|---|-----------------|---|-------|
* | 00 00 00 10 | FE FE FE FE | xx xx xx xx | xx xx xx xx | FE FE FE FE |
* +------------------------+----------+
* 
* (Values above shown in hexadecimal)
* 
* Main routine - debuggable malloc()/calloc()/realloc()/free() example (Part 1 of 7)

Figure 281. Main routine - debuggable malloc()/calloc()/realloc()/free() example
This method is fairly effective in tracking down storage allocation problems. Also, code does not have to be recompiled to use these routines - it just has to be relinked. Note that it is not guaranteed to find all storage allocation errors - if you overwrite the padding with the same value it had before, or you overwrite more storage than you had padding for, you will still have problems.

This code uses the LE/370 heap services to allocate, re-allocate and free storage. A User Heap is used instead of the library heap so that if the heap gets corrupted, the standard library services that themselves use the heap won’t be affected (i.e. if the user heap is damaged, a call to a library function such as printf should still succeed).

Notes of interest:
- The runtime option STORAGE is very useful for tracking down random pointer problems - it initializes heap and/or stack frame storage to a particular value.
- The runtime option RPTSTG(ON) is useful for improving heap and stack frame allocation - it generates a report indicating how stack and heap storage was managed for a given program.

```
#include "ccngmi1.h"
#include <leawi.h>
#include <stdio.h>

/*
heapVerbose: external variable that controls whether heap allocation and free messages are displayed.
*/
int heapVerbose=1;

/*
mallocHeapID: static variable that is the Heap ID used for allocating storage via debug_malloc().
On the first call to debug_malloc(), a Heap will be created and this Heap ID will be set.
All subsequent calls to debug_malloc will use this Heap ID.
*/
static _INT4 mallocHeapID=0;

/*
CHARS_PER_LINE/BYTES_PER_LINE: Used by dump() and DumpLine() to control the width of a storage dump.
*/
#define CHARS_PER_LINE 40
#define BYTES_PER_LINE 16

/*
align: Given a value and the alignment desired (in bits), round the value to the next largest alignment, unless it is already aligned, in which case, just return the value passed.
*/
#pragma inline(align)
static int align(int value, int shift) {  
  int alignment = (0x1 << shift);
  if (value % alignment) {
    return(((value >> shift) << shift) + alignment);
  } else {
    return(value);
  }
}
```

Main routine - debuggable malloc()/calloc()/realloc()/free() example (Part 2 of 7)
/*
 * padding: given a buffer (address and length), return 1 if the entire buffer consists of the pad character specified, otherwise return 0.
 */
#pragma inline(padding)
static int padding(const char* buffer, long size, int pad) {
    int i;
    for (i=0;i<size;++i) {
        if (buffer[i] != pad) return(0);
    }
    return(1);
}

/*
 * CEECmp: Given two feedback codes, return 0 if they have the same message number and facility id, otherwise return 1.
 */
#pragma inline(CEECmp)
static int CEECmp(_FEEDBACK* fc1, _FEEDBACK* fc2) {
    if (fc1->tok_msgno == fc2->tok_msgno && !memcmp(fc1->tok_facid, fc2->tok_facid, sizeof(fc1->tok_facid))) {
        return(0);
    }
    else {
        return(1);
    }
}

/*
 * CEEOk: Given a feedback code, return 1 if it compares the same to condition code CEE000.
 */
#pragma inline(CEEOk)
static int CEEOk(_FEEDBACK* fc) {
    _FEEDBACK CEE000={0,0,0,0,0, {0,0,0}, 0};
    return(CEECmp(fc, &CEE000) == 0);
}

/*
 * CEEErr: Given a title string and a feedback code, print the title to stderr, then print the message associated with the feedback code. If the feedback code message can not be printed out, print out the message number and severity.
 */
static void CEEErr(const char* title, _FEEDBACK* fc) {
    _FEEDBACK msgFC;
    _INT4 dest = 2;
    fprintf(stderr, "\n\n", title);
    CEEMSG(fc, &dest, &msgFC);
    if (!CEEOk(&msgFC)) {
        fprintf(stderr, "Message number:%d with severity %d occurred\n", fc->tok_msgno, fc->tok_sev);
    }
}

Main routine - debuggable malloc()/calloc()/realloc()/free() example (Part 3 of 7)
/ * DumpLine: Dump out a buffer (address and length) to stderr.
 * /
static void DumpLine(char* address, int length) {
  int i, c, charCount=0;
  if (length % 4) length += 4;
  fprintf(stderr, "%8.8p: ", address);
  for (i=0; i < length/4; ++i) {
    fprintf(stderr, "%8.8X ", ((int*)address)??(i??);
    charCount += 9;
  }
  for (i=charCount; i < CHAR_PER_LINE; ++i) {
    putc(' ', stderr);
  }
  fprintf(stderr, "| ");
  for (i=0; i < length; ++i) {
    c = address??(i??);
    c = (isprint(c) ? c : '.');
    fprintf(stderr, "%c", c);
  }
  fprintf(stderr, "\n\n");
}

І * dump: dump out a buffer (address and length) to stderr by dumping out
І a line at a time (DumpLine), until the buffer is written out.
 * /
static void dump(void* generalAddress, int length) {
  int curr = 0;
  char* address = (char*) generalAddress;
  while (&address??(curr??) <&address??(length-BYTES_PER_LINE??)) {
    DumpLine(&address??(curr??), BYTES_PER_LINE);
    curr += BYTES_PER_LINE;
  }
  if (curr < length) {
    DumpLine(&address??(curr??), length-curr);
  }
}

І * debug_malloc: Create a heap if necessary by calling CEECRHP. This only
І needs to be done on the first call to debug_malloc(). Verify
І that the heap creation was ok. If it wasn't, issue an 
І error message and return a NULL pointer.
І Write a message to stderr indicating how many bytes
І are about to be allocated.
І Call CEGTST to allocate the storage requested plus
І additional padding to be placed at the start and end
І of the allocated storage. Verify that the storage allocation
І was successful. If it wasn't, issue an error message and
І return a NULL pointer.
І Write a message to stderr indicating the address of the
І allocated storage.
І Initialize the padding to the value of PADDING_BYTE, so that
І debug_free() will be able to test that the padding was not changed.
І Return the address of the allocated storage (starting after
І the padding bytes).
 */

void* debug_malloc(long initSize) {
  _FEEDBACK fc;
  _POINTER address=0;

Main routine - debuggable malloc()/calloc()/realloc()/free() example (Part 4 of 7)
long totSize;
long* lenPtr;
char* msg;
char* start;
char* end;

if (!mallocHeapID) {
    _INT4 heapSize = HEAP_INIT_SIZE;
    _INT4 heapInc = HEAP_INCR_SIZE;
    _INT4 opts = HEAP_OPTS;
    CEECRHP(&mallocHeapID, &heapSize, &heapInc, &opts, &fc);
    if (!CEEOk(&fc)) {
        CEEErr("Heap creation failed", &fc);
        return(0);
    }
}
if (heapVerbose) {
    fprintf(stderr, "Allocate %d bytes", initSize);
}
/*
 * Add the padding size to the total size, then round up to the
 * nearest double word
 */
totSize = initSize + (PADDING_SIZE*2) + sizeof(long);
totSize = align(totSize, 3);
CEEGTST(&mallocHeapID, &totSize, &address, &fc);
if (!CEEOk(&fc)) {
    msg = "Storage request failed"
    CEEErr(msg, &fc);
    _ctrace(msg);
    return(0);
}
lenPtr = (long*) address;
*lenPtr = initSize;
start = ((char*) address) + sizeof(long);
end = start + initSize + PADDING_SIZE;
memset(start, PADDING_BYTE, PADDING_SIZE);
memset(end, PADDING_BYTE, PADDING_SIZE);
if (heapVerbose) {
    fprintf(stderr, " starting at address %p\n", address);
}
return(start + PADDING_SIZE);

*/
* debug_calloc: Call debug_malloc() to allocate the requested amount
 * of storage. If the allocation was successful,
 * initialize the allocated storage to 0.
 * Return the address of the allocated storage (or a NULL
 * pointer if debug_malloc returned a NULL pointer).
 */
void* debug_calloc(size_t num, size_t size) {
    size_t initSize = num * size;
    void* ptr;
    ptr = debug_malloc(initSize);
    if (ptr) {
        memset(ptr, 0, initSize);
    }
    return(ptr);
}

Main routine - debuggable malloc()/calloc()/realloc()/free() example (Part 5 of 7)
/ * debug_realloc: If a NULL pointer is passed, call debug_malloc() directly. 
 * Call CEECZST to re-allocate the storage requested plus 
 * additional padding to be placed at the start and end 
 * of the allocated storage. 
 * Verify that the storage re-allocation was ok. If it wasn't, 
 * issue an error message, dump the storage, and return a NULL 
 * pointer. 
 * Write a message to stderr indicating the address of the 
 * re-allocated storage. 
 * Initialize the padding to the value of PADDING_BYTE, so 
 * that debug_free() will be able to test that the padding was not 
 * changed. Note that the padding at the start of the storage 
 * does not need to be allocated, since it was already 
 * initialized by an earlier call to debug_malloc(). 
 * Return the address of the re-allocated storage (starting 
 * after the padding bytes). 
 */

void* debug_realloc(char* ptr, long initSize) {
  _FEEDBACK fc;
  _POINTER address = (ptr - sizeof(long) - PADDING_SIZE);
  long oldSize;
  long* lenPtr;
  char* start;
  char* end;
  char* msg;
  long newSize = initSize;
  if (ptr == 0) {
    return(debug_malloc(newSize));
  }
  oldSize = *((long*) address);
  if (heapVerbose) {
    fprintf(stderr, "Re-allocate %d bytes from address %p to ",
        newSize, address);
  }
  /*
  * Add the padding size to the total size, then round up to the
  * nearest double word
  */
  newSize += (PADDING_SIZE*2) + sizeof(long);
  newSize = align(newSize, 3);
  CEECZST(&address, &newSize, &fc);
  if (!CEEOk(&fc)) {
    msg = "Storage re-allocation failed"
    CEEErr(msg, &fc);
    dump(address, oldSize + (PADDING_SIZE*2) + sizeof(long));
    __ctrace(msg);
    return(0);
  }
  lenPtr = (long*) address;
  *lenPtr= initSize;
  start = ((char*) address) + sizeof(long);
  end = start + initSize + PADDING_SIZE;
  memset(end, PADDING_BYTE, PADDING_SIZE);
  if (heapVerbose) {
    fprintf(stderr, "address %p
", address);
  }
}

Main routine - debuggable malloc()/calloc()/realloc()/free() example (Part 6 of 7)
return(start + PADDING_SIZE);
}
/*
 * debug_free: Calculate where the start and end of the originally
 * allocated storage was. The start will be different than the
 * address passed in because the address passed in points after
 * the padding bytes added by debug_malloc() or debug_realloc().
 * Write a message to stderr indicating what address is about
 * to be freed.
 * Verify that the start and end padding bytes have the original
 * padding value. If they don't, dump out the originally
 * allocated storage and issue a trace.
 * Free the storage by calling CEEFRST. If the storage free
 * fails, dump out the storage and issue a trace.
 */
void debug_free(char* ptr) {
    _FEEDBACK fc;
    _POINTER address=(void*) (ptr - sizeof(long) - PADDING_SIZE);
    char* start;
    char* end;
    long size;
    long* lenPtr;
    char* msg;
    lenPtr = (long*) address;
    size = *lenPtr;
    start = ((char*) address) + sizeof(long);
    end = start + size + PADDING_SIZE;
    if (heapVerbose) {
        fprintf(stderr, "Free address %p\n", address);
    }
    if (!padding(start, PADDING_SIZE, PADDING_BYTE) ||
        !padding(end, PADDING_SIZE, PADDING_BYTE)) {
        dump(address, size + (PADDING_SIZE*2) + sizeof(long));
        msg = "Padding overwritten";
        __ctrace(msg);
    } else {
        CEEFRST(&address, &fc);
        if (!CEEOk(&fc)) {
            msg = "Storage debug_free failed";
            CEEErr(msg, &fc);
            dump(address, size + (PADDING_SIZE*2) + sizeof(long));
            __ctrace(msg);
        }
    }
}

Main routine - debuggable malloc()/calloc()/realloc()/free() example (Part 7 of 7)

Calling MVS WTO routines from C

The following examples call a function that will perform a Write To Operator (WTO) call. You can tailor it as you wish. The C code performs an ILC to an assembler routine to do a dynamic WTO call. To use this example, you would perform the following steps; when complete, information is then written to the job log.
1. Assemble the code shown in Figure 282 on page 1149
2. Compile the code shown in Figure 283 on page 1150
3. Link the two together
4. Run CCNGWT2

Note: This example runs only in the TSO BATCH environment.

Figure 282 on page 1149 shows sample program CCNGWT1, which performs a WTO call.
* WRITE TO OPERATOR EXAMPLE *
* PART 1 OF 2-OTHER FILE IS CCNGWT2 *

WTO CSECT
WTO AMODE 31
WTO RMODE ANY

*******
* R1->ADDRESS OF INTEGER -> LENGTH OF STRING
* ->CHARACTER STRING

EDCPRLG DSLEN=DLEN
USING DSA,13

*******
* RANGE CHECK LENGTH
* IGNORE A SINGLE TRAILING NULL CHARACTER

L 5,0(.1) POINT TO LENGTH
LA 15,4 RETURN CODE FOR INVALID LENGTH
ICM 5,'1111',0(5) LENGTH OF MESSAGE
BNP RETURN NOT >0? RETURN
L 6,4(.1) POINT TO MESSAGE
LA 8,9(5,6) POINT TO CHAR AFTER MESSAGE
BCTR 8,0 POINT TO LAST CHARACTER
CLI 0(8),0 IS IT A NULL CHARACTER?
BNE NOENDINGNULL
BCT 5,NOENDINGNULL IGNORE IT: USER SAID WTO(SIZEOF S,S)
B RETURN UNLESS LENGTH WAS DROPPED TO ZERO

NOENDINGNULL DS 0H
LA 7,0 LENGTH OK SO FAR
LA 8,L'BUFFER MAXIMUM LENGTH
CR 5,8 CHECK LENGTH
BNH LENOK
LR 5,8 SHOW ONLY WHAT FITS INTO BUFFER
LA 7,4 REMEMBER SPECIFIED STRING WAS TOO LONG
LENOK DS 0H

*******
* BUILD WTO BUFFER
* COPY LIST FORM OF WTO TO DSA
* EXECUTE WTO

STH 5,PREFIX LENGTH SHOWN GOES INTO PREFIX
BCTR 5,0 REDUCE LENGTH FOR EXECUTE
EX 5,MSG MOVE MESSAGE TEXT
LA 6,PREFIX POINT TO PREFIX OF COPIED MESSAGE
MVC WTOD,WTOL MOVE LIST FORM OF MACRO TO DSA
WTO TEXT=(6),MF=(E,WTOD)

Performing a Write To Operator (Part 1 of 2)

Figure 282. Performing a Write To Operator
********
* IF WTO RETURNED NON-ZERO THAT'S THE RETURN CODE FOR THE USER
* OTHERWISE WE RETURN 4 IF WE TRUNCATED MESSAGE, 0 IF WE DIDN'T

    LTR 15,15 CHECK RC FROM WTO
    BNZ RETURN 0 WTO RC RETURNED TO CALLER
    LR 15,7 TELL CALLER IF STRING WAS TOO LONG
    RETURN DS OH

EDCEPIL
MSG MVC BUFFER(*-*),0(6)
WTOL WTO TEXT=,ROUTE=11,DESC=12,MF=L LIST FORM
WTOLEN EQU *=WTOL LENGTH TO MOVE
DSA EDCOSAD
    DS OF
WTOD DS CL(WTOLEN)
PREFIX DS H
BUFFER DS CL126
DLEN EQU *=DSA
END

Performing a Write To Operator (Part 2 of 2)

Figure 283 shows the program (CCNGWT2) you would run after you compile the
code shown in Figure 282 on page 1149.

Listing Partitioned Data Set Members

This section contains code examples that demonstrate how you can create a list of
all members in a Partitioned Data Set (PDS). Figure 284 on page 1151 shows the
main routine (called CCNGIPI1) and Figure 285 on page 1154 (CCNGIPI2) is the
associated header file.

Note: This information is included to aid you in such a task and is not
programming interface information.
/* this example shows how to create a list of members of a PDS */
/* part 1 of 2 - other file is CCNGIP2 */
/*
* NODE_PTR pds_mem(const char *pds):
* pds must be a fully qualified pds name, for example,
* ID.PDS.DATASET * returns a * pointer to a linked list of
* nodes. Each node contains a member of the * pds and a
* pointer to the next node. If no members exist, the pointer
* is NULL.
* 
* Note: Behavior is undefined if pds is the name of a sequential file.
*/
#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#include "ccngip2.h"

/* RECORD: each record of a pds will be read into one of these structures.
* The first 2 bytes is the record length, which is put into 'count',
* the remaining 254 bytes are put into rest. Each record is 256 bytes long.
*/
define RECLEN 254

typedef struct {
    unsigned short int count;
    char rest[RECLEN];
} RECORD;

/* Local function prototypes */
static int gen_node(NODE_PTR *node, RECORD *rec, NODE_PTR *last_ptr);
static char *add_name(NODE_PTR *node, char *name, NODE_PTR *last_ptr);

NODE_PTR pds_mem(const char *pds) {
    FILE *fp;
    int bytes;
    NODE_PTR node, last_ptr;
    RECORD rec;
    int list_end;
    char *qual_pds;

    node = NULL;
    last_ptr = NULL;

    /* Allocate a new variable, qual_pds, which will be the same as pds, except
    * with single quotes around it, i.e. ID.PDS.DATASET ==> 'ID.PDS.DATA SET'
    */

    qual_pds = (char *)malloc(strlen(pds) + 3);
    if (qual_pds == NULL) {
        fprintf(stderr, "malloc failed for %d bytes\n", strlen(pds) + 3);
        exit(-1);
    }
    sprintf(qual_pds, "'\%s'", pds);

    Example of Listing All Members of a PDS (Part 1 of 4)

    Figure 284. Example of Listing All Members of a PDS
/*
 * Open the pds in binary read mode. The PDS directory will be read
 * one record at a time until either the end of the directory or end-of-file
 * is detected. Call up gen_node() with every record read, to add
 * names to the linked list
 */

fp = fopen(qual_pds,"rb");
if (fp == NULL)
    return(NULL);

do
{
    bytes = fread(&rec, 1, sizeof(rec), fp);
    if ((bytes != sizeof(rec)) && !feof(fp)) {
        perror("FREAD:");
        fprintf(stderr,"Failed in %s, line %d
"
            "FILE__LINE__,sizeof(rec), bytes);
        exit(-1);
    }

    list_end = gen_node(&node,&rec, &last_ptr);
}
while (!feof(fp) && !list_end);
fclose(fp);
free(qual_pds);
return(node);
*/

/*
 * GEN_NODE() processes the record passed. The main loop scans through
 * the record until it has read at least rec->count bytes, or a directory
 * end marker is detected.
 * Each record has the form:
 * +------------+------+------+------+------+----------------+
 * +# of bytes ¦Member¦Member¦......¦Member¦ Unused +
 * + in record ¦ 1 ¦ 2 ¦ ¦ n ¦ +
 * +--count--¦--------------rest-----------------------¦
 * (Note that the number stored in count includes its own
 * two bytes)
 * And, each member has the form:
 * +--------+-------+----+-----------------------------------+
 * + Member ¦TTR ¦info¦ +
 * + Name ¦ ¦byte¦ User Data TTRN's (halfwords) +
 * + 8 bytes|3 bytes| +
 * +--------+-------+----+-----------------------------------+
 */
#define TTRLEN 3 /* The TTR's are 3 bytes long */

Example of Listing All Members of a PDS (Part 2 of 4)
#define ALIAS_MASK ((unsigned int) 0x80)
/*
 * The number of user data half-words is in bits 3-7 of the info byte.
 * SKIP_MASK is used to extract this information. Since this number
 * is
 * in half-words, it needs to be double to obtain the number of bytes.
 */
#define SKIP_MASK ((unsigned int) 0x1F)
/*
 * 8 hex FF's mark the end of the directory
 */
char *endmark = "\xFF\xFF\xFF\xFF\xFF\xFF\xFF\xFF";
static int gen_node(NODE_PTR *node, RECORD *rec, NODE_PTR *last_ptr) {
    char *ptr, *name;
    int skip, count = 2;
    unsigned int info_byte, alias, ttrn;
    char ttr[TTRLEN];
    int list_end = 0;
    ptr = rec->rest;
    while(count < rec->count) {
        if (!memcmp(ptr,endmark,NAMELEN)) {
            list_end = 1;
            break;
        }
        /* member name */
        name = ptr;
        ptr += NAMELEN;
        /* ttr */
        memcpy(ttr,ptr,TTRLEN);
        ptr += TTRLEN;
        /* info_byte */
        info_byte = (unsigned int) (*ptr);
        alias = info_byte & ALIAS_MASK;
        if (!alias) add_name(node,name,last_ptr);
        skip = (info_byte & SKIP_MASK)*2+1;
        ptr += skip;
        count += (TTRLEN + NAMELEN + skip);
    }
    return(list_end);
}
/*
 * ADD_NAME: Add a new member name to the linked node. The new member is
 * added to the end so that the original ordering is maintained.
 */
static char *add_name(NODE_PTR *node, char *name, NODE_PTR *last_ptr) {
    NODE_PTR newnode;
    /* malloc space for the new node */
    newnode = (NODE_PTR)malloc(sizeof(NODE));
    if (newnode == NULL) {
        fprintf(stderr,"malloc failed for %d bytes\n",sizeof(NODE));
        exit(-1);
    }
}

Example of Listing All Members of a PDS (Part 3 of 4)
/* copy the name into the node and NULL terminate it */

    memcpy(newnode->name, name, NAMELEN);
    newnode->name[NAMELEN] = '\0';
    newnode->next = NULL;

    /* add the new node to the linked list */
    if (*last_ptr != NULL) {
        (*last_ptr)->next = newnode;
        *last_ptr = newnode;
    } else {
        *node = newnode;
        *last_ptr = newnode;
    }
    return(newnode->name);

    /* FREE_MEM: This function is not used by pds_mem(), but it should be used
    * as soon as you are finished using the linked list. It frees the storage
    * allocated by the linked list. */
    void free_mem(NODE_PTR node) {
        NODE_PTR next_node = node;
        while (next_node != NULL) {
            next_node = node->next;
            free(node);
            node = next_node;
        }
        return;
    }

Example of Listing All Members of a PDS (Part 4 of 4)

Figure 285 (CCNGIP2) shows the associated header file.

/* this example shows how to create a list of members of a PDS */
/* part 2 of 2-other file is CCNGIP1 */
/*
  * NODE: a pointer to this structure is returned from the call to pds_mem().
  * It is a linked list of character arrays - each array contains a member
  * name. Each next pointer points * to the next member, except the last
  * next member which points to NULL.
  */
#define NAMELEN 8 /* Length of a MVS member name */

typedef struct node {
    struct node *next;
    char name[NAMELEN+1];
} NODE, *NODE_PTR;

NODE_PTR pds_mem(const char *pds);
void free_mem(NODE_PTR list);

Figure 285. ccngip2.h Header file
Appendix I. Application considerations for z/OS UNIX XL C/C++

This appendix briefly describes the extent of z/OS XL C/C++ support available for traditional MVS programming environments when you are using z/OS UNIX.

Relationship to DB2 universal database

No explicit support for DB2 programs exists for POSIX.1 implementation. DB2 z/OS XL C/C++ programs must be processed by a DB2 precompile step to replace Structured Query Language (SQL) statements with z/OS XL C/C++ functions. The precompilation step accepts only MVS data set I/O.

It is possible that an existing DB2 z/OS XL C/C++ application program can be changed to add POSIX.1-defined I/O functions to access data in z/OS UNIX files. IBM, however, does not explicitly support this access. It is also possible that you can write a new POSIX.1.-conforming z/OS XL C/C++ application program that access DB2 data by calling non-POSIX.1-conforming DB2 programs. IBM, however, does not explicitly support this either.

Application programming environments not supported

The following MVS programming environments are not supported for use when developing POSIX.1 z/OS XL C/C++ application programs. Application programs that attempt to take advantage of these environments will not work as intended.

- CICS
- IMS file system

Support for the Curses library

The Curses library provides a set of functions that enable you to manipulate a terminal's display regardless of the terminal type. Using this structure, you can manipulate data on a terminal's display. You can instruct curses to treat the entire terminal display as one large window or you can create multiple windows on the display. The windows can be different sizes and can overlap one another.

Each window on a terminal's display has its own window data structure. This structure keeps state information about the window such as its size and where it is located on the display. Curses uses the window data structure to obtain relevant information it needs to carry out your instructions.

The Curses archive file resides in /usr/lib. The name of the Curses archive file is libcurses.a; this file is used for all applications: base 31-bit, XPLINK 31-bit, and 64-bit. The following is an example of compiling test.c with the Curses archive using XPLINK:

```
c89 -o test -Wc,xplink -Wl,xplink test.c -lcurses
```
The following is an example of compiling test.c with the Curses archive for a 64-bit application:

c89 -o test -Wc,lp64 -Wl,lp64 test.c -lcurses

For more information about curses, refer to the z/OS C Curses manual.
Appendix J. External variables

The POSIX 1003.1 and X/Open CAE Specification 4.2 (XPG4.2) require that the C system header files define certain external variables. Additional variables are defined for use with POSIX or XPG4.2 functions. If you define one of the POSIX or XPG4 feature test macros and include one of these headers, the external variables will be defined in your program. These external variables are treated differently than other global variables in a multithreaded environment (values are thread-specific) and across a call to a fetched module (values are propagated). To access the global variable values (not thread specific), either C with the RENT compiler option or C++ must be used, and the SCEEOBJ autocall library must be specified during the z/OS bind. The SCEEOBJ library must be specified before the SCEELKEX and the SCEELKED libraries. If the SCEEOBJ library is not specified first, then Language Environment cannot find the external variables. Although there are no linker/binder errors or warnings, runtime errors can occur. Functions to access the thread-specific values of these variables are provided for use in a multithreaded environment.

For a dynamically called DLL module to share access to the POSIX external variables with its caller, the DLL module must define the _SHARE_EXT_VARS feature test macro. This is implemented in the current Language Environment runtime. For more information, see the section on feature test macros in z/OS XL C/C++ Runtime Library Reference.

When compiling code with the XPLINK or LP64 compiler options, all access to these external variables is resolved by dynamic linkage, using IMPORT control statements in the CELHS003 (CELQ5003) member of the SCEELIB library. The SCEEOBJ library cannot be used when binding XPLINK executable modules. Because of this, the _SHARE_EXT_VARS (and subordinate) feature test macros need only be used with XPLINK to access the thread-specific values of these external variables without the explicit use of the thread-specific functions.

For more information on the header files referred to in the following sections, see z/OS XL C/C++ Runtime Library Reference.

errno

When a runtime library function is not successful, the function may do any of the following to identify the error:

- Set errno to a documented value.
- Set errno to a value that is not documented. You can use strerror() or perror() to get the message associated with the errno.
- Not set errno.
- Clear errno.

See also errno.h.
daylight

The daylight savings time flag set by tzset(). Note that other time zone sensitive functions such as ctime(), localtime(), mktime(), and strftime() implicitly call tzset(). Use the __dlght() function to access the thread-specific value of daylight. See also time.h.

gdate_err

The variable is set to the following value when an error occurs in the gdate() function.

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>The DATEMSK environment variable is NULL or undefined.</td>
</tr>
<tr>
<td>2</td>
<td>The template file cannot be opened for reading.</td>
</tr>
<tr>
<td>3</td>
<td>Failed to get file status information.</td>
</tr>
<tr>
<td>4</td>
<td>The template file is not a regular file.</td>
</tr>
<tr>
<td>5</td>
<td>An error was encountered while reading the template file.</td>
</tr>
<tr>
<td>6</td>
<td>Memory allocation failed (not enough memory available).</td>
</tr>
<tr>
<td>7</td>
<td>No line in the template file matches the input specification.</td>
</tr>
<tr>
<td>8</td>
<td>Non-valid input specification. For example, February 31 or a time that cannot be represented in a time_t (representing the time in seconds since Epoch - midnight, January 1, 1970 (UTC)).</td>
</tr>
<tr>
<td>9</td>
<td>Unable to determine current time.</td>
</tr>
</tbody>
</table>

Note: This value is unique for z/OS UNIX.

Any changes to errno are unspecified. Use the __gderr() function to access the thread-specific value of gdate_err. The gdate64() function affects the same pointer to the thread-specific value of gdate_err as __gderr() does. The gdate64() function also uses the same gdate_err values as gdate() does. See also time.h.

h_errno

An integer that holds the specific error code when the network nameserver encounters an error. The network nameserver is used by the gethostbyname() and gethostbyaddr() functions. Use the __h_errno() function to access the thread-specific value of h_errno. See also netdb.h.

_loc1

A global character pointer that is set by the regex() function to point to the first matched character in the input string. Use the __loc1() function to access the thread-specific value of _loc1._loc1 is not supported in AMODE 64 applications. See also libgen.h.

loc1

A pointer to characters matched by regular expressions used by step(). The value is not propagated across a call to a fetched module. _loc1 is not supported in AMODE 64 applications. See also regexp.h.
loc2
A pointer to characters matched by regular expressions used by step(). The value is not propagated across a call to a fetched module. loc2 is not supported in AMODE 64 applications. See also regexp.h.

locs
Used by advance() to stop regular expression matching in a string. The value is not propagated across a call to a fetched module. locs is not supported in AMODE 64 applications. See also regexp.h.

optarg
Character pointer used by getopt() for options parsing variables. Use the __optargf() function to access the thread-specific value of optarg. See also stdio.h and unistd.h.

opterr
Error value used by getopt(). Use the __operrf() function to access the thread-specific value of opterr. See also stdio.h and unistd.h.

optind
Integer pointer used by getopt() for options parsing variables. Use the __opindf() function to access the thread-specific value of optind. See also stdio.h and unistd.h.

optopt
Integer pointer used by getopt() for options parsing variables. Use the __optoptf() function to access the thread-specific value of optopt. See also stdio.h and unistd.h.

signgam
Storage for sign of lgamma(). This function defaults to thread specific. See also math.h.

stdin
Standard Input stream. The external variable will be initialized to point to the enclave-level stream pointer for the standard input file. There is no multithreaded function. See also stdio.h.

stderr
Standard Error stream. The external variable will be initialized to point to the enclave-level stream pointer for the standard error file. There is no multithreaded function. See also stdio.h.
**stdout**

Standard Output stream. The external variable will be initialized to point to the enclave-level stream pointer for the standard output file. There is no multithreaded function. See also stdio.h.

---

**t_errno**

An integer that holds the specific error code when a failure occurs in one of the X/Open Transport Interface (XTI) functions. Use the __t_errno() function to access the thread-specific value of t_errno. See also xti.h.

---

**timezone**

Long integer difference from UTC and standard time as set by tzset(). Note that other time zone sensitive functions such as, ctime(), localtime(), mktime(), and strftime() implicitly call tzset(). Use the __tzzone() function to access the thread-specific value of timezone. See also time.h.

---

**tzname**

Character pointer to unsized array of timezone strings used by tzset() and ctime(). The *tzname variable contains the Standard and Daylight Savings time zone names. If the TZ environment variable is present and correct, tzname is set from TZ. Otherwise tzname is set from the LC_TOD locale category. See the tzset() function for a description. There is no multithreaded function. See also time.h.
Appendix K. Packaging considerations

When you develop a program, library, or application that will be shipped as a product, you should use SMP/E to manage the installation. This information provides hints and tips for packaging a C or C++ application. It assumes that you are familiar with SMP/E concepts and terminology. For more information about SMP/E and packaging rules, refer to the following manuals:

- SMP/E for z/OS Reference
- SMP/E for z/OS User’s Guide
- Standard packaging rules for MVS-based products

The way you package your product may have a significant impact on its relationship with other products, its dependency on libraries, and the way it is eventually serviced. For this reason, you should make a packaging plan as part of the design process for your product.

For more information about these compiler options, see z/OS XL C/C++ User’s Guide.

Compiler options

The following options are useful when you compile a program that will be packaged as a product:

TARGET
If your product will run on multiple releases of z/OS, use the TARGET compiler option to specify the lowest level of the z/OS Language Environment that you will support. The compiler will notify you if your application uses any features that are not supported at this level.

The target must be the same release as the compiler or a previous release. If the target is a previous release, you must link with the system library of the target system. You cannot link with libraries from the current release and run the resulting executable with a previous release of z/OS Language Environment.

CSECT
Use the CSECT compiler option or #pragma csect to assign names to CSECTs. This provides you with more control and flexibility when you service the product.

For more information about these compiler options, see z/OS XL C/C++ User’s Guide.

Libraries

Your product can use various type of libraries:

z/OS Language Environment libraries
Because z/OS Language Environment is upward-compatible, a program that runs on a lower level of z/OS Language Environment can also run on higher levels without being relinked or recompiled. You can optionally recompile your programs, if you want to take advantage of new features that are introduced to z/OS Language Environment.
Your own libraries
If your program uses your own libraries, you can statically bind the
libraries with the program and consider them an integral part of the
product.

Third-party libraries
If your application uses third-party vendor libraries, you should consider
whether the linking is static or dynamic (if it is a DLL), and whether the
libraries are upward-compatible. If you statically link a library with your
application, you can use either the ++MOD method or the ++PROGRAM
method, as described in "Linking."

Prelinking
You must use the z/OS Language Environment prelinker before linking your
application if the resultant load module will reside in a PDS and any of the
following are true:
• Your application contains C++ code.
• Your application contains C code that is compiled with the RENT, LONGNAME, DLL,
or IPA compiler option.
• Your application is compiled to run under z/OS UNIX System Services.

SMP/E will not invoke the prelinker. If your product needs to be prelinked, you
should usually prelink as part of your product build and ship the prelinker output
on the SMP/E tape.

Linking
There are two ways to ship an application that is statically linked to a library:
• You can use the ++MOD command to build the application, and not perform the
  final link to the library until the product is installed. If the customer later installs
  a PTF for this library, your application will automatically be relinked.
• You can build the application and link it to the library, and then install it using
  the ++PROGRAM command. If a PTF is issued for the library, this will have no
  effect until you include the updated library in a PTF for your product.

++MOD method
If you want to do the final link-edit step during installation, use the ++MOD
command statement in the MCS. You must compile and then partially link your
program with any libraries that will not exist on the customer's system, and then
produce output in link-edited format. Any references to libraries that will exist on
the customer's system, such as z/OS Language Environment libraries, are
unresolved. Ship this link-edited module on the SMP/E tape.

At installation time, the application is linked to the libraries on the customer's
system. For example, on z/OS V1R4, the application is linked to z/OS Language
Environment V1R4 libraries.

SMP/E supports the automatic library call facility through the use of SYSLIB DD
statements. This allows you to implicitly include modules without explicitly
specifying them in the JCLIN. This can provide flexibility if the link-edit structure
of the application must change during servicing, for example because new
functions are used.
When you service a ++MOD, you must ship your fixes using a ++PTF command statement. The SMP/E tape must contain the text deck (object files) in fixed-block 80 format. SMP/E invokes the link-editor to rebind the new text deck with the existing load module. You must name all of the CSECTs, using the CSECT compiler option or #pragma csect. (If you do not name the CSECTs, CSECT replacement would not happen. Old text records would accumulate in the load module as you ship out subsequent fixes for your product.)

To allow rebind, you must also use the EDIT=YES option in the bind step. This is the default.

++PROGRAM method

You can choose to do the final link step as part of your product build, and ship the output load module to your customer. The advantage is that the whole build process is under your control, and you can perform the final testing of the load module in your own controlled environment.

If your customers have different levels of z/OS Language Environment, you must target your build to the lowest level and link with system libraries at this level. Your product will have a prerequisite that the customer must have z/OS Language Environment at this level or a higher level.

If service is applied to any linked library, this will have no effect on your product until you include the service in a PTF.

The ++PTF command, which is used for shipping and applying fixes, expects input in fixed-block 80 format. The output of the link step is not in this format. You can convert it as follows:

1. UNLOAD - use IEBCOPY to copy the module and its alias (if any) to a sequential file.
2. Run the SMP/E utility GIMDTS to convert the sequential file to a fixed-block 80 file.

Conceptually, the ++PROGRAM copies the whole load module to your customer's target dataset with no additional processing. You customer receives the module exactly as you ship it.
Appendix L. Accessibility

Accessible publications for this product are offered through IBM Knowledge Center (http://www.ibm.com/support/knowledgecenter/SSLTBW/welcome).

If you experience difficulty with the accessibility of any z/OS information, send a detailed message to the "Contact us" web page for z/OS (http://www.ibm.com/systems/z/os/zos/webqs.html) or use the following mailing address.

IBM Corporation
Attention: MHVRCFS Reader Comments
Department H6MA, Building 707
2455 South Road
Poughkeepsie, NY 12601-5400
United States

Accessibility features

Accessibility features help users who have physical disabilities such as restricted mobility or limited vision use software products successfully. The accessibility features in z/OS can help users do the following tasks:

- Run assistive technology such as screen readers and screen magnifier software.
- Operate specific or equivalent features by using the keyboard.
- Customize display attributes such as color, contrast, and font size.

Consult assistive technologies

Assistive technology products such as screen readers function with the user interfaces found in z/OS. Consult the product information for the specific assistive technology product that is used to access z/OS interfaces.

Keyboard navigation of the user interface

You can access z/OS user interfaces with TSO/E or ISPF. The following information describes how to use TSO/E and ISPF, including the use of keyboard shortcuts and function keys (PF keys). Each guide includes the default settings for the PF keys.

- z/OS TSO/E Primer
- z/OS TSO/E User’s Guide
- z/OS V2R2 ISPF User’s Guide Vol I

Dotted decimal syntax diagrams

Syntax diagrams are provided in dotted decimal format for users who access IBM Knowledge Center with a screen reader. In dotted decimal format, each syntax element is written on a separate line. If two or more syntax elements are always present together (or always absent together), they can appear on the same line because they are considered a single compound syntax element.

Each line starts with a dotted decimal number; for example, 3 or 3.1 or 3.1.1. To hear these numbers correctly, make sure that the screen reader is set to read out
punctuation. All the syntax elements that have the same dotted decimal number (for example, all the syntax elements that have the number 3.1) are mutually exclusive alternatives. If you hear the lines 3.1 USERID and 3.1 SYSTEMID, your syntax can include either USERID or SYSTEMID, but not both.

The dotted decimal numbering level denotes the level of nesting. For example, if a syntax element with dotted decimal number 3 is followed by a series of syntax elements with dotted decimal number 3.1, all the syntax elements numbered 3.1 are subordinate to the syntax element numbered 3.

Certain words and symbols are used next to the dotted decimal numbers to add information about the syntax elements. Occasionally, these words and symbols might occur at the beginning of the element itself. For ease of identification, if the word or symbol is a part of the syntax element, it is preceded by the backslash (\) character. The * symbol is placed next to a dotted decimal number to indicate that the syntax element repeats. For example, syntax element *FILE with dotted decimal number 3 is given the format 3 \* FILE. Format 3* FILE indicates that syntax element FILE repeats. Format 3* \* FILE indicates that syntax element * FILE repeats.

Characters such as commas, which are used to separate a string of syntax elements, are shown in the syntax just before the items they separate. These characters can appear on the same line as each item, or on a separate line with the same dotted decimal number as the relevant items. The line can also show another symbol to provide information about the syntax elements. For example, the lines 5.1*, 5.1 LASTRUN, and 5.1 DELETE mean that if you use more than one of the LASTRUN and DELETE syntax elements, the elements must be separated by a comma. If no separator is given, assume that you use a blank to separate each syntax element.

If a syntax element is preceded by the % symbol, it indicates a reference that is defined elsewhere. The string that follows the % symbol is the name of a syntax fragment rather than a literal. For example, the line 2.1 %OP1 means that you must refer to separate syntax fragment OP1.

The following symbols are used next to the dotted decimal numbers.

? indicates an optional syntax element
   The question mark (?) symbol indicates an optional syntax element. A dotted decimal number followed by the question mark symbol (?) indicates that all the syntax elements with a corresponding dotted decimal number, and any subordinate syntax elements, are optional. If there is only one syntax element with a dotted decimal number, the ? symbol is displayed on the same line as the syntax element, (for example 5? NOTIFY). If there is more than one syntax element with a dotted decimal number, the ? symbol is displayed on a line by itself, followed by the syntax elements that are optional. For example, if you hear the lines 5 ?, 5 NOTIFY, and 5 UPDATE, you know that the syntax elements NOTIFY and UPDATE are optional. That is, you can choose one or none of them. The ? symbol is equivalent to a bypass line in a railroad diagram.

! indicates a default syntax element
   The exclamation mark (!) symbol indicates a default syntax element. A dotted decimal number followed by the ! symbol and a syntax element indicate that the syntax element is the default option for all syntax elements that share the same dotted decimal number. Only one of the syntax elements that share the dotted decimal number can specify the ! symbol. For example, if you hear the lines 2? FILE, 2.1! (KEEP), and 2.1 (DELETE), you know that (KEEP) is the
default option for the FILE keyword. In the example, if you include the FILE keyword, but do not specify an option, the default option KEEP is applied. A default option also applies to the next higher dotted decimal number. In this example, if the FILE keyword is omitted, the default FILE(KEEP) is used. However, if you hear the lines 2? FILE, 2.1, 2.1.1 (KEEP), and 2.1.1 (DELETE), the default option KEEP applies only to the next higher dotted decimal number, 2.1 (which does not have an associated keyword), and does not apply to 2? FILE. Nothing is used if the keyword FILE is omitted.

* indicates an optional syntax element that is repeatable

The asterisk or glyph (*) symbol indicates a syntax element that can be repeated zero or more times. A dotted decimal number followed by the * symbol indicates that this syntax element can be used zero or more times; that is, it is optional and can be repeated. For example, if you hear the line 5.1* data area, you know that you can include one data area, more than one data area, or no data area. If you hear the lines 3* , 3 HOST, 3 STATE, you know that you can include HOST, STATE, both together, or nothing.

Notes:

1. If a dotted decimal number has an asterisk (*) next to it and there is only one item with that dotted decimal number, you can repeat that same item more than once.

2. If a dotted decimal number has an asterisk next to it and several items have that dotted decimal number, you can use more than one item from the list, but you cannot use the items more than once each. In the previous example, you can write HOST STATE, but you cannot write HOST HOST.

3. The * symbol is equivalent to a loopback line in a railroad syntax diagram.

+ indicates a syntax element that must be included

The plus (+) symbol indicates a syntax element that must be included at least once. A dotted decimal number followed by the + symbol indicates that the syntax element must be included one or more times. That is, it must be included at least once and can be repeated. For example, if you hear the line 6.1+ data area, you must include at least one data area. If you hear the lines 2+, 2 HOST, and 2 STATE, you know that you must include HOST, STATE, or both. Similar to the * symbol, the + symbol can repeat a particular item if it is the only item with that dotted decimal number. The + symbol, like the * symbol, is equivalent to a loopback line in a railroad syntax diagram.
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Bibliography

This bibliography lists the publications for IBM products that are related to z/OS XL C/C++. It includes publications covering the application programming task. The bibliography is not a comprehensive list of the publications for these products, however, it should be adequate for most z/OS XL C/C++ users. Refer to z/OS V2R2 Information Roadmap, SA23-2299, for a complete list of publications belonging to the z/OS product.

**z/OS**
- z/OS V2R2 Introduction and Release Guide, GA32-0887
- z/OS Planning for Installation, GA32-0890
- z/OS Summary of Message and Interface Changes, SA23-2300
- z/OS V2R2 Information Roadmap, SA23-2299
- z/OS V2R2 Licensed Program Specifications, GA32-0888
- z/OS V2R2 Migration, GA32-0889
- z/OS Program Directory, GI11-9848

**z/OS XL C/C++**
- z/OS XL C/C++ Programming Guide, SC14-7315
- z/OS XL C/C++ User’s Guide, SC14-7307
- z/OS XL C/C++ Language Reference, SC14-7308
- z/OS XL C/C++ Messages, GC14-7305
- z/OS XL C/C++ Runtime Library Reference, SC14-7314
- z/OS C Curses, SA38-0690
- z/OS XL C/C++ Compiler and Runtime Migration Guide for the Application Programmer, GC14-7306
- Standard C++ Library Reference, SC14-7309

**z/OS Metal C Runtime Library**
- z/OS Metal C Programming Guide and Reference, SC14-7313

**z/OS Runtime Library Extensions**
- z/OS Common Debug Architecture Library Reference, SC14-7311
- DWARF/ELF Extensions Library Reference, SC14-7312

**Debug Tool**

**z/OS Language Environment**
- z/OS V2R1.0 Language Environment Concepts Guide, SA38-0687
- z/OS Language Environment Customization, SA38-0685
- z/OS Language Environment Debugging Guide, GA32-0908
- z/OS Language Environment Programming Guide, SA38-0682
- z/OS Language Environment Programming Reference, SA38-0683

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• z/OS V2R1.0 Language Environment Runtime Application Migration Guide, GA32-0912
• z/OS V2R1.0 Language Environment Writing Interlanguage Communication Applications, SA38-0684
• z/OS Language Environment Runtime Messages, SA38-0686

Assembler
• HLASM Language Reference, SC26-4940
• HLASM Programmer’s Guide, SC26-4941

COBOL
• COBOL documentation, which is available at: http://www.ibm.com/software/awdtools/cobol/zos/library/

PL/I
• PL/I documentation, which is available at: http://www.ibm.com/software/awdtools/pli/plizos/library/

VS FORTRAN
• VS FORTRAN documentation, which is available at: http://www.ibm.com/software/awdtools/fortran/vsfortran/library.html

CICS Transaction Server for z/OS
• CICS Transaction Server for z/OS documentation, which is available at: http://www.ibm.com/software/hpcics/

DB2
• DB2 for z/OS documentation, which is available at: http://www.ibm.com/software/data/db2/zos/library.html

IMS/ESA®
• IMS documentation, which is available at: http://www.ibm.com/software/data/ims/library.html

MVS
• z/OS MVS Program Management: User’s Guide and Reference, SA23-1393
• z/OS MVS Program Management: Advanced Facilities, SA23-1392

QMF
• QMF documentation, which is available at: http://www.ibm.com/software/data/qmf/library.html

DFSMSS
• z/OS DFSMS Introduction, SC23-6851
• z/OS DFSMS Managing Catalogs, SC23-6853
• z/OS DFSMS Using Data Sets, SC23-6855
• z/OS DFSMS Macro Instructions for Data Sets, SC23-6852
• z/OS DFSMS Access Method Services Commands, SC23-6846
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